- To present an example of system development
- Our approach: a series of more and more accurate models
- This approach is called refinement
- The models formalize the view of an external observer

- With each refinement observer "zooms in" to see more details

- Each model will be analyzed and proved to be correct
- The aim is to obtain a system that will be correct by construction
- The correctness criteria are formulated as proof obligations
- Proofs will be performed by using the sequent calculus
- Inference rules used in the sequent calculus will be reviewed

- The concepts of state and events for defining models
- Some principles of system development: invariants and refinement
- A refresher of classical logic and simple arithmetic foundations
- A refresher of formal proofs

1. Presentation of the requirement document (as in previous lecture)

2. Defining the refinement strategy

3. Development of the initial model and the refinements

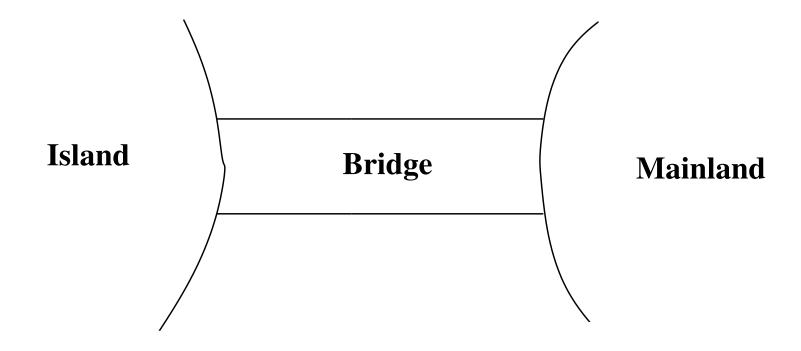
Remark: Theoretical background provided during development

- The system we are going to build is a piece of software connected to some equipment.
- There are two kinds of requirements:
 - those concerned with the equipment, labeled EQP,
 - those concerned with the function of the system, labeled FUN.
- The function of this system is to control cars on a narrow bridge.
- This bridge is supposed to link the mainland to a small island.

The system is controlling cars on a bridge between the mainland and an island

FUN-1

- This can be illustrated as follows



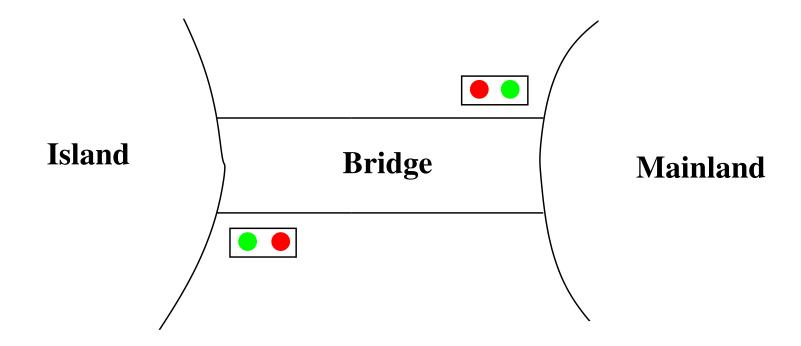
- The controller is equipped with two traffic lights with two colors.

The system has two traffic lights with two colors: green and red

EQP-1

- One of the traffic lights is situated on the mainland and the other one on the island. Both are close to the bridge.

- This can be illustrated as follows



The traffic lights control the entrance to the bridge at both ends of it

EQP-2

- Drivers are supposed to obey the traffic light by not passing when a traffic light is red.

Cars are not supposed to pass on a red traffic light, only on a green one

EQP-3

- There are also some car sensors situated at both ends of the bridge.
- These sensors are supposed to detect the presence of cars intending to enter or leave the bridge.
- There are four such sensors. Two of them are situated on the bridge and the other two are situated on the mainland and on the island.

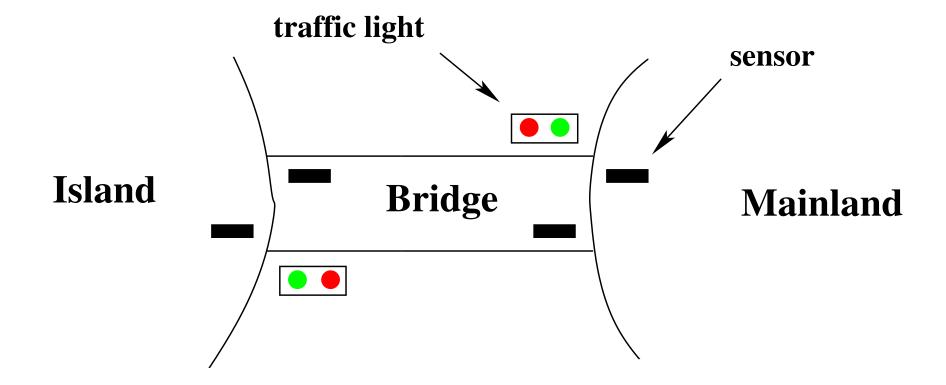
The system is equipped with four car sensors each with two states: on or off

EQP-4

The sensors are used to detect the presence of cars entering or leaving the bridge

EQP-5

- The pieces of equipment can be illustrated as follows:



- This system has two main constraints: the number of cars on the bridge and the island is limited and the bridge is one way.

The number of cars on the bridge and the island is limited

FUN-2

The bridge is one way or the other, not both at the same time

FUN-3

The system is controlling cars on a bridge between the mainland and an island

FUN-1

The number of cars on the bridge and the island is limited

FUN-2

The bridge is one way or the other, not both at the same time

FUN-3

The system has two traffic lights with two colors: green and red

EQP-1

The traffic lights control the entrance to the bridge at both ends of it

EQP-2

Cars are not supposed to pass on a red traffic light, only on a green one

EQP-3

The system is equipped with four car sensors each with two states: on or off

EQP-4

The sensors are used to detect the presence of cars entering or leaving the bridge

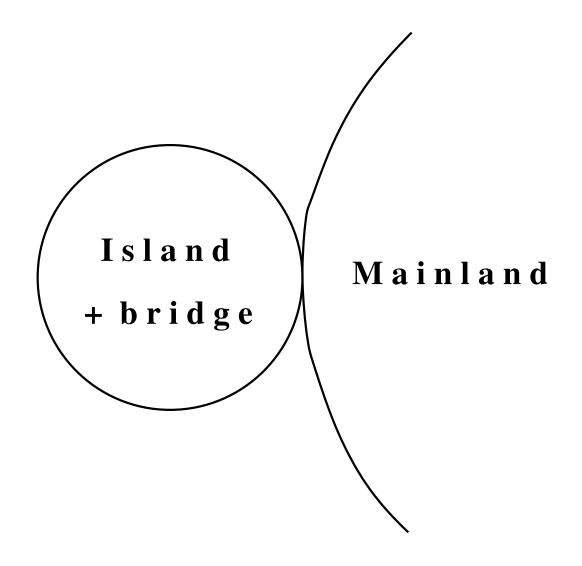
EQP-5

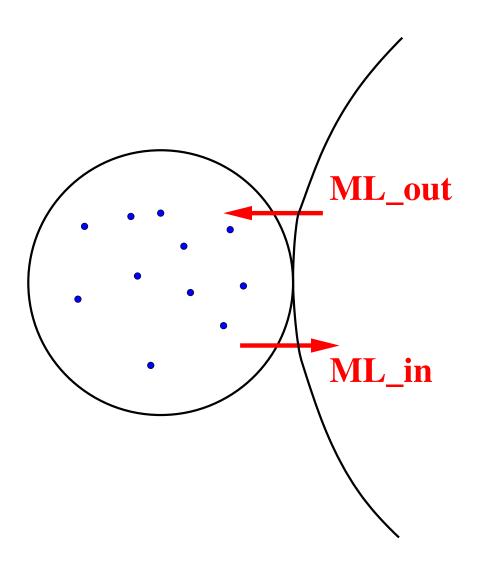
- Initial model: Limiting the number of cars (FUN-2)
- First refinement: Introducing the one way bridge (FUN-3)
- Second refinement: Introducing the traffic lights (EQP-1,2,3)
- Third refinement: Introducing the sensors (EQP-4,5)

- Initial model: Limiting the number of cars (FUN-2)
- First refinement: Introducing the one-way bridge (FUN-3)
- Second refinement: Introducing the traffic lights (EQP-1,2,3)
- Third refinement: Introducing the sensors (EQP-4,5)

Initial Model

- It is very simple
- We completely ignore the equipment: traffic lights and sensors
- We do not even consider the bridge
- We are just interested in the pair "island-bridge"
- We are focusing FUN-2: limited number of cars on island-bridge





- STATIC PART of the state: constant d with axiom axm0_1

constant: d

axm0_1: $d \in \mathbb{N}$

- d is the maximum number of cars allowed on the Island-Bridge

- axm0_1 states that d is a natural number

- Constant d is a member of the set $\mathbb{N} = \{0, 1, 2, \ldots\}$

- DYNAMIC PART: variable v with invariants inv0_1 and inv0_2

variable: n

inv0_1: $n \in \mathbb{N}$

inv0_2: n < d

- n is the effective number of cars on the Island-Bridge

- n is a natural number (inv0_1)

- n is always smaller than or equal to d (inv0_2): this is FUN_2

- Labels axm0_1, inv0_1, ... are chosen systematically
- The label **axm** or **inv** recalls the purpose: axiom of constants or invariant of variables

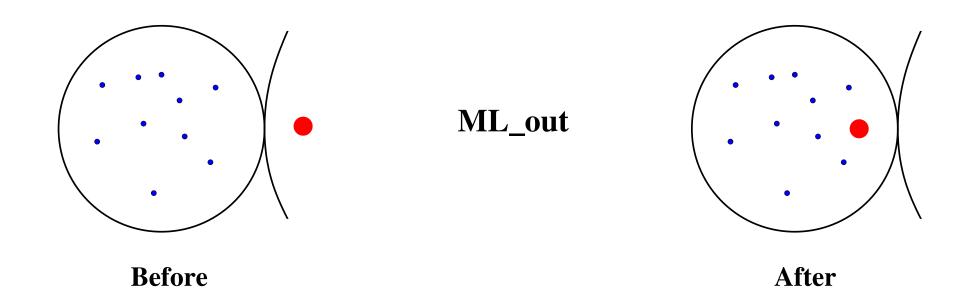
- The 0 as in inv0_1 stands for the initial model.

- Later we will have inv1_1 for an invariant of refinement 1, etc.
- The 1 like in inv0_1 is a serial number

- Any convention is valid as long as it is systematic

- This is the first transition (or event) that can be observed

- A car is leaving the mainland and entering the Island-Bridge



- The number of cars in the Island-Bridge is incremented

- We can also observe a second transition (or event)

- A car leaving the Island-Bridge and re-entering the mainland



- The number of cars in the Island-Bridge is decremented

- Event ML_out increments the number of cars

$$\mathsf{ML}$$
_out $n := n+1$

- Event ML_in decrements the number of cars

$$egin{aligned} \mathsf{ML_in} \ n := n-1 \end{aligned}$$

- An event is denoted by its name and its action (an assignment)

These events are approximations for two reasons:

- 1. They might be refined (made more precise) later
- 2. They might be insufficient at this stage because not consistent with the invariant

We have to perform a proof in order to verify this consistency.

- An invariant is a constraint on the allowed values of the variables

- An invariant must hold on all reachable states of a model

- To verify that this holds we must show that
 - 1. the invariant holds for initial states (later), and
 - 2. the invariant is preserved by all events (following slides)
- We will formalize these two statements as proof obligations (POs)
- We need a rigorous proof showing that these POs indeed hold

- To each event can be associated a before-after predicate
- It describes the relation between the values of the variable(s) just before and just after the event occurrence
- The before-value is denoted by the variable name, say n
- The after-value is denoted by the primed variable name, say n'

The Events

$$egin{aligned} \mathsf{ML_out} \ n := n+1 \end{aligned}$$

$$\mathsf{ML}_{oldsymbol{\cdot}}\mathsf{in} \ n := n-1$$

The corresponding before-after predicates

$$n'=n+1$$

$$n'=n-1$$

These representations are equivalent.

- The before-after predicates we have shown are very simple

$$n'=n+1 \qquad \qquad n'=n-1$$

- The after-value n' is defined as a function of the before-value n
- This is because the corresponding events are deterministic
- In later lectures, we shall consider some non-deterministic events:

$$n' \in \{n+1,n+2\}$$

Let us consider invariant inv0_1

$$n\in\mathbb{N}$$

- And let us consider event ML_out with before-after predicate

$$n'=n+1$$

- Preservation of inv0_1 means that we have (just after ML_out):

$$n' \in \mathbb{N}$$
 that is $n+1 \in \mathbb{N}$

- Under hypothesis $n \in \mathbb{N}$ the conclusion $n+1 \in \mathbb{N}$ holds

- This can be written as follows

$$n \in \mathbb{N} \vdash n+1 \in \mathbb{N}$$

- This type of statement is called a sequent (next slide)

Sequent above: invariant preservation proof obligation for inv0_1

- More General form of this PO will be introduced shortly

- A sequent is a formal statement of the following shape

- H denotes a set of predicates: the hypotheses (or assumptions)

- G denotes a predicate: the goal (or conclusion)

The symbol "⊢", called the turnstyle, stands for provability.
 It is read: "Assumptions H yield conclusion G"

- We collectively denote our set of constants by c
- We denote our set of axiomss by A(c): $A_1(c), A_2(c), \ldots$
- We collectively denote our set of variables by $oldsymbol{v}$
- We denote our set of invariants by I(c,v): $I_1(c,v),I_2(c,v),\ldots$

- We are given an event with before-after predicate $v^\prime = E(c,v)$
- The following sequent expresses preservation of invariant $I_i(c, v)$:

$$A(c),\,I(c,v)\;\vdash\;I_i(c,E(c,v))$$
 INV

- It says: $I_i(c,E(c,v))$ provable under hypotheses A(c) and I(c,v)
- We have given the name INV to this proof obligation

$$A(c),\,I(c,v)\;\vdash\;I_i(c,E(c,v))$$
 INV

- We assume that A(c) as well as I(c,v) hold just before the occurrence of the event represented by $v^\prime=E(c,v)$
- Just after the occurrence, invariant $I_i(c,v)$ becomes $I_i(c,v')$, that is, $I_i(c,E(c,v))$
- The predicate $I_i(c,E(c,v))$ must then hold for $I_i(c,v)$ to be an invariant

- The proof obligation

$$A(c),\,I(c,v)\;\vdash\;I_i(c,E(c,v))$$
 INV

can be re-written vertically as follows:

Axioms
Invariants

Modified Invariant

$$egin{array}{c} A(c) \ I(c,v) \ dash \ I_i(c,E(c,v)) \end{array}$$
 INV

- We have two events

$$\mathsf{ML}$$
_out $n := n+1$

$$\mathsf{ML}_{oldsymbol{-}}\mathsf{in} \ n := n-1$$

- And two invariants

inv0_1:
$$n \in \mathbb{N}$$

inv0_2:
$$n \leq d$$

- Thus, we need to prove four proof obligations

$$\mathsf{ML}$$
_out $n := n+1$

$$(n'=n+1)$$

$$egin{array}{l} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ dots \ n+1 \in \mathbb{N} \end{array}$$

- This proof obligation is named: ML_out / inv0_1 / INV

$$\mathsf{ML}$$
_out $n := n+1$

$$(n'=n+1)$$

$$egin{array}{l} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ dots \ n+1 \leq d \end{array}$$

- This proof obligation is named: ML_out / inv0_2 / INV

$$egin{aligned} \mathsf{ML}\ \mathsf{in}\ n := n-1 \end{aligned}$$

$$(n'=n-1)$$

$$egin{array}{ll} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ dots \ n-1 \in \mathbb{N} \end{array}$$

- This proof obligation is named: ML_in / inv0_1 / INV

$$egin{aligned} \mathsf{ML}\ \mathsf{in}\ n &:= n-1 \end{aligned}$$

$$(n'=n-1)$$

$$egin{array}{l} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ dots \ -1 \leq d \end{array}$$

- This proof obligation is named: ML_in / inv0_2 / INV

ML_out / inv0_1 / INV

$$egin{array}{l} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ dots \ n+1 \in \mathbb{N} \end{array}$$

ML_in / inv0_1 / INV

ML_out / inv0_2 / INV

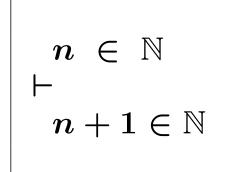
$$egin{array}{cccc} d \in \mathbb{N} & & & & & \ n \in \mathbb{N} & & & & & \ n \leq d & & & & \ & & & & & \ & & & & & \ & & & & & \ & & & & & \ & & & & & \ & & & & & \ & & & & & \ & & & & & \ & & & & \ & & & & & \ & & & & \ & & & & \ & & & & \ & & & \ & & & \ & & & \ & & & \ & & & \ & & & \ & & & \ & & \ & & & \ & & \ & & \ & & \ & & \ & & \ & & \ & & \ & & \ & & \ & & \ & & \ & & \ & & \ & \ & & \ & & \ & & \ & \ & \ & & \$$

ML_in / **inv0_2** / INV

$$egin{array}{ll} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ dots \ n-1 \leq d \end{array}$$

$$egin{array}{l} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ dots \ n+1 \in \mathbb{N} \end{array}$$

 $\begin{tabular}{ll} remove \\ \hline & \longrightarrow \\ hypotheses \\ \end{tabular}$



obvious

- In the first step, we remove some irrelevant hypotheses
- In the second and final step, we accept the sequent as it is
- We have implicitly applied inference rules
- For rigorous reasoning we will make these rules explicit

$$\frac{\mathsf{H}_1 \; \vdash \; \mathsf{G}_1 \quad \cdots \quad \mathsf{H}_n \; \vdash \; \mathsf{G}_n}{\mathsf{H} \; \vdash \; \mathsf{G}} \quad \mathsf{RULE_NAME}$$

- Above horizontal line: n sequents called antecedents ($n \geq 0$)
- Below horizontal line: exactly one sequent called consequent
- To prove the consequent, it is sufficient to prove the antecedents
- A rule with no antecedent (n=0) is called an axiom

- The rule that removes hypotheses can be stated as follows:

- It expresses the monotonicity of the hypotheses

- The Second Peano Axiom

$$\overline{\mathbf{n} \in \mathbb{N} \vdash \mathbf{n} + 1 \in \mathbb{N}}$$
 P2

$$\frac{}{0 < \mathsf{n} \vdash \mathsf{n} - 1 \in \mathbb{N}}$$
 P2'

- Axioms about ordering relations on the integers

$$\frac{}{\mathsf{n} \, < \, \mathsf{m} \, \vdash \, \mathsf{n} + 1 \, \leq \, \mathsf{m}}$$
 INC

$$\overline{\mathbf{n} \leq \mathbf{m} \vdash \mathbf{n} - 1 \leq \mathbf{m}}$$
 DEC

- Consider again the 2nd Peano axiom:

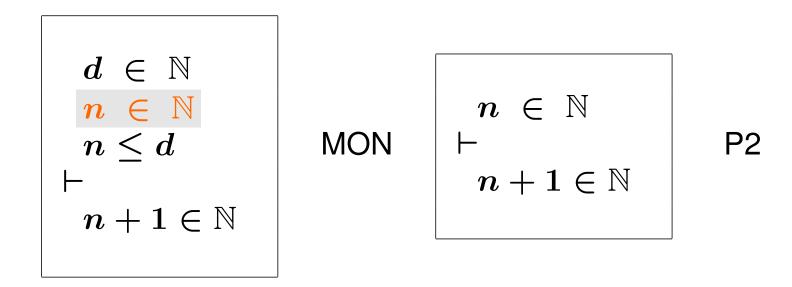
$$n \in \mathbb{N} \vdash n+1 \in \mathbb{N}$$
 P2

- It is a rule schema where **n** is called a meta-variable

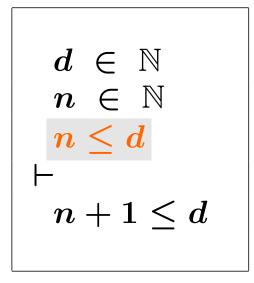
- It can be applied to following sequent by matching a+b with ${\bf n}$:

$$a+b \in \mathbb{N} \vdash a+b+1 \in \mathbb{N}$$

- A proof is a tree of sequents with axioms at the leaves.
- The rules applied to the leaves are axioms.
- Each sequent is labeled with (name of) proof rule applied to it.
- The sequent at the root of the tree is called the root sequent.
- The purpose of a proof is to establish the truth of its root sequent.

