EE301 Homework-2

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Question 1

a)

Let $x[n] = \delta[n]$. Then y[n] = h[n] and equation becomes:

$$h[n] - ah[n-1] = \delta[n] - b\delta[n-1]$$

Also, we know that h[n] = 0 for n < 0 since the system is said to be causal.

For n = 0, we have:

$$h[0] - ah[-1] = \delta[0] - b\delta[-1]$$

$$h[0]=1$$

For n = 1, we have:

$$h[1] - ah[0] = \delta[1] - b\delta[0]$$

$$h[1] - a = -b$$

$$h[1] = a - b$$

For n = 2, we have:

$$h[2] - ah[1] = \delta[2] - b\delta[1]$$

$$h[2] - a(a-b) = 0$$

$$h[2] = a(a-b)$$

For n = 3, we have:

$$h[3] - ah[2] = \delta[3] - b\delta[2]$$

$$h[3] - a^2(a - b) = 0$$

$$h[3] = a^2(a-b)$$

In general, for n > 0, we have $h[n] = a^{n-1}(a - b)$.

$$h[n] = \begin{cases} a^{n-1}(a-b), & n > 0\\ 1, & n = 0\\ 0, & n < 0 \end{cases}$$

If the system is stable, then the following expressions must be satisfied:

$$\sum_{k=-\infty}^{\infty} |h[k]| < \infty \Longleftrightarrow 1 + \sum_{k=1}^{\infty} |a|^{k-1} |a-b| < \infty \Longleftrightarrow 1 + |a-b| \sum_{k=0}^{\infty} |a|^k < \infty$$

Therefore, the system is said to be stable \iff $\begin{cases} a \in \mathbb{R}, & \text{if } a = b \\ -1 < a < 1, & \text{otherwise} \end{cases}$

b)

$$y[n] = h[n] * x[n]$$
 and $x[n] = e^{j\Omega_1 n} + e^{j\Omega_2 n}$

By distribution property of the convolution over addition:

$$y[n] = h[n] * e^{j\Omega_1 n} + h[n] * e^{j\Omega_2 n} = \sum_{k=-\infty}^{\infty} h[k] e^{j\Omega_1 (n-k)} + \sum_{k=-\infty}^{\infty} h[k] e^{j\Omega_2 (n-k)}$$

$$y[n] = e^{j\Omega_1 n} + \sum_{k=1}^{\infty} a^{k-1} (a - \frac{1}{a}) e^{j\Omega_1 (n-k)} + e^{j\Omega_2 n} + \sum_{k=1}^{\infty} a^{k-1} (a - \frac{1}{a}) e^{j\Omega_2 (n-k)}$$

$$y[n] = e^{j\Omega_1 n} + \sum_{k=1}^{\infty} a^{k-1} (a - \frac{1}{a}) e^{j\Omega_1 (n-k)} + e^{j\Omega_2 n} + \sum_{k=1}^{\infty} a^{k-1} (a - \frac{1}{a}) e^{j\Omega_2 (n-k)}$$

$$y[n] = e^{j\Omega_1 n} + \sum_{k=1}^{\infty} a^k \frac{(a^2 - 1)}{a^2} e^{j\Omega_1(n-k)} + e^{j\Omega_2 n} + \sum_{k=1}^{\infty} a^k \frac{(a^2 - 1)}{a^2} e^{j\Omega_2(n-k)}$$

$$y[n] = e^{j\Omega_1 n} + \frac{(a^2 - 1)}{a^2} e^{j\Omega_1 n} \sum_{k=1}^{\infty} a^k e^{-j\Omega_1 k} + e^{j\Omega_2 n} + \frac{(a^2 - 1)}{a^2} e^{j\Omega_2 n} \sum_{k=1}^{\infty} a^k e^{-j\Omega_2 k}$$

$$y[n] = e^{j\Omega_1 n} + \frac{(a^2 - 1)}{a^2} e^{j\Omega_1 n} \sum_{k=1}^{\infty} (ae^{-j\Omega_1})^k + e^{j\Omega_2 n} + \frac{(a^2 - 1)}{a^2} e^{j\Omega_2 n} \sum_{k=1}^{\infty} (ae^{-j\Omega_2})^k$$

