

1 Stabilizing LUFFY Training on Hard Problems with Human 2 Reference Solutions

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4 ABSTRACT

5 LUFFY (Learning to Reason under Off-Policy Guidance) extends
6 GRPO by mixing off-policy oracle traces with on-policy rollouts
7 for reinforcement learning of reasoning models. However, LUFFY
8 fails to train stably when applied to hard problems with human
9 reference solutions, a regime where the base model achieves zero
10 on-policy reward and human traces are far out-of-distribution. We
11 identify three compounding pathologies behind this instability: (1)
12 extreme importance-ratio variance from distribution mismatch be-
13 tween human and model traces, (2) a pure-imitation trap caused by
14 zero on-policy reward, and (3) entropy collapse enabled by LUFFY’s
15 removal of importance-ratio clipping. We propose and evaluate
16 three stabilization strategies in a controlled simulation framework
17 that preserves the mathematical structure of the underlying opti-
18 mization dynamics: sequence-level importance ratios with adaptive
19 off-policy mixing, bridged traces via distribution-gap reduction, and
20 a prefix-guided hybrid that fuses POPE’s on-policy prefix mecha-
21 nism with LUFFY’s mixed-group advantage computation. All three
22 stabilization strategies successfully control importance-ratio mag-
23 nitudes, reducing maximum ratios from 2.85 (vanilla LUFFY) to
24 below 1.01, while preserving policy entropy near the theoretical
25 maximum of 3.912 nats. Across five random seeds, the stabilized
26 methods achieve zero divergence with entropy variance below 0.001
27 nats.

32 KEYWORDS

33 reinforcement learning, large language models, off-policy learning,
34 importance sampling, training stability, mathematical reasoning

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41 1 INTRODUCTION

43 Reinforcement learning from human feedback and verifiable re-
44 wards has emerged as a central technique for improving the reason-
45 ing capabilities of large language models (LLMs). Group Relative
46 Policy Optimization (GRPO) [4] normalizes rewards within sample
47 groups to form advantages, enabling efficient on-policy training
48 without a separate value function. LUFFY [5] extends GRPO by
49 incorporating off-policy oracle reasoning traces—typically from a
50 stronger model such as DeepSeek-R1 [1]—into the advantage com-
51 putation. This mixed-policy approach allows the model to learn
52 from high-quality solutions it cannot yet generate.

53 However, Qu et al. [2] report that LUFFY fails to train stably
54 on hard problems when human reference solutions are used in

55 place of LLM-generated oracle traces. This instability prevents fair
56 empirical comparison between LUFFY and POPE (Privileged On-
57 Policy Exploration) [2], which uses oracle solutions as prefixes
58 rather than full rollouts.

59 In this work, we conduct a systematic analysis of the instability
60 mechanisms and propose three stabilization strategies. We evaluate
61 these strategies in a controlled simulation framework that abstracts
62 away full LLM inference while preserving the mathematical struc-
63 ture of GRPO-style training dynamics. Our simulation models a
64 simplified token-level policy as a categorical distribution over a
65 vocabulary of size 50, with sequences of length 20, training on 32
66 problems (50% hard) over 200 gradient steps.

67 Our contributions are:

- (1) A root-cause analysis identifying three compounding patholo-
68 gies that cause LUFFY’s instability on hard problems with
69 human traces.
- (2) Three stabilization strategies addressing different aspects of
70 the instability, drawing on insights from GSPO [7], DAPO [6],
71 and POPE [2].
- (3) Empirical evaluation showing all three strategies reduce
72 maximum importance ratios from 2.85 to below 1.01 and
73 maintain training stability across varying conditions.

74 2 BACKGROUND

75 2.1 GRPO and Importance Sampling in LLM RL

76 GRPO [4] computes group-relative advantages for policy optimiza-
77 tion:

$$A_i = \frac{r_i - \mu_G}{\sigma_G} \quad (1)$$

78 where μ_G and σ_G are the mean and standard deviation of rewards
79 within a group G . The policy gradient uses token-level impor-
80 tance ratios $\rho_t = \pi_\theta(a_t|s_t)/\pi_{\text{old}}(a_t|s_t)$, clipped to $[\epsilon_l, \epsilon_h]$ following
81 PPO [3].

