

07/02/2019

# Advanced Regression SPH024

Lect. 4c: Tree based methods

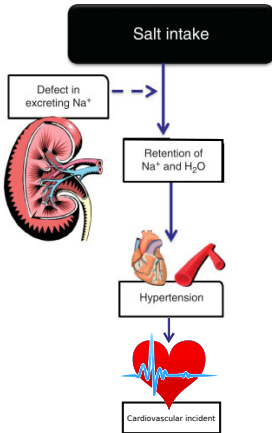
Mentimeter access: [www.menti.com 31 56 08](https://www.menti.com/315608)

## So far

- ① Linear models, OLS, MLE...
- ② Variable importance selection
- ③ High dim. analysis and regularisation
- ④ Mixed effects / hierarchical models
- ⑤ Non-linear models

→ All parametric models: pre-specified relationships between  $X$  and  $Y$

# UKB case study



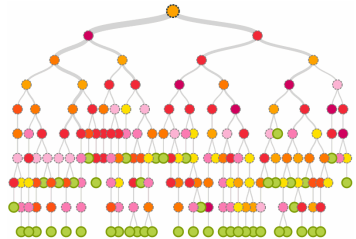
**Case study:** urinary sodium vs CVD in UKBiobank

- Outcomes: Cardiovascular incidents Systolic blood pressure
- Exposure: Na<sup>+</sup>
- Confounders: Age, Sex, K, BMI

# Decision trees



No



Yes

# Decision trees

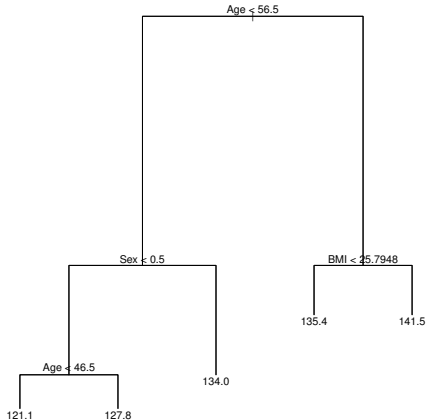
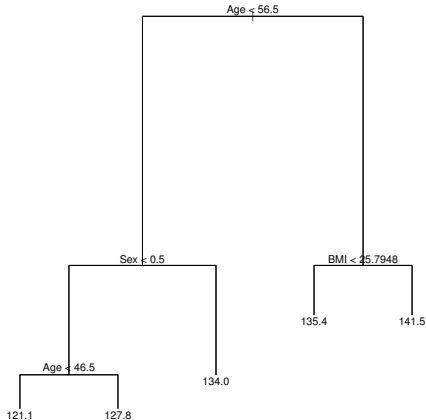


Figure 1: Regression tree on Sys. blood pressure

# Decision trees



Exercise: Interpret this tree

# Decision trees

## Regression trees

- $Y \in \mathbb{R}$ , continuous
- Aim: prediction
- Tree nodes - “leaves” - are discrete  
→ Need to discretise data space
- $\{R_1, R_2, \dots, R_J\}$ : partition of  $X$ ,  $J < n$ 
  - For all  $\{X_i\} \in R_j$ , same prediction  $\hat{Y}_j$
  - Group most similar data points together

$$\{R_1, R_2, \dots, R_J\} = \arg \min \sum_{j=1}^J \sum_{i \in R_j} (y_i - \hat{y}_j)^2$$

# Decision trees

## Regression trees

$$\{R_1, R_2, \dots, R_J\} = \arg \min \sum_{j=1}^J \sum_{i \in R_j} (y_i - \hat{y}_j)^2$$

- Computationally untractable
- Solution: **recursive binary splitting**
  - Recursively cut  $X$  space set in 2



# Decision trees

Recursive binary splitting:

- 1 Split space in 2:

$$R_1(h, s) = \{X | X_h < s\}, R_2(h, s) = \{X | X_h \geq s\}$$

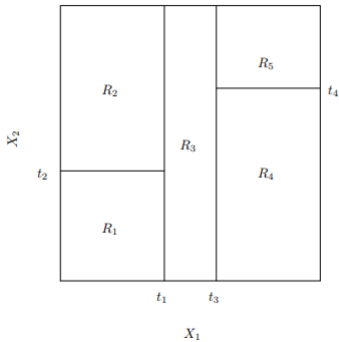
- 2 Minimise RSS:

$$(h^*, s^*) = \arg \min \sum_{i \in R_1(h, s)} (y_i - \hat{y}_1)^2 + \sum_{i \in R_2(h, s)} (y_i - \hat{y}_2)^2$$

- 3 Repeat 1) and 2) within  $R_1$
- 4 Stop when too few observations left

# Decision trees

Draw this tree



# Decision trees

What to do with a tree too big ?

