

Sorting

up:: Algorithm

tags:: #algorithm/sorting

Callbacks

Goal. Sort **any** type of data.

Q. How can `sort()` know how to compare data of type `Double`, `String`, and `java.io.File` without any information about the type of an item's key?

Callback = reference to executable code.

- Client passes array of objects to `sort()` function.
- The `sort()` function calls back object's `compareTo()` method as needed.

Implementing callbacks.

- Java: **interfaces**.
- C: **function pointers**.
- C++: **class-type functors**.
- C#: **delegates**.
- Python, Perl, ML, Javascript: **first-class functions**.

Two useful sorting abstractions

Helper functions. Refer to data through compares and exchanges.

Less. Is item v less than w ?

```
private static boolean less(Comparable v, Comparable w)
{   return v.compareTo(w) < 0; }
```

Exchange. Swap item in array a[] at index i with the one at index j.

```
private static void exch(Comparable[] a, int i, int j)
{
    Comparable swap = a[i];
    a[i] = a[j];
    a[j] = swap;
}
```

Testing

Goal. Test if an array is sorted.

```
private static boolean isSorted(Comparable[] a)
{
    for (int i = 1; i < a.length; i++)
        if (less(a[i], a[i-1])) return false;
    return true;
}
```

Q. If the sorting algorithm passes the test, did it correctly sort the array?

A.

Selection sort

Algorithm. ↑ scans from left to right.

Invariants. 不变式

- Entries to the left of ↑ (including ↑) fixed and in ascending order.
- No entry to right of ↑ is smaller than any entry to the left of ↑.



Selection sort inner loop

To maintain algorithm invariants:

- Move the pointer to the right.

i++;



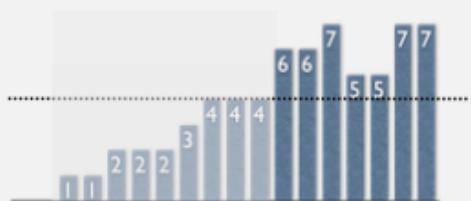
- Identify index of minimum entry on right.

```
int min = i;
for (int j = i+1; j < N; j++)
    if (less(a[j], a[min]))
        min = j;
```



- Exchange into position.

exch(a, i, min);



Selection sort: mathematical analysis

Proposition. Selection sort uses $(N-1) + (N-2) + \dots + 1 + 0 \sim N^2/2$ compares and N exchanges.

i	min	0	1	2	3	4	5	6	7	8	9	10	a[]
		S	O	R	T	E	X	A	M	P	L	E	
0	6	S	O	R	T	E	X	A	M	P	L	E	entries in black are examined to find the minimum
1	4	A	O	R	T	E	X	S	M	P	L	E	entries in red are $a[min]$
2	10	A	E	R	T	O	X	S	M	P	L	E	
3	9	A	E	E	T	O	X	S	M	P	L	R	
4	7	A	E	E	L	O	X	S	M	P	T	R	
5	7	A	E	E	L	M	X	S	O	P	T	R	
6	8	A	E	E	L	M	O	S	X	P	T	R	
7	10	A	E	E	L	M	O	P	X	S	T	R	
8	8	A	E	E	L	M	O	P	R	S	T	X	
9	9	A	E	E	L	M	O	P	R	S	T	X	entries in gray are in final position
10	10	A	E	E	L	M	O	P	R	S	T	X	
		A	E	E	L	M	O	P	R	S	T	X	

Trace of selection sort (array contents just after each exchange)

Running time insensitive to input. Quadratic time, even if input is sorted.
Data movement is minimal. Linear number of exchanges.

Insertion sort

Algorithm. ↑ scans from left to right.

Invariants.

- Entries to the left of ↑ (including ↑) are in ascending order.
- Entries to the right of ↑ have not yet been seen.



Insertion sort inner loop

To maintain algorithm invariants:

- Move the pointer to the right.

i++;



- Moving from right to left, exchange a[i] with each larger entry to its left.

```
for (int j = i; j > 0; j--)  
    if (less(a[j], a[j-1]))  
        exch(a, j, j-1);  
    else break;
```



Insertion sort: mathematical analysis

Proposition. To sort a randomly-ordered array with distinct keys, insertion sort uses $\sim \frac{1}{4} N^2$ compares and $\sim \frac{1}{4} N^2$ exchanges on average.

Pf. Expect each entry to move halfway back.

		a[]										
i	j	0	1	2	3	4	5	6	7	8	9	10
		S	O	R	T	E	X	A	M	P	L	E
1	0	O	S	R	T	E	X	A	M	P	L	E
2	1	O	R	S	T	E	X	A	M	P	L	E
3	3	O	R	S	T	E	X	A	M	P	L	E
4	0	E	O	R	S	T	X	A	M	P	L	E
5	5	E	O	R	S	T	X	A	M	P	L	E
6	0	A	E	O	R	S	T	X	M	P	L	E
7	2	A	E	M	O	R	S	T	X	P	L	E
8	4	A	E	M	O	P	R	S	T	X	L	E
9	2	A	E	L	M	O	P	R	S	T	X	E
10	2	A	E	E	L	M	O	P	R	S	T	X
		A	E	E	L	M	O	P	R	S	T	X

Trace of insertion sort (array contents just after each insertion)

Insertion sort: best and worst case

Best case. If the array is in ascending order, insertion sort makes $N-1$ compares and 0 exchanges.

A E E L M O P R S T X

Worst case. If the array is in descending order (and no duplicates), insertion sort makes $\sim \frac{1}{2} N^2$ compares and $\sim \frac{1}{2} N^2$ exchanges.

X T S R P O M L E E A

Insertion sort: partially-sorted arrays

Def. An **inversion** is a pair of keys that are out of order.

A E E L M O T R X P S
T-R T-P T-S R-P X-P X-S
(6 inversions)

Def. An array is **partially sorted** if the number of inversions is $\leq c N$.

- Ex 1. A subarray of size 10 appended to a sorted subarray of size N .
- Ex 2. An array of size N with only 10 entries out of place.

