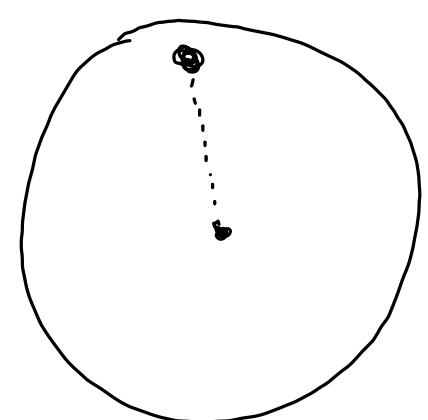
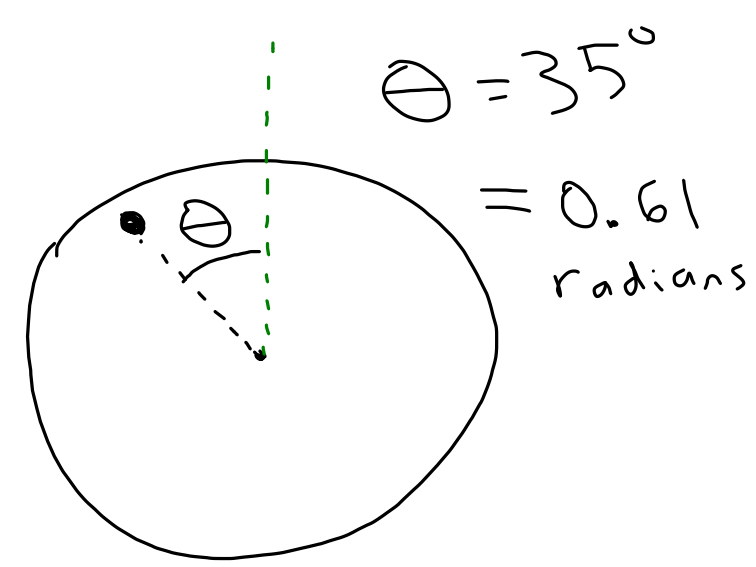


Rotations



initial

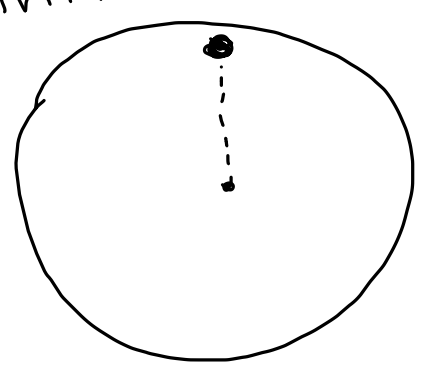
35° rotation
→
counterclockwise



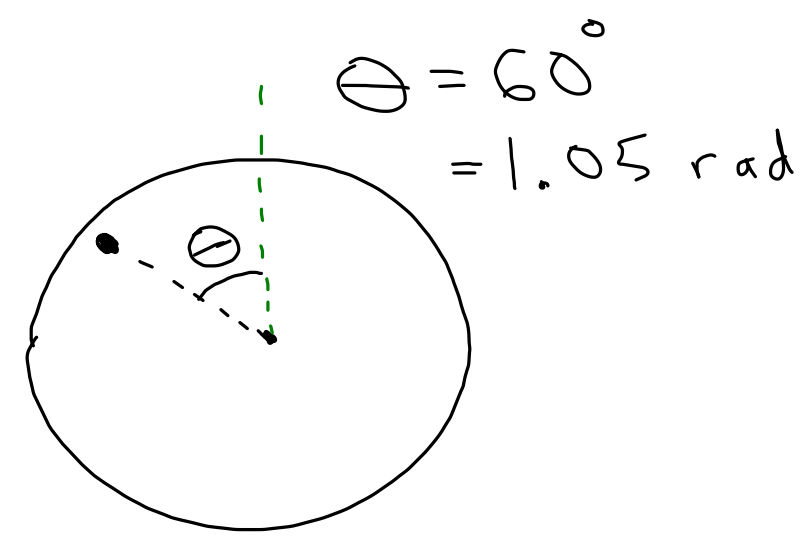
$$\Theta (\text{in radians}) = \frac{\Theta (\text{in degrees}) \pi}{180}$$

angular velocity

initial



2 seconds
→
later



$$t = 0 \text{ s}$$

$$t = 2 \text{ s}$$

$$\omega_{\text{ave}} = \frac{\Delta \Theta}{\Delta t} = \frac{\Theta_f - \Theta_i}{t_f - t_i}$$

