

07/02/2019

Advanced Regression SPH024

Lect. 4c: Tree based methods

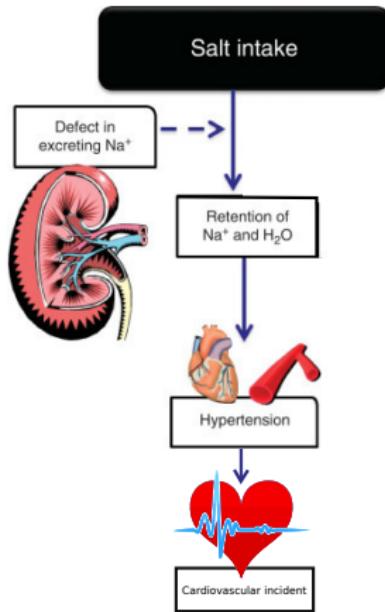
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So far

- ① Linear models, OLS, MLE...
- ② Variable importance selection
- ③ High dim. analysis and regularisation
- ④ Mixed effects / hierarchical models
- ⑤ Non-linear models

→ All parametric models: pre-specified relationships between X and Y

UKB case study



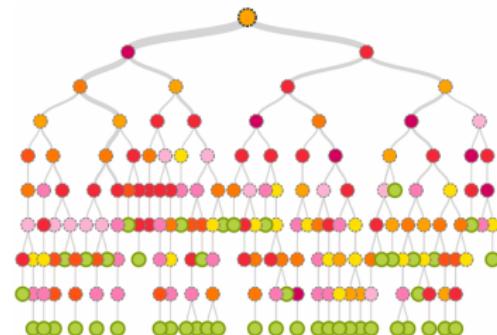
Case study: urinary sodium vs CVD in UKBiobank

- Outcomes: Cardiovascular incidents Systolic blood pressure
- Exposure: Na^+
- Confounders: Age, Sex, K, BMI

Decision trees



No



Yes

Decision trees

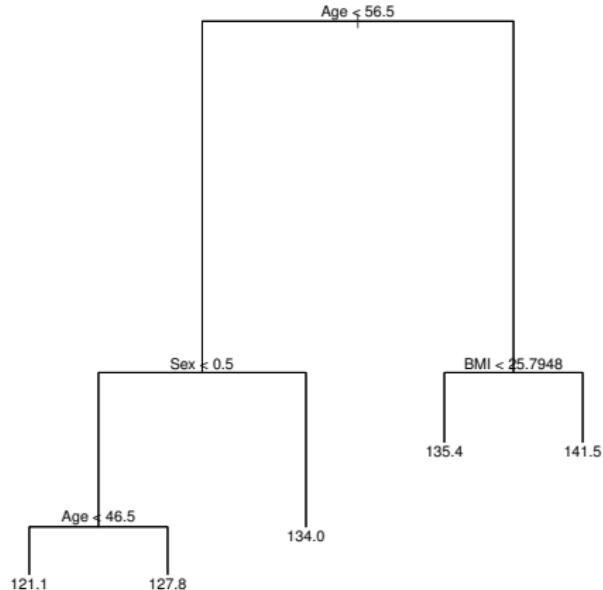
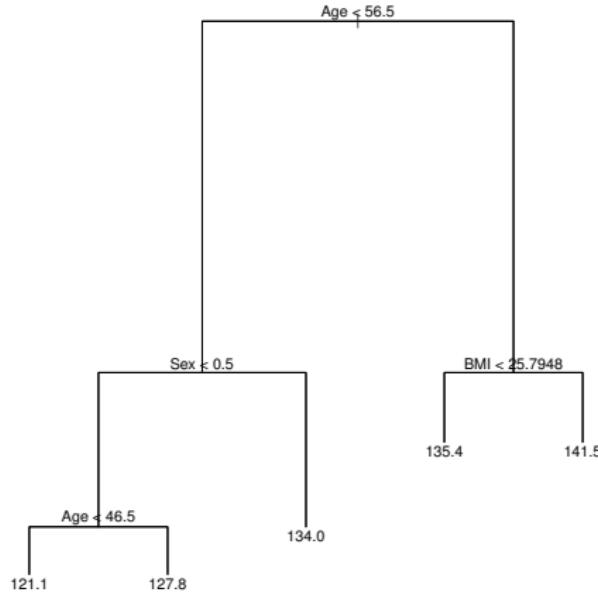


