

# Saarland University, Department of Computer Science

# Neural Network Assignment 5

Deborah Dormah Kanubala (7025906) , Irem Begüm Gündüz (7026821), Anh Tuan Tran (7015463)

December 19, 2022

## Exercise 5.1 (Newton's Method)

#### Exercise 5.1.a

Given a function  $H: \mathbb{R}^n \Longrightarrow \mathbb{R}^m$ For the Taylor approximations:

$$H(x+ \triangle x) = H(x) + \Delta H(x) \triangle x + o(|\triangle x|) = 0$$

In linear approximation, we can neglect  $o(|\nabla x|)$  because it is a constant.

$$H(x) + \Delta H(x) \triangle x = 0$$

NB:  $\triangle x = x_{k+1} - x_k$ 

$$H(x) + \Delta H(x) \Delta x = 0$$

$$x_{k+1} - x_k = -[\Delta H(x)]^{-1} H(x)$$

$$x_{k+1} = x_k - [\Delta H(x)]^{-1} H(x)$$
(1)

#### Exercise 5.1.b

Given  $f(x) = x_1 - 3x_1 + x_2 - x_1x_2$ Update Rule for Gradient Descent:

$$\begin{array}{l} \theta' = \theta^0 - \alpha \nabla J(\theta) \\ \frac{\partial f(x)}{\partial x_1} = 2x_1 - 3 - x_2; \qquad \frac{\partial f(x)}{\partial x_2} = 2x_2 - x_1 \\ x^0 = [1,1] \\ x_1^0 = 1 - 0.5(2(1) - 3 - 1) \\ \nabla x_1' = -2; \qquad x_1^0 = 2 \\ x_2^0 = 1 - 0.5(2(1) - 1) \\ \nabla x_2^0 = 1; \qquad x_2^0 = 0.5 \qquad \therefore l_{2-\text{norm}} = \sqrt{(-2)^2 + (1)^2} = 2.236 \\ x' = [2,0.5] \\ x_1' = 2 - 0.5(2(2) - 3 - 0.5) \\ \nabla x_1' = 0.5; \qquad x_1' = 1.75 \\ x_2 = 0.5 - 0.5(2(0.5) - 2) \\ \nabla x_2' = -1; \qquad x_2' = 1 \qquad \therefore l_{2-\text{norm}} = \sqrt{(0.5)^2 + (1)^2} = 1.118 \\ x^2 = [1.75, 1] \\ x_1^2 = 1.75 - 0.5(2(1.75) - 3 - 1) \\ \nabla x_1^2 = -0.5 \quad ; \qquad x_1^2 = 2 \\ x_2^2 = 1 - 0.5(2(1) - 1.75) \\ \nabla x_2^2 = 0.25; x_2^2 = 0.875 \qquad \therefore l_{2-\text{norm}} = \sqrt{(-0.5)^2 + (0.25)^2} = 0.559 \\ x^3 = [2, 0.875] \\ x_1^3 = 2 - 0.5(2(2) - 3 - 0.875) \\ \nabla x_1^3 = 0.125; \qquad x_1^3 = 1.9375 \\ x_2^3 = 0.875 - 0.5(2(0.875) - 2) \\ \nabla x_2^3 = -0.25; \qquad x_2^3 = 1 \qquad \therefore l_{2-\text{norm}} = \sqrt{(0.125)^2 + (-0.15)^2} = 0.28 \\ x^4 = [1.9375, 1] \\ x_1^4 = 1.9375 - 0.5(2(1.9375) - 3 - 1) \\ \nabla x_1^4 = -0.125; \qquad x_1^4 = 2 \\ x_2^4 = 1 - 0.5(24) - 1.9375 \qquad \therefore l_{2-\text{norm}} = \sqrt{(-0.125)^2 + (0.0625)^2} = 0.14 \\ \nabla x_2^4 = 0.0625; \qquad 0.96875 \\ x^5 = [2.0.96875] \end{array}$$

