

Mecânica Aplicada I

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Turma:1

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1 Exercício 1 (Aceleração angular da fig 1.15)

1)

$${}^R \alpha^{R''} = {}^R \alpha^{R'} + {}^{R'} \alpha^{R''} + {}^R \omega^{R'} \times {}^{R'} \omega^{R''}$$

$${}^R \omega^{R'} = \omega_2 \mathbf{e}_2$$

$${}^{R'} \omega^{R''} = \omega_3 \mathbf{e}_3$$

$${}^R \omega^{R'} \times {}^{R'} \omega^{R''} = \omega_2 \cdot \omega_3 \cdot \mathbf{e}_1$$

$${}^R \alpha^{R''} = 0 + 0 + \omega_2 \mathbf{e}_2 \times \omega_3 \mathbf{e}_3 = \omega_2 \cdot \omega_3 \mathbf{e}_1$$

2 Exercício 2 (Exercício 3 da pag 28

$$2) \frac{x^2}{9} + \frac{y^2}{4} = 1, \quad \dot{x} = 2 \text{ cm/s} \quad \ddot{x} = 1,5 \frac{\text{cm}}{\text{s}^2}$$

$$\vec{OP} = x\hat{i} + y\hat{j}, \text{ sendo } \frac{x^2}{9} + \frac{y^2}{4} = 1$$

$$y = \left(1 - \frac{x^2}{9}\right)^{1/2} \cdot 2$$

$$\vec{OP} = x\hat{i} + 2\left(1 - \frac{x^2}{9}\right)^{1/2}\hat{j}, \text{ no } x = 1$$

$$\vec{OP} = 1\hat{i} + \frac{4\sqrt{2}}{3}\hat{j}$$

2) Inveniente 2 Velocidade

$${}^R V^P = \frac{d \vec{OP}}{dt} = \dot{x} \hat{i} + 2 \frac{1}{2} \cdot \left(1 - \frac{x^2}{9}\right)^{-1/2} \cdot \frac{2x \cdot \dot{x}}{9} \hat{j}$$

$$x = 1 \text{ e } \dot{x} = 2$$

$${}^R V^P = 2 \hat{i} - \frac{2 \cdot 2}{3 \cdot 9 \cdot 2 \sqrt{2}} \hat{j} = 2 \hat{i} - \frac{2 \sqrt{2}}{3 \cdot 2} \hat{j}$$

$${}^R V^P = \left(2 \hat{i} - \frac{\sqrt{2}}{3} \hat{j} \right) \text{ cm/s}$$

2) Exercício 2 aceleração

$$R a^P = R \frac{dV^P}{dt} =$$

$$\ddot{x} i + \frac{1}{3} \left(-\frac{1}{6} (9-x^2)^{-3/2} \cdot (-2x) \cdot \dot{x} \cdot (-2x) \ddot{x} + (9-x^2)^{-1/2} \cdot (-2) \dot{x}^2 + (9-x^2)^{-1/2} \cdot (-2x) \cdot \ddot{x} \right) j$$

$$x = 1 \text{ e } \dot{x} = 2, \ddot{x} = 1,5$$

$$R a^P = 1,5 i + \frac{1}{3} \left(-\frac{1}{2} \cdot 8^{-3/2} \cdot (-2) \cdot 2 \cdot (-2) \cdot 2 + 8^{-1/2} \cdot (-2) \cdot 4 + 8^{-1/2} \cdot (-2) \cdot 1,5 \right) j$$

$$R a^P = 1,5 i + \frac{1}{3} 12 \frac{\sqrt{2}}{4} = \left(1,5 i + \sqrt{2} j \right) \text{ cm/s}^2$$

3 Exercício 3 (Exercício 7 da pagina 33)

3) em $t=0$, $v_0=0$, $x_0=0$, $a = -kv$, $a = -kv^2$

$$a) dv = a \cdot dt$$

$$dv = -kv^2$$

$$\frac{dv}{v^2} = -k dt$$

$$\int_{v_0}^v \frac{dv}{v^2} = -k \int_0^t dt$$

$$-\frac{1}{v} \Big|_{v_0}^v = -k t \Big|_0^t$$

$$-\frac{1}{v} + \frac{1}{v_0} = -kt$$

$$v = \frac{1}{[kt + (1/v_0)]}$$

$$b) dx = v dt$$

$$dx = dt / [kt + (1/v_0)]$$

$$\int_0^x dx = \int_0^t \frac{dt}{[kt + (1/v_0)]}$$

$$x = \ln \left(kt + \frac{1}{v_0} \right)^{1/k}$$

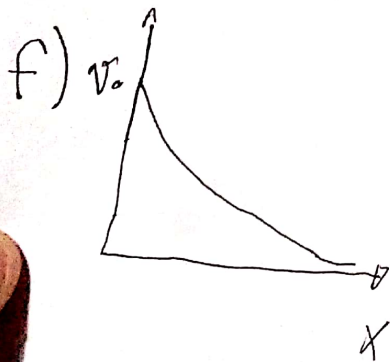
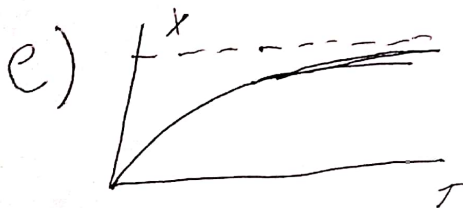
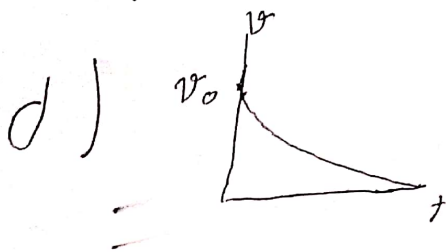
$$3) \quad c) \quad v dv = a dx$$

