

Introduction to Formal Methods

Lecture 12 Symbolic and Concolic Execution Hossein Hojjat & Fatemeh Ghassemi

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Testing

- In practice, most common form of bug-detection
- Each test explores only one possible execution of the system

$$assert(f(2) == 7);$$

- We hope test cases generalize, but no guarantees
- Symbolic execution generalizes testing
- Allows unknown symbolic variables in evaluation

$$x = \alpha$$
; assert(f(x) == $3*x + 1$);

1

Symbolic Execution

- Originally proposed by James King (among others)
 "Symbolic execution and program testing",
 Communications of the ACM, 1976.
- Recent advances in SMT solvers: renewed interest in symbolic execution!
- Companies like Microsoft use tools based on symbolic execution to find serious errors and security vulnerabilities
- Some tools based on symbolic execution: Symbolic PathFinder (SPF), KLEE, DART, CUTE, CREST, S2E, ...

```
void f (x, y) {
  if (x > y) {
    x = x + y;
    y = x - y;
    x = x - y;
  if (x - y > 0)
    assert false
}
```

• Execute the program on symbolic values

```
void f (x, y) {
   if (x > y) {
      x = x + y;
      y = x - y;
      x = x - y;
   if (x - y > 0)
      assert false
   }
}
```

```
\begin{bmatrix}
x = \alpha \\
y = \beta
\end{bmatrix}
```

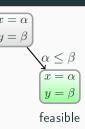
- Execute the program on symbolic values
- Symbolic state maps variables to symbolic values

```
void f (x, y) {
   if (x > y) {
      x = x + y;
      y = x - y;
      x = x - y;
   if (x - y > 0)
      assert false
   }
}
```

- Execute the program on symbolic values
- Symbolic state maps variables to symbolic values
- Path condition is a quantifier-free formula over the symbolic inputs that encodes all branch decisions taken so far

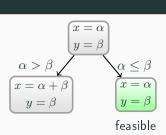
```
void f (x, y) {
   if (x > y) {
      x = x + y;
      y = x - y;
      x = x - y;
   if (x - y > 0)
      assert false
   }
}
```

- Execute the program on symbolic values
- Symbolic state maps variables to symbolic values
- Path condition is a quantifier-free formula over the symbolic inputs that encodes all branch decisions taken so far
- All paths in the program form its execution tree, in which some paths are feasible and some are infeasible



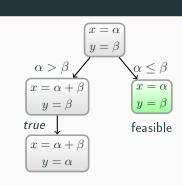
```
void f (x, y) {
   if (x > y) {
      x = x + y;
      y = x - y;
      x = x - y;
   if (x - y > 0)
      assert false
   }
}
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- Execute the program on symbolic values
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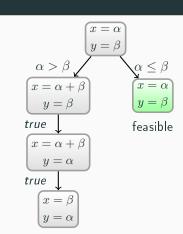
```
void f (x, y) {
   if (x > y) {
      x = x + y;
      y = x - y;
      x = x - y;
   if (x - y > 0)
      assert false
   }
}
```

- Execute the program on symbolic values
- Symbolic state maps variables to symbolic values
- Path condition is a quantifier-free formula over the symbolic inputs that encodes all branch decisions taken so far
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```
void f (x, y) {
   if (x > y) {
      x = x + y;
      y = x - y;
      x = x - y;
   if (x - y > 0)
      assert false
   }
}
```

- Execute the program on symbolic values
- Symbolic state maps variables to symbolic values
- Path condition is a quantifier-free formula over the symbolic inputs that encodes all branch decisions taken so far
- All paths in the program form its execution tree, in which some paths are feasible and some are infeasible



```
void f(x, y) {
       if (x > y) {
                                                                 y = \beta
          x = x + y;
          y = x - y;
          x = x - y;
                                                         y = \beta
          if (x - y > 0)
                                                      true
                                                                         feasible
             assert false
                                                       x = \alpha + \beta
                                                         y = \alpha
                                                      true

    Execute the program on symbolic values

                                                         x = \beta
```