We know that $-1 \le a \le 1$ if a = b for a stable system. Then we have $|ae^{-j\Omega}| \le 1$ for any Ω .

$$y[n] = e^{j\Omega_1 n} + \frac{(a^2 - 1)}{a^2} e^{j\Omega_1 n} \frac{ae^{-j\Omega_1}}{1 - ae^{-j\Omega_1}} + e^{j\Omega_2 n} + \frac{(a^2 - 1)}{a^2} e^{j\Omega_2 n} \frac{ae^{-j\Omega_2}}{1 - ae^{-j\Omega_2}}$$

Question 2

a)

x(t) and h(t) can be written as:

$$x(t) = u(t+1) - u(t-1)$$

$$h(t) = (1-t)[u(t) - u(t-1)] = \begin{cases} 1-t, & 0 < t < 1 \\ 0, & otherwise \end{cases}$$

Then, $y(t) = x(t) * h(t)$

Before evaluating the convolution, consider the following:

$$\hat{y}(t) = u(t) * h(t) = \int_{-\infty}^{\infty} u(t - \tau)h(\tau) d\tau$$

$$= \int_{-\infty}^{t} h(\tau) d\tau = \begin{cases} 0, & t < 0 \\ \int_{0}^{t} (1 - \tau) d\tau, & 0 < t < 1 \end{cases} = \begin{cases} 0, & t < 0 \\ t - \frac{t^{2}}{2}, & 0 < t < 1 \end{cases}$$

$$= \begin{cases} \int_{-\infty}^{t} h(\tau) d\tau, & t > 1 \end{cases}$$

By the properties of the LTI system:

$$\hat{y}(t+1) = u(t+1) * h(t) = \begin{cases} 0, & t+1 < 0 \\ (t+1) - \frac{(t+1)^2}{2}, & 0 < t+1 < 1 \\ \frac{1}{2}, & t+1 > 1 \end{cases} = \begin{cases} 0, & t < -1 \\ (t+1) - \frac{(t+1)^2}{2}, & -1 < t < 0 \\ \frac{1}{2}, & t > 0 \end{cases}$$

$$\hat{y}(t-1) = u(t-1) * h(t) = \begin{cases} 0, & t-1 < 0 \\ (t-1) - \frac{(t-1)^2}{2}, & 0 < t-1 < 1 \end{cases} = \begin{cases} 0, & t < 1 \\ (t-1) - \frac{(t-1)^2}{2}, & 1 < t < 2 \\ \frac{1}{2}, & t > 1 \end{cases}$$

Therefore,
$$y(t) = \hat{y}(t+1) - \hat{y}(t-1) = \begin{cases} 0, & t < -1 \\ \frac{1-t^2}{2}, & -1 < t < 0 \\ \frac{1}{2}, & 0 < t < 1 \\ \frac{1}{2} - (\frac{t^2 - 4t + 3}{2}), & 1 < t < 2 \\ 0, & t > 2 \end{cases}$$

Also, y(t) can be written as:

$$y(t) = \left(\frac{1-t^2}{2}\right) \cdot u(t+1) + \left(\frac{t^2}{2}\right) \cdot u(t) - \left(\frac{t^2 - 4t + 3}{2}\right) \cdot u(t-1) + \left(\frac{t^2 - 4t + 2}{2}\right) \cdot u(t-2)$$

$$w(t) = h(t) * g(t)$$

 $g(t)$ can be written as: $g(t) = x(t) + x(t-1) - x(t+1)$
Then, $w(t) = h(t) * [x(t) + x(t-1) - x(t+1)]$

By the distributive property of the convolution over addition:

$$w(t) = h(t) * x(t) + h(t) * x(t-1) - h(t) * x(t+1)$$

 $w(t) = y(t) + y(t-1) - y(t+1)$ [by considering part a]

