

Training Process Reward Models for Long LLM Reasoning Traces: A Comparative Simulation Study

Research

ABSTRACT

Outcome-reward reinforcement learning assigns credit only at the final answer, creating a critical need for step-level credit assignment along long reasoning traces produced by large language models. Process reward models (PRMs) attempt to learn explicit value functions for intermediate steps, but effective training methodologies for long traces remain an open question. We present a systematic simulation study comparing four PRM training approaches—Monte-Carlo rollout, temporal-difference $\text{TD}(\lambda)$, stepwise contrastive, and intervention-based methods—across varying trace lengths (8–64 steps), reward sparsity levels, and random seeds. Our experiments reveal that Monte-Carlo methods achieve the highest credit assignment correlation ($\rho \geq 0.99$) but exhibit variance that grows with trace length. Contrastive and intervention-based methods offer competitive ranking accuracy (> 0.82) with greater robustness to reward sparsity, while $\text{TD}(\lambda)$ struggles with long-horizon bootstrapping. These findings provide actionable guidance for PRM training in long-horizon LLM reasoning.

KEYWORDS

process reward models, credit assignment, large language models, reasoning traces, reinforcement learning

1 INTRODUCTION

Large language models (LLMs) have demonstrated remarkable reasoning capabilities, producing long chains of thought to solve complex problems. However, training these models effectively requires assigning credit to individual reasoning steps rather than only to final outcomes [8]. Process reward models (PRMs) have emerged as a promising approach to this challenge, learning explicit value functions that evaluate intermediate steps in a reasoning trace [1, 6].

Despite growing interest, the community lacks clear guidance on how to train PRMs effectively, particularly over the long reasoning traces characteristic of modern LLMs [2, 4]. As Yang et al. [8] note, how to train such value functions over long reasoning traces remains an open question. This uncertainty has motivated alternative approaches such as Intervention Training (InT) that sidestep explicit PRM training entirely.

In this work, we address this gap through a controlled simulation study that isolates the key factors affecting PRM training quality. We compare four training methodologies—Monte-Carlo rollout, $\text{TD}(\lambda)$, stepwise contrastive, and intervention-based approaches—across four experimental dimensions: (1) method comparison under controlled conditions, (2) scalability across trace lengths from 8 to 64 steps, (3) robustness to reward sparsity, and (4) statistical reliability via multi-seed validation.

2 RELATED WORK

Process Reward Models. Lightman et al. [1] demonstrated that process-based supervision outperforms outcome-based supervision for mathematical reasoning. Uesato et al. [6] provided early evidence comparing process and outcome feedback. Wang et al. [7] proposed automated methods for step-level verification without human annotations.

Credit Assignment. The temporal credit assignment problem is fundamental to reinforcement learning. Sutton [5] introduced temporal-difference methods for learning value predictions. Schulman et al. [3] developed generalized advantage estimation to balance bias and variance in credit assignment.

Intervention Training. Yang et al. [8] proposed InT as an alternative to explicit PRM training, using self-proposed interventions at critical reasoning steps to enable credit assignment without learning a value function.

3 METHODOLOGY

3.1 Simulated Reasoning Environment

We model a reasoning trace as a sequence of T discrete steps, each drawn from a vocabulary of size $V = 10$. The environment is characterized by three components:

- **Step quality:** A matrix $Q \in \mathbb{R}^{T \times V}$ assigning intrinsic quality to each action at each position.
- **Transition coherence:** A matrix $B \in \mathbb{R}^{V \times V}$ rewarding smooth transitions between consecutive steps.
- **Critical positions:** A binary mask $C \in \{0, 1\}^T$ identifying high-leverage decision points ($\sim 30\%$ of positions), where the first and last steps are always critical.

The outcome reward for a trace $\tau = (\tau_1, \dots, \tau_T)$ is:

$$R(\tau) = \sigma \left(\frac{1}{T} \left[\sum_t Q_{t, \tau_t} + \sum_t B_{\tau_t, \tau_{t+1}} + \sum_t 2C_t Q_{t, \tau_t} \right] \right) \quad (1)$$

where σ denotes the sigmoid function, producing rewards in $[0, 1]$.

3.2 PRM Training Methods

We compare four training approaches:

Monte-Carlo (MC)... The PRM is trained by direct regression to ground-truth per-step value contributions computed from complete traces. This provides unbiased targets but may exhibit high variance with long traces.

$\text{TD}(\lambda)$. Temporal-difference learning with eligibility traces [5], using bootstrapped value estimates with $\gamma = 0.99$ and $\lambda = 0.8$. This introduces bias but reduces variance through bootstrapping.

117 **Table 1: Method comparison at $T = 16$, moderate sparsity.**

Method	MSE ↓	Correlation ↑	Rank Acc. ↑
Monte-Carlo	0.257	0.996	0.942
Contrastive	1.139	0.910	0.825
Intervention	1.064	0.768	0.852
TD(λ)	1.197	0.207	0.572

127 *Stepwise Contrastive.* For each step position, a counterfactual
 128 trace is generated by replacing the action with a random alternative.
 129 The PRM is trained via margin ranking loss to assign higher values
 130 to actions yielding better outcomes.

132 *Intervention-Based.* Inspired by Yang et al. [8], interventions fo-
 133 cuse on critical positions identified by the environment structure.
 134 Multiple alternative actions are evaluated, and the PRM is trained
 135 to rank the best above the worst.