 $y = \alpha$

 $\beta - \alpha > 0$

 $y = \alpha$

infeasible

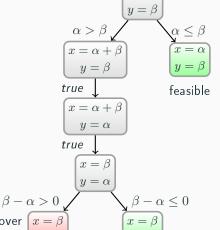
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 - Symbolic state maps variables to symbolic values
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```
void f (x, y) {
  if (x > y) {
    x = x + y;
    y = x - y;
    x = x - y;
  if (x - y > 0)
    assert false
  }
}
```

- Execute the program on symbolic values
- Symbolic state maps variables to symbolic values
- Path condition is a quantifier-free formula over the symbolic inputs that encodes all branch

decisions taken so far

 All paths in the program form its execution tree, in which some paths are feasible and some are infeasible



feasible

 $y = \alpha$

infeasible

Symbolic Representation of State

- Let the set of variables be $V = \{x_1, \dots, x_n\}$
- Program state in symbolic execution

$$\exists \alpha_1 \cdots \alpha_n . \underbrace{(x_1 = e_1) \wedge \cdots \wedge (x_n = e_n)}_{\sigma_s} \land P_C$$

(think of α_i as symbolically representing the initial value of x_i)

- ullet e_i term describing symbolic state of the variables x_i
- ullet P_C path condition
- ullet Variables x_1,\cdots,x_n do not appear in e_1,\cdots,e_n,P_C
- $\alpha_1, \cdots, \alpha_n$ fresh variables that do not appear in the program

$$sp(\exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \land \cdots \land (x_n = e_n) \land P_C, x_i := E)$$

$$sp(\exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \wedge \cdots \wedge (x_n = e_n) \wedge P_C, x_i := E)$$

$$= \exists \beta. (\exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \wedge \cdots \wedge (x_n = e_n) \wedge P_C)[x_i := \beta] \wedge (x_i = E[x_i := \beta])$$

$$\begin{split} & sp\Big(\exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \wedge \cdots \wedge (x_n = e_n) \wedge P_C, x_i := E\Big) \\ &= \exists \beta. \Big(\exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \wedge \cdots \wedge (x_n = e_n) \wedge P_C\Big) \big[x_i := \beta\big] \wedge \big(x_i = E[x_i := \beta]\big) \\ &= \exists \beta. \ \exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \wedge \cdots \wedge (\beta = e_i) \wedge \cdots \wedge (x_n = e_n) \wedge P_C \wedge (x_i = E[x_i := \beta]\big) \\ &\qquad (x_i \text{ not in } e_1, \cdots, e_n, P_C) \end{split}$$

$$\begin{split} & sp\Big(\exists \alpha_1 \cdots \alpha_n.(x_1=e_1) \wedge \cdots \wedge (x_n=e_n) \wedge P_C, x_i := E\Big) \\ &= \exists \beta. \Big(\exists \alpha_1 \cdots \alpha_n.(x_1=e_1) \wedge \cdots \wedge (x_n=e_n) \wedge P_C\Big) \big[x_i := \beta\big] \wedge (x_i = E[x_i := \beta]) \\ &= \exists \beta. \ \exists \alpha_1 \cdots \alpha_n.(x_1=e_1) \wedge \cdots \wedge (\beta=e_i) \wedge \cdots \wedge (x_n=e_n) \wedge P_C \wedge (x_i = E[x_i := \beta]) \\ &\qquad (x_i \text{ not in } e_1, \cdots, e_n, P_C) \\ &= \exists \alpha_1 \cdots \alpha_n.(x_1=e_1) \wedge \cdots \wedge (x_i = E[x_i := e_i]) \wedge \cdots \wedge (x_n=e_n) \wedge P_C \\ &\qquad (\text{one-point rule, move equation for } x_i \text{ inside}) \end{split}$$

