PTE: Predictive Text Embedding through Large-scale Heterogeneous Text Networks

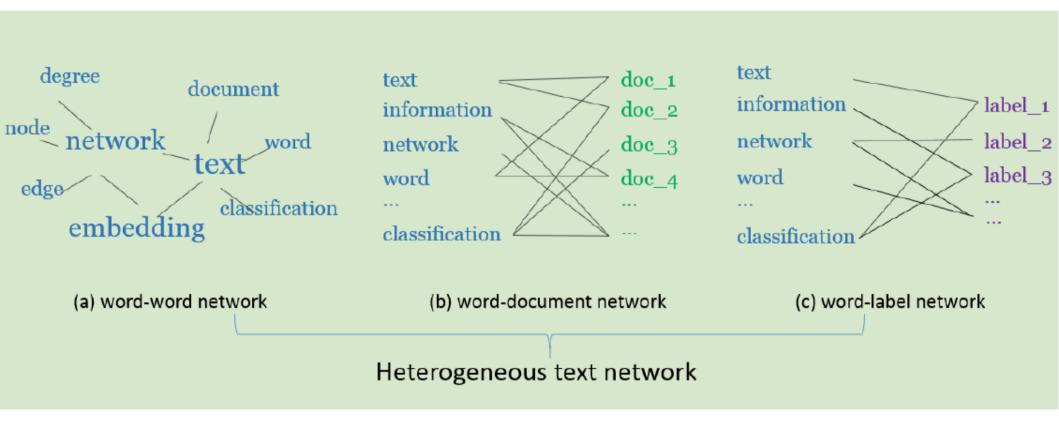
基于大规模异构文本网络的预测性文本嵌入

KDD 2015

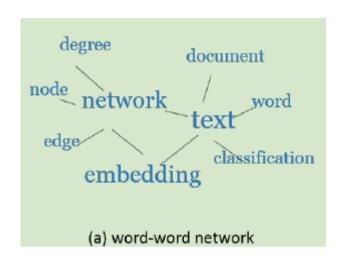
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Heterogeneous Text Networks

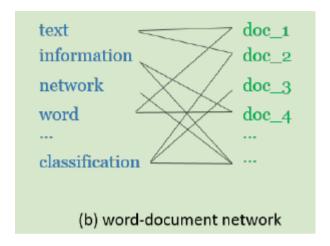


What Is Word-Word Network?



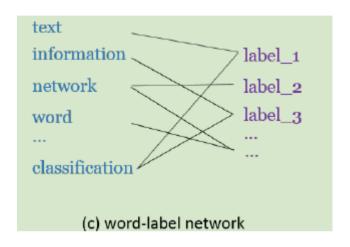
DEFINITION 1. (Word-Word Network) Word-word cooccurrence network, denoted as $G_{ww} = (\mathcal{V}, E_{ww})$, captures the word co-occurrence information in local contexts of the unlabeled data. \mathcal{V} is a vocabulary of words and E_{ww} is the set of edges between words. The weight w_{ij} of the edge between word v_i and v_j is defined as the number of times that the two words co-occur in the context windows of a given window size.

What Is Word-Document Network?



DEFINITION 2. (Word-Document Network) Word-document network, denoted as $G_{wd} = (\mathcal{V} \cup \mathcal{D}, E_{wd})$, is a bipartite network where \mathcal{D} is a set of documents and \mathcal{V} is a set of words. E_{wd} is the set of edges between words and documents. The weight w_{ij} between word v_i and document d_j is simply defined as the number of times v_i appears in document d_j .

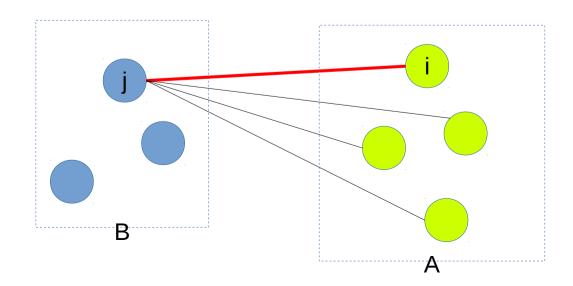
What Is Word-Label Network?



