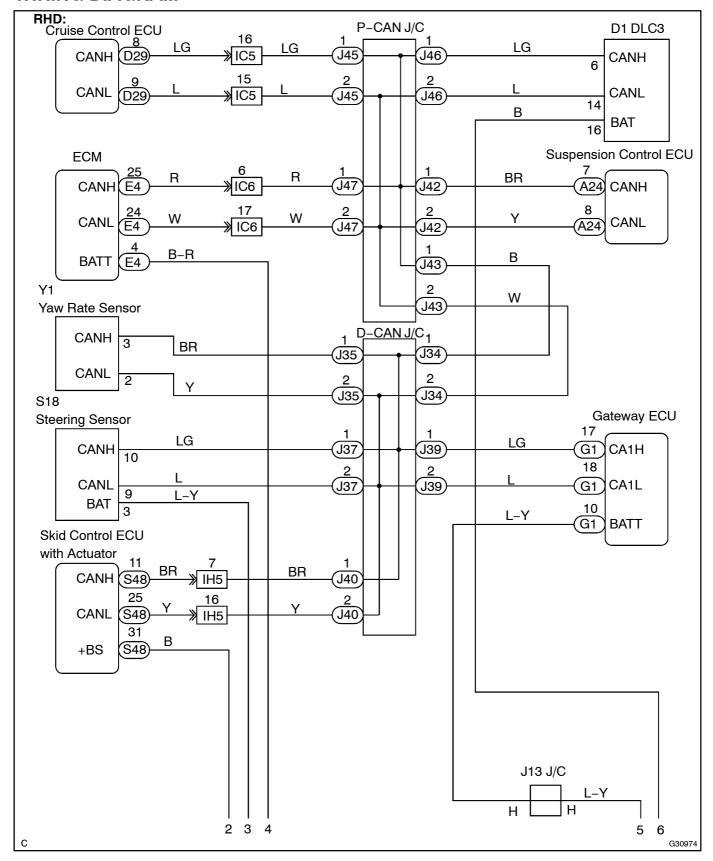
# CHECK CAN BUS LINE FOR SHORT TO +B (RHD, w/o LEXUS Navigation System)

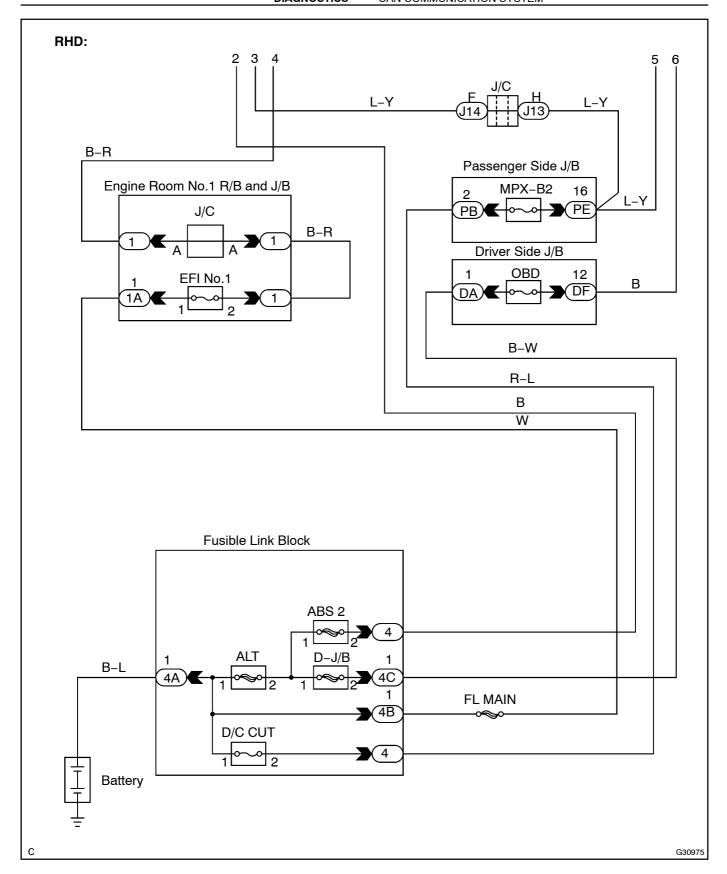
# **CIRCUIT DESCRIPTION**

There may be a short circuit between the CAN bus line and +B when there is resistance between terminals 6 (CANH) and 16 (BAT) or terminals 14 (CANL) and 16 (BAT) of the DLC3.

