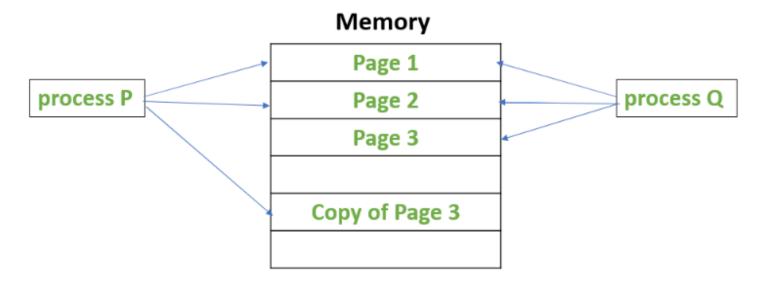
Взаимодействие между процессами

Process ID

```
#include <sys/types.h>
#include <unistd.h>
typedef int pid_t;
pid_t getpid();
pid_t getppid();
uid_t getuid();
gid_t getgid();
$ cat /proc/sys/kernel/pid_max
4194304
fork
fork(2)
#include <unistd.h>
pid_t fork();
Дочерний процесс получает копии:
   • сегмента данных,
   • кучи,
   • стека.
Сегмент кода используется совместно.
Dennis M. Ritchie, The Evolution of the Unix Time-sharing System
#include <stdio.h>
#include <unistd.h>
int globvar = 6;
int main()
    int var;
    pid_t pid;
    var = 88;
    printf("перед вызовом функции fork\n");
    if ((pid = fork()) < 0) {</pre>
        perror("fork");
    } else if (pid == 0) {
        globvar++;
        var++;
    } else {
        sleep(2);
    printf("pid = %ld, globvar = %d, var = %d\n",
        (long)getpid(), globvar, var);
    return 0;
```

Copy-on-write



After process P modifies Page 3

Dirty CoW: CVE-2016-5195

Также наследуются:

- файловые дескрипторы (включая позицию),
- uid и gid,
- идентификаторы группы процессов и сеанса,
- управляющий терминал,
- · cwd и root,
- · umask,
- маска сигналов,
- переменные окружения,
- shared memory,
- отображения в память,
- ограничения на ресурсы.

Различаются:

- pid и ppid,
- значения times(2),
- блокировки файлов (fcntl(2)) сбрасываются,
- таймеры сбрасываются,

0_CL0EXEC in open(2)

• сигналы, ожидающие обработки, очищаются.

exec

```
exec(3)
```

FD_CLOEXEC in fcntl(2)

#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>

vfork

vfork(2)

The vfork() function has the same effect as fork(2), except that the behavior is undefined if the process created by vfork() either modifies any data other than a variable of type pid_t used to store the return value from vfork(), or returns from the function in which vfork() was called, or calls any other function before successfully calling _exit(2) or one of the exec(3) family of functions.

CONFORMING TO: 4.3BSD; POSIX.1-2001 (but marked OBSOLETE). POSIX.1-2008 removes the specification of vfork().

```
int globvar = 6;
int main()
    int var:
    pid_t pid;
    var = 88;
    printf("перед вызовом функции vfork\n");
    if ((pid = vfork()) < 0) {
        perror("fork");
    } else if (pid == 0) {
        globvar++;
        var++;
        exit(0);
    printf("pid = %ld, globvar = %d, var = %d\n",
         (long)getpid(), globvar, var);
    return 0;
}
clone(2), rfork(2)
unshare(2)
posix_spawn(3)
fork() is evil; vfork() is goodness; afork() would be better; clone() is stupid, перевод
system
system(3)
#include <stdlib.h>
int system(const char* cmdstring);
wait
wait(2)
#include <sys/wait.h>
pid_t wait(int* statloc);
pid_t waitpid(pid_t pid, int* statloc, int options);
int waitid(idtype_t idtype, id_t id, siginfo_t* infop, int options);
/* options */
```

```
WNOHANG:
WUNTRACED;
WCONTINUED;
/* status */
WIFEXITED;
WEXITSTATUS;
WIFSIGNALED:
WTERMSIG;
WCOREDUMP:
WIFSTOPPED;
WSTOPSIG:
WIFCONTINUED;
/* idtype */
P_PID;
P_PGID;
P_ALL;
   • Если родительский процесс завершается раньше дочернего, родителем последнего становится init.
   • Если дочерний процесс завершается до того, как родитель вызывает wait или waitpid для его pid, такой процесс
    становится "зомби".
#include <stdlib.h>
#include <sys/types.h>
#include <unistd.h>
int main ()
  pid_t child_pid;
  child_pid = fork ();
  if (child_pid > 0) {
    sleep (60);
  }
  else {
    exit (∅);
  return 0;
}
Изучаем процессы в Linux
Race condition
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
static void charatatime(char *str)
{
    char *ptr;
    int c;
```

setbuf(stdout, NULL);

