

Jacobs University Bremen

Lab Report 3 - Filters

Spring Semester 2023

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Conducted on: **March 16, 2023**

1. Introduction

The objective of the experiment is to show the behavior of simple passive RC circuits acting as filters, one low pass and one high pass, with a sinusoid of different frequencies as an input signal. We measure the properties of these circuits, and we analyze the result of the measurements and how they are represented.

A filter is a network used to select a frequency or range of frequencies while rejecting all others. Usually, they are constructed using active components like transistors or operational amplifiers, however we can also see similar behavior in passive networks of resistors, capacitors, and inductors. There are four general types. High Pass, Low Pass, Band Pass, and Notch Filters.

In our experiment, we analyze Lo-Pass and Band-Pass filters which are simple in nature, only using passive components such as inductors, capacitors, and resistors.

Furthermore, we will use the Bode plot to analyze the frequency response of these filters, and we will use the Nyquist plot to describe the parametric plot of the frequency response of the filters.

1.1 Lo-Pass

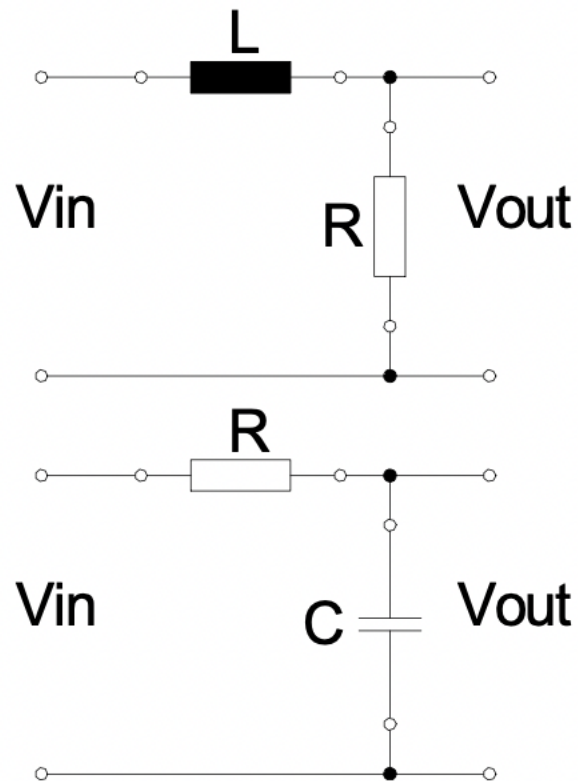


Figure 1.1: Low Pass Filter

A low pass filter allows low frequencies to pass, while it hinders higher frequencies. With high frequencies, the phase shift of the output signal becomes negative relative to the input signal.

It can be designed using a resistor and a capacitor, or an inductor and a resistor. In general, we can get the amplitude ratio of the output signal to the input signal by using the following equation:

For an RC circuit, which is what we design in the experiment:

$$\underline{A} = \frac{V_{out}}{V_{in}} = \frac{1}{1 + j\omega RC} \quad (1.1)$$

To obtain the cutoff frequency, we can use the following equation:

$$\underline{f_c} = \frac{1}{2\pi RC} \quad (1.2)$$

To obtain the amplitude and phase of the output signal, we use the following equations:

$$|\underline{A}| = \frac{1}{\sqrt{1 + (\omega RC)^2}} \text{ and } \phi = -\arctan(\omega RC) \quad (1.3)$$

1.2 Hi-Pass

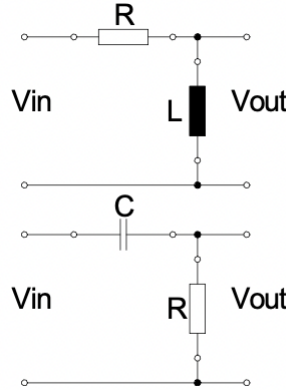


Figure 1.2: High Pass Filter

A high pass filter allows higher frequencies to pass through and attenuates lower frequencies. It can be designed using a resistor and a capacitor, or an inductor and a resistor.

