## EE301 Homework-2

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## Question 1

#### a)

Let  $x[n] = \delta[n]$ . Then y[n] = h[n] $h[n] - ah[n-1] = \delta[n] - b\delta[n-1]$ We know that h[n] = 0 for n < 0 as the system is causal. For n = 0 we have  $h[0] - ah[-1] = \delta[0] - b\delta[-1]$ h[0] = 1For n = 1, we have  $h[1] - ah[0] = \delta[1] - b\delta[0]$ h[1] - a = -bh[1] = a - bFor n=2, we have  $h[2] - ah[1] = \delta[2] - b\delta[1]$ h[2] - a(a-b) = 0h[2] = a(a-b)For n = 3, we have  $h[3] - ah[2] = \delta[3] - b\delta[2]$  $h[3] - a^2(a - b) = 0$  $h[2] = a^2(a-b)$ In general, for n > 0, we have  $h[n] = a^{n-1}(a - b)$ .  $h[n] = \begin{cases} a^{n-1}(a-b), & n > 0\\ 1, & n = 0\\ 0, & n < 0 \end{cases}$ 

If the system is stable, then

$$\begin{split} &\sum_{k=-\infty}^{\infty} |h[k]| < \infty \\ &1 + \sum_{k=1}^{\infty} |a|^{k-1} |a-b| < \infty \\ &1 + |a-b| \sum_{k=0}^{\infty} |a|^k < \infty \end{split}$$

Therefore, -1 < a < 1 if the system is stable.

**b**)

### Question 2

a)

x(t) and h(t) can be written as:

$$x(t) = u(t+1) - u(t-1)$$

$$h(t) = (1-t)[u(t) - u(t-1)] = \begin{cases} 1-t, & 0 < t < 1\\ 0, & otherwise \end{cases}$$
Then,  $u(t) = x(t) * h(t)$ 

Then, y(t) = x(t) \* h(t)

Before evaluating the convolution, consider the following:

$$\hat{y}(t) = u(t) * h(t) = \int_{-\infty}^{\infty} u(t - \tau)h(\tau) d\tau$$

$$\begin{cases} 0, & t < 0 \end{cases}$$

$$= \int_{-\infty}^{t} h(\tau) d\tau = \begin{cases} 0, & t < 0 \\ \int_{0}^{t} (1 - \tau) d\tau, & 0 < t < 1 \end{cases} = \begin{cases} 0, & t < 0 \\ t - \frac{t^{2}}{2}, & 0 < t < 1 \end{cases}$$
$$\int_{0}^{1} (1 - \tau) d\tau, & t > 1 \end{cases}$$

By the properties of the LTI system:

$$\hat{y}(t+1) = u(t+1) * h(t) = \begin{cases} 0, & t+1 < 0 \\ (t+1) - \frac{(t+1)^2}{2}, & 0 < t+1 < 1 \\ \frac{1}{2}, & t+1 > 1 \end{cases} = \begin{cases} 0, & t < -1 \\ (t+1) - \frac{(t+1)^2}{2}, & -1 < t < 0 \\ \frac{1}{2}, & t > 0 \end{cases}$$

$$\hat{y}(t-1) = u(t-1) * h(t) = \begin{cases} 0, & t-1 < 0 \\ (t-1) - \frac{(t-1)^2}{2}, & 0 < t-1 < 1 \end{cases} = \begin{cases} 0, & t < 1 \\ (t-1) - \frac{(t-1)^2}{2}, & 1 < t < 2 \\ \frac{1}{2}, & t > 1 \end{cases}$$

Therefore, 
$$y(t) = \hat{y}(t+1) - \hat{y}(t-1) = \begin{cases} 0, & t < -1 \\ \frac{1-t^2}{2}, & -1 < t < 0 \\ \frac{1}{2}, & 0 < t < 1 \\ \frac{1}{2} - (\frac{t^2 - 4t + 3}{2}), & 1 < t < 2 \\ 0, & t > 2 \end{cases}$$