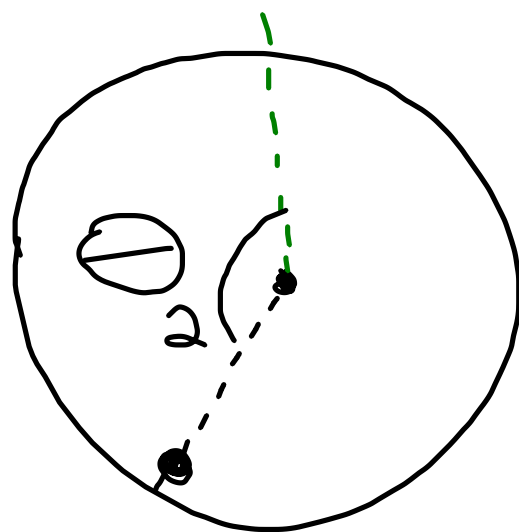
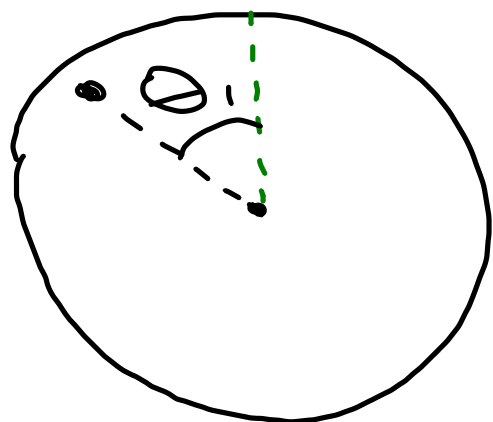
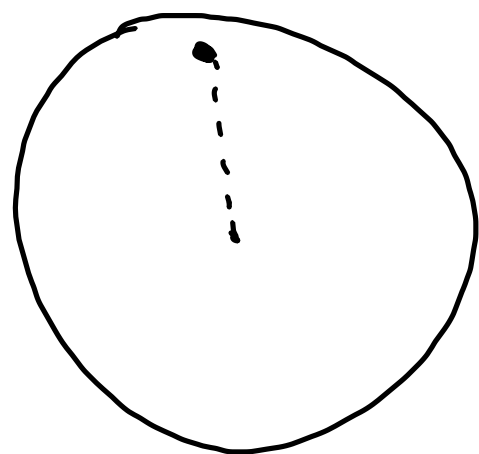
above example:

$$\frac{1.05 - 0 \text{ rad}}{2 - 0 \text{ s}} = 0.525 \frac{\text{rad}}{\text{s}}$$

angular acceleration:

$$\Theta_1 = \frac{\pi}{4} \text{ rad}$$

$$\Theta_2 = \frac{3\pi}{4} \text{ rad}$$



$$t = 0 \text{ s}$$

$$t = 1 \text{ s}$$

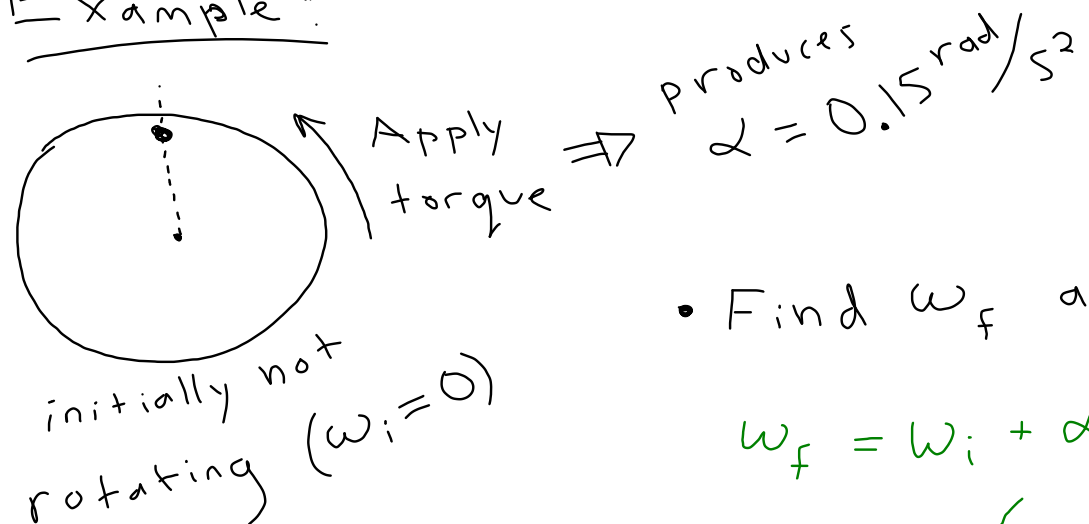
$$t = 2 \text{ s}$$

$$\omega_{ave}^{(1)} = \frac{\frac{\pi}{4} - 0}{1 - 0} = \frac{\pi}{4} \frac{\text{rad}}{\text{s}}$$

$$\omega_{ave}^{(2)} = \frac{\frac{3\pi}{4} - \frac{\pi}{4}}{2 - 1} = \frac{\pi}{2} \frac{\text{rad}}{\text{s}}$$

$$\alpha_{ave} = \frac{\Delta \omega}{\Delta t} = \frac{\omega_f - \omega_i}{t_f - t_i}$$

