

```

/*****
 * Convex Hull
 * *****/
// tested on ACM problem 11065
#include <cstdio>
#include <cmath>
#include <algorithm>
#include <vector>

using namespace std;

class Point {
public:
    int x, y;

    Point () {}
    Point (int _x, int _y) : x(_x), y(_y) {}
};

int ccw(const Point &a, const Point &b, const Point &c) {
    return a.x * (b.y - c.y) + b.x * (c.y - a.y) + c.x * (a.y - b.y);
}

double dist(const Point &a, const Point &b) {
    return sqrt((a.x-b.x)*(a.x-b.x) + (a.y-b.y)*(a.y-b.y));
}

class PointsCmp {
public:
    Point reference;

    bool operator () (const Point &a, const Point &b) {
        int t = ccw(reference, a, b);
        if (t != 0) return t > 0;
        return dist(reference, a) < dist(reference, b);
    }

    PointsCmp(const Point &_reference) : reference(_reference) {}
};

class Polygon {
public:
    vector <Point> points;

    Polygon convexHull() {
        Polygon tmp = *this;

        for (int i = 1; i < tmp.points.size(); ++i) {
            if (tmp.points[i].y < tmp.points[0].y) {
                swap(tmp.points[i], tmp.points[0]);
            }
        }

        sort(tmp.points.begin()+1, tmp.points.end(), PointsCmp(tmp.points[0]));

        Polygon hull;

        if (tmp.size() < 3) {
            return hull;
        }

        hull.points.push_back(tmp.points[0]);
        hull.points.push_back(tmp.points[1]);
        hull.points.push_back(tmp.points[2]);

        int M = hull.points.size();

        for (int i = 3; i < tmp.points.size(); ++i) {
            while (ccw(hull.points[M-2], hull.points[M-1], tmp.points[i]) < 0) {
                hull.points.pop_back();
                --M;
            }
            hull.points.push_back(tmp.points[i]);
            ++M;
        }

        return hull;
    }

    double area() {

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        int retval = 0.0;
        for (int i = 0; i < points.size(); ++i) {
            retval += points[i].x * points[(i+1) % points.size()].y - points[(i+1) % points.size(
        )].x * points[i].y;
        }

        return ((retval < 0) ? -retval : retval) / 2.0;
    }

    void output() {
        for (int i = 0; i < points.size(); ++i) {
            printf("(%d, %d) ", points[i].x, points[i].y);
        }
        printf("\n");
    }
};

```

Polygon P;

```

bool load() {
    int n;
    scanf("%d", &n);
    P.points.resize(n);

    for (int i = 0; i < n; ++i) {
        scanf("%d%d", &P.points[i].x, &P.points[i].y);
    }

    return n;
}

```

```

/*****
 *      Hungarian
 * *****/

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// tested on ACM ICPC live problem 3198

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#include <cstdio>
#include <vector>
#include <algorithm>
#include <cmath>
#include <queue>