DEFINITION 3. (Word-Label Network) Word-label network, denoted as $G_{wl} = (\mathcal{V} \cup \mathcal{L}, E_{wl})$, is a bipartite network that captures category-level word co-occurrences. \mathcal{L} is a set of class labels and \mathcal{V} a set of words. E_{wl} is a set of edges between words and classes. The weight w_{ij} of the edge between word v_i and class c_j is defined as: $w_{ij} = \sum_{(d:l_d=j)} n_{di}$, where n_{di} is the term frequency of word v_i in document d, and l_d is the class label of document d.

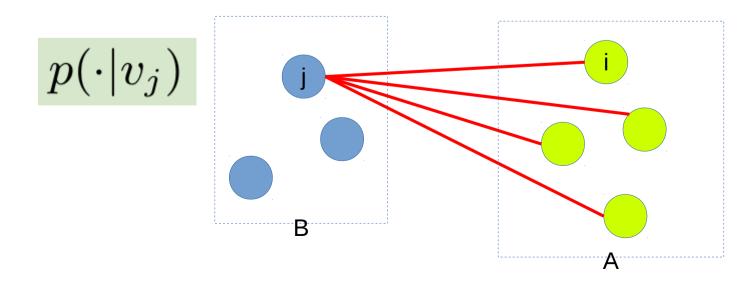
Given a bipartite network $G = (\mathcal{V}_A \cup \mathcal{V}_B, E)$, where \mathcal{V}_A and \mathcal{V}_B are two disjoint sets of vertices of different types, and E is the set of edges between them. We first define the conditional probability of vertex v_i in set \mathcal{V}_A generated by vertex v_j in set \mathcal{V}_B as:

$$p(v_i|v_j) = \frac{\exp(\vec{u}_i^T \cdot \vec{u}_j)}{\sum_{i' \in A} \exp(\vec{u}_{i'}^T \cdot \vec{u}_j)},$$
 (1)



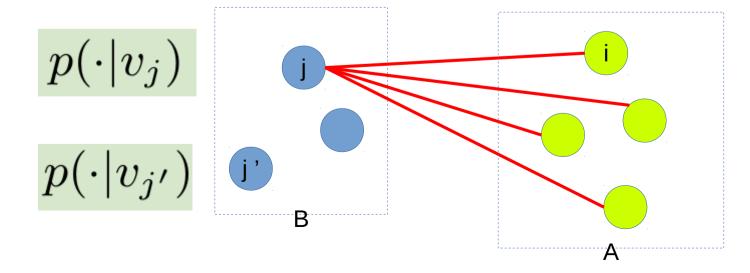
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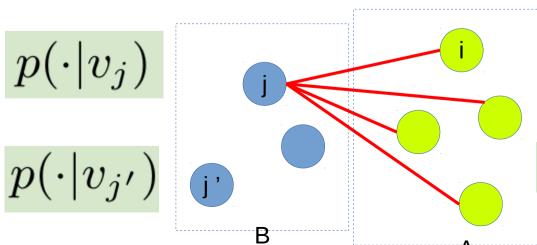
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for each pair of vertices $v_j, v_{j'}$, the second-order proximity can actually be determined by their conditional distributions $p(\cdot|v_j), p(\cdot|v_{j'}).$

How to Embed? Cost Function

$$O = -\sum_{(i,j)\in E} w_{ij} \log p(v_j|v_i). \tag{3}$$

SGD

- By this way, we can define the conditional probabilities and learn the embeddings by optimizing objective function(3)
 - word-word network
 - word-document network
 - work-label network

$$O_{ww} = -\sum_{(i,j)\in E_{ww}} w_{ij} \log p(v_i|v_j)$$

$$O_{wd} = -\sum_{(i,j)\in E_{wd}} w_{ij} \log p(v_i|d_j)$$

$$O_{wl} = -\sum_{(i,j)\in E_{wl}} w_{ij} \log p(v_i|l_j)$$

$$p(v_i|v_j)$$

$$\rightarrow p(v_i|d_j)$$

$$ightharpoonup p(v_i|l_j)$$

Heterogeneous Text Network Embedding

objective function:

$$O_{pte} = O_{ww} + O_{wd} + O_{wl}, \tag{4}$$

Heterogeneous Text Network Embedding

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One solution is to train the model with the unlabeled data (the word-word and word-document networks) and the labeled data simultaneously.