The transfer function is described by:

$$\underline{A} = \frac{1}{1 + \frac{1}{j\omega RC}} \quad (1.4)$$

The amplitude is described by:

$$|A| = \frac{1}{\sqrt{1 + \frac{1}{(\omega RC)^2}}} \quad (1.5)$$

And the phase is described by:

$$\phi = \arctan\left(\frac{1}{\omega RC}\right) \quad (1.6)$$

To find the cutoff frequency for both the low pass and high pass filter for an RC circuit, we use the following relation:

$$f_{-3dB} = \frac{1}{2\pi RC} \quad (1.7)$$

1.3 Band-Pass

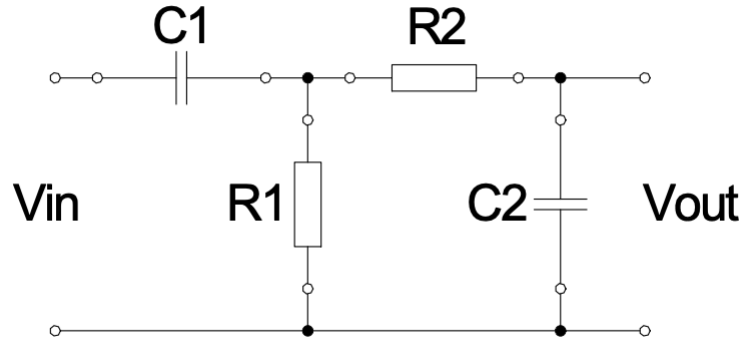


Figure 1.3: Band Pass Filter

A simple band pass filter is simply a combination of a high and low pass filter. It passes through frequencies within a certain range, and attenuates frequencies outside of it. The formula for the amplitude ratio is the same as the low pass filter, but we have to take into account the high pass filter as well. The formula for the cutoff frequency is also the same as the low pass, and high pass filter (1.2).

1.4 Obtaining the characteristic output of a filter

To describe the frequency response of these kinds of networks, we use the Bode plot. We plot the amplitude to frequencies over several decades, and the ratio is calculated. The unit of the result is **decibels**, or **dB**. **dB** is a logarithmic value used for such purposes. It is defined as:

$$A = 20 \cdot \log_{10} \frac{V_{out}}{V_{in}} \quad (1.8)$$

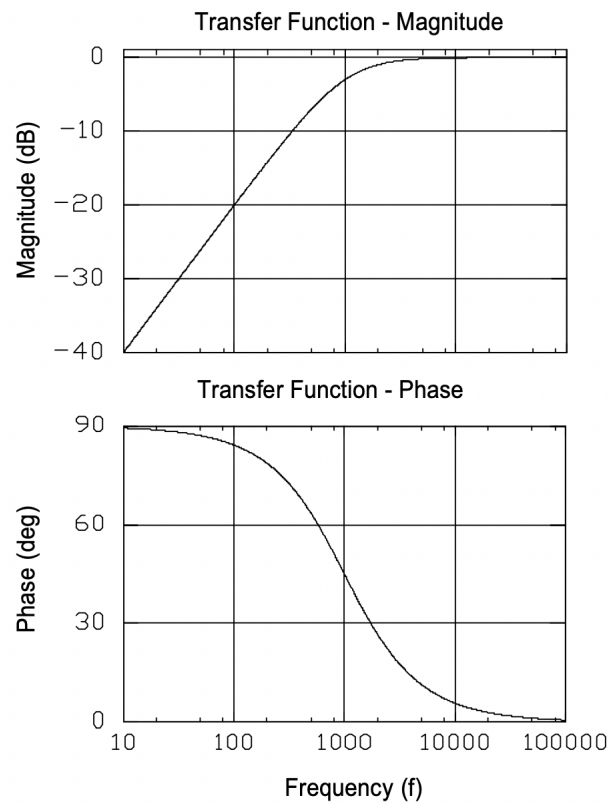


Figure 1.4: A bode plot, showing the magnitude plotted against the frequency, and the phase shift plotted against the frequency.

The other quantity measured is the phase shift ϕ between the input and output signal, taken relative to the input signal. When the output signal is ahead the input, the phase shift ϕ is positive, otherwise it is negative.

A **Nyquist plot** is a parametric plot of a frequency response. In Cartesian coordinates, the real part of the transfer function is plotted on the X axis. The imaginary part is plotted on the Y axis. The frequency is swept as a parameter, resulting in a plot per frequency.