```

using namespace std;

```

#define MAX_R 100 // mora biti >= MAX_C
#define MAX_C 100
#define VELIKO 1000000

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bool zero(int x) { return x == 0; }
bool zero(double x) { return fabs(x) < 1e-12; }

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template <typename tip>

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struct hungarian {
    int n, m;
    tip costs[MAX_R][MAX_C]; // pocente vrijednosti NE OSTAJU ocuvane
    bool ret[MAX_R][MAX_C]; // na kraju, jedinice su matching
    int stars;
    int star_r[MAX_R], star_c[MAX_C];
    int prime_r[MAX_R], prime_c[MAX_C];
    int cover_r[MAX_R], cover_c[MAX_C];

    void matching() {
        for ( ; n < m; ++n)
            for (int c = 0; c < m; ++c)
                costs[n][c] = 0;
        for (int r = 0; r < n; ++r) { star_r[r] = -1; cover_r[r] = 0; }
        for (int c = 0; c < m; ++c) { star_c[c] = -1; cover_c[c] = 0; }
        stars = 0;
        step1();
    }

    void step1() {
        for (int r = 0; r < n; ++r) {
            tip mini = VELIKO;
            for (int c = 0; c < m; ++c) mini = min(mini, costs[r][c]);
            for (int c = 0; c < m; ++c) costs[r][c] -= mini;
        }
        step2();
    }

    void step2() {

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    for (int r = 0; r < n; ++r) {
        for (int c = 0; c < m; ++c) {
            if (star_c[c] != -1) continue;
            if (!zero(costs[r][c])) continue;
            star_r[r] = c;
            star_c[c] = r;
            ++stars;
            break;
        }
    }
    step3();
}

void step3() {
    if (stars == m) {
        for (int r = 0; r < n; ++r)
            for (int c = 0; c < m; ++c)
                ret[r][c] = (star_r[r] == c);
        return; // zavrsetak algoritma
    }
    for (int r = 0; r < n; ++r) cover_r[r] = 0;
    for (int c = 0; c < m; ++c) cover_c[c] = star_c[c] != -1;

    step4();
}

void step4() {
    queue <int> Q;
    for (int c = 0; c < m; ++c) if (!cover_c[c]) Q.push(c);

    for (; !Q.empty(); Q.pop()) {
        int c = Q.front();
        for (int r = 0; r < n; ++r) {
            if (cover_r[r]) continue;
            if (!zero(costs[r][c])) continue;
            if (star_r[r] != -1) {
                cover_c[star_r[r]] = 0;
                cover_r[r] = 1;
                prime_r[r] = c;
                prime_c[c] = r;
                Q.push(star_r[r]);
            } else {
                step5(r, c);
                return;
            }
        }
    }
    tip mini = VELIKO;
    for (int r = 0; r < n; ++r) {
        if (!cover_r[r])
            for (int c = 0; c < m; ++c)
                if (!cover_c[c])
                    mini = min(mini, costs[r][c]);
    }
    step6(mini);
}

void step5(int r, int c) {
    while (star_c[c] != -1) {
        int tmp_r = star_c[c];
        star_r[r] = c;
        star_c[c] = r;
        c = prime_r[tmp_r];
        r = tmp_r;
    }
    star_r[r] = c;
    star_c[c] = r;
    stars++;
    step3();
}

void step6(tip mini) {
    for (int r = 0; r < n; ++r)
        for (int c = 0; c < m; ++c)
            if (cover_r[r] && cover_c[c]) costs[r][c] += mini;
            else if (!cover_r[r] && !cover_c[c]) costs[r][c] -= mini;

    step4();
}

};

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char ploc[100][100];
int N, M;

bool load() {
    scanf("%d%d", &N, &M);

    for (int i = 0; i < N; ++i) {
        scanf("%s", ploc[i]);
    }

    return N+M;
}

int my_abs(int x) { return x < 0 ? -x : x; }
int dist(pair<int, int> a, pair<int, int> b) {
    return my_abs(a.first - b.first) + my_abs(a.second - b.second);
}
vector<pair<int, int>> houses, men;

void generate_costs() {
    houses.clear(); men.clear();

    for (int i = 0; i < N; ++i) {
        for (int j = 0; j < M; ++j) {
            if (ploc[i][j] == 'H') houses.push_back(make_pair(i, j));
            if (ploc[i][j] == 'm') men.push_back(make_pair(i, j));
        }
    }

    H.n = H.m = houses.size();
    for (int i = 0; i < houses.size(); ++i) {
        for (int j = 0; j < men.size(); ++j) {
            H.costs[i][j] = dist(houses[i], men[j]);
        }
    }
}

/*****
 *      KMP
 * *****/
// c/p from Zagreb
#define MAXP 1000
#define MAXT 1000

int pi[MAXP+1];
char T[MAXT+1]; int n;
char P[MAXP+1]; int m;

void compute_prefix_function() {
    pi[1] = 0;
    int k = 0;
    for (int q = 2; q <= m; ++q) {
        while (k > 0 && P[k] != P[q-1]) k = pi[k];
        if (P[k] == P[q-1]) ++k;
        pi[q] = k;
    }
}

void KMP_matcher() {
    int q = 0;

    for (int i = 1; i <= n; ++i) {
        while (q > 0 && P[q] != T[i-1]) q = pi[q];
        if (P[q] == T[i-1]) ++q;
        if (q == m) {
            // we found pattern with shift i-m
            q = pi[q];
        }
    }
}

/*****
 *      Matching
 * *****/
#include <cstdio>
#include <vector>

using namespace std;

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vector <vector <int> > E;
vector <int> connectedF, bio;

int dfs(int s) {
    if (bio[s]) return 0;
    bio[s] = 1;

    for (int i = 0; i < E[s].size(); ++i) {
        if (connectedF[E[s][i]] == s) continue;