Proposition. For partially-sorted arrays, insertion sort runs in linear time.

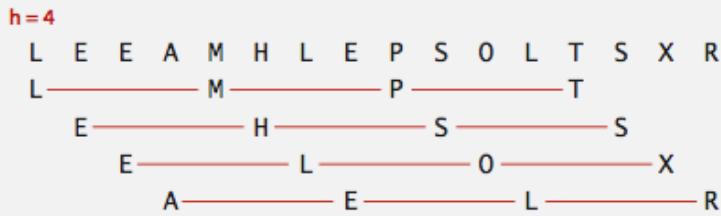
Pf. Number of exchanges equals the number of inversions.

$$\text{number of compares} = \text{exchanges} + (N - 1)$$

Shellsort overview

Idea. Move entries more than one position at a time by *h*-sorting the array.

an *h*-sorted array is *h* interleaved sorted subsequences



Shellsort. [Shell 1959] *h*-sort array for decreasing sequence of values of *h*.

input	S H E L L S O R T E X A M P L E
13-sort	P H E L L S O R T E X A M S L E
4-sort	L E E A M H L E P S O L T S X R
1-sort	A E E E H L L L M O P R S S T X

Shellsort example: increments 7, 3, 1

input

S O R T E X A M P L E

1-sort

A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	E	L	O	P	M	S	X	R	T
A	E	E	L	O	P	M	S	X	R	T
A	E	E	L	M	O	P	S	X	R	T
A	E	E	L	M	O	P	R	S	X	T
A	E	E	L	M	O	P	R	S	T	X

7-sort

S	O	R	T	E	X	A	M	P	L	E
M	O	R	T	E	X	A	S	P	L	E
M	O	R	T	E	X	A	S	P	L	E
M	O	L	T	E	X	A	S	P	R	E
M	O	L	E	E	X	A	S	P	R	T

A	E	E	L	O	P	M	S	X	R	T
A	E	E	L	M	O	P	S	X	R	T
A	E	E	L	M	O	P	S	X	R	T
A	E	E	L	M	O	P	S	X	R	T
A	E	E	L	M	O	P	R	S	X	T
A	E	E	L	M	O	P	R	S	T	X

3-sort

M	O	L	E	E	X	A	S	P	R	T
E	O	L	M	E	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T

result

A E E L M O P R S T X

Shellsort: which increment sequence to use?

Powers of two. 1, 2, 4, 8, 16, 32, ...

No.

Powers of two minus one. 1, 3, 7, 15, 31, 63, ...

Maybe.

→ 3x + 1. 1, 4, 13, 40, 121, 364, ...

OK. Easy to compute.

Sedgewick. 1, 5, 19, 41, 109, 209, 505, 929, 2161, 3905, ...

Good. Tough to beat in empirical studies.

↗
merging of $(9 \times 4^i) - (9 \times 2^i) + 1$
and $4^i - (3 \times 2^i) + 1$

Shellsort: analysis

Proposition. The worst-case number of compares used by shellsort with the $3x+1$ increments is $O(N^{3/2})$.

Property. Number of compares used by shellsort with the $3x+1$ increments is at most by a small multiple of N times the # of increments used.

N	compares	$N^{1.289}$	$2.5 N \lg N$
5,000	93	58	106
10,000	209	143	230
20,000	467	349	495
40,000	1022	855	1059
80,000	2266	2089	2257

measured in thousands

Remark. Accurate model has not yet been discovered (!)

Why are we interested in shellsort?

Example of simple idea leading to substantial performance gains.

Useful in practice.

- Fast unless array size is huge (used for small subarrays).
- Tiny, fixed footprint for code (used in some embedded systems).
- Hardware sort prototype.

bzip2, /linux/kernel/groups.c

uClibc

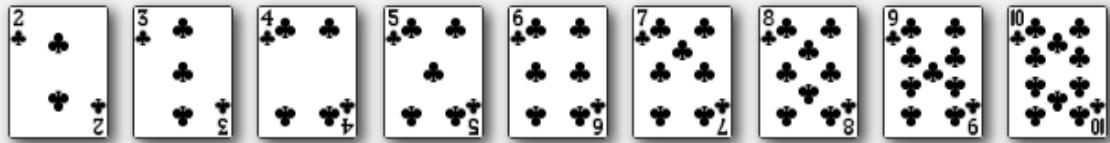
Simple algorithm, nontrivial performance, interesting questions.

- Asymptotic growth rate?
- Best sequence of increments? ← open problem: find a better increment sequence
- Average-case performance?

Lesson. Some good algorithms are still waiting discovery.

Knuth shuffle

- In iteration i , pick integer r between 0 and i uniformly at random.
- Swap $a[i]$ and $a[r]$.



Proposition. [Fisher-Yates 1938] Knuth shuffling algorithm produces a uniformly random permutation of the input array in linear time.

assuming integers
uniformly at random

War story (online poker)

Shuffling algorithm in FAQ at www.planetpoker.com

```
for i := 1 to 52 do begin
    r := random(51) + 1;           ← between 1 and 51
    swap := card[r];
    card[r] := card[i];
    card[i] := swap;
end;
```

Bug 1. Random number r never 52 \Rightarrow 52nd card can't end up in 52nd place.

Bug 2. Shuffle not uniform (should be between 1 and i).

Bug 3. `random()` uses 32-bit seed $\Rightarrow 2^{32}$ possible shuffles.

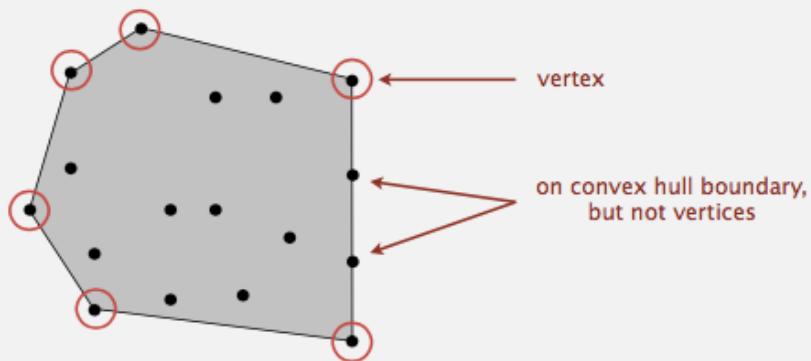
Bug 4. Seed = milliseconds since midnight \Rightarrow 86.4 million shuffles.

