



EE4376 Laboratory for Microprocessors II

LAB 03

Peripherals and Queues: ADC and PWM (LEDC)

Goals:

- With the help of the ADC and the LEDC API's, initialize the peripherals and create a task to perform the readings of the ADC every 100 millisecond.
- This task should feed the information into a queue.
- Create a task that synchronous to the queue to update the PWM's duty cycle based on the value read by the ADC.
- Modify the program in listing 1 to achieve these goals.

Bonus:

Add a port interrupt to stop and start the PWM signal. **+10**

Pre-Lab

Questions:

- What is the function use to create a queue?
- What is the function use to send information into the

queue?

- How do you read information from the queue?

```
#include <stdio.h>
#include "sdkconfig.h"
#include "freertos/FreeRTOS.h"
#include "freertos/task.h"
#include "freertos/queue.h"
#include <driver/ledc.h>
#include <driver/adc.h>

static xQueueHandle duty_queue = NULL;

void ADCtask(void *pvParameter)
{
    while(1)
    {
        vTaskDelay(100/portTICK_PERIOD_MS);
    }
}

void PWMtask(void *pvParameter)
{
    while(1)
    {
        ledc_set_duty();
        ledc_update_duty();
    }
}

void setADC()
{
    adc1_config_width();
    adc1_config_channel_atten(, );
}

void setPWM()
{
    ledc_timer_config_t timerConfig;
    timerConfig.duty_resolution = ;
    timerConfig.timer_num = ;
    timerConfig.freq_hz = ;
    timerConfig.speed_mode = ;
    ledc_timer_config(&timerConfig);

    ledc_channel_config_t tChaConfig;
    tChaConfig.gpio_num = ;
    tChaConfig.speed_mode = ;
    tChaConfig.channel = ;
    tChaConfig.intr_type = ;
}
```

```

        tChaConfig.timer_sel = ;
        tChaConfig.duty = ;
        ledc_channel_config(&tChaConfig);
    }

void app_main()
{
    setADC();
    setPWM();
    duty_queue = xQueueCreate(10, sizeof(int));
    xTaskCreate(&ADCtask,"ADCtask",2048,NULL,5,NULL);
    xTaskCreate(&PWMtask,"PWMtask",2048,NULL,5,NULL);
}

```

Listing 1. Program template for Lab 3.