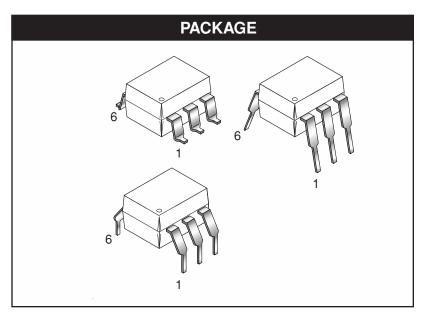
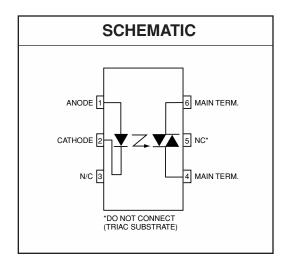


MOC3051-M MOC3052-M





DESCRIPTION

The MOC3051-M and MOC3052-M consist of a AlGaAs infrared emitting diode optically coupled to a non-zero-crossing silicon bilateral AC switch (triac). These devices isolate low voltage logic from 115 and 240 Vac lines to provide random phase control of high current triacs or thyristors. These devices feature greatly enhanced static dv/dt capability to ensure stable switching performance of inductive loads.

FEATURES

- Excellent I_{FT} stability—IR emitting diode has low degradation
- High isolation voltage—minimum 7500 peak VAC
- Underwriters Laboratory (UL) recognized—File #E90700
- 600V peak blocking voltage
- · VDE recognized (File #94766)
 - Ordering option V (e.g. MOC3052V-M)

APPLICATIONS

- · Solenoid/valve controls
- Lamp ballasts
- · Static AC power switch
- · Interfacing microprocessors to 115 and 240 Vac peripherals
- Solid state relay
- · Incandescent lamp dimmers
- · Temperature controls
- Motor controls



MOC3051-M MOC3052-M

ABSOLUTE MAXIMUM RATINGS (T _A = 25°C unless otherwise noted)								
Parameters	Symbol	Device	Value	Units				
TOTAL DEVICE								
Storage Temperature	T _{STG}	All	-40 to +150	°C				
Operating Temperature	T _{OPR}	All	-40 to +85	°C				
Lead Solder Temperature	T _{SOL}	All	260 for 10 sec	°C				
Junction Temperature Range	TJ	All	-40 to +100	°C				
Isolation Surge Voltage ⁽³⁾ (peak AC voltage, 60Hz, 1 sec duration)	V _{ISO}	All	7500	Vac(pk)				
Total Device Power Dissipation @ 25°C	В	All	330	mW				
Derate above 25°C	P _D	All	4.4	mW/°C				
EMITTER								
Continuous Forward Current	I _F	All	60	mA				
Reverse Voltage	V _R	All	3	V				
Total Power Dissipation 25°C Ambient	В	All	100	mW				
Derate above 25°C	P _D	All	1.33	mW/°C				
DETECTOR								
Off-State Output Terminal Voltage	V _{DRM}	All	600	V				
Peak Repetitive Surge Current (PW = 100 ms, 120 pps)	I _{TSM}	All	1	Α				
Total Power Dissipation @ 25°C Ambient	В	All	300	mW				
Derate above 25°C	P _D	All	4	mW/°C				



MOC3051-M MOC3052-M

ELECTRICAL CHARACTERISTICS ($T_A = 25^{\circ}C$ Unless otherwise specified)

INDIVIDUAL COMPONENT CHARACTERISTICS								
Parameters	Test Conditions	Symbol	Device	Min	Тур*	Max	Units	
EMITTER								
Input Forward Voltage	$I_F = 10 \text{ mA}$	V _F	All		1.15	1.5	V	
Reverse Leakage Current	V _R = 3 V	I _R	All		0.05	100	μΑ	
DETECTOR								
Peak Blocking Current, Either Direction	V_{DRM} , $I_F = 0$ (note 1)	I _{DRM}	All		10	100	nA	
Peak On-State Voltage, Either Direction	$I_{TM} = 100 \text{ mA peak}, I_F = 0$	V _{TM}	All		1.7	2.5	V	
Critical Rate of Rise of Off-State Voltage	I _F = 0 (figure 7, @400V)	dv/dt	All	1000			V/µs	