“The generation of random numbers is too important to be left to chance.”

— Robert R. Coveyou

Convex hull 凸包

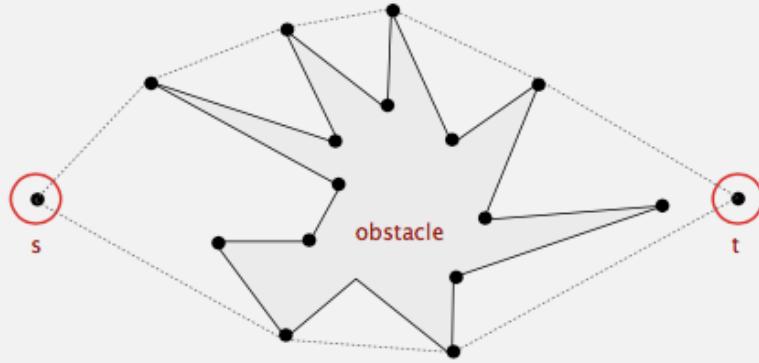
The **convex hull** of a set of N points is the smallest perimeter fence enclosing the points.



Convex hull output. Sequence of vertices in counterclockwise order.

Convex hull application: motion planning

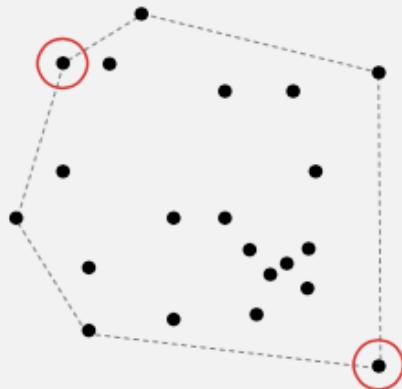
Robot motion planning. Find shortest path in the plane from s to t that avoids a polygonal obstacle.



Fact. Shortest path is either straight line from s to t or it is one of two polygonal chains of convex hull.

Convex hull application: farthest pair

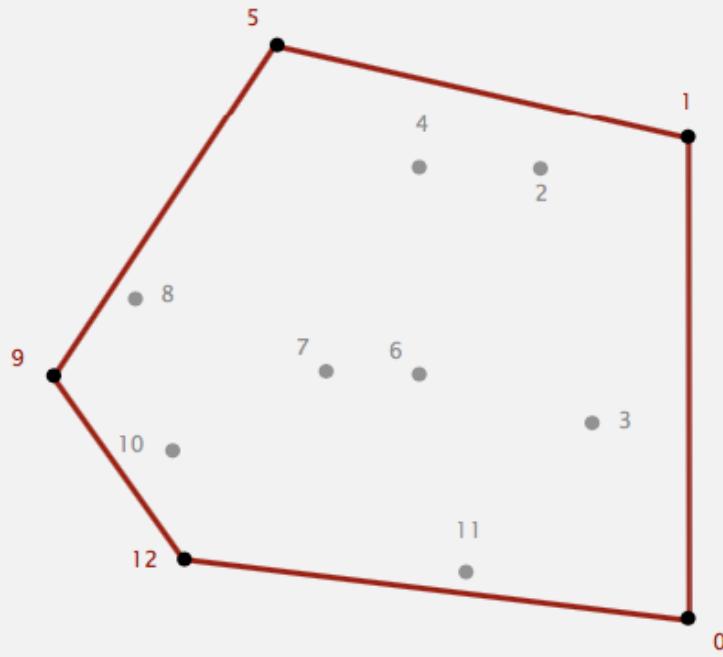
Farthest pair problem. Given N points in the plane, find a pair of points with the largest Euclidean distance between them.



Fact. Farthest pair of points are extreme points on convex hull.

Graham scan demo

- Choose point p with smallest y -coordinate.
- Sort points by polar angle with p .
- Consider points in order; discard unless it creates a ccw turn.



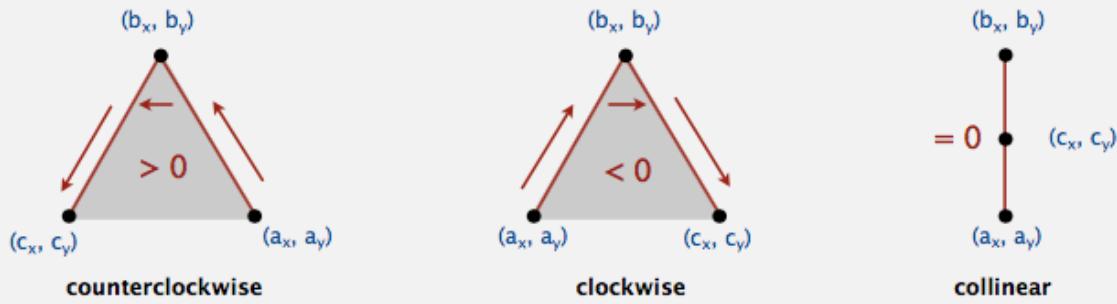
Implementing ccw

CCW. Given three points a , b , and c , is $a \rightarrow b \rightarrow c$ a counterclockwise turn?

- Determinant (or cross product) gives $2x$ signed area of planar triangle.

$$2 \times \text{Area}(a, b, c) = \begin{vmatrix} a_x & a_y & 1 \\ b_x & b_y & 1 \\ c_x & c_y & 1 \end{vmatrix} = (b_x - a_x)(c_y - a_y) - (b_y - a_y)(c_x - a_x)$$
$$(b - a) \times (c - a)$$

- If signed area > 0 , then $a \rightarrow b \rightarrow c$ is counterclockwise.
- If signed area < 0 , then $a \rightarrow b \rightarrow c$ is clockwise.
- If signed area $= 0$, then $a \rightarrow b \rightarrow c$ are collinear.