By the time-invarince property of the LTI system:

$$y(t-1) = \left(\frac{2t-t^2}{2}\right) \cdot u(t) + \left(\frac{t^2-2t+1}{2}\right) \cdot u(t-1) - \left(\frac{t^2-6t+8}{2}\right) \cdot u(t-2) + \left(\frac{t^2-6t+7}{2}\right) \cdot u(t-3)$$

$$y(t+1) = \left(\frac{-t^2-2t}{2}\right) \cdot u(t+2) + \left(\frac{t^2+2t+1}{2}\right) \cdot u(t+1) - \left(\frac{t^2-2t}{2}\right) \cdot u(t) + \left(\frac{t^2-2t-1}{2}\right) \cdot u(t-1)$$

As a result:

$$w(t) = \left(\frac{-t^2 - 2t}{2}\right) \cdot u(t+2) + \left(-t^2 - t\right) \cdot u(t+1) + \left(\frac{t^2}{2}\right) \cdot u(t) + \left(\frac{-t^2 + 4t - 1}{2}\right) \cdot u(t-1) + (t-3) \cdot u(t-2) + \left(\frac{t^2 - 6t + 7}{2}\right) \cdot u(t-3)$$

Question 3

a)

$$x(t) = \cdots + \delta(t+2) - 2\delta(t+1) + \delta(t) - 2\delta(t-1) + \delta(t-2) - 2\delta(t-3) + \cdots$$

It is a perodic signal with fundamental period $T_0 = 2$.

$$a_{k} = \frac{1}{T_{0}} \int_{t_{o}}^{t_{0}+T_{0}} x(t)e^{-jk\omega_{0}t} dt = \frac{1}{2} \int_{-\frac{1}{2}}^{\frac{3}{2}} x(t)e^{-jk\pi t} dt$$

$$a_{k} = \frac{1}{2} \underbrace{\int_{0^{-}}^{0^{+}} \delta(t)e^{-jk\pi t} dt}_{e^{-jk\pi}(0)} + \underbrace{\frac{1}{2} \underbrace{\int_{1^{-}}^{1^{+}} -2\delta(t-1)e^{-jk\pi t} dt}_{e^{-jk\pi}(1)}}_{e^{-jk\pi}(1)}$$

$$\Rightarrow a_{k} = \frac{1}{2} - e^{-jk\pi}$$

$$\Rightarrow x(t) = \sum_{n=0}^{\infty} a_{k}e^{jk\omega_{0}t} = \sum_{n=0}^{\infty} \left(\frac{1}{2} - e^{-jk\pi}\right)e^{jk\pi t}$$

b)

x(t) is a perodic signal with fundamental period, $T_0 = 4$.

$$a_{k} = \frac{1}{4} \int_{-2}^{2} x(t)e^{-jk\omega_{0}t}dt = \frac{1}{4} \int_{0}^{1} \cos(\frac{\pi t}{2})e^{-jk\frac{\pi}{2}t}dt$$

$$a_{k} = \frac{1}{4} \int_{0}^{1} \frac{1}{2} \left(e^{j\frac{\pi}{2}t} + e^{-j\frac{\pi}{2}t}\right)e^{-jk\frac{\pi}{2}t}dt = \frac{1}{8} \int_{0}^{1} \left(e^{-j\frac{\pi}{2}(k-1)t} + e^{-j\frac{\pi}{2}(k+1)t}\right)dt$$

$$a_{k} = -\frac{1}{8} \left(\frac{e^{-j\frac{\pi}{2}(k-1)t}}{j(k-1)\frac{\pi}{2}}\Big|_{0}^{1} + \frac{e^{-j\frac{\pi}{2}(k+1)t}}{j(k+1)\frac{\pi}{2}}\Big|_{0}^{1}\right) = \frac{1}{8} \left[\frac{1 - e^{-j\frac{\pi}{2}(k-1)}}{j(k-1)\frac{\pi}{2}}\right] + \frac{1}{8} \left[\frac{1 - e^{-j\frac{\pi}{2}(k+1)}}{j(k+1)\frac{\pi}{2}}\right]$$

