Introduction to hash tables

Various data structures for mapping storage

A mapping relation is commonly used in dictionaries and databases, to store this relation, popular data structures include:

• Tree (Balanced trees, like AVL, Red Black, etc.)

Complexity	Average	Worst
Space	O(n)	O(n)
Search	$O(\log n)$	O(logn)
Insert	$O(\log n)$	$O(\log n)$
Delete	$O(\log n)$	$O(\log n)$

• Skip-list

Complexity	Average	Worst
Space	O(n)	$O(n \ log \ n)$
Search	$O(\log n)$	O(n)
Insert	$O(\log n)$	O(n)
Delete	$O(\log n)$	O(n)

Hash table

Complexity	Average	Worst
Space	O(n)	O(n)
Search	O(1)	O(n)
Insert	O(1)	O(n)
Delete	O(1)	O(n)

Note: depending on the specific data we would like to hash, the time complexity of hashing itself alone will change, but typically we assume that it is constant time.

What is a hash table?

Hash tables have two core components:

- 1. A hash function $h: u \to \{0, \dots, n-1\}$, which maps all elements in the value domain (universe) u to a *hash value* in image domain $\{0, \dots, n-1\}$.
- 2. A set of n hash buckets, with unique indexes in image domain $\{0, \ldots, n-1\}$.

We may define the methods needed by a hash table to clarify its functions:

```
class HashTable:
def init__(self):
     # Pick a random hash function h
 def insert(self, key, value):
    id = h(key)
     # insert a tuple (key, value) in bucket #id
 def find(self, key):
     id = h(key)
     # find tuple with key=key in bucket #id
     return tuple
 def remove(self, key):
     id = h(key)
     # remove tuple (key, value) from bucket #id
 def update(self, key, value):
     self.remove(key)
     self.insert(key, value)
```

In this definition, we assume that every hash bucket can store multiple key/value entries, note that in a implementation using "probing", this assumption is not necessarily true.

Properties needed by a hash function

In order to have a hash table implementation with average insert / find / remove time complexity equal to O(n), the chosen hash function should have some special properties and guarantees, otherwise it may put all elements in the same bucket, which reduces the hash table to a typical linked list.

For most cases, hash function h needs to have the following properties, we will see reasons behind these choices in sub-sections.

- Should be sufficiently random.
- Should be fast to compute.
- Should have concise description.

Formal definitions

Running time: Suppose the hash table contains keys x_1, \ldots, x_m , we insert a key y, running time is the relative run time against $Size(bucket_{h(y)})$.

Hash function: Hash function is a function which maps the key domain u to hashed image domain from 0 to n-1: $h:u\to\{0,\ldots,n-1\}$.

Random hash function: A random hash function h satisfies: $h \in_u \mathcal{H}$ (h is uniformly chosen from a family \mathcal{H} , probably with some random parameters).

Perfect hash function: A perfect hash function h maps every element x in the input set $s \subseteq u$ to hash domain with no collision, i.e. $\forall x_i, x_j \in s, h(x_i) \neq h(x_j)$.

Symbols: Let u denote the original domain, m denote the hash domain, |u| and |m| denote the size of these two domains, n = |m| be the size of hash domain and number of hash buckets.

Deterministic

If h is deterministic can it be a perfect hash function?

1. If |u| > n

If we hash all elements in u, and put them to buckets, then one bucket will contain $\lceil \frac{|u|}{n} \rceil$ elements, then an adversary can pick all elements belonging to this bucket, then for a set s made up of these elements, h is no longer perfect.

2. if $|u| \leq n$

Then it is possible, because all elements in the universe can be mapped to a unique bucket. (Possible use case: counting sort / Storing json, html files used in browsers with almost fixed static keys, sub-graph storage in graph traversing is also a possible use case.)

A perfect hash function satisfying |s| = n is called a minimal perfect hash function.

And typically perfect hash functions are deterministic, although there exists dynamic perfect hashing methods, they are typically very complex, a usual substitute for these dynamic perfect hashing functions is "cuckoo hashing"

Random oracle model

A ROM hash function satisfies:

- 1. $h_R(x)$ is a random hash function.
- 2. $h_R(x)$ returns a random number for each $x \in u$.
- 3. All hashed values $h(x_0)$ and $h(x_1)$ are mutually **independent**, i.e. subject to i.i.d..

