# Integrated Exercise for Software I Final Review

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- 1. Overview
- 2. Development Environment
- 3. Our Product
- 4. Demo
- 5. Contribution
- 6. Summary

## 1. Overview

#### -> Overview

#### ~ About Our Team ~

Team Name: team\_tower <a href="https://github.com/ie03-aizu-2019/ie03project-team\_tower">https://github.com/ie03-aizu-2019/ie03project-team\_tower</a>

Team Member: s1250125 Takahisa Watanabe

**s1250183 Yuki Homma** 

#### -> Overview

#### ~ System Overview ~

We developed a system to assist road network construction.

#### This system has following functions,

- 1. Detect all intersection points for given roads
- 2. Find the shortest distance and its path for given roads
- 3. Suggest the shortest road to be constructed to link given new locations
- 4. Detect all highways (in graph theorem, it is called bridge)

#### -> Overview

~ About Final Phase ~

We expand some outputs for making users understood it with ease.

## 2. Development Environment

#### -> Development Environment

~ Programming Language~

C language: We are familiar with C.

~ Editor~

**Emacs: We are familiar with Emacs!** 

~ Version Management System ~

GitHub <a href="https://github.com/ie03-aizu-2019/ie03project-team-tower">https://github.com/ie03-aizu-2019/ie03project-team-tower</a>

## 3. Our Product

**Task 1: Implemented** 

Task 2: Implemented

**Tesk 3: Implemented** 

**Tesk 4: Implemented** 

**Task 5 & 6: Not** 

Task 7 & 8: Implemented(some Error)

Task 9: Implemented

Task 10, 11: Not

## Task 1 and Task 2

**Data Structure** 

~ Task 1, Task 2~

```
We use the struct to construct points
typedef struct {
                      Good Idea for many road's
  double x;
                      crossing!
  double y;
  int roadA;
                 The roads which create this point
                 when the roads are crossing.
  int roadB;
  int id;
  point_t;
                  ID for the point (1 \sim n)
```

**Algorithm** 

~ Task 1, Task 2~

Step 1.	If $(5) = 0$	No intersection
Step 2.	Else Calculate s and t from equation (6)	To Step 2 To Step 3
Step 3.	If 0≦s≦1 かつ 0≦t≦1	Intersection found, To Step 4
Step 4.	Else Calculate x,y coordinates.	No intersection
	x is found by substituting s into (1) or (3) y is found by substituting t into (2) or (4)	

$$x = x_{P1} + (x_{Q1} - x_{P1})s$$

(1) 
$$x = x_{P2} + (x_{Q2} - x_{P2})t$$
 (3)

$$y = y_{P1} + (y_{Q1} - y_{P1})s$$

$$(2) y = y_{P2} + (y_{Q2} - y_{P2})t$$

$$|A| = (x_{Q1} - x_{P1})(y_{P2} - y_{Q2}) + (x_{Q2} - x_{P2})(y_{Q1} - y_{P1})$$

(4)

$${S \brace t} = \frac{1}{|A|} \begin{bmatrix} y_{P2} - y_{Q2} & x_{Q2} - x_{P2} \\ y_{P1} - y_{Q1} & x_{Q1} - x_{P1} \end{bmatrix} {x_{P2} - x_{P1} \\ y_{P2} - y_{P1} }$$

(6)

**Source Code** 

~ Task 1, Task 2~

```
// 交差地点を返す関数, ない場合はNotExist {-1, -1}を返す
point_t detectCrossing(point_t pointP_A, point_t pointQ_A, point_t pointP_B, point_t pointQ_B)
    // 交差地点を返す関数, ない場合はNotExist{-1, -1}を返す
    point_t detectCrossing(point_t pointP_A, point_t pointQ_A, point_t pointP_B, point_t pointQ_B) {
 8
      double p1X, p1Y, q1X, q1Y, p2X, p2Y, q2X, q2Y;
                                                        pointP B
      double s, t;
 9
                                                                                             (q1X, q1Y)
10
      double x, y;
      double determinant;
12
      point t crossing;
                                                     (p2X, p2Y)
                                                                          TOAUB
      point_t notExist = \{-1, -1\};
                                                                                                pointQ_A
13
14
      int i, index;
15
                                                                      roadA
16
      p1X = pointP A.x;
17
      p1Y = pointP_A.y;
18
      q1X = pointQ_A.x;
                                                       pointP_A
                                                                                                pointQ_B
19
      q1Y = pointQ_A.y;
20
      p2X = pointP B.x;
21
      p2Y = pointP_B.y;
                                                        (p1X, p1Y)
22
      q2X = pointQ_B.x;
                                                                                               (q2X, q2Y)
23
     q2Y = pointQ B.y;
```