We call this approach *joint training*.

Joint training

Algorithm 1: Joint training.

Data: G_{ww}, G_{wd}, G_{wl} , number of samples T, number of

negative samples K.

Result: word embeddings \vec{w} .

while $iter \leq T$ do

- sample an edge from E_{ww} and draw K negative edges, and update the word embeddings;
- sample an edge from E_{wd} and draw K negative edges, and update the word and document embeddings;
- sample an edge from E_{wl} and draw K negative edges, and update the word and label embeddings;

end

Heterogeneous Text Network Embedding

objective function:

$$O_{pte} = O_{ww} + O_{wd} + O_{wl}, \tag{4}$$

An alternative solution

is to learn the embeddings with unlabeled data first, and then fine-tune the embeddings with the word-label network.

This is inspired by the idea of pre-training and fine-tuning

Pre-training + Fine-tuning

Algorithm 2: Pre-training + Fine-tuning.

Data: G_{ww}, G_{wd}, G_{wl} , number of samples T, number of

negative samples K.

Result: word embeddings \vec{w} .

while $iter \leq T$ do

- sample an edge from E_{ww} and draw K negative edges, and update the word embeddings;
- sample an edge from E_{wd} and draw K negative edges, and update the word and document embeddings;

end while $iter \leq T$ do

• sample an edge from E_{wl} and draw K negative edges, and update the word and label embeddings;

end

Text Embedding

Once the word vectors are learned, the representation of an arbitrary piece of text can be obtained by simply averaging the vectors of the words in that piece of text.

That is, the vector representation of a piece of text $d = w_1 w_2 \cdots, w_n$ can be computed as

$$\vec{d} = \frac{1}{n} \sum_{i=1}^{n} \vec{u}_i, \tag{8}$$

Revisiting Semi-Supervised Learning with Graph Embeddings 基于图嵌入的半监督学习 ICML 2016

Zhilin Yang William W. Cohen Ruslan Salakhutdinov

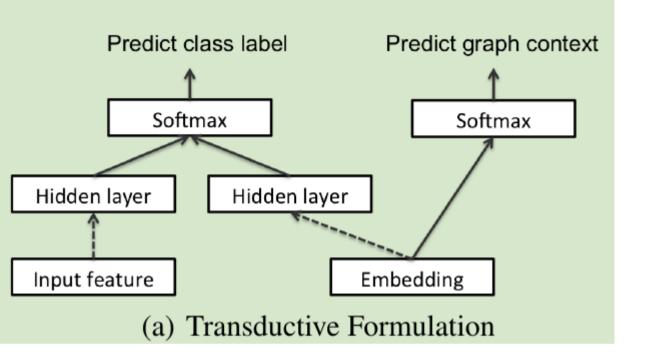
School of Computer Science, Carnegie Mellon University

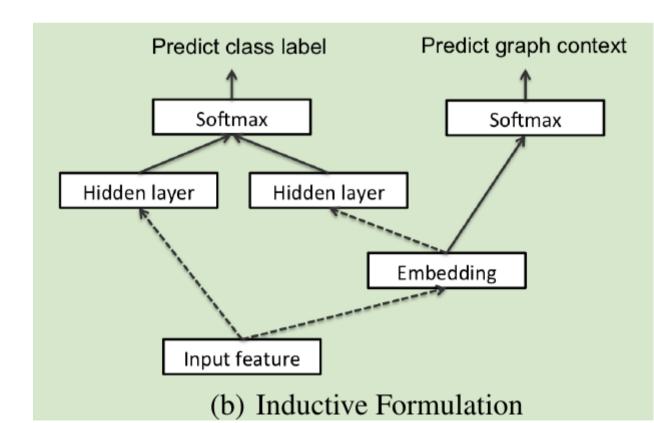
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Main Work

The main highlight of our work is to incorporate embedding techniques into the graph-based semi-supervised learning setting.

There are two learning paradigms, transductive learning and inductive learning.





Semi-Supervised Learning with Graph Embeddings

We formulate our framework based on feed-forward neural networks.

