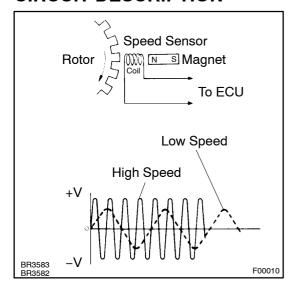
DTC	C0200/31	RIGHT FRONT SPEED SENSOR
	002000	

DTC C0205/32 LEFT FRONT SPEED SENSOR

# **CIRCUIT DESCRIPTION**



The speed sensor detects wheel speed and sends the appropriate signals to the ECU. These signals are used to control the ABS control system. The front and rear rotors have 48 serrations each.

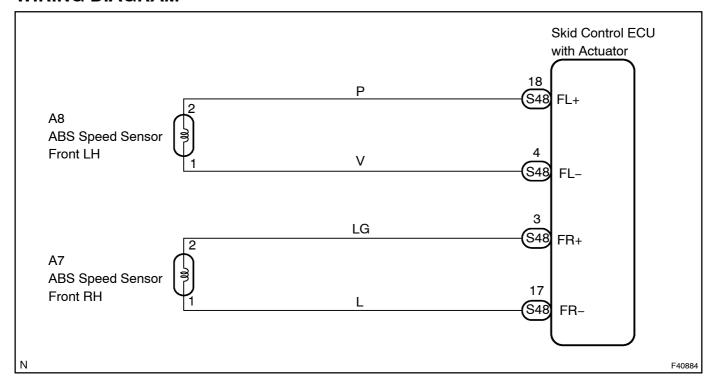
When the rotors rotate, the magnetic field emitted by the permanent magnet in the speed sensor generates an AC voltage. Since the frequency of this AC voltage changes in direct proportion to the speed of the rotor, the frequency is used by the ECU to detect the speed of each wheel.

DTC No.	DTC Detecting Condition	Trouble Area
C0200/31 C0205/32	<ul> <li>(1) All of following conditions continue for at least 1 second.</li> <li>Vehicle speed is more than 10 km/h (6 mph).</li> <li>Open or short in vehicle speed sensor signal circuit.</li> <li>(2) Momentary interruption of the sensor signal of faulty wheel has occurred 7 times or more.</li> <li>(3) Sensor signal circuit is open for 0.5 seconds.</li> </ul>	Right front and left front speed sensor  Each speed sensor circuit  Sensor rotor  Sensor installation

# HINT:

- DTC C0200/31 is for the right front speed sensor.
- DTC C0205/32 is for the left front speed sensor.

# **WIRING DIAGRAM**



# **INSPECTION PROCEDURE**

# 1 | CHECK[HARNESS[AND]CONNECTOR(MOMENTARY[INTERRUPTION)

(a) Using the intelligent tester of the ck for any momentary interruption in the wire harness and connector corresponding to a DTC see page 05-385).

Item	Measurement Item / Range (Display)	Normal Condition
FR Speed Open	FR speed sensor open detection / OPEN or NORMAL	OPEN : Mormentary interruption
FL Speed Open	FL speed sensor open detection / OPEN or NORMAL	OPEN : Mormentary interruption

#### OK:

There are no momentary interruptions.

HINT:

Perform the above inspection before removing the sensor and connector.

NG Go to step 5

OK

# 2 READ VALUE OF INTELLIGENT TESTER II(FRONT SPEED SENSOR)

- (a) Connect the intelligent tester II to the DLC3.
- (b) Start the engine.
- (c) Select the DATA LIST mode on the intelligent tester II.

Item	Measurement Item / Range (Display)	Normal Condition
FR Wheel Speed	Wheel speed sensor (FR) reading / min.: 0 km/h (0 MPH, max.: 326 km/h (202 MPH)	Actual wheel speed
FL Wheel Speed	Wheel speed sensor (FL) reading / min.: 0 km/h (0 MPH, max.: 326 km/h (202 MPH)	Actual wheel speed

(d) Check that there is no difference between the speed value output from the speed sensor displayed on the intelligent tester II and the speed value displayed on the speedometer when driving the vehicle.

There is almost no difference from the displayed speed value.