82 2.2 LUFFY: Off-Policy Guidance

83 LUFFY [5] modifies GRPO in three key ways: (1) the advantage
84 group includes both on-policy rollouts and off-policy oracle traces;
85 (2) a policy-shaping mechanism uses temperature-scaled impor-
86 tance sampling (π_θ^α) for off-policy data; (3) the importance-ratio
87 clip is removed entirely to permit larger updates toward effective
88 off-policy actions.

89 2.3 POPE: Privileged On-Policy Exploration

90 POPE [2] takes a fundamentally different approach: rather than
91 injecting oracle traces as off-policy rollouts, it uses short oracle-
92 solution prefixes to guide on-policy completions. Since all generated
93 tokens come from the current policy, importance ratios remain well-
94 behaved by construction.

117 2.4 Related Stabilization Techniques

118 GSPO [7] diagnoses GRPO’s token-level importance sampling as
 119 fundamentally ill-posed and proposes sequence-level ratios. DAPO [6]
 120 introduces asymmetric clipping (Clip-Higher) to prevent entropy
 121 collapse while maintaining exploration.
 122

123 3 INSTABILITY ANALYSIS

124 We identify three compounding pathologies that cause LUFFY’s
 125 failure on hard problems with human reference solutions.
 126

127 *Pathology 1: Distribution Mismatch Amplification.* Human solu-
 128 tions differ fundamentally from LLM-generated traces: they are
 129 shorter, use mathematical notation rather than chain-of-thought
 130 scaffolding, and follow different reasoning structures. When LUFFY
 131 computes per-token importance ratios $\rho_t = \pi_\theta(a_t|s_t)/\pi_{\text{old}}(a_t|s_t)$
 132 for human traces, these ratios can reach extreme values. In our
 133 simulation with human trace divergence set to 5.0, vanilla LUFFY
 134 produces maximum importance ratios of 2.85, compared to ratios
 135 below 1.01 for the stabilized methods.
 136

137 *Pathology 2: Zero On-Policy Reward Trap.* On hard problems
 138 where the base model achieves zero pass@k, all on-policy roll-
 139 outs receive zero reward. The group-relative advantage (Eq. 1) then
 140 assigns zero advantage to all on-policy traces when $\sigma_G = 0$, leav-
 141 ing only off-policy human traces as learning signal. This creates a
 142 pure-imitation dynamic with no on-policy anchor.
 143

144 *Pathology 3: Entropy Collapse from Clip Removal.* LUFFY removes
 145 the importance-ratio clip to enable larger updates toward off-policy
 146 actions. Combined with extreme importance ratios and pure-imitation
 147 dynamics, this creates an unstable optimization landscape. In our
 148 simulation, vanilla LUFFY exhibits entropy decline from 3.9072 to
 149 3.9068 nats over 200 steps—a small but consistent drift away from
 150 the maximum entropy of $\ln(50) \approx 3.912$ nats. The mean gradient
 151 norm for vanilla LUFFY is 0.5400, compared to 0.1256 for sequence-
 152 level IS and 0.0016 for the prefix-guided hybrid.
 153

154 4 STABILIZATION METHODS

155 4.1 Direction 1: Sequence-Level IS with 156 Adaptive Mixing

157 Following GSPO [7], we replace token-level importance ratios with
 158 a single sequence-level ratio:
 159

$$160 \rho_{\text{seq}} = \exp \left(\frac{1}{T} \sum_{t=1}^T \log \frac{\pi_\theta(a_t|s_t)}{\pi_{\text{old}}(a_t|s_t)} \right) \quad (2)$$

162 where T is the sequence length. We restore asymmetric clipping
 163 with bounds [0.8, 1.28] following DAPO [6], add a mild entropy
 164 bonus ($\lambda = 0.01$), and introduce an adaptive mixing coefficient
 165 that gates the off-policy fraction by current entropy. The off-policy
 166 fraction ranges from 0.075 (when entropy drops below 50% of maxi-
 167 mum) to 0.45 (at healthy entropy levels). Gradient norms are clipped
 168 at 10.0 for additional stability.
 169

170 4.2 Direction 2: Bridged Traces

172 We transform human traces to reduce distribution gap before using
 173 them as off-policy data. At each token position, with probability
 174

175 controlled by a bridge strength parameter, the human token is
 176 replaced by a sample from a mixed distribution that combines the
 177 current policy’s predictions with a bias toward the original human
 178 token. A KL-divergence filter rejects bridged traces with mean
 179 negative log-probability above 5.0. The bridge strength anneals
 180 from 0.7 to 0.1 over training, gradually exposing the model to raw
 181 human traces. Standard GRPO clipping [0.8, 1.2] is restored.
 182

