

# Data Structure - Spring 2022

## 16. Graph: Basics

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**Based on:**

Goodrich, Chapter 9,11

Karumanchi, Chapter 6-7

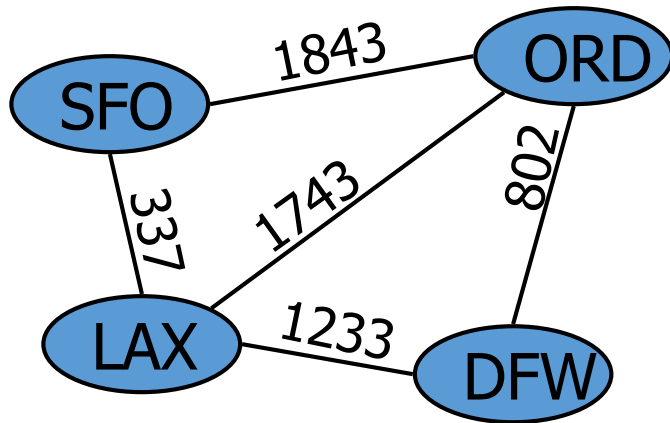
Slides by Prof. Yung Yi, KAIST

Slides by Prof. Chansu Shin, HUFS



Computer Vision Lab  
Hankuk University of Foreign Studies

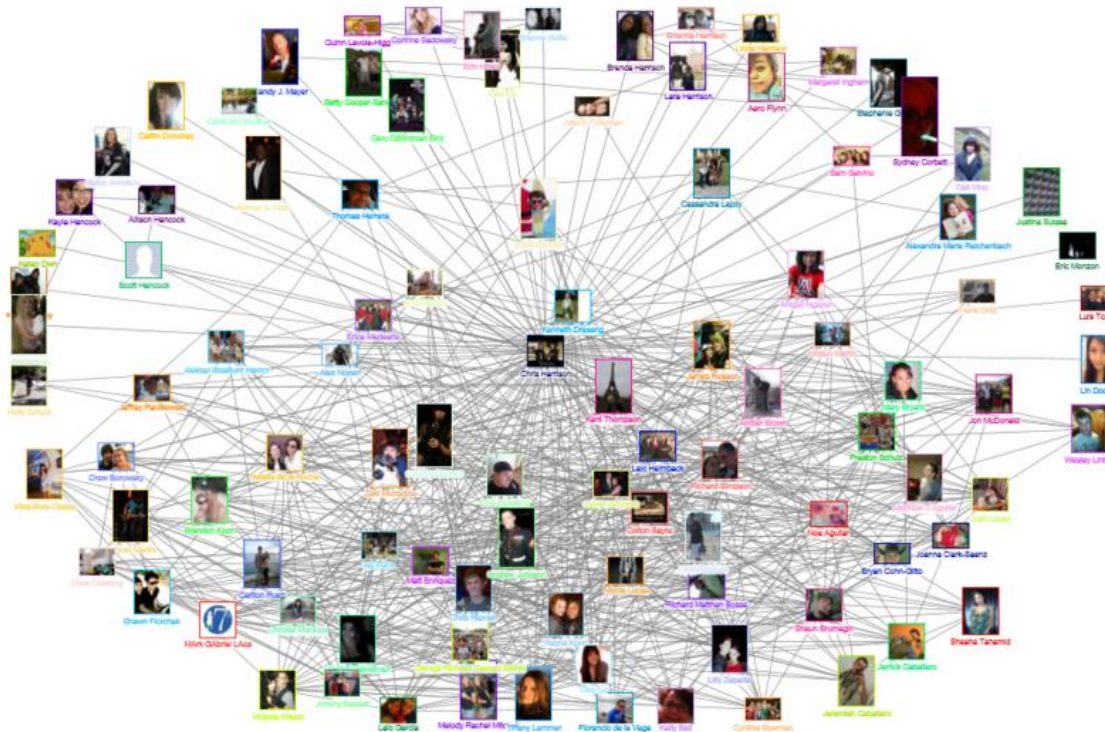
# Graphs: Basics



# Real Life Examples

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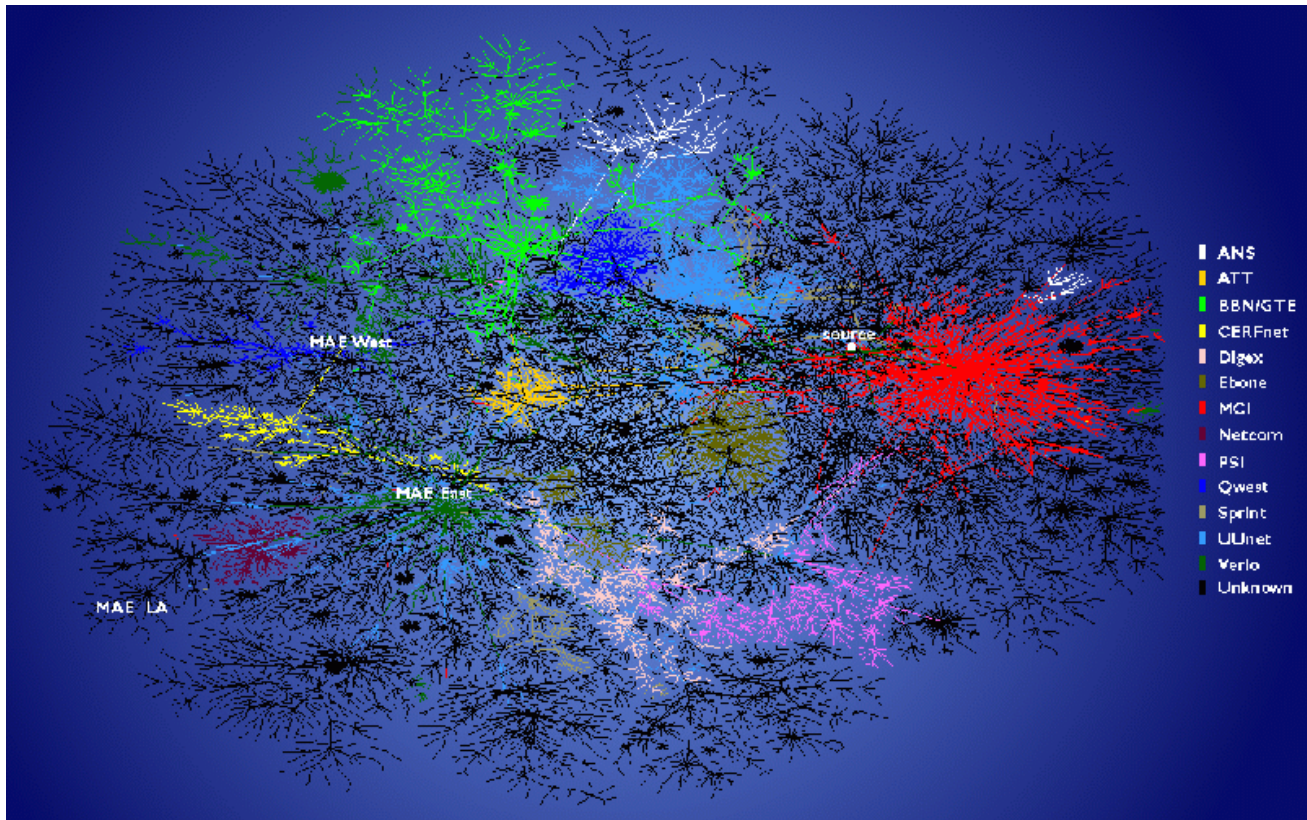
- On-line/Off-line Social Network