**Source Code** 

~ Task 1, Task 2~

```
25
      // 行列式を求める
      determinant = fabs(((q1X - p1X)*(p2Y - q2Y) + (q2X - p2X)*(q1Y - p1Y)));
26
27
      // Step1
28
                                                                                                      (q1X, q1Y)
      if( (determinant <= EPS) && (determinant >= EPS) ) {
30
        return notExist;
31
                                                           (p2X, p2Y)
32
                                                                                      8
33
      // Step2
      // パラメータを求める
34
35
      s = fabs(((q2Y - p2Y)*(p2X - p1X) - (q2X - p2X)*(p2Y - p1Y))) / determinant;
36
      t = fabs(((q1Y - p1Y)*(p2X - p1X) - (q1X - p1X)*(p2Y - p1Y))) / determinant;
37
                                                             (p1X, p1Y)
                                                                                                        (q2X, q2Y)
```

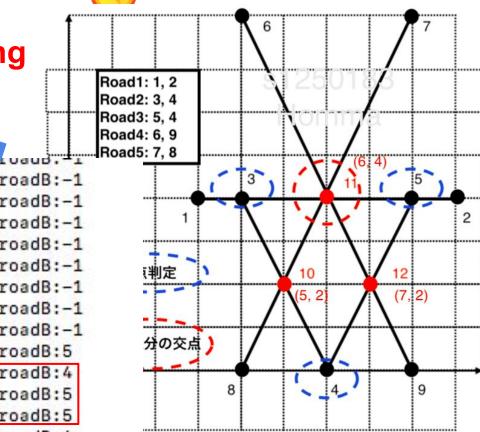
#### **Hard Point**



#### ~ Task 1, Task 2~

It's hard to detect the crossing point where many roads are crossing.

POTITO T X. S. DODDODO, Y. 4. DOD point:2 x:9.000000, y:4.0000 roadB:-1 point:3 x:4.000000, y:4.0000 roadA:-1, roadB:-1 point:4 x:6.000000, y:0.00000 roadA:-1, roadB:-1 point:5 x:8.000000, y:4.00000 roadA:-1, roadB:-1 point:6 x:4.000000, y:8.00000 roadA:-1, roadB:-1 point:7 x:8.000000, v:8.0000/ roadA:-1, roadB:-1 point:8 x:4.000000, y:0/ roadA:-1, roadB:-1 point:9 x:8.000000, yz roadA:-1, roadB:-1 point:10 x:5.000000, y:2 po0000, roadA:2, roadB:5 point:11 x:6.000000, y:4.000000, roadA:1, roadB:4 point:11 x:6.000000, y:4.000000, roadA:1, roadB:5 point:11 x:6.000000, y:4.000000, roadA:4, roadB:5 point:12 x:7.000000, y:2.000000, roadA:3, roadB:4



