







- dp: Difference
- leftEye: Left
- rightEye: Right
- sensorTo: Sensor to
- heading: Heading
- Tracker(D
- diffValues
- resetHea
- sumValue
- minValue:
- trackLine(
- rotateTo(
- stop():voi
- rotate(dou
- rotate(dou
- crossBlac
- myCalibra

```
entialPilot
ightSensor
LightSensor
AxleLength: double
double
)ifferentialPilot,LightSensor,LightSensor,double)
i():int
ding():void
s():int
s():int
():void
double,boolean):void
d
uble):void
uble,boolean):void
k():void
ate():void
```