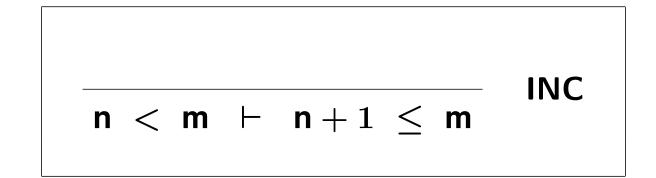


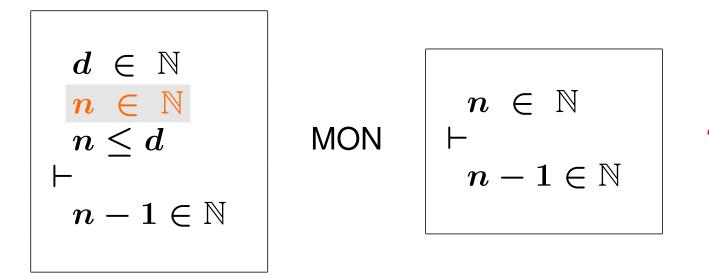
- Proof requires only application of two rules: **MON** and **P2**



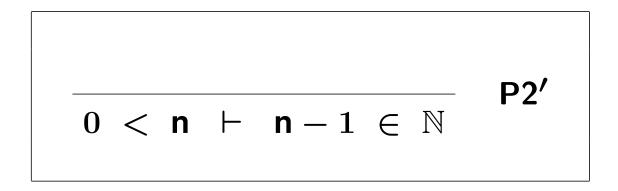
MON
$$n \leq d$$
 $n + 1 \leq d$?

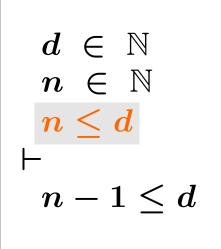
- We put a ? to indicate that we have no rule to apply
- The proof fails: we cannot conclude with rule INC (n < d needed)





- The proof fails: we cannot conclude with rule P2' (0 < n needed)





MON

$$n \leq d \ dash n-1 \leq d$$

DEC

$$n \leq m \vdash n-1 \leq m$$

- We needed hypothesis n < d to prove $ML_out / inv0_2 / INV$
- We needed hypothesis 0 < n to prove ML_in / inv0_1 / INV

$$\mathsf{ML}$$
_out $n := n+1$

$$\mathsf{ML}_{\mathsf{-in}}$$
 $n := n-1$

- We are going to add n < d as a guard to event ML _out
- We are going to add 0 < n as a guard to event ML_in

```
egin{aligned} \mathsf{ML\_out} \ \mathsf{when} \ n < d \ \mathsf{then} \ n := n+1 \ \mathsf{end} \end{aligned}
```

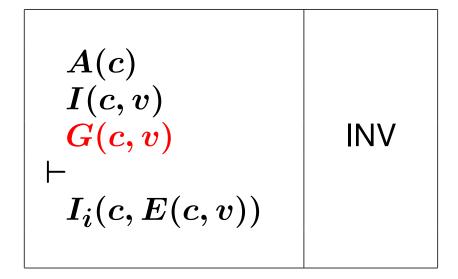
```
egin{aligned} \mathsf{ML}\ \mathsf{in} \ & \mathsf{when} \ 0 < n \ & \mathsf{then} \ n := n-1 \ & \mathsf{end} \end{aligned}
```

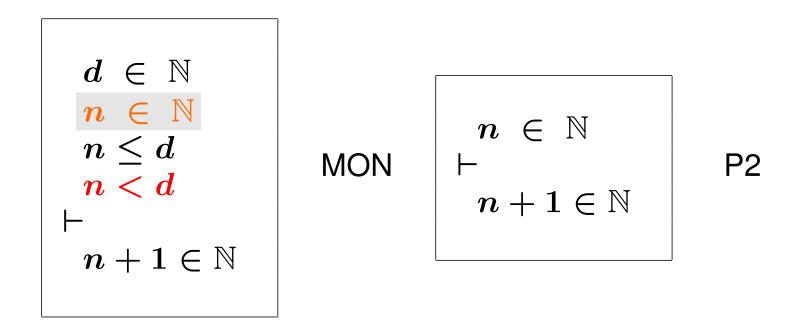
- We are adding guards to the events
- The guard is the necessary condition for an event to "occur"

- Given c with axioms A(c) and v with invariants I(c,v)
- Given an event with guard G(c,v) and b-a predicate $v^{\prime}=E(c,v)$
- We modify the Invariant Preservation PO as follows:

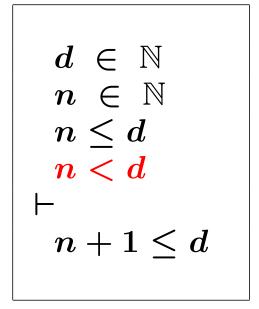
Axioms
Invariants
Guard of the event

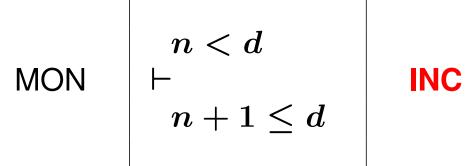
Modified Invariant



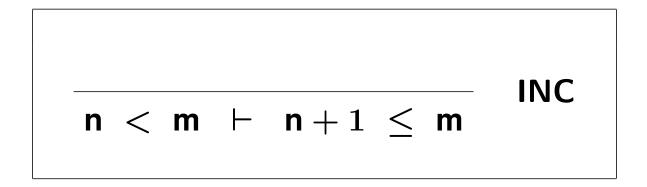


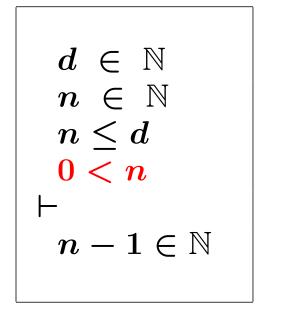
- Adding new assumptions to a sequent does not affect its provability

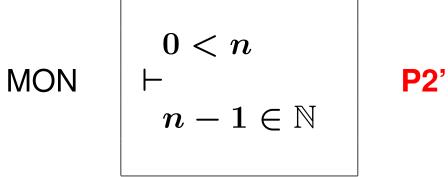




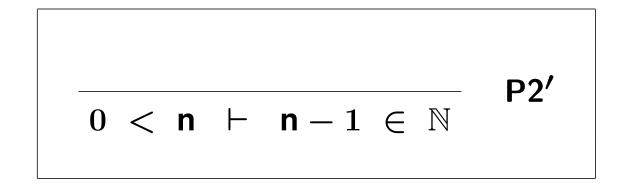
- Now we can conclude the proof using rule **INC**

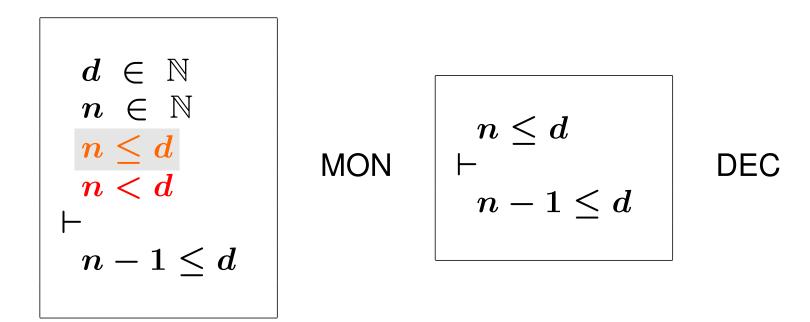






- Now we can conclude the proof using rule P2'





- Again, the proof still works after the addition of a new assumption

$$egin{array}{l} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ n < d \ dots \ n + 1 \in \mathbb{N} \end{array}$$

$$egin{array}{ll} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ 0 < n \ dots \ n-1 \in \mathbb{N} \end{array}$$

$$egin{array}{l} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ n < d \ &\vdash \ n+1 \leq d \end{array}$$

$$egin{array}{l} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ 0 < n \ dots \ n-1 \leq d \end{array}$$

- Our system must be initialized (with no car in the island-bridge)

- The initialization event is never guarded

- It does not mention any variable on the right hand side of :=

-Its before-after predicate is just an after predicate

init

n := 0

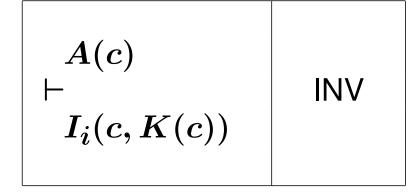
After predicate

n'=0

- Given $oldsymbol{c}$ with axioms $oldsymbol{A}(oldsymbol{c})$ and $oldsymbol{v}$ with invariants $oldsymbol{I}(oldsymbol{c},oldsymbol{v})$
- Given an init event with after predicate $oldsymbol{v'} = oldsymbol{K}(oldsymbol{c})$
- The Invariant Establishment PO is the following:

Axioms

Modified Invariant



axm0₁

Modified inv0_1

 $d\in\mathbb{N}$ \vdash $0\in\mathbb{N}$

inv0_1 / INV

axm0_1

_

Modified inv0_2

 $d\in\mathbb{N}$ \vdash $0\leq d$

inv0_2 / INV

- First Peano Axiom

- Third Peano Axiom (slightly modified)

$$n \in \mathbb{N} \vdash 0 \leq n$$
 P3

$$d\in\mathbb{N}$$
 \vdash
 $0\in\mathbb{N}$

MON

$$egin{array}{c} oldsymbol{0} \in \mathbb{N} \end{array}$$

P1

$$d\in\mathbb{N}$$
 \vdash
 $0\leq d$

- It is possible for the system to be blocked if both guards are false

- We do not want this to happen

- We figure out that one important requirement was missing

Once started, the system should work for ever

FUN-4

- Given c with axioms A(c) and v with invariants I(c,v)
- Given the guards $G_1(c,v),\ldots,G_m(c,v)$ of the events
- We have to prove the following:

$$egin{array}{c} A(c) \ I(c,v) \ dash G_1(c,v) \ ee G_m(c,v) \end{array}$$
 DLF

```
axm0_1
inv0_1
inv0_2
⊢
Disjunction of guards
```

```
egin{array}{ll} d \in \mathbb{N} \ n \in \mathbb{N} \ n \leq d \ dots \ n < d \ ee 0 < n \end{array}
```

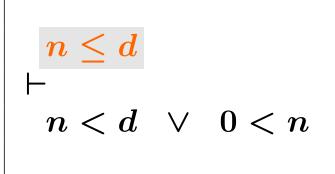
- This cannot be proved with the inference rules we have so far
- $n \leq d$ can be replaced by $n = d \lor n < d$
- We continue our proof by a case analysis:
 - case 1: n = d
 - case 2: n < d

- Proof by case analysis

$$\frac{\mathsf{H},\mathsf{P}\;\vdash\;\mathsf{R}}{\mathsf{H},\;\mathsf{P}\;\vee\;\mathsf{Q}\;\;\vdash\;\mathsf{R}}\quad\mathsf{OR}_{\mathsf{L}}$$

- Choice for proving a disjunctive goal

MON



OR_L

```
n < d
           OR_R1 n < d \vdash n < d ?
```

- The first? seems to be obvious
- The second? can be (partially) solved by applying the equality

- The identity axiom (conclusion holds by hypothesis)

- Rewriting an equality (EQ_LR) and reflexivity of equality (EQL)

$$rac{ extsf{H(F), E = F} \; dash \; extsf{P(F)}}{ extsf{H(E), E = F} \; dash \; extsf{P(E)}} \; extsf{EQ_LR}$$

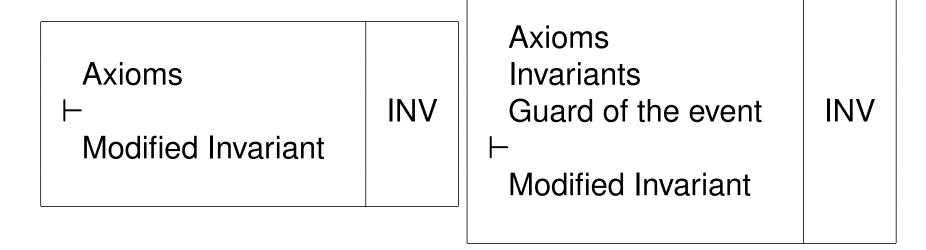
- We still have a problem: d must be positive!

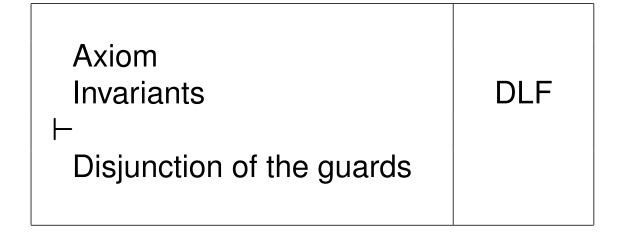
- If d is equal to 0, then no car can ever enter the Island-Bridge

 $axm0_2: 0 < d$

- Thanks to the proofs, we discovered 3 errors
- They were corrected by:
 - adding guards to both events
 - adding an axiom
- The interaction of modeling and proving is an essential element of Formal Methods with Proofs

- We have seen three kinds of proof obligations:
 - The Invariant Establishment PO: INV
 - The Invariant Preservation PO: INV
 - The Deadlock Freedom PO (optional): DLF





constant: d

variable: n

 $\mathsf{axm0}_{-}\mathsf{1} \colon d \in \mathbb{N}$

 $axm0_2: d > 0$

inv0_1: $n \in \mathbb{N}$

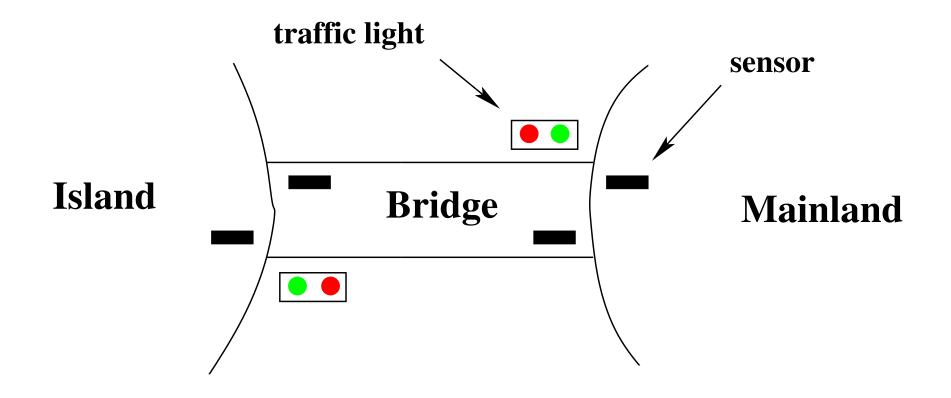
inv0_2: $n \le d$

 $\begin{array}{c} \mathrm{init} \\ n := 0 \end{array}$

 $egin{aligned} \mathsf{ML_out} \ & \mathsf{when} \ & n < d \ & \mathsf{then} \ & n := n+1 \ & \mathsf{end} \end{aligned}$

 $egin{aligned} \mathsf{ML_in} \ & \mathsf{when} \ & 0 < n \ & \mathsf{then} \ & n := n-1 \ & \mathsf{end} \end{aligned}$

- Initial model: Limiting the number of cars (FUN-2)
- First refinement: Introducing the one way bridge (FUN-3)
- Second refinement: Introducing the traffic lights (EQP-1,2,3)
- Third refinement: Introducing the sensors (EQP-4,5)

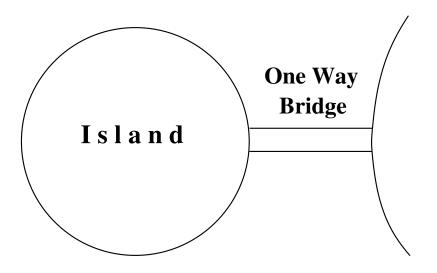


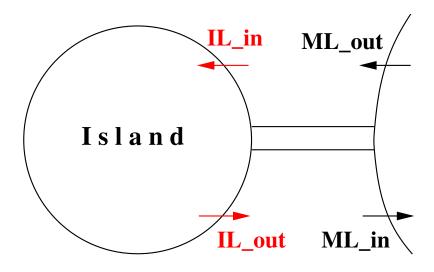
- We go down with our parachute
- Our view of the system gets more accurate

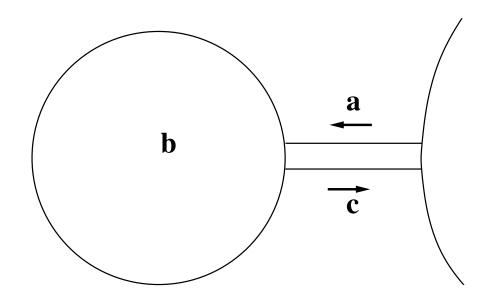
- We introduce the bridge and separate it from the island
- We refine the state and the events

- We also add two new events: IL_in and IL_out

- We are focusing on FUN-3: one-way bridge







- a denotes the number of cars on bridge going to island
- b denotes the number of cars on island
- c denotes the number of cars on bridge going to mainland
- a, b, and c are the concrete variables
- They replace the abstract variable n

Refining the State: Formalizing Variables a, b, and c 88

- Variables a, b, and c denote natural numbers

$$a \in \mathbb{N}$$

$$b \in \mathbb{N}$$

$$c \in \mathbb{N}$$

- Relating the concrete state (a, b, c) to the abstract state (n)

$$a+b+c=n$$

- Formalizing the new invariant: one way bridge (this is FUN-3)

$$a=0 \quad \lor \quad c=0$$

constants: d

variables: a, b, c

inv1_1: $a \in \mathbb{N}$

inv1_2: $b \in \mathbb{N}$

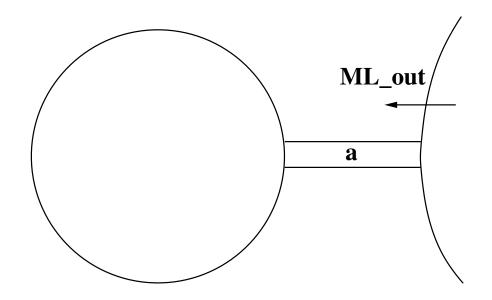
inv1_3: $c \in \mathbb{N}$

inv1_4: a + b + c = n

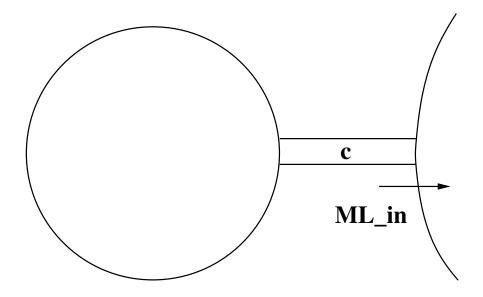
inv1_5: $a = 0 \lor c = 0$

- Invariants inv1_1 to inv1_5 are called the concrete invariants

- inv1_4 glues the abstract state, n, to the concrete state, a, b, c



$$egin{aligned} \mathsf{ML_out} \ \mathsf{when} \ a+b < d \ c = 0 \ \mathsf{then} \ a := a+1 \ \mathsf{end} \end{aligned}$$



 $egin{array}{ll} \mathsf{ML}_{}\mathsf{in} \\ \mathsf{when} \\ 0 < c \\ \mathsf{then} \\ c := c-1 \\ \mathsf{end} \\ \end{array}$

```
egin{aligned} \mathsf{ML\_out} \ & \mathsf{when} \ & a+b < d \ & c = 0 \ & \mathsf{then} \ & a := a+1 \ & \mathsf{end} \end{aligned}
```

$$egin{aligned} \mathsf{ML_in} \ & \mathsf{when} \ & 0 < c \ & \mathsf{then} \ & c := c - 1 \ & \mathsf{end} \end{aligned}$$

Before-after predicates showing the unmodified variables:

$$a' = a + 1 \wedge b' = b \wedge c' = c$$

$$a' = a \wedge b' = b \wedge c' = c - 1$$

The concrete model behaves as specified by the abstract model (i.e., concrete model does not exhibit any new behaviors)

To show this we have to prove that

- every concrete event is simulated by its abstract counterpart (event refinement: following slides)
- 2. to every concrete initial state corresponds an abstract one (initial state refinement: later)

We will make these two conditions more precise and formalize them as proof obligations.

```
egin{array}{c} ({\sf abstract}\_){\sf ML}\_{\sf out} \ {\sf when} \ n < d \ {\sf then} \ n := n+1 \ {\sf end} \ \end{array}
```

```
egin{aligned} (	exttt{concrete}\_) 	exttt{ML\_out} \ 	exttt{when} \ & a+b < d \ & c=0 \ & 	exttt{then} \ & a := a+1 \ & 	exttt{end} \end{aligned}
```

- The concrete version is not contradictory with the abstract one
- When the concrete version is enabled then so is the abstract one

- Executions seem to be compatible

```
egin{array}{c} ({\sf abstract}\_){\sf ML}\_{\sf in} \ {\sf when} \ 0 < n \ {\sf then} \ n := n-1 \ {\sf end} \end{array}
```

```
egin{aligned} (	ext{concrete}\_) 	ext{ML\_in} \ & 	ext{when} \ & 0 < c \ & 	ext{then} \ & c := c - 1 \ & 	ext{end} \end{aligned}
```

- Same remarks as in the previous slide
- But this has to be confirmed by well-defined proof obligations

