

# Frobenius Theorem

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# Chapter 1

## Introduction

This project aims to really formalize the Frobenius Theorem from differential geometry in Lean 4.

## Chapter 2

# Frobenius Theorem

Consider a smooth manifold  $M$  of dimension  $m$ . For local questions we can take  $M = \mathbb{R}^m$ , which could correspond to a chart around some point  $x_0 \in M$ . All functions, vector fields and differential forms are presumed to be smooth ( $C^\infty$ ).

**Definition 1** (involutivity). Let  $L_i = \sum_{k=1}^m f_i^k(x) \partial / \partial x^k$ ,  $i = 1, \dots, r \leq m$ , be first order differential operators, such that the vector fields  $v_i(x) = (f_i^k(x))_{k=1}^m$  are linearly independent. They are said to be in *involution* when there exist functions  $c_{ij}^k(x)$  such that

$$L_i L_j - L_j L_i = \sum_{k=1}^r c_{ij}^k(x) L_k.$$

**Theorem 2** (local Frobenius). *If the first order differential operators  $L_i$ ,  $i = 1, \dots, r \leq m$ , are in involution, then there exist  $m - r$  smooth functions  $u^k(x)$  that satisfy the equations  $L_i u^k(x) = 0$  and such that their gradients  $\nabla u^k(x)$ ,  $k = 1, \dots, m - r$  are linearly independent.*

*Proof.* This proof consists of chaining together several intermediate results, which are proven in separate lemmas below.

The first step is to replace the  $L_i$  operators by some better behaved operators  $L'_i$ , namely satisfying  $[L'_i, L'_j] = 0$  (Lem. 5(e)) and having a form adapted to a split local coordinate system  $(y, z)$  around  $x_0$ . The equations  $L'_i u = 0$  and  $L_i u = 0$  are equivalent (Lem. 3, 4). Lem. 7 shows that there exists a new local coordinate system  $(y, \bar{Z})$  on a neighborhood of  $x_0$ , where  $\bar{Z}^k = \bar{Z}^k(y, z)$ , which is better adapted to our differential equations. Lem. 6 actually shows that the constructed coordinates give us the desired solutions via  $u^k(x) = \bar{Z}^k(y(x), z(x))$ .  $\square$

**Lemma 3.** *If the  $L_i$  as in Def. 1 are in involution, then the  $L'_i = \sum_{i=1}^r \alpha_i^i L_i$ ,  $i' = 1, \dots, r$ , with smooth pointwise invertible  $\alpha_i^i$ , are also in involution.*

*Proof.* It is sufficient to compute the commutator

$$\begin{aligned} L'_i L'_{j'} - L'_{j'} L'_i &= \alpha_i^i \alpha_{j'}^{j'} (L_i L_{j'} - L_{j'} L_i) + \alpha_i^i L_i (\alpha_{j'}^{j'}) L_{j'} - \alpha_{j'}^{j'} L_{j'} (\alpha_i^i) L_i \\ &= \alpha_i^i \alpha_{j'}^{j'} \left( c_{ij}^k + (\alpha^{-1})_j^{j'} L_i (\alpha_{j'}^j) \delta_j^k - (\alpha^{-1})_i^{i'} L_{j'} (\alpha_i^i) \delta_i^k \right) L_k \\ &= \alpha_i^i \alpha_{j'}^{j'} \left( c_{ij}^k + (\alpha^{-1})_j^{j'} L_i (\alpha_{j'}^j) \delta_j^k - (\alpha^{-1})_i^{i'} L_{j'} (\alpha_i^i) \delta_i^k \right) (\alpha^{-1})_k^{k'} L_{k'} \\ &= \sum_{k'=1}^r c'_{i'j'} L_{k'}, \end{aligned}$$

where the formula for  $c_{i'j'}^{k'}$  can be read off from the last equality.  $\square$

**Lemma 4.** *For the operators  $L_{i'}$  as in Lem. 3, a smooth function  $u$  solves  $L_i u = 0$ ,  $i = 1, \dots, r$ , iff it solves  $L_{i'} u = 0$ ,  $i' = 1, \dots, r$ .*

*Proof.* The computation

$$L_{i'} u = \sum_{i=1}^r \alpha_{i'}^i (L_i u)$$

shows that  $L_i u = 0$ ,  $i = 1, \dots, r$ , implies  $L_{i'} u = 0$  for any  $i' = 1, \dots, r$ .  $\square$

