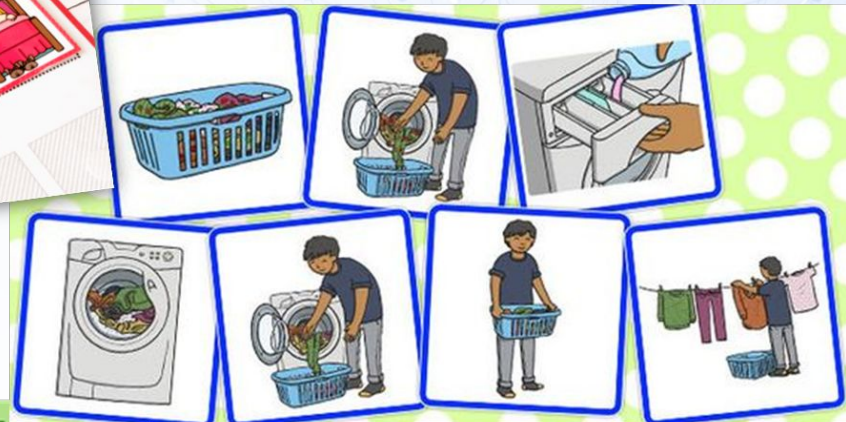




Lesson 2:

Sequence learning in a Tree task

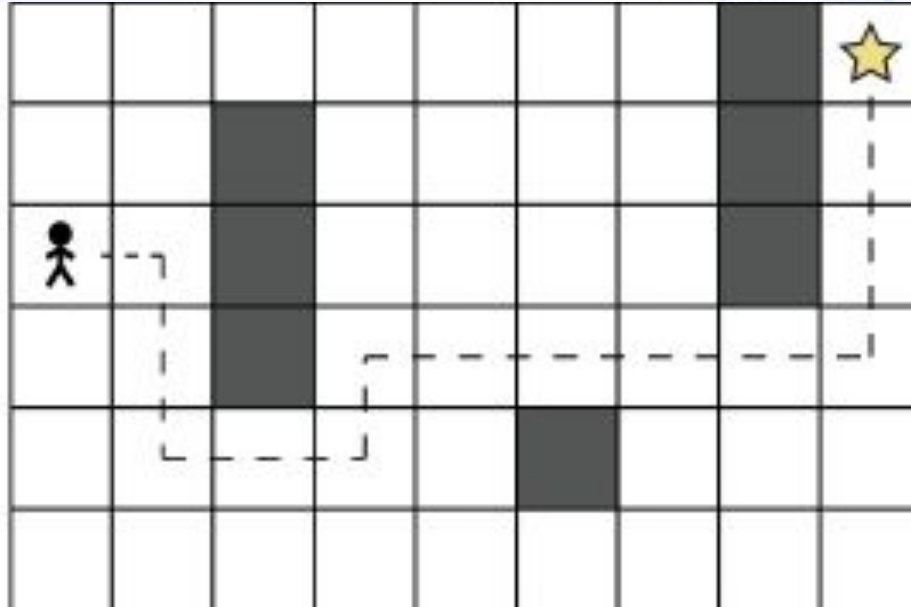


<https://lifeovercs.com/daily-tasks-story-sequencing-activities-for-preschoolers/>