- The concrete guard is stronger than the abstract one

- Each concrete action is compatible with its abstract counterpart

Constants c with axioms A(c)

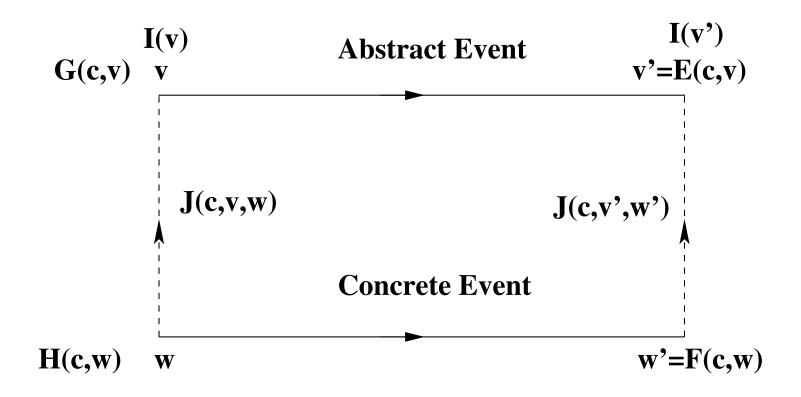
Abstract variables v with abstract invariant I(c, v)

Concrete variables w with concrete invariant J(c, v, w)

Abstract event with guards G(c,v): $G_1(c,v), G_2(c,v), \ldots$

Abstract event with before-after predicate $v^\prime = E(c,v)$

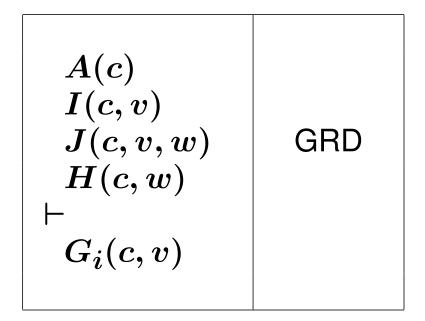
Concrete event with guards H(c,w) and b-a predicate w'=F(c,w)



- 1. The concrete guard is stronger than the abstract one (Guard Strengthening, following slides)
- 2. Each concrete action is simulated by its abstract counterpart (Concrete Invariant Preservation, later)

Axioms
Abstract Invariant
Concrete Invariant
Concrete Guard

Abstract Guard



- ML_out / GRD

- ML_in / GRD

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Concrete guards of ML_out

Abstract guard of ML_out
```

```
egin{array}{l} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a+b+c=n \ a=0 \ \lor \ c=0 \ a+b < d \ c=0 \end{array}
```

ML_out / GRD

```
(abstract-)ML_out when n < d then n := n+1 end
```

```
egin{aligned} (	ext{concrete-}) \mathsf{ML\_out} \ & \mathbf{when} \ & a+b < \mathbf{d} \ & \mathbf{c} = 0 \ & \mathbf{then} \ & a := a+1 \ & \mathbf{end} \end{aligned}
```

$$\begin{array}{c} d \in \mathbb{N} \\ 0 < d \\ n \in \mathbb{N} \\ n \leq d \\ a \in \mathbb{N} \\ b \in \mathbb{N} \\ c \in \mathbb{N} \\ a = 0 \ \lor \ c = 0 \\ a + b < d \\ c = 0 \\ h \\ n < d \end{array} \right.$$

$$\begin{array}{c} a + b + c = n \\ a + b < d \\ h \\ n < d \end{array} \right.$$

$$\begin{array}{c} a + b + c = n \\ a + b < d \\ h \\ n < d \end{array} \right.$$

$$\begin{array}{c} a + b + 0 = n \\ a + b < d \\ h \\ n < d \end{array} \right.$$

$$\begin{array}{c} a + b + 0 = n \\ a + b < d \\ h \\ n < d \end{array} \right.$$

$$\begin{array}{c} a + b + 0 = n \\ a + b < d \\ h \\ n < d \end{array} \right.$$

$$\begin{array}{c} a + b + 0 = n \\ a + b < d \\ h \\ n < d \end{array} \right.$$

$$\dots \begin{vmatrix} a+b=n \\ a+b < d \\ \vdash \\ n < d \end{vmatrix} \mathsf{EQ_LR} \begin{bmatrix} n < d \\ \vdash \\ n < d \end{vmatrix} \mathsf{HYP}$$

The "rule" name ARITH stands for simple arithmetic simplifications.

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Concrete guard of ML_in

Abstract guard of ML_in
```

```
egin{array}{l} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a + b + c = n \ a = 0 \ \lor \ c = 0 \ 0 < c \ dots \ - \ 0 < n \ \end{array}
```

ML_in / GRD

$$egin{array}{lll} d \in \mathbb{N} & \ 0 < d & \ n \in \mathbb{N} & \ n \leq d & \ a \in \mathbb{N} & \ b \in \mathbb{N} & \ c \in \mathbb{N} & \ a + b + c = n & \ a = 0 & \lor & c = 0 & \ 0 < c & \ dots & \ & \ \end{array}$$

MON $egin{array}{c} b \in \mathbb{N} \ a+b+c=n \ \hline a=0 & \lor & c=0 \ 0 < c \end{array}$

$$egin{array}{c} a = 0 & \lor & c = 0 \\ 0 < c & & & \\ 0 < n & & & \\ \end{array}$$

$$egin{array}{l} b \in \mathbb{N} \ a+b+c=n \ \hline egin{array}{c} a=0 \ 0 < c \ \vdash \ 0 < n \end{array} \end{array}$$
 EQ_LR \ldots

$$egin{array}{l} b \in \mathbb{N} \ a+b+c=n \ \hline egin{array}{c} c = 0 \ 0 < c \ \vdash \ 0 < n \end{array} \end{array}$$
 EQ_LR \ldots

MON

$$egin{array}{ll} b \in \mathbb{N} \ a+b+c=n \ \hline a=0 & \lor & c=0 \ 0 < c \ \hline 0 < n \end{array}$$
 ORL

$$egin{array}{c} b \in \mathbb{N} \\ a+b+c=n \\ \hline a=0 \\ 0 < c \\ dash \\ 0 < n \end{array} \hspace{0.5cm} ext{EQ_LR} \ \ldots$$

$$egin{array}{l} b \in \mathbb{N} \ a+b+c=n \ \hline egin{array}{c} c = 0 \ 0 < c \ dots \ 0 < n \end{array} \end{array}$$
 EQ.LR \ldots

$$\begin{array}{c|c} b \in \mathbb{N} \\ \hline 0+b+c=n \\ 0 < c \\ \vdash \\ 0 < n \end{array}$$

ARITH

$$egin{array}{c} oldsymbol{b} \in \mathbb{N} \ oldsymbol{b} + oldsymbol{c} = oldsymbol{n} \ 0 < oldsymbol{c} \ oldsymbol{b} \ 0 < oldsymbol{n} \end{array}$$

ARITH

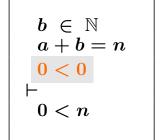
$$egin{array}{c} c \leq n \ 0 < c \ dots \ 0 < n \end{array}$$

ARITH

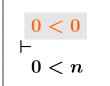
$$egin{bmatrix} 0 < n \ \vdash \ 0 < n \ \end{bmatrix}$$
 HYP

$$\begin{array}{c|c}
b \in \mathbb{N} \\
\hline
a+b+0=n \\
0<0 \\
\vdash \\
0< n
\end{array}$$

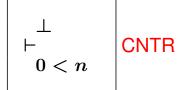
ARITH



MON

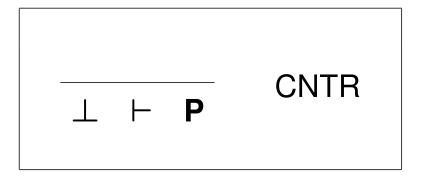


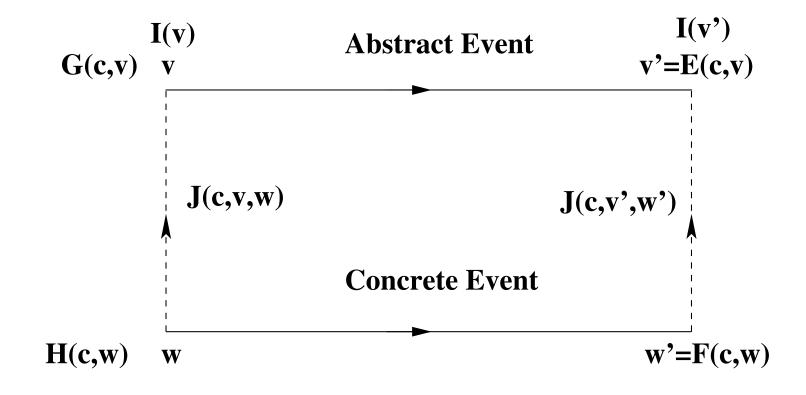
ARITH



- In the previous proof, we have used and additional inference rule

- It says that a false hypothesis entails any goal





Axioms
Abstract Invariants
Concrete Invariants
Concrete Guards

 \vdash

Modified Concrete Invariant

```
egin{array}{c} A(c) \ I(c,v) \ J(c,v,w) \ H(c,w) \ dots \ J_j(c,E(c,v),F(c,w)) \end{array}
```

- ML_out / GRD done

- ML_in / GRD done

- ML_out / inv1_4 / INV

- ML_out / inv1_5 / INV

- ML_in / inv1_4 / INV

- ML_in / inv1_5 / INV

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Concrete guards of ML_out
```

Modified Invariant inv1_4

```
egin{array}{l} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a + b + c = n \ a = 0 \ \lor \ c = 0 \ a + b < d \ c = 0 \ dots \ - \ & + 1 + b + c = n + 1 \end{array}
```

ML_out / inv1_4 / INV

```
(abstract-)ML_out when n < d then n := n+1 end
```

```
\begin{array}{c} (\mathsf{concrete}\text{-})\mathsf{ML}\text{-}\mathsf{out}\\ & \mathbf{when}\\ & a+b < d\\ & c=0\\ & \mathbf{then}\\ & a:=a+1\\ & \mathbf{end} \end{array}
```

MON

$$a+b+c=n$$
 $+a+1+b+c=n+1$
ARITH ...

$$\begin{array}{c|c} a+b+c=n \\ \vdash \\ a+b+c+1=n+1 \end{array}$$

$$\mathsf{EQ}_{\mathsf{L}}\mathsf{LR} \hspace{0.2cm} dash n+1=n+1 \hspace{0.2cm} \mathsf{EQL}$$

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Concrete guards of ML_out
```

Modified Invariant inv1_5

```
egin{array}{l} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a + b + c = n \ a = 0 \ \lor \ c = 0 \ a + b < d \ c = 0 \ dots \ + 1 = 0 \ \lor \ c = 0 \end{array}
```

ML_out / inv1_5 / INV

```
\mathsf{cabstract}	ext{-}\mathsf{)ML}	ext{-}\mathsf{out} \mathsf{cut} \mathsf{cut}
```

```
egin{aligned} (	ext{concrete-}) \mathsf{ML\_out} \ & \mathbf{when} \ & a+b < d \ & c=0 \ & \mathbf{then} \ & \mathbf{a} := a+1 \ & \mathbf{end} \end{aligned}
```

```
egin{array}{l} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a + b + c = n \ a = 0 \ \lor \ c = 0 \ a + b < d \ \hline c = 0 \ dots \ + 1 = 0 \ \lor \ c = 0 \ \end{array}
```

MON
$$c=0$$
 $c=0$ $c=0$ $c=0$

$$egin{array}{c|c} \mathsf{OR_R2} & c=0 \ c=0 \end{array} \hspace{0.2cm} \mathsf{HYP}$$

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Concrete guards of ML_in

Modified Invariant inv1_4
```

```
egin{array}{l} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a + b + c = n \ a = 0 \ \lor \ c = 0 \ 0 < c \ dots \ a + b + c - 1 = n - 1 \end{array}
```

ML_in / inv1_4 / INV

```
(abstract-)ML_in when 0 < n then n := n-1 end
```

```
(	ext{concrte-}) \mathsf{ML}_{	ext{in}} \mathbf{when} 0 < c \mathbf{then} c := c - 1 \mathbf{end}
```

MON
$$\begin{vmatrix} a+b+c=n \\ +a+b+c-1=n-1 \end{vmatrix}$$
 EQLR $\begin{vmatrix} -n-1=n-1 \\ +n-1=n-1 \end{vmatrix}$ EQL

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Concrete guards of ML_in

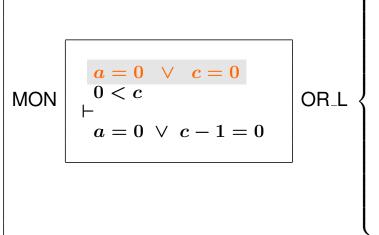
Modified Invariant inv1_5
```

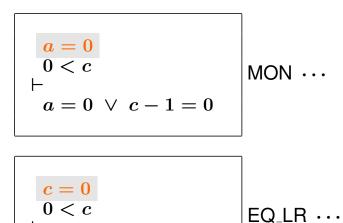
```
egin{array}{l} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a+b+c=n \ a=0 \ \lor \ c=0 \ 0 < c \end{array}
```

ML_in / inv1_5 / INV

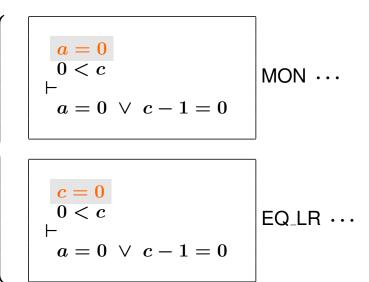
```
\begin{array}{c} (\mathsf{concrete}\text{-})\mathsf{ML}\text{-}\mathsf{in} \\ \quad \mathsf{when} \\ \quad 0 < c \\ \quad \mathsf{then} \\ \quad c := c-1 \\ \quad \mathsf{end} \end{array}
```

```
egin{array}{l} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a+b+c=n \ \hline a=0 & \lor & c=0 \ 0 < c \ \hline \vdash \ a=0 & \lor & c-1=0 \end{array}
```





 $a=0 \ \lor \ c-1=0$



$$\begin{cases} & \dots & \begin{vmatrix} a=0 \\ & -1 \end{vmatrix} & = 0 \\ & -1 \end{vmatrix} & = 0 \end{cases} \lor c-1 = 0$$
 OR_R1
$$\begin{vmatrix} a=0 \\ & -1 \end{vmatrix} & = 0 \\ & -1 \end{vmatrix} = 0$$
 OR_R1
$$\begin{vmatrix} a=0 \\ & -1 \end{vmatrix} + a = 0 \\ & -1 \end{vmatrix} = 0$$
 OR_R1
$$\begin{vmatrix} a=0 \\ & -1 \end{vmatrix} + a = 0 \\ & -1 \end{vmatrix} = 0$$
 CNTR

- Concrete initialization

$$\begin{array}{c} \text{init} \\ a := 0 \\ b := 0 \\ c := 0 \end{array}$$

- Corresponding after predicate

$$a'=0 \ \wedge \ b'=0 \ \wedge \ c'=0$$

Constants c with axioms A(c)

Concrete invariant J(c, v, w)

Abstract initialization with after predicate v' = K(c)

Concrete initialization with after predicate w' = L(c)

Axioms A(c) \vdash Modified concrete invariants $J_j(c,K(c),L(c))$

$$A(c) \ dash \ J_j(c,K(c),L(c))$$

INV

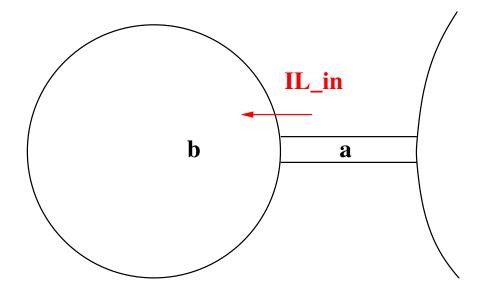
- ML_out / GRD done
- ML_in / GRD done
- ML_out / inv1_4 / INV done
- ML_out / inv1_5 / INV done
- ML_in / inv1_4 / INV done
- ML_in / inv1_5 / INV done
- inv1_4 / INV
- inv1_5 / INV

```
egin{array}{l} {\sf axm0\_1} \\ {\sf axm0\_2} \\ {\vdash} \\ {\sf Modified concrete invariant inv1\_4} \\ (a+b+c=n) \end{array}
```

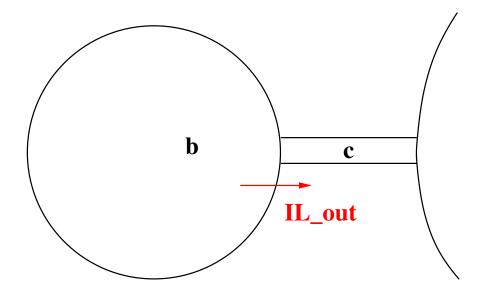
$$d\in\mathbb{N} \ d>0 \ \vdash \ 0+0+0=0$$

```
axm0_1
axm0_2
\vdash
Modified concrete invariant <math>inv1_5
(a = 0 \lor c = 0)
```

- new events add transitions that have no abstract counterpart
- can be seen as a kind of internal steps (w.r.t. abstract model)
- can only be seen by an observer who is "zooming in"
- temporal refinement: refined model has a finer time granularity



 $egin{aligned} \mathsf{IL}_\mathsf{in} \\ \mathsf{when} \\ 0 < a \\ \mathsf{then} \\ a := a - 1 \\ b := b + 1 \\ \mathsf{end} \end{aligned}$



$$egin{aligned} \mathsf{IL_out} \\ \mathsf{when} \\ 0 < b \\ a = 0 \\ \mathsf{then} \\ b := b - 1 \\ c := c + 1 \\ \mathsf{end} \end{aligned}$$

```
\mathsf{IL}_{\mathsf{in}} when 0 < a then a := a - 1 b := b + 1 end
```

$$egin{aligned} \mathsf{IL_out} \\ \mathsf{when} \\ 0 < b \\ a = 0 \\ \mathsf{then} \\ b := b - 1 \\ c := c + 1 \\ \mathsf{end} \end{aligned}$$

Before-after predicates

$$a'=a+1 \ \wedge \ b'=b+1 \ \wedge \ c'=c$$
 $a'=a \ \wedge \ b'=b-1 \ \wedge \ c'=c+1$

The before-after predicate of skip in the initial model

$$n'=n$$

The before-after predicate of skip in the first refinement

$$a'=a \wedge b'=b \wedge c'=c$$

The guard of the skip event is true.

- (1) A new event must refine an implicit event, made of a skip action
 - Guard strengthening is trivial
 - Need to prove invariant refinement
- (2) The new events must not diverge
 - To prove this we have to exhibit a variant
 - The variant yields a natural number (could be more complex)
 - Each new event must decrease this variant

- ML_out / GRD done
- ML_in / GRD done
- ML_out / inv1_4 / INV done
- ML_out / inv1_5 / INV done
- ML_in / inv1_4 / INV done
- ML_in / inv1_5 / INV done
- inv1 4 / INV done
- inv1_5 / INV done
- IL in / inv1 4 / INV
- IL_in / inv1_5 / INV
- IL_out / inv1_4 / INV
- IL_out / inv1_5 / INV

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Concrete guards of IL_in

Modified Invariant inv1_4
```

```
egin{array}{lll} d \in \mathbb{N} & \ 0 < d & \ n \in \mathbb{N} & \ n \leq d & \ a \in \mathbb{N} & \ b \in \mathbb{N} & \ c \in \mathbb{N} & \ a + b + c = n & \ a = 0 & \lor & c = 0 & \ 0 < a & \ dots & \ - & \ - & \ - & \ 1 + b + 1 + c = n & \ \end{array}
```

IL_in / inv1_4 / INV

```
\mathsf{IL}\_\mathsf{in}
\mathsf{when}
0 < a
\mathsf{then}
a := a - 1
b := b + 1
\mathsf{end}
```

MON
$$\begin{vmatrix} a+b+c=n \\ -a-1+b+1+c=n \end{vmatrix}$$
 ARITH $\begin{vmatrix} a+b+c=n \\ -a+b+c=n \end{vmatrix}$ HYP

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Concrete guards of IL_in

Modified Invariant inv1_5
```

```
egin{array}{lll} d \in \mathbb{N} & \ 0 < d & \ n \in \mathbb{N} & \ n \leq d & \ a \in \mathbb{N} & \ b \in \mathbb{N} & \ c \in \mathbb{N} & \ a + b + c = n & \ a = 0 & \lor & c = 0 & \ 0 < a & \ dots & \ -1 = 0 & \lor & c = 0 & \ \end{array}
```

IL_in / inv1_5 / INV

```
\mathsf{IL}in \mathsf{when} 0 < a \mathsf{then} a := a - 1 b := b + 1 \mathsf{end}
```

```
egin{array}{lll} d \in \mathbb{N} & \ 0 < d & \ n \in \mathbb{N} & \ n \leq d & \ a \in \mathbb{N} & \ b \in \mathbb{N} & \ c \in \mathbb{N} & \ a+b+c=n & \ \hline a=0 & \lor & c=0 & \ 0 < a & \ dots & \ -1=0 & \lor & c=0 & \ \end{array}
```

MON $\begin{vmatrix} a=0 & \lor & c=0 \\ 0 < a \\ \vdash & a-1=0 & \lor & c=0 \end{vmatrix}$ OR_L ...

```
egin{array}{l} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a+b+c=n \ \hline a=0 \ \lor \ c=0 \ 0 < a \ \hline +a-1=0 \ \lor \ c=0 \ \end{array}
```

MON $\begin{vmatrix} a=0 & \lor & c=0 \\ 0 < a \\ \vdash & a-1=0 & \lor & c=0 \end{vmatrix}$ OR_L ...