#### Exercise 5.1.c

 $f(x) = x_1^2 - 3x_1 + x_2^2 - x_1x_2$  With the Newton method, we need to find the Hessian matrix which is given as:

$$H = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 x_2} \\ \frac{\partial^2 f}{\partial x_2 x_1} & \frac{\partial^2 f}{\partial x_2^2} \end{bmatrix}$$

$$\frac{\partial f}{\partial x_1} = 2x_1 - 3 - x_2; \quad \frac{\partial^2 f}{\partial x_1^2} = 2 \text{ and } \frac{\partial^2 f}{\partial x_2} = 2x_2 - x_1; \quad \frac{\partial^2 f}{\partial x_2^2} = 2$$

$$\frac{\partial^2 f}{\partial x_1 \partial x_2} = -1 \text{ and } \frac{\partial^2 f}{\partial x_2 \partial x_1} = -1$$

$$\therefore \quad H = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

$$(H(f)|_{x_t})^{-1} = \frac{1}{3} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

$$\nabla f = \begin{bmatrix} 2x_1 - 3 - x_2 \\ 2x_2 - x_1 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} - 0.5 \begin{bmatrix} \frac{1}{3} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \end{bmatrix} \begin{bmatrix} 2x_1 - 3 - x_2 \\ 2x_2 - x_1 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} x_1 - \frac{3}{2} - \frac{1}{2}x_2 \\ -\frac{1}{2} + \frac{1}{2}x_2 \end{bmatrix}$$

$$\Rightarrow 2x_1 + \frac{1}{2}x_2 = -\frac{1}{2}$$

$$\frac{3}{2}x_2 = 3/2$$

$$x_2 = 1, x_1 = -0.5$$

#### Exercise 5.1.d

No. It is not always applicable as the function may be twice continuously differentiable but be constant throughout. Using the function for instance we have:

$$f = 2x^{3} - 5x$$

$$f'(x) = 6x^{2} - 5$$

$$f''(x) = 12x$$

$$for \quad x = 0; f''(x) = 0$$

$$(2)$$

This therefore will mean that there is a saddle point. in machine learning, we often do not want to get stuck in a saddle point.

# Exercise 5.2 Sigmoid Function

## Exercise 5.2.1 Sigmoid Function Derivation

$$\frac{d}{dx} \cdot (x) = \frac{d}{dx} \left[ \frac{1}{1 + e^{-2}} \right]$$

$$= \frac{d}{dx} \left( 1 + e^{-2} \right)^{-1}$$

$$= -\left( 1 + e^{-x} \right)^{-2} \left( -e^{-x} \right)$$

$$= \frac{e^{-x}}{(1 + e^{-x})^2}$$

$$= \frac{1}{1 + e^{-x}} \cdot \frac{e^{-x}}{1 + e^{-x}}$$

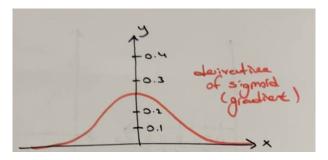
$$= \frac{1}{1 + e^{-x}} \cdot \frac{(1 + e^{-x}) - 1}{1 + e^{-x}}$$

$$= \frac{1}{1 + e^{-x}} \cdot \left( \frac{1 + e^{-x}}{1 + e^{-x}} - \frac{1}{1 + e^{-2}} \right)$$

$$= \frac{1}{1 + e^{-x}} \cdot \left( 1 - \frac{1}{1 + e^{-x}} \right)$$

$$= \sigma(x) \cdot (1 - \sigma(x))$$

### Exercise 5.2.2



The sigmoid function is differentiable in everywhere, which also indicates the sigmoid function is continous.

#### Exercise 5.2.3

$$f(x) = \frac{1}{1 + e^{-x}} \quad f(-x) = \frac{1}{1 + e^{x}}$$

$$\frac{1}{1 + e^{-x}} + \frac{1}{1 + e^{x}} = 1 \text{ (point symmotiic)}$$

$$(1 + e^{x}) (1 + e^{-x})$$

$$\frac{1 + e^{x} + 1 + e^{-x}}{(1 + e^{-x}) (1 + e^{x})} = 1 \rightarrow \frac{2 + e^{x} + e^{-x}}{1 + e^{x} + e^{-x} + e^{-x^{2}}} = 1$$

$$2 + e^{x} + e^{x} = 1 + e^{x} + e^{-k} + e^{-x^{2}}$$

$$1 = e^{-x^{2}}$$

$$\log 1 = \log e^{-x^{2}}$$

$$0 = -x^{2} \quad x = 0$$

### Exercise 5.2.4

$$\sigma(x) = \frac{1}{1 + e^{-z}} - 1$$

$$\sigma(x) = \frac{1}{1 + \sum_{k=0}^{\infty} \frac{(-x)^k}{k!}} - 1 = \frac{x}{4} - \frac{x^3}{48} + \frac{x^5}{480} - \frac{17x^7}{80640}$$