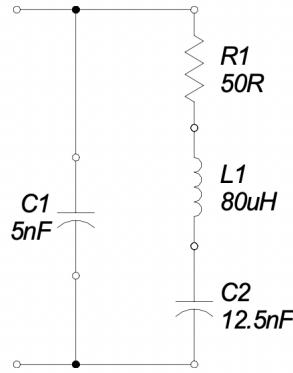


Figure 1.5: An RLC circuit with a capacitor in parallel.

We wish to find how the complex conductance changes when ω changes, given that the impedance for the RLC series circuit is

$$\underline{Z}_S = R_1 + j(\omega L_1 - \frac{1}{\omega C_2})$$

and with the parallel capacitor the admittance is

$$\underline{Y}_{all} = j\omega C_1 + \frac{1}{\underline{Z}_S}$$

When varying ω , a Nyquist plot is generated. The right plot is $\frac{1}{\underline{Y}_{all}}$

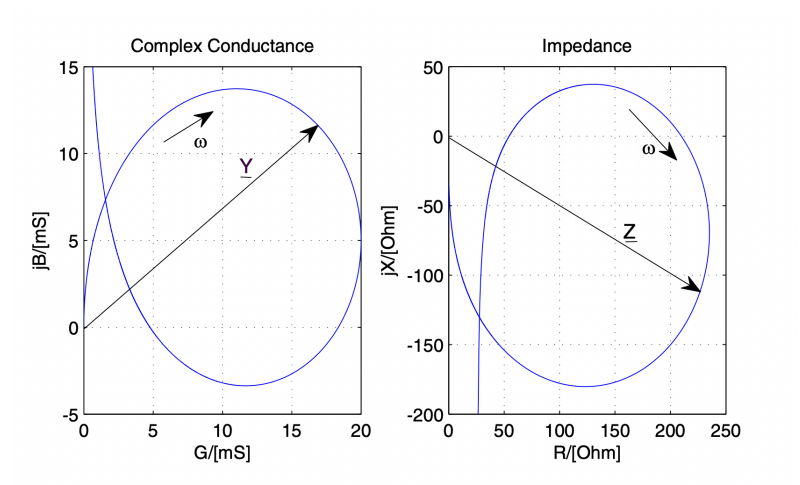


Figure 1.6: The nyquist plot of the RLC circuit.

2. Execution

Equipment: Oscilloscope, Function Generator, BNC-to-Kleps cable.

2.1 Part 1 : Lo-Pass

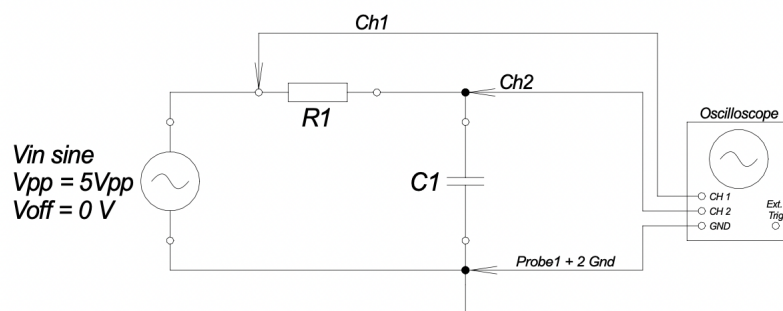


Figure 2.1: $C_1 = 1.5\text{nF}$ and $R_1 = 22\text{K}\Omega$

The signal generator is connected via the BNC-To-Kleps cable. The CH1 channel is used for the input, and the CH2 channel is used for the output. The frequency at the signal generator is then varied in steps of 1, 2, 5, 10 steps up to 100KHz.

Input Voltage(in V)	Output Voltage(in V)	Phase(in deg)	Frequency(in Hz)	Amplitude(in dB)
10.1	10	-0.36	50	-0.09
10.1	10	-0.36	100	-0.09
10.1	10	-2.59	200	-0.09
10.2	10	-6.49	500	-0.17
10.4	10.1	-11.8	1000	-0.25
10.9	10	-23	2000	-0.75
12.2	8	-47.4	5000	-3.67
11.8	5.04	-64	10000	-7.39
12.4	2.8	-75.3	20000	-12.93
11.8	1.14	-82.8	50000	-20.30
11.8	0.596	-84.6	100000	-25.93

Table 2.1: The effect of the frequency on the output amplitude is shown in the table above.

What we see is that the phase shift goes from positive to negative the further we increase the frequency, and that the output amplitude gets smaller and smaller. This is expected as we have built a low-pass filter.