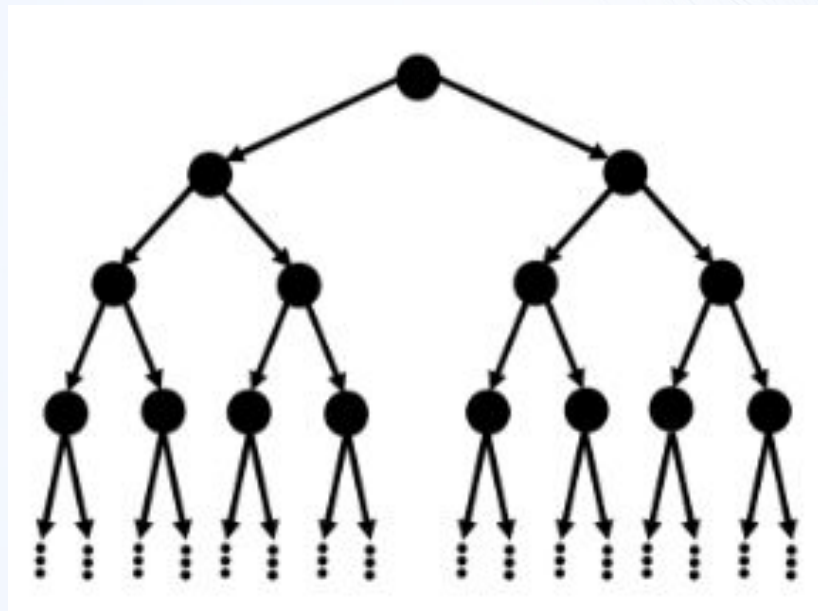
Sequence Learning



Sequence Learning



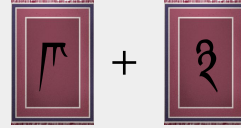
Sequence Learning



Model-free learning

(Two-step task with deterministic transitions)