$$a_{k} = \frac{1}{8} \left[\frac{1 - e^{-j\frac{\pi}{2}k} e^{j\frac{\pi}{2}}}{j(k-1)\frac{\pi}{2}} \right] + \frac{1}{8} \left[\frac{1 - e^{-j\frac{\pi}{2}k} e^{-j\frac{\pi}{2}}}{j(k+1)\frac{\pi}{2}} \right]$$

$$a_{k} = \frac{1}{8} \left[\frac{1 - j e^{-j\frac{\pi}{2}k}}{j(k-1)\frac{\pi}{2}} \right] + \frac{1}{8} \left[\frac{1 + j e^{-j\frac{\pi}{2}k}}{j(k+1)\frac{\pi}{2}} \right] = \frac{1}{4} \left[\frac{k - j e^{-j\frac{\pi}{2}k}}{j(k^{2}-1)\frac{\pi}{2}} \right] = -\frac{1}{4} \left[\frac{e^{-j\frac{\pi}{2}k} + jk}{(k^{2}-1)\frac{\pi}{2}} \right]$$

$$\Rightarrow x(t) = \sum_{k=-\infty}^{\infty} a_{k} e^{jk\omega_{0}t} = \sum_{k=-\infty}^{\infty} -\frac{1}{4} \left(\frac{e^{-j\frac{\pi}{2}k} + jk}}{(k^{2}-1)\frac{\pi}{2}} \right) e^{jk\frac{\pi}{2}t}$$

 $\mathbf{c})$

$$x[n] = (-1)^n + j^n + \cos(\frac{2\pi n}{3}) = e^{j\pi n} + e^{j\frac{\pi}{2}n} + \cos(\frac{2\pi n}{3})$$

Therefore, x[n] can be written as a summation of 3 distinct perodic signals:

$$x[n] = \underbrace{e^{j\pi n}}_{x_1[n]} + \underbrace{e^{j\frac{\pi}{2}n}}_{x_2[n]} + \underbrace{\cos\left(\frac{2\pi n}{3}\right)}_{x_3[n]} = x_1[n] + x_2[n] + x_3[n]$$

 $x_1[n]$ is a periodic signal with fundamental period $N_0 = 2$.

 $x_2[n]$ is a periodic signal with fundamental period $N_0 = 4$.

 $x_3[n]$ is a periodic signal with fundamental period $N_0 = 3$.

Then, the fundamental period of x[n] is the least common multiple of the fundamental periods of these three signals, so $N_0 = 12$.

$$a_k = \frac{1}{T_0} \sum_{n=n_0}^{n_0 + N_0 - 1} x[n] e^{-jk\frac{2\pi}{N_0}n} = \frac{1}{12} \sum_{n=-6}^{5} x[n] e^{-jk\frac{\pi}{6}n}$$

 \mathbf{d}

x(t) is periodic signal with fundamental period $T_0 = 1$.

$$a_k = \frac{1}{T_0} \int_{t_0}^{t_0 + T_0} x(t) e^{-jk\omega_0 t} dt = \int_0^1 e^{-t} e^{-jk2\pi t} dt = \int_0^1 e^{-t(1+jk2\pi)} dt$$

$$= \frac{-1}{1+jk2\pi} \left[e^{-1} \underbrace{e^{-jk2\pi}}_{\cos(2k\pi)} - 1 \right] = \frac{1}{1+jk2\pi} \left(1 - e^{-1} \right)$$

$$\Rightarrow x(t) = \sum_{k=-\infty}^{\infty} \frac{1}{1+jk2\pi} \left(1 - e^{-1} \right) e^{jk2\pi t}$$

e)

$$\Rightarrow y(t) = x(t) - x(t - \frac{1}{2})$$

$$= \sum_{k = -\infty}^{\infty} \frac{\cos(k\pi)}{1 + jk2\pi} \left(e^{\frac{1}{2}} - e^{\frac{-1}{2}} \right) e^{jk2\pi t} - \sum_{k = -\infty}^{\infty} \frac{\cos(k\pi)}{1 + jk2\pi} \left(e^{\frac{1}{2}} - e^{\frac{-1}{2}} \right) e^{jk2\pi (t - \frac{1}{2})}$$

