

IESTI01-Laboratório 2-Keyword Spotting

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1 Introdução

O objetivo do projeto é indentificar as palavras:

- Pato
- Tobias

Além disso , o modelo de Machine Learning também indentifica o som ambiente como "Environment". O dataset foi gravado a partir do Kit TinyML utilizando o microcontrolador Arduino Nano 33 BLE Sense e plataforma Edge Impulse para as etapas de:

- Pré-processamento do dataset
- Dvisão do dataset em treinamento e teste
- Definição do modelo de rede neural
- Treinamento do modelo
- Teste do modelo
- Otimização para reduzir espaço de memória
- Deploy do modelo Arduino Nano 33 BLE Sense

2 Desenvolvimento

O primeiro passo foi gravar áudios à uma taxa de amostragem de 16 kHz em amostras de 10 segundos. Utilizando a ferramenta de divisão de amostras do Edge Impulse, dividir em amostras de 1 segundo e separar em "Treinamento" e "Teste".

Após a curagem do dataset foi definido o modelo de o bloco de processamento MFCC (Mel Frequency Cepstral Coefficient), que é o recomendado para modelos utilizando voz, e em seguida gerar os features que irão fazer a classificação das entradas.

O modelo de Rede Neural escolhido foi o de classificação utilizando a biblioteca Keras. O design pode ser visto na imagem a seguir:

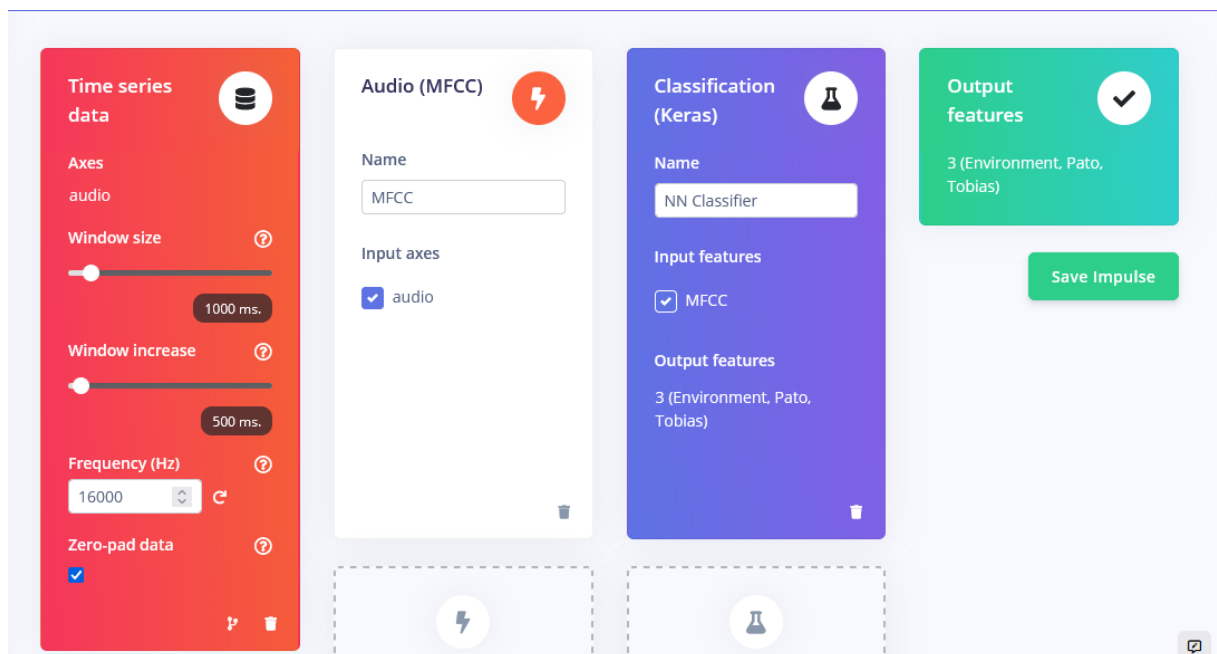


Imagem 1 - Impulse design

Em seguida foram definidos os parâmetros para o processamento do dataset para gerar os features:

Parameters

Mel Frequency Cepstral Coefficients

Number of coefficients

13

Frame length

0.02

Frame stride

0.02

Filter number

32

FFT length

256

Normalization window size

101

Low frequency

300

High frequency

Click to set

Pre-emphasis

Coefficient

0.98

Shift

1

Imagem 2 - Parameters

Por fim é definido a quantidade de ciclos para treinamento, o Learning rate e a arquitetura da Rede Neural. O Edge Impulse também oferece a opção de data augmentation para o enriquecimento do dataset.