**Lemma 5.** *For the operators  $L_i$  from Def. 1, given  $x_0 \in M$ , there exists an open coordinate neighborhood  $U \ni x_0$  such that (a) there exists invertible  $\alpha_{i'}^i$ , as in Lem. 3, (b) there exists a split local chart  $(y, z): M \supset U' \cong \mathbb{R}^r \times \mathbb{R}^{m-r}$ , with (c)  $(y(x_0), z(x_0)) = (0, 0)$ , (d)*

$$L_{i'} = \frac{\partial}{\partial y^{i'}} + \sum_{j=1}^{m-r} f_{i'}^j(y, z) \frac{\partial}{\partial z^j}.$$

and (e)  $[L_{i'}, L_{j'}] = 0$ , for  $i', j' = 1, \dots, r$ , which expressed in terms of  $f_{i'}^j$  means (f)

$$\frac{\partial}{\partial y^{i'}} f_{j'}^j + \sum_{k=1}^{m-r} f_{i'}^k \frac{\partial}{\partial z^k} f_{j'}^j = \frac{\partial}{\partial y^{j'}} f_{i'}^j + \sum_{k=1}^{m-r} f_{j'}^k \frac{\partial}{\partial z^k} f_{i'}^j.$$

*Proof.* Start with the coordinates  $(x^1, \dots, x^m)$  on  $U$  and consider the coordinate components  $L_i = a_i^j(x) \frac{\partial}{\partial x^j}$ . The rank of the matrix  $a_i^j(x_0)$  must be  $r$ , otherwise the  $L_i$  vectors do not constitute a frame for the distribution  $\mathcal{D}$ . Hence, there exists a subset  $I \subseteq \{1, \dots, r\}$  such that the matrix minor  $(a_i^j)_{i \in I, 1 \leq j \leq m}$  is non-singular. Define the coordinates  $y^{i'} = x^{I(i')} - (x_0)^{I(i')}$ ,  $i' = 1, \dots, r$ , and  $z^j = x^{I^c(j)} - (x_0)^{I^c(j)}$ ,  $j = 1, \dots, m-r$ , where  $I(i')$  and  $I^c(j)$  is some ordering of the sets  $I$  and its complement  $I^c$ . Then, restrict to a sub-neighborhood  $U'' \subseteq U$  that is split with respect to the  $(y, z)$  coordinates.

The new coordinate components are

$$L_i = \sum_{i'=1}^r a_i^{I(i')}(x(y, z)) \frac{\partial}{\partial y^{i'}} + \sum_{j=1}^{m-r} a_i^{I^c(j)}(x(y, z)) \frac{\partial}{\partial z^j}.$$

Let  $\beta_{i'}^{i'}(y, z) = a_i^{I(i')}(x(y, z))$  and  $\gamma_i^j(y, z) = a_i^{I^c(j)}(x(y, z))$ , so that by construction  $\beta_{i'}^{i'}(0, 0)$  is non-singular. Since  $\beta: U'' \rightarrow \text{Mat}(r, r)$  is smooth (hence a fortiori continuous) and the subset of non-singular matrices in  $\text{Mat}(r, r)$  is open, there is a possibly smaller split sub-neighborhood  $U' \subseteq U''$  on which  $\beta$  is everywhere non-singular. So, defining  $\alpha_{i'}^j(y, z) = (\beta_{i'}^{i'}(y, z))^{-1}$  on  $U'$  satisfies the desired conclusions (a), (b), (c) and (d), where  $f_{i'}^j(y, z) = \alpha_{i'}^i(y, z) \gamma_i^j(y, z)$ .

To prove (e) and (f), consider the computation

$$\begin{aligned} [L_{i'}, L_{j'}] &= L_{i'} L_{j'} - L_{j'} L_{i'} \\ &= \sum_{k'=1}^r c_{i'j'}^{k'} L_{k'} = \sum_{j=1}^{m-r} \left( \frac{\partial}{\partial y^{i'}} f_{j'}^j - \frac{\partial}{\partial y^{j'}} f_{i'}^j \right) \frac{\partial}{\partial z^j} + \sum_{k=1}^{m-r} \sum_{j=1}^{m-r} \left( f_{i'}^j \frac{\partial}{\partial z^j} f_{j'}^k - f_{j'}^j \frac{\partial}{\partial z^j} f_{i'}^k \right) \frac{\partial}{\partial z^k} \\ &= \sum_{j=1}^{m-r} \left( \frac{\partial}{\partial y^{i'}} f_{j'}^j + \sum_{k=1}^{m-r} f_{i'}^k \frac{\partial}{\partial z^k} f_{j'}^j - \frac{\partial}{\partial y^{j'}} f_{i'}^j - \sum_{k=1}^{m-r} f_{j'}^k \frac{\partial}{\partial z^k} f_{i'}^j \right) \end{aligned}$$