TRANSFER CHARACTERISTICS (T _A = 25°C Unless otherwise specified.)							
DC Characteristics	Test Conditions	Symbol	Device	Min	Тур*	Max	Units
LED Trigger Current,	Main terminal	I _{FT}	MOC3051-M			15	mA
either direction	Voltage = 3V (note 2)		MOC3052-M			10	I
Holding Current, Either Direction		I _H	All		280		μΑ

^{*}Typical values at $T_A = 25^{\circ}C$

Note

- 1. Test voltage must be applied within dv/dt rating.
- 2. All devices are guaranteed to trigger at an I_F value less than or equal to max I_{FT}. Therefore, recommended operating I_F lies between max 15 mA for MOC3051, 10 mA for MOC3052 and absolute max I_F (60 mA).
- 3. Isolation surge votlage, VISO, is an internal device breakdown rating. For this text, pins 1 and 2 are common, and pins 4, 5 and 6 are common.



MOC3051-M MOC3052-M

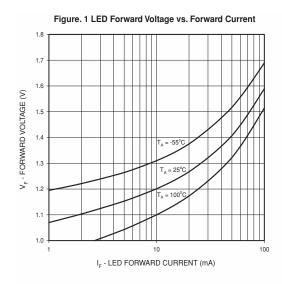
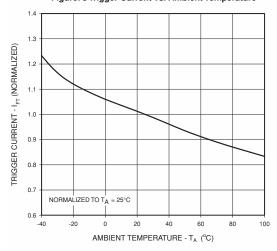


Figure. 3 Trigger Current vs. Ambient Temperature



I_F versus Temperature (normalized)

This graph (figure 3) shows the increase of the trigger current when the device is expected to operate at an ambient temperature below 25°C. Multiply the normalized I_{FT} shown this graph with the data sheet guaranteed I_{FT} .

Example:

$$T_A = -40$$
°C, $I_{FT} = 10$ mA
 I_{FT} @ -40 °C = 10 mA x 1.4 = 14 mA

Phase Control Considerations

LED Trigger Current versus PW (normalized)

Random Phase Triac drivers are designed to be phase controllable. They may be triggered at any phase angle within the AC

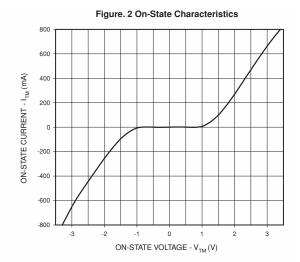
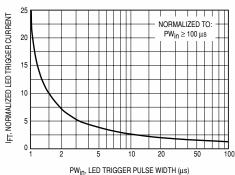


Figure. 4 LED Current Required to Trigger vs. LED Pulse Width



sine wave. Phase control may be accomplished by an AC line zero cross detector and a variable pulse delay generator which is synchronized to the zero cross detector. The same task can be accomplished by a microprocessor which is synchronized to the AC zero crossing. The phase controlled trigger current may be a very short pulse which saves energy delivered to the input LED. LED trigger pulse currents shorter than 100 μs must have an increased amplitude as shown on Figure 4. This graph shows the dependency of the trigger current $I_{\mbox{\scriptsize FT}}$ versus the pulse width can be seen on the chart delay t(d) versus the LED trigger current.

 I_{FT} in the graph I_{FT} versus (PW) is normalized in respect to the minimum specified I_{FT} for static condition, which is specified in the device characteristic. The normalized I_{FT} has to be multiplied with the devices guaranteed static trigger current.

