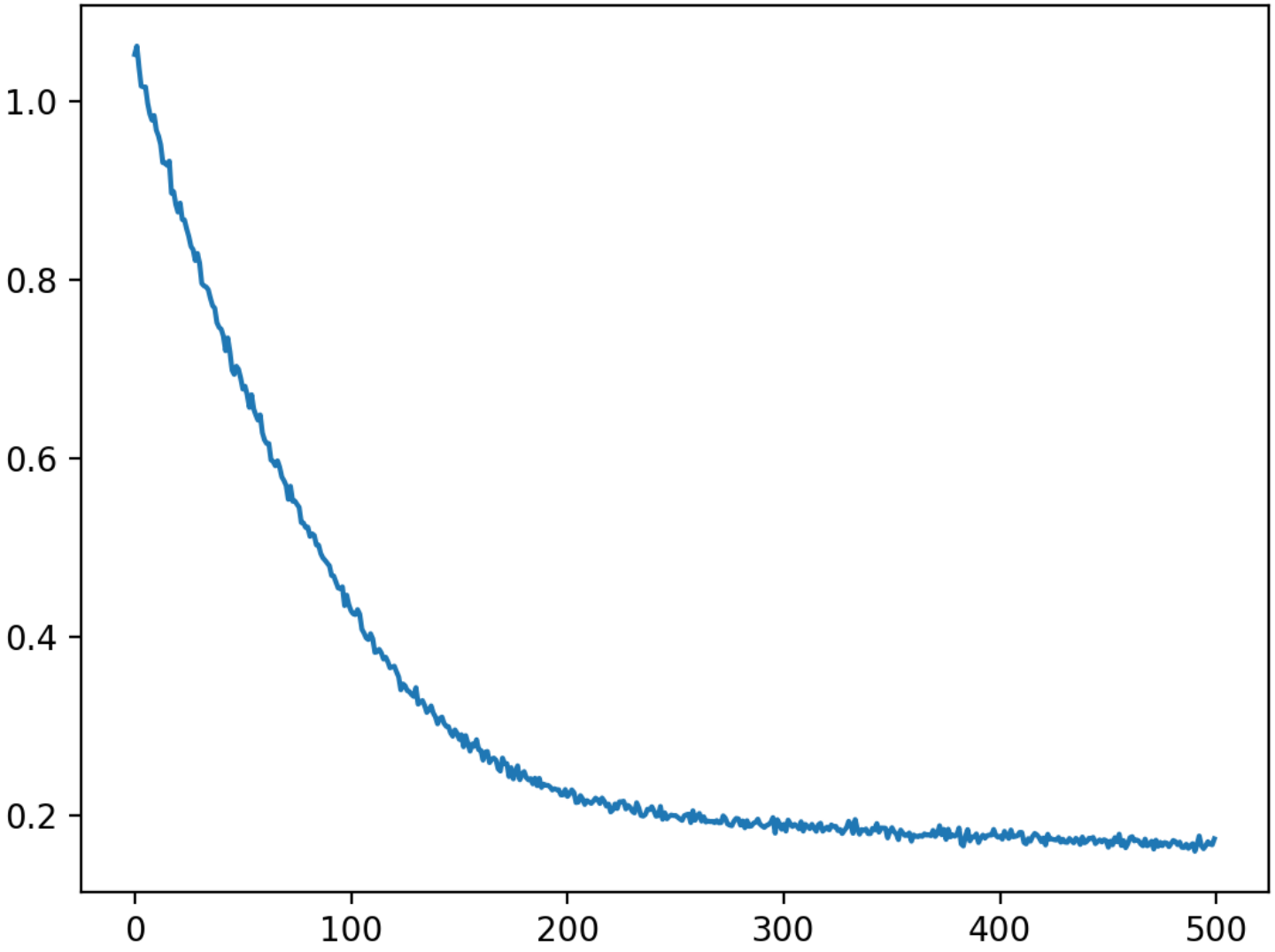
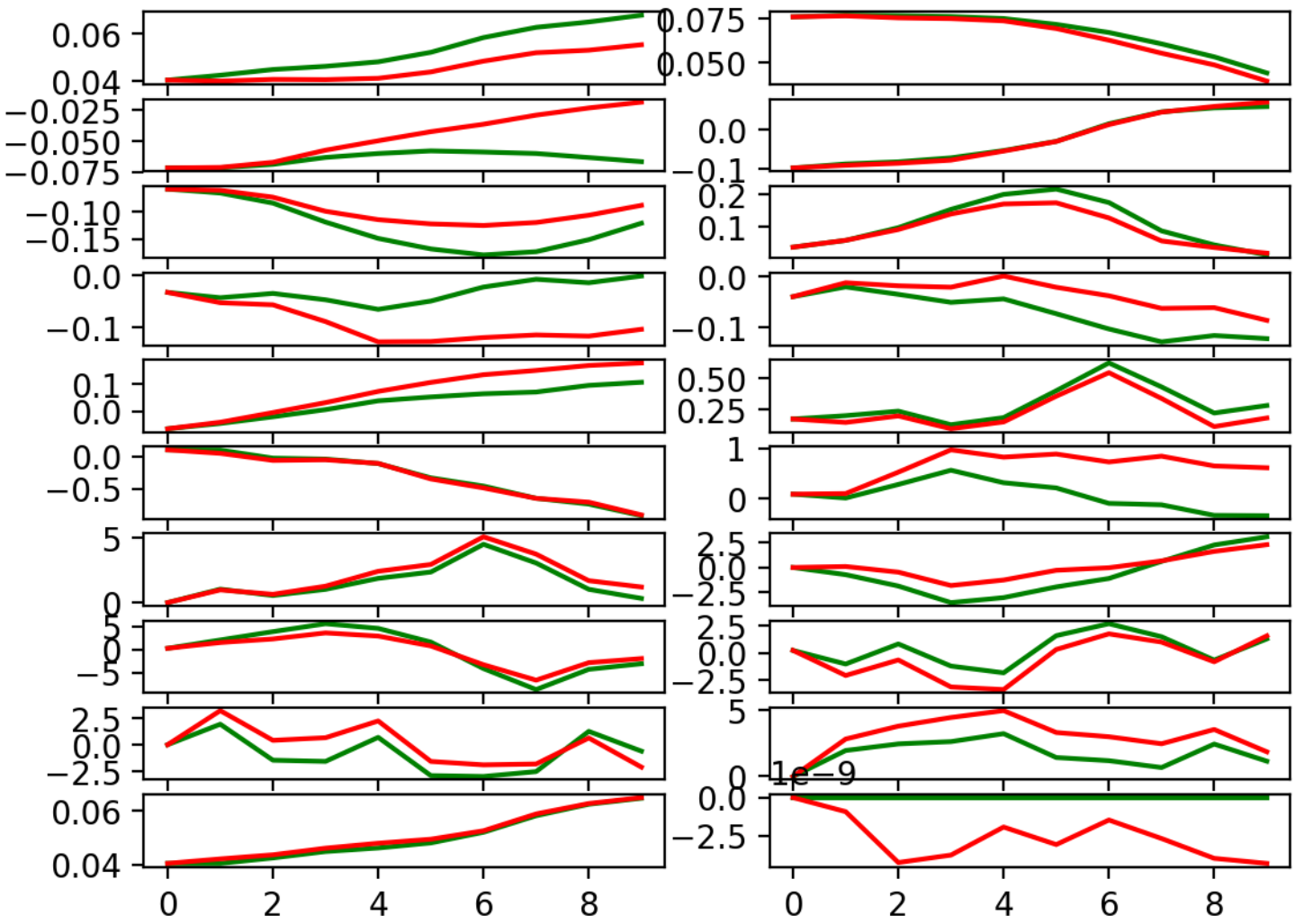