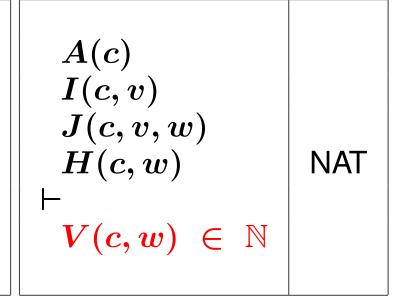
a = 00 < 00 < aEQ_LR ARITH **CNTR** $-1 = 0 \quad \lor \quad c = 0$ $-1 = 0 \quad \lor \quad c = 0$ $a-1=0 \quad \lor \quad c=0$ c = 0c = 0MON OR_{R2} HYP $c=0 \vdash c=0$ $a-1=0 \quad \lor \quad c=0$ $a-1=0 \quad \lor \quad c=0$

Axioms A(c), invariants I(c,v), concrete invariant J(c,v,w)

New event with guard $oldsymbol{H}(oldsymbol{c},oldsymbol{w})$

Variant V(c, w)

Axioms
Abstract invariants
Concrete invariants
Concrete guard of a new event \vdash Variant $\in \mathbb{N}$



Axioms A(c), invariants I(c,v), concrete invariant J(c,v,w)

New event with guard H(c,w) and b-a predicate w'=F(c,w)

Variant V(c, w)

Axioms
Abstract invariants
Concrete invariants
Concrete guard

Modified Var. < Var.

```
egin{array}{c} A(c) \ I(c,v) \ J(c,v,w) \ H(c,w) \ dots \ V(c,F(c,w)) < V(c,w) \end{array}
```

variant_1: 2*a+b

- Weighted sum of $\,a\,$ and $\,b\,$

```
-ML_out / GRD done
```

- —ML_in / GRD done
- -ML_out / inv1_4 / INV done
- -ML_out / inv1_5 / INV done
- -ML_in / inv1_4 / INV done
- -ML_in / inv1_5 / INV done
- -inv1_4 / INV done
- -inv1_5 / INV done
- —IL_in / inv1_4 / INV done
- —IL_in / inv1_5 / INV done
- -IL_out / inv1_4 / INV done
- —IL_out / inv1_5 / INV done

- —IL_in / NAT
- —IL_out / NAT
- $-IL_in / VAR$
- -IL_out / VAR

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Concrete guard of IL_in

Modified variant < Variant
```

```
egin{array}{l} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a+b+c=n \ a=0 \ \lor \ c=0 \ 0 < a \ dots \ \end{array}
```

IL_in / VAR

```
egin{aligned} \mathsf{IL}\ \mathsf{in} \\ \mathbf{when} \\ 0 < a \\ \mathsf{then} \\ a &:= a-1 \\ b &:= b+1 \\ \mathsf{end} \end{aligned}
```

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Concrete guards of IL_out
```

Modified variant < Variant

```
egin{array}{ll} d \in \mathbb{N} \ 0 < d \ n \in \mathbb{N} \ n \leq d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ a+b+c=n \ a=0 \ \lor \ c=0 \ 0 < b \ a=0 \ dots \ - \ 2*a+b-1 < 2*a+b \end{array}
```

IL_out / VAR

```
\begin{array}{c} \mathsf{IL\_out} \\ \mathbf{when} \\ 0 < b \\ a = 0 \\ \mathbf{then} \\ b := b - 1 \\ c := c + 1 \\ \mathbf{end} \end{array}
```

There a no new deadlocks in the concrete model, that is, all deadlocks of the concrete model are already present in the abstract model.

Proof obligation requires that whenever some abstract event is enabled then so is some concrete event.

This proof obligation is optional (depending on system under study).

The $G_i(c,v)$ are the abstract guards

The $H_i(c,v)$ are the concrete guards

If some abstract guard is true then so is some concrete guard:

$$A(c) \ I(c,v) \ J(c,v,w) \ G_1(c,v) ee \dots ee G_m(c,v) \ dash H_1(c,w) ee \dots ee H_n(c,w)$$
 DLF

```
axm0_1
axm0_2
inv0_1
inv0_2
inv1_1
inv1_2
inv1_3
inv1_4
inv1_5
Disjunction of abstract guards

—
Disjunction of concrete guards
```

DLF

```
egin{aligned} \mathsf{ML\_out} \\ \mathsf{when} \\ a+b < d \\ c=0 \\ \mathsf{then} \\ a:=a+1 \\ \mathsf{end} \end{aligned}
```

```
egin{aligned} \mathsf{ML\_in} & & \mathsf{when} \\ & c > 0 \\ & \mathsf{then} \\ & c := c - 1 \\ & \mathsf{end} \end{aligned}
```

```
\begin{array}{c} \mathsf{IL\_in} \\ \mathbf{when} \\ a>0 \\ \mathbf{then} \\ a:=a-1 \\ b:=b+1 \\ \mathbf{end} \end{array}
```

```
\begin{array}{c} \mathsf{IL\_out} \\ \mathbf{when} \\ b>0 \\ a=0 \\ \mathbf{then} \\ b:=b-1 \\ c:=c+1 \\ \mathbf{end} \end{array}
```

$$\frac{\mathbf{H}, \neg \mathbf{P} \vdash \mathbf{Q}}{\mathbf{H} \vdash \mathbf{P} \lor \mathbf{Q}} \quad \mathsf{NEG}$$

$$\frac{\mathsf{H},\mathsf{P},\mathsf{Q}\;\vdash\;\mathsf{R}}{\mathsf{H},\;\mathsf{P}\land\mathsf{Q}\;\vdash\;\mathsf{R}}\quad\mathsf{AND}_{\mathsf{L}}$$

Proof of DLF

```
egin{array}{lll} d \in \mathbb{N} & 0 < d & \\ n \in \mathbb{N} & \\ n \leq d & \\ \hline a \in \mathbb{N} & \\ b \in \mathbb{N} & \\ \hline c \in \mathbb{N} & \\ \hline a + b + c = n & \\ a = 0 & \lor & c = 0 & \\ \hline n > 0 & \lor & n < d & \\ \hline \vdash & (a + b < d \ \land \ c = 0) & \lor & \\ c > 0 & \lor & \\ a > 0 & \lor & \\ (b > 0 \ \land \ a = 0) & \\ \hline \end{array}
```

MON

```
egin{array}{lll} a & \in & \mathbb{N} \\ c & \in & \mathbb{N} \\ a+b+c=n \\ n>0 & \lor & n < d \\ dash \\ (a+b < d \ \land \ c=0) & \lor \\ \hline c>0 & \lor \\ a>0 & \lor \\ (b>0 \ \land \ a=0) \\ \end{array}
```

NEG

```
a \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
n>0 \ \lor \ n < d
c \in \mathbb{N}
c \in
```

```
egin{array}{lll} d \in \mathbb{N} & 0 < d & \\ n \in \mathbb{N} & \\ n \leq d & \\ \hline a \in \mathbb{N} & \\ b \in \mathbb{N} & \\ \hline c \in \mathbb{N} & \\ \hline a + b + c = n & \\ a = 0 & \lor & c = 0 & \\ \hline n > 0 & \lor & n < d & \\ \hline (a + b < d \ \land \ c = 0) & \lor & \\ c > 0 & \lor & \\ a > 0 & \lor & \\ (b > 0 \ \land \ a = 0) & \\ \hline \end{array}
```

NEG

```
\begin{array}{c|c} a \in \mathbb{N} \\ \hline c \in \mathbb{N} \\ a+b+c=n \\ n>0 \ \lor \ n < d \\ \hline \neg \ (c>0) \\ \vdash \\ (a+b < d \ \land \ c=0) \ \lor \\ a>0 \ \lor \\ (b>0 \ \land \ a=0) \end{array}
```

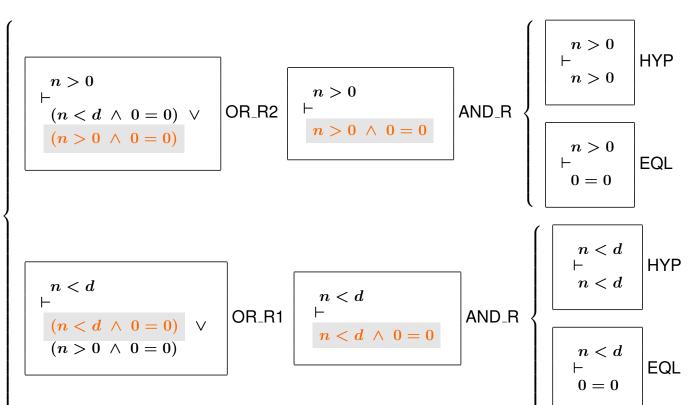
ARITH ...

EQ.LR
$$\begin{vmatrix} \mathbf{0} + \mathbf{b} + \mathbf{0} &= n \\ n > 0 & \lor & n < d \\ \vdash & & & \\ \mathbf{0} + \mathbf{b} &< d \ \land \ 0 = 0) \ \lor \\ (b > 0 \ \land \ 0 = 0) \ \end{vmatrix}$$

ARITH

$$\begin{vmatrix} b = n \\ n > 0 & \lor & n < d \\ \vdash & (b < d \land 0 = 0) & \lor \\ (b > 0 \land 0 = 0) & \lor & \end{aligned}$$
 EQ_LR ...

ARITH



```
-ML_out / GRD done
```

- —ML_in / GRD done
- -ML_out / inv1_4 / INV done
- -ML_out / inv1_5 / INV done
- —ML_in / inv1_4 / INV done
- —ML_in / inv1_5 / INV done
- -inv1_4 / INV done
- -inv1_5 / INV done
- —IL_in / inv1_4 / INV done
- —IL_in / inv1_5 / INV done
- -IL_out / inv1_4 / INV done
- —IL_out / inv1_5 / INV done

- —IL_in / NAT done
- —IL_out / NAT done
- —IL_in / VAR done
- —IL_out / VAR done
- -DLF done

- For old events:
 - Strengthening of guards: GRD
 - Concrete invariant preservation: INV
- For new events:
 - Refining the implicit skip event: INV
 - Absence of divergence: NAT and VAR
- For all events:
 - Relative deadlock freedom: DLF

Axioms
Abstract invariants
Concrete invariants
Concrete guards

Abstract guard

Axioms
Abstract invariants
Concrete invariants
Concrete guard
Modified concrete invariant

Axioms

Modified concrete invariant

Axioms
Abstract invariants
Concrete invariants
Concrete guards of a new event \vdash Variant $\in \mathbb{N}$

Axioms
Abstract invariants
Concrete invariants
Concrete guards of a new event

Modified variant < Variant

Axioms
Abstract invariants
Concrete invariants
Disjunction of abstract events guards

Disjunction of concrete events guards

constants: d

variables: a, b, c

inv1_1: $a \in \mathbb{N}$

inv1_2: $b \in \mathbb{N}$

inv1_3: $c \in \mathbb{N}$

inv1_4: a + b + c = n

inv1_5: $a=0 \lor c=0$

variant1: 2*a+b

```
\begin{array}{c} \text{init} \\ a := 0 \\ b := 0 \\ c := 0 \end{array}
```

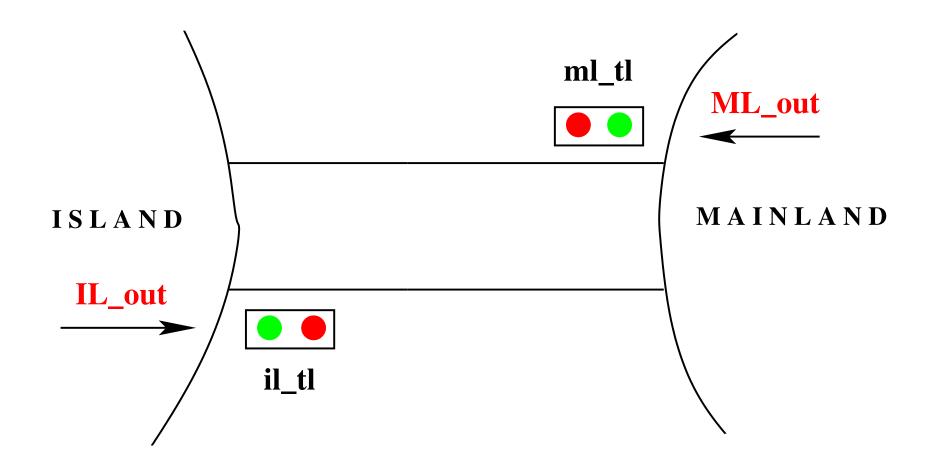
```
\mathsf{ML}in \mathsf{when} 0 < c \mathsf{then} c := c - 1 \mathsf{end}
```

```
egin{aligned} \mathsf{ML\_out} \ & \mathsf{when} \ & a+b < d \ & c = 0 \ & \mathsf{then} \ & a := a+1 \ & \mathsf{end} \end{aligned}
```

```
\mathsf{IL}_{\mathsf{in}} when 0 < a then a := a - 1 b := b + 1 end
```

```
egin{aligned} \mathsf{IL\_out} \\ \mathsf{when} \\ 0 < b \\ a = 0 \\ \mathsf{then} \\ b := b-1 \\ c := c+1 \\ \mathsf{end} \end{aligned}
```

- Initial model: Limiting the number of cars (FUN-2)
- First refinement: Introducing the one way bridge (FUN-3)
- Second refinement: Introducing the traffic lights (EQP-1,2,3)
- Third refinement: Introducing the sensors (EQP-4,5)



set: COLOR

constants: red, green

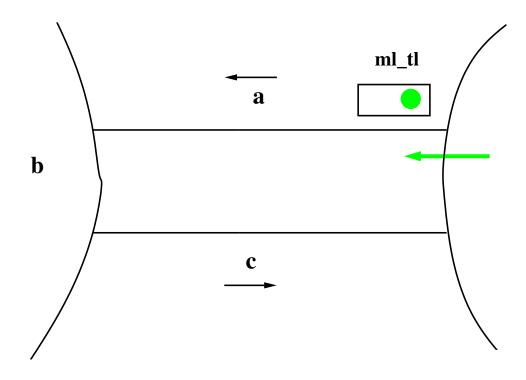
 $axm2_1: COLOR = \{green, red\}$

 $axm2_2$: $green \neq red$

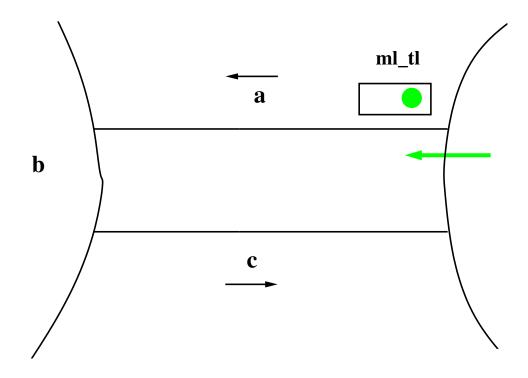
$$il_tl \in COLOR$$

$$ml_tl \in COLOR$$

Remark: Events IL_in and ML_in are not modified in this refinement

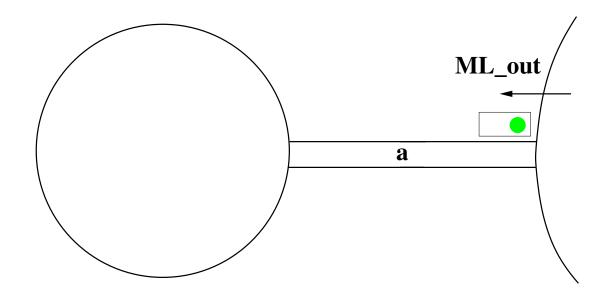


- A green mainland traffic light implies safe access to the bridge

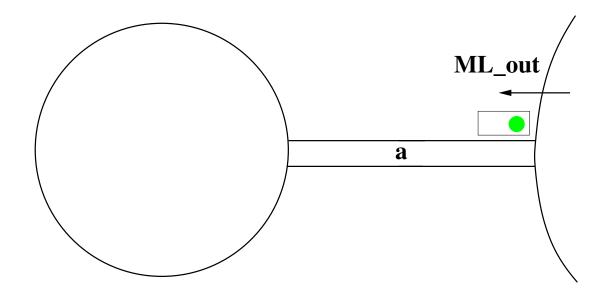


- A green mainland traffic light implies safe access to the bridge

$$ml_tl = {\sf green} \ \Rightarrow \ c = 0 \ \land \ a+b < d$$

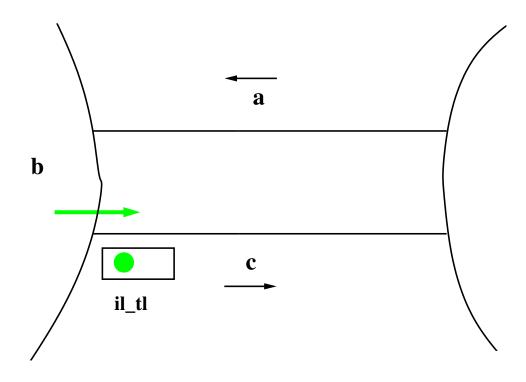


```
({f abstract}_{-}){f ML}_{-}{f out} when c=0 a+b < d then a:=a+1 end
```

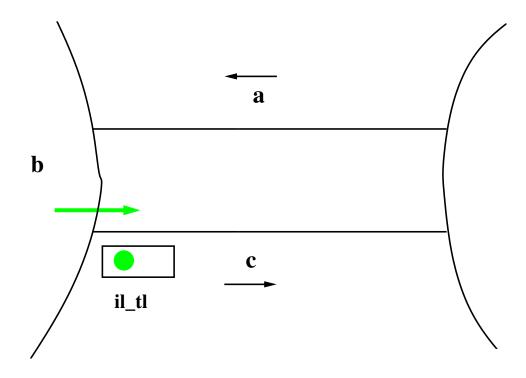


```
({\sf abstract}\_){\sf ML}\_{\sf out} {\sf when} {\it c}=0 {\it a}+{\it b}<{\it d} then {\it a}:={\it a}+1 end
```

 $egin{aligned} (ext{concrete}_) ext{ML_out} \ ext{when} \ ext{ml_tl} = ext{green} \ ext{then} \ ext{$a:=a+1$} \ ext{end} \end{aligned}$

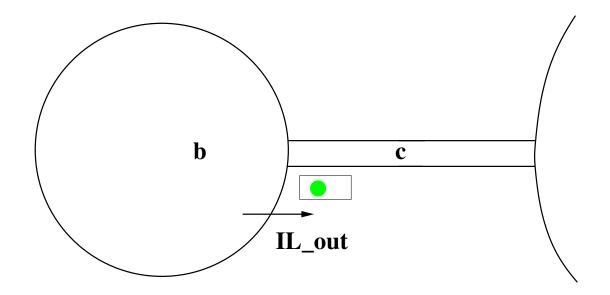


- A green island traffic light implies safe access to the bridge

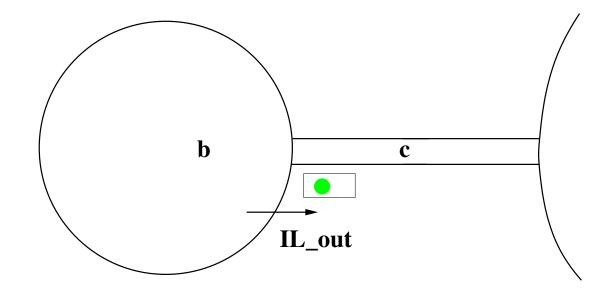


- A green island traffic light implies safe access to the bridge

$$i l_{\scriptscriptstyle -} t l = {\sf green} \ \Rightarrow \ a = 0 \ \land \ 0 < b$$



```
\begin{array}{l} (\mathsf{abstract}\_)\mathsf{IL}\_\mathsf{out} \\ \mathsf{when} \\ a = 0 \\ 0 < b \\ \mathsf{then} \\ b, c := b - 1, c + 1 \\ \mathsf{end} \end{array}
```



```
\begin{array}{l} (\mathsf{abstract}\_)\mathsf{IL}\_\mathsf{out} \\ \mathsf{when} \\ a = 0 \\ 0 < b \\ \mathsf{then} \\ b, c := b - 1, c + 1 \\ \mathsf{end} \end{array}
```

```
egin{aligned} (	ext{concrete}\_) 	ext{IL\_out} \ & 	ext{when} \ & il\_tl = 	ext{green} \ & 	ext{then} \ & b,c := b-1,c+1 \ & 	ext{end} \end{aligned}
```

```
egin{aligned} \mathsf{ML\_tl\_green} \ & \mathbf{when} \ & ml\_tl = \mathsf{red} \ & c = 0 \ & a+b < d \ & \mathsf{then} \ & ml\_tl := \mathsf{green} \ & \mathsf{end} \end{aligned}
```

```
egin{align*} 	ext{L\_tl\_green} & 	ext{when} \ il\_tl = 	ext{red} \ a = 0 \ 0 < b \ 	ext{then} \ il\_tl := 	ext{green} \ 	ext{end} \ \end{aligned}
```