$$= \sum_{k = -\infty}^{\infty} \frac{\cos(k\pi)}{1 + jk2\pi} \left(e^{\frac{1}{2}} - e^{\frac{-1}{2}} \right) e^{jk2\pi t} - \sum_{k = -\infty}^{\infty} \frac{\cos(k\pi)}{1 + jk2\pi} \left(e^{\frac{1}{2}} - e^{\frac{-1}{2}} \right) e^{jk2\pi t} \underbrace{e^{-jk\pi}}_{\cos(k\pi)}$$

$$= \sum_{k = -\infty}^{\infty} \frac{\cos(k\pi)}{1 + jk2\pi} \left(e^{\frac{1}{2}} - e^{\frac{-1}{2}} \right) e^{jk2\pi t} \left(1 - \cos(k\pi) \right)$$

$$= \sum_{k = -\infty}^{\infty} \frac{\cos(k\pi) - \cos(k\pi)^{2}}{1 + jk2\pi} \left(e^{\frac{1}{2}} - e^{\frac{-1}{2}} \right) e^{jk2\pi t}$$

$$y(t) = \sum_{k = -\infty}^{\infty} \frac{\cos(k\pi) - 1}{1 + jk2\pi} \left(e^{\frac{1}{2}} - e^{\frac{-1}{2}} \right) e^{jk2\pi t}$$

Question 4

a)

Note that, any arbitrary periodic signal $\mathbf{x}(t)$ (or, $\mathbf{x}[\mathbf{n}]$) with Fourier series coefficients a_k is real-valued if $a_k^* = a_{-k}$.

For
$$x_1(t)$$
: $a_k^* = [(\frac{1}{2})^{-k}]^* = (\frac{1}{2})^{-k} \neq (\frac{1}{2})^{-(-k)} = (\frac{1}{2})^k = a_{-k}$
For $x_2(t)$: $a_k^* = (\cos(k\pi))^* = \cos(k\pi) = \cos(-k\pi) = a_{-k}$
For $x_3[n]$: $a_k^* = (j\sin(\frac{k\pi}{2}))^* = -j\sin(\frac{k\pi}{2}) = j\sin(\frac{-k\pi}{2}) = a_{-k}$

Thus, $x_2(t)$ and $x_3[n]$ are real-valued signals.

b)

Any arbitrary periodic signal x(t) (or, x[n]) with Fourier series coefficients a_k is even if a_k is a real-valued and even function.

For $x_1(t)$: $a_k = (\frac{1}{2})^{-k} \Rightarrow$ is a real-valued but not even function, i.e., $(\frac{1}{2})^{-k}\Big|_{k=1} \neq (\frac{1}{2})^{-k}\Big|_{k=-1}$ For $x_2(t)$: $a_k = \cos(k\pi) \Rightarrow$ is a real-valued and also an even function since consider that $-1 \leq \cos(k\pi) \leq 1$ and $\cos(k\pi)\Big|_{k=1} = \cos(k\pi)\Big|_{k=-1}$ For $x_3[n]$: $a_k = j\sin(\frac{k\pi}{2}) \Rightarrow$ neither real-valued nor even function.

Therefore, only the signal $x_2(t)$ is even.

c)

By the time-shifting property of Continuous Time Fourier Series:

$$x_2(t-5) = \sum_{k=-100}^{100} \cos(k\pi)e^{-jk\frac{\pi}{5}}e^{jk\frac{2\pi}{50}t} \quad \text{and, also note that} \quad \cos(k\pi) = \frac{1}{2}(e^{jk\pi} + e^{-jk\pi})$$

$$\Rightarrow x_2(t-5) = \sum_{k=-100}^{100} \frac{1}{2}(e^{jk\frac{4\pi}{5}} + e^{-jk\frac{6\pi}{5}})e^{jk\frac{2\pi}{50}t}$$