Symptom	Trouble Area
There is resistance between terminals 6 (CANH) and 16 (BAT) or terminals 14 (CANL) and 16 (BAT) of the DLC3.	Short to +B Cruise control ECU Skid control ECU with actuator Steering sensor Yaw rate sensor Suspension control ECU ECM Gateway ECU

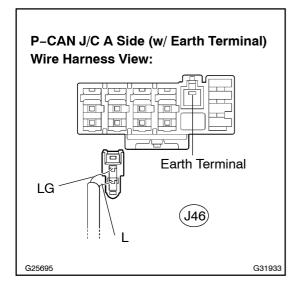
# **WIRING DIAGRAM**





# **INSPECTION PROCEDURE**

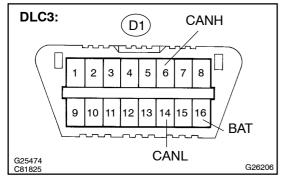
### 1 CHECK CAN BUS LINE FOR SHORT TO +B(DLC3 SUB BUS LINE)



- (a) Turn the ignition switch to the LOCK position.
- (b) Disconnect the DLC3 sub bus line connector (J46) from the P-CAN J/C A side (w/ earth terminal).

### **NOTICE:**

- Before disconnecting the connector, make a note of where it is connected.
- Reconnect the connector to its original position.



(c) Measure the resistance according to the value(s) in the table below.

### Standard:

Tester connection	Condition	Specified value
D1-6 (CANH) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more
D1-14 (CANL) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more

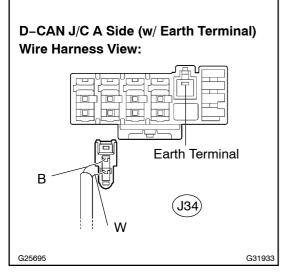
NG

REPAIR OR REPLACE DLC3 SUB BUS LINE OR CONNECTOR (CAN-H, CAN-L)

OK

(a) Reconnect the DLC3 sub bus line connector (J46) to the P-CAN J/C A side (w/ earth terminal).

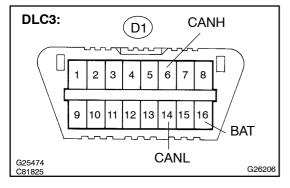




(a) Disconnect the CAN main bus line connector (J34) from the D-CAN J/C A side (w/ earth terminal).

### **NOTICE:**

- Before disconnecting the connector, make a note of where it is connected.
- Reconnect the connector to its original position.



(b) Measure the resistance according to the value(s) in the table below.

### Standard:

Tester connection	Condition	Specified value
D1-6 (CANH) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more
D1-14 (CANL) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more

OK Go to step 16

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(a) Reconnect the CAN main bus line connector (J34) to the D-CAN J/C A side (w/ earth terminal).

5 CHECK CAN BUS LINE FOR SHORT TO +B(SUSPENSION CONTROL ECU SUB BUS LINE)

# P-CAN J/C B Side (w/o Earth Terminal) Wire Harness View: BR J42

### NOTICE:

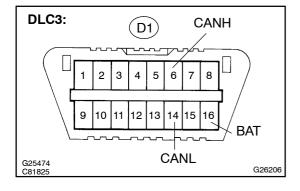
For vehicles without electronic modulated air suspension, go to step 7.

(a) Disconnect the suspension control ECU sub bus line connector (J42) from the P-CAN J/C B side (w/o earth terminal).

### NOTICE:

G31932

- Before disconnecting the connector, make a note of where it is connected.
- Reconnect the connector to its original position.



(b) Measure the resistance according to the value(s) in the table below.

### Standard:

Tester connection	Condition	Specified value
D1-6 (CANH) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more
D1-14 (CANL) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more

OK Go to step 12

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(a) Reconnect the suspension control ECU sub bus line connector (J42) to the P-CAN J/C B side (w/o earth terminal).



CHECK CAN BUS LINE FOR SHORT TO +B(CRUISE CONTROL ECU SUB BUS LINE)

# P-CAN J/C B Side (w/o Earth Terminal) Wire Harness View:

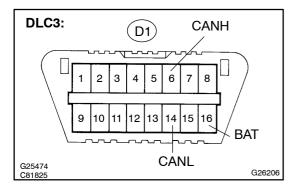
### **NOTICE:**

For vehicles without dynamic laser cruise control, go to step 9.

(a) Disconnect the cruise control ECU sub bus line connector (J45) the P-CAN J/C B side (w/o earth terminal).

### NOTICE:

- Before disconnecting the connector, make a note of where it is connected.
- Reconnect the connector to its original position.



(b) Measure the resistance according to the value(s) in the table below.