result

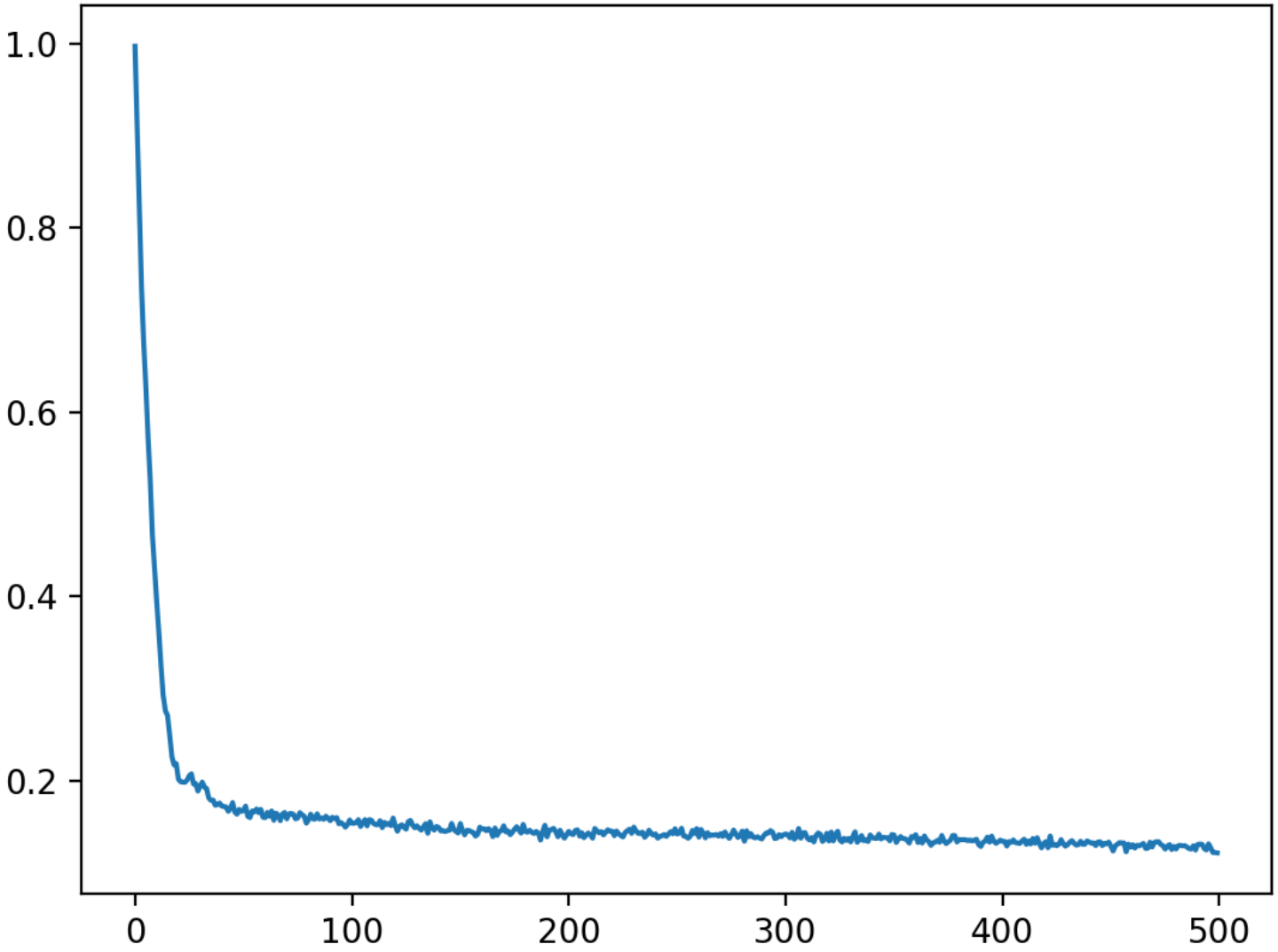
q1

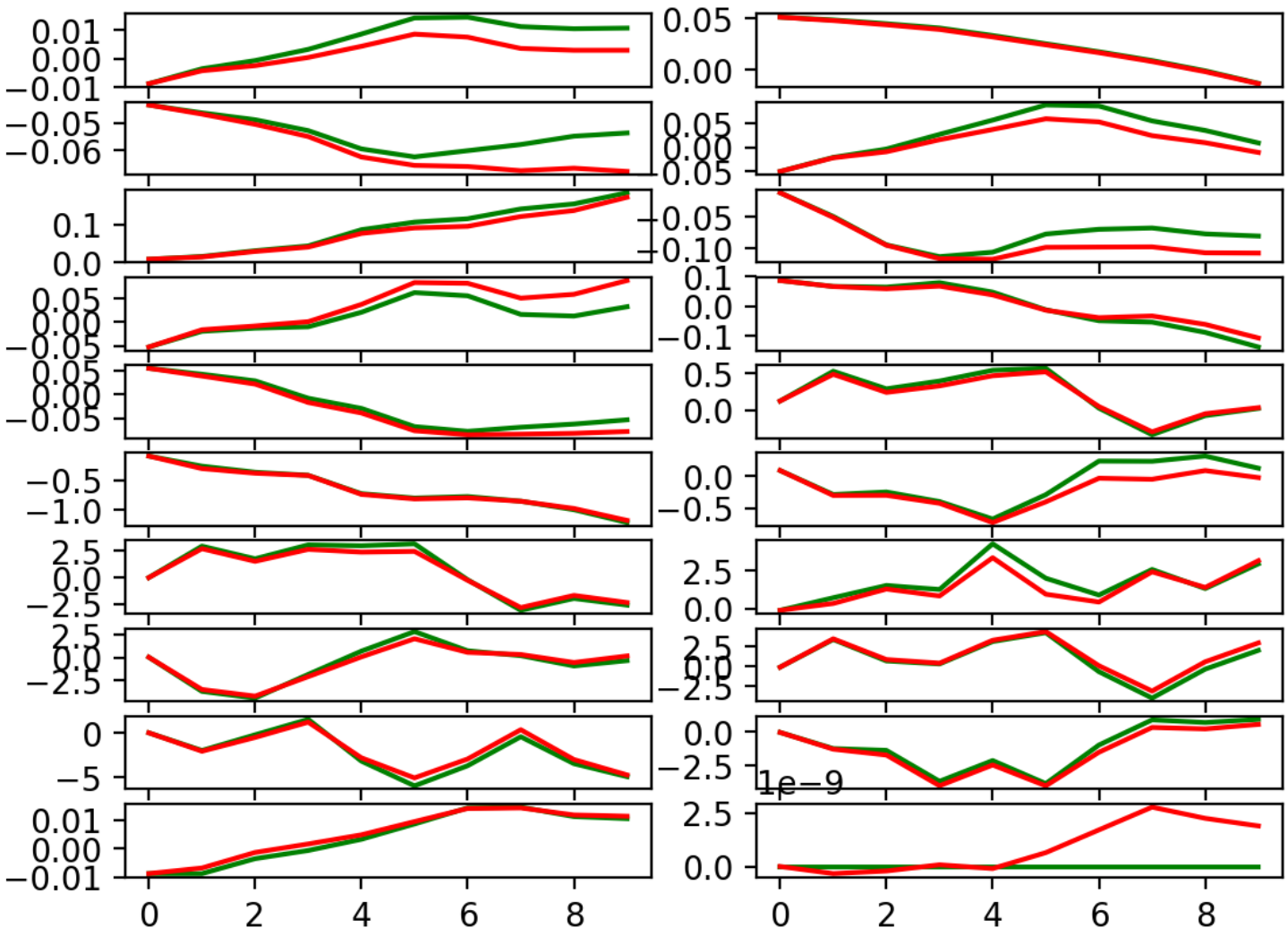