Neural Network settings

Training settings

Number of training cycles ?

100

Learning rate ?

0.005

Audio training options

Data augmentation ?

☐

Imagem 3 - Training settings



Imagem 4 - Architecture

O modelo então é treinado e resulta em Accuracy = 92.5% com Loss = 0.79

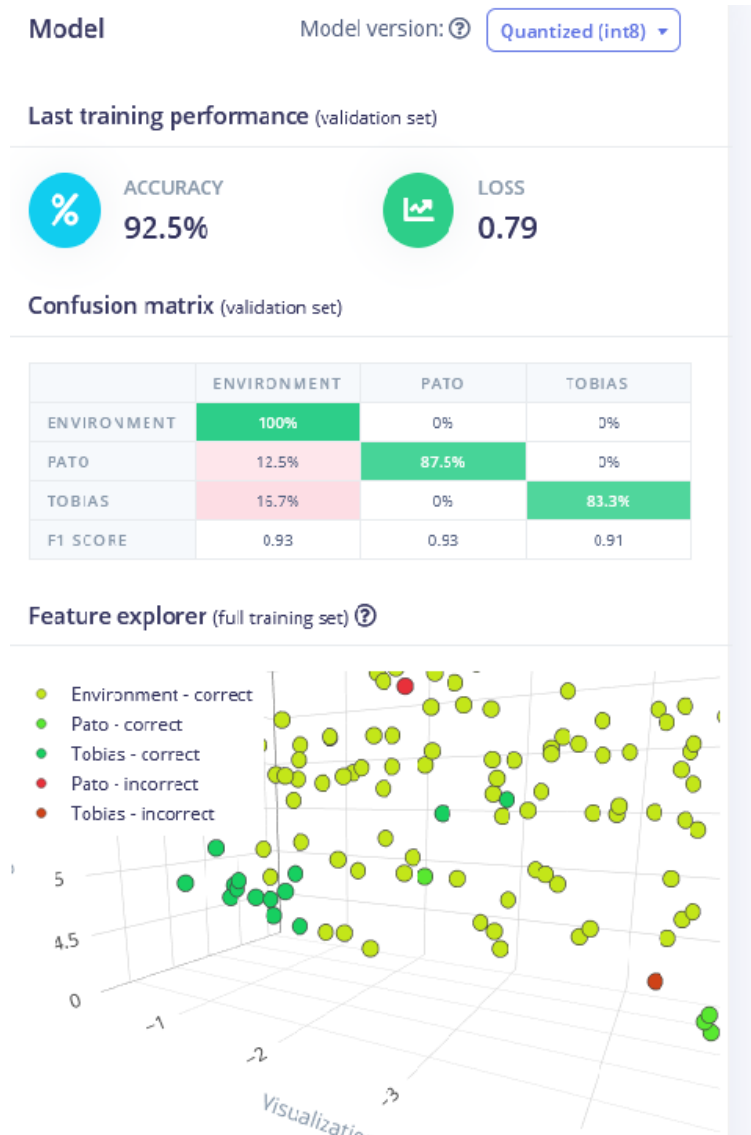


Imagem 5 - Model

É feito o teste a partir do dataset de teste e finalmente o deploy do modelo na placa Arduino Nano 33 BLE Sense. Para o deploy geramos uma biblioteca do modelo e, a partir de um código feito pela própria Edge Impulse para análise contínua de amostras de áudio do microfone, o sistema é implementado na placa. O último passo é implementar a ação de ligar determinada cor do Led conforme o resultado da classificação.