### Standard:

Tester connection	Condition	Specified value
D1-6 (CANH) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more
D1-14 (CANL) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more

ok`

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Go to step 14

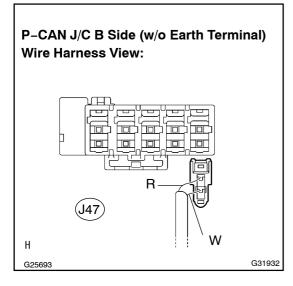
NG

G25693

(a) Reconnect the cruise control ECU sub bus line connector (J45) to the P-CAN J/C B side (w/o earth terminal).



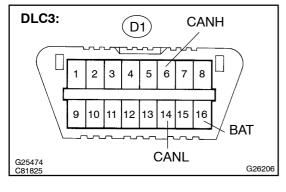
# 9 CHECK CAN BUS LINE FOR SHORT TO +B(ECM SUB BUS LINE)



(a) Disconnect the ECM sub bus line connector (J47) from the P-CAN J/C B side (w/o earth terminal).

### **NOTICE:**

- Before disconnecting the connector, make a note of where it is connected.
- Reconnect the connector to its original position.



(b) Measure the resistance according to the value(s) in the table below.

### Standard:

Tester connection	Condition	Specified value
D1-6 (CANH) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more
D1-14 (CANL) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more



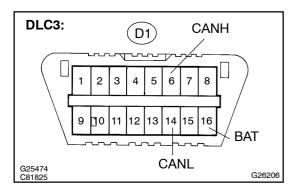
REPAIR OR REPLACE CAN MAIN BUS LINE OR CONNECTOR (D-CAN J/C - P-CAN J/C)

OK

# 10 CONNECT CONNECTOR

(a) Reconnect the ECM sub bus line connector (J47) to the P-CAN J/C B side (w/o earth terminal).

# 11 CHECK[CAN]BUS[LINE[FOR[\$HORT[TO]]+B(D-CAN]]/C)



- (a) Disconnect he ECM connector E4).
- (b) Measure the resistance according to the value (s) in the table below.

### Standard:

Tester@onnection	Condition	Specified[]value
D1-6[[CANH) - D1-16[[BAT]	Ignition[\$witch[DFF	1 MΩ[þr[more
D1-14[[CANL] - D1-16[[BAT]	Ignition[\$witch[DFF	1 MΩ[þr[more

OK REPLACE ECM (SEE PAGE 10-21)

NG

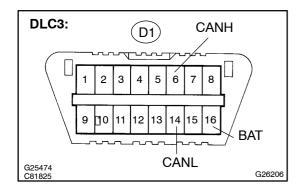
### REPAIR OR REPLACE ECM SUB BUS LINE OR CONNECTOR (CAN-H, CAN-L)

# 12 | CONNECT CONNECTOR

(a) Reconnect[]he[suspension[control[ECU[sub[bus]]ine[connector[J42)]]to[]he[P-CAN[J/C[B[side[w/oearth]]erminal).



# 13 CHECK[CAN[BUS[LINE[FOR[SHORT[TO]]] B(SUSPENSION[CONTROL[ECU[SUB]] BUS[LINE]



- (a) Disconnect the suspension control CU connector A24).
- (b) Measure[the[resistance[according[to[the[value(s)]]n[the table[below.

### Standard:

Tester[connection	Condition	Specified[value
D1-6[[CANH) - D1-16[[BAT)	Ignition[\$witch[DFF	1 MΩ[þr[more
D1-14 (CANL) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more

OK[)

REPLACE[SUSPENSION[CONTROL[ECU[(SEE PAGE[25-20)

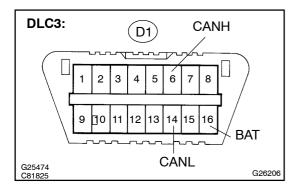
NG

REPAIR OR REPLACE SUSPENSION CONTROL ECU SUB BUS LINE OR CONNECTOR (CAN-H, CAN-L)

(a) Reconnect[he[cruise[control[ECU[sub[bus[line[connector[J45)[lo]]he[P-CAN]]/C[B[side[w/o[earth terminal].



15 CHECK[CAN[BUS[LINE[FOR[SHORT[TO]]]+B(CRUISE[CONTROL[ECU[SUB[BUS LINE]]



- (a) Disconnect the truise control ECU connector D29).
- (b) Measure the resistance according to the value (s) in the table below.

