from linearalgebra import vec

$$\begin{split} & \textit{icf}_i = \textit{vec}\left(c_i^{-1}\right) \\ & \textit{qq1}_i = \left(\textit{icf}_{i,1}, \textit{icf}_{i,2}, \textit{icf}_{i,3}\right) \\ & \textit{qq2}_i = \left(\textit{icf}_{i,5}, \textit{icf}_{i,6}, \textit{icf}_{i,9}\right) \\ & \textit{qlin}_i = c_i^{-1} v_{i,*} \\ & v\_\textit{out}_i = \begin{bmatrix} \textit{qq1}_i^T \\ \left(\textit{qq1}_{i,2}, \textit{qq2}_{i,1}, \textit{qq2}_{i,2}\right)^T \\ \left(\textit{qq1}_{i,3}, \textit{qq2}_{i,2}, \textit{qq2}_{i,3}\right)^T \end{bmatrix}^{-1} \textit{qlin}_i \end{split}$$

where

$$v \in \mathbb{R}^{m \times 3}$$
 $f \in \mathbb{Z}^{t \times 3}$ 
 $c_i \in \mathbb{R}^{3 \times 3}$ 
 $n \in \mathbb{Z}$