



# **Earth Observation Data Analysis**

## **HOMEWORK03 - SURFACE DETECTION FROM SAR SENTINEL-1 DATA**

**Objective:** explore Sentinel-1 SAR data for estimating vegetation cover, inland water, chlorophyll-a sea concentration and supervised classification within a region of interested (ROI).

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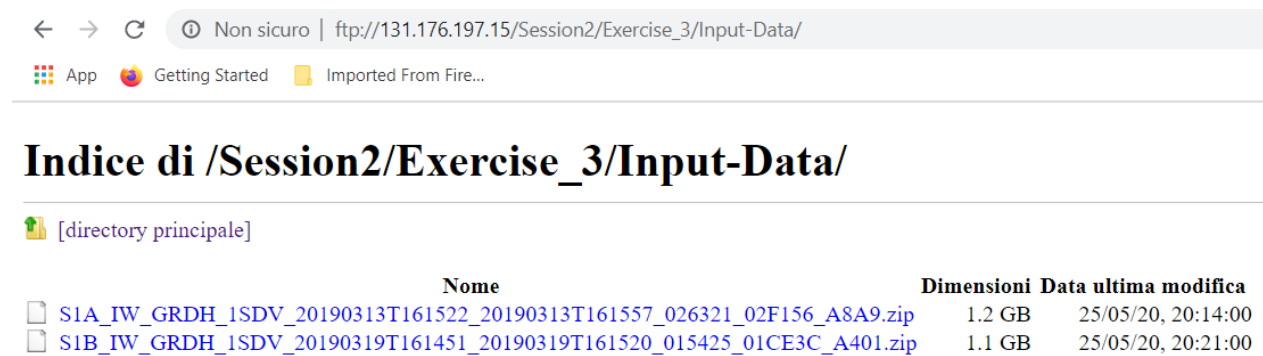
**UWAMAHIRWE BONAVENTURE - 1850306**

**REZA POURRAHIM - 1859334**

**HAFIZ MUHAMMAD HASSAN - 1873829**

July 2020

The input data is downloaded from this ftp:



The screenshot shows a web browser interface for an FTP directory. The address bar displays 'Non sicuro | ftp://131.176.197.15/Session2/Exercise\_3/Input-Data/'. Below the address bar, there are navigation icons and a status bar. The main content area shows the directory index for '/Session2/Exercise\_3/Input-Data/'. It includes a link to the principal directory '[directory principale]' and a table of files.

Nome	Dimensioni	Data ultima modifica
<a href="#">S1A_IW_GRDH_1SDV_20190313T161522_20190313T161557_026321_02F156_A8A9.zip</a>	1.2 GB	25/05/20, 20:14:00
<a href="#">S1B_IW_GRDH_1SDV_20190319T161451_20190319T161520_015425_01CE3C_A401.zip</a>	1.1 GB	25/05/20, 20:21:00

The data that is going to be used ,based on ship detection, flood detection and earthquake detection :

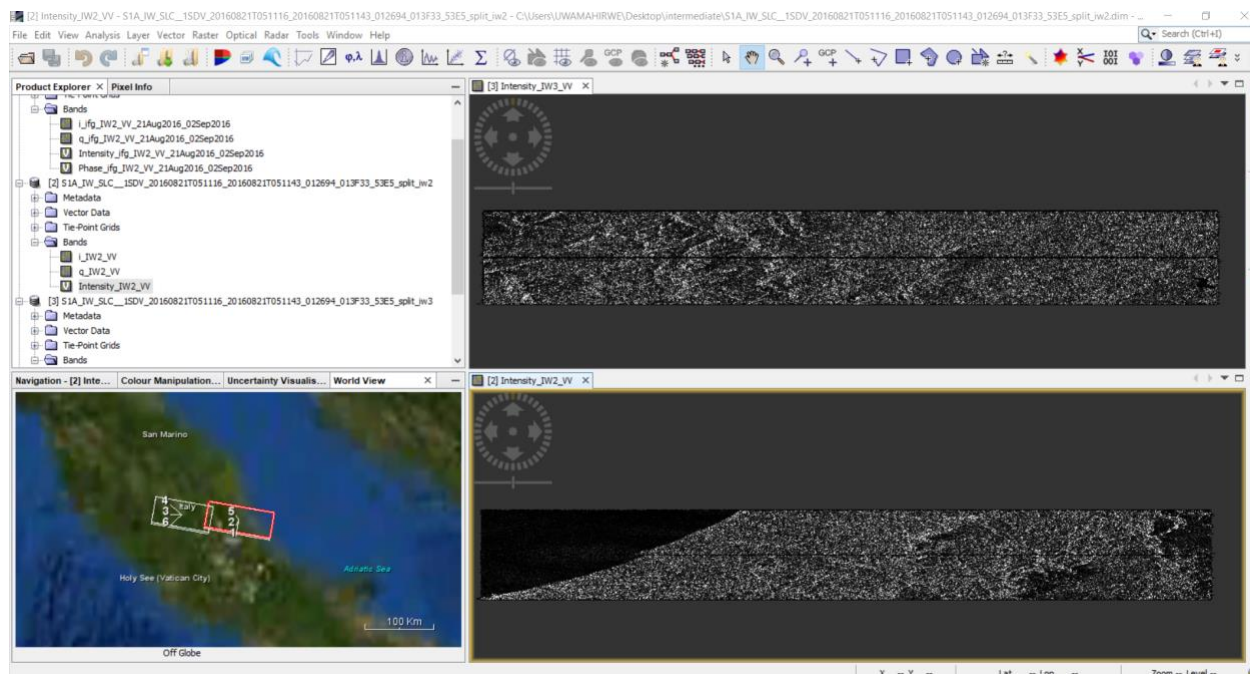
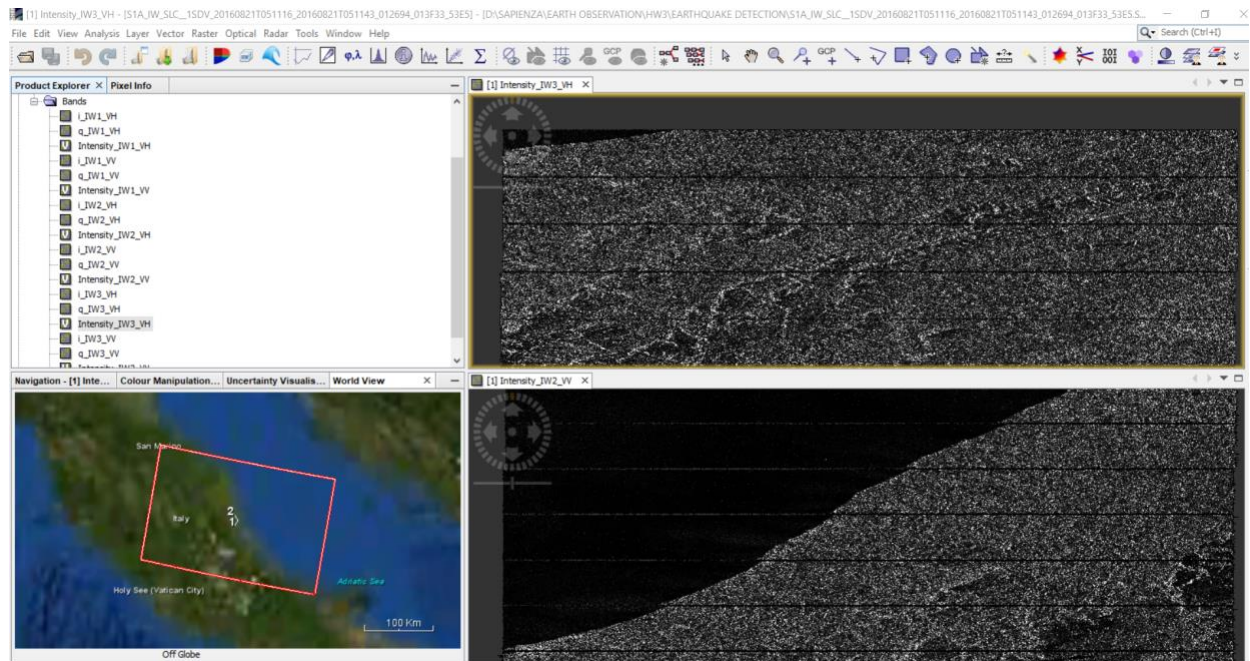
### Download Sentinel-1 SAR data

- ✓ Pre-Event Acquisition (master) - 21 August 2016  
S1A\_IW\_SLC\_\_1SDV\_20160821T051116\_20160821T051143\_012694\_013F33\_53E5.SAFE
- ✓ Post-Event Acquisition (slave) – 02 September 2016  
S1A\_IW\_SLC\_\_1SDV\_20160902T051117\_20160902T051144\_012869\_014526\_DFB4.SAFE
- ✓ Selected Product Ship detection:  
S1A\_IW\_GRDH\_1SDV\_20200128T050429\_20200128T050454\_030996\_038F5D\_4119.SAFE
- ✓ Selected Product Flood:  
S1A\_IW\_GRDH\_1SDV\_20190313T161522\_20190313T161557\_026 321\_02F156\_A8A9.SAFE  
S1B\_IW\_GRDH\_1SDV\_20190319T161451\_20190319T161520\_015425\_01CE3C\_A401.SAFE