### Standard:

Tester[connection	Condition	Specified[value
D1-6[[CANH) - D1-16[[BAT)	Ignition[\$witch[DFF	1 MΩ[þr[more
D1-14[[CANL] - D1-16[[BAT]	Ignition[\$witch[DFF	1 MΩ[þr[more



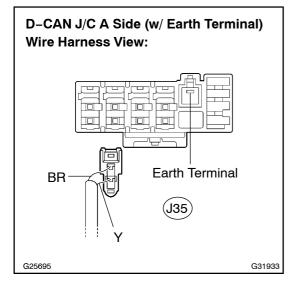
REPAIR OR REPLACE CRUISE CONTROL ECU SUB BUS LINE OR CONNECTOR (CAN-H, CAN-L)

OK

REPLACE[CRUISE[CONTROL[ECU[ASSY[[SEE[PAGE[82-2]

(a) Reconnect the CAN main bus line connector (J34) to the D-CAN J/C A side (w/ earth terminal).

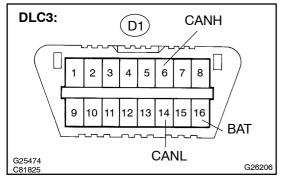
# 17 CHECK CAN BUS LINE FOR SHORT TO +B(YAW RATE SENSOR SUB BUS LINE)



(a) Disconnect the yaw rate sensor sub bus line (J35) from the D-CAN J/C A side (w/ earth terminal).

### **NOTICE:**

- Before disconnecting the connector, make a note of where it is connected.
- Reconnect the connector to its original position.



(b) Measure the resistance according to the value(s) in the table below.

### Standard:

Tester connection	Condition	Specified value
D1-6 (CANH) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more
D1-14 (CANL) - D1-16 (BAT)	Ignition Switch OFF	1 MΩ or more

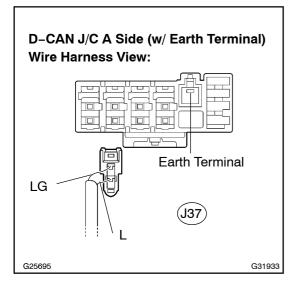
OK Go to step 24

NG

# 18 CONNECT CONNECTOR

(a) Reconnect the yaw rate sensor sub bus line connector (J35) to the D-CAN J/C A side (w/ earth terminal).

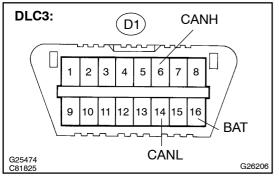
# 19 CHECK CAN BUS LINE FOR SHORT TO +B(STEERING SENEOR SUB BUS LINE)



(a) Disconnect the steering sensor sub bus line connector (J37) from the D-CAN J/C A side (w/ earth terminal).

### **NOTICE:**

- Before disconnecting the connector, make a note of where it is connected.
- Reconnect the connector to its original position.



(b) Measure the resistance according to the value(s) in the table below.

### Standard:

Tester connection	Condition	Specified value
D1-6 (CANH) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more
D1-14 (CANL) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more

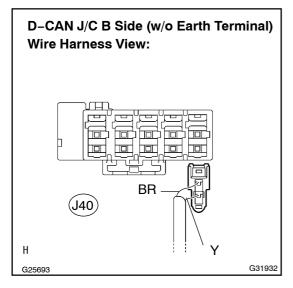
OK Oo to step 28

NG

# 20 | CONNECT CONNECTOR

(a) Reconnect the steering sensor sub bus line connector (J37) to the D-CAN J/C A side (w/ earth terminal).

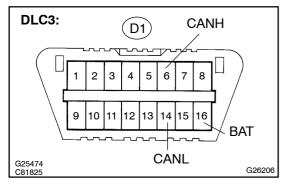
# 21 CHECK CAN BUS LINE FOR SHORT TO +B(SKID CONTROL ECU SUB BUS LINE)



(a) Disconnect the skid control ECU sub bus line connector (J40) from the D-CAN J/C B side (w/o earth terminal).

### **NOTICE:**

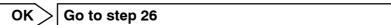
- Before disconnecting the connector, make a note of where it is connected.
- Reconnect the connector to its original position.



(b) Measure the resistance according to the value(s) in the table below.

### Standard:

Tester connection	Condition	Specified value
D1-6 (CANH) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more
D1-14 (CANL) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more

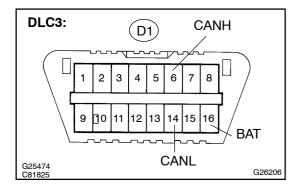


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(a) Reconnect[the[skid[control]] CU[sub[bus[]]ne[connector[]J40)[to[the[]] - CAN[]/C[] [side[]w/o[arth[]] rminal).

# \_\_\_\_

## 23 | CHECK|CAN|BUS|LINE|FOR|SHORT|TO|+B(GATEWAY|ECU|SUB|BUS|LINE)



- (a) Disconnect he gateway ECU connector G1).
- (b) Measure the resistance according to the value (s) n the table below.