where x = 0

# Exercise 5.3 (Basics of Forward and Backward passes in computational graphs)

## Exercise 5.3.a

Forward pass:

$$h_{1} = ReLU(x_{1} * 2 + x_{2} * 1 + x_{3} * -2)$$

$$= ReLU(3 * 2 + 1 * 1 + -1 * -2)$$

$$= ReLU(9)$$

$$= max(0, 9)$$

$$= 9$$
(3)

$$h_{2} = ReLU(x_{1} * -1 + x_{2} * -3 + x_{3} * 5)$$

$$= ReLU(3 * -1 + 1 * -3 + -1 * 5)$$

$$= ReLU(-11)$$

$$= max(0, -11)$$

$$= 0$$
(4)

$$o'_{1} = h_{1} * 6 + h_{2} * -1$$
  
=  $9 * 6 + 0 * -1$  (5)  
=  $54$ 

$$o'_{2} = h_{1} * 2 + h_{2} * 8$$
  
=  $9 * 2 + 0 * 8$   
=  $18$  (6)

$$o_{1} = \frac{exp(o'_{1})}{exp(o'_{1}) + exp(o'_{2})}$$

$$= \frac{exp(54)}{(exp(54) + exp(18))}$$

$$\approx 1$$
(7)

$$o_{2} = \frac{exp(o_{2}')}{exp(o_{1}') + exp(o_{2}')}$$

$$= \frac{exp(18)}{exp(54) + exp(18)}$$

$$\approx 0$$
(8)

In a binary classification problem, the output will be the label that's corresponds for  $o_1$ . For example, if  $o_1$  corresponds for class 0, then the output is 0.

## Exercise 5.3.b

$$e = c * d$$

$$\Rightarrow \frac{\partial e}{\partial c} = d \quad and \quad \frac{\partial e}{\partial d} = c \tag{9}$$

$$c = a + b$$

$$\Rightarrow \frac{\partial c}{\partial a} = 1 \quad and \quad \frac{\partial c}{\partial b} = 1$$
(10)

$$d = b + 1$$

$$\Rightarrow \frac{\partial d}{\partial b} = 1 \quad and \quad \frac{\partial d}{\partial a} = 0 \tag{11}$$

Therefore, we have

$$\frac{\partial e}{\partial b} = \frac{\partial e}{\partial c} * \frac{\partial c}{\partial b} + \frac{\partial e}{\partial d} * \frac{\partial d}{\partial b}$$
 (12)

and

$$\frac{\partial e}{\partial a} = \frac{\partial e}{\partial c} * \frac{\partial c}{\partial a} + \frac{\partial e}{\partial d} * \frac{\partial d}{\partial a} = \frac{\partial e}{\partial c} * \frac{\partial c}{\partial a}$$
(13)

## Exercise 5.4 - Weight Space Symmetry

## Exercise 5.4.a

The number of ways to interchanges (both input and output) weights of neurons is equal to the number of permutations of M neurons: M!.

The number of ways to choose neurons for change of sign of input weight and output weights are:  $2^{M}$ .

Therefore, the total number of equivalent transformations is  $M! * 2^M$ 

## Exercise 5.5 (Hessian and Optimization: Bonus)

#### Exercise 5.4.b

With N layers, each layer has  $M!*2^M$  equivalent transformations. The total number of equivalent transformations is  $(M!*2^M)^N$ .

#### Exercise 5.5.a

- Figure a: Hessian is positive because it is a convex curve.
- **Figure b:** The Hessian has negative eigenvalues because it is a concave curve.
- Figure c: The Hessian has one positive/negative and one eigenvalue been 0
- **Figure d:** The Hessian has one eigenvalue been positive and the other negative.

#### Exercise 5.5.b

- **Figure a:** Hessian is positive-definite of all positive eigenvalues concave-up or convex.
- **Figure b:** Hessian is negative-definite of all positive eigenvalues concave-up or convex.
- **Figure c:** Hessian is neither but it could also be a semi-positive definite incase the other eigenvalue is positive.

• Figure d: Hessian is neither.