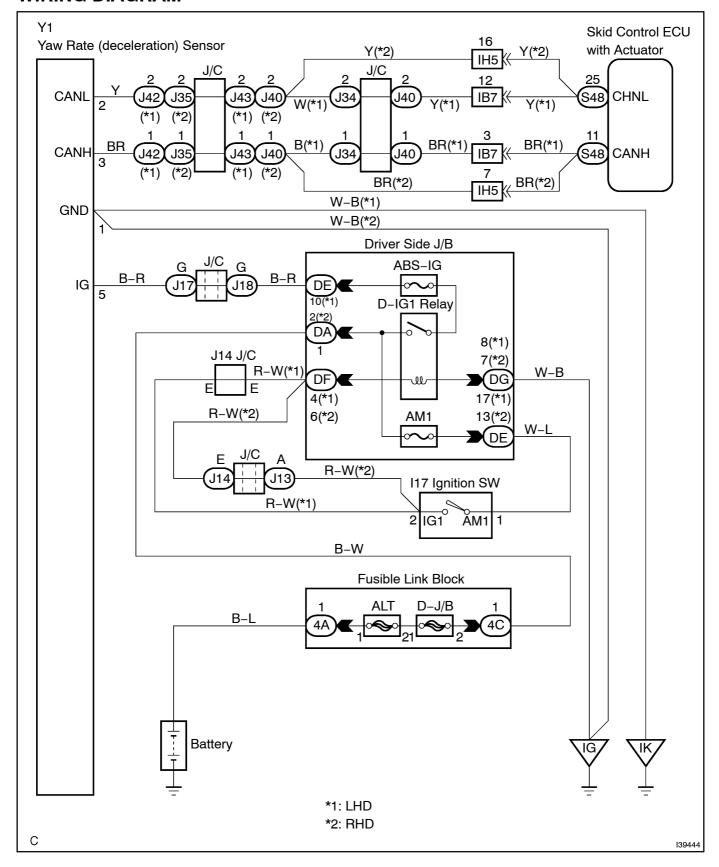
DTC	C1232/32	MALFUNCTION IN DECELERATION SENSOR
DTC	C1234/34	MALFUNCTION IN YAW RATE SENSOR
DTC	C1243/43	MALFUNCTION IN DECELERATION SENSOR
	•	
DTC	C1244/44	OPEN OR SHORT IN DECELERATION SENSOR CIRCUIT
DTC	C1245/45	MALFUNCTION IN DECELERATION SENSOR
DTC	C1381/97	MALFUNCTION IN POWER SUPPLY VOLTAGE YAW/DECELERATION SENSOR

# **CIRCUIT DESCRIPTION**

The yaw rate and deceleration sensor detect any gravity applied to the vehicle and transmits the signal to skid control ECU via CAN communication.

DTC No.	DTC Detecting Condition	Trouble Area
C1232/32	While the vehicle is at a speed of 10 km/h (6mph) or more, the condition that the fluctuation range of the signal from either GL1 or GL2 is under 80 mV and the other is above 1.9 V continues for 30 seconds or more.	Yaw rate (deceleration) sensor     Yaw rate (deceleration) sensor circuit
C1234/34	Sensor malfunction signal is received from yaw rate sensor.	Yaw rate (deceleration) sensor     Yaw rate (deceleration) sensor circuit
C1243/43	The following condition repeats 16 times.  • GL1 and GL2 do not change by more than 2LSB when the vehicle decelerates from 30 km/h (19 mph) to 0 km/h (0 mph).	Yaw rate (deceleration) sensor     Yaw rate (deceleration) sensor circuit
C1244/44	When any of the following (1 to 2) is detected:  (1) All of the following conditions continue for at least 60 seconds.  • Vehicle is stopped.  • Difference between GL1 and GL2 does not drop below 0.4G once it reaches 0.6G or more.  (2)  • Data malfunction signal is received from deceleration sensor.	Yaw rate (deceleration) sensor     Yaw rate (deceleration) sensor circuit
C1245/45	The following condition continues for at least 60 seconds.  • Difference between the values calculated from deceleration sensor value and vehicle speed exceeds 0.35G.	Yaw rate (deceleration) sensor     Yaw rate (deceleration) sensor circuit
C1381/97	Deceleration sensor power source malfunction signal is received for at least 10 sec. at a speed of more than 3 km/h (2 mph).	Yaw rate (deceleration) sensor     Yaw rate (deceleration) sensor power source circuit

### **WIRING DIAGRAM**



# **INSPECTION PROCEDURE**

HINT:

 $\label{lem:with_condition} When $$ U0123/62, $$ U0124/95 $$ or $$ U0126/63 $$ ard output $$ gether with $$ C1244/44, $$ 1245/45, $$ and $$ 1381/97 $$ inspect and $$ gether with $$ are sindicated $$ u0124/95 $$ or $$ 0126/63 $$ inst.$ 

### 1 | CHECK[\$ENSOR[INSTALLATION(YAW[RATE[\$ENSOR)

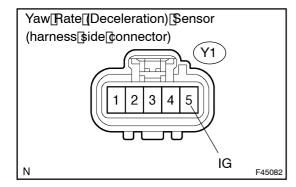
(a) Check [hat [he] yaw [ate [deceleration]] sensor [has [been [installed [properly [see [page [32-63]]]]] ok-

- The sensor is tightened to the specified torque.
- The sensor is not tilted.

NG INSTALL YAW RATE SENSOR CORRECTLY

OK

# 2 | CHECK HARNESS AND CONNECTOR(IG TERMINAL)



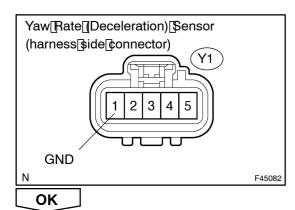
- (a) Disconnect the yaw rate (deceleration) sensor connector.
- (b) Turn the ignition switch to the ON position.
- (c) Measure the voltage according to the value(s) in the table below.

#### Standard:

Tester Connection	Spe	ecified Condition		
Y1-5 (IG) - Body ground	10 to 14 V			
NG REPAIR OR CONNECTOR	R	EPLACE	HARNESS	OR



# 3 | CHECK[HARNESS[AND[CONNECTOR(GND[TERMINAL)



- (a) Disconnect[the[yaw[rate]]deceleration)[sensor[connector.
- (b) Measure the resistance according to the value (s) in the table below.

### Standard:

Tester Connection	Specified[Condition		
Y1-1[[GND] -[Body[ground	Below[] Ω		
REPAIR OR ROUNECTOR	EPLACE   HARNESS   OR		

### REPLACE[ABS[&[TRACTION[ACTUATOR[ASSY[SEE[PAGE[32-53]

### **NOTICE:**

When replacing the ABS TRACTION actuator assy, perform zero point calibration (see page 05-387).