Also, y(t) can be written as:

$$y(t) = (\frac{1-t^2}{2}) \cdot u(t+1) + (\frac{t^2}{2}) \cdot u(t) - (\frac{t^2-4t+3}{2}) \cdot u(t-1) + (\frac{t^2-4t+2}{2}) \cdot u(t-2)$$

b)

$$w(t) = h(t) * g(t)$$
  
 $g(t)$  can be written as:  $g(t) = x(t) + x(t-1) - x(t+1)$   
Then,  $w(t) = h(t) * [x(t) + x(t-1) - x(t+1)]$ 

By the distributive property of the convolution over addition:

$$w(t) = h(t) * x(t) + h(t) * x(t-1) - h(t) * x(t+1)$$
  
 $w(t) = y(t) + y(t-1) - y(t+1)$  [by considering part a]

By the time-invarince property of the LTI system:

$$y(t-1) = \left(\frac{2t-t^2}{2}\right) \cdot u(t) + \left(\frac{t^2-2t+1}{2}\right) \cdot u(t-1) - \left(\frac{t^2-6t+8}{2}\right) \cdot u(t-2) + \left(\frac{t^2-6t+7}{2}\right) \cdot u(t-3)$$

$$y(t+1) = \left(\frac{-t^2-2t}{2}\right) \cdot u(t+2) + \left(\frac{t^2+2t+1}{2}\right) \cdot u(t+1) - \left(\frac{t^2-2t}{2}\right) \cdot u(t) + \left(\frac{t^2-2t-1}{2}\right) \cdot u(t-1)$$

As a result:

$$w(t) = \left(\frac{-t^2 - 2t}{2}\right) \cdot u(t+2) + \left(-t^2 - t\right) \cdot u(t+1) + \left(\frac{t^2}{2}\right) \cdot u(t) + \left(\frac{-t^2 + 4t - 1}{2}\right) \cdot u(t-1) + (t-3) \cdot u(t-2) + \left(\frac{t^2 - 6t + 7}{2}\right) \cdot u(t-3)$$

## Question 3

**a**)

$$x(t) = \dots + \delta(t+2) - 2\delta(t+1) + \delta(t) - 2\delta(t-1) + \delta(t-2) - 2\delta(t-3) + \dots$$
It is a perodic signal with fundamental period  $T_0 = 2$ .
$$a_k = \frac{1}{T_0} \int_t^{t_0 + T_0} x(t)e^{-jk\omega_0 t} dt = \frac{1}{2} \int_{-1}^{\frac{3}{2}} x(t)e^{-jk\pi t} dt$$

$$a_k = \frac{1}{2} \underbrace{\int_{0^-}^{0^+} \delta(t) e^{-jk\pi t} dt}_{e^{-jk\pi(0)}} + \underbrace{\frac{1}{2} \underbrace{\int_{1^-}^{1^+} -2\delta(t-1) e^{-jk\pi t} dt}_{e^{-jk\pi(1)}}}_{e^{-jk\pi(1)}}$$
 Also, recall that  $\underbrace{\int_{-\infty}^{\infty} \delta(t-t_0) x(t) = x(t_0)}_{e^{-jk\pi(0)}}$   $\Rightarrow a_k = \frac{1}{2} - e^{-jk\pi}$   $\Rightarrow x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} = \sum_{k=-\infty}^{\infty} \left(\frac{1}{2} - e^{-jk\pi}\right) e^{jk\pi t}$ 

**b**)

x(t) is a perodic signal with fundamental period,  $T_0 = 4$ .

$$a_{k} = \frac{1}{4} \int_{-2}^{2} x(t)e^{-jk\omega_{0}t}dt = \frac{1}{4} \int_{0}^{1} \cos(\frac{\pi t}{2})e^{-jk\frac{\pi}{2}t}dt$$

$$a_{k} = \frac{1}{4} \int_{0}^{1} \frac{1}{2} \left(e^{j\frac{\pi}{2}t} + e^{-j\frac{\pi}{2}t}\right)e^{-jk\frac{\pi}{2}t}dt = \frac{1}{8} \int_{0}^{1} \left(e^{-j\frac{\pi}{2}(k-1)t} + e^{-j\frac{\pi}{2}(k+1)t}\right)dt$$

