

Siddharth Narayanaswamy

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<http://iffsid.com>

Skills

extensive computer-vision, signals and systems, and robotics background, strong experience with machine learning, statistics, visual perception, cognitive science, knowledge representation, algorithms and compiler design, haptics, automatic-differentiation, stochastic and non-deterministic programming languages, functional, logic, and constraint programming.

Languages

Scheme, Haskell, Lisp, C/C++, MATLAB, Python, Prolog, Java, VHDL, Verilog, DSP(AD Blackfin) assembly, microcontroller assembly, x86 assembly
native English, Tamil, and Hindi

Experience

PhD student, Artificial Intelligence

Jeffrey Mark Siskind

2008 – present

Purdue University

designed and built custom robots for general manipulation tasks
solved vision and robotic manipulation problems using AD-based optimization
implemented closed-loop visual-servoing mechanism to drive motor control
developed and implemented stochastic programs to use language & vision, and reasoning about rules jointly, to solve for perception
developed novel and robust tracking, segmentation, and action recognition methods as part of the DARPA Mind's Eye program
nondeterministic programming for solving constraint-satisfaction problems
stochastic modeling via probabilistic programming
TA for ECE473 & ECE570, Artificial Intelligence
<http://iffsid.com/research.html>

Undergraduate Research Project

Guided by Professor Muniyandi Manivannan

May 2007 – Aug. 2008

IIT-Madras

implemented a DIY Part-Task Laparoscopic Simulator
optimized vision algorithms to run on low-cost uncalibrated components
tested against industry-standard equipment to demonstrate reasonably low error margins
worked on a haptic-vision developmental interface
collaborated with practicing doctors to test feasibility

Part-Time Instructor

The Princeton Review(Manya Education Pvt.Ltd.)

Oct. 2007 – Aug. 2008

Chennai, India

for the GRE and GMAT standardized exams
tutored around 250 students

Undergraduate Research Intern

Doors and Gates Pvt.Ltd.

May 2007 – Sept. 2007

Chennai, India

implemented a range of IR control mechanisms for controller operations
tested and used implemented mechanisms successfully in robots during competitions
designed hybrid control mechanism for non-line-of-sight applications
that included switching between multiple modes of operation autonomously

Education

Phd Student, Artificial Intelligence

Artificial Intelligence, Computer Vision, Natural Language Processing
Machine Learning, Robotics

2008 – present

Purdue University

Bachelor of Engineering - Electronics and Communication

Image Processing, Speech Processing, Computer Vision
Communication Systems, Embedded Systems (Robotics)

2004 – 2008

Anna University, India

Publications / Posters

Recognizing Human Activities from Partially Observed Videos

Y. Cao, D. Barrett, A. Barbu, N. Siddharth, H. Yu, A. Michaux, Y. Lin, S. Dickinson, J. Siskind, S. Wang

IEEE Conference on Computer Vision and Pattern Recognition (CVPR)

Jun 2013

Poster

Seeing Unseeability to See the Unseeable

N. Siddharth, A. Barbu, and J. M. Siskind
Advances in Cognitive Systems(ACS)

Oct 2012

Paper/Journal

Simultaneous Object Detection, Tracking, and Event Recognition

A. Barbu, N. Siddharth, A. Michaux, and J. M. Siskind
Advances in Cognitive Systems(ACS)

Oct 2012

Paper/Journal

Video In Sentences Out

A. Barbu, A. Bridge, Z. Burchill, D. Coroian and S. Dickinson , S. Fidler, A. Michaux, S. Mussman and N. Siddharth , D. Salvi, L. Schmidt, J. Shangguan and J. M. Siskind, J. Waggoner, S. Wang, J. Wei and Y. Yin and Z. Zhang
Proceedings of the Twenty-Eighth Conf. on Uncertainty in Artificial Intelligence(UAI)

Aug 2012

Paper/Conference

A Visual Language Model for Estimating Object Pose and Structure in a Generative Visual Domain

N Siddharth, A. Barbu, and J. M. Siskind
Proceedings of 2011 IEEE International Conf. on Robotics and Automation(ICRA)

May 2011

Paper/Conference

Learning Physically-Instantiated Game Play Through Visual Observation

A. Barbu, N Siddharth, and J. M. Siskind
Proceedings of 2010 IEEE International Conf. on Robotics and Automation(ICRA)

May 2010

Paper/Conference

Design of a Do-It-Yourself VR Based Laparoscopic Simulator

N.Siddharth, M.Manivannan, Suresh Devasahayam, and George Mathew
Medicine Meets Virtual Reality (MMVR17)

Jan. 2009

Poster