$$v dv = -k v^2 dx$$

$$\frac{dv}{v} = -k dx$$

$$\ln v = kx$$

$$v = e^{-kx}$$



4 Exercício 4 (Exercício 8 da página 34)

4) $R_a^p = -kVi$, k constante positiva, $x=0$

a) $d\vec{v} = a dt$
 $d\vec{v} = -k\vec{v} dt$

$\frac{d\vec{v}}{\vec{v}} = -k dt$
 $\vec{v} = v_0 e^{-kt}$

c) $\vec{v} d\vec{v} = a dx$
 $\vec{v} d\vec{v} = -k\vec{v} dx$

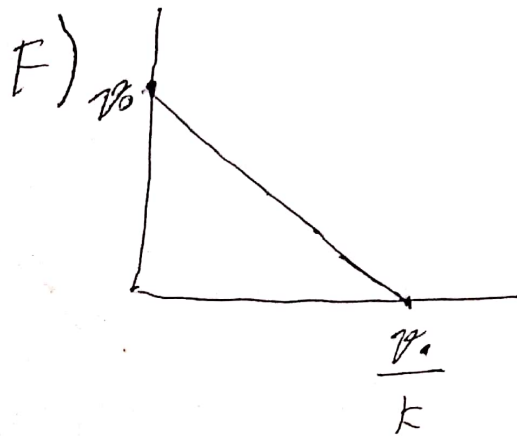
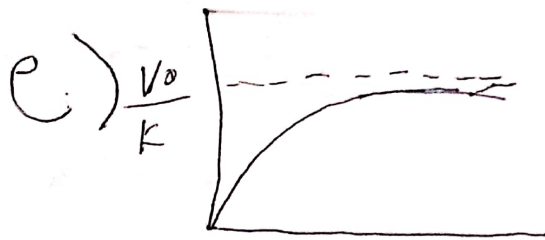
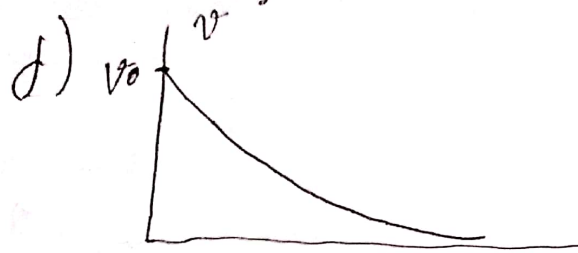
$d\vec{v} = -k dx$
 $\int_{v_0}^{\vec{v}} d\vec{v} = -k \int_0^x dx$
 $\vec{v} = v_0 - kx$

b) $dx = \vec{v} dt$
 $dx = v_0 e^{-kt} dt$

$\int_0^x dx = v_0 \int_0^t e^{-kt} dt$

$x = \frac{v_0}{k} (1 - e^{-kt})$

Questão 4)



5 Exercício 5 (Exercício 5 da pagina 47)

$$5) \quad \vec{V} = V_0 \sin \theta \vec{e}_r + V_0 \cos \theta \vec{e}_\theta = \dot{r} \vec{e}_r + \dot{r} \theta \cdot \vec{e}_\theta$$

$$\frac{b \dot{\theta}}{\cos \theta} = V_0 \cos \theta$$

$$\dot{\theta} = \frac{V_0 \cos^2 \theta}{b}$$

$$\dot{\theta} = \frac{V_0 2 \cos \theta (-\sin \theta)}{b} \dot{\theta} = -\frac{2 V_0 \cos \theta \sin \theta}{b}$$

$$\left(\frac{V_0}{b} \cos^2 \theta \right) = \frac{-2 V_0^2}{b^2} \cos^3 \theta \sin \theta = \dot{\theta}$$

$$\frac{-2 V_0^2}{b^2} \cos^3 \theta \sin \theta = \dot{\theta}$$

6 Exercício 6 (Exercício 8 da página 49)

$$c) \rho = b(1 + \cos \phi) \quad \vec{OP} = \rho \hat{j} \\ \vec{OP} = b(1 + \cos \phi) \hat{j}$$

$$\rho + \theta = 90^\circ; \quad \cos \phi = \sin \theta$$

$$\boxed{\vec{OP} = b(1 + \sin \theta) \hat{j}}$$

$$\frac{d\vec{OP}}{d\theta} = b \dot{\theta} \cos \theta; \quad \boxed{\vec{V} = b \dot{\theta} \cos \theta \hat{j}}$$

$$\frac{d\vec{V}}{d\theta} = (b \ddot{\theta} \cos \theta - b \dot{\theta}^2 \sin \theta) \hat{j}$$

$$\boxed{\vec{a} = b(\ddot{\theta} \cos \theta - \dot{\theta}^2 \sin \theta) \hat{j}}$$

7 Exercício 7 (Exercício 9 da página 50)

$$7) \quad \vec{O}P = r \hat{i} \quad \vec{O}^vP = b \phi \hat{i}$$

$$\theta + \phi = 360^\circ \quad \theta + \phi = 2\pi$$

$$\phi = 2\pi - \theta$$

$$\vec{O}P = (2\pi - \theta) b \hat{i}$$

$$v^P = \frac{d\vec{O}P}{d\theta}$$

$$a^P = \frac{dv^P}{d\theta}$$

$$v^P = -b \dot{\theta} \hat{i}$$

$$a^P = -b \ddot{\theta} \hat{i}$$