Two classic sorting algorithms

Critical components in the world's computational infrastructure.

- Full scientific understanding of their properties has enabled us to develop them into practical system sorts.
- Quicksort honored as one of top 10 algorithms of 20th century in science and engineering.

Mergesort. [this lecture]

- Java sort for objects.
- Perl, C++ stable sort, Python stable sort, Firefox JavaScript, ...

Quicksort. [next lecture]

- Java sort for primitive types.
- C qsort, Unix, Visual C++, Python, Matlab, Chrome JavaScript, ...

Mergesort

Basic plan.

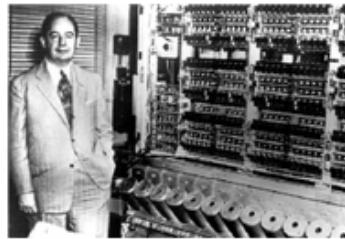
- Divide array into two halves.
- Recursively sort each half.
- Merge two halves.

input	M	E	R	G	E	S	O	R	T	E	X	A	M	P	L	E	
sort left half	E	E	G	M	O	R	R	S	T	E	X	A	M	P	L	E	
sort right half	E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X	
merge results	A	E	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X

Mergesort overview

First Draft of a Report on the EDVAC

John von Neumann



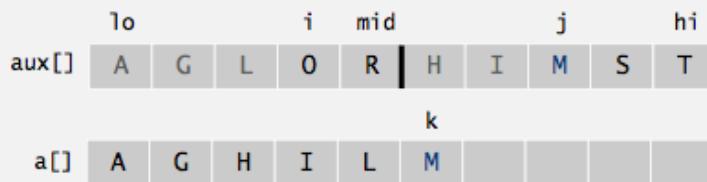
Merging: Java implementation

```
private static void merge(Comparable[] a, Comparable[] aux, int lo, int mid, int hi)
{
    assert isSorted(a, lo, mid);      // precondition: a[lo..mid] sorted
    assert isSorted(a, mid+1, hi);    // precondition: a[mid+1..hi] sorted

    for (int k = lo; k <= hi; k++)                                copy
        aux[k] = a[k];

    int i = lo, j = mid+1;
    for (int k = lo; k <= hi; k++)                                merge
    {
        if      (i > mid)          a[k] = aux[j++];
        else if (j > hi)          a[k] = aux[i++];
        else if (less(aux[j], aux[i])) a[k] = aux[j++];
        else                      a[k] = aux[i++];
    }

    assert isSorted(a, lo, hi);      // postcondition: a[lo..hi] sorted
}
```

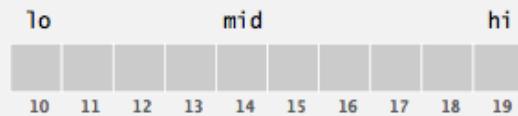


Mergesort: Java implementation

```
public class Merge
{
    private static void merge(...)
    { /* as before */ }

    private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
    {
        if (hi <= lo) return;
        int mid = lo + (hi - lo) / 2;
        sort(a, aux, lo, mid);
        sort(a, aux, mid+1, hi);
        merge(a, aux, lo, mid, hi);
    }

    public static void sort(Comparable[] a)
    {
        aux = new Comparable[a.length];
        sort(a, aux, 0, a.length - 1);
    }
}
```



Mergesort: empirical analysis

Running time estimates:

- Laptop executes 10^8 compares/second.
- Supercomputer executes 10^{12} compares/second.

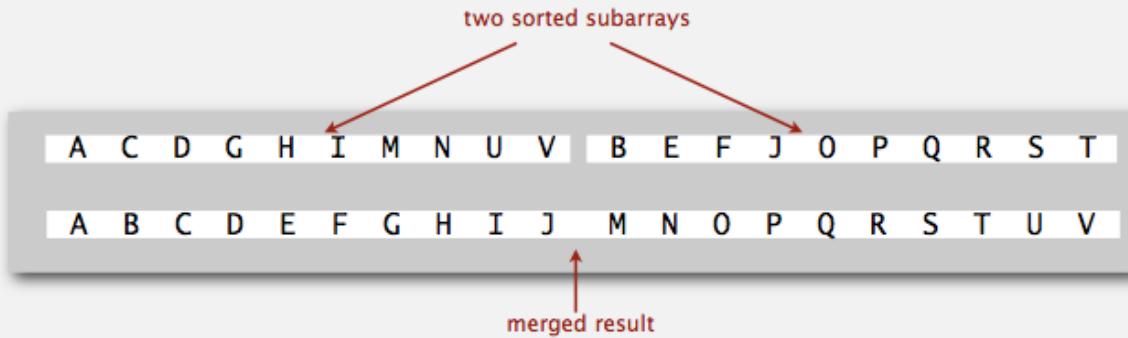
computer	insertion sort (N^2)			mergesort ($N \log N$)		
	thousand	million	billion	thousand	million	billion
home	instant	2.8 hours	317 years	instant	1 second	18 min
super	instant	1 second	1 week	instant	instant	instant

Bottom line. Good algorithms are better than supercomputers.

Mergesort analysis: memory

Proposition. Mergesort uses extra space proportional to N .

Pf. The array `aux[]` needs to be of size N for the last merge.



Def. A sorting algorithm is **in-place** if it uses $\leq c \log N$ extra memory.

Ex. Insertion sort, selection sort, shellsort.

Challenge for the bored. In-place merge. [Kronrod, 1969]

Mergesort: practical improvements

Use insertion sort for small subarrays.

- Mergesort has too much overhead for tiny subarrays.
- Cutoff to insertion sort for ≈ 7 items.

```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo + CUTOFF - 1)
    {
        Insertion.sort(a, lo, hi);
        return;
    }
    int mid = lo + (hi - lo) / 2;
    sort (a, aux, lo, mid);
    sort (a, aux, mid+1, hi);
    merge(a, aux, lo, mid, hi);
}
```

Mergesort: practical improvements

Stop if already sorted.