• Strongest postcondition introduces no new existential quantifiers for this form of symbolic representation

$$\begin{split} sp\Big(\exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \wedge \cdots \wedge (x_n = e_n) \wedge P_C, x_i := E\Big) \\ &= \exists \beta. \Big(\exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \wedge \cdots \wedge (x_n = e_n) \wedge P_C\Big) [x_i := \beta] \wedge (x_i = E[x_i := \beta]) \\ &= \exists \beta. \ \exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \wedge \cdots \wedge (\beta = e_i) \wedge \cdots \wedge (x_n = e_n) \wedge P_C \wedge (x_i = E[x_i := \beta]) \\ &\qquad (x_i \text{ not in } e_1, \cdots, e_n, P_C) \\ &= \exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \wedge \cdots \wedge (x_i = E[x_i := e_i]) \wedge \cdots \wedge (x_n = e_n) \wedge P_C \\ &\qquad (\text{one-point rule, move equation for } x_i \text{ inside}) \end{split}$$

 $\exists \alpha_1 \cdots \alpha_n. (x_1 = e_1) \wedge \cdots \wedge (x_i = E[x_1, ..., x_n := e_1, ..., e_n]) \wedge \cdots \wedge (x_n = e_n) \wedge P_C$ (replace $x_1, ..., x_n$ vars in E)

 $sp(\exists \alpha_1 \cdots \alpha_n.(x_1 = e_1) \wedge \cdots \wedge (x_n = e_n) \wedge P_C, x_i := E)$

 Strongest postcondition introduces no new existential quantifiers for this form of symbolic representation

$$=\exists \beta. \Big(\exists \alpha_1 \cdots \alpha_n. (x_1 = e_1) \wedge \cdots \wedge (x_n = e_n) \wedge P_C\Big) [x_i := \beta] \wedge (x_i = E[x_i := \beta])$$

$$=\exists \beta. \ \exists \alpha_1 \cdots \alpha_n. (x_1 = e_1) \wedge \cdots \wedge (\beta = e_i) \wedge \cdots \wedge (x_n = e_n) \wedge P_C \wedge (x_i = E[x_i := \beta])$$

$$(x_i \text{ not in } e_1, \cdots, e_n, P_C)$$

$$= \ \exists \alpha_1 \cdots \alpha_n. (x_1 = e_1) \wedge \cdots \wedge (x_i = E[x_i := e_i]) \wedge \cdots \wedge (x_n = e_n) \wedge P_C$$

$$(\text{one-point rule, move equation for } x_i \text{ inside})$$

$$= \ \exists \alpha_1 \cdots \alpha_n. (x_1 = e_1) \wedge \cdots \wedge (x_i = E[x_1, ..., x_n := e_1, ..., e_n]) \wedge \cdots \wedge (x_n = e_n) \wedge P_C$$

• Calculating sp of $x_i := E$ consists of

(replace $x_1, ..., x_n$ vars in E)

- 1. Evaluate E in the current state (i.e. $E[x_1,...,x_n:=e_1,...,e_n]$)
- 2. Update the equation for x_i to the new E

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
int main() {
  x = read();
  y = read();
  test(x,y);
```