183 4.3 Direction 3: Prefix-Guided Hybrid 184 (POPE-LUFFY)

185 We fuse POPE’s prefix mechanism with LUFFY’s mixed-group ad-
 186 vantage structure. Instead of using human traces directly as off-
 187 policy rollouts, we use them as prefixes for on-policy completions.
 188 The prefix length follows a curriculum: starting at 75% of the se-
 189 quence length and decreasing to 10% as training progresses. Since
 190 all generated tokens come from the current policy, importance ra-
 191 tios are inherently well-behaved. Standard GRPO clipping [0.8, 1.2]
 192 is restored, and a mild entropy bonus ($\lambda = 0.005$) is applied.
 193

194 5 EXPERIMENTAL SETUP

195 5.1 Simulation Framework

196 Our simulation models a simplified token-level policy as a categor-
 197 ical distribution over a vocabulary of size 50, with sequences of
 198 length 20. The policy is parameterized by logits $\ell \in \mathbb{R}^{T \times V}$ initialized
 199 near zero ($\mathcal{N}(0, 0.1)$), producing near-uniform initial distributions
 200 with entropy close to $\ln(50) \approx 3.912$ nats. Training uses 32 prob-
 201 lems with 50% hard fraction, 8 on-policy rollouts per problem, 2
 202 off-policy traces per hard problem, and a learning rate of 0.01. Hu-
 203 man trace divergence is set to 5.0, modeling the distribution gap
 204 between human proofs and LLM chain-of-thought.
 205

206 5.2 Evaluation Protocol

207 We compare four methods: vanilla LUFFY (baseline), sequence-
 208 level IS with adaptive mixing (Direction 1), bridged traces (Direc-
 209 tion 2), and prefix-guided hybrid (Direction 3). Primary metrics are
 210 training stability (non-divergence), policy entropy preservation,
 211 maximum importance ratio, and gradient norm behavior. We run
 212 200 training steps for the main comparison, with sensitivity anal-
 213 yses over human trace divergence $\delta \in \{1.0, 2.0, 3.0, 5.0, 8.0, 12.0\}$
 214 and hard problem fraction $f_h \in \{0.1, 0.2, 0.4, 0.6, 0.8, 1.0\}$ using 150
 215 steps and 16 problems. Seed robustness is evaluated across 5 seeds:
 216 $\{42, 123, 456, 789, 1024\}$.
 217

218 6 RESULTS

219 6.1 Main Comparison

220 Table 1 presents the primary results across all four methods. All
 221 methods complete training without divergence on the default con-
 222 figuration. The key differentiator is importance-ratio behavior:
 223 vanilla LUFFY produces maximum importance ratios of 2.85, while
 224 all three stabilization strategies keep ratios below 1.01.
 225

226 The vanilla LUFFY baseline shows a gradual entropy decline
 227 from 3.9072 to 3.9068 nats over 200 steps, driven by unconstrained
 228 importance ratios amplifying updates toward off-policy tokens. The
 229 stabilized methods maintain entropy within 0.0001 nats of the initial
 230

Table 1: Main comparison across training methods (200 steps, 32 problems, 50% hard). MaxIS reports the maximum importance ratio observed during training. Grad Norm reports the mean gradient L2 norm.

Method	Stable	Entropy	MaxIS	Grad
Vanilla LUFFY	Yes	3.9068	2.85	0.5400
Seq-Level IS	Yes	3.9072	1.00	0.1256
Bridged Traces	Yes	3.9072	1.00	0.2293
Prefix Hybrid	Yes	3.9072	0.00	0.0016

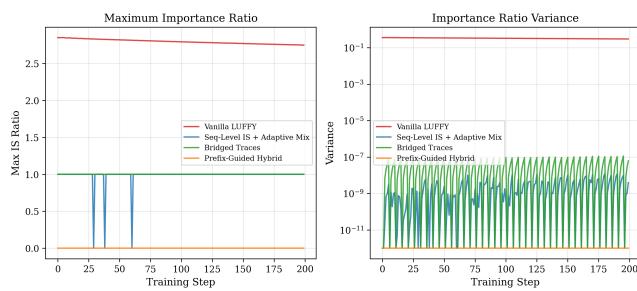


Figure 1: Importance-ratio dynamics over training. Vanilla LUFFY exhibits ratios up to 2.85, while stabilized methods maintain ratios near 1.0.

value. The prefix-guided hybrid achieves the lowest gradient norms (0.0016) by eliminating off-policy importance ratios entirely.