Example:

Guaranteed I_{FT} = 10 mA, Trigger pulse width PW = 3 μ s I_{FT} (pulsed) = 10 mA x 5 = 50 mA



MOC3051-M MOC3052-M

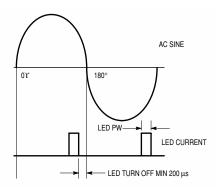
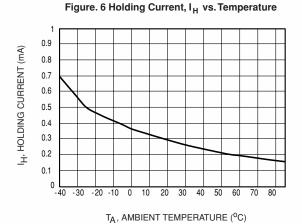
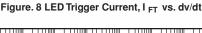
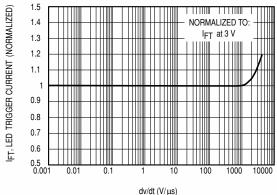


Figure 5. Minimum Time for LED Turn-Off to Zero Cross of AC Trailing Edge







Minimum LED Off Time in Phase Control Applications

In Phase control applications one intends to be able to control each AC sine half wave from 0 to 180 degrees. Turn on at zero degrees means full power and turn on at 180 degree means zero power. This is not quite possible in reality because triac driver and triac have a fixed turn on time when activated at zero degrees. At a phase control angle close to 180 degrees the driver's turn on pulse at the trailing edge of the AC sine wave must be limited to end 200 ms before AC zero cross as shown in Figure 5. This assures that the triac driver has time to switch off. Shorter times may cause loss of control at the following half cycle.

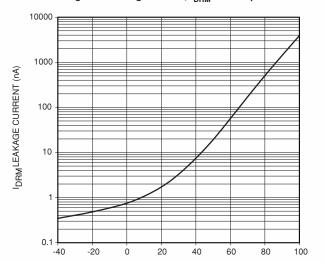


Figure. 7 Leakage Current, I DRM vs. Temperature

IFT versus dv/dt

Triac drivers with good noise immunity (dv/dt static) have internal noise rejection circuits which prevent false triggering of the device in the event of fast raising line voltage transients. Inductive loads generate a commutating dv/dt that may activate the triac drivers noise suppression circuits. This prevents the device from turning on at its specified trigger current. It will in this case go into the mode of "half waving" of the load. Half waving of the load may destroy the power triac and the load.

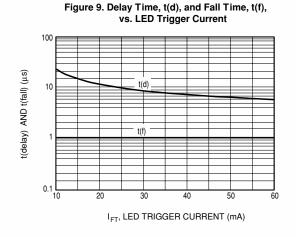
TA, AMBIENT TEMPERATURE (°C)

Figure 8 shows the dependency of the triac drivers I_{FT} versus the reapplied voltage rise with a Vp of 400 V. This dv/dt condition simulates a worst case commutating dv/dt amplitude.

It can be seen that the I_{FT} does not change until a commutating dv/dt reaches 1000 V/ms. The data sheet specified I_{FT} is therefore applicable for all practical inductive loads and load factors.



MOC3051-M MOC3052-M



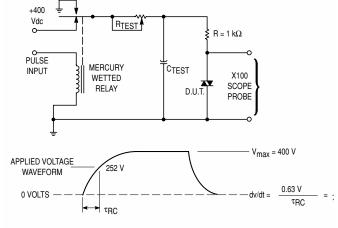


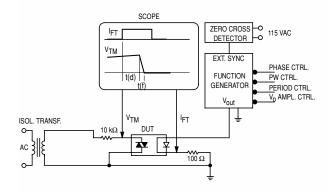
Figure 10. Static dv/dt Test Circuit

t(delay), t(f) versus IFT

The triac driver's turn on switching speed consists of a turn on delay time t(d) and a fall time t(f). Figure 9 shows that the delay time depends on the LED trigger current, while the actual trigger transition time t(f) stays constant with about one micro second.

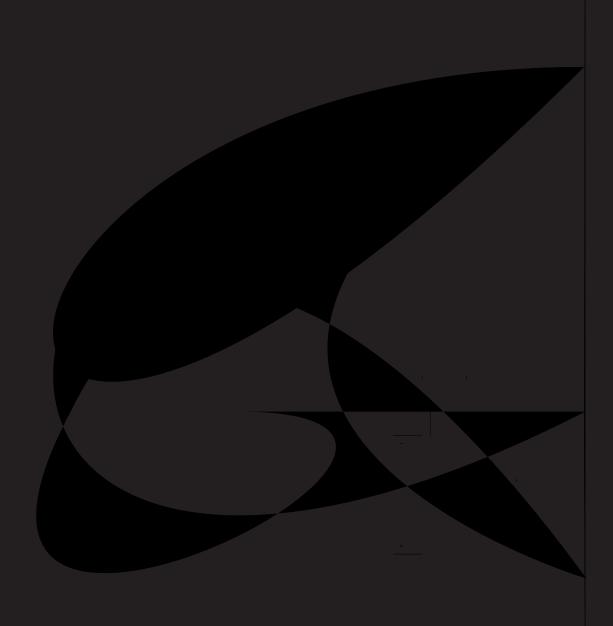
The delay time is important in very short pulsed operation because it demands a higher trigger current at very short trigger pulses. This dependency is shown in the graph I_{FT} versus LED PW.