- Can you find the inputs that make the program reach the ERROR?
- Let's execute this example with classic symbolic execution

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
int main() {
  x = read();
  v = read();____
  test(x,y);
```

- read() reads a value from input
- We don't know what those read values are so we set them to fresh symbolic values α and β
- ullet P_C is true because so far we have not executed any conditionals

$$\sigma_s: x = \alpha \wedge y = \beta$$
 $P_C: \mathit{true}$

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
                              \sigma_s: x = \alpha \wedge y = \beta \wedge z = 2\beta P_C: true
     if (x > y + 10)
       ERROR;

    We simply execute the function

                                      twice() and add the new symbolic
                                     value for z
int main() {
  x = read();
  y = read();
  test(x,y);
```

```
int twice(int v) {
                                         • We fork the analysis into 2 paths:
   return 2 * v;
                                           the true and the false path
                                         • We need to duplicate the state of the
void test(int x,int y){
                                           analysis
  z = twice(y);
   if (x == z) {
                                          This is the result if x=z:
     if (x > y + 10)
                              \sigma_s: x = \alpha \land y = \beta \land z = 2\beta P_C: \alpha = 2\beta
        ERROR;
                                          This is the result if x \neq z:
                                \sigma_s: x = \alpha \land y = \beta \land z = 2\beta P_C: \alpha \neq 2\beta
int main() {
  x = read();
  v = read();
  test(x,y);
```

```
int twice(int v) {

    We can avoid further exploring a path

   return 2 * v;
                                           if we know the constraint P_C is unsat
                                         • In this example, both P_C's are sat so
void test(int x,int y){
                                           we need to keep exploring both paths
  z = twice(y);
   if (x == z) {
                                          This is the result if x=z:
     if (x > y + 10)
                               \sigma_s: x = \alpha \land y = \beta \land z = 2\beta P_C: \alpha = 2\beta
        ERROR;
                                          This is the result if x \neq z:
                                \sigma_s: x = \alpha \land y = \beta \land z = 2\beta P_C: \alpha \neq 2\beta
int main() {
  x = read();
  y = read();
  test(x,y);
```

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
int main() {
 x = read();
  v = read();
  test(x,y);
```

- Let's explore the path when
 x == z is true
- Once again we get 2 more paths

This is the result if x > y + 10: $\sigma_s : x = \alpha \land y = \beta \land z = 2\beta$ $P_C : \alpha = 2\beta \land \alpha > \beta + 10$

This is the result if $x \le y + 10$: $\sigma_s : x = \alpha \land y = \beta \land z = 2\beta$ $P_C : \alpha \ne 2\beta \land \alpha \le \beta + 10$

```
int twice(int v) {
                                      • So the following path reaches ERROR
  return 2 * v;
void test(int x,int y){
                                     This is the result if x > y + 10:
  z = twice(y);
  if (x == z) {
                                      \sigma_s: x = \alpha \wedge y = \beta \wedge z = 2\beta
     if (x > y + 10)
                                       P_C: \alpha = 2\beta \wedge \alpha > \beta + 10
        ERROR;
int main() {
  x = read();
  y = read();
  test(x,y);
```

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
  }
int main() {
 x = read();
  y = read();
  test(x,y);
```

 \bullet So the following path reaches $\ensuremath{\mathsf{ERROR}}$

This is the result if x > y + 10: $\sigma_s : x = \alpha \wedge y = \beta \wedge z = 2\beta$ $P_C : \alpha = 2\beta \wedge \alpha > \beta + 10$

- \bullet We can now ask the SMT solver for a satisfying assignment to the P_C formula
- For instance, $\alpha=40$, $\beta=20$ is a satisfying assignment.
- Running the program with those concrete inputs triggers the error

Handling Loops: a limitation

```
int F(unsigned int k) {
  int sum = 0;
  int i = 0;
  for (; i < k; i++)
    sum += i;
  return sum;
}</pre>
```

- A serious limitation of symbolic execution is unbounded loops
- Symbolic execution runs the program for a finite number of paths
- What if we do not know the bound on a loop?