}

int main()

pid_t pid;

putc(c, stdout);

for (ptr = str; (c = *ptr++) != 0;)

```
if ((pid = fork()) < 0) {</pre>
        perror("fork");
    } else if (pid == 0) {
        charatatime("from child process\n");
        charatatime("from parent process\n");
    exit(0);
Сигналы
```

signal(7)

- null signal: сигнал с номером 0.
- Сигналы, генерируемые терминалом (SIGINT, SIGHUP).
- Аппаратные ошибки (SIGSEGV, SIGBUS).
- Программные ситуации (SIGURG, SIGPIPE, SIGALRM).

```
/* ISO C99 signals. */
#define SIGINT
                              /* Interactive attention signal. */
                       2
#define SIGILL
                       4
                              /* Illegal instruction. */
#define SIGABRT
                              /* Abnormal termination. */
                     6
#define SIGFPE
                      8
                             /* Erroneous arithmetic operation. */
                             /* Invalid access to storage. */
#define SIGSEGV
                      11
#define SIGTERM
                      15
                              /* Termination request. */
/* Historical signals specified by POSIX. */
#define SIGHUP
                1 /* Hangup. */
#define SIGQUIT
                       3
                             /* Quit. */
#define SIGTRAP
                     5
                             /* Trace/breakpoint trap. */
                      9
                             /* Killed. */
#define SIGKILL
#define SIGPIPE
                     13
                              /* Broken pipe.
#define SIGALRM
                      14
                              /* Alarm clock. */
/* Historical signals specified by POSIX. */
#define SIGBUS
                       7
                            /* Bus error. */
#define SIGSYS
                       31
                              /* Bad system call. */
/* New(er) POSIX signals (1003.1-2008, 1003.1-2013). */
#define SIGURG
                       23
                              /* Urgent data is available at a socket. */
#define SIGSTOP
                       19
                              /* Stop, unblockable. */
#define SIGTSTP
                       20
                              /* Keyboard stop. */
#define SIGCONT
                      18
                              /* Continue. */
#define SIGCHLD
                      17
                              /* Child terminated or stopped. */
#define SIGTTIN
                      21
                              /* Background read from control terminal. */
#define SIGTTOU
                      22
                             /* Background write to control terminal. */
                      29
                             /* Pollable event occurred (System V). */
#define SIGPOLL
#define SIGXFSZ
                      25
                              /* File size limit exceeded. */
#define SIGXCPU
                      24
                              /* CPU time limit exceeded. */
#define SIGVTALRM
                      26
                             /* Virtual timer expired. */
                      27
#define SIGPROF
                             /* Profiling timer expired. */
                             /* User-defined signal 1. */
#define SIGUSR1
                      10
                      12
#define SIGUSR2
                             /* User-defined signal 2. */
```

```
void psignal(int sig, const char* msg);
void psiginfo(const siginfo_t *pinfo, const char* msg);
kill(2), raise(3)
```

#include <signal.h>

```
#include <signal.h>
int kill(pid_t pid, int sig);
int raise(int signo);
Default disposition

    Term

   • Ign

    Core

    Stop

    Cont

signal(2)
#include <signal.h>
typedef void (*sighandler_t)(int);
sighandler_t signal(int signum, sighandler_t handler);
/* handler */
SIG_IGN;
SIG_DFL;
#include <stdio.h>
#include <signal.h>
#include <unistd.h>
static void sig_usr(int signo)
    if (signo == SIGUSR1)
        printf("принят сигнал SIGUSR1\n");
    else if (signo == SIGUSR2)
        printf("принят сигнал SIGUSR2\n");
    else
        printf("принят сигнал %d\n", signo);
}
int main()
    if (signal(SIGUSR1, sig_usr) == SIG_ERR)
        perror("signal SIGUSR1");
    if (signal(SIGUSR2, sig_usr) == SIG_ERR)
        perror("signal SIGUSR2");
    for(;;)
        pause();
}
pause(2)
#include <unistd.h>
int pause();
Правила использования сигналов в Unix
О чем нельзя забывать при работе с POSIX-сигналами
```