- Turning lights to green when proper conditions hold

variables: a, b, c, ml_tl, il_tl

inv2_1: $ml_tl \in COLOR$

inv2_2: $il_{-}tl \in COLOR$

inv2_3: $ml_-tl = {\sf green} \ \Rightarrow \ a+b < d \ \land \ c=0$

inv2_4: $il_{-}tl = \text{green} \Rightarrow 0 < b \land a = 0$

```
egin{aligned} \mathsf{ML\_out} \ & \mathsf{when} \ & ml\_tl = \mathsf{green} \ & \mathsf{then} \ & a := a+1 \ & \mathsf{end} \end{aligned}
```

```
IL_out when il\_tl = 	ext{green} then b := b - 1 c := c + 1 end
```

Events ML_in and IL_ in are unchanged

```
\mathsf{ML} in \mathsf{when} 0 < c then c := c - 1 end
```

```
\mathsf{IL}\_\mathsf{in} when 0 < a then a := a - 1 b := b + 1 end
```

variables: a, b, c, ml_tl, il_tl

- Variables a, b, and c were present in the previous refinement

- Variables ml_tl and il_tl are superposed to a, b, and c

- We have thus to extend rule INV

```
Abstract_Event when G(c,u,v) then u:=E(c,u,v) v:=M(c,u,v) end
```

```
\mathsf{Concrete}_{-}\mathsf{Event} egin{array}{c} \mathbf{when} \\ H(c,v,w) \\ \mathbf{then} \\ v := N(c,v,w) \\ w := F(c,v,w) \\ \mathbf{end} \end{array}
```

```
Axioms
Abstract invariants
Concrete invariants
Concrete guards
⇒
Same actions on
common variables
```

```
A(c)
I(c,u,v)
J(c,u,v,w)
H(c,v,w)
\Rightarrow
M(c,u,v) = N(c,v,w)
```

SIM

- We have to apply 3 Proof Obligations:
 - GRD,
 - SIM,
 - INV

- On 4 events: ML_out, IL_out, ML_in, IL_in
- And 2 main invariants:

inv2_3: $ml_-tl = {\sf green} \ \Rightarrow \ a+b < d \ \land \ c=0$

inv2_4: $il_{-}tl = \text{green} \Rightarrow 0 < b \land a = 0$

```
\begin{array}{c} \mathsf{ML\_out} \\ \mathbf{when} \\ c = 0 \\ a + b < d \\ \mathbf{then} \\ a := a + 1 \\ \mathbf{end} \end{array}
```

```
IL_out when a=0 0 < b then b:=b-1 c:=c+1 end
```

```
egin{array}{ll} \mathsf{ML\_in} & \mathsf{when} & & & & & & \\ & 0 < c & & & & & \\ & then & & & & & \\ & c := c - 1 & & & & \\ & \mathsf{end} & & & & & \end{array}
```

```
egin{aligned} \mathsf{IL}\ \mathsf{in} \\ & \mathsf{when} \\ & 0 < a \\ & \mathsf{then} \\ & a := a-1 \\ & b := b+1 \\ & \mathsf{end} \end{aligned}
```

```
\mathsf{ML}_out \mathbf{when} ml\_tl = \mathsf{green} \mathsf{then} a := a + 1 \mathsf{end}
```

```
egin{aligned} \mathsf{IL\_out} & \mathbf{when} \\ & il\_tl = \mathsf{green} \\ & \mathbf{then} \\ & b := b-1 \\ & c := c+1 \\ & \mathsf{end} \end{aligned}
```

```
egin{aligned} \mathsf{ML\_in} & & \mathsf{when} \\ & 0 < c \\ & \mathsf{then} \\ & c := c-1 \\ & \mathsf{end} \end{aligned}
```

```
\begin{array}{c} \mathsf{IL\_in} \\ \mathbf{when} \\ 0 < a \\ \mathbf{then} \\ a := a-1 \\ b := b+1 \\ \mathbf{end} \end{array}
```

- SIM is completely trivial since the actions are the same

```
\begin{array}{c} \mathsf{ML\_out} \\ \mathbf{when} \\ c = 0 \\ a + b < d \\ \mathbf{then} \\ a := a + 1 \\ \mathbf{end} \end{array}
```

```
 \begin{array}{c} \mathsf{IL\_out} \\ \mathbf{when} \\ a = 0 \\ 0 < b \\ \mathbf{then} \\ b := b - 1 \\ c := c + 1 \\ \mathbf{end} \end{array}
```

```
egin{aligned} \mathsf{ML\_in} & & \mathsf{when} & \\ & 0 < c & \\ & \mathsf{then} & \\ & c := c-1 & \\ & \mathsf{end} & \end{aligned}
```

```
\begin{array}{c} \mathsf{IL\_in} \\ \mathbf{when} \\ 0 < a \\ \mathbf{then} \\ a := a - 1 \\ b := b + 1 \\ \mathbf{end} \end{array}
```

```
egin{aligned} \mathsf{ML\_out} & & \mathsf{when} \\ & & ml\_tl = \mathsf{green} \\ & \mathsf{then} \\ & a := a+1 \\ & \mathsf{end} \end{aligned}
```

```
egin{aligned} \mathsf{IL\_out} & \mathbf{when} \\ & \mathit{il\_tl} = \mathbf{green} \\ & \mathbf{then} \\ & b := b-1 \\ & c := c+1 \\ & \mathbf{end} \end{aligned}
```

```
egin{aligned} \mathsf{ML\_in} & & \mathsf{when} & & & & & & \\ & 0 < c & & & & & & \\ & then & & & & & & \\ & c := c - 1 & & & & & \\ & \mathsf{end} & & & & & & & \end{aligned}
```

```
\begin{array}{c} \mathsf{IL\_in} \\ \mathbf{when} \\ 0 < a \\ \mathbf{then} \\ a := a-1 \\ b := b+1 \\ \mathbf{end} \end{array}
```

- GRD is also trivial

```
inv2_3: ml\_tl = {\sf green} \ \Rightarrow \ a+b < d \ \land \ c=0 inv2_4: il\_tl = {\sf green} \ \Rightarrow \ 0 < b \ \land \ a=0
```

```
\begin{array}{c} \mathsf{ML\_out} \\ \mathbf{when} \\ c = 0 \\ a + b < d \\ \mathbf{then} \\ a := a + 1 \\ \mathbf{end} \end{array}
```

```
IL_out when a = 0 0 < b then b := b - 1 c := c + 1 end
```

```
egin{array}{ll} \mathsf{ML\_in} & \mathsf{when} & \ 0 < c & \mathsf{then} & \ c := c - 1 & \mathsf{end} & \end{array}
```

```
\begin{array}{c} \mathsf{IL\_in} \\ \mathbf{when} \\ 0 < a \\ \mathbf{then} \\ a := a - 1 \\ b := b + 1 \\ \mathbf{end} \end{array}
```

```
egin{aligned} \mathsf{ML\_out} & & & \\ & \mathbf{when} & \\ & ml\_tl = \mathsf{green} & \\ & \mathbf{then} & \\ & a := a+1 & \\ & \mathbf{end} & \end{aligned}
```

```
egin{aligned} \mathsf{IL\_out} & \mathbf{when} \\ & \mathit{il\_tl} = \mathbf{green} \\ & \mathbf{then} \\ & b := b-1 \\ & c := c+1 \\ & \mathbf{end} \end{aligned}
```

```
\mathsf{ML}in \mathsf{when} 0 < c \mathsf{then} c := c - 1 \mathsf{end}
```

```
\begin{array}{c} \mathsf{IL\_in} \\ \mathbf{when} \\ 0 < a \\ \mathbf{then} \\ a := a-1 \\ b := b+1 \\ \mathbf{end} \end{array}
```

- INV applied to ML_in and IL_in holds trivially

```
inv2_3: ml\_tl = {\sf green} \ \Rightarrow \ a+b < d \ \land \ c=0
```

inv2_4:
$$il_tl = {\sf green} \ \Rightarrow \ 0 < b \ \land \ a = 0$$

```
egin{aligned} \mathsf{ML\_out} & \mathsf{when} \\ c &= 0 \\ a+b < d \\ \mathsf{then} \\ a &:= a+1 \\ \mathsf{end} \end{aligned}
```

```
 \begin{array}{c} \mathsf{IL\_out} \\ \mathbf{when} \\ a = 0 \\ 0 < b \\ \mathbf{then} \\ b := b - 1 \\ c := c + 1 \\ \mathbf{end} \end{array}
```

```
egin{aligned} \mathsf{ML\_in} & & \mathsf{when} \\ & 0 < c \\ & \mathsf{then} \\ & c := c-1 \\ & \mathsf{end} \end{aligned}
```

```
\begin{array}{c} \mathsf{IL\_in} \\ \mathbf{when} \\ 0 < a \\ \mathbf{then} \\ a := a - 1 \\ b := b + 1 \\ \mathbf{end} \end{array}
```

```
\mathsf{ML\_out} \mathsf{when} ml\_tl = \mathsf{green} \mathsf{then} a := a + 1 \mathsf{end}
```

```
egin{aligned} \mathsf{IL\_out} & \mathbf{when} \\ & \mathit{il\_tl} = \mathsf{green} \\ & \mathbf{then} \\ & b := b-1 \\ & c := c+1 \\ & \mathbf{end} \end{aligned}
```

```
egin{aligned} \mathsf{ML\_in} & & \mathsf{when} \\ & 0 < c \\ & \mathsf{then} \\ & c := c-1 \\ & \mathsf{end} \end{aligned}
```

```
\begin{array}{c} \mathsf{IL\_in} \\ \mathbf{when} \\ 0 < a \\ \mathbf{then} \\ a := a-1 \\ b := b+1 \\ \mathbf{end} \end{array}
```

- INV applied to ML_out and IL_out raise some difficulties

- ML_out / inv2_4 / INV

- IL_out / inv2_3 / INV

- ML_out / inv2_3 / INV

- IL_out / inv2_4 / INV

- Rules about implication

$$\frac{\mathsf{H},\mathsf{P},\mathsf{Q}\;\vdash\;\mathsf{R}}{\mathsf{H},\;\mathsf{P},\;\mathsf{P}\Rightarrow\mathsf{Q}\;\vdash\;\mathsf{R}}\quad\mathsf{IMP_L}$$

$$\frac{\mathsf{H},\mathsf{P}\ \vdash \mathsf{Q}}{\mathsf{H}\ \vdash \mathsf{P} \Rightarrow \mathsf{Q}} \quad \mathsf{IMP}_{-}\mathsf{R}$$

- Rules about negation

$$\frac{\mathsf{H} \; \vdash \; \mathsf{P}}{\mathsf{H}, \; \neg \, \mathsf{P} \; \vdash \; \mathsf{Q}} \quad \mathsf{NOT}_{\mathsf{L}}\mathsf{L}$$

```
axm0_1
axm<sub>0</sub> 2
axm2 1
axm2 2
inv0 1
inv<sub>0</sub> 2
inv1 1
inv1_2
inv1 3
inv1 4
inv1_5
inv2 1
inv2 2
inv23
inv2 4
Guard of event ML out
Modified invariant inv2_4
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n \in \mathbb{N}
\begin{matrix} n \leq d \\ a \in \mathbb{N} \end{matrix}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = {\sf green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = \text{green} \implies 0 < b \land a = 0
ml_{-}tl = green
il_{-}tl = green \Rightarrow 0 < b \wedge a + 1 = 0
```

ML_out / inv2_4 / INV

```
\mathsf{ML}_out \mathsf{when} ml\_tl = \mathsf{green} then a := a + 1 end
```

```
d \in \mathbb{N}
0 < d
COLOR = \{ green, red \}
green \neq red
n\in\mathbb{N}
n \le d
a\in\mathbb{N}
b \in \mathbb{N}
c\in\mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il\_tl \in COLOR
ml_{-}tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = green \Rightarrow 0 < b \land a = 0
ml_-tl={\sf green}
il_{-}tl = \text{green} \implies 0 < b \land a + 1 = 0
```

```
egin{aligned} \mathsf{MON} & egin{aligned} \mathsf{green} 
eq \mathsf{red} \ il\_tl = \mathsf{green} \ \Rightarrow \ 0 < b \ \land \ a = 0 \ ml\_tl = \mathsf{green} \ dots \ il\_tl = \mathsf{green} \ \Rightarrow \ 0 < b \ \land \ a + 1 = 0 \end{aligned} egin{aligned} \mathsf{IMP\_R} \cdots \ \mathsf{IMP\_R} \end{aligned}
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n\in\mathbb{N}
n \le d
a\in\mathbb{N}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = \text{green} \implies 0 < b \land a = 0
ml_-tl = {\sf green}
il_{-}tl = \text{green} \implies 0 < b \land a + 1 = 0
```

```
\begin{array}{c|c} \mathsf{green} \neq \mathsf{red} \\ il\_tl = \mathsf{green} \ \Rightarrow \ 0 < b \ \land \ a = 0 \\ ml\_tl = \mathsf{green} \\ \vdash \\ il\_tl = \mathsf{green} \ \Rightarrow \ 0 < b \ \land \ a + 1 = 0 \end{array} \qquad \mathsf{IMP\_R} \cdots
```

```
egin{aligned} & \mathsf{green} 
eq \mathsf{red} \ & il\_tl = \mathsf{green} \ \Rightarrow \ 0 < b \ \land \ a = 0 \ & ml\_tl = \mathsf{green} \ & il\_tl = \mathsf{green} \ & \vdash \ & 0 < b \ \land \ a + 1 = 0 \end{aligned}
```

```
\mathsf{IMP\_L} \begin{array}{|c|c|c|} & \mathsf{green} \neq \mathsf{red} \\ & 0 < b \ \land \ a = 0 \\ & ml\_tl = \mathsf{green} \\ & il\_tl = \mathsf{green} \\ & \vdash \\ & 0 < b \ \land \ a+1 = 0 \end{array}
```

AND_L · · ·

```
 \begin{array}{c|c} \mathsf{green} \neq \mathsf{red} \\ 0 < b \\ a = 0 \\ \cdots & \mathit{ml\_tl} = \mathsf{green} \\ \mathit{il\_tl} = \mathsf{green} \\ \vdash \\ 0 < b \ \land \ a+1 = 0 \end{array} \hspace{0.5cm} \mathsf{AND\_R}
```

```
ml\_tl = {\sf green} \ il\_tl = {\sf green} \ dots \ 0 < b
```

0 < b a = 0

 $\mathsf{green} \neq \mathsf{red}$

```
egin{aligned} & \mathsf{green} 
eq \mathsf{red} \ 0 < b \ a = 0 \ ml\_tl = \mathsf{green} \ il\_tl = \mathsf{green} \ \vdash \ a+1 = 0 \end{aligned}
```

```
\begin{array}{c} \mathsf{green} \neq \mathsf{red} \\ ml\_tl = \mathsf{green} \\ il\_tl = \mathsf{green} \\ \vdash \\ \underline{0+1=0} \end{array}
```

```
egin{aligned} & \mathsf{green} 
eq \mathsf{red} \ & ml\_tl = \mathsf{green} \ & il\_tl = \mathsf{green} \ & \vdash \ & 1 = 0 \end{aligned}
```

ARITH

?

```
axm<sub>0</sub> 1
axm0 2
axm2_1
axm2_2
inv0 1
inv<sub>0</sub> 2
inv1 1
inv1_2
inv1 3
inv1 4
inv1_5
inv2 1
inv2 2
inv2 3
inv2 4
Guard of IL_out
Modified inv2_3
```

```
d \in \mathbb{N}
0 < d
COLOR = \{ green, red \}
green \neq red
n \in \mathbb{N}
egin{array}{c} n \leq d \ a \in \mathbb{N} \end{array}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \text{green} \implies a + b < d \land c = 0
il_{-}tl = \overline{\mathsf{green}} \Rightarrow 0 < b \land a = 0
il_{-}tl = green
ml_{-}tl = \text{green} \implies a + b - 1 < d \land c + 1 = 0
```

IL_out / inv2_3 / INV

```
egin{aligned} \mathsf{IL\_out} & & & & \\ & & & \mathsf{when} & \\ & & & il\_tl = \mathsf{green} & \\ & & \mathsf{then} & \\ & & b := b-1 & \\ & & c := c+1 & \\ & & \mathsf{end} & \end{aligned}
```

```
d \in \mathbb{N}
0 < d
COLOR = \{\mathsf{green}, \mathsf{red}\}
green \neq red
n \in \mathbb{N}
n \leq d
a \in \mathbb{N}
b \in \mathbb{N}
c\in\mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \text{green} \implies a + b < d \land c = 0
il_{-}tl = \mathsf{green} \ \Rightarrow \ 0 < b \ \land \ a = 0
il_-tl= green
ml_{-}tl = \text{green} \implies a + b - 1 < d \land c + 1 = 0
```

```
\begin{array}{c|c} \mathsf{MON} & \mathsf{green} \neq \mathsf{red} \\ ml\_tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c=0 \\ il\_tl = \mathsf{green} \\ \vdash \\ ml\_tl = \mathsf{green} \ \Rightarrow \ a+b-1 < d \ \land \\ c+1=0 \end{array} \quad \mathsf{IMP\_R} \ \cdots
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n \in \mathbb{N}
n \le d
a \in \mathbb{N}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \text{green} \implies a + b < d \land c = 0
il_{-}tl = \text{green} \implies 0 < b \land a = 0
il_{-}tl = green
ml_{-}tl = \text{green} \Rightarrow a + b - 1 < d \land c + 1 = 0
```

```
\begin{array}{c|c} \mathsf{MON} & \mathsf{green} \neq \mathsf{red} \\ ml\_tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c=0 \\ il\_tl = \mathsf{green} \\ \vdash \\ ml\_tl = \mathsf{green} \ \Rightarrow \ a+b-1 < d \ \land \\ c+1=0 \end{array} \quad \mathsf{IMP\_R} \ \cdots
```

 $green
eq red \ ml_tl = green \ \Rightarrow a+b < d \ \land \ c=0 \ il_tl = green \ ml_tl = green \ + b-1 < d \ \land \ c+1=0$

 $\mathsf{IMP}_{-}\mathsf{L}$

```
\begin{array}{c} \mathsf{green} \neq \mathsf{red} \\ a+b < d \ \land \ c = 0 \\ il\_tl = \mathsf{green} \\ ml\_tl = \mathsf{green} \\ \vdash \\ a+b-1 < d \ \land \\ c+1 = 0 \end{array}
```

AND L · · ·

 $egin{aligned} & \mathsf{green}
eq \mathsf{red} \ a+b < d \ c = 0 \ il_tl = \mathsf{green} \ ml_tl = \mathsf{green} \ \vdash \ a+b-1 < d \ \land \ c+1 = 0 \end{aligned}$

AND_R

```
\begin{array}{l} \mathsf{green} \neq \mathsf{red} \\ a+b < d \\ c=0 \\ il\_tl = \mathsf{green} \\ ml\_tl = \mathsf{green} \\ \vdash \\ a+b-1 < d \end{array} \mathsf{MON} \boxed{ \begin{array}{c} a+b < d \vdash a+b-1 < d \end{array} \mathsf{DEC} }
```

$$egin{aligned} & \mathsf{green}
eq \mathsf{red} \ c &= 0 \ & il_tl = \mathsf{green} \ & ml_tl = \mathsf{green} \ & \vdash \ & c+1 = 0 \end{aligned}$$

$$\begin{array}{c} \mathsf{green} \neq \mathsf{red} \\ il_tl = \mathsf{green} \\ ml_tl = \mathsf{green} \\ \vdash \\ \underline{0+1=0} \end{array}$$

$$egin{aligned} { t green} &
eq { t red} \ il_tl = { t green} \ ml_tl = { t green} \ \vdash \ 1 = 0 \end{aligned}$$

ARITH

- In both cases, we were stopped by attempting to prove the following

```
egin{aligned} & \mathsf{green} 
eq \mathsf{red} \ il\_tl = \mathsf{green} \ ml\_tl = \mathsf{green} \ \vdash \ 1 = 0 \end{aligned}
```

Both traffic lights are assumed to be green!