hw4_q1_cheetah_n500_arch1x32



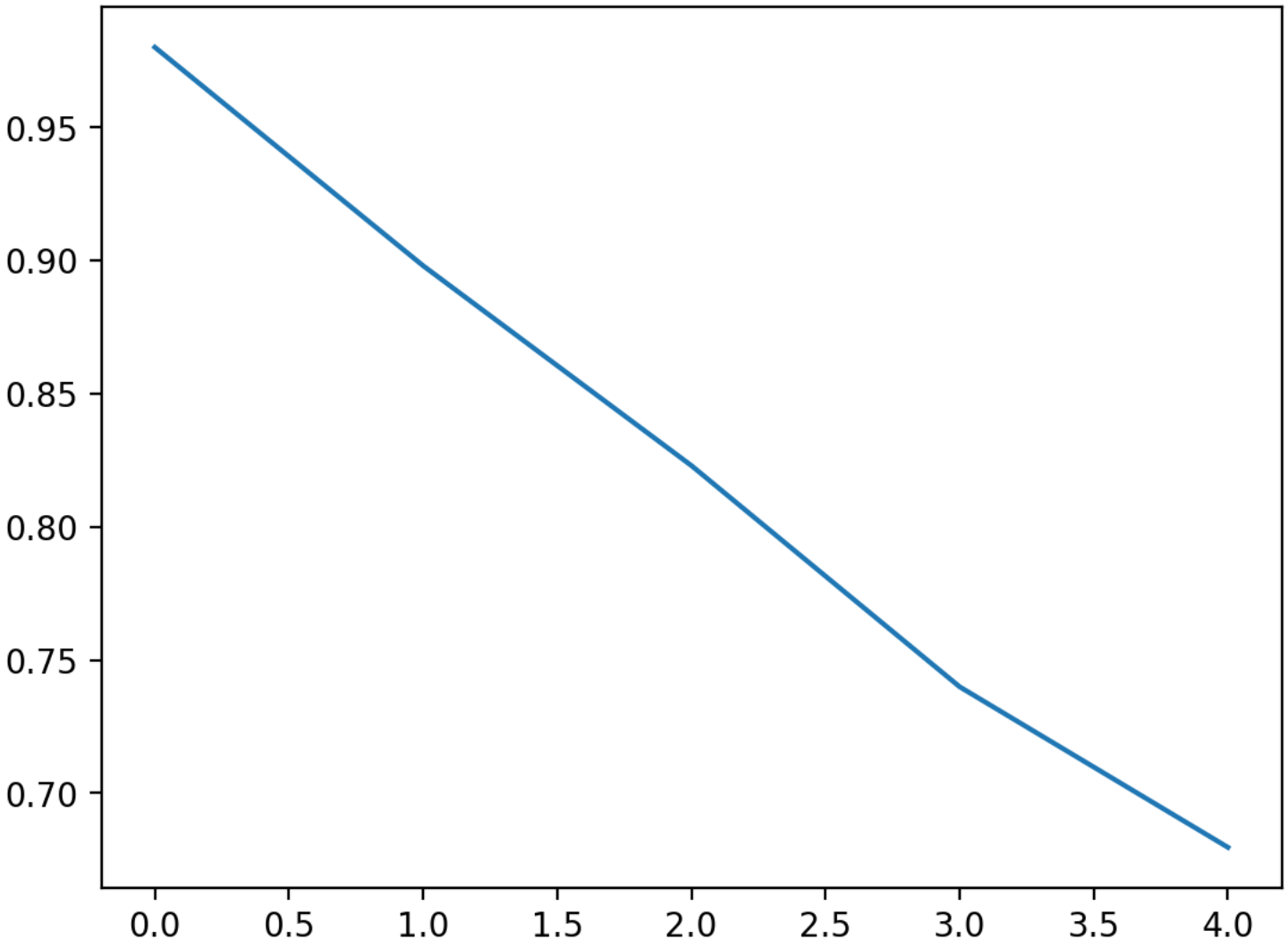