Given the input feature vector \mathbf{x} , the k-th hidden layer of the network is denoted as \mathbf{h}^k , which is a nonlinear function of the previous hidden layer \mathbf{h}^{k-1} defined as: $\mathbf{h}^k(\mathbf{x}) = \text{ReLU}(\mathbf{W}^k\mathbf{h}^{k-1}(\mathbf{x}) + b^k)$, where \mathbf{W}^k and b^k are parameters of the k-th layer, and $\mathbf{h}^0(\mathbf{x}) = \mathbf{x}$. We adopt rectified linear unit $\text{ReLU}(x) = \max(0, x)$ as the nonlinear function in this work.

Cost Function

The loss function of our framework can be expressed as

$$\mathcal{L}_s + \lambda \mathcal{L}_u$$

where \mathcal{L}_s is a supervised loss of predicting the labels, and \mathcal{L}_u is an unsupervised loss of predicting the graph context.

Unsupervised Loss

the unsuper-

vised loss with negative sampling can be written as

$$\mathcal{L}_u = -\mathbb{E}_{(i,c,\gamma)} \log \sigma(\gamma \mathbf{w}_c^T \mathbf{e}_i)$$
 (3)

Label Loss

$$p(y|\mathbf{x}, \mathbf{e}) = \frac{\exp[\mathbf{h}^k(\mathbf{x})^T, \mathbf{h}^l(\mathbf{e})^T] \mathbf{w}_y}{\sum_{y'} \exp[\mathbf{h}^k(\mathbf{x})^T, \mathbf{h}^l(\mathbf{e})^T] \mathbf{w}_{y'}}, \quad (4)$$

 $[\cdot,\cdot]$ denotes concatenation of two row vectors and \mathbf{w} represents the model parameter.

Cost Function

Combined with Eq. (3), the loss function of transductive learning is defined as:

$$-\frac{1}{L} \sum_{i=1}^{L} \log p(y_i | \mathbf{x}_i, \mathbf{e}_i) - \lambda \mathbb{E}_{(i,c,\gamma)} \log \sigma(\gamma \mathbf{w}_c^T \mathbf{e}_i),$$

Model Training

Algorithm 2 Model Training (Transductive)

Input: A, $\mathbf{x}_{1:L+U}$, $y_{1:L}$, λ , batch iterations T_1, T_2 and sizes N_1, N_2

repeat

for
$$t \leftarrow 1$$
 to T_1 do

on label

ightharpoonup Sample a batch of labeled instances i of size N_1

Supervised Training
$$\mathcal{L}_s = -\frac{1}{N_1} \sum_i p(y_i | \mathbf{x}_i, \mathbf{e}_i)$$

Take a gradient step for \mathcal{L}_s

end for

SGD with mini-batch mode

for $t \leftarrow 1$ to T_2 do

Sample a batch of context from $p(i, c, \gamma)$ of size N_2

Unsupervised Training
$$\mathcal{L}_u = -\frac{1}{N_2} \sum_{(i,c,\gamma)} \log \sigma(\gamma \mathbf{w}_c^T \mathbf{e}_i)$$

 \blacksquare Take a gradient step for \mathcal{L}_u

end for

until stopping

TransNet: Translation-Based Network Representation Learning for Social Relation Extraction 用于社交关系提取的基于转移的网络表示学习 AAAI

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What Does "Translation" Mean?

"Translation"

here means the movement that changes the position of a vector in representation space.

Translation Mechanism

Specifically, for each edge e=(u,v) and its corresponding label set l, the representation of vertex v is expected to be close to the representation of vertex u plus the representation of edge e.

the translation mechanism among u, v and e can be formalized as

$$\mathbf{u} + \mathbf{l} \approx \mathbf{v}'. \tag{1}$$
 head vertex

Translation Mechanism Cost

Specifically, for each edge e=(u,v) and its corresponding label set l, the representation of vertex v is expected to be close to the representation of vertex u plus the representation of edge e.

We employ a distance function $d(\mathbf{u} + \mathbf{l}, \mathbf{v}')$ to estimate the degree of (u, v, l) that matches the Eq. (1). In practice, we simply adopt L_1 -norm.