- This indicates that an "obvious" invariant was missing
- In fact, at least one of the two traffic lights must be red

inv2_5:
$$ml_tl = \operatorname{red} \ \lor \ il_tl = \operatorname{red}$$

```
egin{aligned} & {\sf green} 
eq {\sf red} \ & {\it ml\_tl} = {\sf red} \ & {\it vl\_tl} = {\sf red} \ & {\it il\_tl} = {\sf red} \ & {\it il\_tl} = {\sf green} \ & {\it ml\_tl} = {\sf green} \ & \vdash \ & 1 = 0 \end{aligned}
```

```
green \neq red
                                   green \neq red
ml\_tl = \mathsf{red}
                                   green = red
il_{-}tl = {\sf green}
                      EQ_LR
                                   il_-tl= green
                                                      NOT_L · · ·
ml_{-}tl = green
                                   1 = 0
1 = 0
green \neq red
                                   green \neq red
il_{-}tl = \mathsf{red}
                                   green = red
il_-tl={\sf green}
                                   ml\_tl = \mathsf{green}
                      EQ_LR
                                                         NOT_L · · ·
ml_{-}tl = \text{green}
                                   1 = 0
1 = 0
```

inv2_5: $ml_tl = \operatorname{red} \ \lor \ il_tl = \operatorname{red}$

This could have been deduced from these requirements

The bridge is one way or the other, not both at the same time

FUN-3

Cars are not supposed to pass on a red traffic light, only on a green one

EQP-3

- ML_out / inv2_4 / INV done
- IL_out / inv2_3 / INV done
- ML_out / inv2_3 / INV
- IL_out / inv2_4 / INV
- ML_tl_green / inv2_5 / INV
- IL_tl_green / inv2_5 / INV

```
axm<sub>0</sub> 1
axm0 2
axm2 1
axm2_2
inv0 1
inv<sub>0</sub> 2
inv1 1
inv1_2
inv1 3
inv1 4
inv1_5
inv2 1
inv2 2
inv2 3
inv2 4
Guard of ML_out
Modified inv2 3
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n \in \mathbb{N}
\stackrel{n}{\overset{<}{\in}}\stackrel{d}{\overset{}{\in}}\mathbb{N}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \text{green} \implies a+b < d \land c=0
il_{-}tl = green \Rightarrow 0 < b \wedge a = 0
ml_{-}tl = green
ml_{-}tl = \text{green} \implies a+1+b < d \land c=0
```

 ML -out / $\mathsf{inv2}$ -3 / INV

```
egin{aligned} \mathsf{ML\_out} \ & \mathsf{when} \ & ml\_tl = \mathsf{green} \ & \mathsf{then} \ & a := a + 1 \ & \mathsf{end} \end{aligned}
```

```
d\in\mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n \in \mathbb{N}
n \le d
a\in\mathbb{N}
b \in \mathbb{N}
c\in\mathbb{N}
a+b+c=n
a = 0 \quad \lor \quad c = 0
ml\_tl \in COLOR
il\_tl \in COLOR
ml_{-}tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = green \Rightarrow 0 < b \land a = 0
ml_{\perp}tl = \text{green}
ml_{-}tl = \mathsf{green} \ \Rightarrow \ a+1+b < d \ \land
                                      c = 0
```

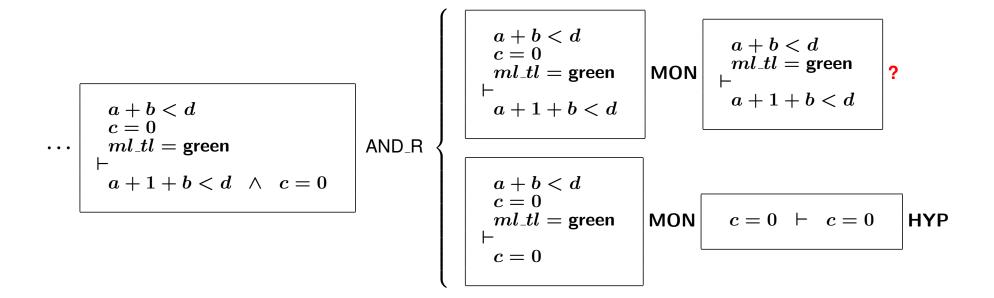
```
egin{aligned} \mathsf{MON} & ml\_tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c = 0 \ & \mathsf{IMP\_R} \cdots \ & ml\_tl = \mathsf{green} \ \Rightarrow \ a+1+b < d \ \land \ c = 0 \end{aligned} egin{aligned} \mathsf{IMP\_R} \cdots \end{aligned}
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n \in \mathbb{N}
n \le d
a\in\mathbb{N}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \text{green} \implies a+b < d \land c=0
il_{-}tl = \text{green} \implies 0 < b \land a = 0
ml_{-}tl = green
ml_{-}tl = \text{green} \implies a+1+b < d \land
                                   c = 0
```

$$egin{aligned} \mathsf{MON} & ml_tl = \mathsf{green} \; \Rightarrow \; a+b < d \; \wedge \; c = 0 \ & ml_tl = \mathsf{green} \; \Rightarrow \; a+1+b < d \; \wedge \; c = 0 \end{aligned} egin{aligned} \mathsf{IMP_R} \cdots \end{aligned}$$

$$ml_tl = ext{green} \Rightarrow a+b < d \land c=0$$
 $ml_tl = ext{green}$ $+$ $a+1+b < d \land c=0$

$$\mathsf{IMP_L} \left| egin{array}{c} a+b < d & \wedge & c = 0 \\ ml_tl = \mathsf{green} \\ \vdash & a+1+b < d & \wedge & c = 0 \end{array} \right| \; \mathsf{AND_L} \; \cdots$$



- This requires splitting the ML_out in two separate events ML_out_1 and ML_out_2

```
ML\_out\_1
when
ml\_tl = green
a+1+b < d
then
a := a+1
end
```

```
egin{aligned} \mathsf{ML\_out\_2} & \mathbf{when} \\ & \mathit{ml\_tl} = \mathsf{green} \\ & \mathit{a+1+b} = \mathit{d} \\ & \mathsf{then} \\ & \mathit{a:=a+1} \\ & \mathit{ml\_tl} := \mathsf{red} \\ & \mathsf{end} \end{aligned}
```

```
egin{aligned} \mathsf{ML\_out\_1} \ & \mathsf{when} \ & ml\_tl = \mathsf{green} \ & a+1+b < d \ & \mathsf{then} \ & a := a+1 \ & \mathsf{end} \end{aligned}
```

```
egin{aligned} \mathsf{ML\_out\_2} \ & \mathsf{when} \ & ml\_tl = \mathsf{green} \ & a+1+b=d \ & \mathsf{then} \ & a := a+1 \ & ml\_tl := \mathsf{red} \ & \mathsf{end} \end{aligned}
```

- When a+1+b=d then only one more car can enter the island
- Consequently, the traffic light ml_tl must be turned red (while the car enters the bridge)

```
axm0 1
axm0 2
axm2_1
axm2 2
inv0_1
inv0 2
inv1 1
inv1_2
inv1_3
inv1_4
inv1_5
inv2 1
inv2 2
inv2_3
inv2_4
Guard of ML_out_1
Modified inv2 3
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n \in \mathbb{N}
n \leq d
a \in \mathbb{N}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = green \Rightarrow 0 < b \land a = 0
ml_{-}tl = {\sf green}
 a + 1 + b < d
 ml _{oldsymbol{-}}tl = {\sf green} \ \Rightarrow \ a+1+b < d \ \land \ c=0
```

 $\mathsf{ML_out_1} \ / \ \mathrm{inv2_3} \ / \ \mathsf{INV}$

```
ML out 1
  when
    ml_{-}tl = green
    a + 1 + b < d
 then
    a := a + 1
  end
```

```
d\in\mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n\in {}^{cute{N}}
n \le d
a\in\mathbb{N}
b \in \mathbb{N}
c\in\mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il\_tl \in COLOR
ml_{-}tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = green \Rightarrow 0 < b \land a = 0
ml_{-}tl = {\sf green}
a+1+b < d
 ml_{-}tl = \text{green} \implies a+1+b < d \land
                                   c = 0
```

```
egin{aligned} \mathsf{MON} & egin{aligned} ml\_tl = \mathsf{green} & \Rightarrow \ a+b < d \ \land \ c = 0 \ & +1+b < d \ & + \ & ml\_tl = \mathsf{green} \ \Rightarrow \ a+1+b < d \ \land \ c = 0 \end{aligned} egin{aligned} \mathsf{IMP\_R} \cdots \end{aligned}
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n\in\mathbb{N}
n \le d
a\in\mathbb{N}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \text{green} \implies a+b < d \land c=0
il_{-}tl = \text{green} \implies 0 < b \land a = 0
ml_{-}tl = green
a + 1 + b < d
ml_{-}tl = \text{green} \implies a+1+b < d \land
                                   c = 0
```

```
egin{aligned} \mathsf{MON} & egin{aligned} ml\_tl = \mathsf{green} & \Rightarrow \ a+b < d \ \land \ c = 0 \ & a+1+b < d \ & & \\ ml\_tl = \mathsf{green} & \Rightarrow \ a+1+b < d \ \land \ c = 0 \end{aligned} egin{aligned} \mathsf{IMP\_R} \cdots \end{aligned}
```

```
ml\_tl = 	ext{green} \quad \Rightarrow \quad a+b < d \quad \wedge \quad c=0 ml\_tl = 	ext{green} a+1+b < d h a+1+b < d \quad \wedge \quad c=0
```

AND_L · · ·

$$egin{array}{c} a+b < d \ c=0 \ ml_tl = {\sf green} \ a+1+b < d \ & \land & c=0 \ \end{array}$$

$$egin{array}{l} a+b < d \\ c=0 \\ ml_tl = {\sf green} \\ a+1+b < d \\ \vdash \\ a+1+b < d \end{array}$$

 AND_R

 $\left| \begin{array}{c} a+1+b < d \\ \vdash \\ a+1+b < d \end{array} \right| \text{HYP}$

$$a+b < d$$
 $c=0$
 $ml_tl = ext{green}$
 $a+1+b < d$
 \vdash
 $c=0$

$$\boxed{ \begin{tabular}{c|c|c} {\sf MON} & c=0 & \vdash & c=0 \\ \hline \end{tabular} \begin{tabular}{c|c|c} {\sf HYP} \\ \hline \end{tabular}$$

```
axm0_1
axm<sub>0</sub> 2
axm2_1
axm2 2
inv0<sub>1</sub>
inv0_2
inv1 1
inv1 2
inv1 3
inv1_4
inv1 5
inv2 1
inv2 2
inv23
inv2 4
Guard of ML out 2
```

Modified inv2_3

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n \in \mathbb{N}
n \leq d
a \in \mathbb{N}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = green \Rightarrow 0 < b \land a = 0
ml_-tl={\sf green}
a+1+b=d
 red = green \Rightarrow a+1+b < d \land c=0
```

 $ML_out_2 / inv_2_3 / INV$

```
ML out 2
 when
   ml_-tl= green
   a+1+b=d
 then
   a := a + 1
   ml\_tl := red
 end
```

```
d\in\mathbb{N}
0 < d
COLOR = \{ green, red \}
green \neq red
n \in \mathbb{N}
n \le d
a \in \mathbb{N}
b \in \mathbb{N}
c\in\mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il\_tl \in COLOR
ml_{-}tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = green \Rightarrow 0 < b \land a = 0
ml\_tl = \mathsf{green}
a+1+b=d
 red = green \Rightarrow a+1+b < d \land
                                   c = 0
```

```
\begin{array}{|c|c|c|c|c|}\hline \mathsf{MON} & \mathbf{green} \neq \mathsf{red} \\ \vdash & \mathsf{red} = \mathsf{green} \ \Rightarrow \ a+1+b < d \ \land \ c = 0 \end{array} \quad \mathsf{IMP\_R}
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n\in \mathbb{N}
n \le d
a\in\mathbb{N}
b \in \mathbb{N}
c\in\mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il\_tl \in COLOR
ml_{-}tl = {\sf green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = \text{green} \implies 0 < b \land a = 0
ml_{-}tl = {\sf green}
a+1+b=d
red = green \Rightarrow a+1+b < d \land
                                   c = 0
```

```
green \neq red
MON
                                                   IMP R
        red = green \implies a+1+b < d \land c=0
```

$$egin{array}{c} {
m green}
eq {
m red} = {
m green} \ {
m red} = {
m green} \ {
m red} = a+1+b < d \ \land \ c=0 \end{array}$$

EQ_LR

$$egin{aligned} \mathsf{green}
eq \mathsf{green} \ \vdash \ a+1+b < d & \wedge & c=0 \end{aligned}$$

NOT_L

EQL

- ML_out / inv2_4 / INV done
- IL_out / inv2_3 / INV done
- ML_out / inv2_3 / INV done
- IL_out / inv2_4 / INV
- ML_tl_green / inv2_5 / INV
- IL_tl_green / inv2_5 / INV

```
axm0 1
axm0 2
axm2 1
axm2_2
inv0_1
inv0 2
inv1 1
inv1 2
inv1_3
inv1 4
inv1 5
inv2 1
inv2 2
inv2 3
inv2 4
Guard of event IL_out
Modified invariant inv2 4
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n \in \mathbb{N}
n \leq d
a \in \mathbb{N}
b \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = {\sf green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = \text{green} \Rightarrow 0 < b \land a = 0
il_{-}tl = green
il_{-}tl = green \Rightarrow 0 < b-1 \land a = 0
```

IL_out / inv2_4 / INV

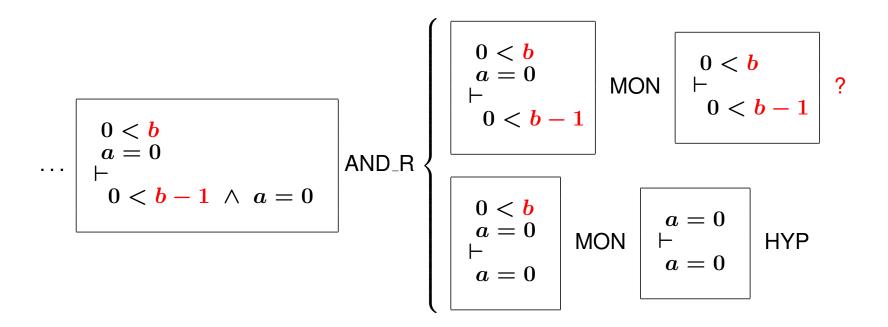
```
egin{aligned} \mathsf{IL\_out} & \mathbf{when} \\ & \mathit{il\_tl} = \mathsf{green} \\ & \mathsf{then} \\ & b := b-1 \\ & c := c+1 \\ & \mathsf{end} \end{aligned}
```

```
d \in \mathbb{N}
0 < d
COLOR = \{ green, red \}
green \neq red
n \in \mathbb{N}
n \leq d
a \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \mathsf{green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = \text{green} \implies 0 < b \land a = 0
il_{-}tl = green
il_{-}tl = green \Rightarrow 0 < b-1 \land a = 0
```

```
egin{aligned} \emph{il\_tl} = \mathsf{green} &\Rightarrow 0 < \pmb{b} \ \land \ a = 0 \ \emph{il\_tl} = \mathsf{green} \ \vdash \ \emph{il\_tl} = \mathsf{green} &\Rightarrow 0 < \pmb{b} - \mathbf{1} \ \land \ a = 0 \end{aligned} 	ext{IMP\_R}
```

 $il_tl = ext{green} \Rightarrow 0 < b \land a = 0$ $il_tl = ext{green}$ \vdash $0 < b - 1 \land a = 0$

$$egin{array}{c|c} \mathsf{IMP_L} & 0 < oldsymbol{b} & \wedge & a = 0 \ & \vdash & \ 0 < oldsymbol{b} - 1 & \wedge & a = 0 \ \end{array} & \mathsf{AND_L} \end{array}$$



- This requires splitting the concrete IL_out in two separate events IL_out_1 and IL_out_2

```
egin{aligned} & \mathsf{IL\_out\_1} \\ & \mathbf{when} \\ & \mathit{il\_tl} = \mathsf{green} \\ & \mathit{b} 
eq 1 \\ & \mathsf{then} \\ & \mathit{b}, \mathit{c} := \mathit{b} - 1, \mathit{c} + 1 \\ & \mathsf{end} \end{aligned}
```

```
egin{aligned} & \mathsf{IL\_out\_2} \\ & \mathsf{when} \\ & il\_tl = \mathsf{green} \\ & b = 1 \\ & \mathsf{then} \\ & b, c := b-1, c+1 \\ & il\_tl := \mathsf{red} \\ & \mathsf{end} \end{aligned}
```

```
egin{aligned} 	ext{IL\_out\_1} & & & & \\ 	ext{when} & & & & \\ 	ext{$il\_tl$} = & & & \\ 	ext{$b \neq 1$} & & \\ 	ext{then} & & & \\ 	ext{$b,c:=b-1,c+1$} & & \\ 	ext{end} & & & \end{aligned}
```

```
egin{aligned} 	ext{IL\_out\_2} & 	ext{when} \ il\_tl = 	ext{green} \ b = 1 \ 	ext{then} \ b, c := b - 1, c + 1 \ il\_tl := 	ext{red} \ 	ext{end} \end{aligned}
```

- When b=1, then only one car remains in the island
- Consequently, the traffic light $i l_- t l$ can be turned red (after this car has left)

```
axm0 1
axm0 2
axm2_1
axm2 2
inv0_1
inv<sub>0</sub> 2
inv1<sub>1</sub>
inv1_2
inv1_3
inv1_4
inv1_5
inv2 1
inv2 2
inv2_3
inv2_4
Guard of event IL_out_1
Modified invariant inv2 4
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
\mathsf{green} \neq \mathsf{red}
n \in \mathbb{N}
n \leq d
a \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{\scriptscriptstyle -}tl = {\sf green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = green \Rightarrow 0 < b \land a = 0
il_{-}tl = green
b \neq 1
il_{-}tl = \text{green} \implies 0 < b-1 \land a = 0
```

IL_out_1 / **inv2_4** / INV

```
egin{aligned} 	ext{IL\_out\_1} & 	ext{when} \ & il\_tl = 	ext{green} \ & b 
eq 1 \ & 	ext{then} \ & b, c := b - 1, c + 1 \ & 	ext{end} \end{aligned}
```

```
d \in \mathbb{N}
0 < d
COLOR = \{ green, red \}
green \neq red
n \in \mathbb{N}
n \leq d
a \in \mathbb{N}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il\_tl \in COLOR
ml_{-}tl = {\sf green} \ \Rightarrow \ a+b < d \ \land \ c=0
il_{-}tl = \text{green} \implies 0 < b \land a = 0
il_{-}tl = green
b \neq 1
il_{-}tl = \text{green} \implies 0 < b-1 \land a = 0
```

```
il\_tl = 	ext{green} \Rightarrow 0 < b \land a = 0 il\_tl = 	ext{green} b 
eq 1 \vdash il\_tl = 	ext{green} \Rightarrow 0 < b - 1 \land a = 0
```

 $\mathsf{IMP}_{\mathsf{R}}$

$$il_tl = ext{green} \ \Rightarrow \ 0 < b \ \land \ a = 0$$
 $il_tl = ext{green}$
 $b
eq 1$
 $b < b - 1 \ \land \ a = 0$

 $\mathsf{IMP_L} \left| \begin{array}{c} 0 < \textcolor{red}{b} \, \land \, a = 0 \\ \textcolor{red}{b \neq 1} \\ \textcolor{blue}{\vdash} \\ 0 < \textcolor{blue}{b - 1} \, \land \, a = 0 \end{array} \right| \, \mathsf{AND_L}$

$$0 < \frac{b}{a = 0}$$
 $b \neq 1$
 $0 < b - 1 \land a = 0$
AND_R

$$0 < b$$

$$a = 0$$

$$b \neq 1$$

$$0 < b - 1$$

MON

$$0 < \frac{b}{b} \neq 1$$

$$\vdash$$

$$0 < b - 1$$

ARITH

$$\begin{vmatrix} 0 < b - 1 \\ \vdash \\ 0 < b - 1 \end{vmatrix} \mathsf{HYP}$$

$$egin{array}{c} 0 < oldsymbol{b} \ a = 0 \ b
eq 1 \ a = 0 \end{array} egin{array}{c} \mathsf{MON} \end{array} egin{array}{c} a = 0 \ a = 0 \end{array} \end{array} HYP$$

```
axm0 1
axm0 2
axm2_1
axm2 2
inv0_1
inv0 2
inv1 1
inv1_2
inv1_3
inv1_4
inv1_5
inv2 1
inv2 2
inv2_3
inv2_4
Guard of event IL_out_2
Modified invariant inv2 4
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
\mathsf{green} \neq \mathsf{red}
n \in \mathbb{N}
n \leq d
a \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il_{-}tl \in COLOR
ml_{-}tl = \text{green} \implies a+b < d \land c = 0
il_{-}tl = green \Rightarrow 0 < b \land a = 0
il_{-}tl = green
b=1
red = green \Rightarrow 0 < b-1 \land a = 0
```

IL_out_1 / **inv2_4** / INV

