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KMLtoGarminFPL / README.md

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History

1 contributor

217 lines (158 sloc) | 9.75 KB

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KMLtoGarminFPL

This repository contains a Python program to convert a flight plan defined as a KML file to the Garmin FPL flight plan (FPL) format. The Garmin FPL flight plan format is used in Garmin GNS 400w/500w model series used in some aircraft.

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Software Required

1. Python 3
2. Garmin FlightPlan Migrator with USB Drivers software version 3.10: https://www8.garmin.com/support/download_details.jsp?id=4471

Hardware Required

1. Computer with a windows operating system
2. Garmin FlightPlan Migrator Kit: <https://www.garmin.com/en-US/p/35228/pn/010-11308-20>

A note about the Garmin FlightPlan Migrator Hardware and Software

To transfer FPL files to a Garmin GNS unit via card, you need the special Garmin card reader/writer and the FlightPlan Migrator software. The card and reader seem to be proprietary. Even after installing the drivers, the card reader with the card inserted do not appear as external drives from Windows (unlike a typical USB drive, for example). The Garmin FlightPlan Migrator software lets you load FPL files on the card into one of 19 spaces.

As of September 2022, Garmin card reader/writers are available from Amazon for about \$70 https://www.amazon.com/dp/B01JTFZPFG?psc=1&ref=ppx_yo2ov_dt_b_product_details and the cards can be purchased from Garmin for \$375: <https://www.garmin.com/en-US/p/35229>

Instructions

1. Create a new flight plan and save it as a KML file. For example, 'new_flight_plan.kml'
2. Decide on a prefix to name the waypoints of the new flight plan. For example, if you choose the prefix "A", the waypoints will be named: A01, A02, ..., A99.
3. Use python to run the KMLtoGarminFPL.py program like this: "python ./KMLtoGarminFPL.py -i new_flight_plan.kml -n A"
4. The program will generate two files: "new_flight_plan_as_waypoints_A.kml" and "new_flight_plan_as_waypoints_A.fpl". The "new_flight_plan_as_waypoints_A.kml" file contains the new flight plan waypoints in a KML file. The "new_flight_plan_as_waypoints_A.fpl" file contains the new flight plan waypoints and the flight route in the Garmin FPL format.
5. Load the "new_flight_plan_as_waypoints_A.fpl" file onto a Garmin card using the Garmin FlightPlan Migrator software and the Garmin FlightPlan Migrator Kit's special card reader.
6. From the cockpit, remove the original card from the slot on the right side of the Garmin GNS unit.
7. Insert the card with the new FPL file into the slot on the right side of the Garmin GNS unit.
8. Power on the Garmin GNS unit.
9. Using the Garmin menu system, load the waypoints and flight plan.
10. **IMPORTANT** Turn off the Garmin GNS unit, remove the card with the FPL file, replace it with the original card, and then turn the Garmin GNS unit on
11. Confirm that the new waypoints and flight plan are loaded.

Flight Plan KML files

During our project we defined flight plans as multi-part line shapefiles in QGIS and exported them as KML files. The resulting KML files defined the flight plan by a set of "longitude, latitude" locations, each defining the start/end point of each line segment. Specifically, the KML files have blocks like this:

```
<MultiGeometry><LineString><coordinates>-148.409488684457,70.1879369846318
-150.185878001433,71.3641064917923 -151.868207666983,71.6826939896295
-151.786142805248,71.7138328639197 -150.110904212891,71.395591937114
-150.025993171817,71.4296743112763 -151.700658574275,71.7449206097164
-151.610999271859,71.7760539944028 -149.93793727737,71.4646961861542
-149.843591676177,71.4996543291621 -151.526088230785,71.8074996278754
-151.438032336339,71.8388928343137 -149.75553578173,71.535544895473
-149.67376959403,71.5713682569899 -151.356266148638,71.869255081541
-151.258775694072,71.9034760808731 -149.585713699583,71.6051398244629
-149.503947511882,71.6368702451494 -151.164430092879,71.9376346478209
-151.082663905178,71.9697842051396 -149.415891617436,71.6725038002111
-149.340415136481,71.7021474148267 -150.997752864105,71.9999349054457
-150.903407262912,72.0310070735427 -149.258648948781,71.730758889851
-149.183172467826,71.7612957842083 -150.824785928584,72.0600901208561
-150.752454301003,72.0891276428685 -149.104551133499,71.7917833693959
-148.409538538044,70.1842836276263</coordinates></LineString></MultiGeometry>
```

Note that each "longitude, latitude" pair is separated by a space and that the entire flight plan is defined in a single block. The KMLtoGarminFPL.py Python code parses these coordinate pairs and simply rewrites them into a format that the the Garmin FlightPlan Migrator can understand.