With the above definitions, for each (u, v, l) and its negative sample $(\hat{u}, \hat{v}, \hat{l})$, the translation part of TransNet aims to minimize the hinge-loss as follows:

$$\mathcal{L}_{trans} = \max(\gamma + d(\mathbf{u} + \mathbf{l}, \mathbf{v}') - d(\hat{\mathbf{u}} + \hat{\mathbf{l}}, \hat{\mathbf{v}}'), 0), \quad (2)$$

where $\gamma > 0$ is a margin hyper-parameter

What Is Social Relation Extraction?

Formally, we define the problem of SRE as follows. Suppose there is a social network G = (V, E), where V is the set of vertices, and $E \subseteq (V \times V)$ are edges between vertices. Besides, the edges in E are partially labeled, denoted as E_L .

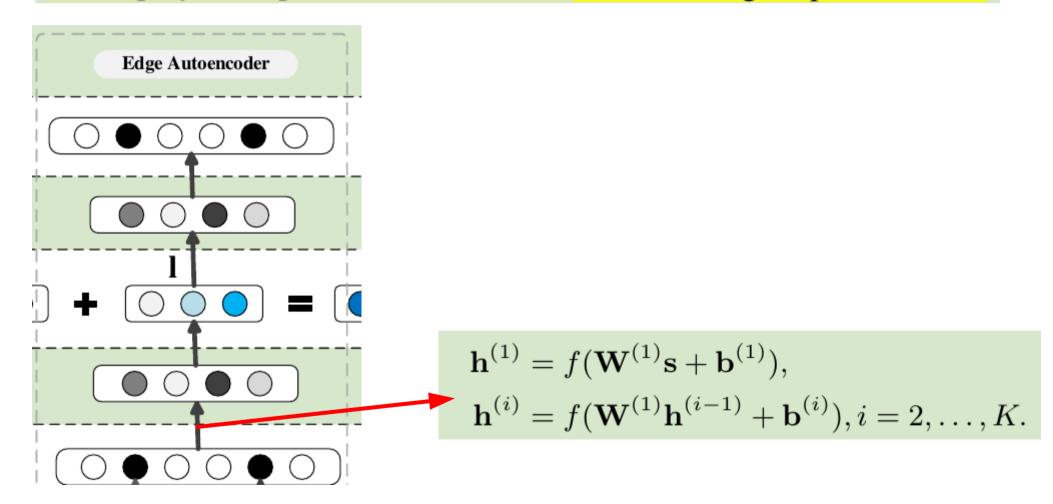
Finally, given the overall network structure and the labeled edges in E_L , SRE aims to predict the labels over unlabeled edges in E_U , where $E_U = E - E_L$ represents the unlabeled

Main Work

In this work, we focus on the problem of incorporating rich relation information on edges into NRL.

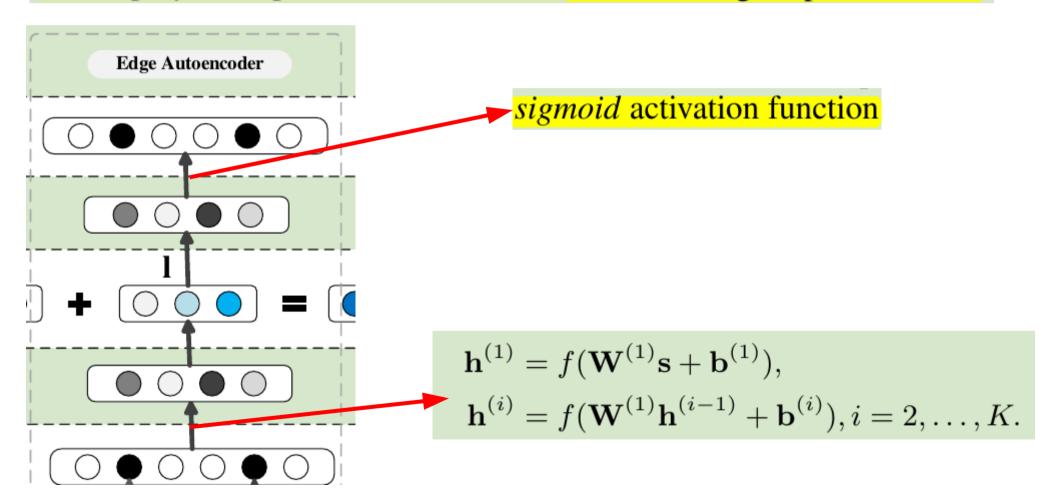
Edge Representation Construction

we employ a deep autoencoder to con-struct the edge representations.