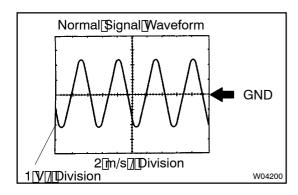
HINT:

There is tolerance of  $\pm$  10 % in the speedometer indication.

NG Go to step 4

OK

# 3 | INSPECT| SPEED| SENSOR| AND | SENSOR| ROTOR| SERRATIONS



# INSPECTION USING OSCILLOSCOPE

- (a) Connect[the[bscilloscope[to[terminal[FR+ -[FR-[br[FL+ -[FL-[bf[the[skid[bontrol[ECU.
- (b) Drive the vehicle at approximately 30 km/h 19 mph), and check the signal waveform.

# OK:

# A[waveform[as[shown[in[affigure[should[be[output. HINT:

- As the Vehicle speed (wheel fevolution speed) increases, a cycle of the Ververorm framework and the fluctuation in the output Voltage becomes greater.
- When noise is identified in the waveform on the oscilloscope, error signals are generated due to the speed sensor rotor scratches, ooseness or for gign matter attached of the



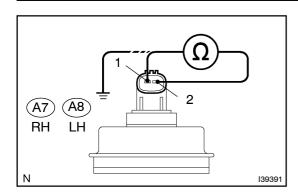
OK

# REPLACE[ABS[&[TRACTION[ACTUATOR[ASSY[[SEE[PAGE[32-53]]

#### NOTICE:

When replacing the ABS & TRACTION actuator assy, perform zero point calibration (see page 05–387).

# 4 INSPECT FRONT SPEED SENSOR



- (a) Make sure that there is no looseness at the connectors' locking part and connecting part of connector.
- (b) Disconnect the speed sensor connector.
- (c) Measure the resistance according to the value(s) in the table below.

# Standard:

# LH:

Tester Connection	Specified Condition
A8-2 (FL+) - A8-1 (FL-)	0.6 to 2.5 kΩ

# RH:

Tester Connection	Specified Condition
A7-2 (FR+) - A7-1 (FR-)	0.6 to 2.5 kΩ

(d) Measure the resistance according to the value(s) in the table below.

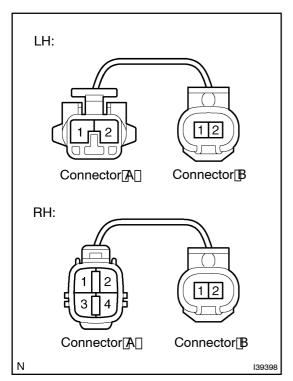
# Standard:

# LH:

Tester Connection	Specified Condition
A8-2 (FL+) - Body ground	1 M $\Omega$ or higher
A8-1 (FL-) - Body ground	1 MΩ or higher

# RH:

Tester Connection	Specified Condition
A7-2 (FR+) - Body ground	1 M $\Omega$ or higher
A7-1 (FR-) - Body ground	1 MΩ or higher



# FRONT SPEED SENSOR SUB-WIRE HARNESS

- (a) Remove the front ender iner.
- (b) Make \$\text{ure} \text{the} \text{speed} \end{\text{sensor} \text{connector} \text{and} \text{the} \text{vire} \\
  \text{harness} \text{ide} \text{connector} \text{are} \text{securely} \text{connected}.
- (c) Disconnect he speed sensor connector nside he hicle.
- (d) Measure the resistance according to the value (s) in the table below.

## Standard:

## LH:

Tester[Connection	Specified[Condition
(Connector[A-1) -[Connector[B-1)	Below[] [Ω
(Connector[A-2) -[Connector[B-2)	Below[] [Ω

## RH:

Tester Connection	Specified[Condition
(Connector[A−1) -[[Connector[B−1)	Below[][Ω
(Connector[A-2) -[Connector[B-2)	Below[][Ω

(e) Measure the resistance according to the value (s) in the table below.

## Standard:

#### LH:

Tester[Connection	Specified[Condition
(Connector[A-1) -[Connector[A-2)	1 MΩ[ðpr[ħigher

## RH:

Tester@onnection	Specified[Condition
(Connector[A-1) -[Connector[A-2)	1 MΩ[ɸr[ħigher

(f) Measure the resistance according to the value (s) in the table below.