State 1

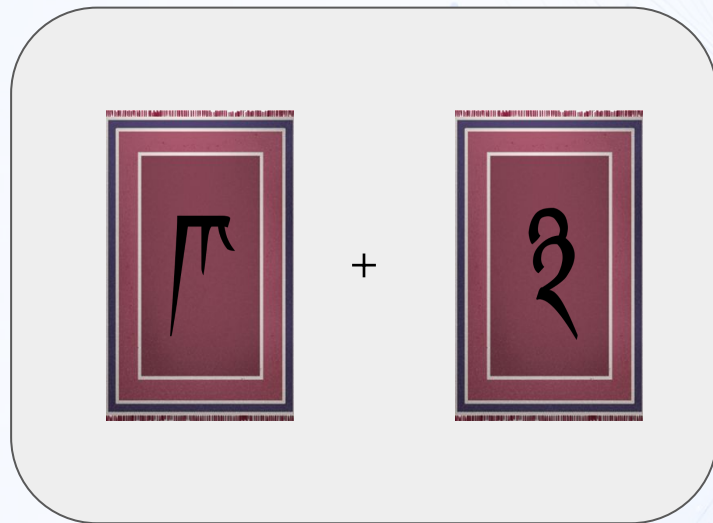


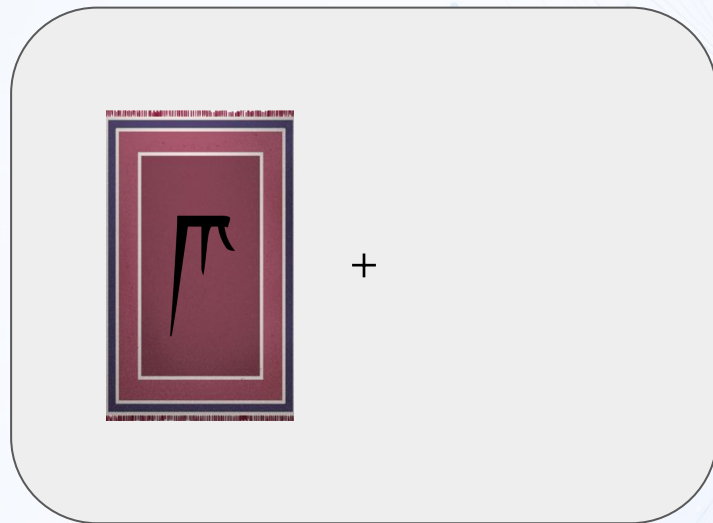
State 2

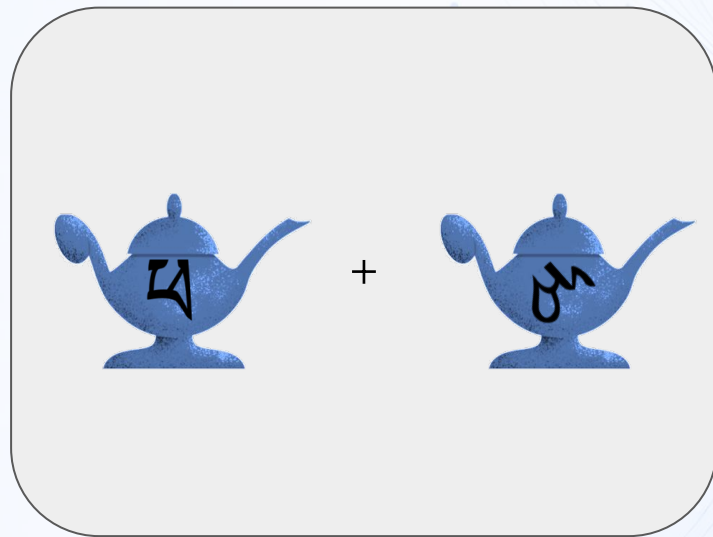


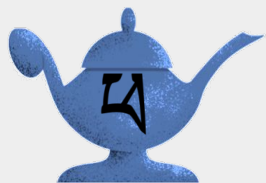
State 3





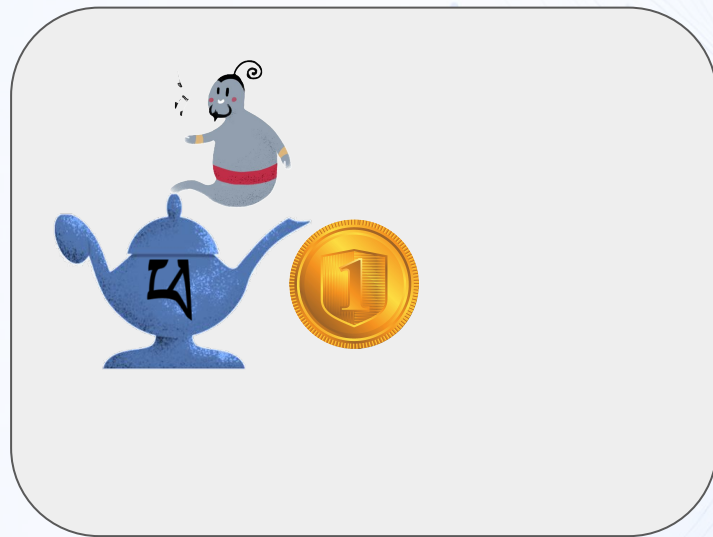