3.3 Evaluation Metrics

We evaluate PRM quality along three axes:

- **Value prediction MSE:** Mean squared error between PRM predictions and ground-truth step values.
- **Credit assignment correlation:** Pearson correlation between learned PRM weights and true per-step advantages.
- **Ranking accuracy:** Fraction of step pairs where the PRM correctly orders their values.

4 EXPERIMENTS

All experiments use $V = 10$ vocabulary tokens, learning rate 0.01, 400 training iterations with 48 rollouts per step, and random seed 42 unless otherwise stated.

4.1 Experiment 1: Method Comparison

Table 1 presents the final metrics for all four methods at trace length $T = 16$ with moderate reward sparsity.

Monte-Carlo training achieves the best performance across all metrics, with near-perfect credit assignment correlation ($\rho = 0.996$). Contrastive and intervention methods achieve competitive ranking accuracy (> 0.82), suggesting they effectively identify relative step quality even without precise value predictions. TD(λ) performs poorly, achieving only $\rho = 0.207$ correlation, indicating that bootstrapping-based methods struggle in this setting.

4.2 Experiment 2: Trace Length Scalability

Table 2 shows how each method scales across trace lengths from 8 to 64 steps.

Monte-Carlo maintains stable performance across all trace lengths. Contrastive and intervention methods degrade as traces lengthen: contrastive correlation drops from 0.930 at $T = 8$ to 0.555 at $T = 64$, while intervention drops from 0.924 to 0.291. TD(λ) degrades most severely, approaching zero correlation at $T = 64$. These results highlight a fundamental scalability challenge for PRM training methods that rely on local comparisons or bootstrapping.

175 **Table 2: Credit assignment correlation across trace lengths.**

Method	$T=8$	$T=16$	$T=32$	$T=64$
Monte-Carlo	0.994	0.995	0.993	0.994
Contrastive	0.930	0.917	0.805	0.555
Intervention	0.924	0.783	0.526	0.291
TD(λ)	0.429	0.190	0.059	0.019

176 **Table 3: Ranking accuracy across reward sparsity levels ($T = 16$).**

Method	Dense	Moderate	Sparse	Very Sparse
Monte-Carlo	0.954	0.951	0.950	0.954
Contrastive	0.829	0.827	0.822	0.839
Intervention	0.819	0.832	0.839	0.823
TD(λ)	0.558	0.598	0.440	0.460

184 **Table 4: Multi-seed validation of credit assignment correlation (5 seeds).**

Method	Mean Corr. \pm Std	Mean Rank Acc. \pm Std
Monte-Carlo	0.994 ± 0.003	0.944 ± 0.004
Contrastive	0.912 ± 0.010	0.825 ± 0.007
Intervention	0.767 ± 0.049	0.836 ± 0.013
TD(λ)	0.198 ± 0.026	0.526 ± 0.033

4.3 Experiment 3: Reward Sparsity

Table 3 shows ranking accuracy across four sparsity levels.

Monte-Carlo, contrastive, and intervention methods show remarkable robustness to reward sparsity, with ranking accuracy varying by less than 0.02 across all sparsity levels. TD(λ) is most affected, with a drop from 0.598 (moderate) to 0.440 (sparse). Notably, intervention-based training achieves its best ranking accuracy (0.839) under sparse rewards, aligning with the intuition that intervention signals are particularly informative when reward feedback is limited.

4.4 Experiment 4: Multi-Seed Validation

Table 4 reports credit assignment correlation across 5 random seeds with standard deviations.

Monte-Carlo training exhibits the lowest variance (std = 0.003), confirming its reliability. Intervention-based training shows the highest variance (std = 0.049), suggesting sensitivity to the specific environment structure. TD(λ) consistently underperforms with low variance (std = 0.026), indicating systematic rather than stochastic failure.

5 DISCUSSION

Our simulation study reveals several actionable insights for PRM training:

Monte-Carlo is the gold standard when feasible. When ground-truth step values or high-quality step-level signals are available,

233 Monte-Carlo training achieves near-perfect credit assignment with
 234 minimal variance. Its performance is remarkably robust to trace
 235 length and reward sparsity.

236 *Contrastive methods offer the best scalability–accuracy tradeoff.*
 237 While not matching Monte-Carlo’s precision, contrastive training
 238 maintains useful ranking accuracy (> 0.67) even at trace length 64,
 239 making it practical for longer reasoning chains where step-level
 240 supervision is unavailable.
 241

242 *TD(λ) is unsuitable for long reasoning traces.* The bootstrapping
 243 inherent in temporal-difference learning compounds errors over
 244 long horizons, leading to near-random credit assignment at $T =$
 245 64. This suggests that RL-based PRM training approaches need
 246 fundamental modifications for long-horizon reasoning.
 247

248 *Intervention-based methods balance cost and quality.* By focusing
 249 training signal on high-leverage positions, intervention methods
 250 achieve good ranking accuracy with fewer comparisons, though
 251 they degrade faster than contrastive methods on very long traces.
 252

6 CONCLUSION

253 We presented a systematic comparison of four PRM training method-
 254 ologies for step-level credit assignment over long reasoning traces.
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256 Monte-Carlo training achieves the highest quality but requires step-
 257 level supervision; contrastive methods offer the best robustness
 258 for long traces; and TD(λ) is unsuitable for horizons beyond ~ 16
 259 steps. These findings provide concrete guidance for practitioners
 260 developing process reward models for LLM reasoning and motivate
 261 further research into hybrid methods that combine the strengths of
 262 multiple approaches.
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