# Real Life Examples

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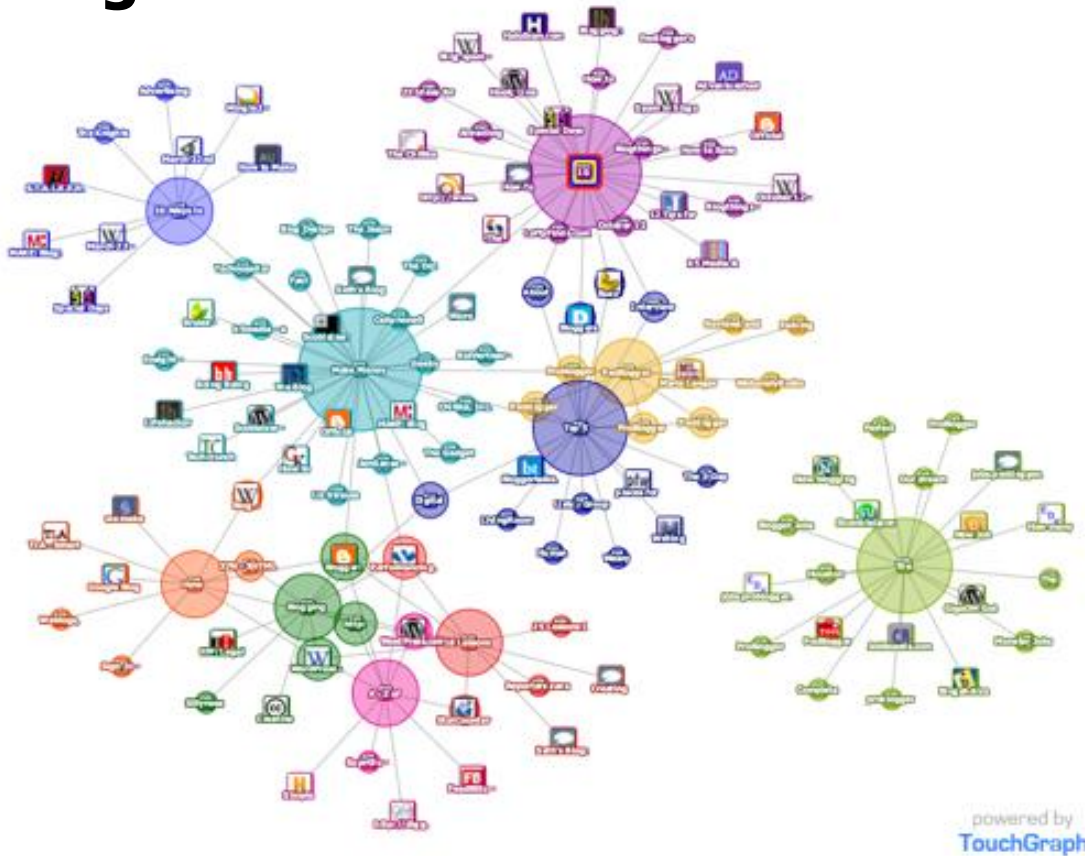
- **Internet Connectivity**



# Real Life Examples

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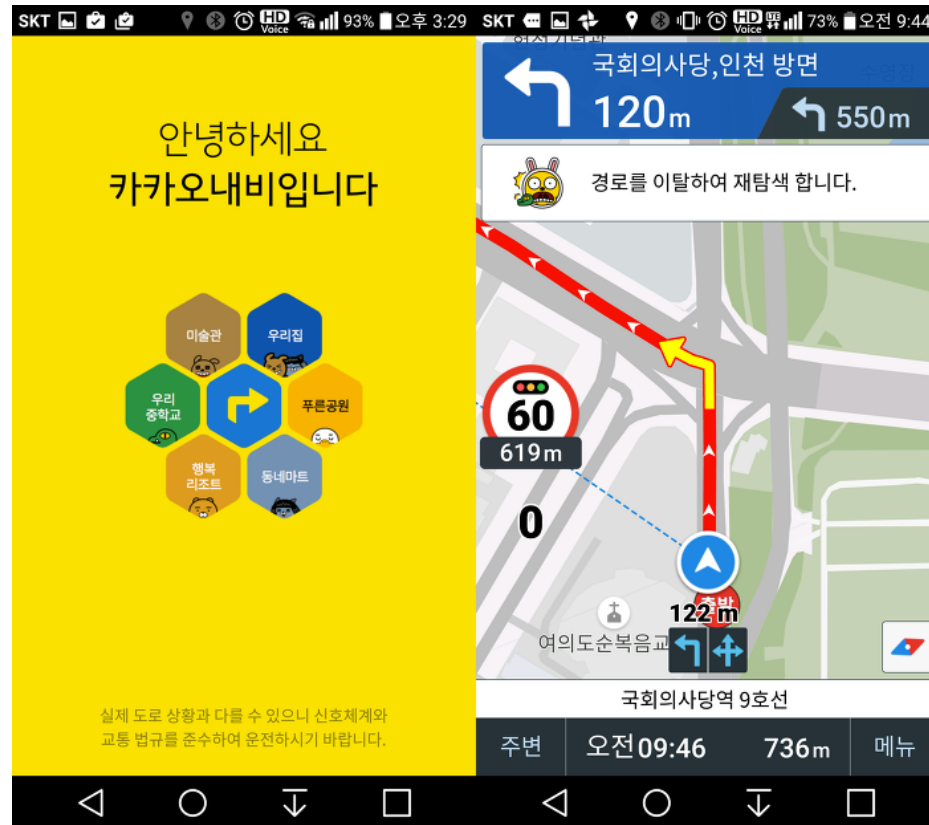
- **WebBlog Connections**