## Standard:

#### LH:

Tester@onnection	Specified[Condition
(Connector[A−1) –[Body[ground	1 MΩ[þr[ħigher
(Connector[A−2) –[Body[ground	1 MΩ[ð̞r[ḫigher

## RH:

Tester@onnection	Specified[Condition
(Connector[A−1) –[Body[ground	1 MΩ[o̞r[higher
(Connector[A−2) –[Body[ground	1 MΩ[o̞r[ḫigher

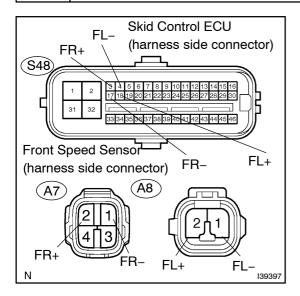
## **NOTICE:**

Check[the[speed[sensor[signal[after[replacement (see[page[05-389]).



REPLACE[FRONT[\$PEED[\$ENSOR (SEE[PAGE[32-61)

# 5 CHECK HARNESS AND CONNECTOR(FRONT SPEED SENSOR – SKID CONTROL ECU)



- (a) Disconnect the skid control ECU connector and the front speed sensor connector.
- (b) Measure the resistance according to the value(s) in the table below.

## Standard:

## LH:

Tester Connection	Specified Condition
S48-18 (FL+) - A8-2 (FL+)	Below 1 Ω
S48-4 (FL-) - A8-1 (FL-)	Below 1 Ω

# RH:

Tester Connection	Specified Condition
S48-3 (FR+) - A7-2 (FR+)	Below 1 Ω
S48-17 (FR-) - A7-1 (FR-)	Below 1 Ω

(c) Measure the resistance according to the value(s) in the table below.

## Standard:

## LH:

Tester Connection	Specified Condition
S48-18 (FL+) - Body ground	1 M $\Omega$ or higher
S48-4 (FL-) - Body ground	1 M $\Omega$ or higher

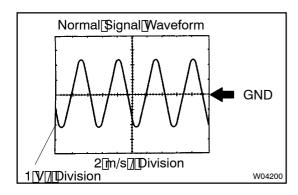
# RH:

Tester Connection	Specified Condition
S48-3 (FR+) - Body ground	1 MΩ or higher
S48-17 (FR-) - Body ground	1 MΩ or higher

NG REPAIR OR REPLACE HARNESS OR CONNECTOR

OK

# 6 INSPECT SPEED SENSOR AND SENSOR ROTOR SERRATIONS



# INSPECTION USING OSCILLOSCOPE

- (a) Connect[the[bscilloscope[to[terminal]FR+ -[FR-[br[FL+ -[FL-[bf[the[skid]control]FCU.
- (b) Drive the vehicle at approximately 30 km/h 19 mph), and check the signal waveform.

## OK:

# A [waveform as shown in a figure should be output. HINT:

- Asthetyehiclespeed()Wheelfevolution(speed)(increases, acycleof(thetyvaveform(harrows(and(thetfluctuation(in)the output()voltage(becomes())reater.
- When noise is identified in the waveform on the oscilloscope, error signals are generated due to the speed sensor rotor scratches, ooseness or for gign matter attached of the

NG Go[to[step[7

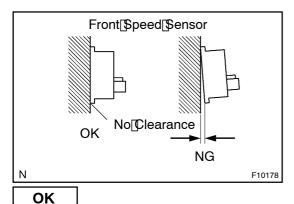
OK

## REPLACE ABS & TRACTION ACTUATOR ASSY (SEE PAGE 32-53)

#### NOTICE:

When replacing the ABS TRACTION actuator assy, perform zero point calibration (see page \$05-387).

# 7 | INSPECT|FRONT|SPEED|SENSOR|INSTALLATION



(a) Check the speed sensor installation.

OK:

There[is]no[clearance[between[the[sensor[and[the[front steering[knuckle.

**NOTICE:** 

Check[the[speed[sensor[signal[after[the[replacement (see[page[05-389]).

NG□

REPLACE FRONT SPEED SENSOR

REPLACE[ABS[&[TRACTION[ACTUATOR[ASSY[[SEE[PAGE[32-53]]

#### **NOTICE:**

When replacing the ABS TRACTION actuator assy, perform zero point calibration (see page 05-387).