2.2 Part 2 : Band-Pass

To determine the properties of a band-pass filter, we had two possible RC combinations. One combination would lead to a high pass filter, and the other would lead to a low pass filter.

We had two resistors, one of $82K\Omega$ and one of $10.0K\Omega$. We also had two capacitors, one of $1.5nF$ and one of $100nF$.

To determine the right combination, we used the formula for the cutoff frequency of a high and low pass filter:

$$f_c = \frac{1}{2\pi RC} \quad (2.1)$$

And plugging in the values for $R=82K\Omega$ and $C=1.5nF$, we get:

$$f_c = \frac{1}{2\pi \cdot 82K\Omega \cdot 1.5nF} = 12939.42Hz \quad (2.2)$$

Which is the low pass filter, as the cutoff frequency is the greatest out of all the other combinations.

And plugging in the values for $R=10K\Omega$ and $C=100nF$, we get:

$$f_c = \frac{1}{2\pi \cdot 10K\Omega \cdot 100nF} = 159.15Hz \quad (2.3)$$

Which is the high pass filter, as the cutoff frequency is the smallest out of all the other combinations.

We use a sine signal with a 5Vpp amplitude without an offset at the function generator. We vary the frequency of the generator from 50Hz all the way to 100kHz. We use the oscilloscope to measure the input and output amplitude, and we record the following values:

Input Voltage(in V)	Output Voltage(in V)	Phase(in deg)	Frequency(in Hz)	Amplitude(in dB)
10.4	2.92	73.4	50	-11.03
10.4	5.2	53	100	-6.02
10	7.68	38.8	200	-2.29
10	9.44	16.5	500	-0.50
10.4	10	4.32	1000	-0.34
10.9	10.5	-4.04	2000	-0.32
11.6	10.5	-19.4	5000	-0.87
11.6	9.12	-37.7	10000	-2.09
11.6	6.4	-55	20000	-5.17
11.6	2.92	-73.4	50000	-11.98
12.4	1.54	-80.5	100000	-18.12

Table 2.2: The effect of the frequency on the output amplitude is shown above. We see what we expect: Between certain frequencies the amplitude is greater, while when going as high as 100kHz or as low as 50Hz we notice a significant decline.

3. Evaluation

3.1 Part 1

Below are the results of the low pass filter. The measured frequencies and amplitudes are then plotted on a bode plot.

Input Voltage(in V)	Output Voltage(in V)	Phase(in deg)	Frequency(in Hz)	Amplitude(in dB)
10.1	10	-0.36	50	20.00
10.1	10	-0.36	100	20.00
10.1	10	-2.59	200	20.00
10.2	10	-6.49	500	20.00
10.4	10.1	-11.8	1000	20.09
10.9	10	-23	2000	20.00
12.2	8	-47.4	5000	18.06
11.8	5.04	-64	10000	14.05
12.4	2.8	-75.3	20000	8.94
11.8	1.14	-82.8	50000	1.14
11.8	0.596	-84.6	100000	-4.50

Table 3.1: The measured frequencies and amplitudes from the low pass filter.

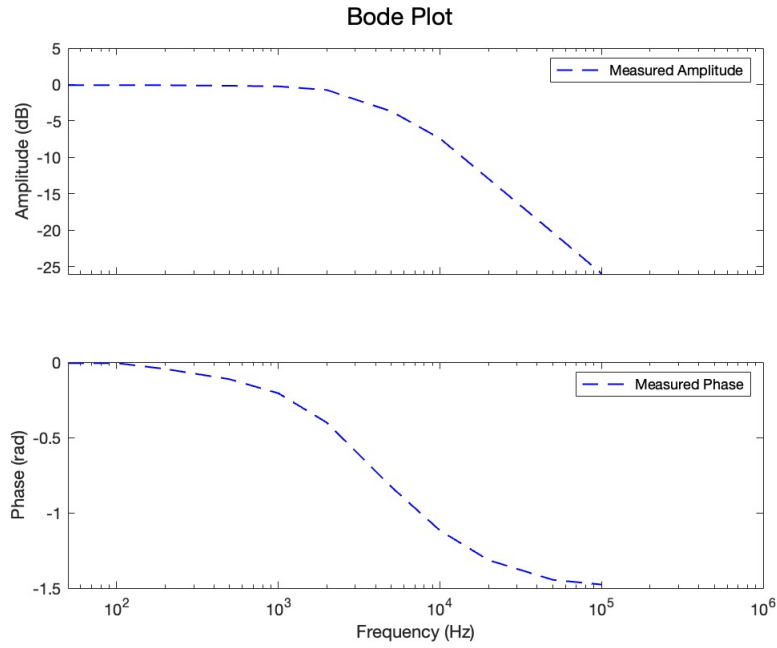


Figure 3.1: Bode plot of measured frequencies, amplitudes and phase shifts of the low pass filter.