Прерванные сигналами системные вызовы

signal(7)

If a signal handler is invoked while a system call or library function call is blocked, then either: * the call is automatically restarted after the signal handler returns; or * the call fails with the error EINTR.

```
• read(2), write(2), ioctl(2) on "slow" device: terminal, pipe, socket.

    open(2) if it can block (e.g. for a FIFO).

   wait(2), waitpid(2).

    socket interfaces: accept(2), connect(2), send(2), recv(2).

    flock(2) and fcntl(2).

    POSIX message queue interfaces.

   getrandom(2).
   • pthread_mutex_lock(3), pthread_cond_wait(3) and related.

    POSIX semaphore interfaces.

 read(2) from inotify(7).

again:
    if ((n = read(fd, buf, BUFFSIZE)) < 0) {</pre>
         if (errno == EINTR)
              goto again; /* просто прерванный системный вызов */
                            /* обработать другие возможные ошибки */
}
```

The Rise of Worse is Better by Richard P. Gabriel, перевод

Unix and C are the ultimate computer viruses.

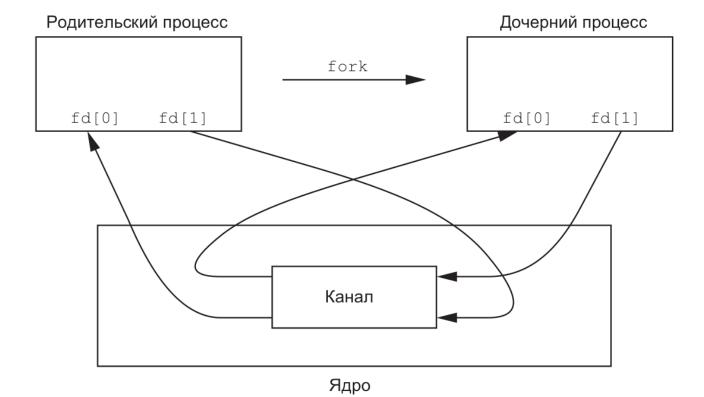
Реентрабельные функции

signal-safety(7)

Fetching and setting the value of errno is async-signal-safe provided that the signal handler saves errno on entry and restores its value before returning.

```
alarm(2)
#include <unistd.h>
unsigned int alarm(unsigned int seconds);
getpwnam(3)
#include <stdio.h>
#include <string.h>
#include <signal.h>
#include <pwd.h>
#include <unistd.h>
static void my_alarm(int signo)
    struct passwd *rootptr;
    printf("внутри обработчика сигнала\n");
    if ((rootptr = getpwnam("root")) == NULL)
        perror("getpwnam");
    alarm(1);
}
static const char* username = "andrew";
int main(void)
    struct passwd* ptr;
    signal(SIGALRM, my_alarm);
    alarm(1);
    for (;;) {
        if ((ptr = getpwnam(username)) == NULL)
            perror("getpwnam");
        if (strcmp(ptr->pw_name, username) != 0)
```

```
printf("возвращаемое значение повреждено! pw_name = %s\n",
                    ptr->pw_name);
    }
}
Маска заблокированных сигналов
#include <signal.h>
int sigemptyset(sigset_t *set);
int sigfillset(sigset_t *set);
int sigaddset(sigset_t *set, int signo);
int sigdelset(sigset_t *set, int signo);
int sigismember(const sigset_t *set, int signo);
sigprocmask(2)
#include <signal.h>
int sigprocmask(int how, const sigset_t* set, sigset_t* oset);
/* how */
SIG_BLOCK;
SIG_UNBLOCK;
SIG_SETMASK;
sigaction
sigaction(2)
#include <signal.h>
int sigaction(int signo, const struct sigaction* act, struct sigaction* oact);
struct sigaction {
    void
          (*sa_handler)(int);
            (*sa_sigaction)(int, siginfo_t *, void *);
    sigset_t sa_mask;
               sa_flags:
};
Межпроцессовые коммуникации
Межпроцессовые коммуникации LINUX
Полудуплексные каналы (ріре)
ls | sort
pipe(2)
#include <unistd.h>
int
pipe(int pipefd[2]);
pipe2(int pipefd[2], int flags);
#define PIPE BUF 4096 /* Linux */
```



```
#include <stdio.h>
#include <unistd.h>
#include <sys/types.h>
int main(void)
          fd[2], nbytes;
  int
          childpid;
 pid_t
 char
          string[] = "Hello, world!\n";
          readbuffer[80];
  char
  pipe(fd);
  if ((childpid = fork()) == -1)
     perror("fork");
     exit(1);
  if (childpid == 0)
     /* Child process closes up input side of pipe */
     close(fd[0]);
     /* Send "string" through the output side of pipe */
     write(fd[1], string, strlen(string));
     exit(0);
  }
 else
    /* Parent process closes up output side of pipe */
    close(fd[1]);
    /* Read in a string from the pipe */
    nbytes = read(fd[0], readbuffer, sizeof(readbuffer));
    printf("Received string: %s", readbuffer);
  return(0);
```

pipe(7)