- Is biggest item in first half \leq smallest item in second half?
- Helps for partially-ordered arrays.

A	B	C	D	E	F	G	H	I	J	M	N	O	P	Q	R	S	T	U	V
A	B	C	D	E	F	G	H	I	J	M	N	O	P	Q	R	S	T	U	V

```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo) return;
    int mid = lo + (hi - lo) / 2;
    sort(a, aux, lo, mid);
    sort(a, aux, mid+1, hi);
    if (!less(a[mid+1], a[mid])) return;
    merge(a, aux, lo, mid, hi);
}
```

Bottom-up mergesort

Basic plan.

- Pass through array, merging subarrays of size 1.
- Repeat for subarrays of size 2, 4, 8, 16,

	a[i]															
	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
sz = 1	M	E	R	G	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, aux, 0, 0, 1)	E	M	R	G	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, aux, 2, 2, 3)	E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, aux, 4, 4, 5)	E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, aux, 6, 6, 7)	E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, aux, 8, 8, 9)	E	M	G	R	E	S	O	R	E	T	X	A	M	P	L	E
merge(a, aux, 10, 10, 11)	E	M	G	R	E	S	O	R	E	T	A	X	M	P	L	E
merge(a, aux, 12, 12, 13)	E	M	G	R	E	S	O	R	E	T	A	X	M	P	L	E
merge(a, aux, 14, 14, 15)	E	M	G	R	E	S	O	R	E	T	A	X	M	P	E	L
sz = 2																
merge(a, aux, 0, 1, 3)	E	G	M	R	E	S	O	R	E	T	A	X	M	P	E	L
merge(a, aux, 4, 5, 7)	E	G	M	R	E	O	R	S	E	T	A	X	M	P	E	L
merge(a, aux, 8, 9, 11)	E	G	M	R	E	O	R	S	A	E	T	X	M	P	E	L
merge(a, aux, 12, 13, 15)	E	G	M	R	E	O	R	S	A	E	T	X	E	L	M	P
sz = 4																
merge(a, aux, 0, 3, 7)	E	E	G	M	O	R	R	S	A	E	T	X	E	L	M	P
merge(a, aux, 8, 11, 15)	E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X
sz = 8																
merge(a, aux, 0, 7, 15)	A	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X

Bottom-up mergesort: Java implementation

```
public class MergeBU
{
    private static void merge(...)
    { /* as before */

    public static void sort(Comparable[] a)
    {
        int N = a.length;
        Comparable[] aux = new Comparable[N];
        for (int sz = 1; sz < N; sz = sz+sz)
            for (int lo = 0; lo < N-sz; lo += sz+sz)
                merge(a, aux, lo, lo+sz-1, Math.min(lo+sz+sz-1, N-1));
    }
}
```

but about 10% slower than recursive,
top-down mergesort on typical systems

Bottom line. Simple and non-recursive version of mergesort.

Complexity of sorting

Model of computation. Allowable operations.

Cost model. Operation count(s).

Upper bound. Cost guarantee provided by some algorithm for X .

Lower bound. Proven limit on cost guarantee of all algorithms for X .

Optimal algorithm. Algorithm with best possible cost guarantee for X .

Example: sorting.

- Model of computation: decision tree.
- Cost model: # compares.
- Upper bound: $\sim N \lg N$ from mergesort.
- Lower bound: $\sim N \lg N$.
- Optimal algorithm = mergesort.

First goal of algorithm design: optimal algorithms.

Complexity results in context

Compares? Mergesort **is** optimal with respect to number compares.

Space? Mergesort **is not** optimal with respect to space usage.



Lessons. Use theory as a guide.

Ex. Design sorting algorithm that guarantees $\frac{1}{2} N \lg N$ compares?

Ex. Design sorting algorithm that is both time- and space-optimal?

Stability

A typical application. First, sort by name; then sort by section.

`Selection.sort(a, Student.BY_NAME);`

Andrews	3	A	664-480-0023	097 Little
Battle	4	C	874-088-1212	121 Whitman
Chen	3	A	991-878-4944	308 Blair
Fox	3	A	884-232-5341	11 Dickinson
Furia	1	A	766-093-9873	101 Brown
Gazsi	4	B	766-093-9873	101 Brown
Kanaga	3	B	898-122-9643	22 Brown
Rohde	2	A	232-343-5555	343 Forbes

`Selection.sort(a, Student.BY_SECTION);`

Furia	1	A	766-093-9873	101 Brown
Rohde	2	A	232-343-5555	343 Forbes
Chen	3	A	991-878-4944	308 Blair
Fox	3	A	884-232-5341	11 Dickinson
Andrews	3	A	664-480-0023	097 Little
Kanaga	3	B	898-122-9643	22 Brown
Gazsi	4	B	766-093-9873	101 Brown
Battle	4	C	874-088-1212	121 Whitman

@#%&@! Students in section 3 no longer sorted by name.

A **stable** sort preserves the relative order of items with equal keys.

Stability

Q. Which sorts are stable?

A. Insertion sort and mergesort (but not selection sort or shellsort).

sorted by time	sorted by location (not stable)	sorted by location (stable)
Chicago 09:00:00	Chicago 09:25:52	Chicago 09:00:00
Phoenix 09:00:03	Chicago 09:03:13	Chicago 09:00:59
Houston 09:00:13	Chicago 09:21:05	Chicago 09:03:13
Chicago 09:00:59	Chicago 09:19:46	Chicago 09:19:32
Houston 09:01:10	Chicago 09:19:32	Chicago 09:19:46
Chicago 09:03:13	Chicago 09:00:00	Chicago 09:21:05
Seattle 09:10:11	Chicago 09:35:21	Chicago 09:25:52
Seattle 09:10:25	Chicago 09:00:59	Chicago 09:35:21
Phoenix 09:14:25	Houston 09:01:10	Houston 09:00:13
Chicago 09:19:32	Houston 09:00:13	Houston 09:01:10
Chicago 09:19:46	Phoenix 09:37:44	Phoenix 09:00:03
Chicago 09:21:05	Phoenix 09:00:03	Phoenix 09:14:25
Seattle 09:22:43	Phoenix 09:14:25	Phoenix 09:37:44
Seattle 09:22:54	Seattle 09:10:25	Seattle 09:10:11
Chicago 09:25:52	Seattle 09:36:14	Seattle 09:10:25
Chicago 09:35:21	Seattle 09:22:43	Seattle 09:22:43
Seattle 09:36:14	Seattle 09:10:11	Seattle 09:22:54
Phoenix 09:37:44	Seattle 09:22:54	Seattle 09:36:14

Note. Need to carefully check code ("less than" vs. "less than or equal to").