Explanations:

• Why randomly choose the function?

Because we need to evaluate the performance of family \mathcal{H} by evaluating their $\mathbb{E}(run\ time)$. And for some security reasons, because we do not want adversaries be able to infer the original value from the hashed value.

• Randomness of $h \Rightarrow i.i.d.$

The randomly chosen h (through parameter R) does not guarantee i.i.d..

Suppose the mapped domain is {0, 1}, and there is $\forall R \ \forall x \in u, h_R(x) = 0$, then:

$$P\{h(x_0) = 0\} \neq P\{h(x_0) = 0 \mid h(x_1) = 1\} * P\{h(x_1) = 1\}$$

Because the right side (RHS) of the equation is always 0 but left is always 1.

Universal hash functions

A universal hash function, usually prefixed by k, reading "k-universal hash functions", satisfies:

1. $h_R(x)$ is a random hash function.

2.

$$orall \{x_1,\ldots,x_k\}\subseteq u, (y_1,\ldots,y_k)\in m \qquad P_{h_R\in\mathcal{H}}\{h(x_1)=y_1\wedge\ \ldots\ \wedge h(x_k)=y_k\}\leq |m|^{-k}$$

Note that all x are distinct and y are not necessarily distinct.

For 2-universal hash functions, we usually use an even weaker requirement: $P_{h_R \in \mathcal{H}}\{h(x_1) = h(x_2)\} \leq \frac{1}{|m|}$ for the sake of simplicity, this should be trivial to prove using the above definition.

Relation between above assumptions

So there are 3 levels of assumptions in random hash functions:

- 1. h is a perfect hash function (every element in its own bucket), $|u| \ll n$.
- 2. h is a ROM.
- 3. h is a 2-universal hash function.

The strongness relation is: 1 > 2 > 3.

- $1\Rightarrow 2$ is trivially understandable, so we will skip it now.
- $2 \Rightarrow 3$: suppose h is a ROM, we can prove assumption 3 by:

$$\begin{split} & P\{h(x) = h(y)\} \\ &= \sum_{k=0}^{n-1} P\{h(x) = k | h(y) = k\} \\ &= \sum_{k=0}^{n-1} P\{h(x) = k\} * P\{h(y) = k\} \\ &= 1/n \end{split}$$

2-universal hash function performance

Running time for a hash table with 2-universal hash function is constant.

Proof

Suppose hash table contains m elements: $x_1, \ldots x_m \in u$, and $m \leq n$, we search for element $y \in u$:

$$\mathbb{E}\{runtime\}$$

Note: c is a constant like O(1), used to represent other costs like hashing

$$0 \leq c * \mathbb{E}(\sum_i^m \mathbb{I}\{h(x_i) = h(y)\})$$

$$egin{aligned} ext{Note: } \mathbb{E}(\mathbb{I}\{h(x_i) = h(y)\}) &= P\{h(x_i) = h(y)\} \ &= c * \sum_i^m \mathbb{E}(\mathbb{I}\{h(x_i) = h(y)\}) \end{aligned}$$

Note:
$$P\{h(x_i) = h(y)\} \le \frac{1}{n} ext{ if } x_i \ne y$$

 $\le c * (\frac{m-1}{n} + 1)$

Note: if
$$m \le n$$

 $< 2 * c$

If m>n, rehashing happens, i.e. grow bucket size n, update hash function to accommodate new bucket size, then compute a new hash value for each element in the hash table, and finally delete the old table. Typically we will grow n exponentially, e.g.: to 2n.

Rehashing cost is O(n) in total, and average runtime cost for each element is still O(1) after dividing the total cost by element number, this can be proved by:

Suppose grow hash table from 1 to M:

- Insertion cost: From element 1 to M, constant for each so $\mathcal{O}(M)$ in total.
- Re-hashing cost: From 2, 4, 8, ..., to M: $2+4+8+\ldots M \leq 2M$, so total cost is O(M).
- Deletion cost: O(M)

After rehashing, $m \leq n$ is satisfied again, so running time will still be O(1) after that.