hw4_q1_cheetah_n500_arch2x250

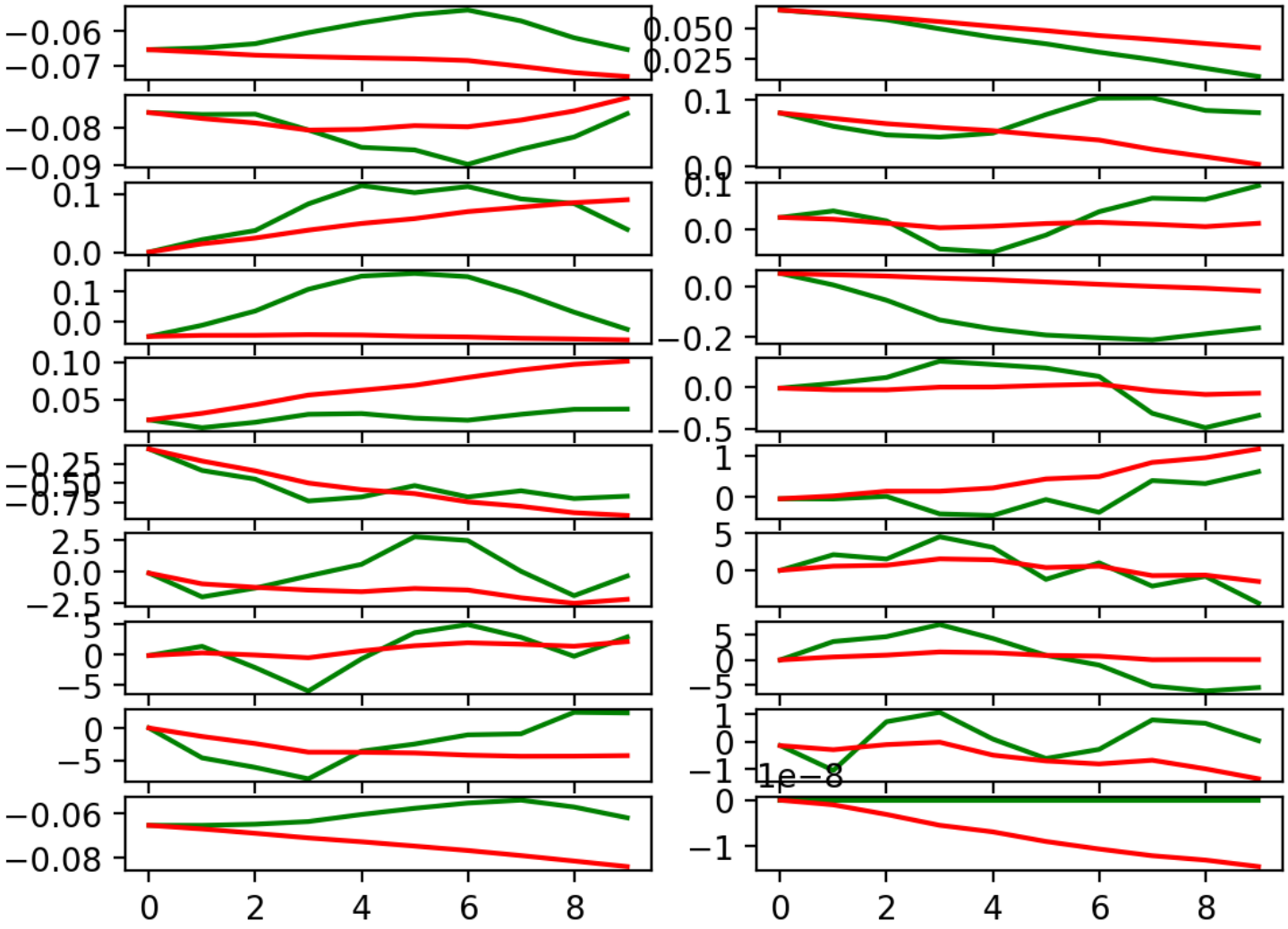