Example:



- Find ω_f after 3s.

$$\omega_f = \omega_i + \alpha t$$

$$\omega_f = 0 + (0.15 \frac{\text{rad}}{\text{s}^2})(3\text{s}) =$$

$$\boxed{\omega_f = 0.45 \frac{\text{rad}}{\text{s}}}$$

- What is Θ_f after 3s?

$$\Theta_f = \Theta_i + \omega_i t + \frac{1}{2} \alpha t^2$$

$$\Theta_f = 0 + 0(3) + \frac{1}{2}(0.15)(3)^2$$

$$\boxed{\Theta_f = 0.675 \text{ rad}} = 38.7^\circ$$

Summary

Analogies:

$$x \longrightarrow \Theta$$

$$v \longrightarrow \omega$$

$$a \longrightarrow \alpha$$

$$t \longrightarrow t$$

$$\omega_f = \omega_i + \alpha t$$

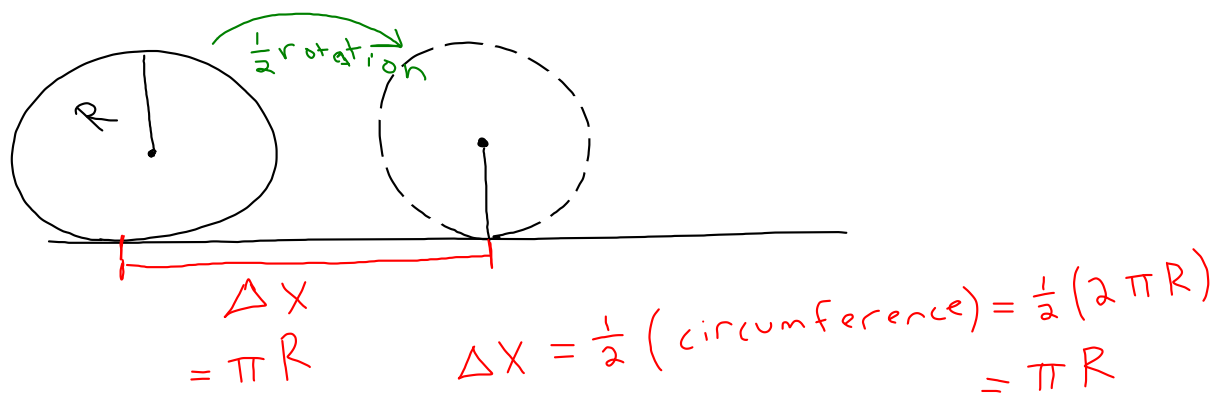
$$\Theta_f = \Theta_i + \omega_i t + \frac{1}{2} \alpha t^2$$

$$\Theta_f = \Theta_i + \frac{1}{2}(\omega_i + \omega_f)t$$

$$\omega_f^2 = \omega_i^2 + 2\alpha(\Theta_f - \Theta_i)$$

constant α

Tangential Velocity, acceleration



In general:

$$\Delta X = (\text{fraction of a full rotation}) (\text{circumference})$$

$$\Delta X = \left(\frac{\Theta \text{ (in radians)}}{2\pi} \right) (2\pi R)$$

Aside:

$$\Delta X = \left(\frac{\Theta \text{ (deg.)}}{360} \right) (2\pi R)$$

$$\Delta X = 0.0175 \Theta R$$

in degrees

$$\Delta X = \Theta R$$

↑ in radians

↓ divide by Δt

$$\frac{\Delta X}{\Delta t} = \frac{\Theta R}{\Delta t}$$

$$V = \omega R$$

↑ in rad/s

↓ divide by Δt again

$$\frac{V}{\Delta t} = \frac{\omega}{\Delta t} R$$

$$a = \alpha R$$

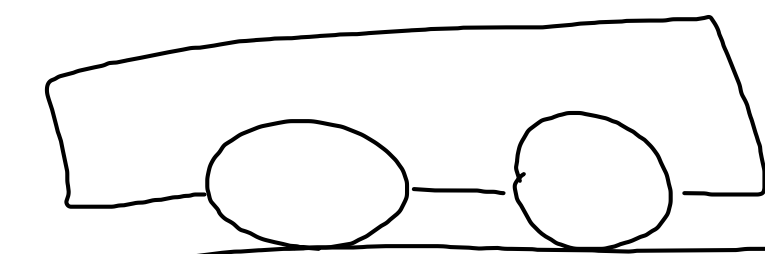
↑ in rad/s²

Example :