## Task 3 and Task 4

### Dijkstra's algorithm

#### For finding the shortest path between nodes

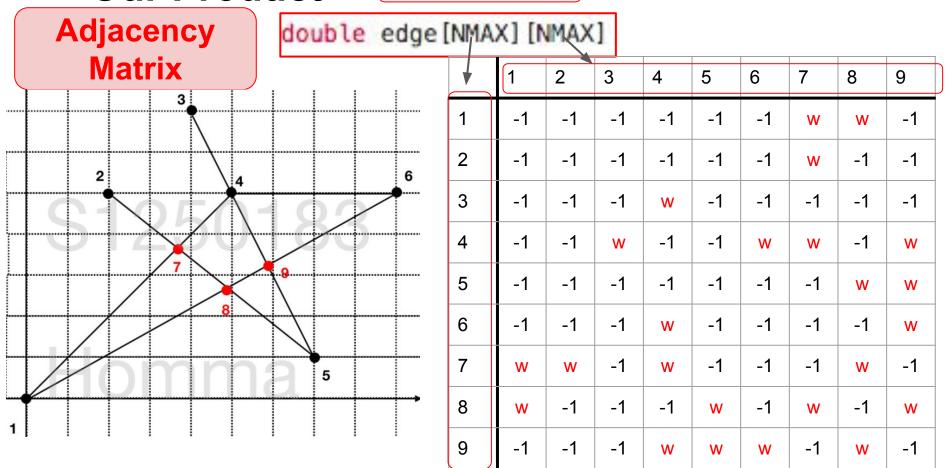
```
グラフ G=(V,E)、スタートとなる頂点 s、および u から v への辺の長さ \mathrm{length}(u,v) を入力として受け取る
// 初期化
各頂点 v \in V に対し、d(v) \leftarrow (v = s \text{ ならば } 0、それ以外は \infty)
                                                                         We do not use priority queue
各頂点 v \in V に対し、prev(v) \leftarrow 「無し」
                                                                        O(n^2)
Q に V の頂点を全て追加
// 本計算
while (Q が空ではない)
 u \leftarrow Q から d(u) が最小である頂点を取り除く
 for each (u からの辺がある各頂点 v \in V)
    if ( d(v) > d(u) + \operatorname{length}(u, v) )
                                  Reference from Wikipedia,
      d(v) \leftarrow d(u) + \text{length}(u, v)
                                  https://ja.wikipedia.org/wiki/%E3%83%80%E3%82%A4%E3%82%AF%E3%82%B9%
      prev(v) \leftarrow u
                                  E3%83%88%E3%83%A9%E6%B3%95
```

~ Task 3, Task 4~

```
座標の構造体
    typedef struct {
      double x;
      double y;
                            We use the struct of
      int roadA;
                            points as a node in graph
8
      int roadB;
     double cost;
                    訪問済みのフラグ
10
     int done;
     int preNode: // 最短経路として選択された自身の前のノード
      int id;
13
    } point t;
```

**Data Structure** 

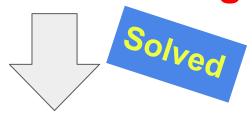
#### ~ Task 3, Task 4~





~ Task 3, Task 4 ~

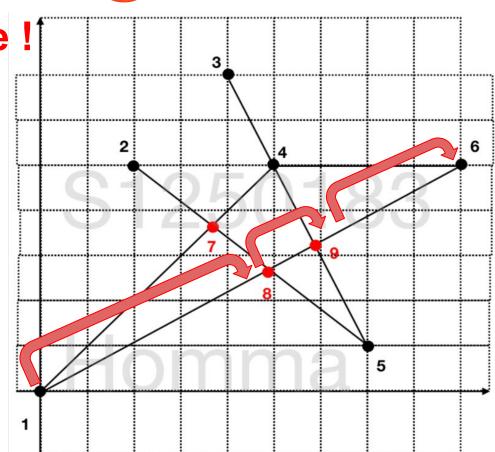
It's hard to create edge!



We created the edges <u>one by one</u> for each road.

Crossing points have the id of road which is on. (roadA, roadB)

That makes us possible to create edge with ease.



## Task 5 and Task 6

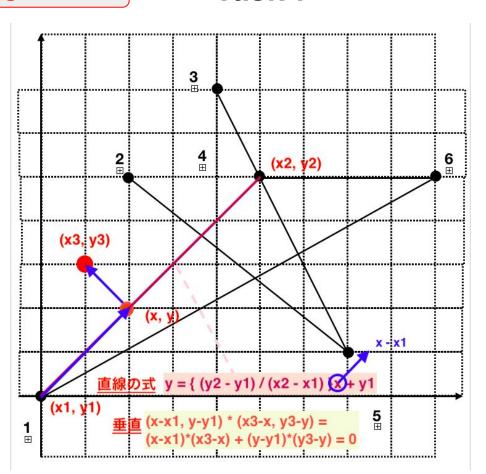
## Mr. Watanabe will explain.