Hence, for each fixed  $i', j'$ , the  $\frac{\partial}{\partial y^{k'}}$  components of the right-hand side vanish, while those of the left-hand side equal  $\sum_{k'=1}^{m-r} c_{i'j'}^{k'} \frac{\partial}{\partial y^{k'}}$ , meaning that all components of  $c_{i'j'}^{k'}$  must vanish, proving (e). On the other hand, the vanishing of the right-hand side of the last equality proves (f).  $\square$

**Lemma 6.** Consider the operators  $L'_{i'}$  and the split neighborhood  $U \ni x_0$  as in Lem. 5. Let  $Z^k(y, z)$  and  $\bar{Z}^k(y, z)$  satisfy the inversion identity  $\bar{Z}^k(y, Z(y, z)) = z^k$ , for all  $z$  on a sufficiently small neighborhood of  $z = 0$ , and for all  $y$  on a sufficiently small neighborhood of  $y = 0$ . Suppose that  $Z^j(y, z)$  satisfies (a)  $Z^j(0, z) = z^j$  and (b)

$$\frac{\partial Z^j}{\partial y^{i'}}(y, z) = f_{i'}^j(y, Z^j(y, z)).$$

Then

$$L'_{i'} \bar{Z}(y, z) = 0, \quad i' = 1, \dots, r,$$

and vice versa.

*Proof.* Start by differentiating the inversion identity:

$$\begin{aligned} 0 &= \frac{\partial}{\partial y^{i'}} z^k = \frac{\partial}{\partial y^{i'}} \bar{Z}^k(y, Z(y, z)) \\ &= \frac{\partial \bar{Z}^k}{\partial y^{i'}}(y, z') \Big|_{z'=Z(y, z)} + \frac{\partial Z^j}{\partial y^{i'}}(y, z) \frac{\partial \bar{Z}^k}{\partial z'^j}(y, z') \Big|_{z'=Z(y, z)} \\ &= \left( \frac{\partial \bar{Z}^k}{\partial y^{i'}}(y, z') + f_{i'}^j(y, z') \frac{\partial \bar{Z}^k}{\partial z'^j}(y, z') \right) \Big|_{z'=Z(y, z)} \\ &\quad + \left( \frac{\partial Z^j}{\partial y^{i'}}(y, z) - f_{i'}^j(y, z') \right) \frac{\partial \bar{Z}^k}{\partial z'^j}(y, z') \Big|_{z'=Z(y, z)}. \end{aligned}$$

Recall that being a diffeomorphism, the Jacobian  $\frac{\partial \bar{Z}^k}{\partial z'^j}(y, z')$  non-singular on the sufficiently small split domain, with  $(\frac{\partial \bar{Z}^k}{\partial z'^j}(y, z'))^{-1} = \frac{\partial Z^j}{\partial z^k}(y, z) \Big|_{z=\bar{Z}(y, z')}$ . Hence, rearranging the last equality, we find

$$\frac{\partial Z^j}{\partial z^k}(y, z) L'_{i'} \bar{Z}^k(y, z') \Big|_{z'=Z(y, z)} = - \left( \frac{\partial Z^j}{\partial y^{i'}}(y, z) - f_{i'}^j(y, Z(y, z)) \right).$$

Hence, if one side of the equality vanishes, then so does the other, which proves the desired equivalence.  $\square$

**Lemma 7.** Let  $Z^j(y, z)$  be as in Lem. 6. Then,  $\zeta^j(t, y, z) = Z^j(ty, z)$  satisfies  $\zeta^j(0, y, z) = z^j$  and the equations

$$\frac{\partial}{\partial t} \zeta^j(t, y, z) = y^{i'} f_{i'}^j(ty, \zeta(t, y, z)).$$

Conversely, if  $\zeta^j(t, y, z)$  satisfies the initial value problem above, then there exists a sufficiently small neighborhood of  $(y, z) = (0, 0)$  for which  $Z^j(t, y, z)$  exists up to at least  $t = 1$ . Then  $Z^j(y, z) = \zeta^j(1, y, z)$  satisfies the conditions in the hypotheses of Lem. 6.