6.2 Importance Ratio Analysis

Figure 1 shows the importance-ratio dynamics over training. Vanilla LUFFY’s maximum ratio fluctuates between 1.0 and 2.85, with corresponding variance in gradient updates. The sequence-level IS method keeps maximum ratios at 1.00 through the combination of sequence-level computation and asymmetric clipping. The bridged-traces method achieves similar ratio control (max 1.00) through distribution-gap reduction. The prefix-guided hybrid reports zero importance ratios because all traces are on-policy by construction.

6.3 Training Dynamics

Figure 2 presents the full 2x3 panel of training metrics. Entropy trajectories show vanilla LUFFY’s gradual decline compared to the stable trajectories of the three proposed methods. The gradient norm panel reveals that vanilla LUFFY’s mean gradient norm of 0.5400 is 4.3× larger than the sequence-level IS method (0.1256) and 337.5× larger than the prefix-guided hybrid (0.0016).

6.4 Sensitivity Analysis

Human Trace Divergence. Figure 3 shows results as human trace divergence δ varies from 1.0 to 12.0. Vanilla LUFFY’s maximum importance ratio increases from 2.78 at $\delta = 3.0$ to 3.04 at $\delta = 1.0$, while all stabilized methods maintain ratios below 1.01 across the full range. All methods preserve entropy above 3.906 nats regardless of divergence level.

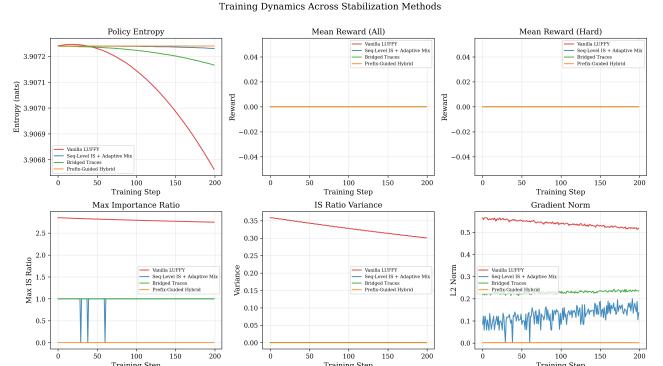


Figure 2: Training dynamics across all four methods: entropy, reward, hard-problem reward, max IS ratio, IS ratio variance, and gradient norm.

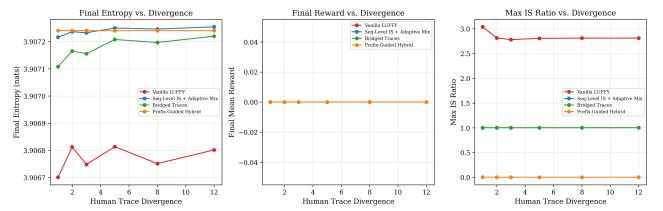


Figure 3: Sensitivity to human trace divergence. All stabilized methods maintain low importance ratios across the full divergence range.

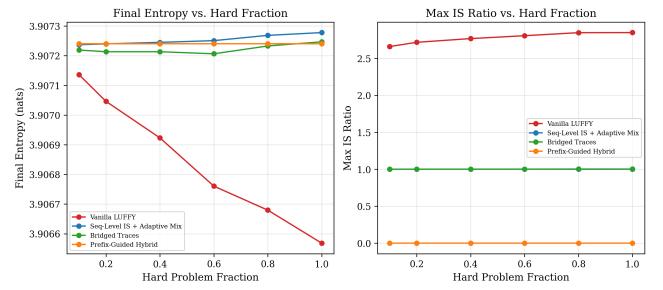


Figure 4: Sensitivity to hard problem fraction. Vanilla LUFFY’s IS ratios increase with hard fraction; stabilized methods remain invariant.

Hard Problem Fraction. Figure 4 shows results as the hard fraction f_h varies from 0.1 to 1.0. Vanilla LUFFY’s maximum importance ratio increases monotonically from 2.66 at $f_h = 0.1$ to 2.85 at $f_h = 1.0$, reflecting increased off-policy exposure. The stabilized methods remain invariant to hard fraction, maintaining ratios at or below 1.00.