Note: your input KML file has to have the same general format as the example code block above for the Python program to work. If your input KML file looks different, modify the Python code so that it parses your KML or reformat your KML.

Example

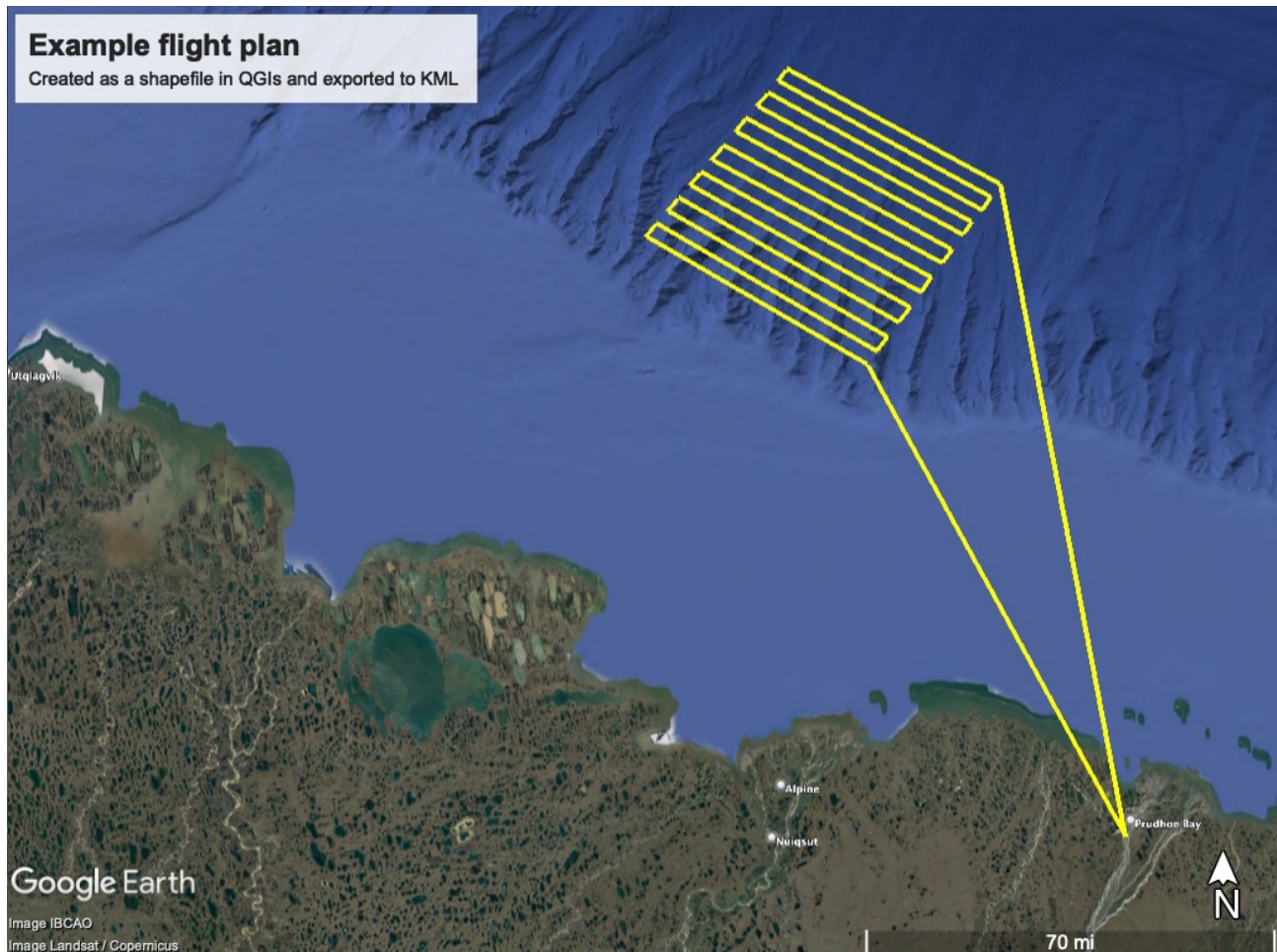
We include two example INPUT kml files and their corresponding OUTPUT fpl files. Input files:

1. Example_flight_plan_lines_Day_01.kml
2. Example_flight_plan_lines_Day_02.kml

Day 01 Example

The Day 01 Example input KML file is located in `./examples/Example_flight_plan_lines_Day_01.kml`

If you load this KML file into Google Earth or another software then you'll see the flight plan is a set of connected lines, starting and ending from Deadhorse Airport (PASC) in Prudhoe Bay, Alaska.