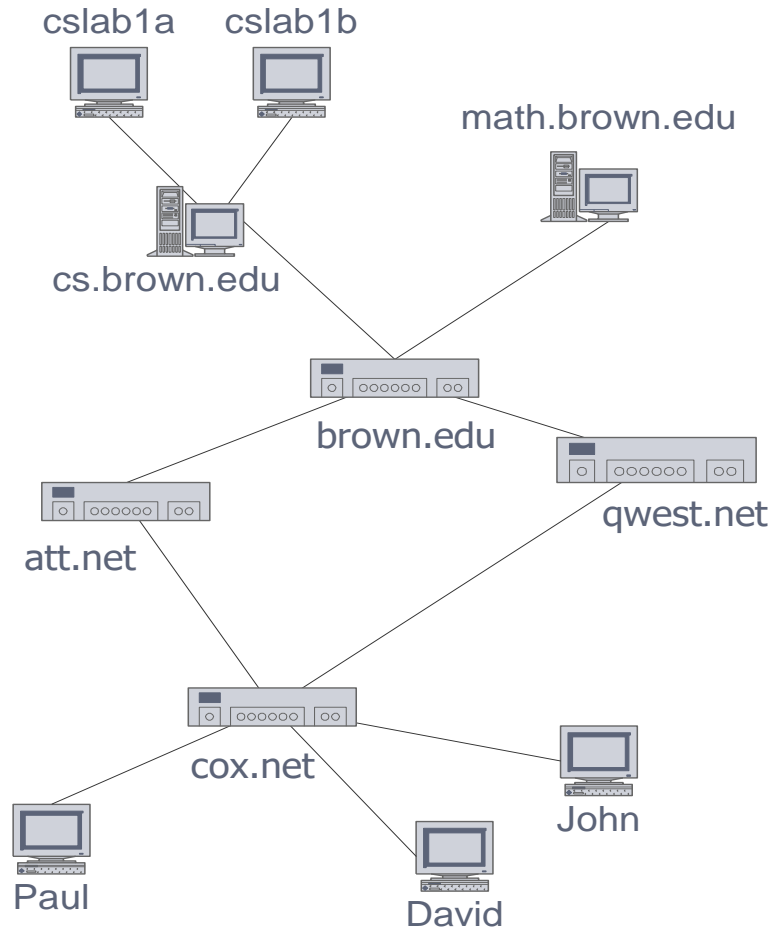
# Real Life Examples

- Navigator



# Other Applications

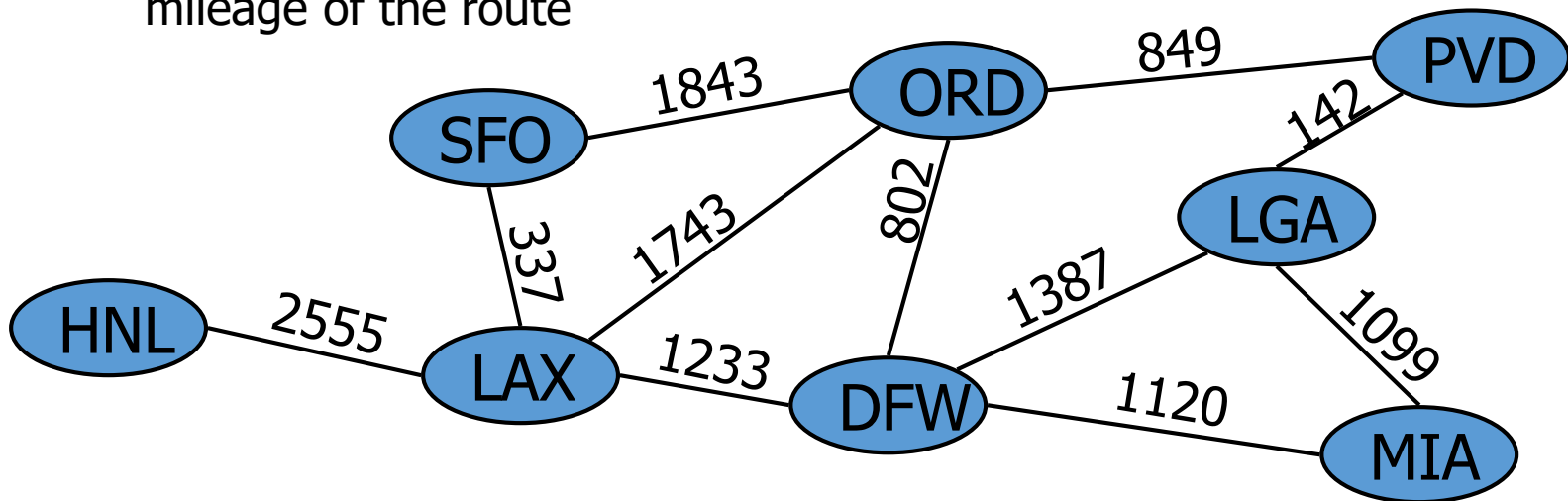
- **Electronic circuits**
  - Printed circuit board
  - Integrated circuit
- **Transportation networks**
  - Highway network
  - Flight network
- **Computer networks**
  - Local area network
  - Internet
  - Web
- **Databases**
  - Entity-relationship diagram



# Graphs

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- **A graph is a pair  $(V, E)$ , where**
  - $V$  is a set of nodes, called **vertices**
  - $E$  is a collection of pairs of vertices, called **edges**
  - Vertices and edges are positions and store elements
- **Example:**
  - A vertex represents an airport and stores the three-letter airport code
  - An edge represents a flight route between two airports and stores the mileage of the route





# Edge Types

- **Directed edge**

- ordered pair of vertices  $(u,v)$
- first vertex  $u$  is the origin
- second vertex  $v$  is the destination
- e.g., a flight

- **Undirected edge**

- unordered pair of vertices  $(u,v)$
- e.g., a flight route

- **Directed graph**

- all the edges are directed
- e.g., route network

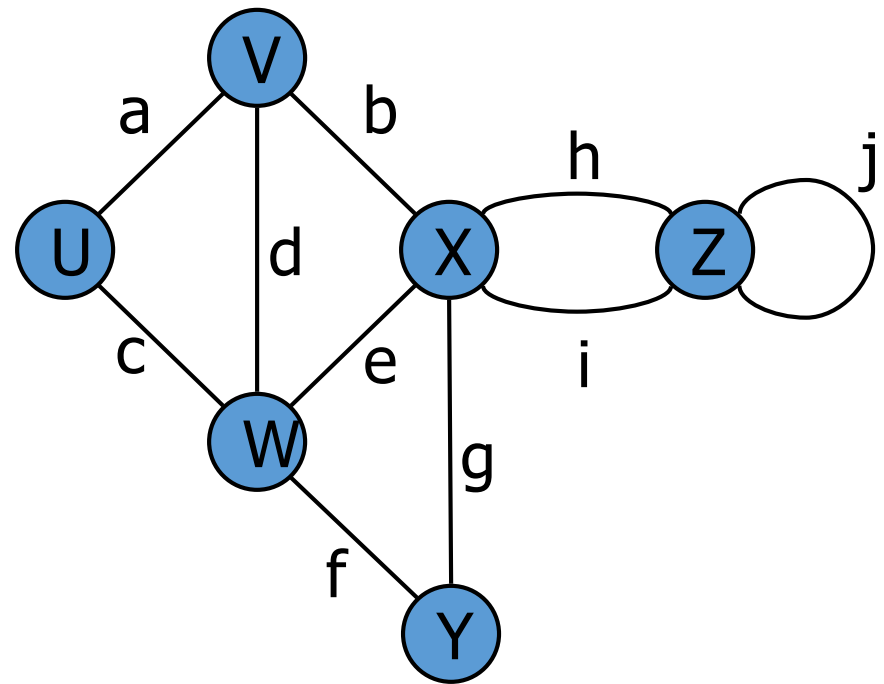
- **Undirected graph**

- all the edges are undirected
- e.g., flight network



# Terminology

- **End vertices (or endpoints) of an edge**
  - U and V are the endpoints of a
- **Edges incident on a vertex**
  - a, d, and b are incident on V
- **Adjacent vertices**
  - U and V are adjacent
- **Degree of a vertex**
  - X has degree 5
- **Parallel edges**
  - h and i are parallel edges
- **Self-loop**
  - j is a self-loop



# Terminology (cont.)

- **Path**

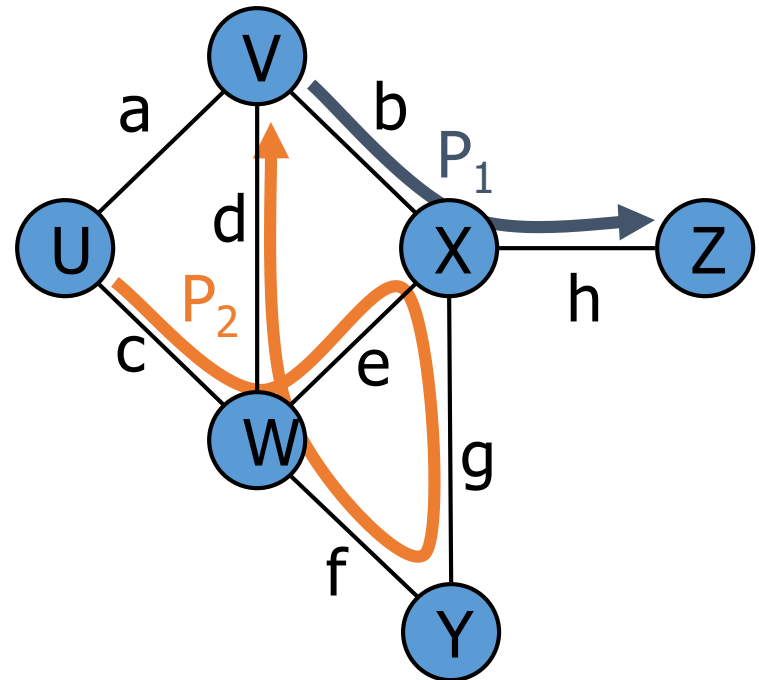
- sequence of alternating vertices and edges
- begins with a vertex
- ends with a vertex
- each edge is preceded and followed by its endpoints

- **Simple path**

- path such that all its vertices and edges are distinct

- **Examples**

- $P_1 = (V, b, X, h, Z)$  is a simple path
- $P_2 = (U, c, W, e, X, g, Y, f, W, d, V)$  is a path that is not simple



# Terminology (cont.)

- **Cycle**

- circular sequence of alternating vertices and edges
- each edge is preceded and followed by its endpoints