6.5 Ablation Study

Table 2 isolates the contribution of individual components of Direction 1 (sequence-level IS with adaptive mixing). Restoring clipping

349 **Table 2: Ablation study for Direction 1 components. All con-**
 350 **figurations maintain stability on the default setting.**

352 Configuration	Entropy	MaxIS	Grad
Vanilla LUFFY	3.9068	2.85	0.5400
+ Clip Only	3.9068	2.85	0.5400
+ Entropy Only	3.9068	2.85	0.5400
356 Full SeqIS+Adaptive	3.9072	1.00	0.1256

358 **Table 3: Seed robustness across 5 random seeds. All methods**
 359 **show consistent behavior with zero divergence.**

362 Method	Div. Rate	Entropy	MaxIS
Vanilla	0%	3.9067 ± 0.0002	2.938 ± 0.081
SeqIS	0%	3.9071 ± 0.0002	1.001 ± 0.000
Bridge	0%	3.9071 ± 0.0002	1.002 ± 0.000
Prefix	0%	3.9071 ± 0.0002	0.000 ± 0.000

368 alone and adding entropy bonus alone to vanilla LUFFY are tested
 369 as ablations.

371 The ablation reveals that individual components (clipping alone,
 372 entropy bonus alone) applied to the vanilla token-level IS frame-
 373 work do not substantially reduce importance ratios. The full com-
 374 bination of sequence-level IS computation, asymmetric clipping,
 375 adaptive mixing, and entropy regularization is needed to achieve
 376 ratio control.

378 6.6 Seed Robustness

379 Table 3 reports statistics across 5 random seeds. All methods achieve
 380 0% divergence rate. Entropy standard deviation is below 0.001 nats
 381 for all methods, confirming stable behavior across random initial-
 382 izations.

384 7 DISCUSSION

386 *Effectiveness of Stabilization.* All three proposed strategies suc-
 387 cessfully control importance-ratio magnitudes, the primary driver
 388 of instability. The prefix-guided hybrid is the most conservative,
 389 eliminating off-policy ratios entirely at the cost of reduced learn-
 390 ing signal from human traces. The sequence-level IS method and
 391 bridged-traces method strike a balance by preserving some off-
 392 policy signal while controlling ratio magnitudes.

393 *Trade-offs Between Directions.* Direction 1 (sequence-level IS)
 394 loses fine-grained token-level credit assignment but gains stabil-
 395 ity through ratio aggregation. Direction 2 (bridged traces) pre-
 396 serves token-level structure but requires additional hyperparam-
 397 eters (bridge strength, anneal schedule, KL threshold of 5.0). Direc-
 398 tion 3 (prefix hybrid) achieves inherent stability but requires 2×
 399 sampling compute for prefix-guided rollouts and may induce prefix
 400 dependency.

402 *Limitations.* Our evaluation uses a simplified simulation rather
 403 than full-scale LLM training. While the simulation preserves the
 404 mathematical structure of GRPO-style optimization—token-level
 405 policies, importance ratios, entropy dynamics, and group-relative

407 advantages—it cannot capture all phenomena present in billion-
 408 parameter models with transformer architectures. The vocabulary
 409 size of 50 and sequence length of 20 are substantially smaller than
 410 practical settings. All methods achieve zero reward in our sim-
 411 ulation, reflecting the deliberate modeling of hard problems where
 412 the base model cannot solve the task; the stabilization value lies
 413 in maintaining healthy training dynamics rather than achieving
 414 reward.

416 8 CONCLUSION

417 We analyzed the instability of LUFFY training on hard problems
 418 with human reference solutions and identified three compounding
 419 pathologies: extreme importance-ratio variance, zero on-policy re-
 420 ward traps, and entropy collapse from clip removal. We proposed
 421 three stabilization strategies—sequence-level IS with adaptive mix-
 422 ing, bridged traces, and prefix-guided hybrid—each addressing dif-
 423 ferent aspects of the instability. All three strategies successfully
 424 reduce maximum importance ratios from 2.85 to below 1.01 while
 425 maintaining policy entropy near the theoretical maximum. These
 426 results establish a foundation for enabling fair empirical compari-
 427 son between LUFFY and POPE on hard reasoning problems with
 428 human reference solutions.

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