Now run the program, point to the Day 01 example flight plan KML file, and choose "A" as our waypoint prefix:

```
python ./KMLtoGarminFPL.py -i ./examples/Example_flight_plan_lines_Day_01.kml -n A
```

The output is as follows:

=====

Welcome to the KML to Garmin FPL tool

```
-----  
| Severine Fournier (NASA/JPL) |  
| Tom Hutchinson (Kenn Borek Air) |  
| Ian Fenty (NASA/JPL) |  
-----
```

Input KML filename is ./examples/Example_flight_plan_lines_Day_01.kml
Waypoint prefix is A

Output files will be
kml waypoints: ./examples/Example_flight_plan_lines_Day_01_as_waypoints_A.kml
fpl waypoints and route: ./examples
/Example_flight_plan_lines_Day_01_as_waypoints_and_route_A.fpl

opening ./examples/Example_flight_plan_lines_Day_01.kml

Coordinates read from the input kml file

#	lon	lat
1	-148.409	70.188
2	-150.186	71.364
3	-151.868	71.683
4	-151.786	71.714
5	-150.111	71.396
6	-150.026	71.430
7	-151.701	71.745
8	-151.611	71.776
9	-149.938	71.465
10	-149.844	71.500
11	-151.526	71.808
12	-151.438	71.839
13	-149.756	71.536
14	-149.674	71.571
15	-151.356	71.869
16	-151.259	71.903
17	-149.586	71.605
18	-149.504	71.637
19	-151.164	71.938
20	-151.083	71.970
21	-149.416	71.673
22	-149.340	71.702
23	-150.998	72.000
24	-150.903	72.031
25	-149.259	71.731
26	-149.183	71.761
27	-150.825	72.060
28	-150.752	72.089
29	-149.105	71.792
30	-148.410	70.184

Write KML file: ./examples/Example_flight_plan_lines_Day_01_as_waypoints_A.kml

Write FPL file: ./examples/Example_flight_plan_lines_Day_01_as_waypoints_and_route_A.fpl

GOOD LUCK!

=====

You should be able to load the new FPL file in `./examples`

`/Example_flight_plan_lines_Day_01_as_waypoints_and_route_A.fpl` into the Garmin FlightMigrator program and save it on the Garmin card.

The new KML file `./examples/Example_flight_plan_lines_Day_01_as_waypoints_A.kml` only includes the waypoints of the flight plan, with each waypoint named A01, A02, ... A99.



If you load the original KML flight LINES and the new KML flight WAYPOINTS you'll see the following:



Day 02 Example

We include a second example day (input flight line KML and output waypoint KML and output FPL file) for your reference. The code to run it is:

```
python ./KMLtoGarminFPL.py -i ./examples/Example_flight_plan_lines_Day_02.kml -n B
```

The output is:

```
KMLtoGarminFPL.py -i <input_kml_file> -o <output_file_noformat> -n <waypoint_prefix>
```

```
=====
```

```
Welcome to the KML to Garmin FPL tool
```

```
-----
| Severine Fournier (NASA/JPL) |
| Tom Hutchinson (Kenn Borek Air) |
| Ian Fenty (NASA/JPL) |
-----
```

```
Input KML filename is ./examples/Example_flight_plan_lines_Day_02.kml
```

```
Waypoint prefix is B
```

```
Output files will be
```

```
  kml waypoints: ./examples/Example_flight_plan_lines_Day_02_as_waypoints_B.kml
```

```
  fpl waypoints and route: ./examples
```

```
/Example_flight_plan_lines_Day_02_as_waypoints_and_route_B.fpl
```

```
opening ./examples/Example_flight_plan_lines_Day_02.kml
```

```
Coordinates read from the input kml file
```

#	lon	lat
1	-148.405	70.190
2	-149.963	71.322
3	-149.969	72.999
4	-150.476	72.997
5	-150.455	71.317
6	-150.959	71.325
7	-150.975	73.007
8	-151.484	72.997
9	-151.483	71.317
10	-152.004	71.318
11	-151.984	73.005
12	-152.488	73.002
13	-152.462	71.312
14	-152.978	71.283
15	-152.976	72.998
16	-153.463	72.992
17	-153.490	71.200
18	-154.175	71.190
19	-154.163	73.000
20	-154.966	72.998
21	-154.971	71.205
22	-153.994	70.598
23	-153.939	70.598
24	-153.888	70.597
25	-153.394	70.591
26	-152.911	70.584
27	-152.852	70.583
28	-152.805	70.582
29	-148.405	70.190

```
Write KML file: ./examples/Example_flight_plan_lines_Day_02_as_waypoints_B.kml
```

```
Write FPL file: ./examples/Example_flight_plan_lines_Day_02_as_waypoints_and_route_B.fpl
```

Good luck out there!!