3 Código

```
1
3 * Edge Impulse Arduino examples
  * Copyright (c) 2021 EdgeImpulse Inc.
5 *
  * Permission is hereby granted, free of charge, to any person obtaining a
  copy
7 * of this software and associated documentation files (the "Software"), to
  deal
  * in the Software without restriction, including without limitation the
  rights
9 * to use, copy, modify, merge, publish, distribute, sublicense, and/or
  sell
  * copies of the Software, and to permit persons to whom the Software is
11 * furnished to do so, subject to the following conditions:
  *
13 * The above copyright notice and this permission notice shall be included
  in
  * all copies or substantial portions of the Software.
15 *
  * THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS
  OR
17 * IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY,
  * FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL
  THE
19 * AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER
  * LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING
  FROM,
21 * OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS
  IN THE
  * SOFTWARE.
23 */

25 // If your target is limited in memory remove this macro to save 10K RAM
#define EIDSP_QUANTIZE_FILTERBANK 0
27
  /**
29 * Define the number of slices per model window. E.g. a model window of
  1000 ms
  * with slices per model window set to 4. Results in a slice size of 250 ms
  .
31 * For more info: https://docs.edgeimpulse.com/docs/continuous-audio-sampling
```

```

    */
33 #define EI_CLASSIFIER_SLICES_PER_MODEL_WINDOW 3

35 /* Includes
    _____ */

#include <PDM.h>
37 #include <IESTIO1_Key_Word_Spotting-1.0.2_inferencing.h>

39 /** Audio buffers, pointers and selectors */
typedef struct {
41     signed short *buffers[2];
43     unsigned char buf_select;
45     unsigned char buf_ready;
47     unsigned int buf_count;
49     unsigned int n_samples;
51 } inference_t;

static inference_t inference;
static bool record_ready = false;
static signed short *sampleBuffer;
51 static bool debug_nn = false; // Set this to true to see e.g. features
    generated from the raw signal
static int print_results = -(EI_CLASSIFIER_SLICES_PER_MODEL_WINDOW);

53 /**
55  * @brief      Arduino setup function
57  */
void setup()
{
59     // put your setup code here, to run once:
    Serial.begin(115200);

61     Serial.println("Edge Impulse Inferencing Demo");

63     //Setup leds
    pinMode(LED_BUILTIN, OUTPUT);
65     pinMode(LED_R, OUTPUT);
67     pinMode(LED_G, OUTPUT);
69     pinMode(LED_B, OUTPUT);

71     //ensure the LED is off by default
    digitalWrite(LED_BUILTIN, LOW);

73     digitalWrite(LED_R, HIGH);
75     digitalWrite(LED_G, HIGH);
    digitalWrite(LED_B, HIGH);

    // summary of inferencing settings (from model_metadata.h)

```



```

77 ei_printf("Inferencing settings:\n");
ei_printf("\tInterval: %.2f ms.\n", (float)ELCLASSIFIER_INTERVAL_MS);
79 ei_printf("\tFrame size: %d\n", ELCLASSIFIER_DSP_INPUT_FRAME_SIZE);
ei_printf("\tSample length: %d ms.\n", ELCLASSIFIER_RAW_SAMPLE_COUNT /
16);
81 ei_printf("\tNo. of classes: %d\n", sizeof(
ei_classifier_inferencing_categories) /
sizeof(
ei_classifier_inferencing_categories
[0]));

83
run_classifier_init();
85 if (microphone_inference_start(ELCLASSIFIER_SLICE_SIZE) == false) {
ei_printf("ERR: Failed to setup audio sampling\r\n");
87 return;
}
89 }

91 void turn_off_leds() {
digitalWrite(LED_R, HIGH);
93 digitalWrite(LED_G, HIGH);
digitalWrite(LED_B, HIGH);
95 }

97 void turn_on_leds(int pred_index) {
switch(pred_index)
99 {
case 0:
101 turn_off_leds();
digitalWrite(LED_G, LOW);
103 break;

105 case 1:
turn_off_leds();
107 digitalWrite(LED_R, LOW);
break;

109 case 2:
turn_off_leds();
111 digitalWrite(LED_B, LOW);
113 break;

115 }
}
117

/**
119 * @brief Arduino main function. Runs the inferencing loop.

