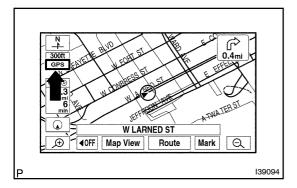
VEHICLE[POSITION[MARK[DEVIATES[GREATLY

INSPECTION PROCEDURE

1 | CHECK[THE[GPS[MARK



(a) Check that the GPS mark is displayed.

OK:The GPS mark is displayed.

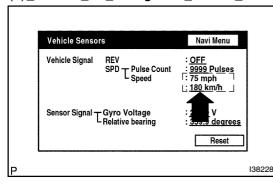
NG

GO[TO['GPS[MARK[IS[NOT[DISPLAYED"[IN[THE FLOW[CHART[SEE[PAGE[05-1821]

OK

2 | NAVIGATION CHECK MODE (VEHICLE SENSORS)

(a) Enter the Navigation Check mode Vehicle Sensors (ase page 5-1757).



(b) While driving, compare the SPD indicator of the eading on the speedometer. Check that these readings are almost the same.

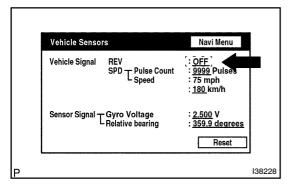
OK: The readings are almost the same.

NG∐

GO[TO["SPEED[\$IGNAL[CIRCUIT[|NAVIGATION ECU - COMBINATION[METER[ASSY]"]N[]THE FLOW[CHART[[SEE[PAGE[05-1859]]

OK

3 | NAVIGATION CHECK MODE (VEHICLE SENSORS)



(a) Move the shift ever to the Ror position.

Standard:

Shift[]ever	Display
Р	OFF
R	ON

HINT:

The display is updated once per second. As a flesult, it is flormal for the display of agreement the actual change in the switch.



GO[TO["REVERSE[SIGNAL[CIRCUIT"[]N[]THE FLOW[CHART[[SEE[PAGE[05-1865]



PROCEED_TO_NEXT_CIRCUIT_INSPECTION_\$HOWN_IN_PROBLEM_\$YMPTOMS_TABLE (SEE_PAGE_05-17/71)