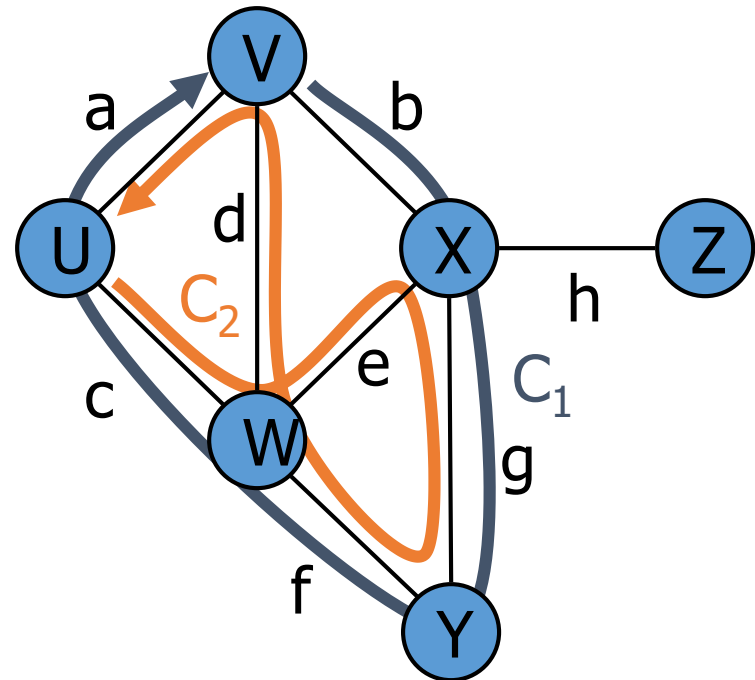
- **Simple cycle**

- cycle such that all its vertices and edges are distinct

- **Examples**

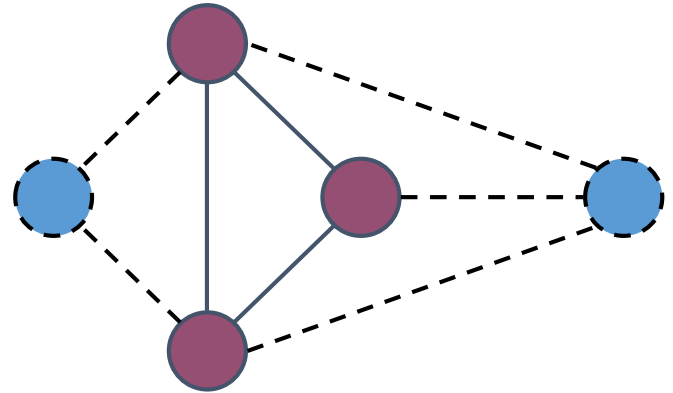
- $C_1 = (V, b, X, g, Y, f, W, c, U, a, \rightarrow)$  is a simple cycle
- $C_2 = (U, c, W, e, X, g, Y, f, W, d, V, a, \rightarrow)$  is a cycle that is not simple

- **Note) Tree is a graph without cycles**

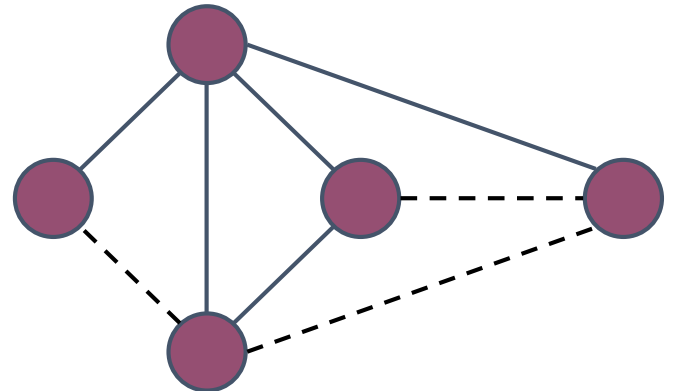


# Subgraphs

- **A subgraph  $S$  of a graph  $G$  is a graph such that**
  - The vertices of  $S$  are a subset of the vertices of  $G$
  - The edges of  $S$  are a subset of the edges of  $G$
- **A spanning subgraph of  $G$  is a subgraph that contains all the vertices of  $G$**



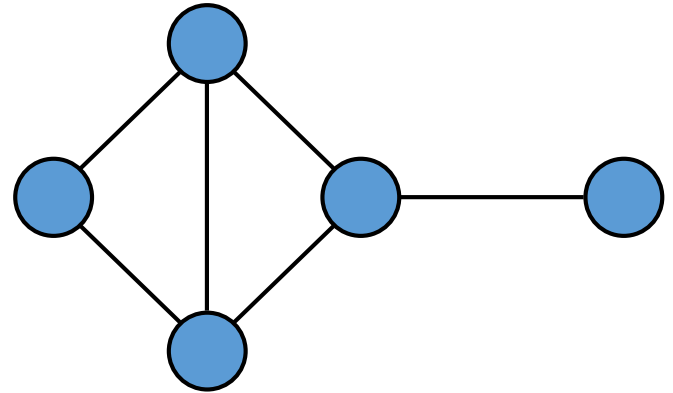
Subgraph



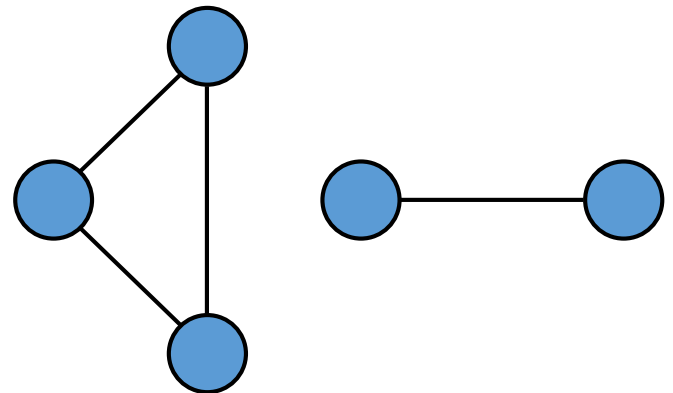
Spanning subgraph

# Connectivity

- **A graph is connected if there is a path between every pair of vertices**
- **A connected component of a graph  $G$  is a maximal connected subgraph of  $G$**
- **“Maximal”?**



Connected graph



Non connected graph with two connected components



# Trees and Forests

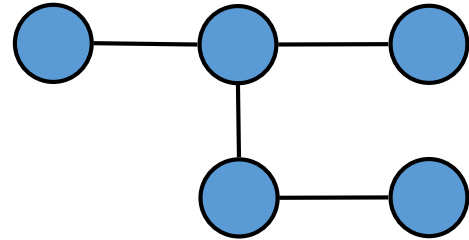
- **A (free) tree is an undirected graph  $T$  such that**

- $T$  is connected
- $T$  has no cycles

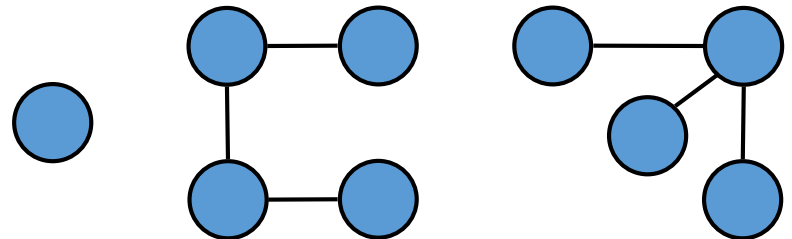
This definition of tree is different from the one of a rooted tree