$$a_{k} = -\frac{1}{8} \left(\frac{e^{-j\frac{\pi}{2}(k-1)t}}{j(k-1)\frac{\pi}{2}}\Big|_{0}^{1} + \frac{e^{-j\frac{\pi}{2}(k+1)t}}{j(k+1)\frac{\pi}{2}}\Big|_{0}^{1}\right) = \frac{1}{8} \left[\frac{1-e^{-j\frac{\pi}{2}(k-1)}}{j(k-1)\frac{\pi}{2}}\right] + \frac{1}{8} \left[\frac{1-e^{-j\frac{\pi}{2}(k+1)}}{j(k+1)\frac{\pi}{2}}\right]$$

$$a_{k} = \frac{1}{8} \left[\frac{1-e^{-j\frac{\pi}{2}k}e^{j\frac{\pi}{2}}}{j(k-1)\frac{\pi}{2}}\right] + \frac{1}{8} \left[\frac{1-e^{-j\frac{\pi}{2}k}e^{-j\frac{\pi}{2}}}{j(k+1)\frac{\pi}{2}}\right]$$

$$a_{k} = \frac{1}{8} \left[\frac{1-je^{-j\frac{\pi}{2}k}}{j(k-1)\frac{\pi}{2}}\right] + \frac{1}{8} \left[\frac{1+je^{-j\frac{\pi}{2}k}}{j(k+1)\frac{\pi}{2}}\right] = \frac{1}{4} \left[\frac{k-je^{-j\frac{\pi}{2}k}}{j(k^{2}-1)\frac{\pi}{2}}\right] = -\frac{1}{4} \left[\frac{e^{-j\frac{\pi}{2}k}+jk}}{(k^{2}-1)\frac{\pi}{2}}\right]$$

$$\Rightarrow x(t) = \sum_{k=0}^{\infty} a_{k}e^{jk\omega_{0}t} = \sum_{k=0}^{\infty} -\frac{1}{4} \left(\frac{e^{-j\frac{\pi}{2}k}+jk}}{(k^{2}-1)\frac{\pi}{2}}\right)e^{jk\frac{\pi}{2}t}$$

 $\mathbf{c})$ 

$$x[n] = (-1)^n + j^n + \cos(\frac{2\pi n}{3}) = e^{j\pi n} + e^{j\frac{\pi}{2}n} + \cos(\frac{2\pi n}{3})$$

Therefore, x[n] can be written as a summation of 3 distinct perodic signals:

$$x[n] = \underbrace{e^{j\pi n}}_{x_1[n]} + \underbrace{e^{j\frac{\pi}{2}n}}_{x_2[n]} + \underbrace{\cos\left(\frac{2\pi n}{3}\right)}_{x_3[n]} = x_1[n] + x_2[n] + x_3[n]$$

 $x_1[n]$  is a periodic signal with fundamental period  $N_0 = 2$ .

 $x_2[n]$  is a periodic signal with fundamental period  $N_0 = 4$ .

 $x_3[n]$  is a periodic signal with fundamental period  $N_0 = 3$ .

Then, the fundamental period of x[n] is the least common multiple of the fundamental periods of these three signals, so  $N_0 = 12$ .

$$a_k = \frac{1}{T_0} \sum_{n=n_0}^{n_0 + N_0 - 1} x[n] e^{-jk\frac{2\pi}{N_0}n} = \frac{1}{12} \sum_{n=-6}^{5} x[n] e^{-jk\frac{\pi}{6}n}$$

d)

x(t) is periodic signal with fundamental period  $T_0 = 1$ .

$$a_{k} = \frac{1}{T_{0}} \int_{t_{o}}^{t_{0}+T_{0}} x(t)e^{-jk\omega_{0}t}dt = \int_{\frac{-1}{2}}^{\frac{1}{2}} e^{-t}e^{-jk2\pi t}dt = \int_{\frac{-1}{2}}^{\frac{1}{2}} e^{-t(1+jk2\pi)}dt$$

$$= \frac{-1}{1+jk2\pi} \left[ e^{\frac{-1}{2}} \underbrace{e^{-jk\pi}}_{\cos(k\pi)} - e^{\frac{1}{2}} \underbrace{e^{jk\pi}}_{\cos(k\pi)} \right] = \frac{\cos(k\pi)}{1+jk2\pi} \left( e^{\frac{1}{2}} - e^{\frac{-1}{2}} \right)$$

$$\Rightarrow x(t) = \sum_{k=-\infty}^{\infty} \frac{\cos(k\pi)}{1+jk2\pi} \left( e^{\frac{1}{2}} - e^{\frac{-1}{2}} \right) e^{jk2\pi t}$$