```

```

121  */
122  void loop()
123  {
124      bool m = microphone_inference_record();
125      if (!m) {
126          ei_printf("ERR: Failed to record audio...\n");
127          return;
128      }
129
130      signal_t signal;
131      signal.total_length = ELCLASSIFIER_SLICE_SIZE;
132      signal.get_data = &microphone_audio_signal_get_data;
133      ei_impulse_result_t result = {0};
134
135      ELIMPULSE_ERROR r = run_classifier_continuous(&signal, &result,
136          debug_nn);
137      if (r != ELIMPULSE_OK) {
138          ei_printf("ERR: Failed to run classifier (%d)\n", r);
139          return;
140      }
141
142      if (++print_results >= (ELCLASSIFIER_SLICES_PER_MODEL_WINDOW)) {
143          // print the predictions
144          ei_printf("Predictions ");
145          ei_printf("(DSP: %d ms., Classification: %d ms., Anomaly: %d ms.)",
146              result.timing.dsp, result.timing.classification, result.timing.
147              anomaly);
148          ei_printf(": \n");
149          for (size_t ix = 0; ix < ELCLASSIFIER_LABEL_COUNT; ix++) {
150              ei_printf("    %s: %.5f\n", result.classification[ix].label,
151                  result.classification[ix].value);
152          }
153          int pred_index = 0;
154          float pred_value = result.classification[0].value;
155
156          for (size_t ix = 0; ix < ELCLASSIFIER_LABEL_COUNT; ix++) {
157              ei_printf("    %s: %.5f\n", result.classification[ix].label, result
158                  .classification[ix].value);
159              if (result.classification[ix].value > pred_value){
160                  pred_index = ix;
161                  pred_value = result.classification[ix].value;
162              }
163          }
164          ei_printf(" Prediction: %s with probability %.2f\n", result.
165              classification[pred_index].label, pred_value);
166          turn_on_leds(pred_index);
167          #if ELCLASSIFIER_HAS_ANOMALY == 1

```

```

163         ei_printf("    anomaly score: %.3f\n", result.anomaly);
164     #endif
165
166     print_results = 0;
167 }
168 }
169
170 /**
171  * @brief      Printf function uses vsnprintf and output using Arduino
172  *             Serial
173  *
174  * @param[in]  format      Variable argument list
175  */
176 void ei_printf(const char *format, ...) {
177     static char print_buf[1024] = { 0 };
178
179     va_list args;
180     va_start(args, format);
181     int r = vsnprintf(print_buf, sizeof(print_buf), format, args);
182     va_end(args);
183
184     if (r > 0) {
185         Serial.write(print_buf);
186     }
187 }
188
189 /**
190  * @brief      PDM buffer full callback
191  *
192  *             Get data and call audio thread callback
193  */
194 static void pdm_data_ready_inference_callback(void)
195 {
196     int bytesAvailable = PDM.available();
197
198     // read into the sample buffer
199     int bytesRead = PDM.read((char *)&sampleBuffer[0], bytesAvailable);
200
201     if (record_ready == true) {
202         for (int i = 0; i < bytesRead; i++) {
203             inference.buffers[inference.buf_select][inference.buf_count++]
204                 = sampleBuffer[i];
205
206             if (inference.buf_count >= inference.n_samples) {
207                 inference.buf_select ^= 1;
208                 inference.buf_count = 0;
209                 inference.buf_ready = 1;
210             }
211         }
212     }
213 }

```

```

    }
209 }
}
211
/**
213  * @brief      Init inferencing struct and setup/start PDM
    *
215  * @param[in]  n_samples  The n samples
    *
217  * @return     { description_of_the_return_value }
    */
219 static bool microphone_inference_start(uint32_t n_samples)
{
221     inference.buffers[0] = (signed short *)malloc(n_samples * sizeof(signed
        short));

223     if (inference.buffers[0] == NULL) {
        return false;
225     }

227     inference.buffers[1] = (signed short *)malloc(n_samples * sizeof(signed
        short));

229     if (inference.buffers[1] == NULL) {
        free(inference.buffers[0]);
231         return false;
    }

233     sampleBuffer = (signed short *)malloc((n_samples >> 1) * sizeof(signed
        short));

235     if (sampleBuffer == NULL) {
        free(inference.buffers[0]);
237         free(inference.buffers[1]);
239         return false;
    }

241     inference.buf_select = 0;
243     inference.buf_count = 0;
    inference.n_samples = n_samples;
245     inference.buf_ready = 0;

247     // configure the data receive callback
    PDM.onReceive(&pdm_data_ready_inference_callback);

249     PDM.setBufferSize((n_samples >> 1) * sizeof(int16_t));
251