To draw the bode plot of the calculated amplitudes and phase, we use the following formulas: $|A| = \frac{1}{\sqrt{1+(\omega RC)^2}}$ and $\phi = -\arctan(\omega RC)$

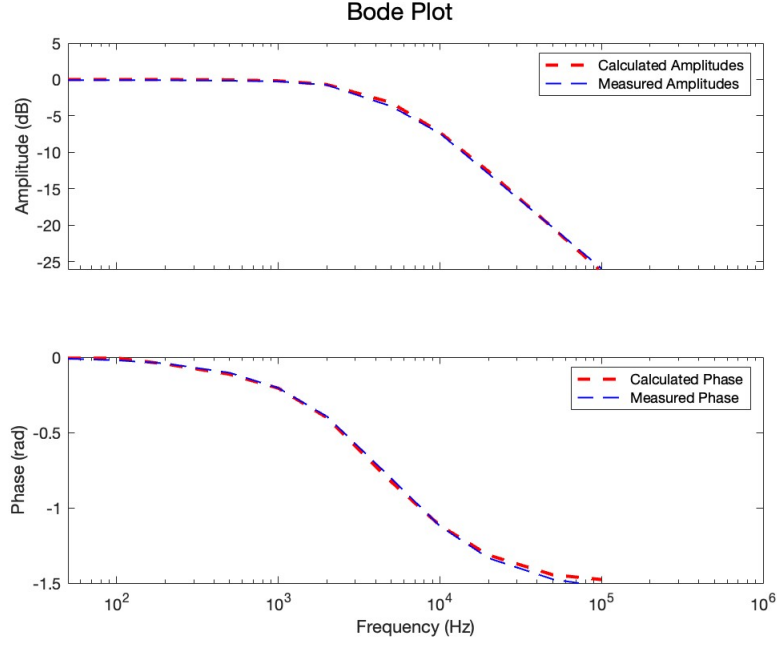


Figure 3.2: Bode plot of calculated amplitudes and phase shifts of the low pass filter using measured frequencies.

The calculated cutoff frequency can be obtained by the following relation for the low pass filter circuit:

$$f_{-3dB} = \frac{1}{2\pi RC} \quad (3.1)$$

Where the cutoff frequency becomes

$$f_{-3dB} = \frac{1}{2\pi(22 \cdot 10^3 \Omega) \cdot (1 \cdot 10^{-9} F)} = 4822.8 Hz \quad (3.2)$$

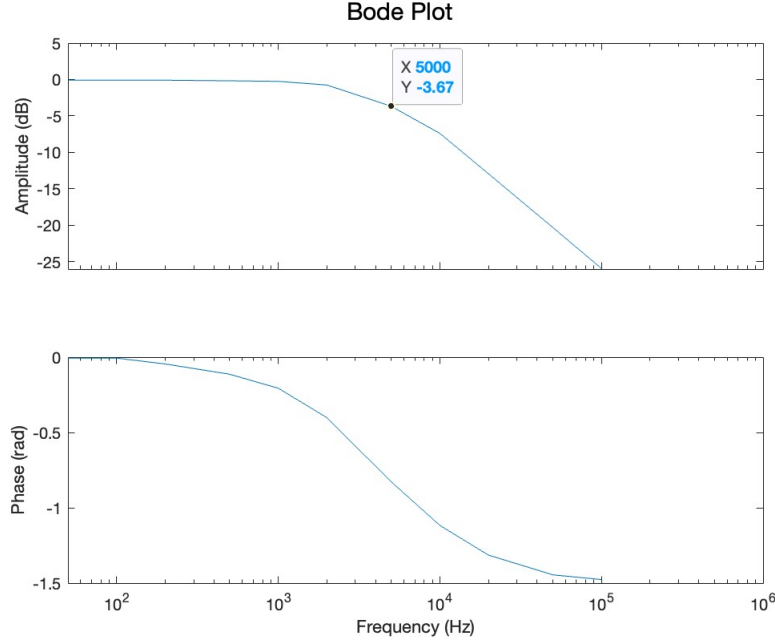


Figure 3.3: Bode plot of measured amplitudes and phase shifts of the low pass filter using measured frequencies.