Quicksort

Basic plan.

- **Shuffle** the array.
- **Partition** so that, for some j
 - entry $a[j]$ is in place
 - no larger entry to the left of j
 - no smaller entry to the right of j
- **Sort** each piece recursively.



Sir Charles Antony Richard Hoare
1980 Turing Award

input	Q	U	I	C	K	S	O	R	T	E	X	A	M	P	L	E
shuffle	K	R	A	T	E	L	E	P	U	I	M	Q	C	X	O	S
partition	E	C	A	I	E	K	L	P	U	T	M	Q	R	X	O	S
	<i>partitioning item</i>															
sort left	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
sort right	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
result	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X

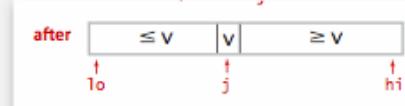
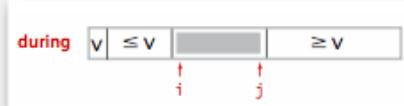
Quicksort: Java code for partitioning

```
private static int partition(Comparable[] a, int lo, int hi)
{
    int i = lo, j = hi+1;
    while (true)
    {
        while (less(a[++i], a[lo]))           find item on left to swap
            if (i == hi) break;

        while (less(a[lo], a[--j]))           find item on right to swap
            if (j == lo) break;

        if (i >= j) break;                  check if pointers cross
        exch(a, i, j);                   swap
    }

    exch(a, lo, j);                  swap with partitioning item
    return j;                        return index of item now known to be in place
}
```



Quicksort: Java implementation

```
public class Quick
{
    private static int partition(Comparable[] a, int lo, int hi)
    { /* see previous slide */ }

    public static void sort(Comparable[] a)
    {
        StdRandom.shuffle(a);
        sort(a, 0, a.length - 1);
    }

    private static void sort(Comparable[] a, int lo, int hi)
    {
        if (hi <= lo) return;
        int j = partition(a, lo, hi);
        sort(a, lo, j-1);
        sort(a, j+1, hi);
    }
}
```

shuffle needed for
performance guarantee
(stay tuned)

Quicksort: implementation details

Partitioning in-place. Using an extra array makes partitioning easier (and stable), but is not worth the cost.

Terminating the loop. Testing whether the pointers cross is a bit trickier than it might seem.

Staying in bounds. The `(j == lo)` test is redundant (why?), but the `(i == hi)` test is not.

Preserving randomness. Shuffling is needed for performance guarantee.

Equal keys. When duplicates are present, it is (counter-intuitively) better to stop on keys equal to the partitioning item's key.

Quicksort: empirical analysis

Running time estimates:

- Home PC executes 10^8 compares/second.
- Supercomputer executes 10^{12} compares/second.

	insertion sort (N^2)			mergesort ($N \log N$)			quicksort ($N \log N$)		
computer	thousand	million	billion	thousand	million	billion	thousand	million	billion
home	instant	2.8 hours	317 years	instant	1 second	18 min	instant	0.6 sec	12 min
super	instant	1 second	1 week	instant	instant	instant	instant	instant	instant

Lesson 1. Good algorithms are better than supercomputers.

Lesson 2. Great algorithms are better than good ones.

Quicksort: worst-case analysis

Worst case. Number of compares is $\sim \frac{1}{2} N^2$.

lo	j	hi	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
initial values			A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
random shuffle			A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
0	0	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
1	1	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
2	2	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
3	3	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
4	4	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
5	5	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
6	6	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
7	7	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
8	8	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
9	9	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
10	10	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
11	11	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
12	12	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
13	13	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
14		14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
			A	B	C	D	E	F	G	H	I	J	K	L	M	N	O

Quicksort: summary of performance characteristics

Worst case. Number of compares is quadratic.

- $N + (N - 1) + (N - 2) + \dots + 1 \sim \frac{1}{2} N^2$.
- More likely that your computer is struck by lightning bolt.

Average case. Number of compares is $\sim 1.39 N \lg N$.

- 39% more compares than mergesort.
- **But** faster than mergesort in practice because of less data movement.

Random shuffle.

- Probabilistic guarantee against worst case.
- Basis for math model that can be validated with experiments.

Caveat emptor. Many textbook implementations go **quadratic** if array

- Is sorted or reverse sorted.
- Has many duplicates (even if randomized!)

Quicksort properties

Proposition. Quicksort is an **in-place** sorting algorithm.

Pf.

- Partitioning: constant extra space.
- Depth of recursion: logarithmic extra space (with high probability).

can guarantee logarithmic depth by recurring on smaller subarray before larger subarray

Proposition. Quicksort is **not stable**.

Pf.

i	j	0	1	2	3
		B ₁	C ₁	C ₂	A ₁
1	3	B ₁	C ₁	C ₂	A ₁
1	3	B ₁	A ₁	C ₂	C ₁
0	1	A ₁	B ₁	C ₂	C ₁

Quicksort: practical improvements

Insertion sort small subarrays.

- Even quicksort has too much overhead for tiny subarrays.
- Cutoff to insertion sort for ≈ 10 items.
- Note: could delay insertion sort until one pass at end.

```
private static void sort(Comparable[] a, int lo, int hi)
{
    if (hi <= lo + CUTOFF - 1)
    {
        Insertion.sort(a, lo, hi);
        return;
    }
    int j = partition(a, lo, hi);
    sort(a, lo, j-1);
    sort(a, j+1, hi);
}
```

Quicksort: practical improvements

Median of sample.