- Overfitting

# Decision trees

What to do with a tree too big ?

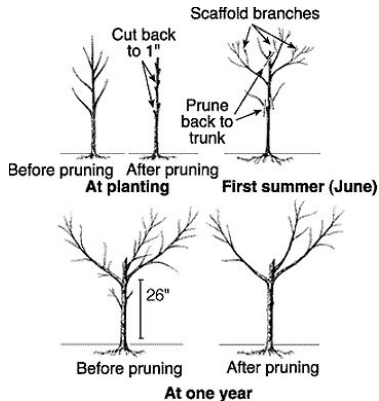
- Overfitting

**Solution: Pruning**

Select optimal sub-tree:

$$\min \sum_{j=1}^{|T|} \sum_{i \in R_j} (y_i - \hat{y}_j)^2 + \alpha |T|$$

$|T|$ : # leaves in resulting tree



# Decision trees

## Classification trees

- $Y \in \{0, 1\}$  **or categorical**  $\in \{1, 2, \dots, K\}$
- **Aim:** prediction
- $\{R_1, R_2, \dots, R_J\}$ : partition of  $X$ ,  $J < n$ 
  - For all  $\{X_i\} \in R_j$ , same **category**  $\bar{Y}_j = k$
  - Group data points with same categories together

$$p_{mk} = \mathbb{P}((X_i, Y_i) \in R_m, \bar{Y}_m = k),$$

$$\min G = \sum_k p_{mk}(1 - p_{mk}) \text{ or } \min H = - \sum_k p_{mk} \log(p_{mk})$$

# Decision trees

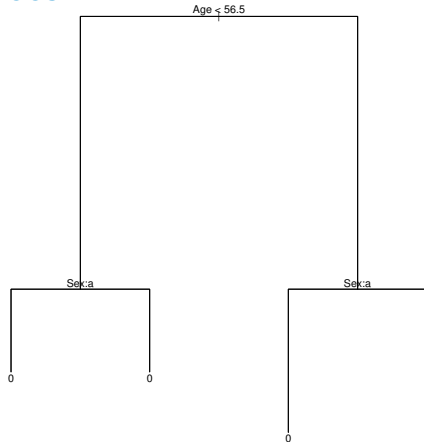


Figure 2: Classification tree on CVD risk

## Decision trees - Limitations

- + Interpretability
- + Graphical representation
- + Qualitative / categorical data
- - Poor prediction ability
- - Highly non-robust
  - slightly diff. tree parameters on the same data = completely diff. results
  - high variance

## Decision trees - Limitations

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**Solution: Aggregate several trees**



# Tree Bagging

Combine several trees together

- 1 Create  $B$  bootstrap samples  $(X^b, Y^b)$ ,  $b \leq B$
- 2 Fit decision trees  $\hat{f}^b$ 
  - prediction / classification:  $\hat{Y}^b = \hat{f}^b(X)$
  - NO pruning
- 3 Average predictions over  $B$  samples:

$$\hat{f}_{bag}(X) = \frac{1}{B} \sum_b \hat{f}^b(X)$$

- 4 New “tree”:  $\hat{Y}_{bag} = \hat{f}_{bag}(X)$

# Boosting

Tree boosting: recursive shrinkage for decision trees.