Comparing against the cutoff frequency of the measured wave, we see that it is quite within range of the calculated cutoff frequency of 4822.8Hz.

To find the gradient of $|A|$, we find the derivative of the magnitude of the transfer function:

$$\frac{d|A|}{df} = \frac{d}{df} \left(\frac{1}{\sqrt{1 + (\omega RC)^2}} \right) = \frac{-(2 * (2\pi f RC) * (2\pi RC))}{2(1 + (2\pi f RC)^2)^{\frac{3}{2}}} = -\frac{(4\pi^2 R^2 C^2) f}{(1 + 4\pi^2 f^2 R^2 C^2)^{\frac{3}{2}}} \quad (3.3)$$

Taking the limit of $|A| = \frac{1}{\sqrt{1 + (\omega RC)^2}}$ and the limit of $\phi = -\tan^{-1}(\omega RC)$, we get the following table:

Case	Behaviour of f	Amplitude	Phase
$f \gg f_{-3dB}$	$f \rightarrow \infty$	0	-90°
$f = f_{-3dB}$	$f \rightarrow f_{-3dB}$	$\frac{1}{\sqrt{2}}$	-45°
$f \ll f_{-3dB}$	$f \rightarrow 0$	1	0°

Table 3.2: The behavior of the frequency depending on the case of f_{-3dB}

By this table we can infer that when the frequency is under that of the cutoff frequency, the ratio is one - the filter should ideally let the signal pass through without attenuation and any phase shift. We can also infer that when the frequency is that of the cut-off frequency, we get the amplitude and the phase of the corner frequency. Lastly, we can infer that when the frequency is way greater than the cut-off frequency, the amplitude is zero and the phase is -90° .

3.2 Part 2

Below are the results of the band-pass filter. The measured frequencies and amplitudes are then plotted on a bode plot.

Input Voltage(in V)	Output Voltage(in V)	Phase(in deg)	Frequency(in Hz)	Amplitude(in dB)
10.4	2.92	73.4	50	-11.03
10.4	5.2	53	100	-6.02
10	7.68	38.8	200	-2.29
10	9.44	16.5	500	-0.50
10.4	10	4.32	1000	-0.34
10.9	10.5	-4.04	2000	-0.32
11.6	10.5	-19.4	5000	-0.87
11.6	9.12	-37.7	10000	-2.09
11.6	6.4	-55	20000	-5.17
11.6	2.92	-73.4	50000	-11.98
12.4	1.54	-80.5	100000	-18.12

Table 3.3: The measured input voltage, output voltage, phase, and amplitude ratio in dB

We then plot the frequency response on the bode plot as shown below:

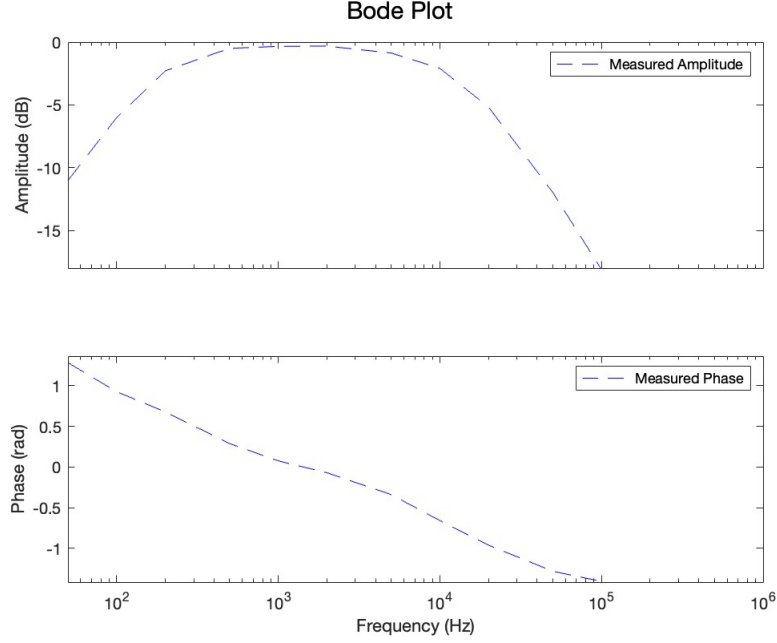


Figure 3.4: Bode plot of measured frequencies, amplitudes and phase shifts of the band pass filter.