Loops and Recursion

Dealing with infinite execution trees:

- Finitize paths by limiting the size of P_C (bounded verification)
- Use loop invariants (verification)

```
while (b) {
  c
}
assert(P)
```

```
assert(I)
havoc(x1,...,xn)
assume(I)
if (b) {
   c
   assert(I)
} else
   assert(P)
```

where $x1, \cdots, xn$ are variables modified in c and I is the loop invariant

When Constraint Solving Fails

- Despite best efforts, the program may be using constraints in a fragment which the SMT solver does not handle well
- For instance, suppose the SMT solver does not handle non-linear constraints well
 - Decision problem for non-linear integer arithmetic is undecidable
 - We can encode the Halting problem for Turing machines in non-linear integer arithmetic
- Let us consider a modification of our running example

Modified Example

```
int twice(int v) {
                             • Here, we changed the twice ()
  return v * v;
                               function to contain a non-linear result.

    Let's see what happens when we

void test(int x,int y){
                               symbolically execute the program now
  z = twice(y);
  if (x == z) {
     if (x > y + 10)
       ERROR;
int main() {
  x = read();
  y = read();
  test(x,y);
```

Modified Example

```
int twice(int v) {
  return v * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
int main() {
 x = read();
  y = read();
  test(x,y);
```

This is the result if x=z: $\sigma_s: x=\alpha \wedge y=\beta \wedge z=\beta \times \beta$ $P_C: \alpha=\beta \times \beta$

- ullet Now, if we are to invoke the SMT solver with the P_C formula, it would be unable to compute satisfying assignments
- We cannot know whether the path is feasible or not

Solution: Concolic Execution

- Concolic Execution: combines both symbolic execution and concrete (normal) execution
- The basic idea is to have the concrete execution drive the symbolic execution
- Here, the program runs as usual (it needs to be given some input),
 but in addition it also maintains the usual symbolic information

Concolic Execution: Example

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);

    read() reads a value from input

  if (x == z) {
                                     • Suppose we read x = 22 and y = 7
     if (x > y + 10)
       ERROR;
                                     • We will keep both the concrete store
                                       and the symbolic store and path
                                       constraint
int main() {
                                         \sigma: x = 22 \land y = 7
  x = read();
                                         \sigma_s: x = \alpha \wedge y = \beta
  y = read(); _
                                              P_C: true
  test(x,y);
```

Concolic Execution: Example

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
 z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
int main() {
 x = read();
  y = read();
  test(x,y);
```

```
\sigma: x=22 \wedge y=7 \wedge z=14 \sigma_s: x=\alpha \wedge y=\beta \wedge z=2\beta P_C: \mathit{true}
```

 The concrete execution will now take the else branch of x == z

Concolic Execution: Example

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
                                       • Hence, we get:
  if (x == z) {
                                       \sigma : x = 22 \land y = 7 \land z = 14
     if (x > y + 10)
                                       \sigma_s: x = \alpha \wedge y = \beta \wedge z = 2\beta
        ERROR;
                                              P_C: \alpha \neq 2\beta
int main() {
  x = read();
  y = read();
  test(x,y);
```

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
  }
int main() {
  x = read();
  y = read();
  test(x,y);
```

- At this point, concolic execution decides that it would like to explore the true branch of x == z and hence it needs to generate concrete inputs to explore it
- It negates the P_C constraint, obtaining:

$$P_C: \ \alpha = 2\beta$$

- It then calls the SMT solver to find a satisfying assignment of that constraint
- Let us suppose the SMT solver returns:

$$\alpha = 2, \beta = 1$$

• The concolic execution then runs the program with this input

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x^* > y + 10)
      ERROR;
int main() {
 x = read();
  v = read();
  test(x,y);
```

• With the input x=2, y=1 we reach this program point with the following information:

$$\sigma: x = 2 \land y = 1 \land z = 2$$

$$\sigma_s: x = \alpha \land y = \beta \land z = 2\beta$$

$$P_C: \alpha = 2\beta$$

Continuing further we get:

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR:
  }
int main() {
 x = read();
  v = read();
  test(x,y);
```

• We reach the else branch of x>y+10 $\sigma: x=2 \wedge y=1 \wedge z=2$ $\sigma_s: x=\alpha \wedge y=\beta \wedge z=2\beta$