        if (connectedF[E[s][i]] == -1 || dfs(connectedF[E[s][i]])) {
            connectedF[E[s][i]] = 1;
            return 1;
        }
    }

    return 0;
}

int matching() {
    int sol = 0;
    bio.resize(hor.size());
    connectedF.resize(vert.size());
    fill(connectedF.begin(), connectedF.end(), -1);

    for (int i = 0; i < hor.size(); ++i) {
        fill(bio.begin(), bio.end(), 0);
        sol += dfs(i);
    }

    return sol;
}

/*****
 *      Min cost max flow
 * *****/
// from WA library
#include <iostream>
#include <algorithm>
#include <queue>

using namespace std;

const int N = 205, INF = 100000000;
// cost[i][j] == cost[j][i] always!
int graph[N][N], cost[N][N], reduced_cost[N][N];
int potential[N], prev[N], source = N - 1, sink = N - 2;

void reduce_cost() {
    for (int i = 0; i < N; i++)
        for (int j = 0; j < N; j++)
            if (graph[i][j] >= 0)
                reduced_cost[i][j] += potential[i] - potential[j];
}

typedef pair<int, int> pii;

int dijkstra() {
    reduce_cost();

    fill(potential, potential + N, 2 * INF);
    fill(prev, prev + N, -1);
    priority_queue<pii, vector<pii>, greater<pii> > pq;

    pq.push(pii(0, source));
    potential[source] = 0;

    while (!pq.empty()) {
        pii v = pq.top(); pq.pop();
        int c = v.first, curr = v.second;

        if (potential[curr] < c) continue;

        for (int next = 0; next < N; next++) {
            if (graph[curr][next] <= 0) continue;
            if (potential[next] <= c + reduced_cost[curr][next]) continue;
            potential[next] = c + reduced_cost[curr][next];
            prev[next] = curr;
            pq.push(pii(potential[next], next));
        }
    }
}

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    }
    return potential[sink];
}

int update(int& v) {
    int ret = INF;
    for (int c = sink, p = prev[c]; c != source; c = p, p = prev[c])
        ret = min(ret, graph[p][c]);
    for (int c = sink, p = prev[c]; c != source; c = p, p = prev[c])
        v += cost[p][c] * ret, graph[p][c] -= ret, graph[c][p] += ret;
    return ret;
}

int min_cost_max_flow(int& c) {
    int flow = 0; c = 0;

    fill(potential, potential + N, INF);
    copy(cost[0], cost[N], reduced_cost[0]);
    potential[source] = 0;
    for (int k = 0; k < N; k++)
        for (int i = 0; i < N; i++)
            for (int j = 0; j < N; j++)
                if (graph[i][j] > 0)
                    potential[j] = min(potential[j], potential[i] + cost[i][j]);

    while (dijkstra() < INF) flow += update(c);
    return flow;
}

/*****
 *      Network flow
 *      *****/
// tested on 11082 ACM problem
#include <cstdio>
#include <cstring>
#include <cstdlib>
#include <queue>
#define INF 0x3f3f3f

using namespace std;

int cap[42][42];
int how[42], ff[42];

int bfs(int source, int sink) {
    memset(how, -1, sizeof how);
    memset(ff, 0, sizeof ff);
    how[source] = source;
    ff[source] = INF;

    queue<int> Q;
    Q.push(source);

    while (Q.size()) {
        int s = Q.front(); Q.pop();

        if (s == sink) break;

        for (int i = 0; i < 42; ++i) {
            if (cap[s][i] != 0 && how[i] == -1) {
                ff[i] = min(ff[s], cap[s][i]);
                how[i] = s;
                Q.push(i);
            }
        }
    }

    return ff[sink];
}

void flow(int source, int sink) {
    int maxflow = 0;
    for (int f = 0; f = bfs(source, sink); maxflow += f) {
        for (int s = sink; s != source; s = how[s]) {
            cap[how[s]][s] -= f;
            cap[s][how[s]] += f;
        }
    }
}

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    }
}

/*****
 *      Number theory
 * *****/
// WA library.
// CRT NOT TESTED
// extended gcd works
#include <cmath>
#include <cstdlib>
#include <cstdio>
#include <algorithm>

using namespace std;

ldiv_t div_correct(long y, long x) {
    ldiv_t v = ldiv(y, x);
    if (y < 0 && v.rem != 0) {
        v.quot -= 1;
        v.rem += labs(x);
    }
    return v;
}

pair<long, long> extended_gcd(long a, long b) {
    if (a % b == 0)
        return pair<long, long>(0, 1);
    else {
        ldiv_t v = div_correct(a, b);
        pair<long, long> t = extended_gcd(b, v.rem);
        return pair<long, long>(t.second, t.first - t.second * v.quot);
    }
}

long crt(long *a, long *n, long r)
{
    long N = 1;
    for (int k = 0; k < r; k++)
        N *= n[k];

    long s = 0;
    for (int k = 0; k < r; k++)
    {
        long p = N / n[k];
        long x = extended_gcd(p, n[k]).first;
        s += a[k] * p * x;
        s %= N;
    }
    return s;
}

int main() {
    long A, B;
    while (scanf("%ld%ld", &A, &B) != EOF) {
        pair<long, long> xy = extended_gcd(A, B);
        printf("%ld %ld %ld\n", xy.first, xy.second, A * xy.first + B * xy.second);
    }
}

/*****
 *      SCC
 * *****/
// Tested on 11504
#include <cstdio>
#include <cstring>
#include <vector>
#define MAX 100000

using namespace std;

vector <vector <int> > E;
int on_stack[MAX], visited[MAX], component[MAX];
int num_components;
int global_time;
vector <int> node_stack;

void load() {
    int n, m;
    scanf("%d%d", &n, &m);
    E.clear();