Furthermore, to obtain the calculated amplitude and phase of the bandpass filter, one must use the appropriate formulas:

$$|A_{lo}| = \frac{1}{\sqrt{1 + (\omega RC)^2}} \text{ and } \phi_{lo} = -\arctan(\omega RC) \text{ for the low pass filter, and}$$

$$|A_{hi}| = \frac{1}{\sqrt{1 + 1/(\omega RC)^2}} \text{ and } \phi_{hi} = \arctan\left(\frac{1}{\omega RC}\right) \text{ for the high pass filter}$$

To combine these results, the low and high amplitudes are multiplied, and the phases are added.

$$|A_{total}| = |A_{hi}| * |A_{lo}| \text{ and } \phi_{total} = \phi_{hi} + \phi_{lo}$$

Using this methodology, we can compose a graph of calculated amplitude and phase values and compare it to our measured values.

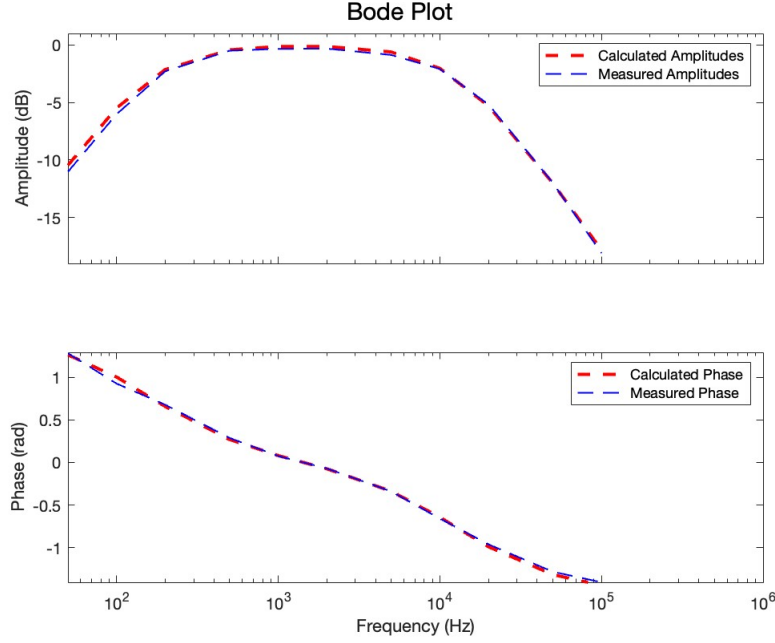


Figure 3.5: Bode plot of calculated phase and amplitude vs the bode plot of the measured phase and amplitude.

We see that the calculated values are very close, almost superimposed. This means that our measured values are as expected, and very close to the nominal amplitude and phase.

To calculate the lower and upper cut-off frequencies, we have to treat each component of the band-pass filter (high and low pass) independently.

We find that for the high-pass component's frequency:

$$f_{-3dB} = \frac{1}{2\pi \cdot 10^4 \cdot 10^{-7}} = 159.15\text{Hz} \quad (3.4)$$

and for the low-pass component's frequency:

$$f_{-3dB} = \frac{1}{2\pi \cdot 8200 \cdot 1.5 \cdot 10^{-9}} = 12939\text{Hz} \quad (3.5)$$

The center frequency is then defined as the root of the multiple of both components' frequencies, so:

$$f_c = \sqrt{f_{c,lo} \cdot f_{c,hi}} = \sqrt{12939 \cdot 159.15} = 1435\text{Hz} \quad (3.6)$$

The bandwidth is simply the difference between the components, so

$$B = f_{c,lo} - f_{c,hi} = 12939 - 159.15 = 12779.85\text{Hz} \quad (3.7)$$

The phase shift, ϕ , at the cutoff frequencies is calculated for their respective component:

$$\phi_{hi} = \arctan\left(\frac{1}{2\pi \cdot 12779.85 \cdot 8200 \cdot 1.5 \cdot 10^{-9}}\right) = 45^\circ \quad (3.8)$$

And for the low pass component:

$$\phi_{hi} = -\arctan(2\pi \cdot 159.15 \cdot 10^4 \cdot 10^{-7}) = -45^\circ \quad (3.9)$$

So the total phase shift, by summation:

$$\phi_{total} = \phi_{hi} + \phi_{lo} = 45^\circ - 45^\circ = 0^\circ \quad (3.10)$$

The results of the measurements are very close to the calculations. The only error that we encounter is from the measurements of the oscilloscope, and due to the passive components used not being completely ideal.