## Task 7

**Algorithm** 

~ Task 7 ~

We use the idea of inner product in vectors



**Algorithm** 

~ Task 7 ~

For each road, we find x and y, such a following conditions

Inner product = 0

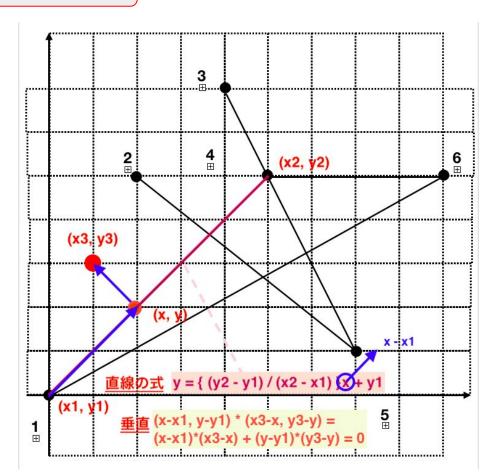
AND

On the road

And then

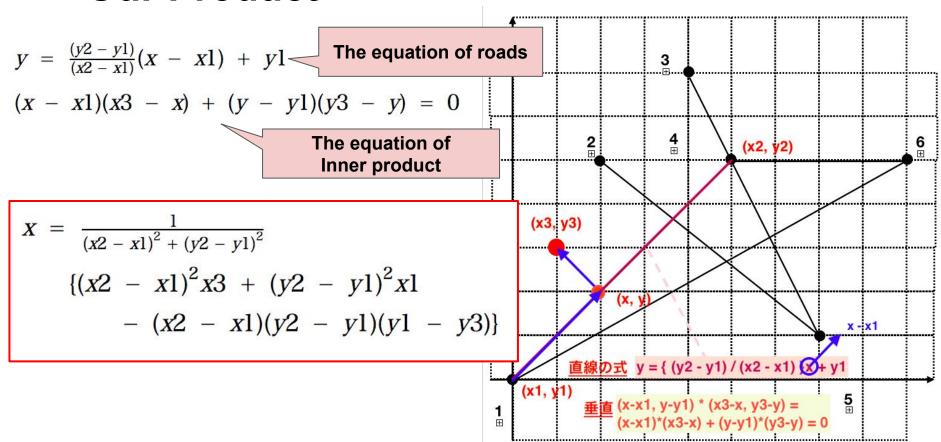
The point(x,y) which has the shortest distance from new point

That point is answer



**Algorithm** 

~ Task 7 ~



```
46
47
       * 全ての道に対して内積を求め、
       * 内積が0の時の座標と距離を出す(その道までの最短距離)
48
49
       * そのなかで一番距離が小さいものを採用
50
       */
      for(i = 1; i <= m; i++) {
51
52
        pointPIndex = searchPointIndex(point, n, road[i][0]);
53
        pointQIndex = searchPointIndex(point, n, road[i][1]);
        // x1, y1 は 線分端点Pの座標
54
55
        x1 = point[pointPIndex].x;
        y1 = point[pointPIndex].y;
56
        // x2, y2 は 線分端点Qの座標
57
58
        x2 = point[pointQIndex].x;
        y2 = point[pointQIndex].y;
59
60
61
        coef1 = pow(x2-x1, 2.0);
        coef2 = pow(y2-y1, 2.0);
62
63
        // 方程式を解く
64
65
        x[i] = (1 / (coef1 + coef2)) * (coef1 * x3 + coef2 * x1 - (x2-x1)*(y2-y1)*(y1-y3));
        y[i] = (((y2 - y1)/(x2 - x1)) * (x[i] - x1)) + y1;
66
        // 距離を求める
6.7
        distance[i] = sqrt(fabs((x3 - x[i])*(x3 - x[i]) + (y3 - y[i])*(y3 - y[i])));
68
69
70
```

```
// 最短距離の座標を返す
78
79
      min = INF;
80
      minIndex = 0;
81
      for(i = 1; i <= m; i++) {
        if( (min > distance[i]) && (x[i] != x3) && (y[i] != y3) ) {
82
83
          min = distance[i];
84
          minIndex = i;
85
86
87
88
      connectPoint.x = x[minIndex];
      connectPoint.y = y[minIndex];
89
90
91
       return connectPoint;
92
```

## Task 8

**Algorithm** 

~ Task 8 ~

How to find the <u>bridge edge</u> in graph?

- 1) For every edge (u, v), do following
- ....a) Remove (u, v) from graph
- ....b) See if the graph remains connected (We can

either use BFS or DFS)

We use DFS

....c) Add (u, v) back to the graph.