```

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E.resize(n);

for (int i = 0; i < m; ++i) {
    int a, b;
    scanf("%d%d", &a, &b);
    E[a-1].push_back(b-1);
}

}

int dfs(int s) {
    int lowlink = visited[s] = global_time++;
    node_stack.push_back(s);
    on_stack[s] = 1;

    for (int i = 0; i < E[s].size(); ++i) {
        if (!visited[E[s][i]]) {
            lowlink = min(lowlink, dfs(E[s][i]));
        } else if (on_stack[E[s][i]]) {
            lowlink = min(lowlink, visited[E[s][i]]);
        }
    }

    if (lowlink == visited[s]) {
        // s defines new component consisting of nodes on stack
        ++num_components;
        while (true) {
            int t = node_stack.back();
            component[node_stack.back()] = num_components;
            on_stack[node_stack.back()] = 0;
            node_stack.pop_back();
            if (t == s) break;
        }
    }

    return lowlink;
}

/*****
 *      Tournament tree
 *      *****/
// NOT YET TESTED
// igor's new code
// supports:
// * find minimum in a range
// * change an element
#include <cstdio>
#include <algorithm>
#define MAXN 1000000
#define INF 0x3f3f3f3f

using namespace std;

int tournament[2*MAXN + 1];
int tt_size;
int A[MAXN];

void tt_create(int n) {
    for (tt_size = 1; tt_size < n; tt_size *= 2);

    for (int i = tt_size; i < tt_size*2; ++i) {
        if (i-tt_size < n) tournament[i] = A[i-tt_size];
        else tournament[i] = INF;
    }
    for (int i = tt_size - 1; i >= 1; --i) {
        tournament[i] = min(tournament[2*i], tournament[2*i+1]);
    }
}

int tt_change(int index, int new_value) {
    tournament[tt_size + index] = new_value;

    for (int i = tt_size + index; i >= 1; i /= 2) {
        tournament[i] = min(tournament[2*i], tournament[2*i+1]);
    }
}

// [from, to> [lo, hi>
int _tt_query(int from, int to, int p, int lo, int hi) {
    if (to <= lo || from >= hi) return INF;
    if (from <= lo && to >= hi) return tournament[p];

```



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    return min(_tt_query(from, to, 2*p, lo, (lo+hi)/2), _tt_query(from, to, 2*p + 1, (lo+hi)/2, hi));
}

int tt_query(int from, int to) {
    return _tt_query(from, to, 1, 0, tt_size);
}
/*****
 *      Union find
 * *****/
// NOT TESTED YET
// C/P from Univ of Zagreb library
#include <stdio>
#define MAXN 1000000
#define NOT_CONNECTED 0
#define CONNECTED 1
#define ALREADY_CONNECTED 2

int dad[MAXN], rank[MAXN];
// int kids[MAXN]; // if we want to find largest componenet

int union_find(int a, int b, bool connect = true) {
    int topa, topb;
    int newtop;

    for (topa = a; topa != dad[topa]; topa = dad[topa]);
    for (topb = b; topb != dad[topb]; topb = dad[topb]);
    dad[a] = topa; dad[b] = topb;

    if (topa != topb && connect) {
        if (rank[topa] > rank[topb]) {
            // kids[topa] += kids[topb];
            dad[topb] = newtop = topa;
        } else {
            // kids[topb] += kids[topa];
            dad[topa] = newtop = topb;
            if (rank[topa] == rank[topb]) rank[topb]++;
        }

        int x;
        for ( ; a != topa; ) x = dad[a], dad[a] = newtop, a = x;
        for ( ; b != topb; ) x = dad[b], dad[b] = newtop, b = x;

        return CONNECTED;
    } else {
        int x;
        for ( ; a != topa; ) x = dad[a], dad[a] = topa, a = x;
        for ( ; b != topb; ) x = dad[b], dad[b] = topb, b = x;

        return connect || topa == topb ? ALREADY_CONNECTED : NOT_CONNECTED;
    }
}

void union_find_init(int n) {
    for (int i = 0; i < n; ++i) {
        dad[i] = i;
        rank[i] = 0;
        // kids[i] = 1;
    }
}

```