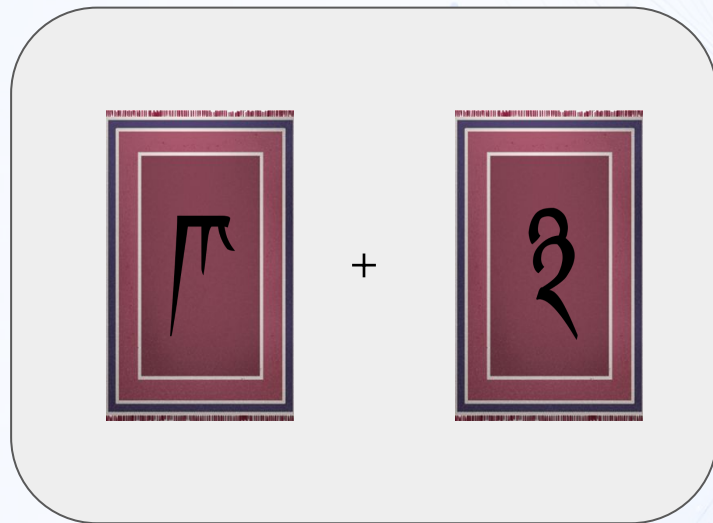




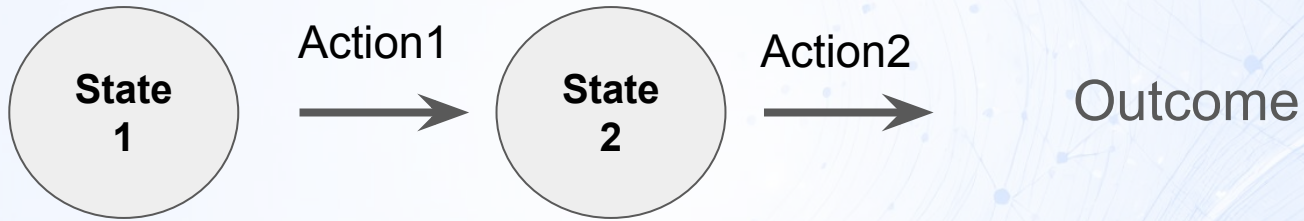
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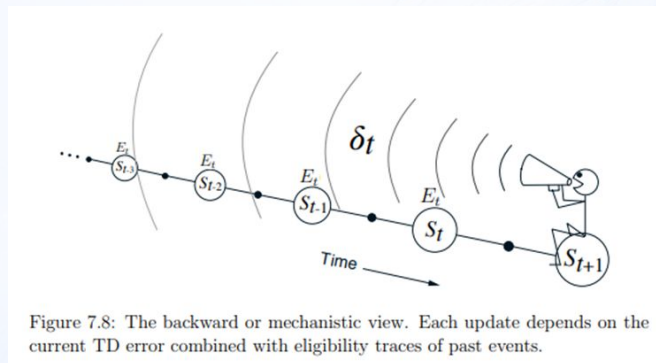
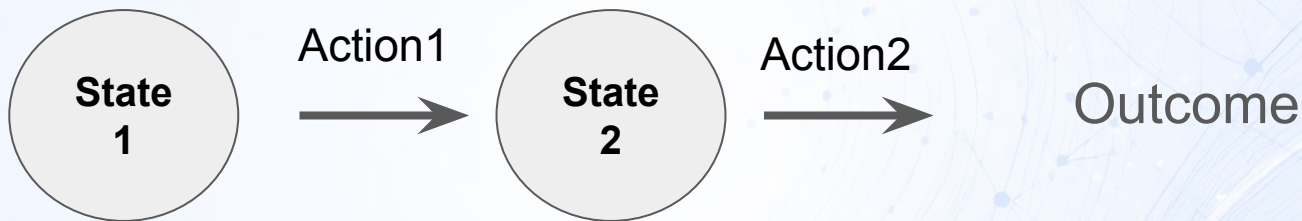