const. a

$$t = 4 \text{ s}$$

$$v_i = 0$$



$$R = 0.2 \text{ m}$$

$$\Delta x = 7 \text{ m}$$

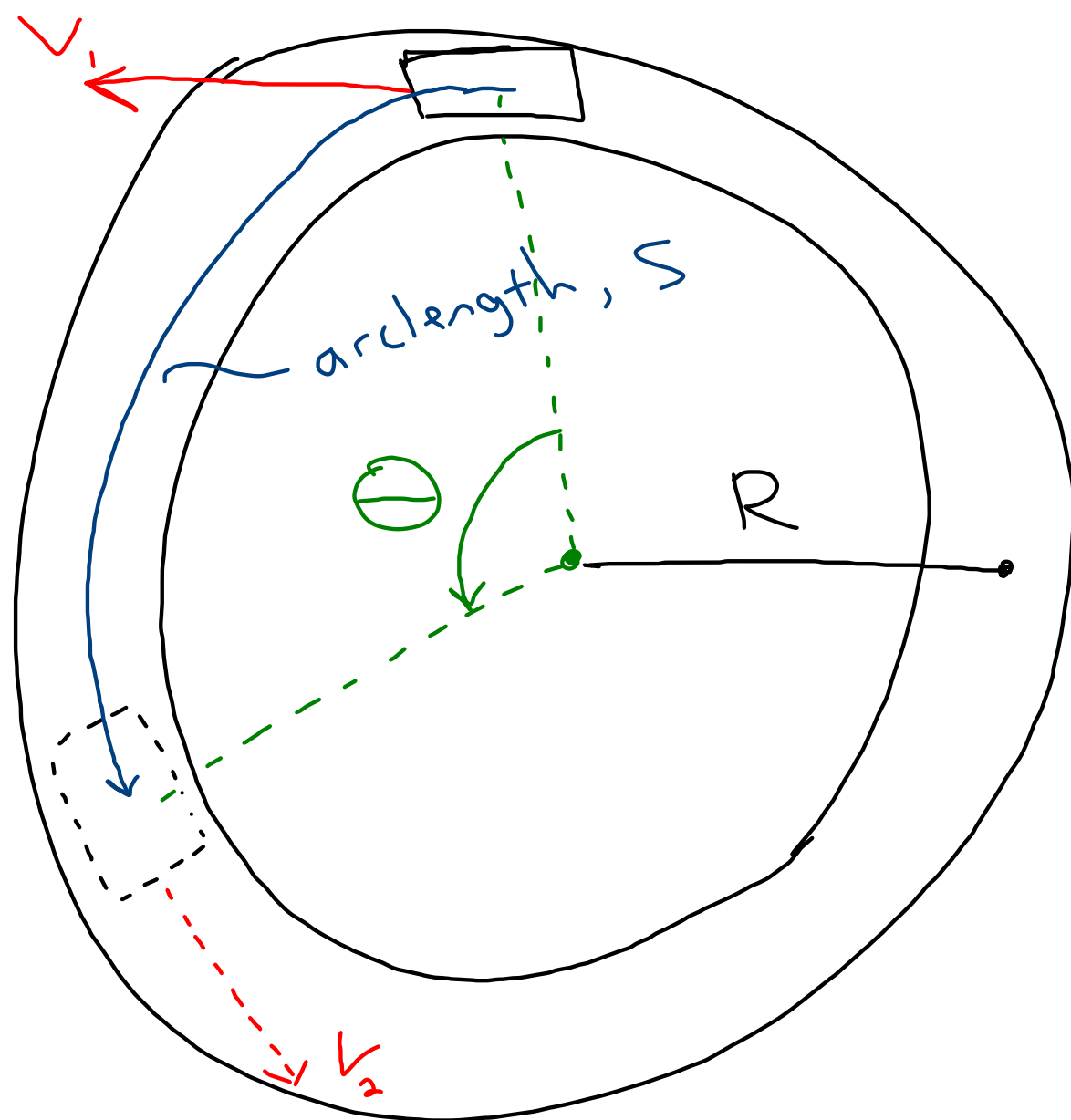


- Find α and ω_f for the wheels.
- Find the number of rotations done by the wheels.

Answers: $\alpha = 4.375 \frac{\text{rad}}{\text{s}^2}$

$$\omega_f = 17.5 \text{ rad/s}$$

$$5.57 \text{ rotations}$$



Aerial
View of
race track

$$S = R \Theta$$

↑ in radians

$$V_T = R \omega$$

$$a_T = R \alpha$$

T = tangential