### Standard:

Tester[connection	Condition	Specified[yalue
D1-6[[CANH) - D1-16[[BAT)	Ignition[\$witch[DFF	1 MΩ[þr[jmore
D1-14[[CANL] - D1-16[[BAT]	Ignition[\$witch[DFF	1 MΩ[þr[jmore

OK

REPLACE[GATEWAY[ECU

NG

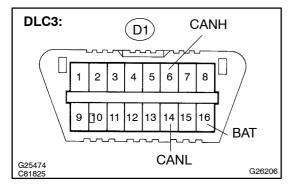
### REPAIR OR REPLACE GATEWAY (ECU SUB BUS LINE OR CONNECTOR (CAN-H, CAN-L)

# 24 CONNECT CONNECTOR

(a) Reconnect[the[yaw[]ate[\$ensor[\$ub[]bus[]ine[connector[]J35)[]o[]he[]D-CAN[]/C[A[\$ide[]w/[earth[]erminal).

# 25□

# CHECK[CAN]BUS[LINE]FOR[\$HORT[TO]+B(YAW]RATE[\$ENSOR[\$UB]|BUS[LINE)



- (a) Disconnect the vaw rate sensor connector Y1).
- (b) Measure the resistance according to the value (s) in the table below.

### Standard:

Tester@connection	Condition	Specified[yalue
D1–6∏CANH) – D1–16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more
D1-14 (CANL) - D1-16 (BAT)	Ignition Switch OFF	1 M $\Omega$ or more

OK

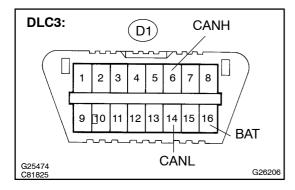
REPLACE YAW RATE SENSOR (SEE PAGE 32-63)

NG

REPAIR OR REPLACE YAW RATE SENSOR SUB BUS LINE OR CONNECTOR (CAN-H, CAN-L)

(a) Reconnect[the[skid[control]] CU[sub[bus[]]ne[connector[]J40)[to[the[]] - CAN[]/C[] [side[]w/o[arth[]] ral).

# 27 | CHECK[CAN[BUS[LINE[FOR[SHORT[TO]]]+B(SKID[CONTROL[ECU[SUB[BUS[LINE]]



- (a) Disconnect he skid control ECU connector S48).
- (b) Measure the resistance according to the value (s) in the table below.

### Standard:

Tester[connection	Condition	Specified[yalue
D1-6[[CANH) - D1-16[[BAT)	Ignition[\$witch[DFF	1 MΩ[þr[jmore
D1-14[[CANL] - D1-16[[BAT]	Ignition[\$witch[DFF	1 MΩ[þr[jmore

ок

 $\begin{array}{lll} \textbf{REPLACE} & \textbf{SKID} \\ \hline & \textbf{CONTROL} \\ \hline & \textbf{ECU} \\ \hline & \textbf{WITH} \\ \hline & \textbf{ACTUATOR} \\ \hline & \textbf{(SEEPAGE} \\ \hline & \textbf{32-53)} \\ \end{array}$ 

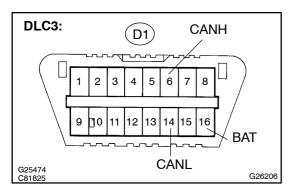
NG

# REPAIR OR REPLACE SKID CONTROL ECU SUB BUS LINE OR CONNECTOR (CAN-H, CAN-L)

# 28 CONNECT CONNECTOR

(a) Reconnect[the[steering[sensor[sub[bus[ine[connector[J37)[to[the[D-CAN]/C]]side[w/earth[terminal]).

# 29 | CHECK[CAN[BUS[LINE[FOR[\$HORT[TO]]+B(STEERING[\$ENSOR[\$UB[BUS[LINE]



- (a) Disconnect the steering sensor connector S18).
- (b) Measure[the[resistance[according[to[the[yalue(s)]]n[the table[below.

### Standard:

Tester[connection	Condition	Specified[yalue
D1-6[[CANH) - D1-16[[BAT)	Ignition[\$witch[DFF	1 MΩ[or[more
D1-14[[CANL] - D1-16[[BAT]	Ignition[switch[DFF	1 MΩ[þr[jnore

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REPLACE | STEERING | SENSOR | (SEE | PAGE 32-65)

NG

REPAIR[OR[REPLACE[STEERING[SENSOR[SUB[BUS[LINE[OR[CONNECTOR[CAN-H,[CAN-L)