- Best choice of pivot item = median.
- Estimate true median by taking median of sample.
- Median-of-3 (random) items.



~ 12/7 N ln N compares (slightly fewer)
~ 12/35 N ln N exchanges (slightly more)

```
private static void sort(Comparable[] a, int lo, int hi)
{
    if (hi <= lo) return;

    int m = medianOf3(a, lo, lo + (hi - lo)/2, hi);
    swap(a, lo, m);

    int j = partition(a, lo, hi);
    sort(a, lo, j-1);
    sort(a, j+1, hi);
}
```

Selection

Goal. Given an array of N items, find a k^{th} smallest item.

Ex. Min ($k = 0$), max ($k = N - 1$), median ($k = N/2$).

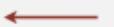
Applications.

- Order statistics.
- Find the "top k ."

Use theory as a guide.

- Easy $N \log N$ upper bound. How?
- Easy N upper bound for $k = 1, 2, 3$. How?
- Easy N lower bound. Why?

Which is true?

- $N \log N$ lower bound?  is selection as hard as sorting?
- N upper bound?  is there a linear-time algorithm for each k ?

Quick-select

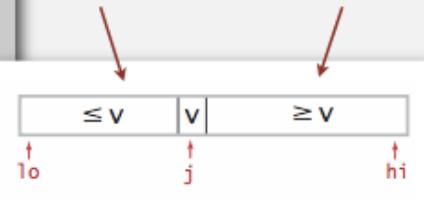
Partition array so that:

- Entry $a[j]$ is in place.
- No larger entry to the left of j .
- No smaller entry to the right of j .

Repeat in one subarray, depending on j ; finished when j equals k .

```
public static Comparable select(Comparable[] a, int k)
{
    StdRandom.shuffle(a);
    int lo = 0, hi = a.length - 1;
    while (hi > lo)
    {
        int j = partition(a, lo, hi);
        if      (j < k) lo = j + 1;
        else if (j > k) hi = j - 1;
        else            return a[k];
    }
    return a[k];
}
```

if $a[k]$ is here
set hi to $j-1$ if $a[k]$ is here
set lo to $j+1$



Quick-select: mathematical analysis

Proposition. Quick-select takes linear time on average.

Pf sketch.

- Intuitively, each partitioning step splits array approximately in half:
 $N + N/2 + N/4 + \dots + 1 \sim 2N$ compares.
- Formal analysis similar to quicksort analysis yields:

$$C_N = 2N + 2k \ln(N/k) + 2(N-k) \ln(N/(N-k))$$

($2 + 2 \ln 2$) N to find the median

Remark. Quick-select uses $\sim \frac{1}{2}N^2$ compares in the worst case, but
(as with quicksort) the random shuffle provides a probabilistic guarantee.

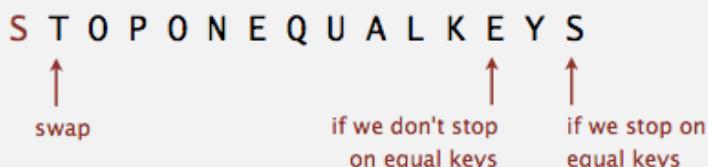
Duplicate keys

Mergesort with duplicate keys. Between $\frac{1}{2}N\lg N$ and $N\lg N$ compares.

Quicksort with duplicate keys.

- Algorithm goes quadratic unless partitioning stops on equal keys!
- 1990s C user found this defect in `qsort()`.

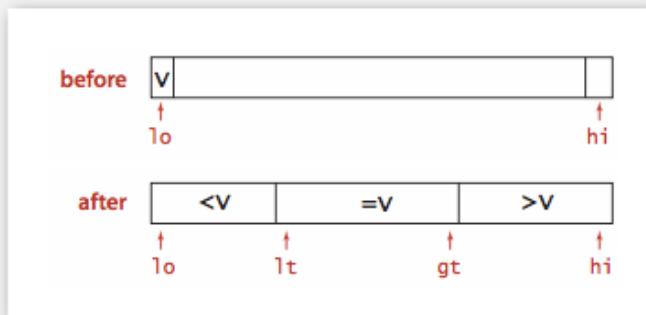
several textbook and system implementation also have this defect



3-way partitioning

Goal. Partition array into 3 parts so that:

- Entries between `lt` and `gt` equal to partition item `v`.
- No larger entries to left of `lt`.
- No smaller entries to right of `gt`.

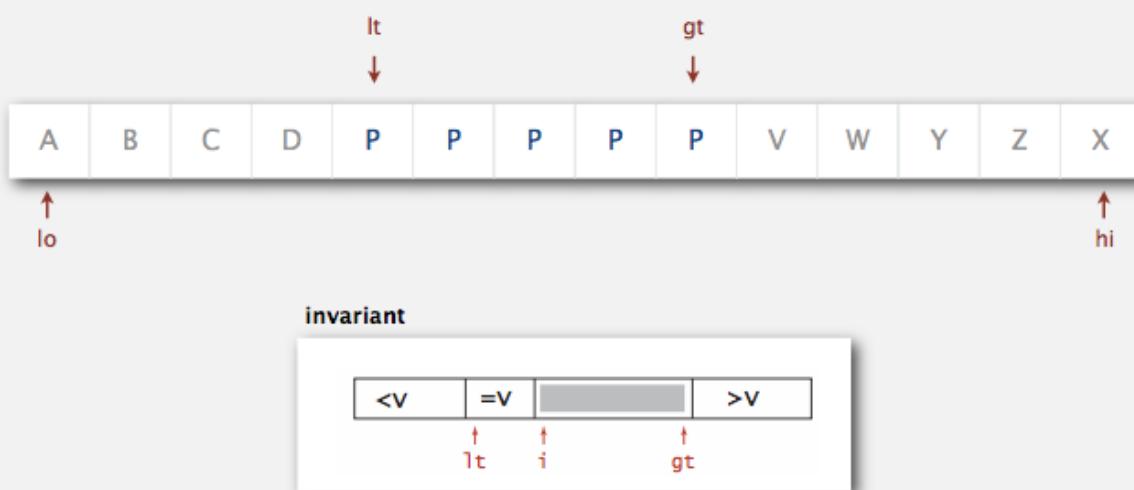


Dutch national flag problem. [Edsger Dijkstra]

- Conventional wisdom until mid 1990s: not worth doing.
- New approach discovered when fixing mistake in C library `qsort()`.
- Now incorporated into `qsort()` and Java system sort.