```
\begin{array}{c} \mathsf{IL\_out\_2}\\ \textbf{when}\\ il\_tl = \mathsf{green}\\ b = 1\\ \mathbf{then}\\ b, c, il\_tl := b-1, c+1, red\\ \mathsf{end} \end{array}
```

```
d \in \mathbb{N}
0 < d
COLOR = \{green, red\}
green \neq red
n \in \mathbb{N}
n \le d
a \in \mathbb{N}
b \in \mathbb{N}
c \in \mathbb{N}
a+b+c=n
a=0 \quad \lor \quad c=0
ml\_tl \in COLOR
il\_tl \in COLOR
ml_{-}tl = {\sf green} \implies a+b < d \land c = 0
il_{-}tl = \text{green} \Rightarrow 0 < b \land a = 0
il_{-}tl = green
b=1
red = green \Rightarrow 0 < b-1 \land a = 0
```

$$\begin{array}{c|c} \mathsf{MON} & \mathsf{green} \neq \mathsf{red} \\ \vdash \\ \mathsf{red} = \mathsf{green} \ \Rightarrow \ 0 < \frac{b}{a} - 1 \ \land \\ a = 0 \end{array} \mathsf{IMP_R}$$

$$egin{array}{ll} {\sf green}
eq {\sf red} \ {\sf red} = {\sf green} \ dash \ 0 < {\it b} - 1 \quad \wedge \quad a = 0 \end{array}$$

EQ_LR

$$egin{aligned} & \mathsf{green}
eq \mathsf{green} \ dash \ & 0 < oldsymbol{b} - 1 \ & \wedge \ & a = 0 \end{aligned}$$

- ML_out / inv2_4 / INV done
- IL_out / inv2_3 / INV done
- ML_out / inv2_3 / INV done
- IL_out / inv2_4 / INV done
- ML_tl_green / inv2_5 / INV
- IL_tl_green / inv2_5 / INV

But the new invariant **inv2_5** is not preserved by the new events

inv2_5:
$$ml_tl = \operatorname{red} \ \lor \ il_tl = \operatorname{red}$$

Unless we correct them as follows:

```
egin{aligned} \mathsf{ML\_tl\_green} \ & \mathbf{when} \ & ml\_tl = \mathsf{red} \ & a+b < d \ & c = 0 \ & \mathsf{then} \ & ml\_tl := \mathsf{green} \ & il\_tl := \mathsf{red} \ & \mathsf{end} \end{aligned}
```

```
egin{aligned} 	ext{LL_lgreen} & 	ext{when} \ & il\_tl = 	ext{red} \ & 0 < b \ & a = 0 \ & 	ext{then} \ & il\_tl := 	ext{green} \ & ml\_tl := 	ext{red} \ & 	ext{end} \end{aligned}
```

- Correct event refinement: OK

- Absence of divergence of new events: FAILURE

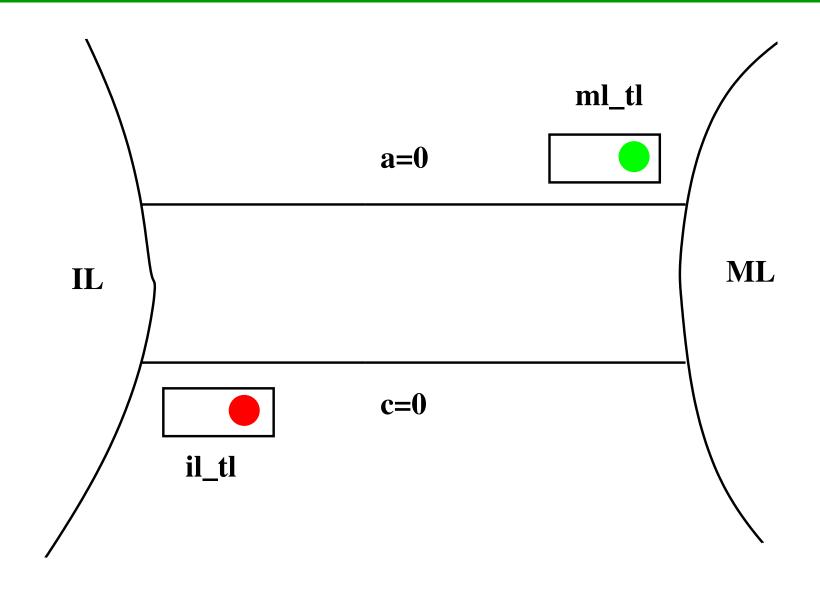
- Absence of deadlock: ?

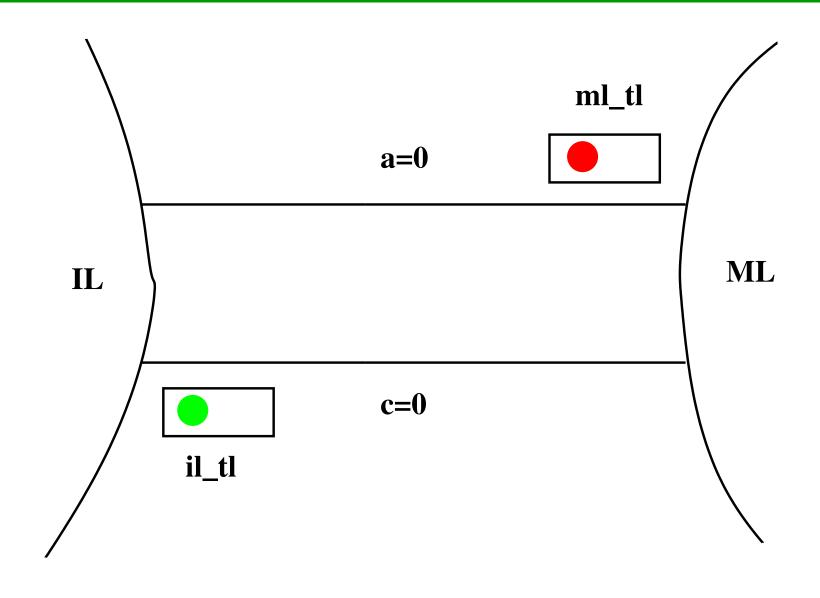
```
egin{align*} \mathsf{ML\_tl\_green} \ & \mathsf{when} \ & ml\_tl = \mathsf{red} \ & a+b < d \ & c = 0 \ & \mathsf{then} \ & ml\_tl := \mathsf{green} \ & il\_tl := \mathsf{red} \ & \mathsf{end} \ & \mathsf{end} \ & \mathsf{end} \ & \mathsf{ond} \ & \mathsf
```

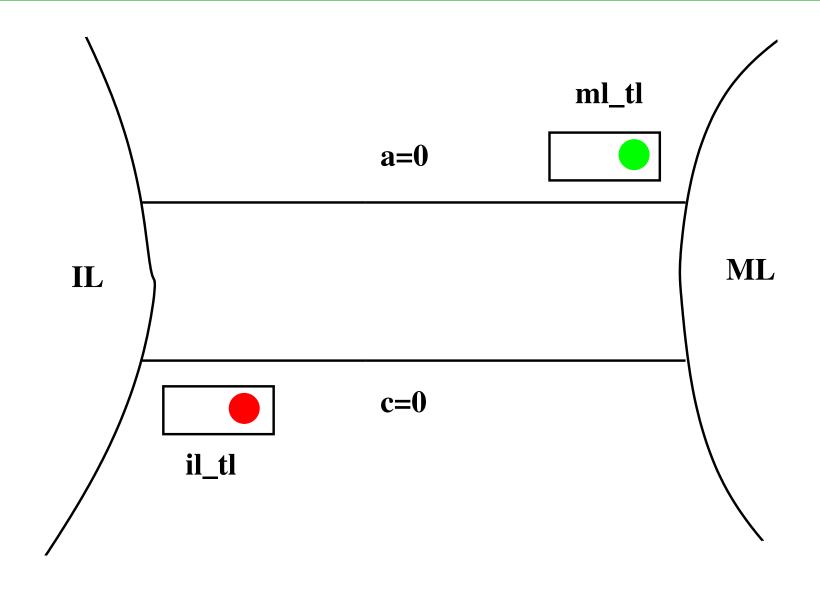
```
egin{align*} 	ext{LLtl\_green} & 	ext{when} \ il\_tl = 	ext{red} \ 0 < b \ a = 0 \ 	ext{then} \ il\_tl := 	ext{green} \ ml\_tl := 	ext{red} \ 	ext{end} \ \end{aligned}
```

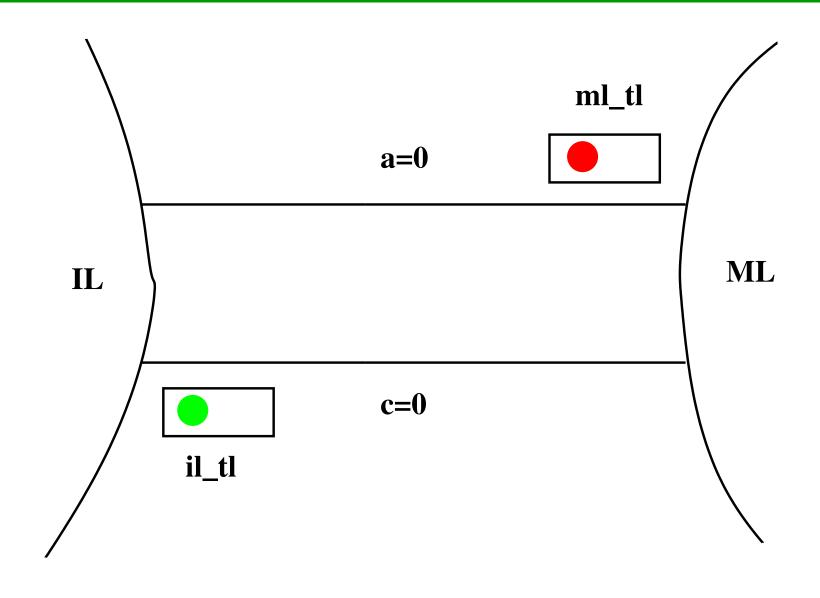
When a and c are both equal to 0 and b is positive, then both events are always alternatively enabled

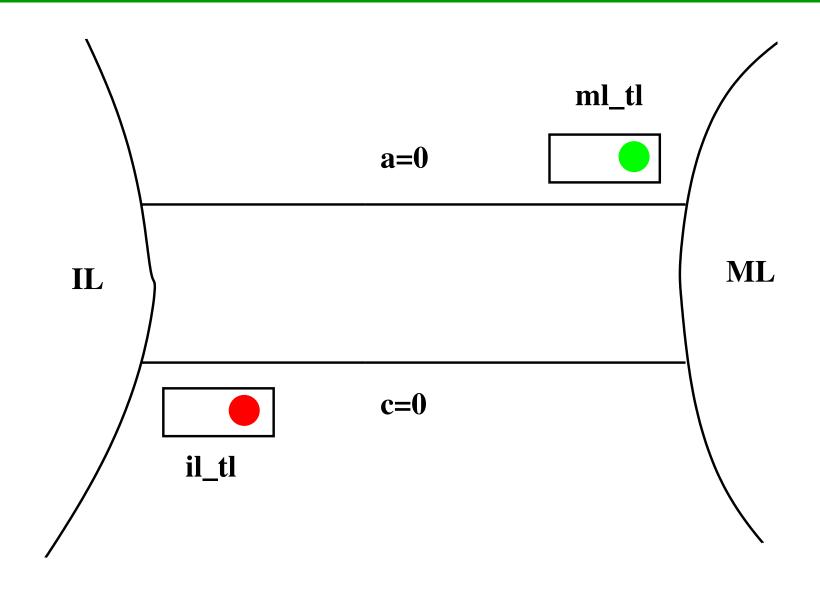
The lights can change colors very rapidly

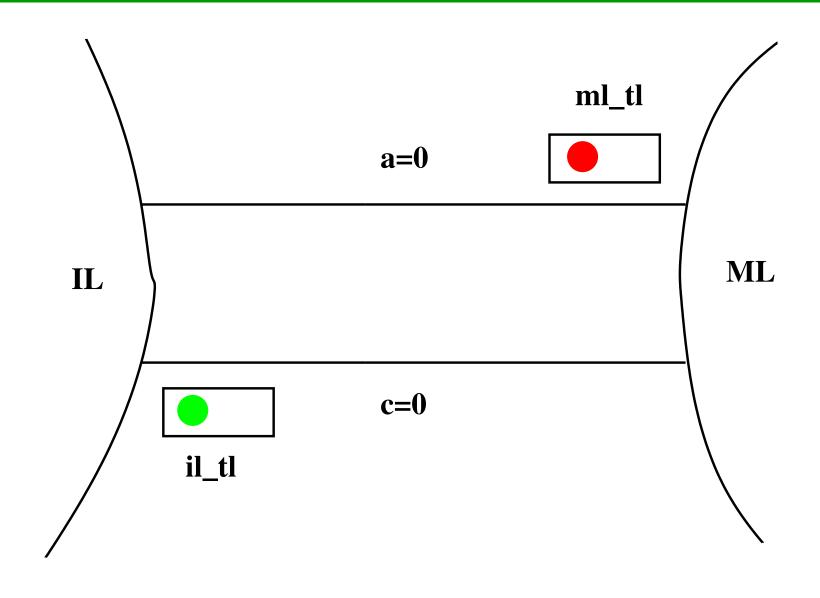












- Allowing each light to turn green only when at least one car has passed in the other direction

- For this, we introduce two additional variables:

inv2_6: $ml_pass \in \{0,1\}$

inv2_7: $il_pass \in \{0,1\}$

```
egin{aligned} \mathsf{ML\_out\_1} \ & \mathbf{when} \ & ml\_tl = \mathbf{green} \ & a+1+b < d \ & \mathbf{then} \ & a := a+1 \ & ml\_pass := 1 \ & \mathbf{end} \end{aligned}
```

```
egin{aligned} \mathsf{ML\_out\_2} \ & \mathsf{when} \ & ml\_tl = \mathsf{green} \ & a+1+b=d \ & \mathsf{then} \ & a := a+1 \ & ml\_tl := \mathsf{red} \ & ml\_pass := 1 \ & \mathsf{end} \end{aligned}
```

```
egin{aligned} 	ext{IL\_out\_1} & 	ext{when} \ & il\_tl = 	ext{green} \ & b 
eq 1 \ & then \ & b := b - 1 \ & c := c + 1 \ & il\_pass := 1 \ & 	ext{end} \end{aligned}
```

```
egin{aligned} \mathsf{lL\_out\_2} \ & \mathsf{when} \ & il\_tl = \mathsf{green} \ & b = 1 \ & \mathsf{then} \ & b := b - 1 \ & c := c + 1 \ & il\_tl := \mathsf{red} \ & il\_pass := 1 \ & \mathsf{end} \end{aligned}
```

```
ML_tl_green
  when
    ml\_tl = \mathsf{red}
    a+b < d
    c = 0
    il\_pass = 1
  then
    ml_{-}tl:= green
    il\_tl := \mathsf{red}
     ml\_pass := 0
  end
```

```
IL_tl_green
  when
    il\_tl = \mathsf{red}
    0 < b
     a = 0
     ml\_pass = 1
  then
    il_{-}tl := green
     ml\_tl := \mathsf{red}
     il\_pass := 0
  end
```

We exhibit the following variant

variant_2: $ml_pass + il_pass$

To be Proved

$$egin{aligned} ml_tl &= \mathsf{red} \ a+b < d \ c &= 0 \ il_pass &= 1 \ \Rightarrow \ il_pass + 0 < \ ml_pass + il_pass \end{aligned}$$

$$egin{aligned} il_tl &= \mathsf{red} \ b > 0 \ a &= 0 \ ml_pass &= 1 \ \Rightarrow \ ml_pass + 0 < \ ml_pass + il_pass \end{aligned}$$

This cannot be proved. This suggests the following invariants:

inv2_8: $ml_tl = \text{red} \Rightarrow ml_pass = 1$

inv2_9: $il_tl = \operatorname{red} \Rightarrow il_pass = 1$

```
0 < d
ml_{-}tl \in \{ {\sf red}, {\sf green} \}
il_{-}tl \in \{\text{red}, \text{green}\}
ml\_pass \in \{0,1\}
il\_pass~\in\{0,1\}
a \in \mathbb{N}
b \in \mathbb{N}
c \in \mathbb{N}
ml\_tl = \mathsf{red} \ \Rightarrow \ ml\_pass = 1
il\_tl = \mathsf{red} \ \Rightarrow \ il\_pass = 1
(ml\_tl = \mathsf{red} \ \land \ a+b < d \ \land \ c=0 \ \land \ il\_pass = 1) \ \lor
(il\_tl = \mathsf{red} \ \land \ a = 0 \ \land \ b > 0 \ \land \ ml\_pass = 1) \ \lor
ml\_tl = {\sf green} \ \lor \ il\_tl = {\sf green} \ \lor \ a>0 \ \lor \ c>0
```

The previous statement reduces to the following, which is true

$$egin{array}{lll} 0 < d \ a \in \mathbb{N} \ b \in \mathbb{N} \ c \in \mathbb{N} \ \end{array} \ & \Rightarrow \ (a+b < d \ \land \ c = 0) \ \lor \ (a=0 \ \land \ b > 0) \ \lor \ a > 0 \ \lor \ c > 0 \ \end{array}$$

- Thanks to the proofs:
 - We discovered 4 errors

- We introduced several additional invariants

- We corrected 4 events

- We introduced 2 more variables

Conclusion: we Introduced the Superposition Rule

Axioms
Abstract invariants
Concrete invariants
Concrete guards

Same actions on common variables

variables: a, b, c,

 $ml_tl, il_tl, ml_pass, il_pass$

inv2_1: $ml_-tl \in \{\text{red}, \text{green}\}$

inv2_2: $il_{-}tl \in \{\text{red}, \text{green}\}$

inv2_3: $ml_{-}tl = 1 \Rightarrow a+b < d \wedge c = 0$

inv2_4: $il_{-}tl = 1 \Rightarrow 0 < b \wedge a = 0$

```
inv2_5: ml\_tl = \operatorname{red} \ \lor \ il\_tl = \operatorname{red}
```

inv2_6:
$$ml_pass \in \{0,1\}$$

inv2_7:
$$il_pass \in \{0,1\}$$

inv2_8:
$$ml_tl = \text{red} \Rightarrow ml_pass = 1$$

inv2_9:
$$il_{-}tl = \text{red} \Rightarrow il_{-}pass = 1$$

variant2: $ml_pass + il_pass$

```
egin{aligned} \mathsf{ML\_out\_1} \ & \mathsf{when} \ & ml\_tl = \mathsf{green} \ & a+1+b < d \ & \mathsf{then} \ & a := a+1 \ & ml\_pass := 1 \ & \mathsf{end} \end{aligned}
```

```
egin{aligned} \mathsf{ML\_out\_2} \ & \mathsf{when} \ & ml\_tl = \mathsf{green} \ & a+1+b=d \ & \mathsf{then} \ & a := a+1 \ & ml\_pass := 1 \ & ml\_tl := \mathsf{red} \ & \mathsf{end} \end{aligned}
```

```
egin{aligned} 	ext{IL\_out\_1} & 	ext{when} \ & il\_tl = 	ext{green} \ & b 
eq 1 \ & then \ & b := b - 1 \ & c := c + 1 \ & il\_pass := 1 \ & 	ext{end} \end{aligned}
```

```
egin{aligned} 	ext{IL\_out\_2} & 	ext{when} \ il\_tl = 	ext{green} \ b = 1 \ 	ext{then} \ b := b - 1 \ c := c + 1 \ il\_pass := 1 \ il\_tl := 	ext{red} \ 	ext{end} \end{aligned}
```

```
ML_tl_green
  when
     ml\_tl = \mathsf{red}
     a+b < d
     c = 0
     il\_pass=1
  then
     ml\_tl := \mathsf{green}
     il\_tl := \mathsf{red}
     ml\_pass := 0
  end
```

```
IL_tl_green
  when
     il\_tl = \mathsf{red}
     0 < b
     a = 0
     ml\_pass = 1
  then
     il_{-}tl := green
     ml\_tl := \mathsf{red}
     il_{-}pass := 0
  end
```

- These events are identical to their abstract versions

```
egin{array}{ll} \mathsf{ML\_in} & & & \\ \mathsf{when} & & \\ 0 < c & & \\ \mathsf{then} & & \\ c := c-1 & & \\ \mathsf{end} & & \end{array}
```