The turn on transition time t(f) combined with the power triac's turn on time is important to the power dissipation of this device



- The mercury wetted relay provides a high speed repeated pulse to the D.U.T.
- 2. 100x scope probes are used, to allow high speeds and voltages.
- 3. The worst-case condition for static dv/dt is established by triggering the D.U.T. with a normal LED input current, then removing the current. The variable R_{TEST} allows the dv/dt to be gradually increased until the D.U.T. continues to trigger in response to the applied voltage pulse, even after the LED current has been removed. The dv/dt is then decreased until the D.U.T. stops triggering. τ_{RC} is measured at this point and recorded.

6-PIN DIP RANDOM-F OPTOISOLATORS TRIAC DR (600 VOLT I -EMIC NOUCT R Page 7 of 11 ild Semiconductor Corporation



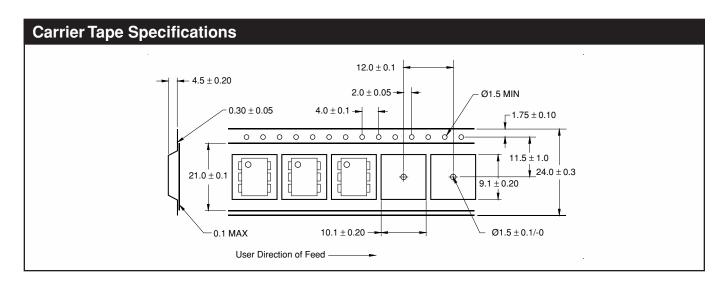
-EMIC NOUCT R

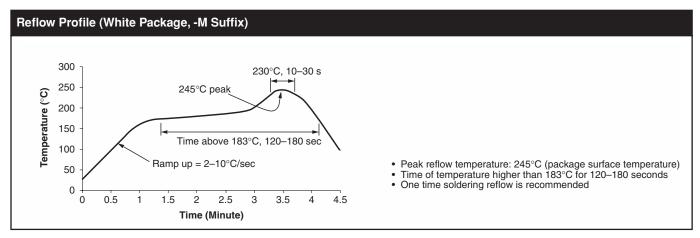
6-PIN DIP RANDOM-PHASE OPTOISOLATORS TRIAC DRIVERS (600 VOLT PEAK)





MOC3051-M MOC3052-M







MOC3051-M MOC3052-M

DISCLAIMER

FAIRCHILD SEMICONDUCTOR RESERVES THE RIGHT TO MAKE CHANGES WITHOUT FURTHER NOTICE TO ANY PRODUCTS HEREIN TO IMPROVE RELIABILITY, FUNCTION OR DESIGN. FAIRCHILD DOES NOT ASSUME ANY LIABILITY ARISING OUT OF THE APPLICATION OR USE OF ANY PRODUCT OR CIRCUIT DESCRIBED HEREIN; NEITHER DOES IT CONVEY ANY LICENSE UNDER ITS PATENT RIGHTS, NOR THE RIGHTS OF OTHERS.

LIFE SUPPORT POLICY

FAIRCHILD'S PRODUCTS ARE NOT AUTHORIZED FOR USE AS CRITICAL COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS WITHOUT THE EXPRESS WRITTEN APPROVAL OF THE PRESIDENT OF FAIRCHILD SEMICONDUCTOR CORPORATION. As used herein:

- Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and (c) whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury of the user.
- A critical component in any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.