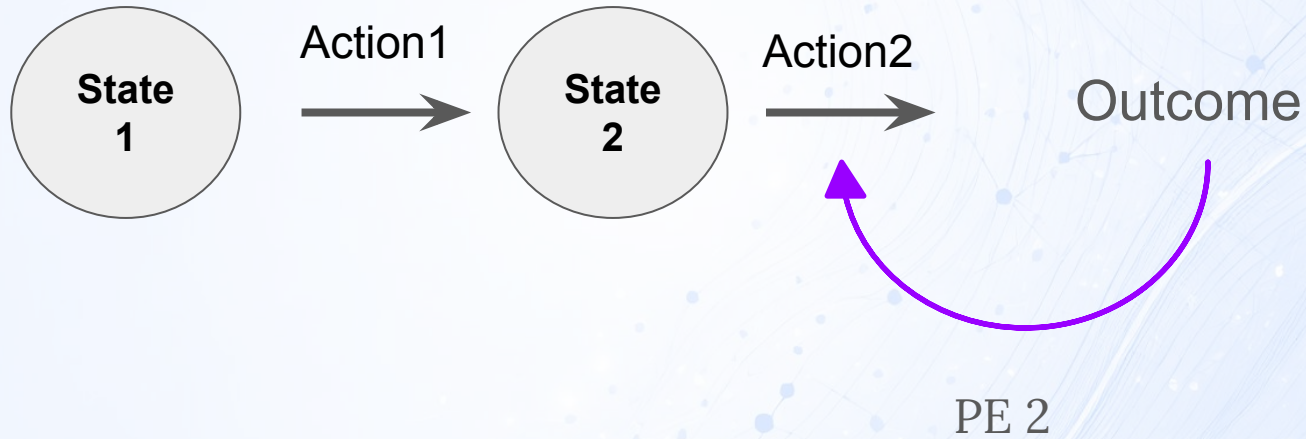
Model-free sequence learning



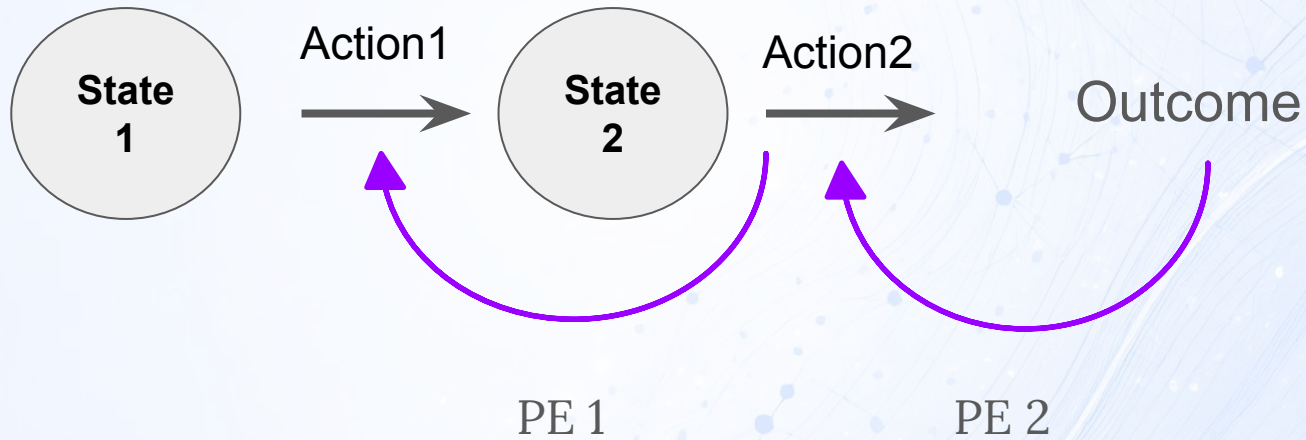
Model-free sequence learning



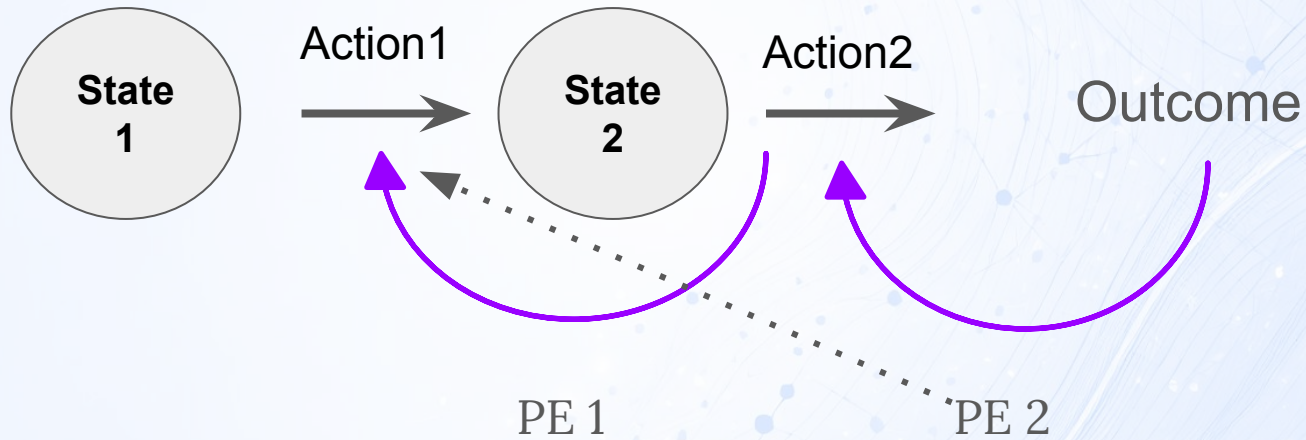
Model-free sequence learning



Model-free sequence learning



Model-free sequence learning



Model-free sequence learning

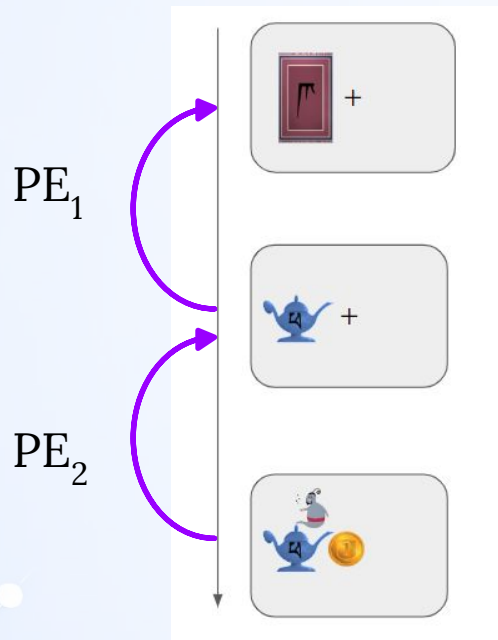
Parameters

α - Learning rate

β - Inverse temperature

λ - Eligibility factor, determines the decay rate of the eligibility traces

Model-free sequence learning



Action value updating

$$PE_1 = Q(s_2, a_1)_t - Q(s_1, a_1)_t$$

$$PE_2 = r_t - Q(s_2, a_1)_t$$

$$Q(s_1, a_1)_{t+1} = Q(s_1, a_1)_t + \alpha \cdot PE_1 + \alpha \cdot \lambda \cdot PE_2$$

$$Q(s_2, a_1)_{t+1} = Q(s_2, a_1)_t + \alpha \cdot PE_2$$

Model-free sequence learning

Action selection

$$P(s_1, a_t = 1) = \frac{e^{\beta \cdot Q(s_1, a_1)t}}{e^{\beta \cdot Q(s_1, a_1)t} + e^{\beta \cdot Q(s_1, a_2)t} + e^{\beta \cdot Q(s_2, a_1)t}}$$

$$P(s_2, a_t = 1) = \frac{e^{\beta \cdot Q(s_2, a_1)t} + e^{\beta \cdot Q(s_2, a_2)t}}{e^{\beta \cdot Q(s_2, a_1)t} + e^{\beta \cdot Q(s_2, a_2)t}}$$

Model-free sequence learning

Step-by-step:

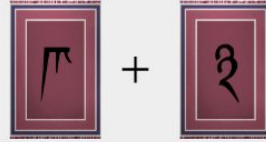
1

simulating artificial behavior

2

estimate parameters

State 1



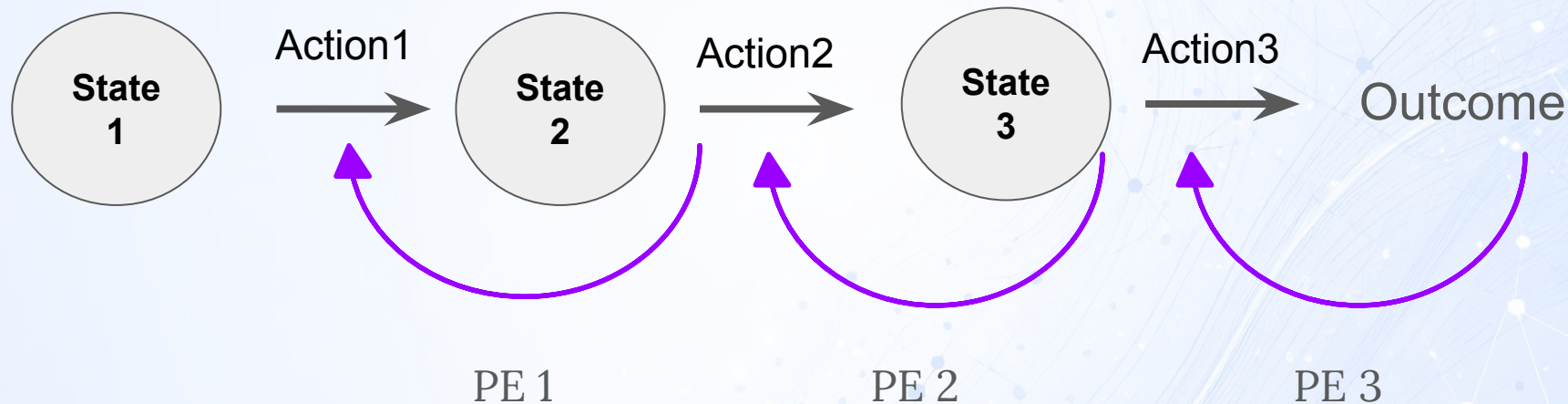
State 2



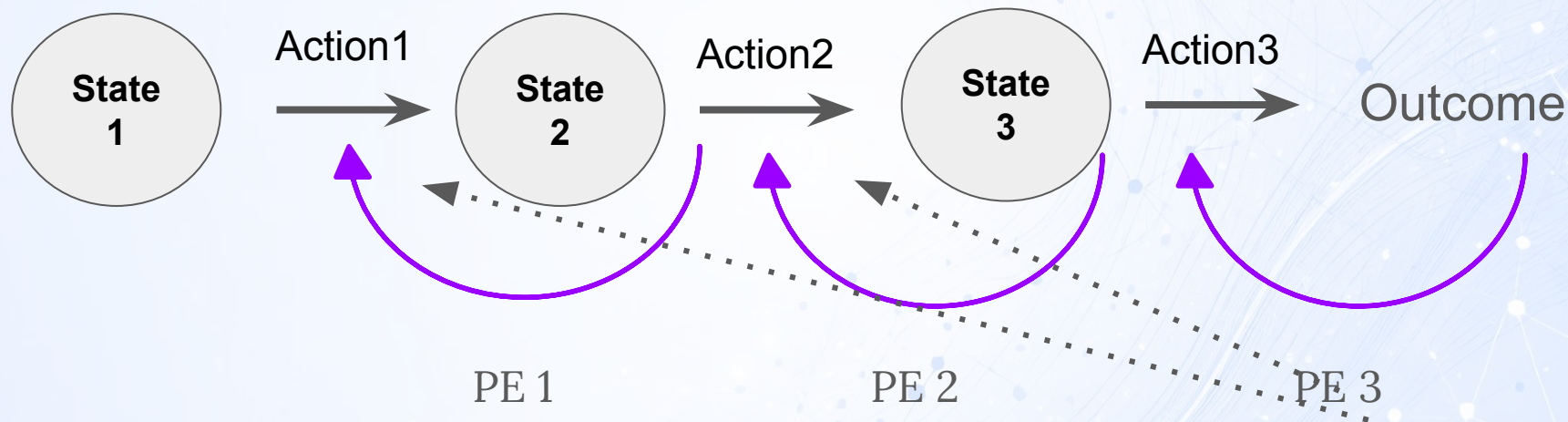
State 3



Model-free sequence learning



Model-free sequence learning



Model-free sequence learning