```
egin{aligned} \mathsf{IL}\ \mathsf{in} \\ \mathsf{when} \\ 0 < a \\ \mathsf{then} \\ a := a - 1 \\ b := b + 1 \\ \mathsf{end} \end{aligned}
```

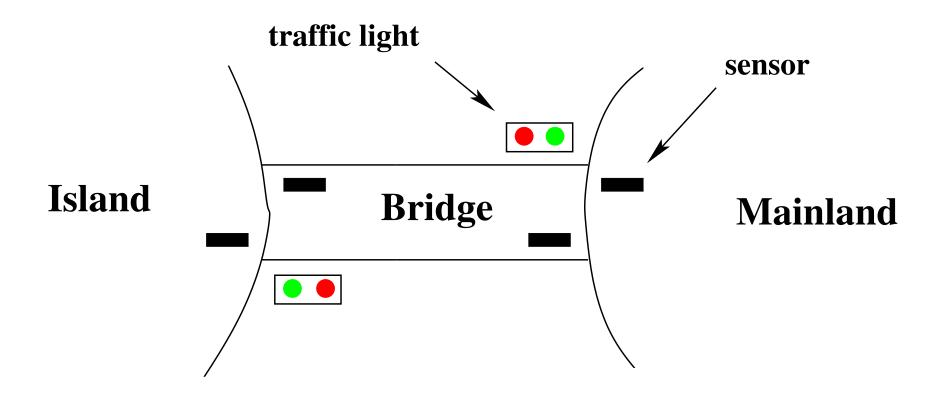
- Initial model: Limiting the number of cars (FUN_2)

- First refinement: Introducing the one way bridge (FUN_3)

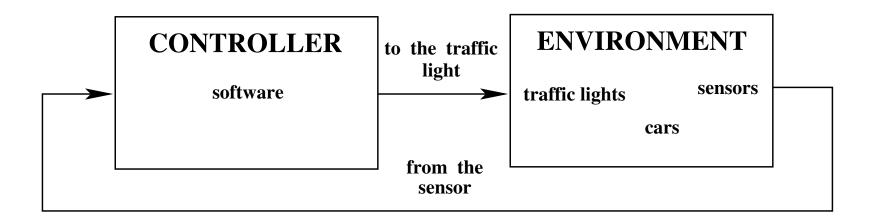
- Second refinement: Introducing the traffic lights (EQP_1,2,3)

- Third refinement: Introducing the sensors (EQP_4,5)

Reminder of the physical system



- -We want to clearly identify in our model:
 - The controller
 - The environment
 - The communication channels between the two



```
Contoller variables: a,
b,
c,
ml\_pass,
il\_pass
```

These new variables denote physical objects

Environment variables: A,

B,

C,

 $ML_OUT_SR,$

 $ML_IN_SR,$

 $IL_OUT_SR,$

 IL_IN_SR

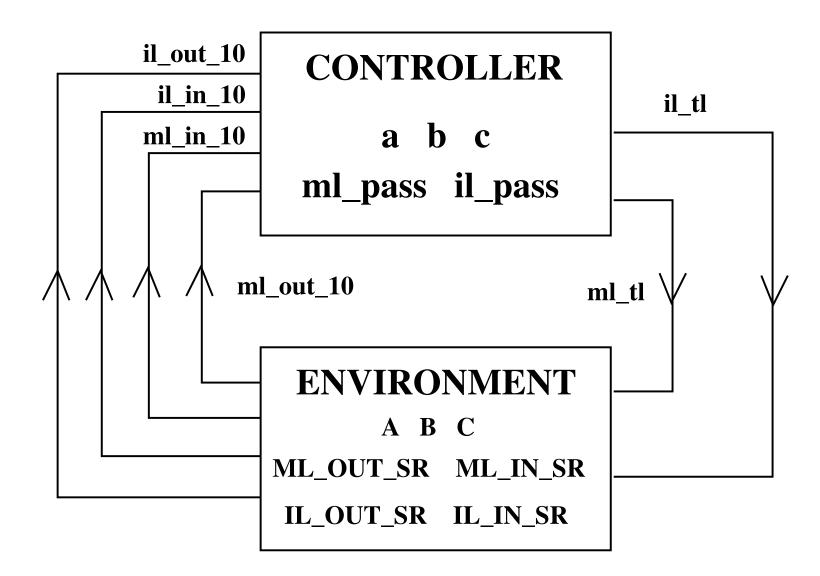
Output channels: ml_-tl ,

 $m{i}m{l}_{-}m{t}m{l}$

```
Input channels: ml\_out\_10, \ ml\_in\_10, \ il\_in\_10, \ il\_out\_10
```

A message is sent when a sensor moves from "on" to "off":





carrier sets: $\dots, SENSOR$

constants: \dots, on, off

axm3_1: $SENSOR = \{on, off\}$

axm3_2: $on \neq off$

 $inv3_{-}1: ML_{-}OUT_{-}SR \in SENSOR$

 $inv3_2: ML_IN_SR \in SENSOR$

 $inv3_{-}3: IL_{-}OUT_{-}SR \in SENSOR$

 $inv3_4: IL_IN_SR \in SENSOR$

 inv3_{-5} : $A \in \mathbb{N}$

 $inv3_{-}6: B \in \mathbb{N}$

 $inv3_{-7}: C \in \mathbb{N}$

 $inv3_-8: ml_out_-10 \in BOOL$

 $inv3_{-}9: ml_{-}in_{-}10 \in BOOL$

 $inv3_{-}10: il_out_{-}10 \in BOOL$

 $inv3_{-}11: il_{-}in_{-}10 \in BOOL$

When sensors are on, there are cars on them

$$inv3_{-}12: IL_{-}IN_{-}SR = on \Rightarrow A > 0$$

inv3_13:
$$IL_OUT_SR = on \Rightarrow B > 0$$

$$inv3_14: ML_IN_SR = on \Rightarrow C > 0$$

The sensors are used to detect the presence of cars entering or leaving the bridge

EQP-5

Drivers obey the traffic lights

 $\text{inv3}_15: \quad ml_out_10 = \text{TRUE} \quad \Rightarrow \quad ml_tl = green$

 $inv3_{-}16: il_out_{-}10 = TRUE \Rightarrow il_tl = green$

Cars are not supposed to pass on a red traffic light, only on a green one

EQP-3

When a sensor is "on", the previous information is treated

```
\text{inv3\_17}: \quad IL\_IN\_SR = on \quad \Rightarrow \quad il\_in\_10 = \text{FALSE}
```

$$\text{inv3}_18: \quad IL_OUT_SR = on \quad \Rightarrow \quad il_out_10 = \text{FALSE}$$

$$\text{inv3}_19: \quad ML_IN_SR = on \quad \Rightarrow \quad ml_in_10 = \text{FALSE}$$

$$inv3_20: ML_OUT_SR = on \Rightarrow ml_out_10 = FALSE$$

The controller must be fast enough so as to be able to treat all the information coming from the environment

FUN-5

Linking the physical and logical cars (1)

```
inv3_21: il_in_10 = TRUE \land ml_out_10 = TRUE \Rightarrow A = a
```

 $\text{inv3}_22: \quad il_in_10 = \text{FALSE} \ \land \ ml_out_10 = \text{TRUE} \ \Rightarrow \ A = a+1$

 ${
m inv3_23}: \quad il_in_10 = {
m TRUE} \ \land \ ml_out_10 = {
m FALSE} \ \Rightarrow \ A=a-1$

 $inv3_24: \quad il_in_10 = FALSE \ \land \ ml_out_10 = FALSE \ \Rightarrow \ A = a$

Linking the physical and logical cars (2)

```
inv3\_25: il\_in\_10 = TRUE \land il\_out\_10 = TRUE \Rightarrow B = b
```

$$inv3_26: il_in_10 = TRUE \land il_out_10 = FALSE \Rightarrow B = b + 1$$

$$inv3_27: il_in_10 = FALSE \land il_iout_10 = TRUE \Rightarrow B = b-1$$

$$inv3_28: il_in_10 = FALSE \land il_out_10 = FALSE \Rightarrow B = b$$

```
inv3_29: il\_out_10 = TRUE \land ml\_out_10 = TRUE \Rightarrow C = c
```

$$\text{inv3_30}: \quad il_out_10 = \text{TRUE} \ \land \ ml_out_10 = \text{FALSE} \ \Rightarrow \ C = c+1$$

$$inv3_{-}31: il_out_10 = FALSE \land ml_out_10 = TRUE \implies C = c-1$$

$$\mathrm{inv3_32}: \quad il_out_10 = \mathrm{FALSE} \ \land \ ml_out_10 = \mathrm{FALSE} \ \Rightarrow \ C = c$$

The basic properties hold for the physical cars

inv3_33:
$$A = 0 \lor C = 0$$

$$inv3_34: A+B+C \leq d$$

The number of cars on the bridge and the island is limited

FUN-2

The bridge is one way or the other, not both at the same time

FUN-3

```
\begin{array}{l} \mathsf{ML\_out\_1}\\ \mathbf{when}\\ \underline{ml\_out\_10} = \mathbf{TRUE}\\ \underline{a+b+1} \neq d\\ \mathbf{then}\\ \underline{a:=a+1}\\ \underline{ml\_pass:=1}\\ \underline{ml\_out\_10:=\mathrm{FALSE}}\\ \mathbf{end} \end{array}
```

```
\begin{array}{l} \mathsf{ML\_out\_2} \\ \mathbf{when} \\ \underline{ml\_out\_10} = \mathbf{TRUE} \\ \underline{a+b+1} = d \\ \mathbf{then} \\ \underline{a:=a+1} \\ \underline{ml\_tl:=red} \\ \underline{ml\_pass:=1} \\ \underline{ml\_out\_10:=\mathrm{FALSE}} \\ \mathbf{end} \end{array}
```

```
(	ext{abstract-}) 	ext{ML\_out\_1} \ 	ext{when} \ ml\_tl = 	ext{green} \ a+b+1 
eq d \ 	ext{then} \ a := a+1 \ ml\_pass := 1 \ 	ext{end}
```

```
(abstract-)ML_out_2 when ml\_tl = 	ext{green} a+b+1=d then a:=a+1 ml\_pass:=1 ml\_tl:=	ext{red} end
```

```
\begin{array}{c} \textbf{IL\_out\_1}\\ \textbf{when}\\ \underline{il\_out\_10} = \underline{TRUE}\\ \underline{b} \neq 1\\ \textbf{then}\\ \underline{b} := \underline{b-1}\\ \underline{c} := \underline{c+1}\\ \underline{il\_pass} := 1\\ \underline{il\_out\_10} := \underline{FALSE}\\ \textbf{end} \end{array}
```

```
\begin{array}{c} \text{IL\_out\_2} \\ \textbf{when} \\ \underline{il\_out\_10} = \text{TRUE} \\ b = 1 \\ \textbf{then} \\ b := b-1 \\ c := c+1 \\ \underline{il\_tl} := red \\ \underline{il\_pass} := 1 \\ \underline{il\_out\_10} := \text{FALSE} \\ \textbf{end} \\ \end{array}
```

```
(	ext{abstract-}) 	ext{IL\_out\_1} \  egin{array}{c} 	ext{when} \ il\_tl = 	ext{green} \ b 
eq 1 \ 	ext{then} \ b := b - 1 \ c := c + 1 \ il\_pass := 1 \ 	ext{end} \ \end{array}
```

```
egin{aligned} \mathsf{ML\_in} & \mathsf{when} \\ & \underline{ml\_in\_10} = \mathrm{TRUE} \\ & 0 < c \\ & \mathsf{then} \\ & c := c-1 \\ & \underline{ml\_in\_10} := \mathrm{FALSE} \\ & \mathsf{end} \end{aligned}
```

```
IL_in when  \frac{il\_in\_10 = \text{TRUE}}{0 < a}  then  a := a - 1   b := b + 1   \underline{il\_in\_10 := \text{FALSE}}  end
```

```
(\mathsf{abstract}	ext{-})\mathsf{ML}	ext{-}\mathsf{in} \mathsf{when} 0 < c \mathsf{then} c := c - 1 \mathsf{end}
```

```
(abstract-)IL_in when 0 < a then a := a - 1 b := b + 1 end
```

```
egin{align*} \mathsf{ML\_tl\_green} & \mathsf{when} \\ & \mathit{ml\_tl} = \mathit{red} \\ & \mathit{a} + \mathit{b} < \mathit{d} \\ & \mathit{c} = 0 \\ & \mathit{il\_pass} = 1 \\ & \mathit{il\_out\_10} = \mathsf{FALSE} \\ & \mathsf{then} \\ & \mathit{ml\_tl} := \mathit{green} \\ & \mathit{il\_tl} := \mathit{red} \\ & \mathit{ml\_pass} := \mathsf{FALSE} \\ & \mathsf{end} \\ \end{pmatrix}
```

```
egin{align*} 	ext{L\_tl\_green} & 	ext{when} \ il\_tl = red \ a = 0 \ ml\_pass = 1 \ \underline{ml\_out\_10} = 	ext{FALSE} \ 	ext{then} \ il\_tl := green \ ml\_tl := red \ il\_pass := 	ext{FALSE} \ 	ext{end} \ \end{aligned}
```

```
(abstract-)ML\_tl\_green
when
ml\_tl = red
a+b < d
c=0
il\_pass = 1
then
ml\_tl := green
il\_tl := red
ml\_pass := 0
end
```

```
egin{array}{llll} (abstract-)lL\_tl\_green & & when & & il\_tl = red & & 0 < b & & & a = 0 & & & \\ & & a = 0 & & & & \\ & & ml\_pass = 1 & & \\ & & then & & & il\_tl := green & & & \\ & & & ml\_tl := red & & & \\ & & & il\_pass := 0 & & \\ & & & end & & \\ \end{array}
```

```
egin{aligned} \mathsf{ML\_out\_arr} \ & \mathbf{when} \ & ML\_OUT\_SR = off \ & ml\_out\_10 = \mathrm{FALSE} \ & \mathbf{then} \ & ML\_OUT\_SR := on \ & \mathbf{end} \end{aligned}
```

```
IL_in_arr when IL\_IN\_SR = off il\_in\_10 = \mathrm{FALSE} A>0 then IL\_IN\_SR := on end
```

```
egin{align*} \mathsf{ML\_in\_arr} & \mathsf{when} & ML\_IN\_SR = off \\ ml\_in\_10 = \mathsf{FALSE} \\ C > 0 & \mathsf{then} \\ ML\_IN\_SR := on \\ \mathsf{end} & \mathsf{end
```

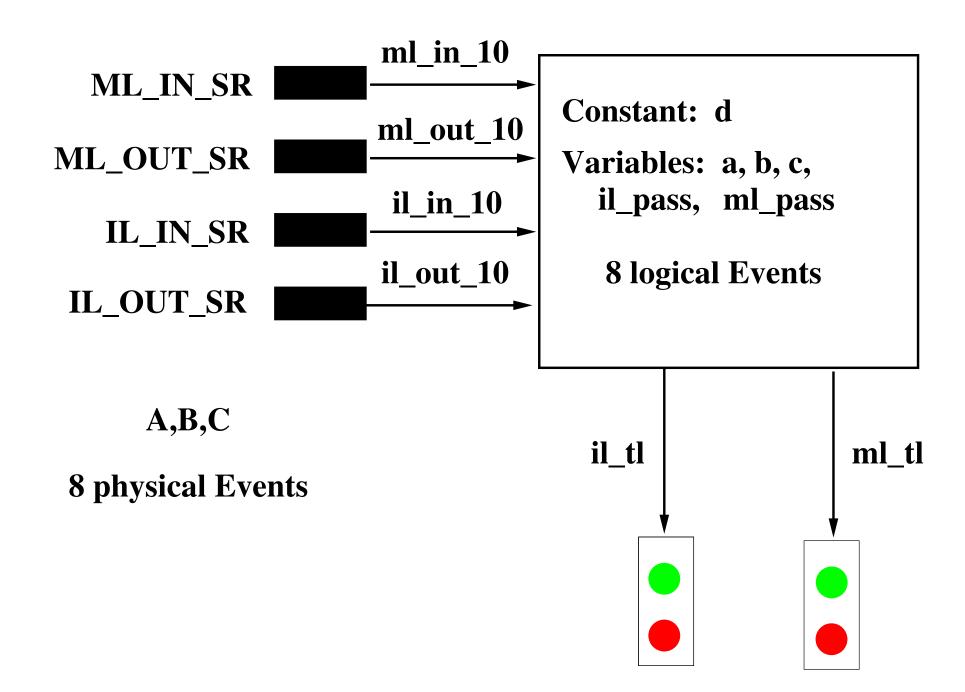
```
egin{aligned} \mathsf{IL\_out\_arr} \\ \mathbf{when} \\ IL\_OUT\_SR &= off \\ il\_out\_10 &= \mathsf{FALSE} \\ B &> 0 \\ \mathsf{then} \\ IL\_OUT\_SR &:= on \\ \mathsf{end} \end{aligned}
```

```
egin{aligned} \mathsf{ML\_out\_dep} \ & \mathsf{when} \ & ML\_OUT\_SR = on \ & ml\_tl = green \ & \mathsf{then} \ & ML\_OUT\_SR := off \ & ml\_out\_10 := \mathrm{TRUE} \ & \mathsf{end} \end{aligned}
```

```
IL_in_dep when IL\_IN\_SR = on then IL\_IN\_SR := off il\_in\_10 := \mathrm{TRUE} A = A - 1 B = B + 1 end
```

```
egin{align*} \mathsf{ML\_in\_dep} \ & \mathsf{when} \ & ML\_IN\_SR = on \ & \mathsf{then} \ & ML\_IN\_SR := off \ & ml\_in\_10 := \mathrm{TRUE} \ & C = C - 1 \ & \mathsf{end} \ &
```

```
egin{aligned} 	ext{L_out\_dep} & 	ext{when} \ IL\_OUT\_SR = on \ il\_tl = green \ 	ext{then} \ IL\_OUT\_SR := off \ il\_out\_10 := 	ext{TRUE} \ B = B - 1 \ C = C + 1 \ 	ext{end} \end{aligned}
```



- What is to be systematically proved?
 - Invariant preservation
 - Correct refinements of transitions
 - No divergence of new transitions
 - No deadlock introduced in refinements

- When are these proofs done?

- Who states what is to be proved?
 - An automatic tool: the Proof Obligation Generator
- Who is going to perform these proofs?
 - An automatic tool: the Prover
 - Sometimes helped by the Engineer (interactive proving)

About Tools 266

Three basic tools:

- Proof Obligation Generator
- Prover
- Model translators into Hardware or Software languages
- These tools are embedded into a Development Data Base
- Such tools already exist in the Rodin Platform

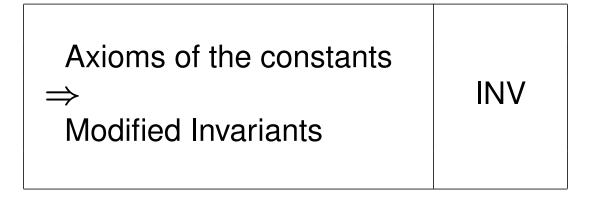
- This development required 253 proofs
 - Initial model: 7 (0)
 - 1st refinement: 27 (0)
 - 2nd refinement: 81 (1)
 - 3rd refinement: 138 (3)
- All proved automatically (except 4) by the Rodin Platform

$P \ \land \ Q$	conjunction
$P \ \lor \ Q$	disjunction
$P \Rightarrow Q$	implication
$\neg P$	negation
$x \in S$	set membership operator

N	set of Natural Numbers: $\{0,1,2,3,\ldots\}$
\mathbb{Z}	set of Integers: $\{0,1,-1,2,-2,\ldots\}$
$\{a,b,\ldots\}$	set defined in extension
a+b	addition of a and b
a-b	subtraction of a and b

a*b	product of a and b
a=b	equality relation
$a \leq b$	smaller than or equal relation
a < b	smaller than relation

- For the init event in the initial model



- For other events in the initial model

Axioms of the constants
Invariants
Guard of the event

→
Modified Invariants

- This rule is not mandatory

Axiom of the constant
Invariants

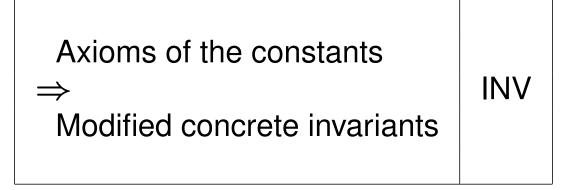
⇒
Disjunction of the guards

- For old events only

Axioms of the constants
Abstract invariants
Concrete invariants
Concrete guards

Abstract guards

- For init event only



- For all events (except init)

- New events refine an implicit non-guarded event with skip action

Axioms of the constants
Abstract invariant
Concrete invariant
Concrete guard

→
Modified concrete invariant

Refinement Rules (4): Non-divergence of New Events

- For new events only

Axioms of the constants
Abstract invariants
Concrete invariants
Concrete guard of a new event \Rightarrow Variant $\in \mathbb{N}$

Refinement Rules (5): Non-divergence of New Events

- For new events only

Axioms of the constants Abstract invariants Concrete invariants Disj. of abs. guards

 \Rightarrow

Disj. of conc. guards

VAR

Refinement Rules (6): Relative Deadlock Freeness

- Global proof rule

Axioms of the constants
Abstract invariants
Concrete invariants
Disjunction of abstract guards

DLF

 \Rightarrow

Disjunction of concrete guards

- For old events (in case of superposition)

Axioms of constants
Abstract invariants
Concrete invariants
Concrete guards

⇒
Same actions on common variables