Reference from **GeekforGeeks**, <a href="https://www.geeksforgeeks.org/bridge-in-a-graph/">https://www.geeksforgeeks.org/bridge-in-a-graph/</a>

#### -> Test case generator

We implemented test case generator using C language.

```
n = 100;
m = 99:
p = 100:
q = 100;
printf("%d %d %d %d\n", n, m, p, q);
for(i = 0; i < n; i++) {
  // 0から100000までの乱数を発生
 x = rand() % 100000;
 y = rand() % 100000;
 printf("%d %d\n", x, y);
for(i = 0; i < m; i++) {
 // 1から99までの乱数を発生
 pointP = rand() % 99 + 1;
  point() = rand() % 99 + 1;
 printf("%d %d\n", pointP, pointQ);
for(i = 0; i < q; i++) {
 // 1から100までの乱数を発生
 start = rand() % 100 + 1;
  end = rand() % 100 + 1;
  orCross = rand() % 4:
  if(orCross == 0) {
   printf("%d %d 1\n", start, end);
  } else if(orCross == 1) {
   printf("C%d %d 1\n", start, end);
 } else if(orCross == 2) {
   printf("%d C%d 1\n", start, end);
  } else {
    printf("C%d C%d 1\n", start, end);
```

#### -> Visualizer

No.

## 4. Demo

## Task 2

#### -> Demo

#### **Test Case 1**

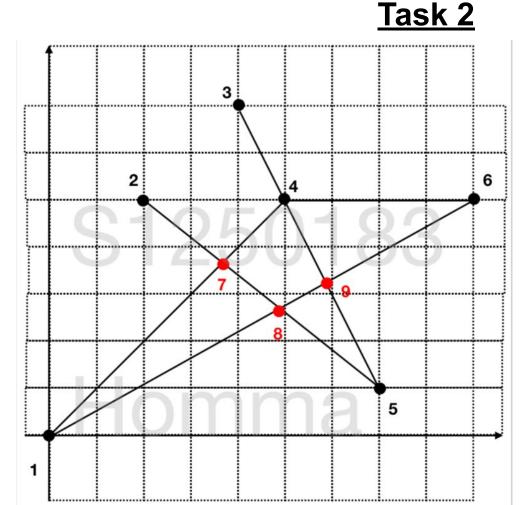
25

3 5

46

#### Output

3.66667 3.66667 4.86885 2.70492 5.86957 3.26087



#### Task 2



7 5

13

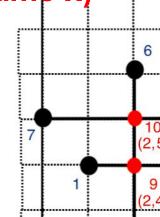
78

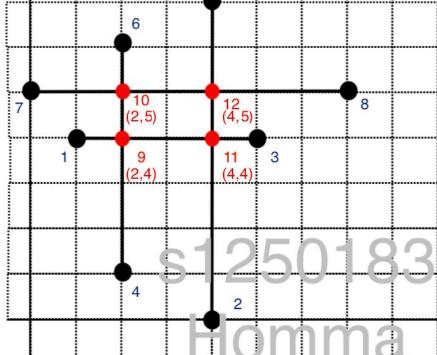
Output

2.000000 4.000000 2.000000 5.000000

4.000000 4.000000

4.000000 5.000000





5

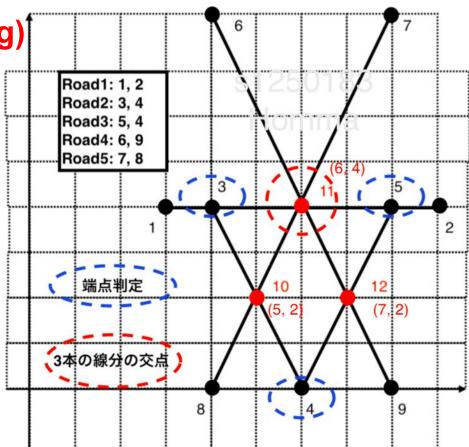
#### Task 2

Test Case 3(3 roads crossing)

78

#### Output

5.000000 2.000000 6.000000 4.000000 7.000000 2.000000



-> Demo Task 2

## Test Case 4(n = 200 m = 100)

```
Input
200 100 0 0
148 886
107 87
449 387
609 351
184 59
87 59
152 30
198 73
154 31
150 47
121 99
181 45
52 65
```