- **A forest is an undirected graph without cycles**

- **The connected components of a forest are trees**



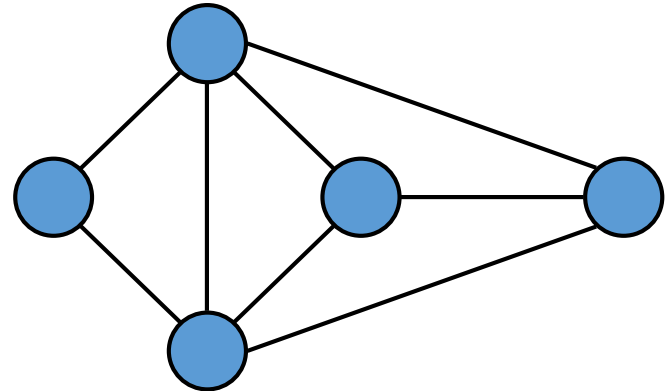
Tree



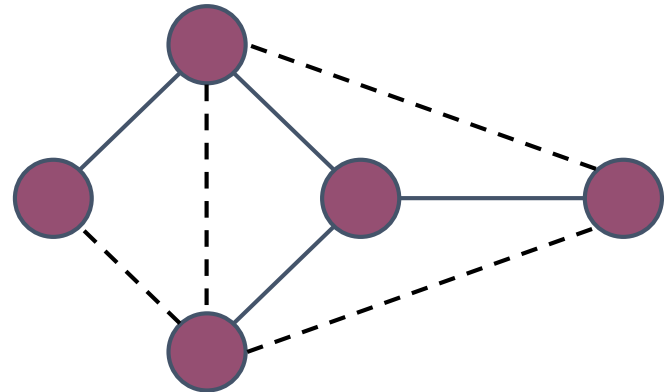
Forest

# Spanning Trees and Forests

- A spanning tree of a connected graph is a spanning subgraph that is a tree
- A spanning tree is not unique unless the graph is a tree
- Spanning trees have applications to the design of communication networks
- A spanning forest of a graph is a spanning subgraph that is a forest



Graph



Spanning tree

# Some Properties for Undirected Graphs

## Property 1

$$\sum_v \deg(v) = 2m$$

Proof: each edge is counted twice

## Property 2

In an undirected graph with no self-loops and no multiple edges

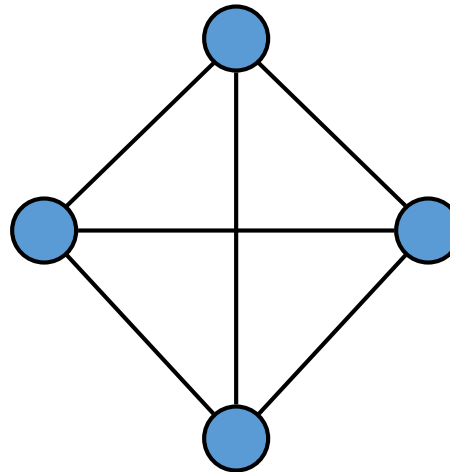
$$m \leq n(n-1)/2$$

Proof: each vertex has degree at most  $(n-1)$

**What is the bound for a directed graph?**

## Notation

$n$	number of vertices
$m$	number of edges
$\deg(v)$	degree of vertex $v$



## Example

- $n = 4$
- $m = 6$
- $\deg(v) = 3$

# Main Methods of the Graph ADT

- **Vertices and edges**

- are positions
- store elements

- **Accessor methods**

- `e.endVertices()`: a list of the two endvertices of `e`
- `e.opposite(v)`: the vertex opposite of `v` on `e`
- `u.isAdjacentTo(v)`: true if `u` and `v` are adjacent
- `*v`: reference to element associated with vertex `v`
- `*e`: reference to element associated with edge `e`

- **Update methods**

- `insertVertex(o)`: insert a vertex storing element `o`
- `insertEdge(v, w, o)`: insert an edge `(v,w)` storing element `o`
- `eraseVertex(v)`: remove vertex `v` (and its incident edges)
- `eraseEdge(e)`: remove edge `e`

- **Iterable collection methods**

- `incidentEdges(v)`: list of edges incident to `v`
- `vertices()`: list of all vertices in the graph
- `edges()`: list of all edges in the graph

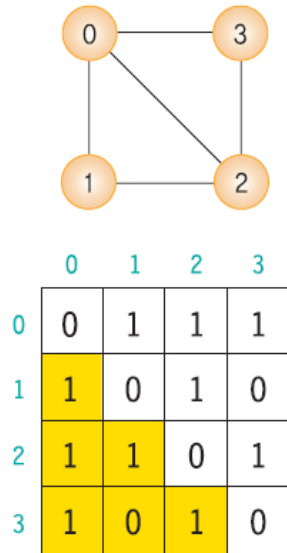
What is the data structure to represent a graph?

We will discuss three ways

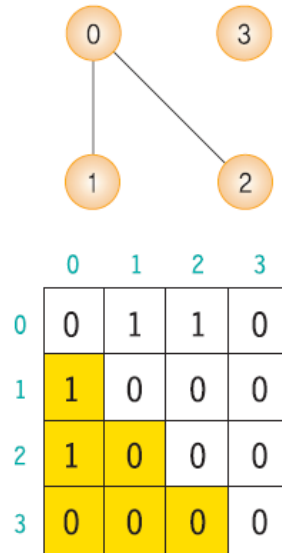
# Representation: 2D Array

- **Adjacency matrix)**

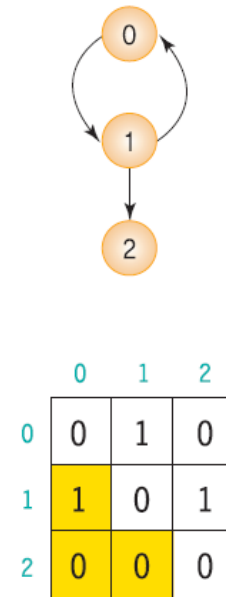
- If edge  $(i, j)$  exists,  $M[i][j] = 1$ .  
Otherwise,  $M[i][j] = 0$
- The adj. matrix for an undirected graph has zero-diagonal and is symmetric.



(a)



(b)

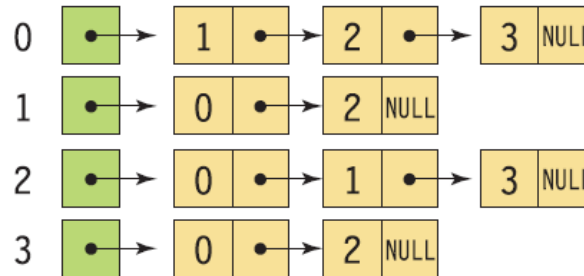
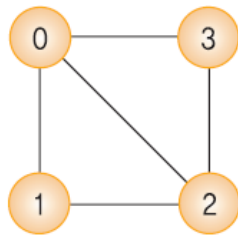


(c)

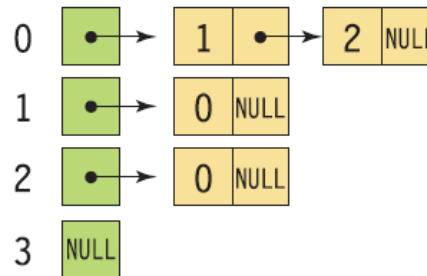
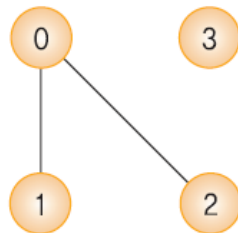


# Representation : Adjacency List

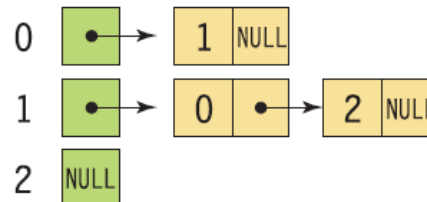
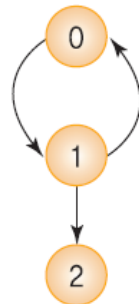
- List of adjacent vertices



(a)



(b)



(c)

# Performance

<ul style="list-style-type: none"> <li>▪ <math>n</math> vertices, <math>m</math> edges</li> <li>▪ no parallel edges</li> <li>▪ no self-loops</li> </ul>	Edge List	Adjacency List	Adjacency Matrix
Space	$n + m$	$n + m$	$n^2$
$v$ .incidentEdges()	$m$	$\deg(v)$	$n$
$u$ .isAdjacentTo( $v$ )	$m$	$\min(\deg(v), \deg(w))$	1
insertVertex( $o$ )	1	1	$n^2$
insertEdge( $v, w, o$ )	1	1	1
eraseVertex( $v$ )	$m$	$\deg(v)$	$n^2$
eraseEdge( $e$ )	1	1	1