## 1. EARTHQUAKE DETECTION BY SAR DIFFERENTIAL INTERFEROMETRY

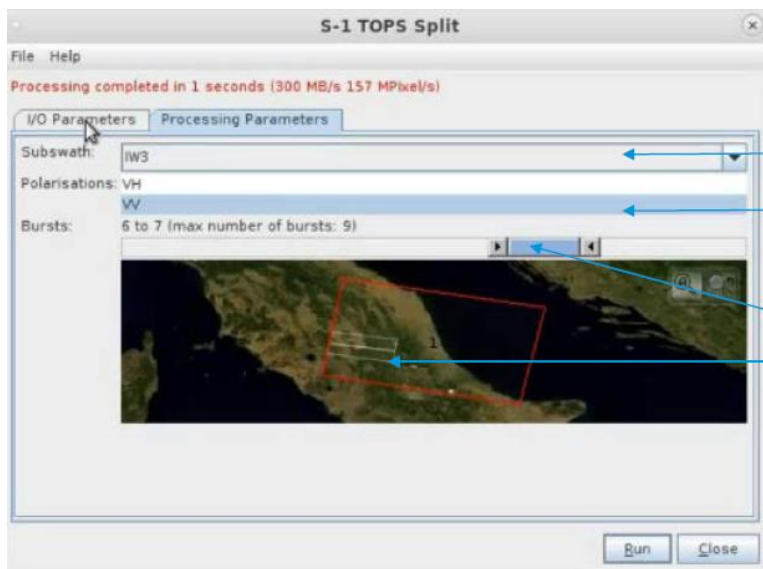
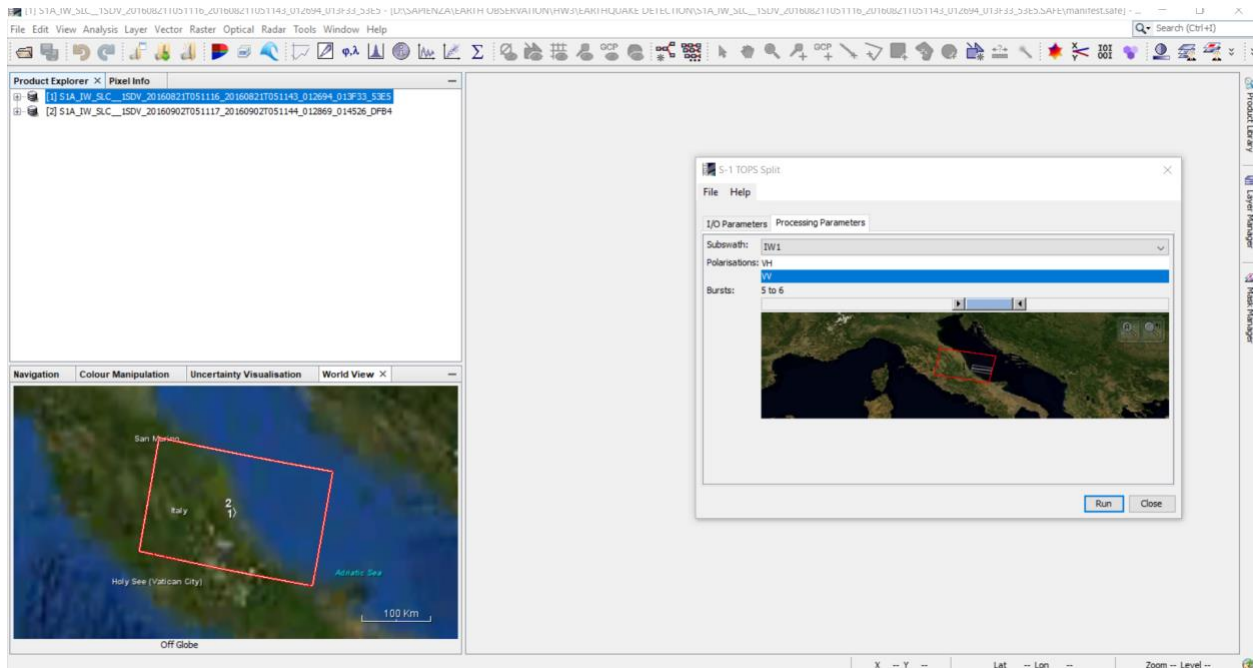
### Amatrice Earthquake in central Italy on 24 August 2016

- a. data band exploration and geolocation for IW2/IW3 subswaths for master/slave images



## b. Subswath/burst TOPSAR splitting

we change subswath IW2 and IW3 then we choose polarization to VV and change bursts to 5-6 to IW2 and subswath IW3 to VV polarization then bursts to 6-7

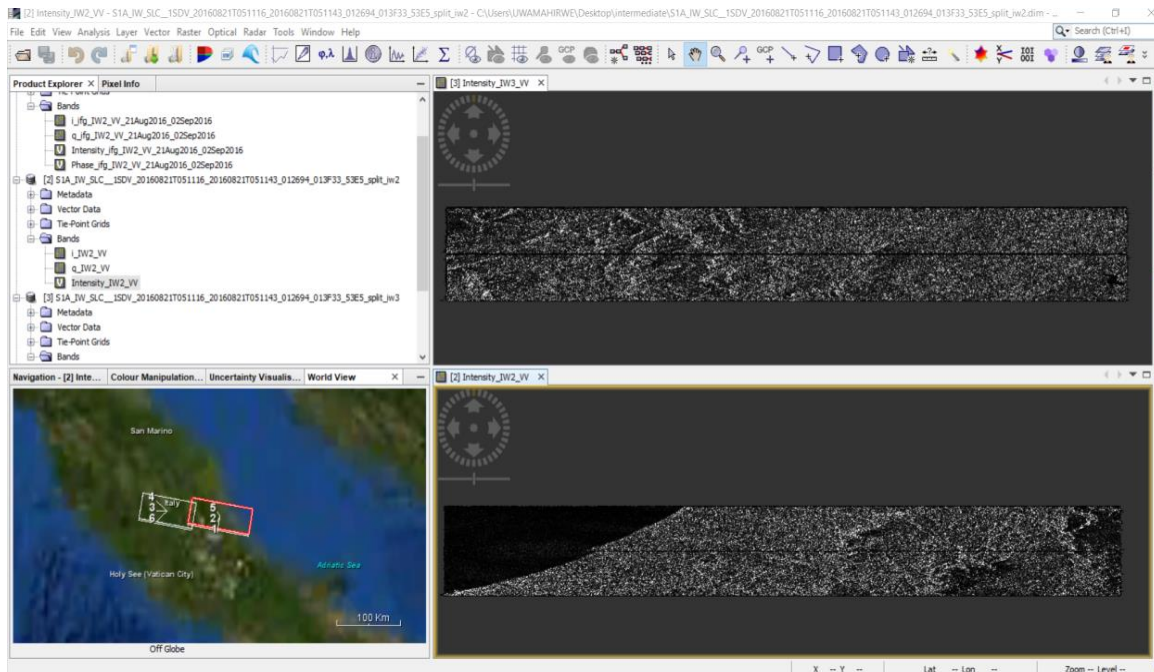


Subswath IW3

VV Polarisation

Bursts: 6-7





### c. Orbit precisising and interferogram generation/backgeocoding

Passing from linear scale to the logarithmic scale  
Changing detection between master and slave

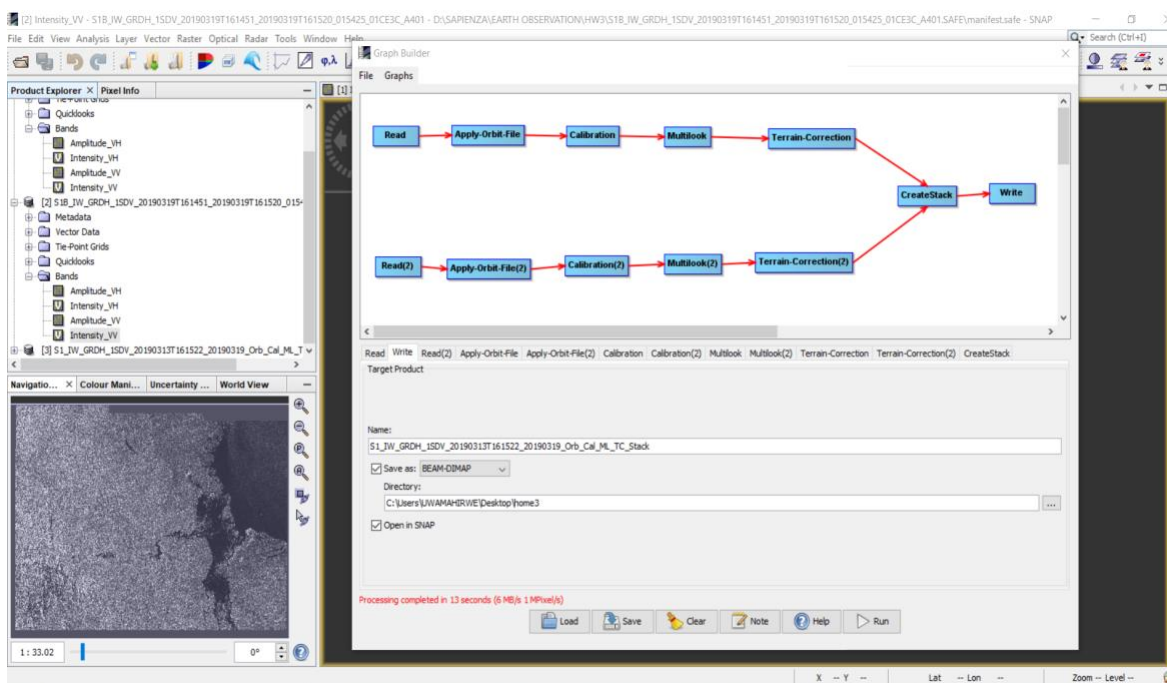
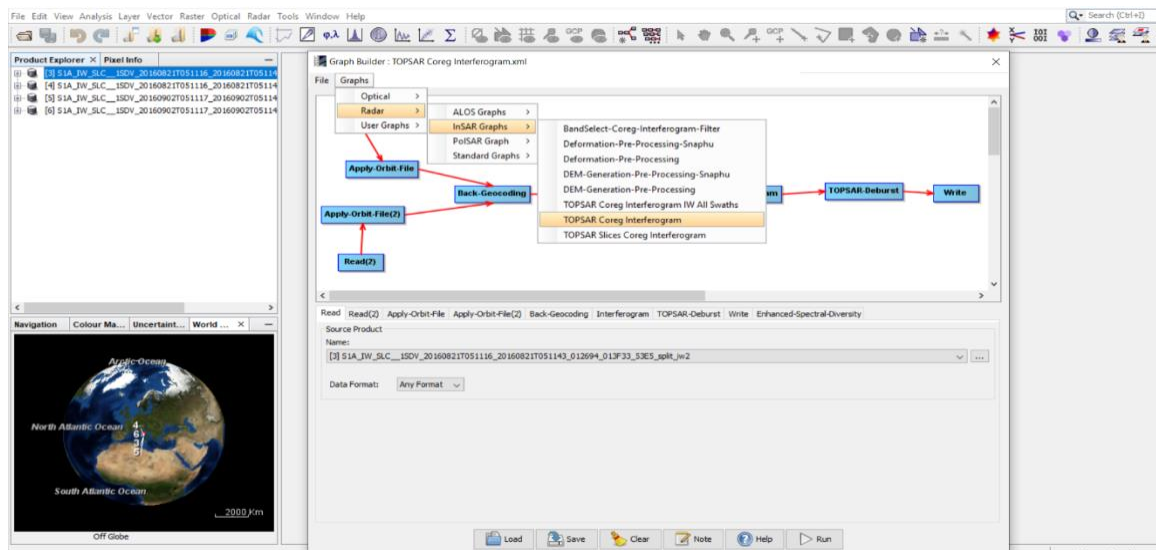
#### IW2 vs IW3

Due to the operating mode of sentinel 1, we have to observe the intensity mode IW2 in bands which has 9 burst, Before splitting this product we shall use the mode TOPSAR, since the earthquake didn't take the whole region we have to save some computation time by taking the small place where we know that has had effect due to the earthquake, we will select some few area after the earthquake.