Output

???
(random)

# Task 4

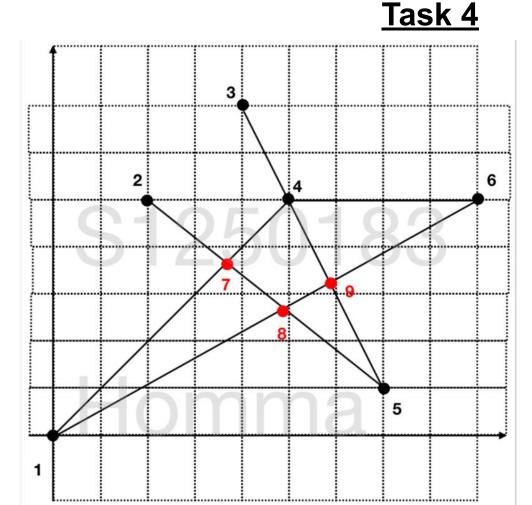
#### **Test Case 1**

C1 C3 1

Output

7.07107 1 C1 4 6.10882 5 C3 6 5.88562 C1 4 6 NA 2.68432

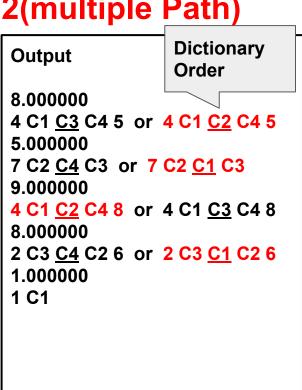
C1 C2 C3

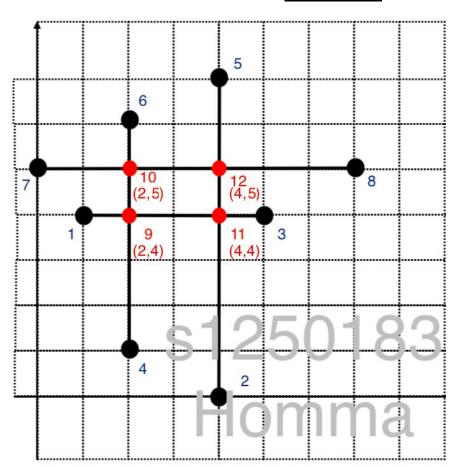


#### Task 4

**Test Case 2(multiple Path)** 

1 C1 1





-> Demo Task 4

## Test Case 4(n = 200 m = 100)

```
Input

200 100 0 100

239 296

92 163

148 903

578 669

557 656

322 559

.....

371 895 1
```

917 C589 1 83 C406 1 99 C760 1 C487 542 1 C124 C903 1

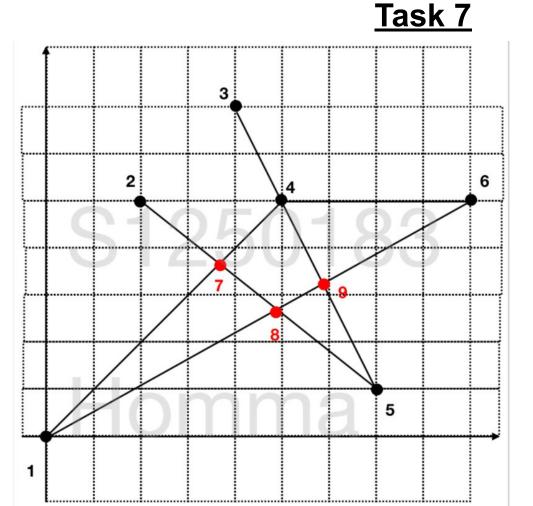
```
Output
???
(random)
```

# Task 7

#### **Test Case 1**

# Input 6540 0 0 5 4 3 6

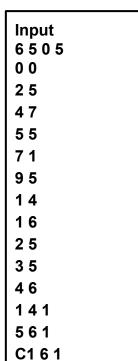
# Output 5.78049 1.97561 9 5 5.4 4.2 4.2 6.6