◆  $v$ .incidentEdges(): matrix row check

◆  $u$ .isAdjacentTo( $v$ ): using  $v$ 's key

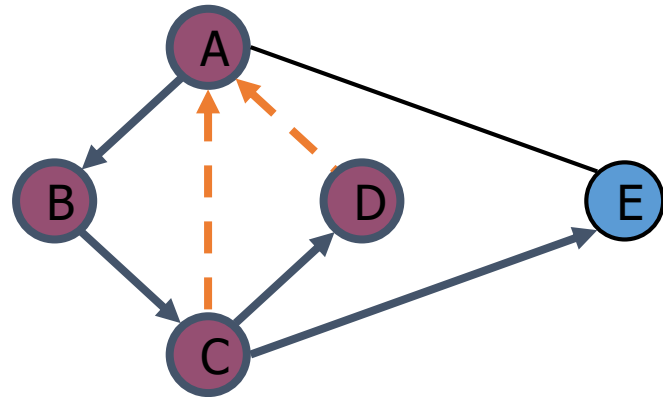
# Performance

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$u$ .isAdjacentTo( $v$ )	$m$	$\min(\deg(v), \deg(w))$	1
insertVertex( $o$ )	1	1	$n^2$
insertEdge( $v, w, o$ )	1	1	1
eraseVertex( $v$ )	$m$	$\deg(v)$	$n^2$
eraseEdge( $e$ )	1	1	1

◆  $v$ .incidentEdges(): direct access to incident edges

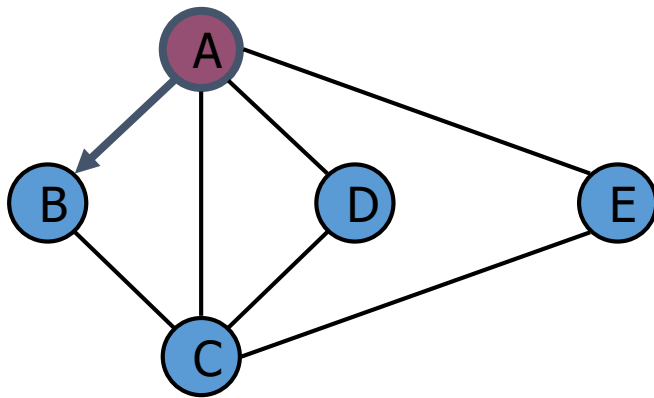
◆  $u$ .isAdjacentTo( $v$ ):

# Depth-First Search

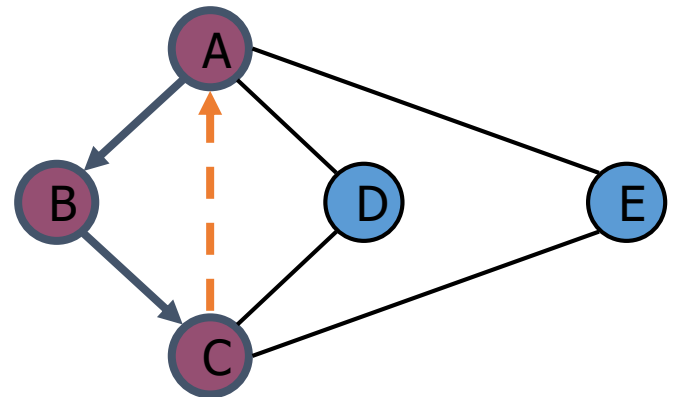
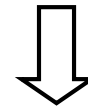
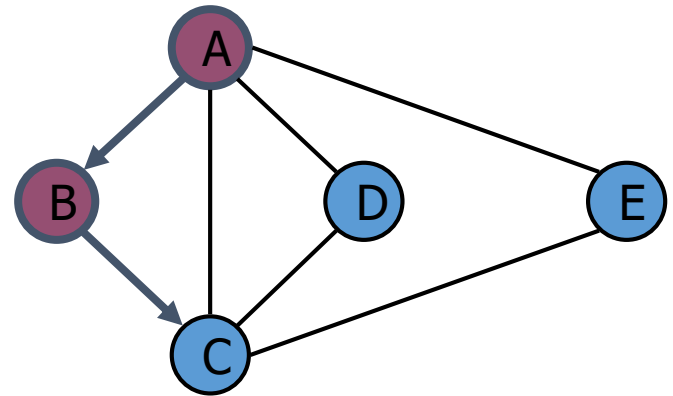
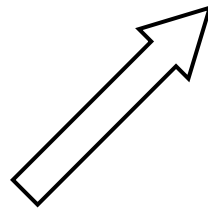
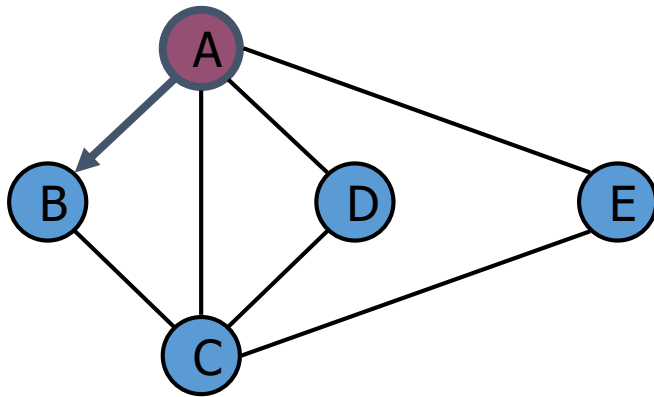
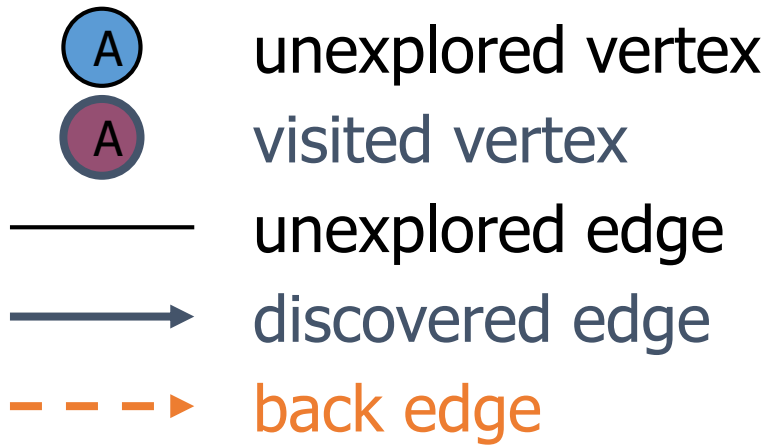


# Depth-First Search

- **Depth-first search (DFS) is a general technique for traversing a graph**
- **Why is this traversal important?**
- **Let's first see the example**