**e**)

Recall that: 
$$y(t) = h(t) * x(t)$$
 
$$x(t) * \delta(t) = x(t)$$
 
$$x(t) * \delta(t) = x(t)$$
 
$$x(t) * \delta(t) - \delta(t - \frac{1}{2})$$
 
$$x(t) * \delta(t) - x(t) * \delta(t) - x(t) * \delta(t - \frac{1}{2})$$
 
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$$x(t) * \delta(t) - x(t) * \delta(t - \frac{1}{2})$$
 
$$x(t) * \delta(t) - x(t) * \delta(t - \frac{1}{2})$$
 
$$x(t) * \delta(t) - x(t) * \delta(t - \frac{1}{2})$$
 
$$x(t) * \delta(t) - x(t) * \delta(t - \frac{1}{2})$$
 
$$x(t) * \delta(t) - x(t) * \delta(t) + x(t) * \delta(t - \frac{1}{2})$$
 
$$x(t) * \delta(t) - x(t) * \delta(t) + x(t) * \delta(t) * \delta(t) + x(t) * \delta(t) * \delta(t) * \delta(t) + x(t) * \delta(t) * \delta(t) * \delta(t) * \delta(t) * \delta(t) * \delta(t)$$

## Question 4

**a**)

Note that, any arbitrary periodic signal x(t) (or, x[n]) with Fourier series coefficients  $a_k$  is real-valued if  $a_k^* = a_{-k}$ .

For 
$$x_1(t)$$
:  $a_k^* = [(\frac{1}{2})^{-k}]^* = (\frac{1}{2})^{-k} \neq (\frac{1}{2})^{-(-k)} = (\frac{1}{2})^k = a_{-k}$   
For  $x_2(t)$ :  $a_k^* = (\cos(k\pi))^* = \cos(k\pi) = \cos(-k\pi) = a_{-k}$   
For  $x_3[n]$ :  $a_k^* = (j\sin(\frac{k\pi}{2}))^* = -j\sin(\frac{k\pi}{2}) = j\sin(\frac{-k\pi}{2}) = a_{-k}$ 

Thus,  $x_2(t)$  and  $x_3[n]$  are real-valued signals.

#### b)

Any arbitrary periodic signal x(t) (or, x[n]) with Fourier series coefficients  $a_k$  is even if  $a_k$  is a real-valued and even function.

For  $x_1(t)$ :  $a_k = (\frac{1}{2})^{-k} \Rightarrow$  is a real-valued but not even function, i.e.,  $(\frac{1}{2})^{-k}\Big|_{k=1} \neq (\frac{1}{2})^{-k}\Big|_{k=-1}$ For  $x_2(t)$ :  $a_k = \cos(k\pi) \Rightarrow$  is a real-valued and also an even function since consider that  $-1 \leq \cos(k\pi) \leq 1$  and  $\cos(k\pi)\Big|_{k=1} = \cos(k\pi)\Big|_{k=-1}$ For  $x_3[n]$ :  $a_k = j\sin(\frac{k\pi}{2}) \Rightarrow$  neither real-valued nor even function.

Therefore, only the signal  $x_2(t)$  is even.

#### $\mathbf{c}$ )

By the time-shifting property of Continuous Time Fourier Series:

$$x_2(t-5) = \sum_{k=-100}^{100} \cos(k\pi) e^{-jk\frac{\pi}{5}} e^{jk\frac{2\pi}{50}t} \quad \text{and, also note that} \quad \cos(k\pi) = \frac{1}{2} (e^{jk\pi} + e^{-jk\pi})$$

$$\Rightarrow x_2(t-5) = \sum_{k=-100}^{100} \frac{1}{2} (e^{jk\frac{4\pi}{5}} + e^{-jk\frac{6\pi}{5}}) e^{jk\frac{2\pi}{50}t}$$

Thus,  $x_2(t-5)$  is another periodic signal with Fourier series coefficients  $b_k = \frac{1}{2}(e^{jk\frac{4\pi}{5}} + e^{-jk\frac{6\pi}{5}})$ . Also, remember the theorem mentioned above, the signal  $x_2(t-5)$  is real if  $b_k^* = b_{-k}$ .  $b_k^* = (\frac{1}{2}(e^{jk\frac{4\pi}{5}} + e^{-jk\frac{6\pi}{5}}))^* = \frac{1}{2}(e^{-jk\frac{4\pi}{5}} + e^{jk\frac{6\pi}{5}}) = b_{-k} \Rightarrow$  the signal  $x_2(t-5)$  is real.

