



#### Computer Vision 6

# **Object Detection (Lab)**



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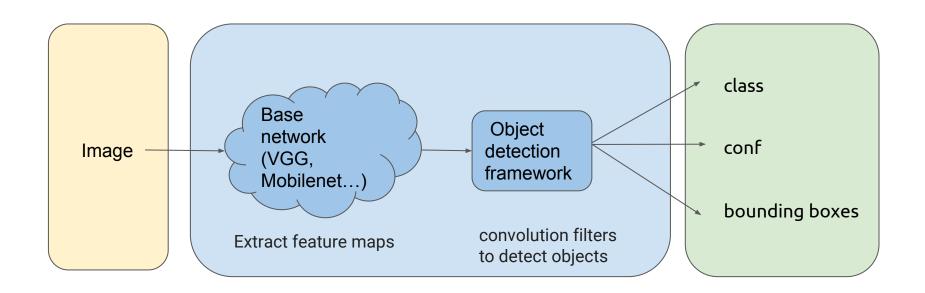
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## SSD: Single Shot Multibox Detector

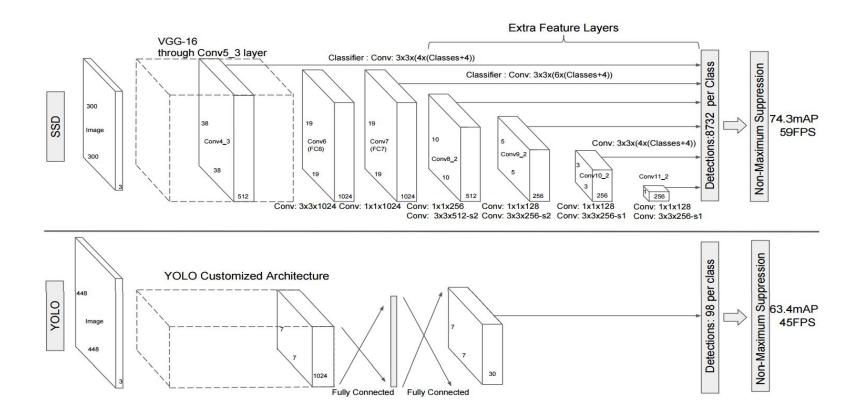
SSD is designed to be **independent of the base network**, and so it can run on top of pretty much any feature extractor.



### What is new?

Other detectors make predictions for only a single feature map while SSD **combines predictions** across multiple feature maps at different sizes.

### What is new?



### Losses

- Cross entropy (softmax) for **classification**
- Smooth L1 for localization

### **Dataset**

- Pascal VOC 2007 (20 classes)
- Annotations:

[xmin, ymin, xmax, ymax, one hot encoded classes]

### Prior boxes

We need a set of prior boxes.

The annotations are "encoded" using this prior boxes.

This "encoded" annotations and the images will be the input to our network.

(The prior boxes that do not match with any ground truth bounding box are labeled as background)



# The Lab



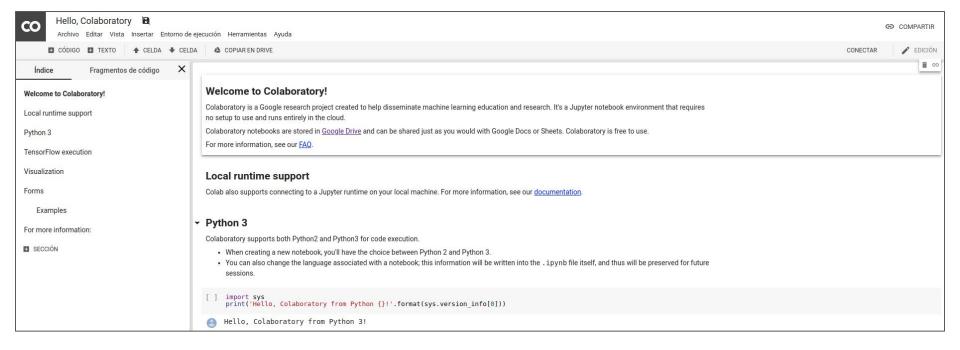
# Today's objectives

- Learn how to use SSD to detect objects.
- See the different steps that SSD requires for training and inference.
- Test SSD network loading weights





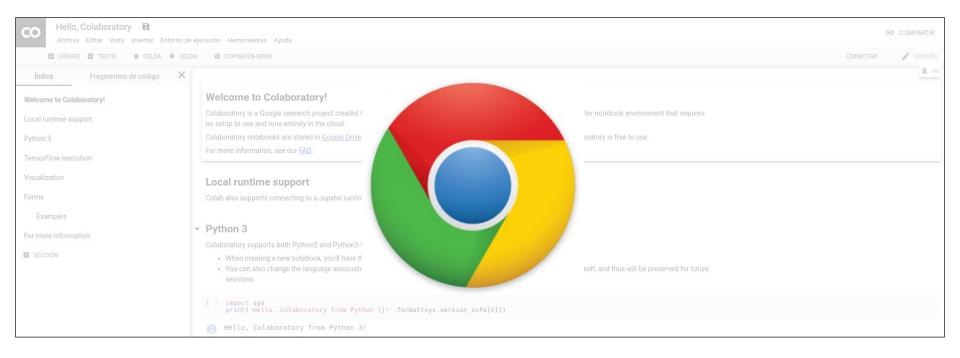
## Google Colab



https://colab.research.google.com/



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### Lab



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## UPC

## Google Colab

- Login in <u>Colab</u> with a Google account: yours or <u>aidlupc2019@gmail.com</u> (talentcenter)
- 2. Open the notebook of this lab session
- Copy this notebook to your Drive to be able to run it (or open in draft mode if using <u>aidlupc2019@gmail.com</u>)
- 4. Change runtime type to work with GPU! Your trainings will be much faster :)