Dijkstra 3-way partitioning demo

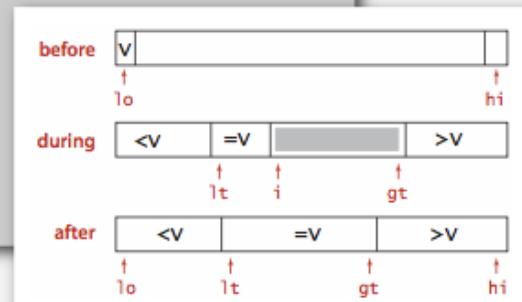
- Let v be partitioning item $a[lo]$.
- Scan i from left to right.
 - $(a[i] < v)$: exchange $a[lt]$ with $a[i]$; increment both lt and i
 - $(a[i] > v)$: exchange $a[gt]$ with $a[i]$; decrement gt
 - $(a[i] == v)$: increment i



3-way quicksort: Java implementation

```
private static void sort(Comparable[] a, int lo, int hi)
{
    if (hi <= lo) return;
    int lt = lo, gt = hi;
    Comparable v = a[lo];
    int i = lo;
    while (i <= gt)
    {
        int cmp = a[i].compareTo(v);
        if      (cmp < 0) exch(a, lt++, i++);
        else if (cmp > 0) exch(a, i, gt--);
        else               i++;
    }

    sort(a, lo, lt - 1);
    sort(a, gt + 1, hi);
}
```



Duplicate keys: lower bound

Sorting lower bound. If there are n distinct keys and the i^{th} one occurs x_i times, any compare-based sorting algorithm must use at least

$$\lg \left(\frac{N!}{x_1! x_2! \cdots x_n!} \right) \sim - \sum_{i=1}^n x_i \lg \frac{x_i}{N}$$

$N \lg N$ when all distinct;
linear when only a constant number of distinct keys

comparisons in the worst case.

Proposition. [Sedgewick-Bentley, 1997]

Quicksort with 3-way partitioning is **entropy-optimal**.

Pf. [beyond scope of course]

proportional to lower bound

Bottom line. Randomized quicksort with 3-way partitioning reduces running time from linearithmic to linear in broad class of applications.

Java system sorts

Arrays.sort().

- Has different method for each primitive type.
- Has a method for data types that implement Comparable.
- Has a method that uses a Comparator.
- Uses tuned quicksort for primitive types; tuned mergesort for objects.

```
import java.util.Arrays;

public class StringSort
{
    public static void main(String[] args)
    {
        String[] a = StdIn.readStrings();
        Arrays.sort(a);
        for (int i = 0; i < N; i++)
            StdOut.println(a[i]);
    }
}
```

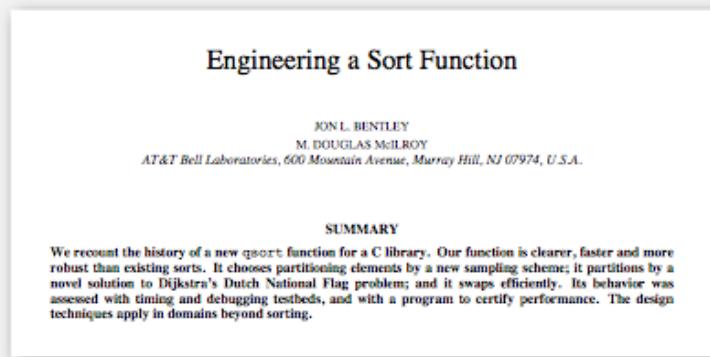
Q. Why use different algorithms for primitive and reference types?

+ Merge sort for objects. Stable && Using objects has less consideration about spaces
+ Quick sort for primitives. Faster in practice && Save space

Engineering a system sort

Basic algorithm = quicksort.

- Cutoff to insertion sort for small subarrays.
- Partitioning scheme: Bentley-McIlroy 3-way partitioning.
- Partitioning item.
 - small arrays: middle entry
 - medium arrays: median of 3
 - large arrays: Tukey's ninther [next slide]



Now widely used. C, C++, Java 6,

System sort: Which algorithm to use?

Many sorting algorithms to choose from:

Internal sorts.

- Insertion sort, selection sort, bubblesort, shaker sort.
- Quicksort, mergesort, heapsort, samplesort, shellsort.
- Solitaire sort, red-black sort, splaysort, Yaroslavskiy sort, psort, ...

External sorts. Poly-phase mergesort, cascade-merge, oscillating sort.

String/radix sorts. Distribution, MSD, LSD, 3-way string quicksort.

Parallel sorts.

- Bitonic sort, Batcher even-odd sort.
- Smooth sort, cube sort, column sort.
- GPUsort.

Sorting summary

	inplace?	stable?	worst	average	best	remarks
selection	✓		$N^2 / 2$	$N^2 / 2$	$N^2 / 2$	N exchanges
insertion	✓	✓	$N^2 / 2$	$N^2 / 4$	N	use for small N or partially ordered
shell	✓		?	?	N	tight code, subquadratic
merge		✓	$N \lg N$	$N \lg N$	$N \lg N$	$N \log N$ guarantee, stable
quick	✓		$N^2 / 2$	$2 N \ln N$	$N \lg N$	$N \log N$ probabilistic guarantee fastest in practice
3-way quick	✓		$N^2 / 2$	$2 N \ln N$	N	improves quicksort in presence of duplicate keys
???	✓	✓	$N \lg N$	$N \lg N$	N	holy sorting grail

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