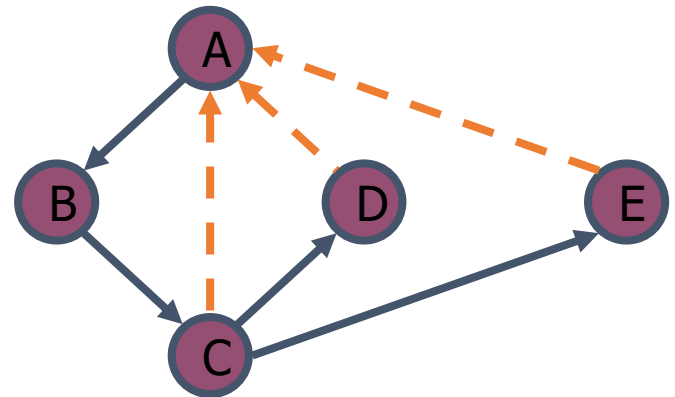
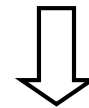
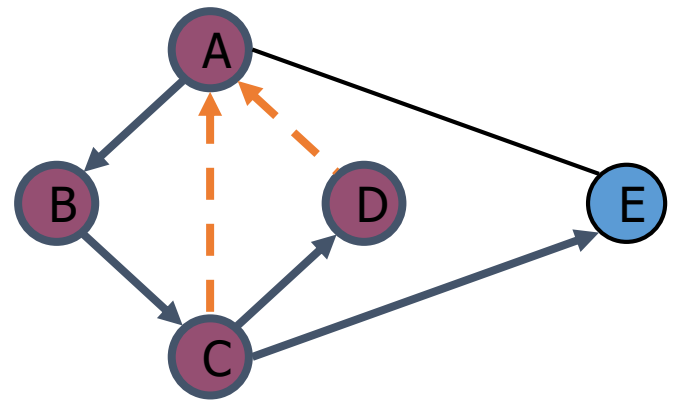
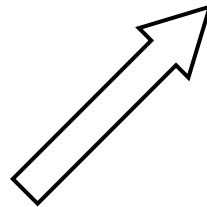
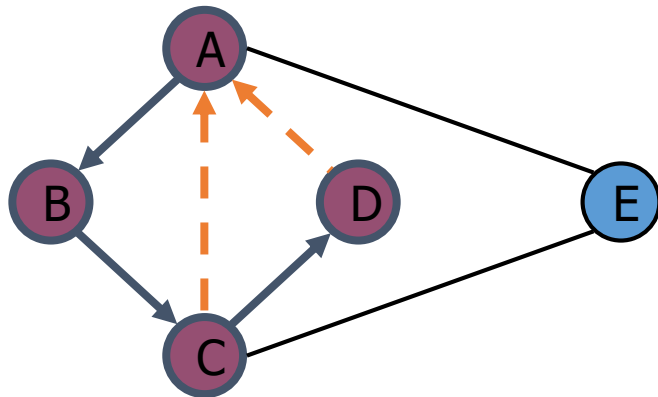
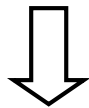
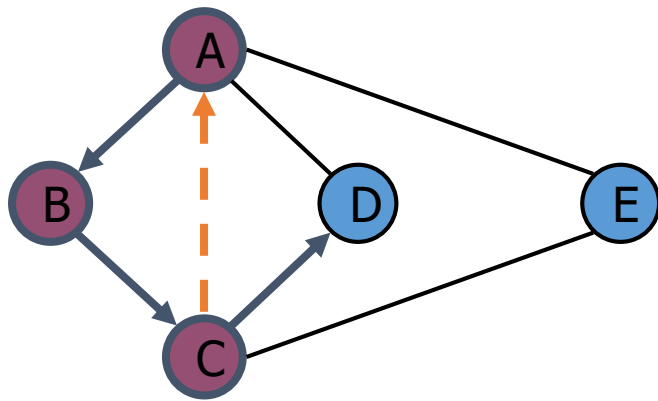


# Example





# Example (cont.)



One implication: discovery edges form a spanning tree.<sup>27</sup>

# Depth-First Search

- **A DFS traversal of a graph  $G$** 
  - Visits all the vertices and edges of  $G$
  - Determines whether  $G$  is connected (how?)
  - Computes the connected components of  $G$  (how?)
  - Computes a spanning forest of  $G$
- **DFS on a graph with  $n$  vertices and  $m$  edges takes  $O(n + m)$  time**
- **DFS can be further extended to solve other graph problems**
  - Find and report a path between two given vertices
  - Find a cycle in the graph

# DFS Algorithm

- The algorithm uses a mechanism for setting and getting “labels” of vertices and edges

## Algorithm *DFS*(*G*)

**Input** graph *G*

**Output** labeling of the edges of *G*  
as discovery edges and  
back edges

**for all** *u* ∈ *G.vertices*()

*u.setLabel*(*UNEXPLORED*)

**for all** *e* ∈ *G.edges*()

*e.setLabel*(*UNEXPLORED*)

**for all** *v* ∈ *G.vertices*()

**if** *v.getLabel*() = *UNEXPLORED*  
*DFS*(*G*, *v*)

## Algorithm *DFS*(*G*, *v*)

**Input** graph *G* and a start vertex *v* of *G*

**Output** labeling of the edges of *G*  
in the connected component of *v*  
as discovery edges and back edges

*v.setLabel*(*VISITED*)

**for all** *e* ∈ *G.incidentEdges*(*v*)

**if** *e.getLabel*() = *UNEXPLORED*

*w* ← *e.opposite*(*v*)

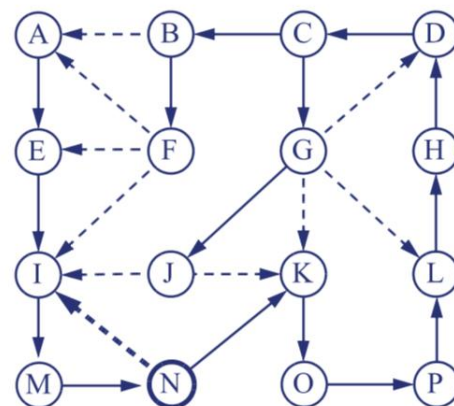
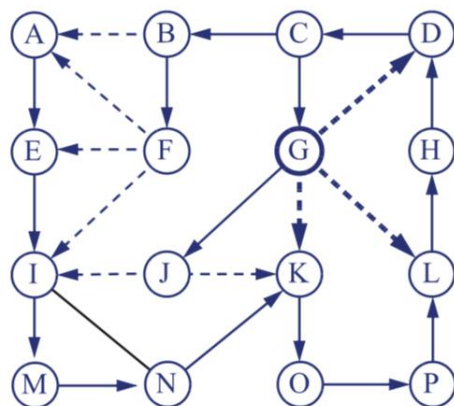
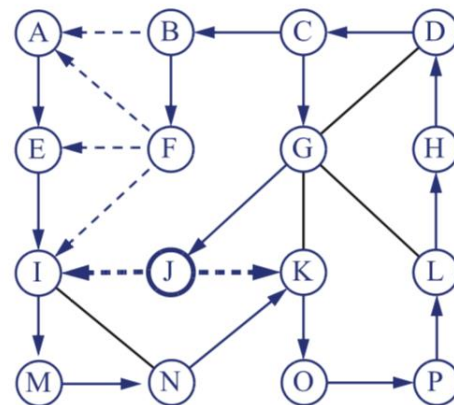
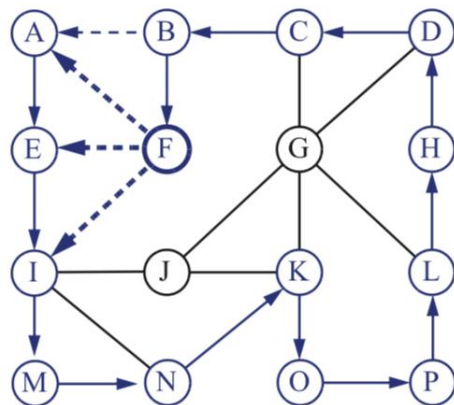
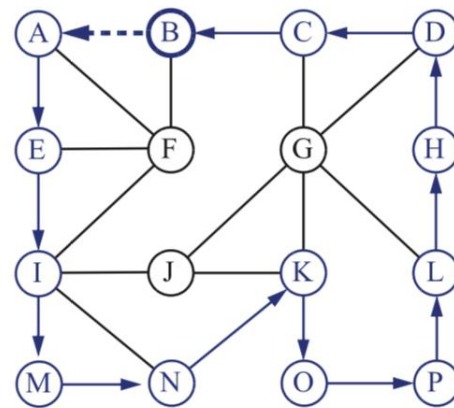
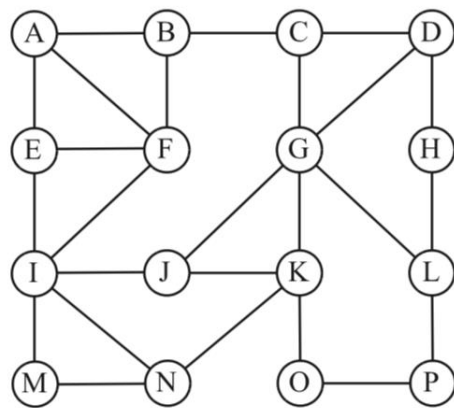
**if** *w.getLabel*() = *UNEXPLORED*