Figure 1: Regression tree on Sys. blood pressure

Decision trees



Exercise: Interpret this tree

Decision trees

Regression trees

- $Y \in \mathbb{R}$, continuous
- Aim: prediction
- Tree nodes - “leaves” - are discrete
→ Need to discretise data space
- $\{R_1, R_2, \dots, R_J\}$: partition of X , $J < n$
 - For all $\{X_i\} \in R_j$, same prediction \hat{Y}_j
 - Group most similar data points together

$$\{R_1, R_2, \dots, R_J\} = \arg \min \sum_{j=1}^J \sum_{i \in R_j} (y_i - \hat{y}_j)^2$$

Decision trees

Regression trees

$$\{R_1, R_2, \dots, R_J\} = \arg \min \sum_{j=1}^J \sum_{i \in R_j} (y_i - \hat{y}_j)^2$$

- Computationally untractable
- Solution: **recursive binary splitting**
 - Recursively cut X space set in 2

Decision trees

Recursive binary splitting:

- ➊ Split space in 2:

$$R_1(h, s) = \{X | X_h < s\}, R_2(h, s) = \{X | X_h \geq s\}$$

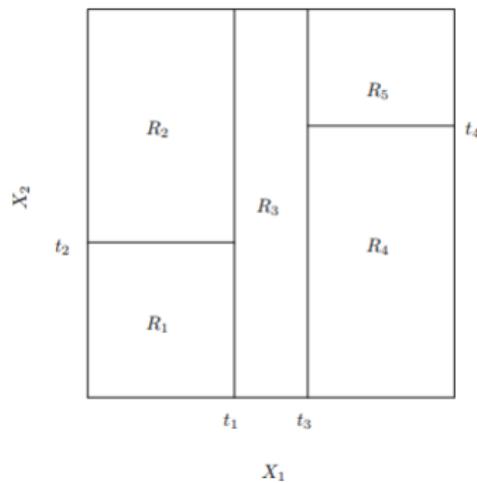
- ➋ Minimise RSS:

$$(h^*, s^*) = \arg \min \sum_{i \in R_1(h, s)} (y_i - \hat{y}_1)^2 + \sum_{i \in R_2(h, s)} (y_i - \hat{y}_2)^2$$

- ➌ Repeat 1) and 2) within R_1
- ➍ Stop when too few observations left

Decision trees

Draw this tree



Decision trees

What to do with a tree too big ?

- Overfitting

Decision trees

What to do with a tree too big ?

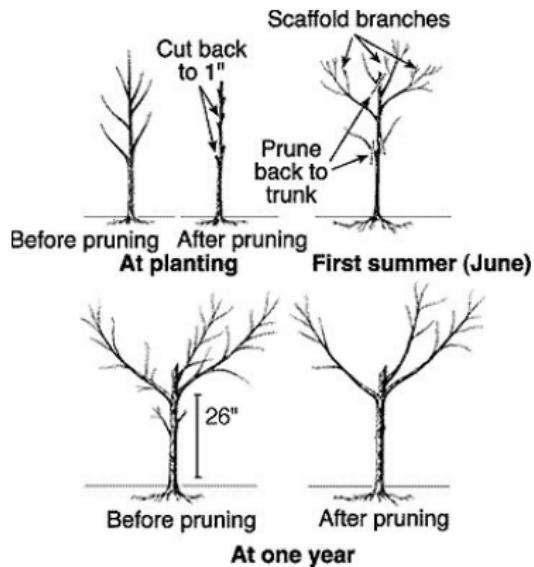
- Overfitting

Solution: Pruning

Select optimal sub-tree:

$$\min \sum_{j=1}^{|T|} \sum_{i \in R_j} (y_i - \hat{y}_j)^2 + \alpha |T|$$

$|T|$: # leaves in resulting tree



Decision trees

Classification trees

- $Y \in \{0, 1\}$ or **categorical** $\in \{1, 2, \dots, K\}$
- Aim: prediction
- $\{R_1, R_2, \dots, R_J\}$: partition of X , $J < n$
 - For all $\{X_i\} \in R_j$, same **category** $\bar{Y}_j = k$
 - Group data points with same categories together

$$p_{mk} = \mathbb{P}((X_i, Y_i) \in R_m, \bar{Y}_m = k),$$

$$\min G = \sum_k p_{mk}(1 - p_{mk}) \text{ or } \min H = - \sum_k p_{mk} \log(p_{mk})$$