Back geo-coding is used to register the master acquisition and slave acquisition

Before computing the compute, the interferogram, we added enhanced spectral diversity operator which is needed to compensate some issues that are present between two consecutive burst.

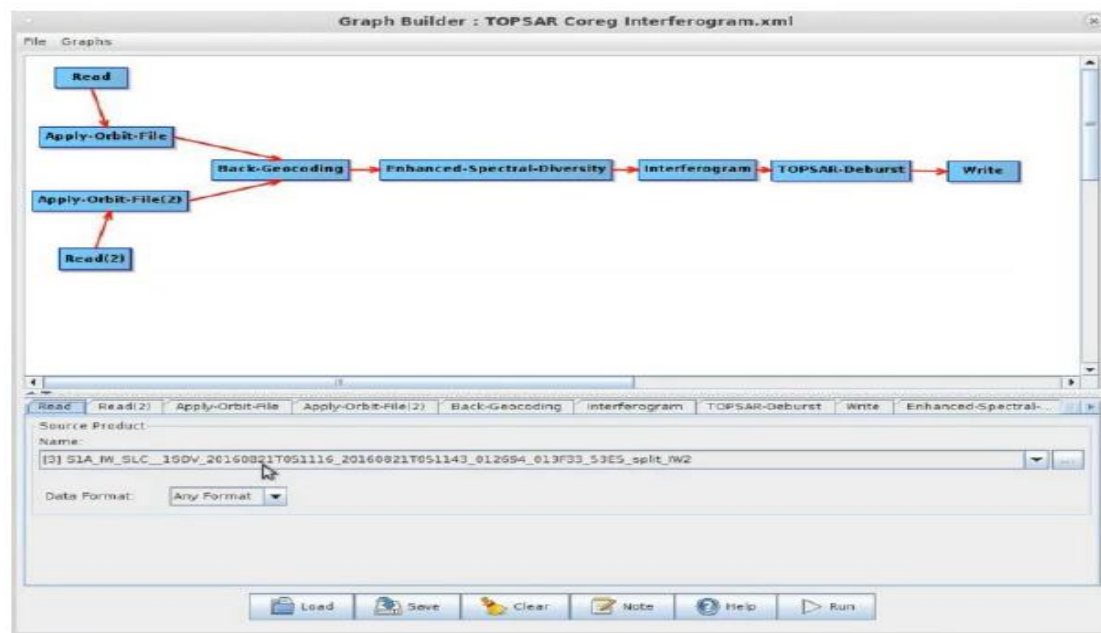
The first read operator should have the master acquisition of 20160821... and the second read should have the slave acquisition 20160902.



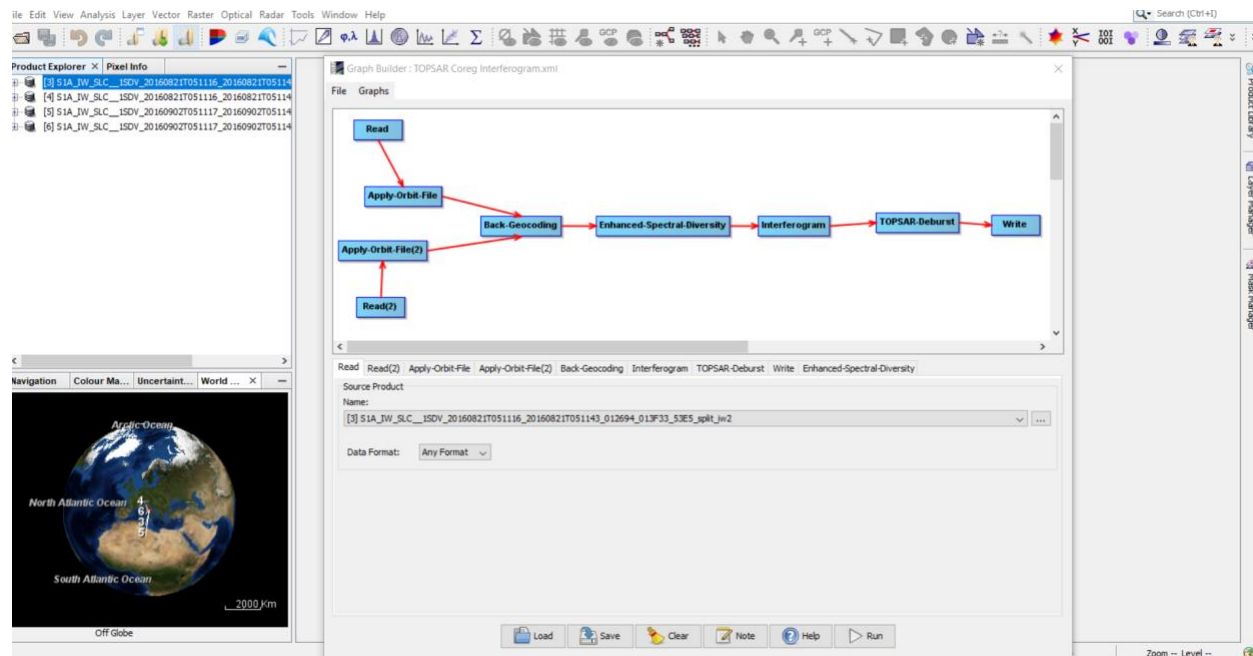


d. Spectral-diversity enhancement and TOPSAR debursting

Graphs->Radar->InSAR Graphs->TOPSAR Coreg Interferogram Adapt the graph template removing the “TOPSAR Split” blocks (already applied) and adding the “Enhanced Spectral Diversity”



e. interferogram flattening and coherence generation



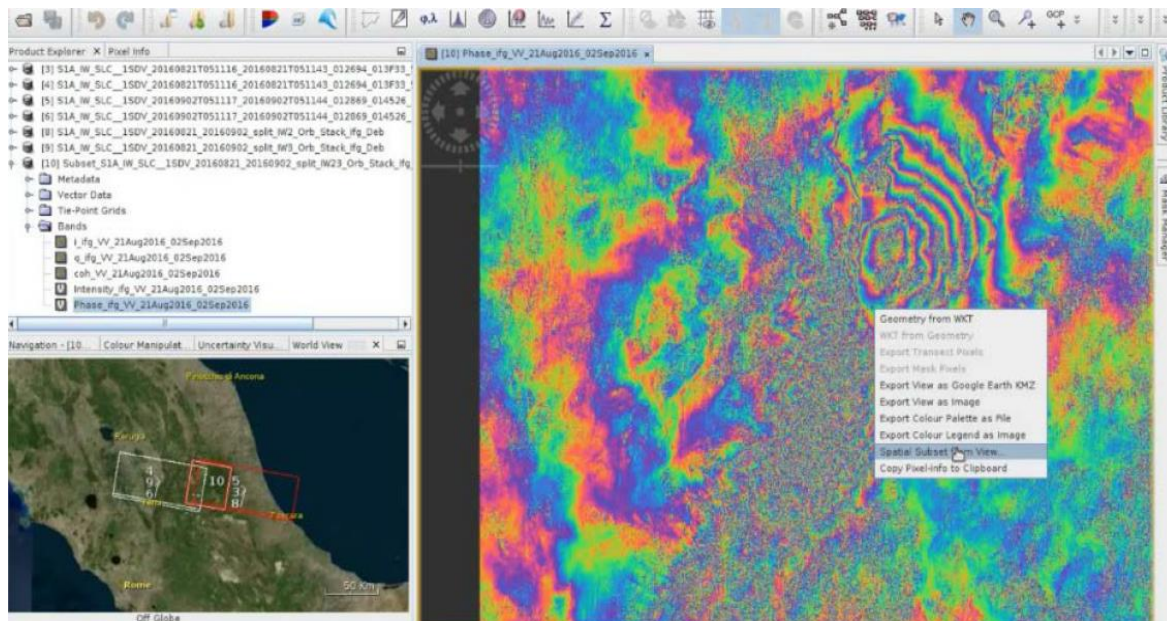
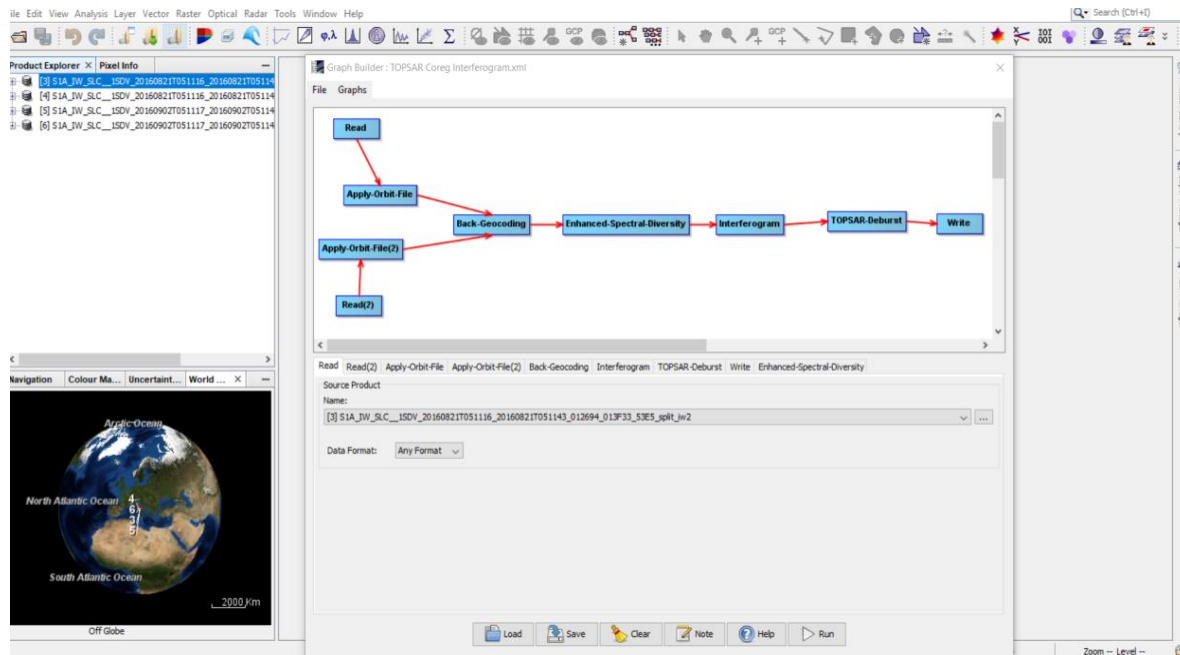
- f. topographic phase subtraction and ROI subsetting
- g. phase filtering and multilooking
- h. no-data subsetting for smaller ROI

