## Test-Report Part 1

## Test List

Test-ID	Test-Name	Description
1	Install-Script	We wrote an install script to
	mstan seript	make it more easy to get our
		framework to work on a new
		Computer and need to make
		sure if all required packages
		are installed correctly.
2	Start SimRobot	Start the software SimRobot
		and test if everything works
		correctly.
3	Upload Software	Test if our code can be
	, '	uploaded on a robot via the
		hulks upload.sh script.
4	Customize Scene SimRobot	Customize a scene based on
		our field as it is smaller than
		the official one, for the
		SimRobot and execute it.
5	Set Up Teams	The robot settings are
		configured by JSON files. We
		need to test if we are able to
		set up customized teams which
		suit our needs.
6	Gammaray Anastasia– Execute	Gammaray describes to the
	Code	frameworks process when a
		nao robot gets configured to
		run the code of our
		framework.
7	Gammaray Tom – Execute	Gammaray describes to the
	Code	frameworks process when a
		nao robot gets configured to
		run the code of our
		framework.
8	Gammaray Luc – Execute Code	Gammaray describes to the
		frameworks process when a
		nao robot gets configured to run the code of our
		framework.
9	Sot Un Tooms for	
	Set Up Teams for GameController	Set up Custom Teams for the GameController
10	SendActionsSimRobot	Send specific commands to a
	SCHUACHOHSSIIIINODOL	virtual robot. For example
		penalize it.
11	SendActionsRealRobot	Send specific commands to a
	SelidActionshedinopot	real robot. For example
		penalize it.
12	Set up MATE real	See if the MATE software
	Jet up MATE Teat	works on a real robot.
		works on a real lobot.

13	Set up MATE SimRobot	See if the MATE software
		works on a virtual robot
14	Orientation Single Robot	Analyze what a single robots
		perceived location is compared
		to its actual location.
15	Orientation Two Robots	Same as above but the robots
		act as team now (test
		collective perception)
16	Recognize Football	See if the robots are able to
		recognize the football.
17	Walk towards Football	See if a robot is able to walk
		accurately to the football
18	Kick the ball towards the right	The robots have to be able to
	direction	realize whether they head into
		the right direction and
		therefore kick the ball towards
		the enemy's goal.
19	Behavior Roles	Check if the robots are
		behaving in the way their
		current roles were defined.
20	Brightness	Test if the brightness is good
		enough for the robots to play
		football properly.
21	Ball in the corner	See how the robot acts like if
		the ball is lying in the corner.
22	Searching ball	Observe what strategies the
		robot applies to find the ball.
23	Kicking Density	See if the robot customizes the
		strength with that he kicks the
		ball.
24	Restart after Penalisation	Look if the robot starts
		immediately after penalty time
		is over.
25	Whistle Recognition	Test if the robots are
		recognizing the starting
		whistle.
26	Start-Position Finding	Test if the robots are taking
		their determined position
		flawlessly after every point and
		at the start of the game.
27	Foul Handling	Test what strategies are
		implemented in the current
		framework to prevent fouls
		and look if they work properly.
28	Eyes friend / enemy detection	Find out if the light of the eyes
		help for enemy detection.
29	Behavior when mates	See if the behavior roles
	Penalised	change if one or more
		teammates are Penalised.
30	Whole 2 vs 2 Game	Test a whole 2 vs 2 game with
		two custom prepared teams.