# Task 8

# Task 8

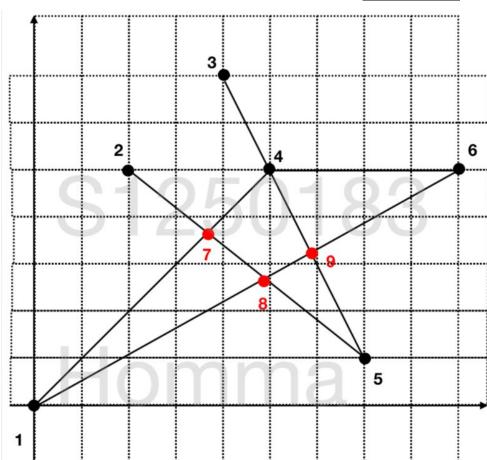
## **Test Case 1**



C1000 1 1 C1 C3 1

# Output

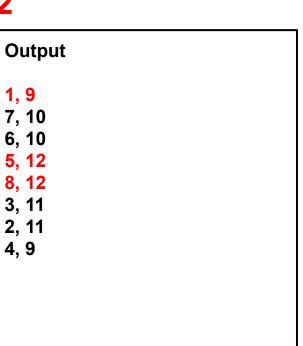
2, 7 3, 9

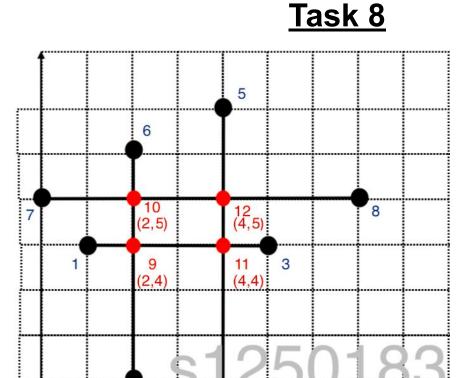


#### **Test Case 2**

## Input 8405 14 40 5 4 47 0 5 7 5 6 4 5 2 4 5 1 7 C3 1 481 261

1 C1 1

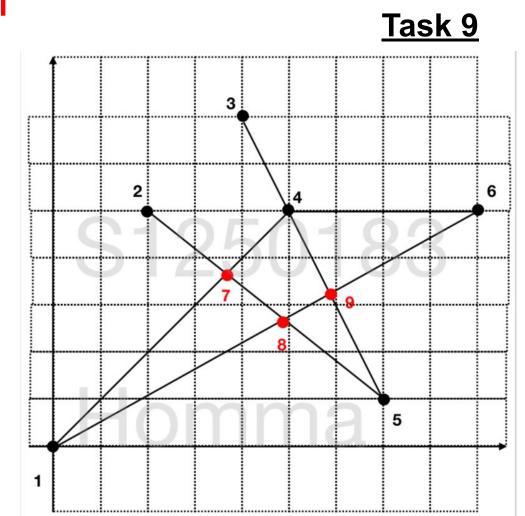




# Task 9

## -> Demo Test Case 1





```
-> Demo
```

$$(n = 100 \text{ m} = 99, p = 100 \text{ q} = 100)$$
 Task 9

# Test Case (n = 200 m = 199, p = 100 q = 100)

```
Input
<u>100 99</u> 100 100
239 296
92 163
148 903
578 669
557 656
322 559
371 895 1
917 C589 1
83 C406 1
99 C760 1
C487 542 1
C124 C903 1
```

```
Output
???
(random)
```

# 5. Contribution

#### -> Member's Role

#### s1250125: Takahisa Watanabe

- Task 1, 2 (Input part)
- Task 5, 6 (not working)

#### s1250183: Yuki Homma

- Task 1, 2 (Detecting crossing part)
- Task 3, 4, 7, 8, 9
- Created the test cases for Task 1, 2, 3, 4, 7, 8, 9
- Created the slides for midterm and final presentation

### -> Contribution

Apr 14, 2019 – Jul 31, 2019

Contributions: Commits ▼







# 6. Summary

# -> Summary

~ Difficulty in development system ~

It is hard for us to satisify the constraints on each tasks.

~ What is the best thing in our system ? ~

Our system can detect the point where many roads are crossing.

# -> Summary

~ What we learned from this project ~

It is too hard to complete project without corporation.

~ What knowledge do we want to share with other groups? ~ We want to share the knowledge of tools.

# Thank you.