 Again, concolic execution may want to explore the true branch of x>y+10

 $P_C: \alpha = 2\beta \wedge \alpha < \beta + 10$

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR:
  }
int main() {
 x = read();
  v = read();
  test(x,y);
```

• We reach the else branch of x>y+10 $\sigma: x=2 \wedge y=1 \wedge z=2$ $-\sigma_s: x=\alpha \wedge y=\beta \wedge z=2\beta$

$$\sigma_s: x = \alpha \land y = \beta \land z = 2\beta$$

 $P_C: \alpha = 2\beta \land \alpha < \beta + 10$

• Concolic execution now negates the conjunct $\alpha \le \beta + 10$ obtaining: $\alpha = 2\beta \land \alpha > \beta + 10$

• A satisfying assignment is: $\alpha = 30 \land \beta = 15$

```
int twice(int v) {
  return 2 * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
int main() {
 x = read();
  y = read();
  test(x,y);
```

• If we run the program with the input:

$$x = 30 \land y = 15$$

- We will now reach the ERROR state
- As we can see from this example, by keeping the symbolic information, the concrete execution can use that information in order to obtain new inputs.

Non-linear constraints

Let us return to the problem of non-linear constraints

```
int twice(int v) {
  return v * v; -
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
int main() {
 x = read();
  y = read();
  test(x,y);
```

 Let us again consider our example and see what concolic execution would do with non-linear constraints

```
int twice(int v) {
  return v * v;
                                   • read() reads a value from input
void test(int x,int y){
                                   • Suppose we read x = 22 and y = 7
  z = twice(y);
  if (x == z) {
     if (x > y + 10)
       ERROR;
                                        \sigma: x = 22 \land y = 7
                                        \sigma_s: x = \alpha \wedge y = \beta
                                            P_C: true
int main() {
  x = read();
  y = read(); *
  test(x,y);
```

```
int twice(int v) {
  return v * v;
void test(int x,int y){
                               \sigma : x = 22 \land y = 7 \land z = 49
  z = twice(y); \sigma_s: x = \alpha \land y = \beta \land z = \beta \times \beta
  if (x == z) {
                                            P_C: true
     if (x > y + 10)
                                    • The concrete execution will now take
       ERROR;
                                      the else branch of x == z
int main() {
  x = read();
  y = read();
  test(x,y);
```

```
int twice(int v) {
   return v * v;
void test(int x,int y){
  z = twice(y);
                                         • Hence, we get:
  if (x == z) {
                                         \sigma : x = 22 \land y = 7 \land z = 49
     if (x > y + 10)
                                       \sigma_s: x = \alpha \land y = \beta \land z = \beta \times \beta
        ERROR;
                                               P_C: \alpha \neq \beta \times \beta
int main() {
  x = read();
  y = read();
  test(x,y);
```

```
int twice(int v) {
  return v * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
  }
int main() {
  x = read();
  y = read();
  test(x,y);
```

- We have a non-linear constraint $\alpha = \beta \times \beta$
- If we would like to explore the true branch we negate the constraint, obtaining $\alpha = \beta \times \beta$ but again we have a non-linear constraint
- \bullet In this case, concolic execution simplifies the constraint by plugging in the concrete values for β
- $\beta=7$ so we obtain the simplified constraint: $\alpha=49$
- Hence, it now runs the program with the input

$$x = 49$$
, $y = 7$

```
int twice(int v) {
  return v * v;
void test(int x,int y){
  z = twice(y);
  if (x == z) {
    if (x > y + 10)
      ERROR;
  }
int main() {
 x = read();
  v = read();
```

test(x,y);

Running with the input

$$x = 49 , y = 7$$

• We reach the error state.

Notice that with these inputs, if we try to simplify non-linear constraints by plugging in concrete values (as concolic execution does), then concolic execution we will never reach the else branch of the if (x > y + 10) statement

Reference

Cristian Cadar, Koushik Sen, "Symbolic execution for software testing: three decades later", Communications of the ACM, Volume 56, Issue 2, February 2013, Pages 82-90.