1.0
0.8
0.6
0.4
0.2
0
100
200
300
400
500



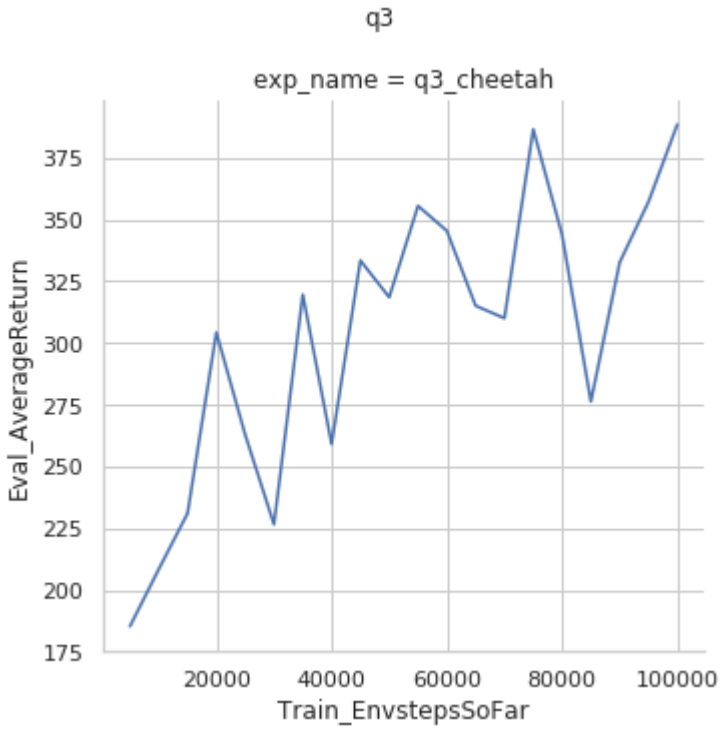