```

```

253 // initialize PDM with:
254 // - one channel (mono mode)
255 // - a 16 kHz sample rate
256 if (!PDM.begin(1, EI_CLASSIFIER_FREQUENCY)) {
257     ei_printf("Failed to start PDM!");
258 }
259
260 // set the gain, defaults to 20
261 PDM.setGain(127);
262
263 record_ready = true;
264
265 return true;
266 }
267
268 /**
269  * @brief      Wait on new data
270  *
271  * @return     True when finished
272  */
273 static bool microphone_inference_record(void)
274 {
275     bool ret = true;
276
277     if (inference.buf_ready == 1) {
278         ei_printf(
279             "Error sample buffer overrun. Decrease the number of slices per
280             model window "
281             "(EI_CLASSIFIER_SLICES_PER_MODEL_WINDOW)\n");
282         ret = false;
283     }
284
285     while (inference.buf_ready == 0) {
286         delay(1);
287     }
288
289     inference.buf_ready = 0;
290
291     return ret;
292 }
293
294 /**
295  * Get raw audio signal data
296  */
297 static int microphone_audio_signal_get_data(size_t offset, size_t length,
298     float *out_ptr)
299 {

```

```

297     numpy::int16_to_float(&inference.buffers[inference.buf_select ^ 1][
        offset], out_ptr, length);

299     return 0;
}

301 /**
303  * @brief      Stop PDM and release buffers
304  */
305 static void microphone_inference_end(void)
306 {
307     PDM.end();
308     free(inference.buffers[0]);
309     free(inference.buffers[1]);
310     free(sampleBuffer);
311 }

313 #if !defined(EL_CLASSIFIER_SENSOR) || EL_CLASSIFIER_SENSOR !=
    EL_CLASSIFIER_SENSOR_MICROPHONE
314 #error "Invalid model for current sensor."
315 #endif

```

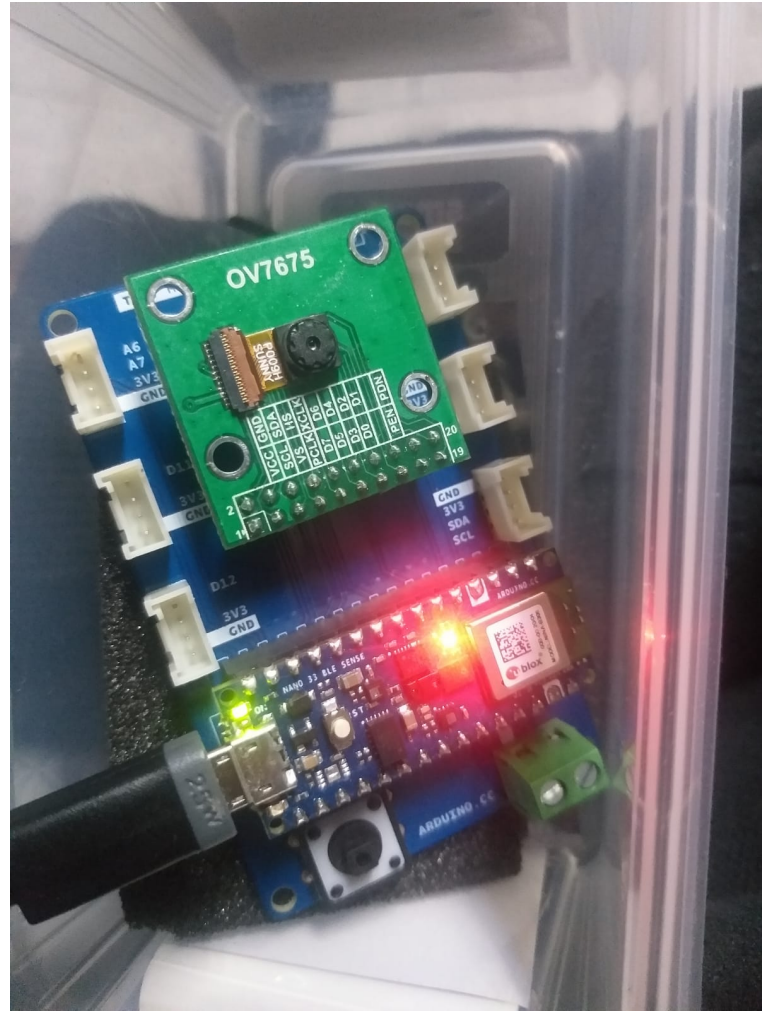


Imagem 6 -Pato



Imagem 7 - Tobias



Imagem 8 - Environment

4 Conclusão

Fazendo os testes é possível constatar que o modelo funciona, porém para aumentar a confiabilidade e evitar falsos positivos é interessante expandir o dataset com outras palavras.