To obtain the Nyquist plot of the band-pass filter, we multiply the transfer functions of the low-pass and high-pass components, and then multiply by the input voltage.

$$U_R(\omega) = (H_{lo}(j\omega) \cdot H_{hi}(j\omega)) \cdot V_{in} \quad (3.11)$$

$$U_R(\omega) = \frac{1}{(C_1 \cdot R_1 \cdot j\omega + 1) \left(\frac{1}{C_2 \cdot R_2 \cdot j\omega} + 1\right)} V_{in} \quad (3.12)$$

Where we have established that $\omega = 2\pi f$.

The nyquist plot is then drawn using MATLAB.

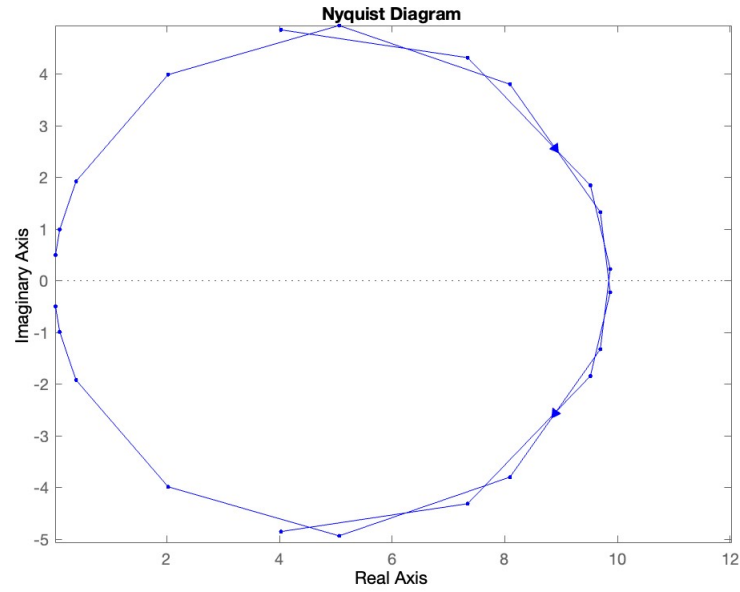


Figure 3.6: Nyquist plot of the bandpass filter, composed of the transfer function of the high pass filter and the low pass filter. Found using MATLAB's nyquist function with the combined transfer functions of the low and high pass filter, with the frequencies we have tested ranging from 50Hz to 100kHz.

4. Conclusion

In conclusion, we examined the bode plot, and thereby frequency response of a low pass filter and a band-pass filter. The low pass filter was measured in the lab using the oscilloscope, using a simple passive component-based RC circuit.

To analyze the band-pass filter, we also included a nyquist plot. The calculated values were very close to the measured values, and the only error source are the passive elements themselves not being entirely ideal, and the oscilloscope's measurements. The values were as expected, and the cut-off frequencies lined up nicely with what we measured.

Furthermore, we learned how the product of transfer functions can be used to identify more complex filters, such as the band-pass filter, which while simple in nature is very useful in proving the usefulness of transfer functions.

We found that taking the limit of the low pass filter as the frequency is greater than the cut-off frequency, the amplitude tends to zero, and the phase to -90 degrees, which was observed in our plots as well. We also found that taking the limit of the low pass filter as the frequency is just at the cut-off frequency, we get a phase shift of about -45 degrees, and as the frequency tends to zero, the amplitude is maximized and the phase is 0 degrees.

The band-pass filter was also built and it was shown to only let a range of frequencies pass through, where an increasing frequency around the center frequency range (about 1000-2000Hz) would result in a larger amplitude, and a decreasing frequency or a larger one would result in a smaller amplitude.

5. References

- Gen EE 2 - CH-211-B Manual
- Google Sheets
- MATLAB
- CH-211-A Lecture 2 - Frequency Response Analysis