For  $k \leq K$ , do:

- 1 Fit decision trees  $\hat{f}^k$  with  $d$  leaves only to  $(X_i, \epsilon_{i,k})$ :

$$\hat{f}^{k+1}(X_i) = \hat{f}^{k-1}(X_i) + \lambda \hat{f}^k(X_i)$$

- 2 Update errors

$$\epsilon_{i,k} = Y_i - \hat{f}^k(X_i)$$

Shrinkage parameter  $\lambda$ : learning rate

$d$ : max. depth of trees, fixed

# Random Forests

Bagging of de-correlated trees

- ① Create  $B$  bootstrap samples  $(X^b, Y^b)$ ,  $b \leq B$
- ② Fit decision trees  $\hat{f}^b$ 
  - at every split  $j \leq J$ , optimise over  $m \ll p$  random predictors only:

$$\Omega(m) = \{q | q \in [1, p]\}, |\Omega(m)| = m < p$$

$$\min_{h \in \Omega(m)} \sum_{i \in R_j(h)} (y_i - \hat{y}_j)^2$$

- Often  $m \simeq \sqrt{p}$
- ③ Average predictions:

$$\hat{f}_{bag}(X) = \frac{1}{B} \sum_b \hat{f}^b(X)$$

# Random Forests vs Bagging



Bagging



Random forest

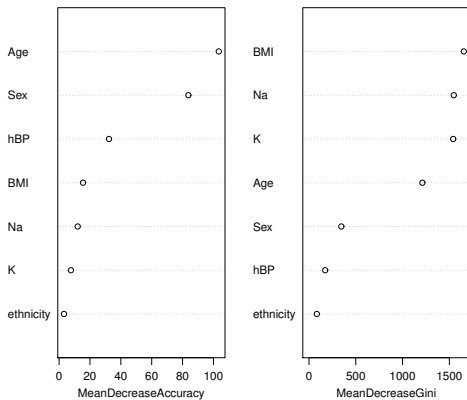
## Variable importance

- Measure how much each variable improves trees' prediction across forest
- Over all nodes  $j \leq J_b$  of all trees  $\hat{f}_1, \hat{f}_2, \dots, \hat{f}_B$ , record decrease in RSS / G or H index over every predictor  $h \leq p$ :

$$i(j) = \text{RSS}(j) - \frac{n_{j+1,1}}{n} \text{RSS}(j+1,1) - \frac{n_{j+1,2}}{n} \text{RSS}(j+1,2)$$
$$\text{Imp}(X_h) = \frac{1}{B} \sum_b \sum_{j \leq J_b, X_h \text{ used}} \frac{n_j}{n} i(j)$$

- “Important” predictors  $X_h$  for  $Y$ : high  $\text{Imp}(X_h)$  values

# Variable Importance



## OOB error estimation

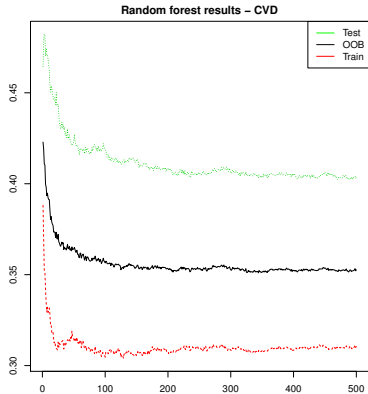
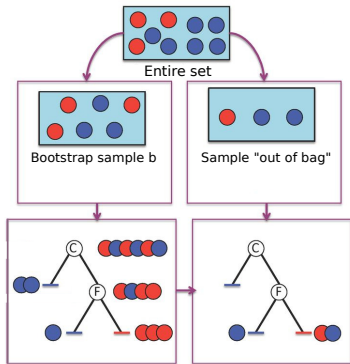
Similar to cross-validation, in bagging / random forests

- $B$  bootstrap samples, with decision tree  $\hat{f}_b$ 
  - No tree  $\hat{f}_b$  uses every observation  $(X_i, Y_i)$ ,  $i \leq n$
  - $OOB_b = \{i \leq n | i \notin b\}$
- Use  $OOB_b$  samples as validation sets:

$$\epsilon(OOB) = \frac{1}{B} \sum_b \sum_{i, i \in OOB_b} RSS(Y_i, \hat{f}_b(X_i))$$

- $\epsilon(OOB)$ : out of bag error

# OOB error estimation





# Important takeaways

- Decision trees
  - Regression & classification
  - Binary splitting
  - Pruning
- Bagging & Random forests
  - Bootstrapping
  - Boosting
  - Variable importance
  - OOB Error estimate