The formulation of this three exercises(f,g,h) is one process which hold many operators and each operators has its own features but some of them ,we changed their features others we let it by default as it is discussed down here.

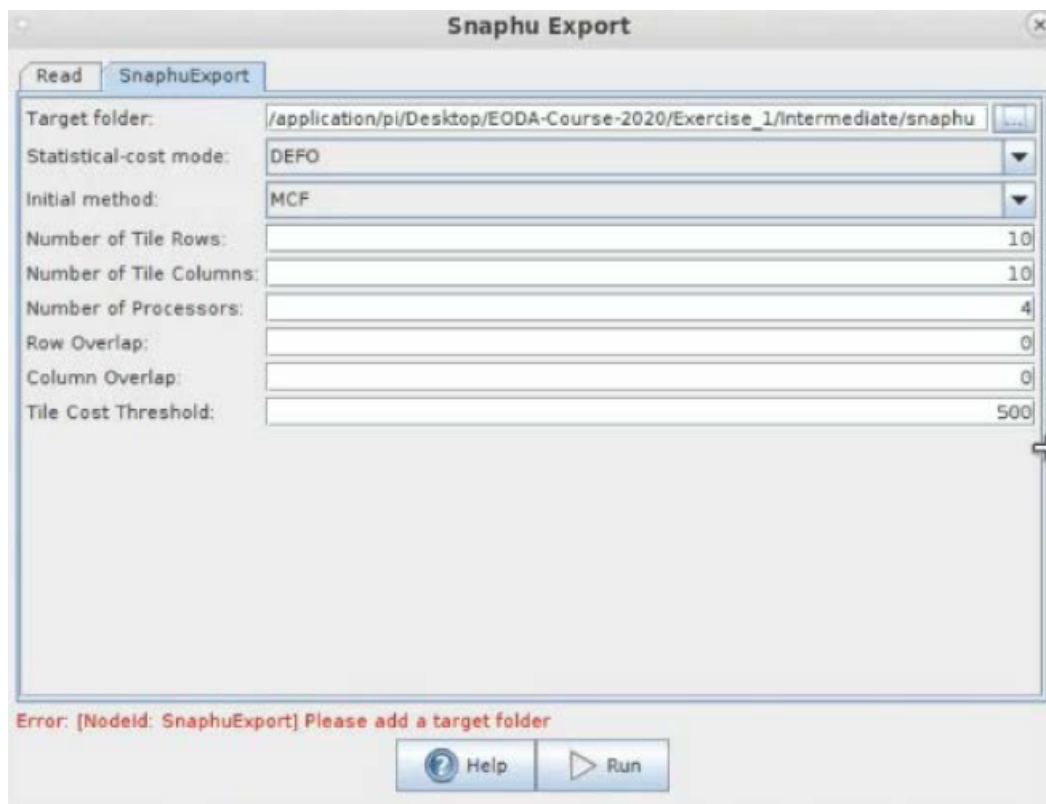
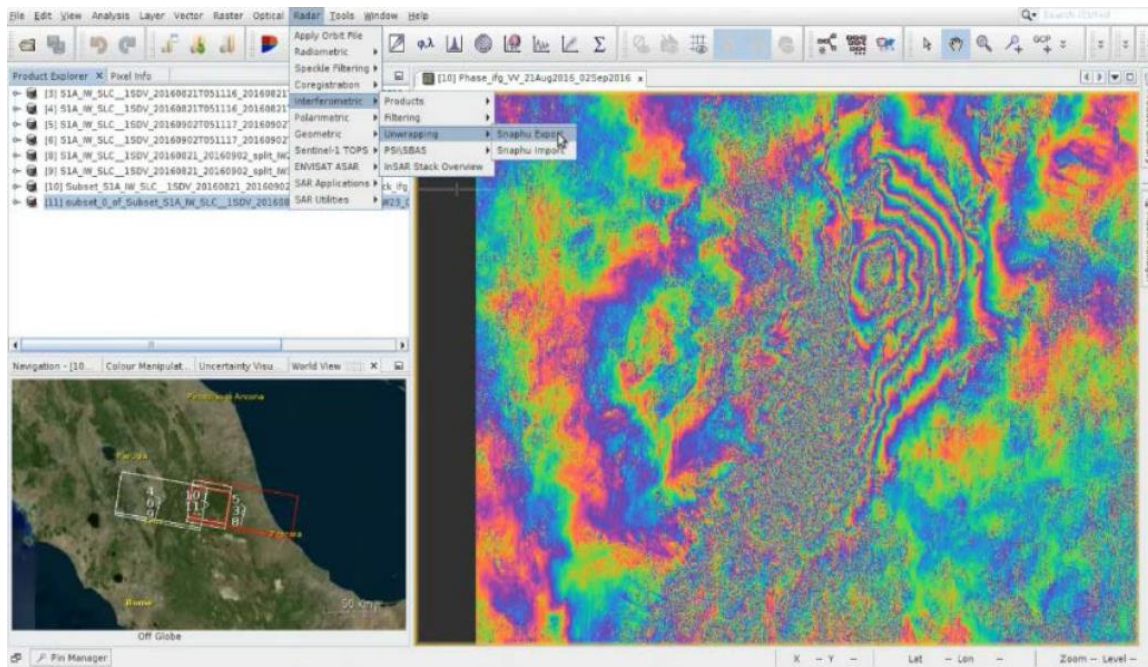
After creating the IW2 and IW3 interferogram we need to merge them and run the following workflow:

- Subtract the topographic phase (Differential SAR Interferometry)
- Subsetting over defined AOI
- Goldstein Phase Filtering
- Multilooking