*Proof.* The easy direction is proved by the following computation:

$$\begin{aligned}
\frac{\partial}{\partial t} \zeta^j(t, y, z) &= \frac{\partial}{\partial t} Z^j(ty, z) \\
&= y^{i'} \frac{\partial Z^j}{\partial y^{i'}}(y', z) \Big|_{y'=ty} \\
&= y^{i'} f_{i'}^j(y', Z^j(y', z)) \Big|_{y'=ty} \\
&= y^{i'} f_{i'}^j(ty, Z(ty, z)) = y^{i'} f_{i'}^j(ty, \zeta(t, y, z)).
\end{aligned}$$

For the converse direction, consider the following computation, where we use the ODE satisfied by  $\zeta^j(t, y, z)$  and the identity from Lem. 5(f):

$$\begin{aligned}
&\frac{\partial}{\partial t} \left( \frac{\partial}{\partial y^{i'}} \zeta^j(t, y, z) - t f_{i'}^j(ty, \zeta(t, y, z)) \right) \\
&= \frac{\partial}{\partial y^{i'}} \frac{\partial}{\partial t} \zeta^j(t, y, z) \\
&\quad - f_{i'}^j(ty, \zeta(t, y, z)) - ty^{j'} \frac{\partial}{\partial y^{j'}} f_{i'}^j(y', \zeta(t, y, z)) \Big|_{y'=ty} - t \left( \frac{\partial}{\partial t} \zeta^k(t, y, z) \right) \frac{\partial}{\partial z'^k} f_{i'}^j(ty, z') \Big|_{z'=\zeta(t, y, z)} \\
&= \frac{\partial}{\partial y^{i'}} (y^{j'} f_{j'}^j(ty, \zeta(t, y, z))) \\
&\quad - f_{i'}^j(ty, \zeta(t, y, z)) - ty^{j'} \frac{\partial}{\partial y^{j'}} f_{i'}^j(y', z') \Big|_{y'=ty, z'=\zeta(t, y, z)} - ty^{j'} f_{j'}^k(y', z') \frac{\partial}{\partial z'^k} f_{i'}^j(y', z') \Big|_{y'=ty, z'=\zeta(t, y, z)} \\
&= \left( f_{i'}^j(y', z') + ty^{j'} \frac{\partial}{\partial y^{i'}} f_{j'}^j(y', z') + \left( \frac{\partial}{\partial y^{i'}} \zeta^k(t, y, z) \right) y^{j'} \frac{\partial}{\partial z'^k} f_{j'}^j(y', z') \right) \Big|_{y'=ty, z'=\zeta(t, y, z)} \\
&\quad - \left( f_{i'}^j(y', z') + ty^{j'} \frac{\partial}{\partial y^{i'}} f_{j'}^j(y', z') + ty^{j'} f_{i'}^k(y', z') \frac{\partial}{\partial z'^k} f_{j'}^j(y', z') \right) \Big|_{y'=ty, z'=\zeta(t, y, z)} \\
&= \left( \frac{\partial}{\partial y^{i'}} \zeta^k(t, y, z) - t f_{i'}^k(ty, \zeta(t, y, z)) \right) y^{j'} \frac{\partial}{\partial z'^k} f_{j'}^j(y', z') \Big|_{y'=ty, z'=\zeta(t, y, z)}
\end{aligned}$$

Hence, we find that  $\eta(t, y, z) = \frac{\partial}{\partial y^{i'}} \zeta^k(t, y, z) - t f_{i'}^k(ty, \zeta(t, y, z))$  satisfies a linear ODE. Hence, by the uniqueness of ODE solutions (Lem. 8(b)), if the initial condition  $\eta(0, y, z) = 0$  is satisfied, the solution must identically vanish,  $\eta(t, y, z) = 0$ , which upon setting  $t = 1$  proves that  $Z^j(y, z) = \zeta^j(1, y, z)$  satisfies the desired differential equation, (Lem. 8(c)). It remains to check the vanishing initial condition:

$$\begin{aligned}
\eta(0, y, z) &= \frac{\partial}{\partial y^{i'}} \zeta^j(0, y, z) - 0 \cdot f_{i'}^j(0\zeta(0, y, z)) \\
&= \frac{\partial}{\partial y^{i'}} z^j - 0 = 0.
\end{aligned}$$