To check whether the signal  $x_2(t-5)$  is even,  $b_k$  can be written as:

$$\begin{array}{l} b_k = \frac{1}{2}[\cos(k\frac{4\pi}{5}) + j\sin(k\frac{4\pi}{5}) + \cos(k\frac{6\pi}{5}) - j\sin(k\frac{6\pi}{5})] \\ b_k = \frac{1}{2}[\cos(k\frac{4\pi}{5}) + \cos(k\frac{6\pi}{5})] - \frac{1}{2}j[\sin(k\frac{6\pi}{5}) - \sin(k\frac{4\pi}{5})] \end{array}$$

Also, note that 
$$sina - sinb = 2cos(\frac{a+b}{2})sin(\frac{a-b}{2})$$

Thus, 
$$b_k = \frac{1}{2} \left[ \cos(k \frac{4\pi}{5}) + \cos(k \frac{6\pi}{5}) \right] - j \left[ \cos(2\pi k) \sin(k \frac{2\pi}{5}) \right]$$
  
 $\Rightarrow b_k = \frac{1}{2} \left( \cos(k \frac{4\pi}{5}) + \cos(k \frac{6\pi}{5}) \right) - j \sin(k \frac{2\pi}{5})$ 

As a result, it can be seen that  $b_k$  is not real-valued, so the signal  $x_2(t-5)$  is not even.

d)

By differentiation property of Continuous Time Fourier Series:

$$\frac{d}{dt}x_2(t) = \sum_{k=-\infty}^{\infty} \cos(k\pi)jk \frac{2\pi}{50} e^{jk\frac{2\pi}{50}} \Rightarrow \text{ is a periodic signal with Fourier series coefficients } c_k$$
 such that  $c_k = \cos(k\pi)jk \frac{2\pi}{50}$ .
$$c_k^* = -jk \frac{2\pi}{50}\cos(k\pi) \quad \text{and} \quad c_{-k} = j(-k) \frac{2\pi}{50}\cos(-k\pi) = -jk \frac{2\pi}{50}\cos(k\pi)$$

$$c_k^* = c_{-k} \Rightarrow \frac{d}{dt}x_2(t) \text{ is real-valued.}$$

Note that,  $cos(k\pi)$  take only the values +1 or -1, so it is always real-valued. However,  $-jk\frac{2\pi}{50}$  is purely imaginary. Therefore,  $\frac{d}{dt}x_2(t)$  is not even.

e)

**Parseval's Identity:** For any continuous-time periodic signal x(t) with the Fourier series coefficients  $a_k$ ,

$$\frac{1}{T_0} \int_{t_0}^{t_0 + T_0} x(t) x^*(t) dt = \sum_{k = -\infty}^{\infty} a_k a_k^* \Rightarrow \frac{1}{T_0} \int_{t_0}^{t_0 + T_0} |x(t)|^2 dt = \sum_{k = -\infty}^{\infty} |a_k|^2$$

In this question,  $x_1(t)$  is a periodic signal whose fundamental period,  $T_0 = 50$  and its Fourier series coefficients  $a_k = (\frac{1}{2})^{-k}$ . Please also note that, for this signal, the coefficients are defined only for  $0 \le k \le 100$  since outside this domain all of the coefficients are equal to 0. So, by using Parseval's identity, the average power of  $x_1(t)$  in one period:

$$\frac{1}{50} \int_0^{50} |x_1(t)|^2 dt = \sum_{k=0}^{100} |a_k|^2 = \sum_{k=0}^{100} \left(\frac{1}{2}\right)^{-2k} = \sum_{k=0}^{100} 4^k = 1 + 4^1 + 4^2 + 4^3 + \dots + 4^{100}$$

#### Question 5

**a**)

b)