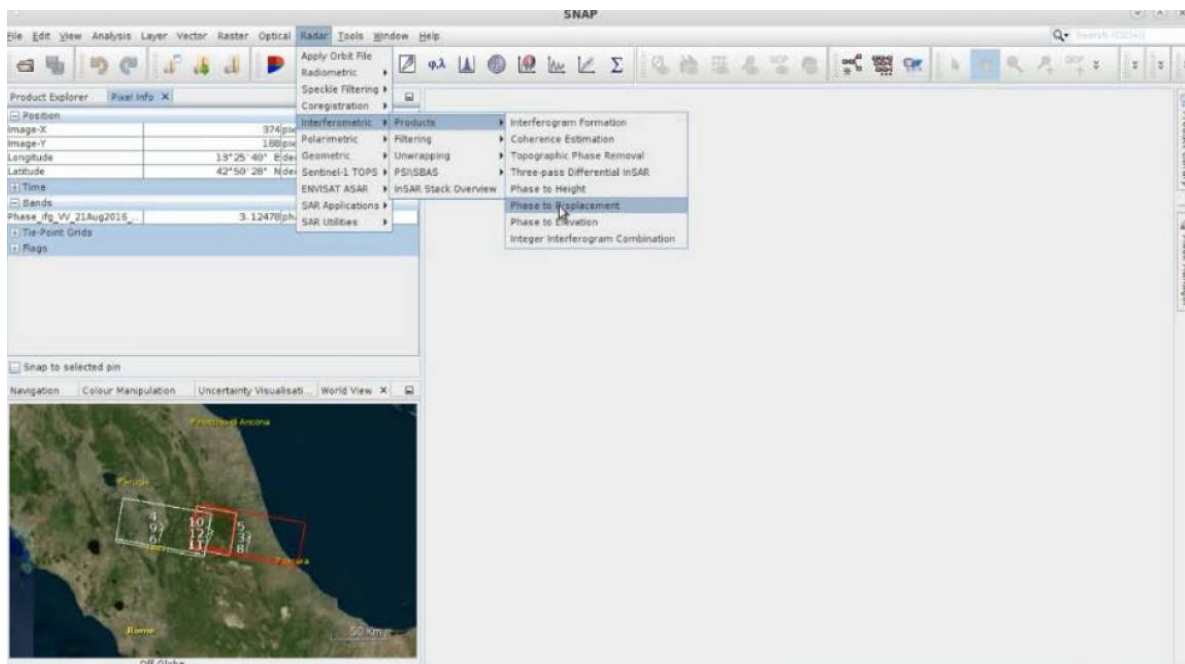
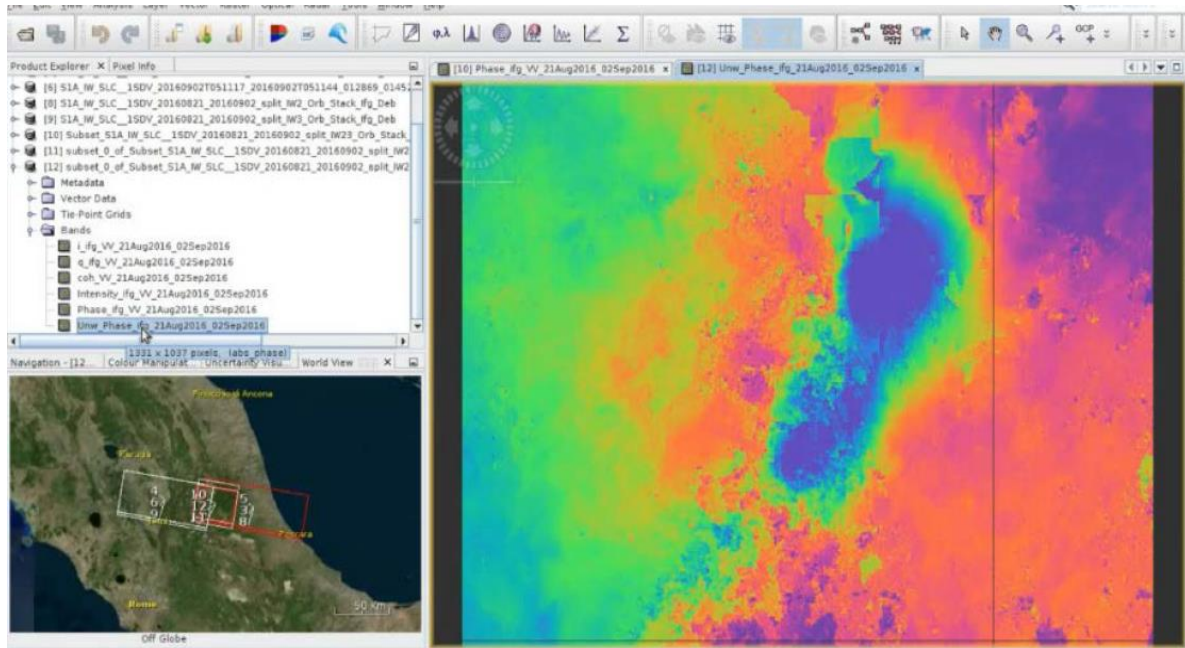




i. Phase-unwrapping by SNAPHU external operator

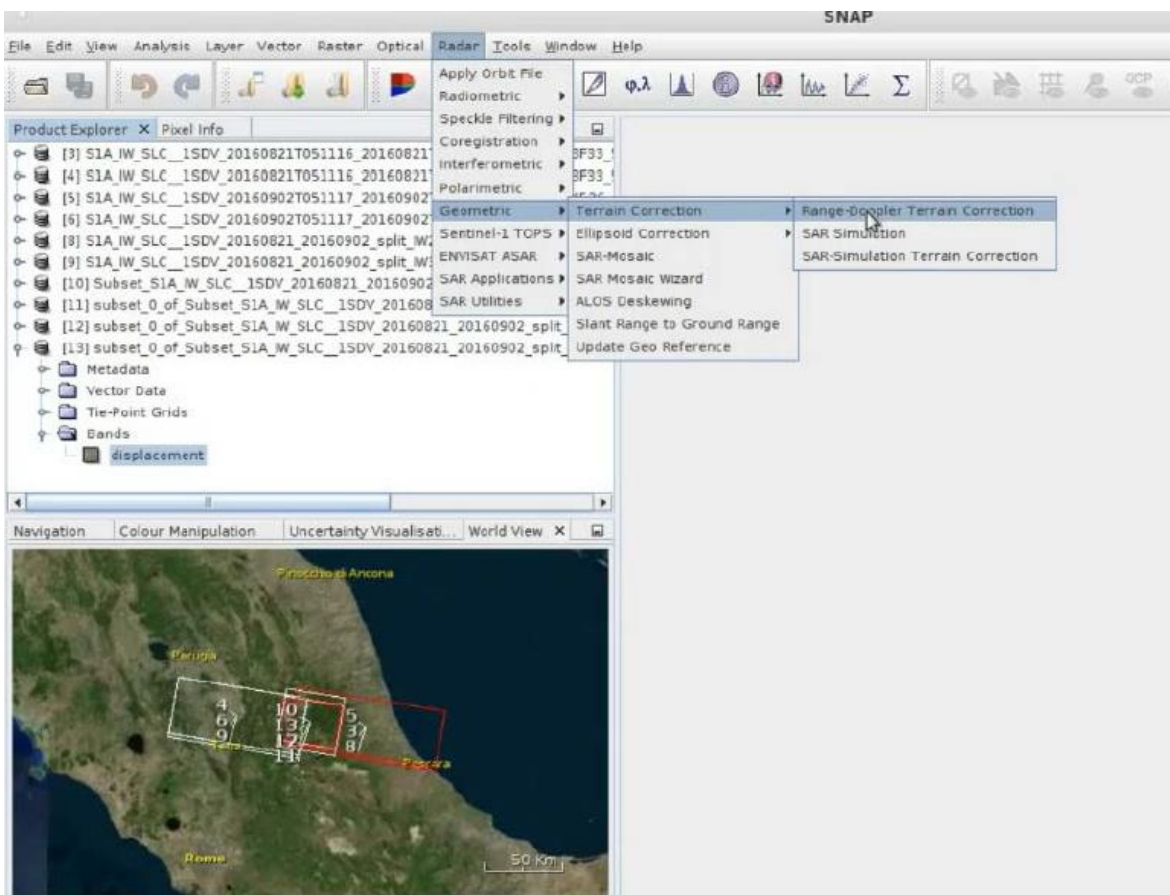
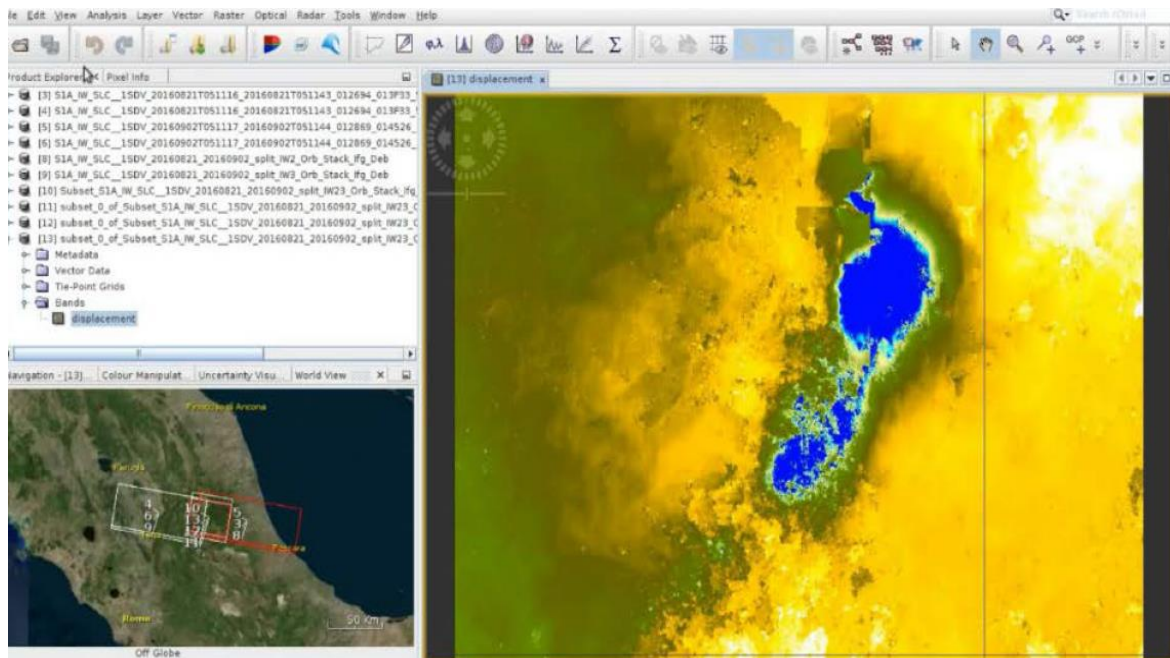


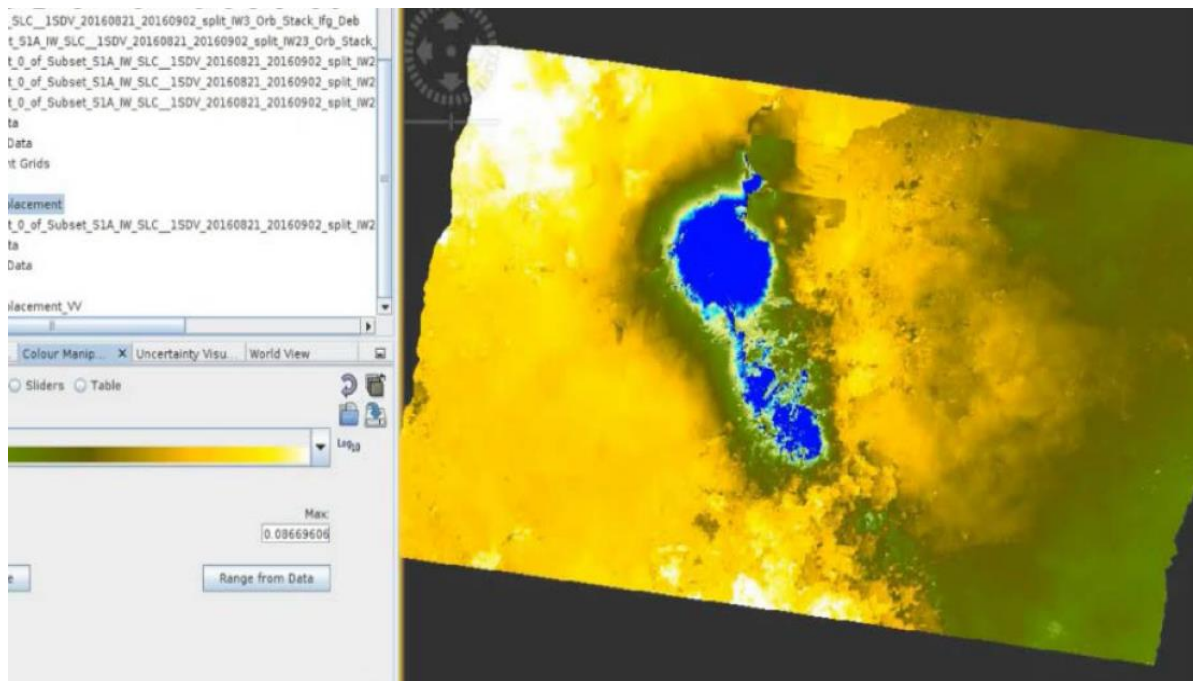
j. phase-to-displacement conversion along line-of-sight (LOS)