The proof is completed by noting that the inverse function  $\bar{Z}(y, z)$  exists on a sufficiently small neighborhood of  $(y, z) = (0, 0)$ , because the continuity of  $\frac{\partial Z^j}{\partial z^k}$  and the property that  $\frac{\partial Z^j}{\partial z^k} \Big|_{z=0} = \delta_k^j$  ensures that  $Z^j(y, z)$  is an immersion (has non-singular jacobian) on a neighborhood of  $(y, z) = (0, 0)$  and hence a diffeomorphism on a possibly smaller neighborhood (use inverse function theorem).  $\square$

**Lemma 8.** *An ODE initial value problem (a sufficiently general one to cover the one for  $\zeta^j(t, y, z)$  in Lem. 7 and the one for  $\eta_{i'}^j(t, y, z)$  in the proof of Lem. 7) (a) has a solution that is jointly smooth in  $(t, y, z)$ , which (b) is unique, and (c) exists (at least) up to time  $t = 1$  on a sufficiently small neighborhood of  $(y, z) = (0, 0)$ .*

*Proof.* This should follow from the Picard-Lindelöf ODE existence and uniqueness theorem with parameters.  $\square$

**Definition 9** (differential forms).

**Definition 10** (differential ideal).

**Theorem 11** (differential form Frobenius). *If  $\alpha_i$ ,  $i = 1, \dots, k \leq m - k$  are 1-forms on  $M$  that generate a closed differential ideal. Then there exist smooth scalar functions  $u_i(x)$ ,  $i = 1, \dots, m - k$  such that the exact 1-forms  $du_i$ ,  $i = 1, \dots, m - k$  generate the same differential ideal.*

**Definition 12** (tangent distribution). A *tangent distribution* on a manifold  $M$  is a vector subbundle  $\mathcal{D} \hookrightarrow TM$  (equivalently, an embedding of vector bundles).

**Definition 13** (Lie bracket). On a manifold  $M$ , given two vector fields  $u, v$  (sections of the tangent bundle  $TM$ ), their *Lie bracket*  $w = [u, v]$  is the vector field that satisfies the identity  $w(f) = u(v(f)) - v(u(f))$ , where vector fields act as first order differential operators on a smooth function  $f$ . In coordinate form, if  $u = u^i \partial_i$ ,  $v = v^i \partial_i$ ,  $w = w^i \partial_i$ , then  $w^j = u^i \partial_i v^j - v^i \partial_i u^j$ . The vector fields  $u, v$  *commute* (or are *in involution* in the sense of Def. 1) if  $[u, v] = 0$ .

**Definition 14** (involutive distribution). A tangent distribution  $\mathcal{D} \hookrightarrow TM$  is *involutive* if, for any two vector field sections  $u, v$  of  $\mathcal{D}$ , the Lie bracket  $[u, v]$  is also a section of  $\mathcal{D}$ .

**Definition 15** (integral submanifold). Given a manifold  $M$  with a tangent distribution  $\mathcal{D} \hookrightarrow TM$  of rank  $r$  (as a vector bundle), a submanifold  $\iota: N \hookrightarrow M$  passing through  $x_0 \in M$  is called an *integral submanifold* of the distribution  $\mathcal{D}$  if it is everywhere tangent to  $\mathcal{D}$ ,  $T\iota(TN) \subseteq \mathcal{D}$ , where naturally  $\dim N \leq r$ . In the case  $\dim N = r$ , the integral submanifold is called *maximal* (in dimension).

**Definition 16** (foliation).

**Theorem 17** (vector field Frobenius). *Let  $\mathcal{D} \subseteq TM$  be an involutive tangent space distribution of rank  $r \leq m = \dim M$ . Then, for every  $x_0 \in M$ , there exists a maximal integral submanifold  $\iota: \mathbb{R}^r \hookrightarrow M$  of  $\mathcal{D}$  such that  $\iota(0) = x_0$ . Moreover, these integral submanifolds collect into a  $r$ -dimensional foliation of  $M$  whose leaves are everywhere tangent to the distribution  $\mathcal{D}$ .*