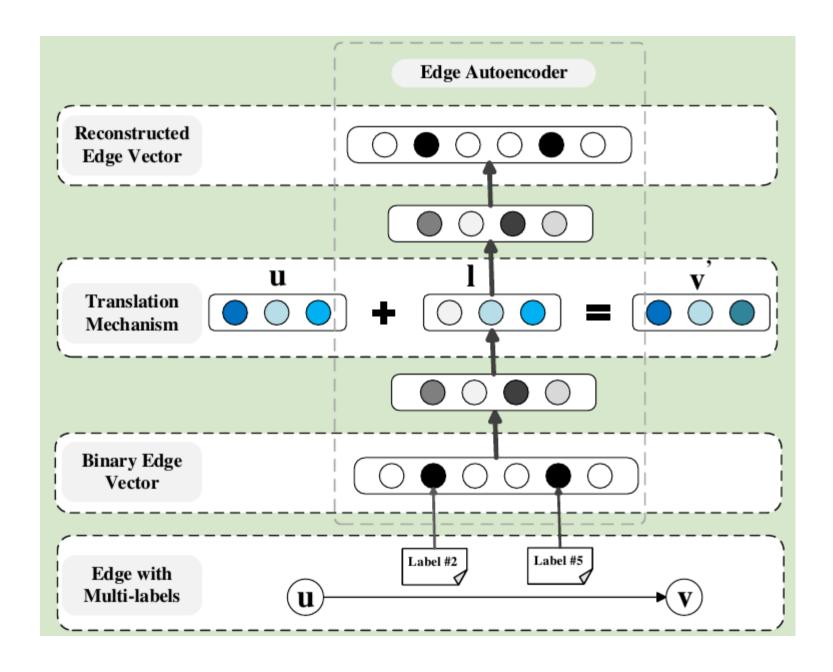


Edge Representation Construction

we employ a deep autoencoder to con-struct the edge representations.



Translation Mechanism & Edge Representation



Reconstruction Loss

Reconstruction Loss: Autoencoder aims to minimize the distance between inputs and the reconstructed outputs. The reconstruction loss is shown as:

$$\mathcal{L}_{rec} = ||\mathbf{s} - \hat{\mathbf{s}}||. \tag{5}$$

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However, due to the sparsity of the input vector, the number of zero elements in s is much larger than that of non-zero elements.

Reconstruction Loss

$$\mathcal{L}_{rec} = ||\mathbf{s} - \hat{\mathbf{s}}||. \tag{5}$$

However, due to the sparsity of the input vector, the number of zero elements in s is much larger than that of non-zero elements.

$$\mathcal{L}_{ae} = ||(\mathbf{s} - \hat{\mathbf{s}}) \odot \mathbf{x}||, \tag{6}$$

where \mathbf{x} is a weight vector and \odot means the Hadamard product. For $\mathbf{x} = {\{\mathbf{x}_i\}}_{i=1}^{|T|}$, $\mathbf{x}_i = 1$ when $\mathbf{s}_i = 0$ and $\mathbf{x}_i = \beta > 1$ otherwise.

Overall Cost

$$\mathcal{L} = \mathcal{L}_{trans} + \alpha [\mathcal{L}_{ae}(l) + \mathcal{L}_{ae}(\hat{l})] + \eta \mathcal{L}_{reg}. \tag{7}$$

Here, we introduce two hyper-parameters α and η to balance the weights of different parts. Besides, \mathcal{L}_{reg} is an L2-norm regularizer to prevent overfitting, which is defined as

$$\mathcal{L}_{reg} = \sum_{i=1}^{K} (||W^{(i)}||_2^2 + ||b^{(i)}||_2^2). \tag{8}$$

One More Thing

Thanks for Listening

Preferences

- [1]First-order Proximity
 - https://blog.csdn.net/github_36326955/article/details/72528656
- [2]KL-divergence
 - https://baike.baidu.com/item/%E7%9B%B8%E5% AF%B9%E7%86%B5/4233536?fr=aladdin
- [3] 《 PTE: Predictive Text Embedding through Large-scale Heterogeneous Text Networks 》