# Application of Information Theory, Lecture 2 Joint & Conditional Entropy, Mutual Information

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# Part I

# **Joint and Conditional Entropy**

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$$= \frac{1}{2} \cdot 1 + \frac{1}{2} \cdot 2 = 1\frac{1}{2}$$

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▶ The joint entropy of  $(X_1, ..., X_n) \sim p$ , is

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$$= \frac{3}{4} H(\frac{1}{3}, \frac{2}{3}) + \frac{1}{4} H(1, 0) = 0.6887 \neq H(Y|X).$$

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# Conditional entropy, cont..

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- ► H(Y|X) = H(X, Y) H(X) is as an alternative definition for H(Y|X).

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Jensen inequality: for any concave function f, values  $t_1, \ldots, t_k$  and  $\lambda_1, \ldots, \lambda_k \in [0, 1]$  with  $\sum_i \lambda_i = 1$ , it holds that  $\sum_i \lambda_i f(t_i) \leq f(\sum_i \lambda_i t_i)$ . Let  $(X, Y) \sim p$ .

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Assume X and Y are independent (i.e.,  $p(x, y) = p_X(x) \cdot p_Y(y)$  for any x, y)

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For rvs  $X_1, \ldots, X_k$ , it holds that

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Proof: ?

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▶ (from last class) Let  $X_1, ..., X_n$  be Boolean iid with  $X_i \sim (\frac{1}{3}, \frac{2}{3})$ . Compute  $H(X_1, ..., X_n)$ 

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### **Applications**

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Interpretation

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- Interpretation
- Upper bounds

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$$\implies t \ge \log n! = \Theta(n \log n)$$

Let  $p=(p_1,\ldots,p_n)$  and  $q=(q_1,\ldots,q_n)$  be two distributions, and for  $\lambda\in[0,1]$  consider the distribution  $\tau_\lambda=\lambda p+(1-\lambda)q$ . (i.e.,  $\tau_\lambda=(\lambda p_1+(1-\lambda)q_1,\ldots,\lambda p_n+(1-\lambda)q_n)$ .

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We are now certain that we drew the graph of the (two-dimensional) entropy function right...

# Part II

# **Mutual Information**

▶ I(X; Y) — the "information" that X gives on Y

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- ► I(X; Y|Z) := H(Y|Z) H(Y|X,Z)  $\geq 0$

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- I(X; Y|Z) := H(Y|Z) H(Y|X,Z)  $\geq 0$
- ► I(X; Y|Z) = I(Y; X|Z) (since I(X'; Y') = I(Y'; X'))

X	0	1
0	$\frac{1}{4}$	$\frac{1}{4}$
1	1 2	0

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$$= H(Y) - H(Y|X)$$

$$= h(\frac{1}{4}) - \frac{1}{2}h(\frac{1}{2})$$

### Claim 4 (Chain rule for mutual information)

For rvs  $X_1, ..., X_k, Y$ , it holds that  $I(X_1, ..., X_k; Y) = I(X_1; Y) + I(X_2; Y|X_1) + ... + I(X_k; Y|X_1, ..., X_{k-1})$ .

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# Part III

# **Data processing**

# **Data processing Inequality**

## **Definition 5 (Markov Chain)**

Rvs  $(X, Y, Z) \sim p$  form a Markov chain, denoted  $X \to Y \to Z$ , if  $p(x, y, z) = p_X(x) \cdot p_{Y|X}(y|x) \cdot p_{Z|Y}(z|y)$ , for all x, y, z.

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For any rvs X and Y, and any (even random) g, it holds that

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- ▶ We call  $\hat{X}$  an estimator for X (from Y).

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