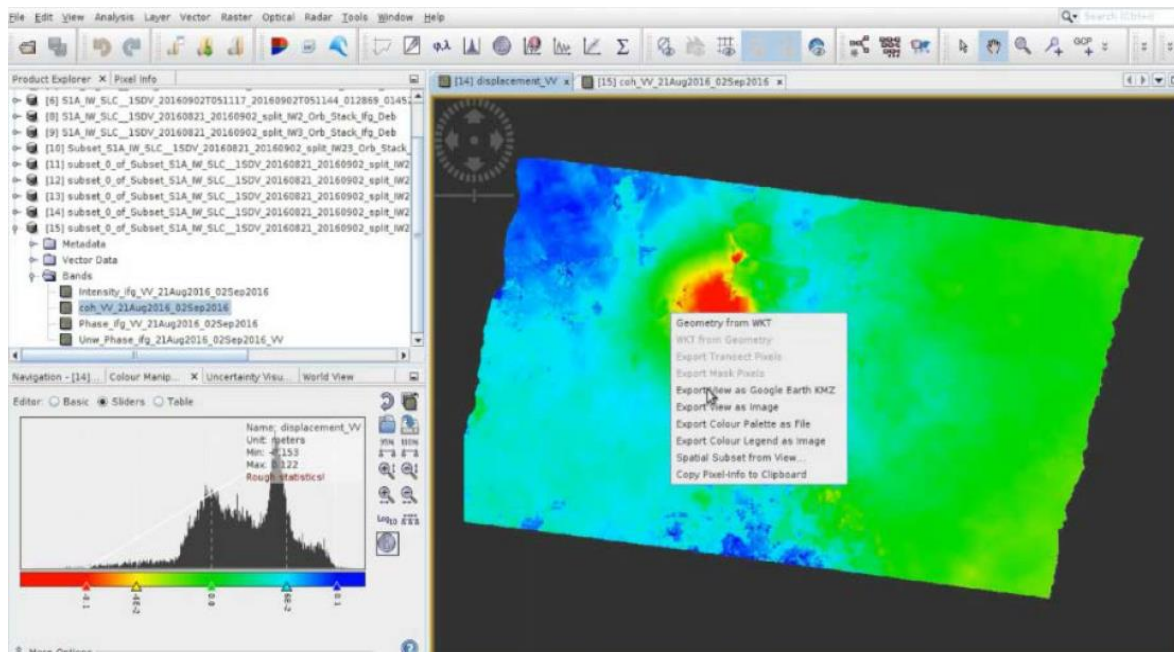


k. terrain-correction projection and false-color visualization



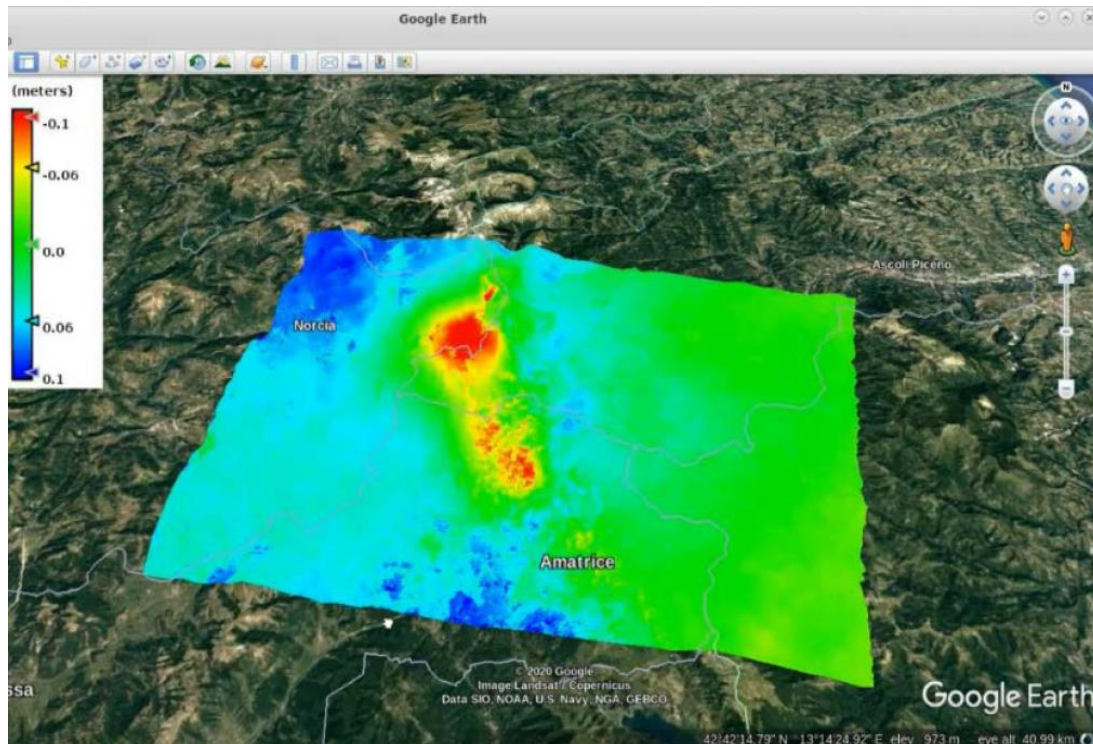


1. Exporting the terrain-corrected map as KMZ and visualizing on G-Earth.



Mapping KMZ in Google Earth



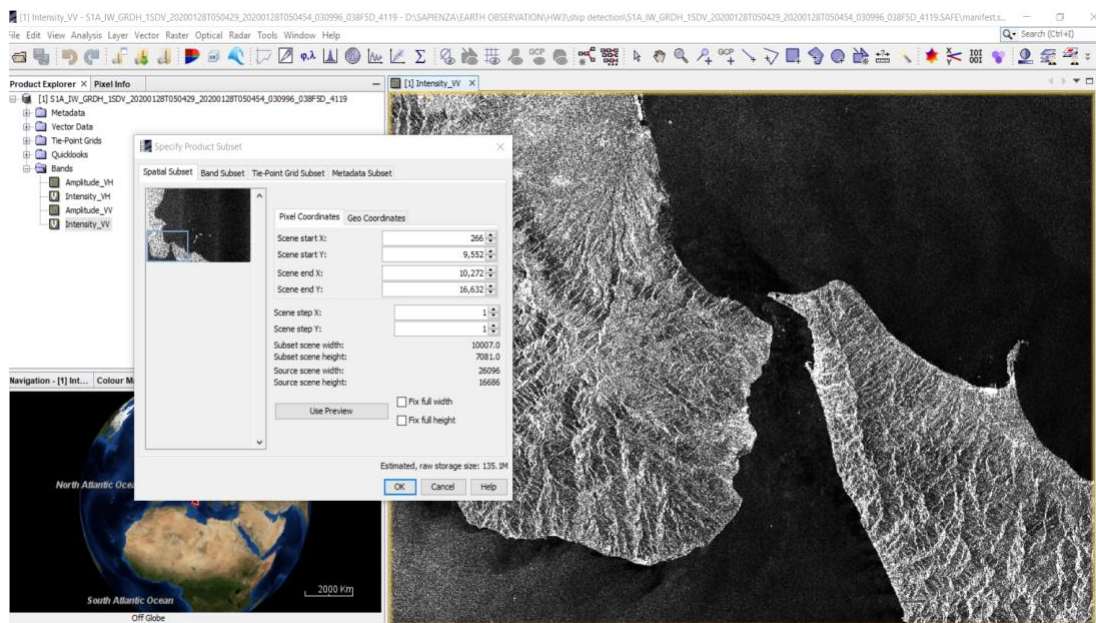


## 2. SHIP DETECTION BY SAR BACKSCATTERING Messina strait in southern Italy on 28 January 2020

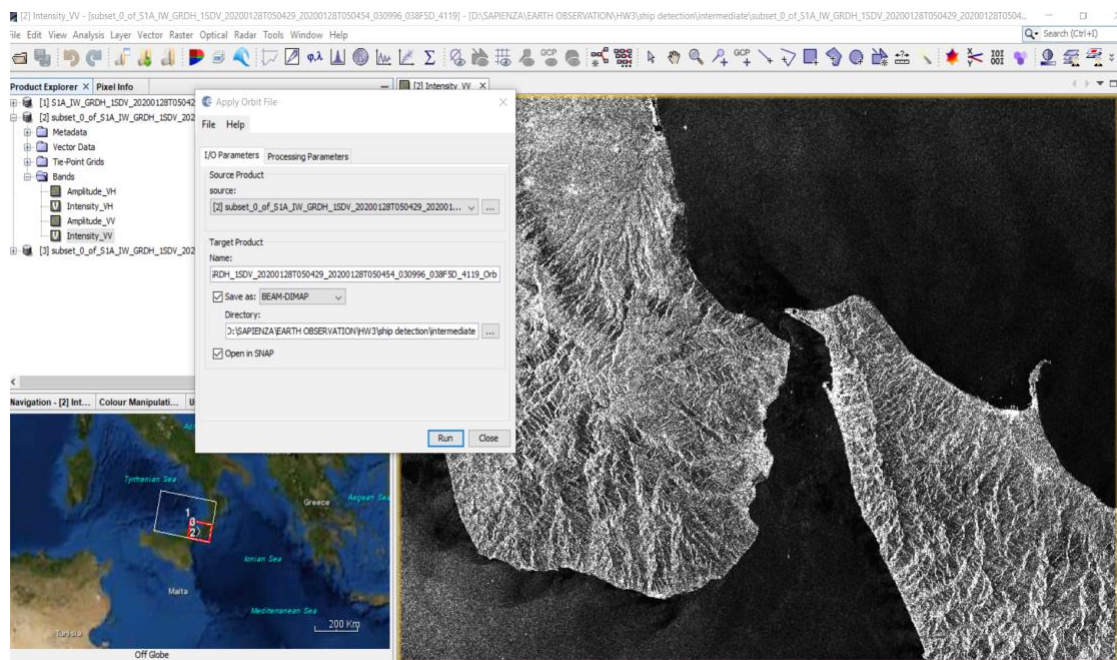
Perform the SAR processing steps:

- data band exploration and subsetting for ROI

we perform spatial subset in order to perform out interest which is Messina strait in southern Italy

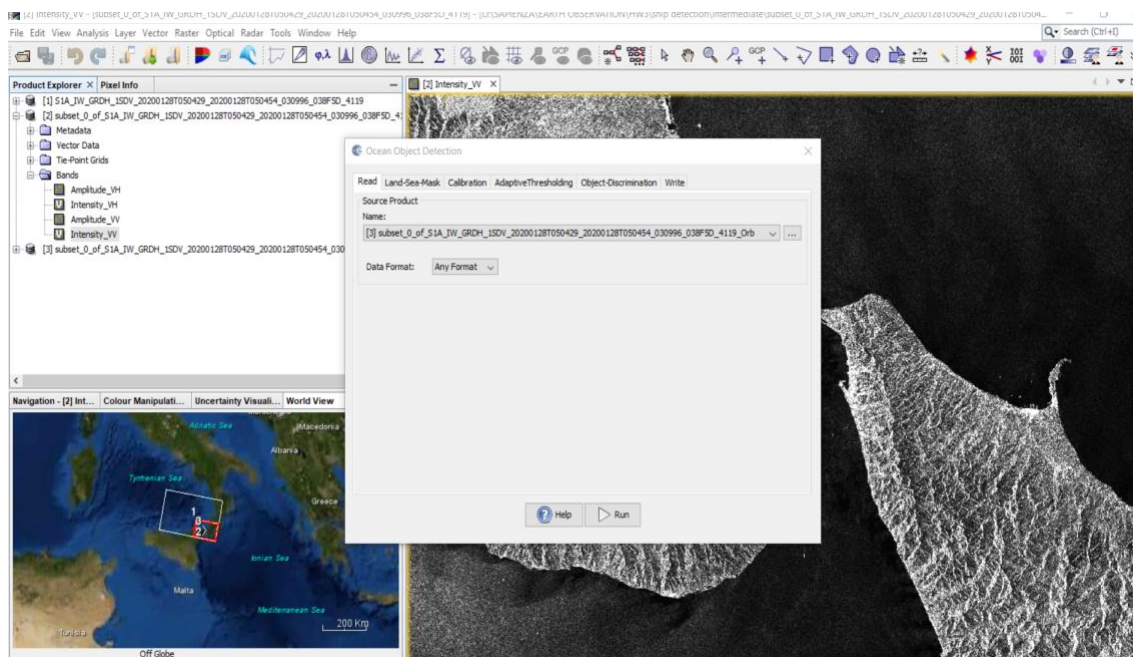


## b. orbit precising



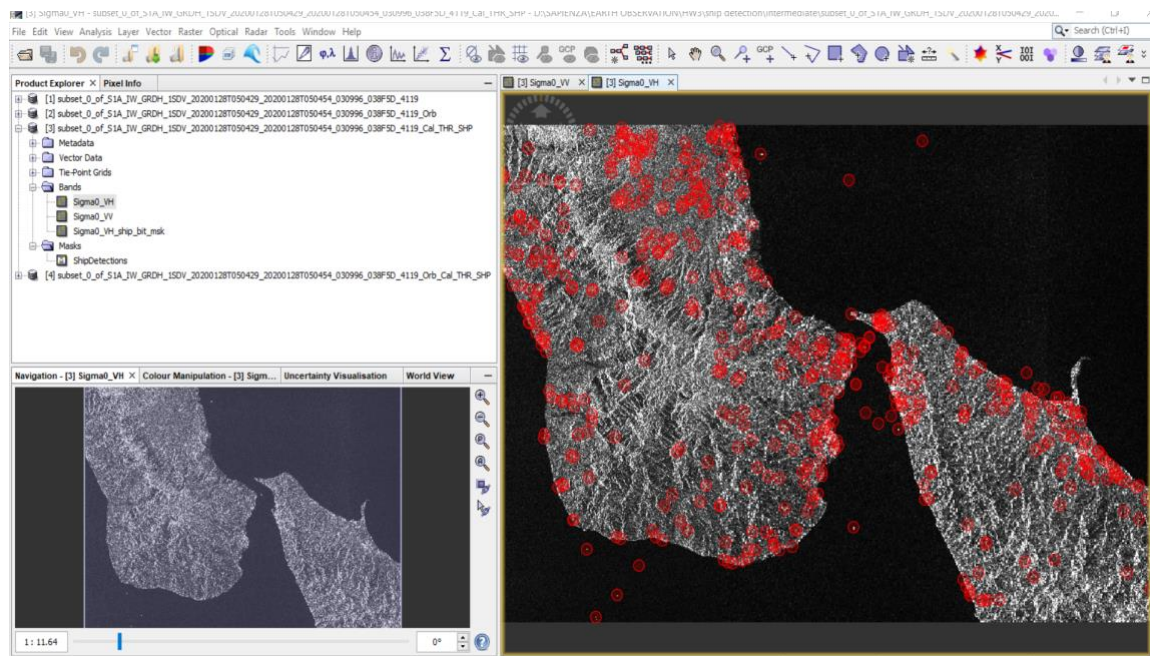
## c. Land-sea masking and calibration

we have the workflow of the object detection from read >land-sea-mask > calibration->adaptive thresholding > object discrimination > write. Then we need to mask out the land because we are focusing on sea through then we increase the number of pixel up to 50, for calibration and adaptive thresholding ,we let with default value.

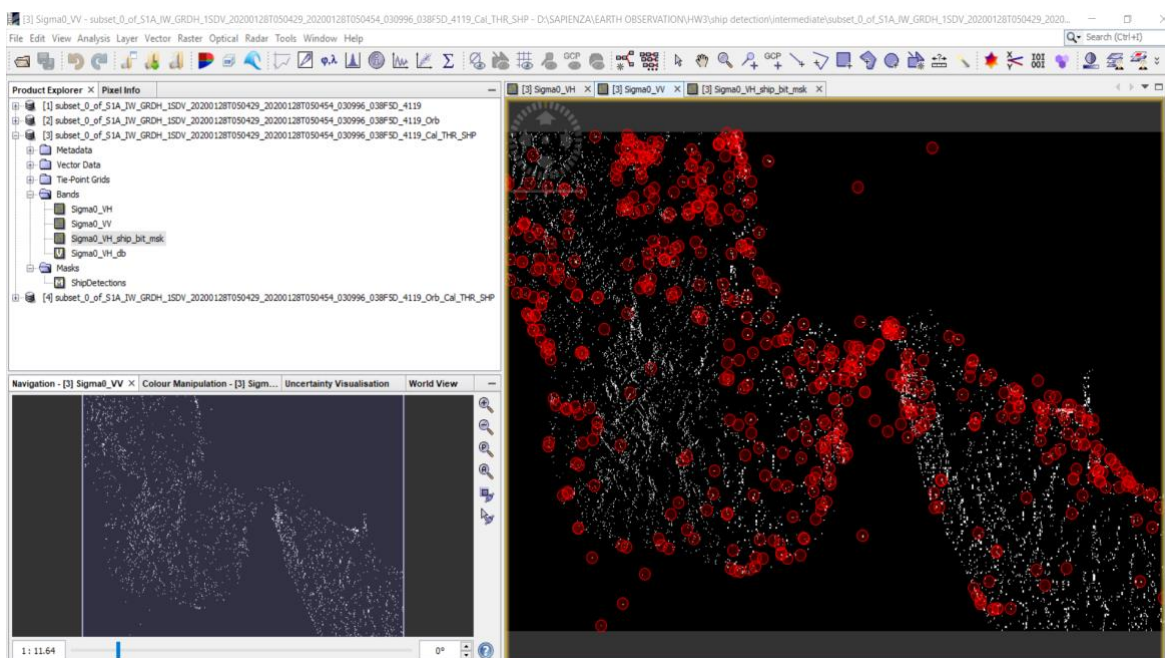




d. adaptive thresholding by appropriate windowing and probability of false alarm (PEA)