*e.setLabel*(*DISCOVERY*)

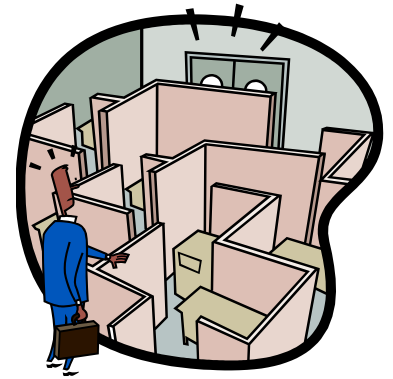
*DFS*(*G*, *w*)

**else**

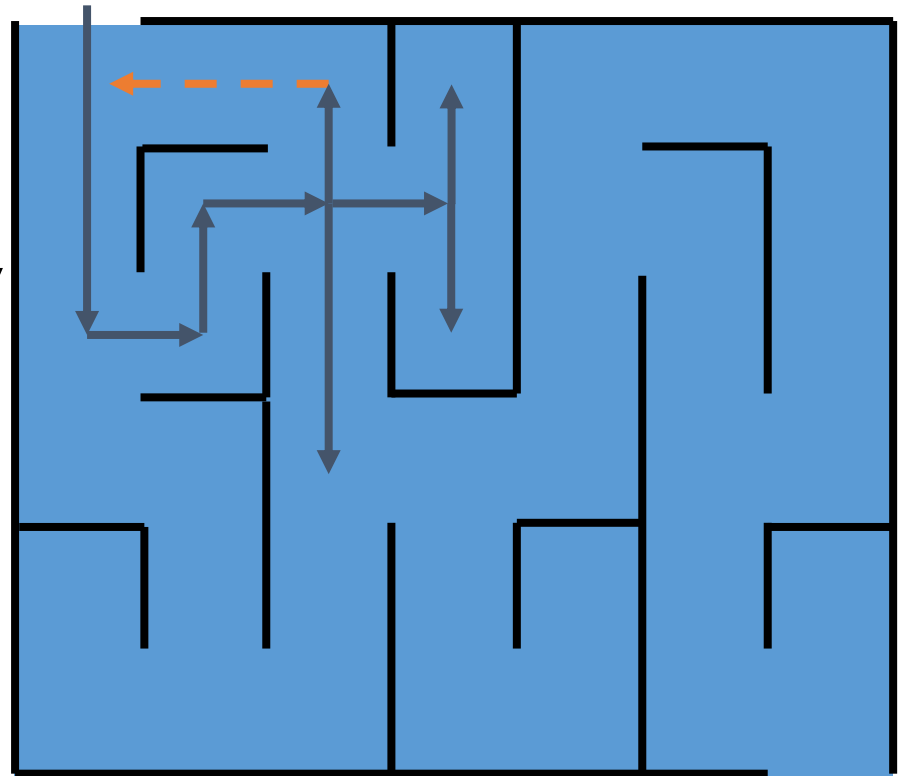
*e.setLabel*(*BACK*)



# DFS and Maze Traversal



- **The DFS algorithm is similar to a classic strategy for exploring a maze**
  - We mark each intersection, corner and dead end (vertex) visited
  - We mark each corridor (edge) traversed
  - We keep track of the path back to the entrance (start vertex) by means of a rope (recursion stack)



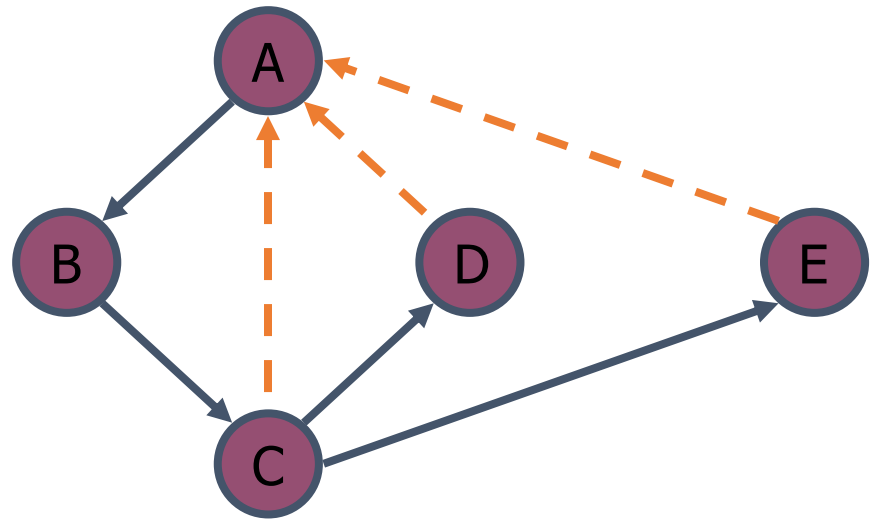
# Properties of DFS

## Property 1

**$DFS(G, v)$  visits all the vertices and edges in the connected component of  $v$**

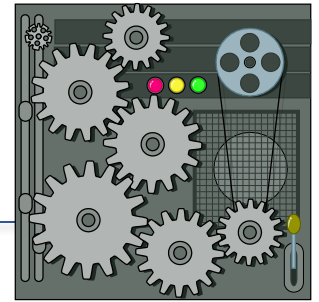
## Property 2

**The discovery edges labeled by  $DFS(G, v)$  form a spanning tree of the connected component of  $v$**





# Analysis of DFS



- **Setting/getting a vertex/edge label takes  $O(1)$  time**
- **Each vertex is labeled twice**
  - once as UNEXPLORED
  - once as VISITED
- **Each edge is labeled twice**
  - once as UNEXPLORED
  - once as DISCOVERY or BACK
- **Method incidentEdges is called once for each vertex**
  - Complexity of `v.incidentEdges`:  $\deg(v)$
- **DFS runs in  $O(n + m)$  time provided the graph is represented by the adjacency list structure**
  - Recall that  $\sum_v \deg(v) = 2m$

# Path Finding



- We can specialize the DFS algorithm to find a path between two given vertices  $u$  and  $z$  using the template method pattern
- We call  $DFS(G, u)$  with  $u$  as the start vertex
- We use a stack  $S$  to keep track of the path between the start vertex and the current vertex
- As soon as destination vertex  $z$  is encountered, we return the path as the contents of the stack

```
Algorithm pathDFS( $G, v, z$ )  
   $v.setLabel(VISITED)$   
   $S.push(v)$   
  if  $v = z$   
    return  $S.elements()$   
  for all  $e \in v.incidentEdges()$   
    if  $e.getLabel() = UNEXPLORED$   
       $w \leftarrow e.opposite(v)$   
      if  $w.getLabel() = UNEXPLORED$   
         $e.setLabel(DISCOVERY)$   
         $S.push(e)$   
         $pathDFS(G, w, z)$   
         $S.pop(e)$   
      else  
         $e.setLabel(BACK)$   
   $S.pop(v)$ 
```

# Cycle Finding



- We can specialize the DFS algorithm to find a simple cycle using the template method pattern
- We use a stack  $S$  to keep track of the path between the start vertex and the current vertex
- As soon as a back edge  $(v, w)$  is encountered, we return the cycle as the portion of the stack from the top to vertex  $w$

```
Algorithm cycleDFS( $G, v, z$ )
   $v.setLabel(VISITED)$ 
   $S.push(v)$ 
  for all  $e \in v.incidentEdges()$ 
    if  $e.getLabel() = UNEXPLORED$ 
       $w \leftarrow e.opposite(v)$ 
       $S.push(e)$ 
      if  $w.getLabel() = UNEXPLORED$ 
         $e.setLabel(DISCOVERY)$ 
         $pathDFS(G, w, z)$ 
         $S.pop(e)$ 
      else
         $T \leftarrow$  new empty stack
        repeat
           $o \leftarrow S.pop()$ 
           $T.push(o)$ 
        until  $o = w$ 
        return  $T.elements()$ 
   $S.pop(v)$ 
```