A pipe has a limited capacity. If the pipe is full, then a write(2) will block or fail, depending on whether the O_NONBLOCK flag is set. Different implementations have different limits for the pipe capacity. Applications should not rely on a particular capacity: an application should be designed so that a reading process consumes data as soon as it is available, so that a writing process does not remain blocked.

Since Linux 2.6.11, the pipe capacity is 16 pages (i.e., 65,536 bytes in a system with a page size of 4096 bytes).

Так все же, насколько быстры каналы в Linux?

Benchmarks for Inter-Process-Communication Techniques

```
popen
popen(3)
#include <stdio.h>
FILE *popen(const char* cmdstring, const char* type);
int pclose(FILE *stream);
Именованные каналы (FIFO)
$ mknod MYFIFO p
mknod(2)
#include <sys/stat.h>
#include <fcntl.h>
#include <unistd.h>
int mknod(const char *pathname, mode_t mode, dev_t dev);
#include <stdio.h>
#include <stdlib.h>
#include <sys/stat.h>
#include <unistd.h>
#include <linux/stat.h>
                        "MYFIFO"
#define FIF0_FILE
int main(void)
  FILE *fp;
  char readbuf[80];
  /* Create the FIFO if it does not exist */
  umask(0);
  mknod(FIF0_FILE, S_IFIF0|0666, 0);
  while(1)
    fp = fopen(FIF0_FILE, "r");
    fgets(readbuf, 80, fp);
    printf("Received string: %s\n", readbuf);
    fclose(fp);
  return(0);
```

UNIX domain sockets

```
#include <sys/socket.h>
int socketpair(int domain, int type, int protocol, int sockfd[2]);
/* Linux, Solaris */
struct sockaddr_un {
    sa_family_t sun_family; /* AF_UNIX */
    char sun_path[108]; /* полное имя */
};
/* FreeBSD, MacOS */
struct sockaddr_un {
    unsigned char sun_len; /* длина адреса сокета */
    sa_family_t sun_family; /* AF_UNIX */
    char sun_path[104]; /* полное имя */
};
#include <stdio.h>
#include <stddef.h>
#include <sys/socket.h>
#include <sys/un.h>
int main()
    int fd, size;
    struct sockaddr_un un;
    un.sun_family = AF_UNIX;
    strcpy(un.sun_path, "foo.socket");
    if ((fd = socket(AF_UNIX, SOCK_STREAM, 0)) < 0)</pre>
        perror("socket");
    size = offsetof(struct sockaddr_un, sun_path) + strlen(un.sun_path);
    if (bind(fd, (struct sockaddr *)&un, size) < 0)</pre>
        perror("bind");
    printf("Done!\n");
    return 0;
}
UDS server
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <sys/socket.h>
#include <sys/un.h>
#include <unistd.h>
#define NAME "echo.socket"
int main()
{
    int sock, msgsock, rval;
    struct sockaddr_un server;
    char buf[1024];
    sock = socket(AF_UNIX, SOCK_STREAM, 0);
```

```
if (sock < 0) {
    perror("opening stream socket");
    exit(1);
}
server.sun_family = AF_UNIX;
strcpy(server.sun_path, NAME);
if (bind(sock, (struct sockaddr *) &server, sizeof(struct sockaddr_un))) {
    perror("binding stream socket");
    exit(1);
printf("Socket has name %s\n", server.sun_path);
listen(sock, 5);
for (;;) {
    msgsock = accept(sock, 0, 0);
    if (msgsock == -1)
        perror("accept");
        break;
    else do {
        bzero(buf, sizeof(buf));
        if ((rval = read(msgsock, buf, 1024)) < 0)
            perror("reading stream message");
        else if (rval == 0)
            printf("Ending connection\n");
        else
            send(msgsock, buf, strlen(buf), 0);
    } while (rval > 0);
    close(msgsock);
close(sock);
unlink(NAME);
```

Windows/WSL Interop with AF_UNIX