Thus, $x_2(t-5)$ is another periodic signal with Fourier series coefficients $b_k = \frac{1}{2}(e^{jk\frac{4\pi}{5}} + e^{-jk\frac{6\pi}{5}})$. Also, remember the theorem mentioned above, the signal $x_2(t-5)$ is real if $b_k^* = b_{-k}$. $b_k^* = (\frac{1}{2}(e^{jk\frac{4\pi}{5}} + e^{-jk\frac{6\pi}{5}}))^* = \frac{1}{2}(e^{-jk\frac{4\pi}{5}} + e^{jk\frac{6\pi}{5}}) = b_{-k} \Rightarrow \text{the signal } x_2(t-5) \text{ is real.}$

To check whether the signal $x_2(t-5)$ is even, b_k can be written as:

$$\begin{array}{l} b_k = \frac{1}{2}[\cos(k\frac{4\pi}{5}) + j\sin(k\frac{4\pi}{5}) + \cos(k\frac{6\pi}{5}) - j\sin(k\frac{6\pi}{5})] \\ b_k = \frac{1}{2}[\cos(k\frac{4\pi}{5}) + \cos(k\frac{6\pi}{5})] - \frac{1}{2}j[\sin(k\frac{6\pi}{5}) - \sin(k\frac{4\pi}{5})] \end{array}$$

Also, note that
$$sina - sinb = 2cos(\frac{a+b}{2})sin(\frac{a-b}{2})$$

Thus,
$$b_k = \frac{1}{2} [\cos(k\frac{4\pi}{5}) + \cos(k\frac{6\pi}{5})] - j[\cos(2\pi k)\sin(k\frac{2\pi}{5})]$$

 $\Rightarrow b_k = \frac{1}{2} (\cos(k\frac{4\pi}{5}) + \cos(k\frac{6\pi}{5})) - j\sin(k\frac{2\pi}{5})$

As a result, it can be seen that b_k is not real-valued, so the signal $x_2(t-5)$ is not even.

d)

By differentiation property of Continuous Time Fourier Series:

$$\frac{d}{dt}x_2(t) = \sum_{k=-\infty}^{\infty} \cos(k\pi)jk \frac{2\pi}{50} e^{jk\frac{2\pi}{50}} \Rightarrow \text{ is a periodic signal with Fourier series coefficients } c_k$$
 such that $c_k = \cos(k\pi)jk \frac{2\pi}{50}$.
$$c_k^* = -jk \frac{2\pi}{50} \cos(k\pi) \quad \text{and} \quad c_{-k} = j(-k) \frac{2\pi}{50} \cos(-k\pi) = -jk \frac{2\pi}{50} \cos(k\pi)$$

$$c_k^* = c_{-k} \Rightarrow \frac{d}{dt}x_2(t) \text{ is real-valued.}$$

Note that, $cos(k\pi)$ take only the values +1 or -1, so it is always real-valued. However, $-jk\frac{2\pi}{50}$ is purely imaginary. Therefore, $\frac{d}{dt}x_2(t)$ is not even.

e)

Parseval's Identity: For any continuous-time periodic signal x(t) with the Fourier series coefficients a_k ,

$$\frac{1}{T_0} \int_{t_0}^{t_0 + T_0} x(t) x^*(t) dt = \sum_{k = -\infty}^{\infty} a_k a_k^* \Rightarrow \frac{1}{T_0} \int_{t_0}^{t_0 + T_0} |x(t)|^2 dt = \sum_{k = -\infty}^{\infty} |a_k|^2$$

In this question, $x_1(t)$ is a periodic signal whose fundamental period, $T_0 = 50$ and its Fourier series coefficients $a_k = (\frac{1}{2})^{-k}$. Please also note that, for this signal, the coefficients are defined only for $0 \le k \le 100$ since outside this domain all of the coefficients are equal to 0. So, by using Parseval's identity, the average power of $x_1(t)$ in one period:

$$\frac{1}{50} \int_0^{50} |x_1(t)|^2 dt = \sum_{k=0}^{100} |a_k|^2 = \sum_{k=0}^{100} \left(\frac{1}{2}\right)^{-2k} = \sum_{k=0}^{100} 4^k = 1 + 4^1 + 4^2 + 4^3 + \dots + 4^{100}$$