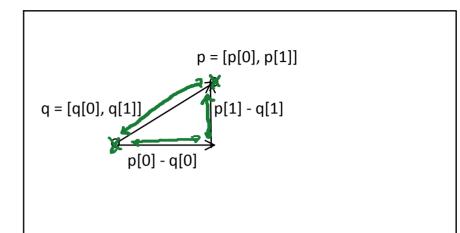
Point/point distance

Two points

Math - points on canvas p, q

Python - list of coordinates [p[0], p[1]], [q[0], q[1]]



Pythagorean theorem

Math
$$\int dist(p, q)^2 == (p[0] - q[0])^2 + (p[1] - q[1])^2$$

Python def dist(p, q):

return math.sqrt((p[0] - q[0]) ** 2 + (p[1] - q[1]) ** 2)

Vectors and motion

Vector as difference of two points

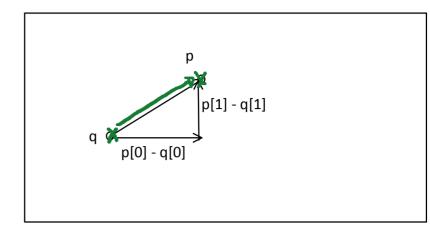
Math



Python - list of components

$$-v[0] = p[0] - q[0]$$

$$\sim$$
 v[1] = p[1] - q[1]



Move/translate point using a vector

Math

Python

$$p[0] = q[0] + v[0]$$

$$p[1] = q[1] + v[1]$$

Update for motion

Math - point at position p with velocity \boldsymbol{v}

$$p = p + a * v$$

Python

$$p[0] = p[0] + a * v[0]$$

$$p[1] = p[1] + a * v[1]$$

Collisions

Motion update

$$p[0] = p[0] + a * v[0]$$

 $p[1] = p[1] + a * v[1]$

Collision of ball of with center p and radius r with wall

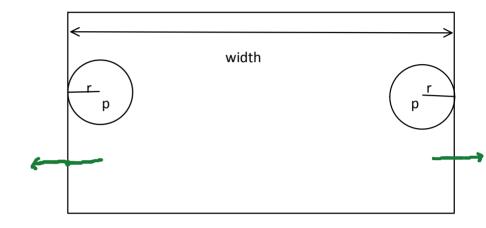
Left wall p[0] <= r

Right wall p[0] >= (width - 1) - r

Collision of point p with wall

Left wall p[0] <= 0

Right wall p[0] >= width - 1



Reflections

Reflections - update the velocity vector \mathbf{v}

Motion update

$$p[0] = p[0] + a * v[0]$$

 $p[1] = p[1] + a * v[1]$

Left wall
Compute reflected velocity vector

$$v[0] = -v[0]$$

