# CRUISE MAIN INDICATOR LIGHT CIRCUIT

#### **CIRCUIT DESCRIPTION**

When the cruise control main switch is on, the CRUISE main indicator light and READY indicator light come on.

This indicates the control condition (presence or absence of a vehicle in front, vehicle–to–vehicle distance, and set vehicle speed) and fail–safe state through the multiplex communication system and CAN communication system.

The master warning light and CRUISE main indicator light come on and vehicle-to-vehicle distance information is displayed on the combination meter as the alarm buzzer sounds.

Items such as "Clean Radar Sensor", "Cruise not Available", "Check Cruise System" and "Radar Cruise Ready" are displayed in the multi-information display on the combination meter when the ECM detects signals from each sensor and actuator and sends them to the combination meter via CAN and BEAN. HINT:

If the vehicle in front in the same lane significantly decreases vehicle speed or another vehicle pulls in front of your vehicle, adequate deceleration cannot be applied and the vehicle–to–vehicle distance will shorten. At this time, the system sounds the buzzer and the master warning light blinks to warn the driver.

Each indicator in the dynamic laser cruise control uses CAN and BEAN for communication. Therefore, if there are any malfunctions in this circuit, check for DTCs in the CAN communication and multiplex communication systems.

# INSPECTION PROCEDURE

## 1 | PERFORM[ACTIVE]TEST[ON]INTELLIGENT[TESTER]I

- (a) Connect the intelligent tester in the DLC3.
- (b) Check the cruise control witch by using ACTIVE TEST.

#### COMBINATION METER:

Description	Tester[display	Check[condition
"CRUISE"[indicator[is[DN]][DFF	Indicat.[Lamp[Cruise	ON -[DFF
Graphic[area[]s[DN[][DFF	Indicat.[Laser[Cruise[Display	ON -[DFF
"CHECK[CRUISE[\$YSTEM"[]ndicator[]s ON[[DFF	Indicat.[Lamp[L-Cruise[Check	ON -[DFF
"RADAR[READY"[Indicator[]s[DN][DFF	Indicat.[Lamp[L-Cruise[Ready	ON -[DFF

OK: Indicator light comes on.

NG

GO[TO[COMBINATION[METER[\$YSTEM (SEE[PAGE[05-2148)

OK

## 2 | READ[VALUE[ON[INTELLIGENT[TESTER]]]

- (a) Connect the intelligent tester to the DLC3.
- (b) Turn the ignition witch to the ON position, and turn the intelligent tester in main witch on.
- (c) Select[he]tem['CCS[ndicator[M-CPU",['CCS[]ndicator[S-CPU",]'CCS[Ready[M-CPU"[pr]'CCS Ready[S-CPU"[nt]]he[DATA[LIST,[and[]]ead[]]ts[value[displayed[]]he[]ntelligent[]]ester[]].
- (d) Check[the[CRUISE[main[indicator[i]ght]and[READY[indicator[i]ght, when[the[cruise[control]main]switch is[ON[and]when[it]]s[OFF.

#### ECM:

ltem	Measurement[]tem[] Display[[Range)	Normal@ondition	Diagnostic∏Note
CCS[Ready[M-CPU	Cruise@ontrol[system[standby condition[]Main[CPU)][DN[]pr[DFF	ON[⇔[0FF]]Change[0N/OFF each[jime[Main[\$W[js[pushed.	*1
CCS[Ready[\$-CPU	Cruise@ontrol[system[standby condition[Sub[CPU)][DN[or[DFF	ON[⇔[0FF]]Change[0N/0FF each[]ime[Main[\$W[]s[pushed.	*1
CCS[]ndicator[]M-CPU	Cruise[indicator[signal[Main[CPU)] /[DN[or[DFF	ON@CCS@EADY"@N OFF@CCS@EADY"@FF	*2
CCS[]ndicator[\$-CPU	Cruise[indicator[signal[[Sub[CPU]] /[DN[pr[DFF]	ON@CCS@EADY"DN OFF@CCS@EADY"DFF	*2

 $OK: \cite{When} \cite{When}$ 

HINT:

\*1[]s[DK,[]but[]\*2[]s[NG[]->[DTC[]output[]or[]ECM[]failure

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REPLACE ECM (SEE PAGE 10-21)

OK

PROCEED[TO[NEXT[CIRCUIT[]NSPECTION[\$HOWN[]N[PROBLEM[\$YMPTOMS[TABLE (SEE[PAGE[05-3638)