Decision trees

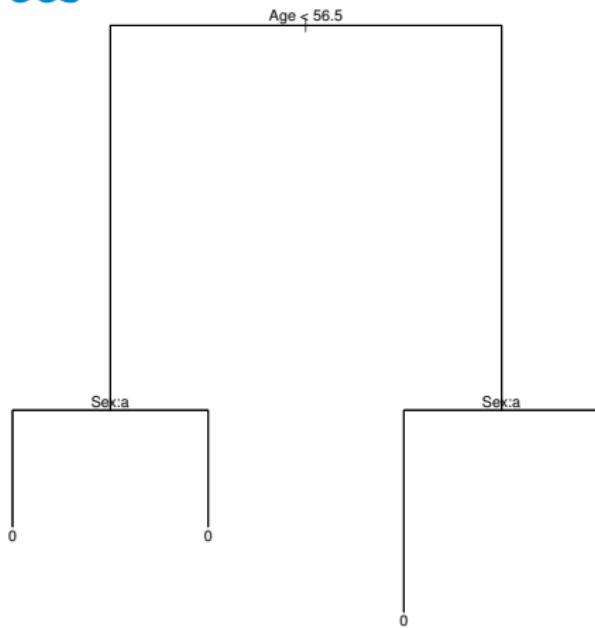


Figure 2: Classification tree on CVD risk

Decision trees - Limitations

- + Interpretability
- + Graphical representation
- + Qualitative / categorical data
- - Poor prediction ability
- - Highly non-robust
 - slightly diff. tree parameters on the same data = completely diff. results
 - high variance

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Solution: Aggregate several trees

Tree Bagging

Combine several trees together

- ① Create B bootstrap samples (X^b, Y^b) , $b \leq B$
- ② Fit decision trees \hat{f}^b
 - prediction / classification: $\hat{Y}^b = \hat{f}^b(X)$
 - NO pruning
- ③ Average predictions over B samples:

$$\hat{f}_{bag}(X) = \frac{1}{B} \sum_b \hat{f}^b(X)$$

- ④ New “tree”: $\hat{Y}_{bag} = \hat{f}_{bag}(X)$

Boosting

Tree boosting: recursive shrinkage for decision trees.

For $k \leq K$, do:

- ① Fit decision trees \hat{f}^k with d leaves only to $(X_i, \epsilon_{i,k})$:

$$\hat{f}^{k+1}(X_i) = \hat{f}^{k-1}(X_i) + \lambda \hat{f}^k(X_i)$$

- ② Update errors

$$\epsilon_{i,k} = Y_i - \hat{f}^k(X_i)$$

Shrinkage parameter λ : learning rate

d : max. depth of trees, fixed

Random Forests

Bagging of de-correlated trees

- ① Create B bootstrap samples (X^b, Y^b) , $b \leq B$
- ② Fit decision trees \hat{f}^b
 - at every split $j \leq J$, optimise over $m \ll p$ random predictors only:

$$\Omega(m) = \{q | q \in [1, p]\}, |\Omega(m)| = m < p$$

$$\min_{h \in \Omega(m)} \sum_{i \in R_j(h)} (y_i - \hat{y}_j)^2$$

- Often $m \simeq \sqrt{p}$
- ③ Average predictions:

$$\hat{f}_{bag}(X) = \frac{1}{B} \sum_b \hat{f}^b(X)$$

Random Forests vs Bagging



Bagging



Random forest

Variable importance

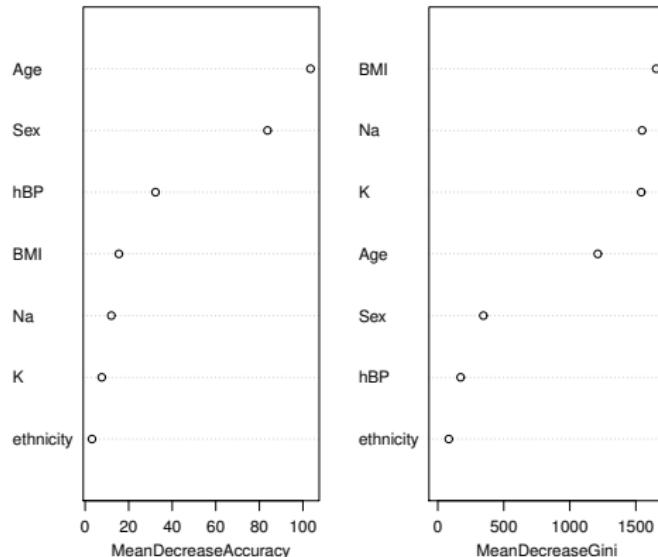
- Measure how much each variable improves trees' prediction across forest
- Over all nodes $j \leq J_b$ of all trees $\hat{f}_1, \hat{f}_2, \dots, \hat{f}_B$, record decrease in RSS / G or H index over every predictor $h \leq p$:

$$i(j) = RSS(j) - \frac{n_{j+1,1}}{n} RSS(j+1,1) - \frac{n_{j+1,2}}{n} RSS(j+1,2)$$

$$Imp(X_h) = \frac{1}{B} \sum_b \sum_{j \leq J_b, X_h \text{ used}} \frac{n_j}{n} i(j)$$

- “Important” predictors X_h for Y : high $Imp(X_h)$ values

Variable Importance



OOB error estimation

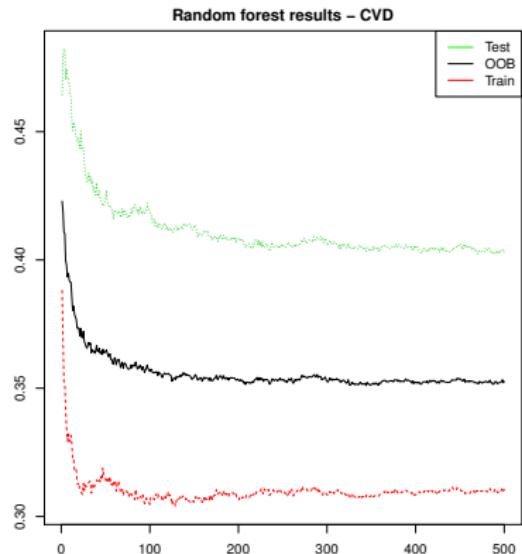
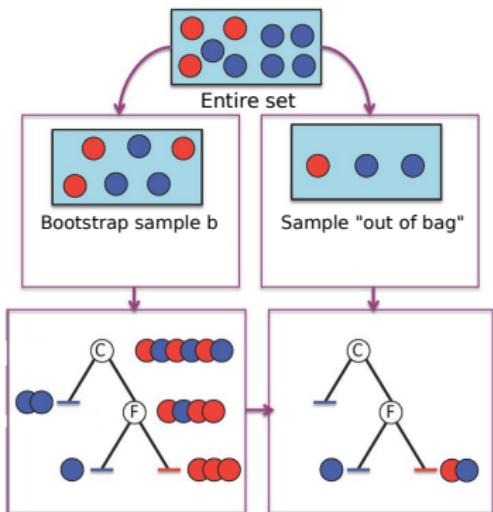
Similar to cross-validation, in bagging / random forests

- B bootstrap samples, with decision tree \hat{f}_b
 - No tree \hat{f}_b uses every observation (X_i, Y_i) , $i \leq n$
 - $OOB_b = \{i \leq n | i \notin b\}$
- Use OOB_b samples as validation sets:

$$\epsilon(OOB) = \frac{1}{B} \sum_b \sum_{i, i \in OOB_b} RSS(Y_i, \hat{f}_b(X_i))$$

- $\epsilon(OOB)$: out of bag error

OOB error estimation



Important takeaways

- Decision trees
 - Regression & classification
 - Binary splitting
 - Pruning
- Bagging & Random forests
 - Bootstrapping
 - Boosting
 - Variable importance
 - OOB Error estimate