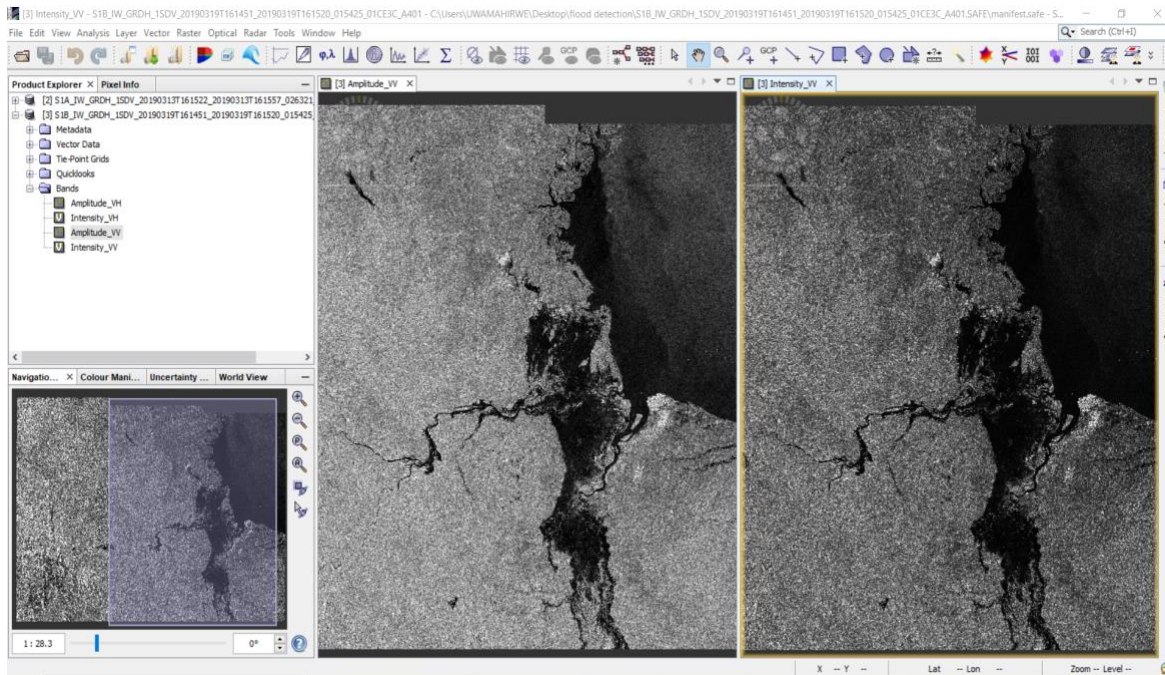
e. object discrimination by min-max sizing and conversion to decibels (dB)



### 3. FLOOD DETECTION BY SAR BACKSCATTERING Flood in Mozambique on 13 March 2019

Perform the DInSAR processing steps:

- a. data band exploration and subsetting for ROI  
we choose GRDH since we want to focus on amplitude and intensity



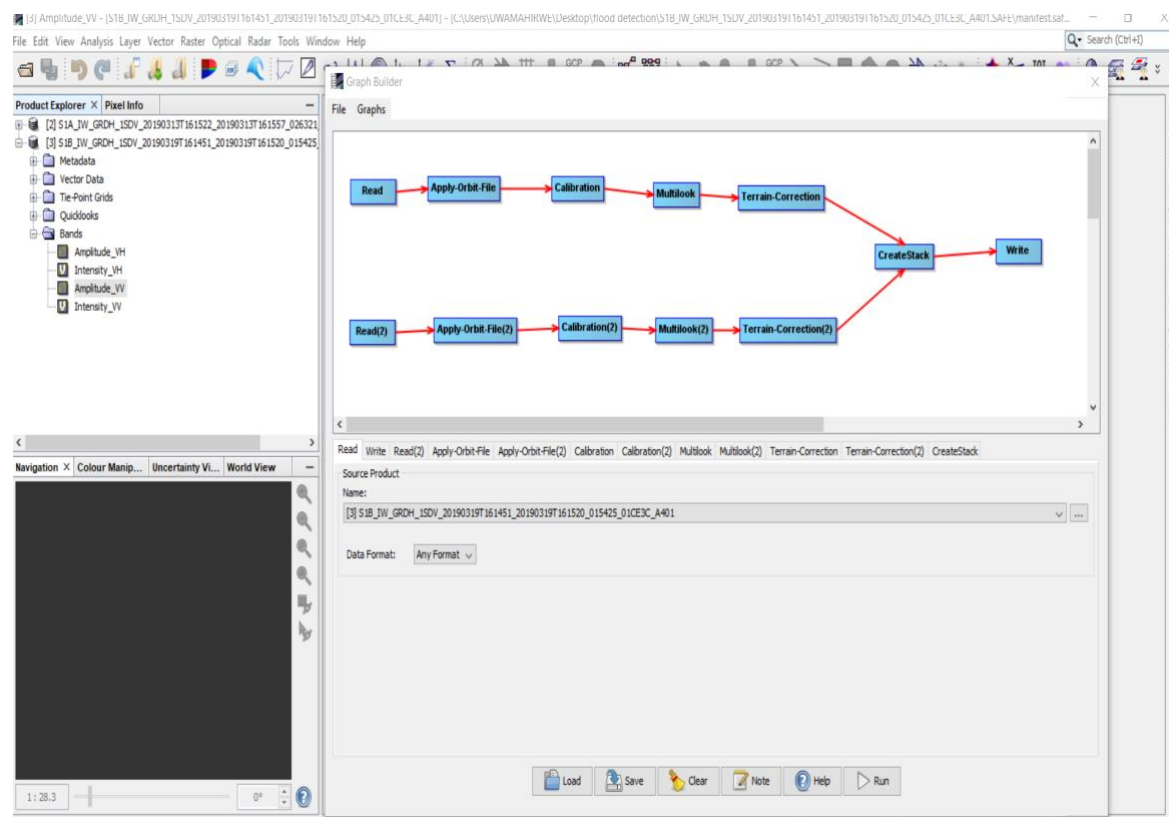
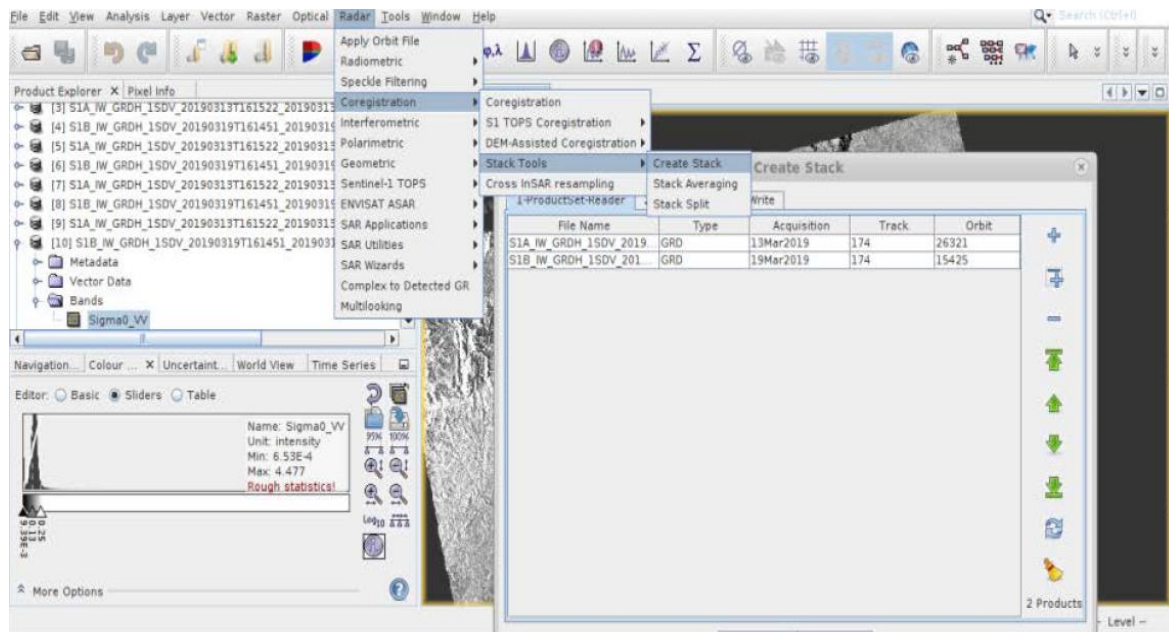
- b. orbit precisising and projection
- c. calibration and multilooking
- d. terrain correction
- e. image stacking

The formulation of this 4 exercises(b,c,d,e) is one process which hold many operators and each operators has it's own features but some of them ,we changed their features others we let it by default as it is discussed down here.

read -> apply-orbit-file-> calibration-> multilook -> terrain-correction ->  
createstack -> write

read(2) -> apply-orbit-file(2)-> calibration(2)-> multilook(2) -> terrain-correction(2) ->

read operator 20190313 file then for apply-orbit-file operator we set default setting,on calibration operator we choose VV polarization and we choose the output sigma 0,on multilook operator,we increase the number of loops ,we can loose some pixel but we are looking forward to increase our multilooking model.terrain-correction operator we set by default,on create stack operot we change initial offset method to geolocation.





f. Thresholding, sigma-0-VV RGB combination and flood area detection

by convert our bands which are slave image and master image form linear to dB ,after than we need to change detection from created images by setting some condition based on Sigma0\_VV\_mst\_13Mar2019\_db and Sigma0\_VV\_slv1\_19Mar2019\_db

RED

```
(Sigma0_VV_mst_13Mar2019_db && Sigma0_VV_slv1_19Mar2019_db) ? if
abs(Sigma0_VV_mst_13Mar2019_db -Sigma0_VV_slv1_19Mar2019_db)>3 then
Sigma0_VV_slv1_19Mar2019_db else
avg(Sigma0_VV_mst_13Mar2019_db,Sigma0_VV_slv1_19Mar2019_db) : NaN
```

GREEN

```
(Sigma0_VV_mst_13Mar2019_db && Sigma0_VV_slv1_19Mar2019_db) ? if
abs(Sigma0_VV_mst_13Mar2019_db -Sigma0_VV_slv1_19Mar2019_db)>3 then
Sigma0_VV_mst_13Mar2019_db else
avg(Sigma0_VV_mst_13Mar2019_db,Sigma0_VV_slv1_19Mar2019_db) : NaN
```

BLUE

```
(Sigma0_VV_mst_13Mar2019_db && Sigma0_VV_slv1_19Mar2019_db) ? if
abs(Sigma0_VV_mst_13Mar2019_db -Sigma0_VV_slv1_19Mar2019_db)>3 then
Sigma0_VV_mst_13Mar2019_db else
avg(Sigma0_VV_mst_13Mar2019_db,Sigma0_VV_slv1_19Mar2019_db) : NaN
```