hw4_q1_cheetah_n5_arch2x250

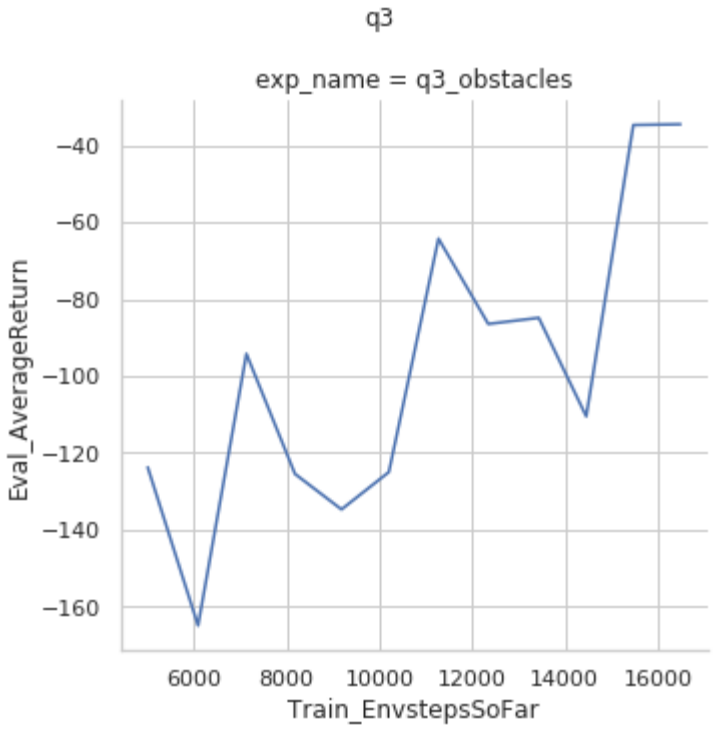

0.95
0.90
0.85
0.80
0.75
0.70
0.0
0.5
1.0
1.5
2.0
2.5
3.0
3.5
4.0

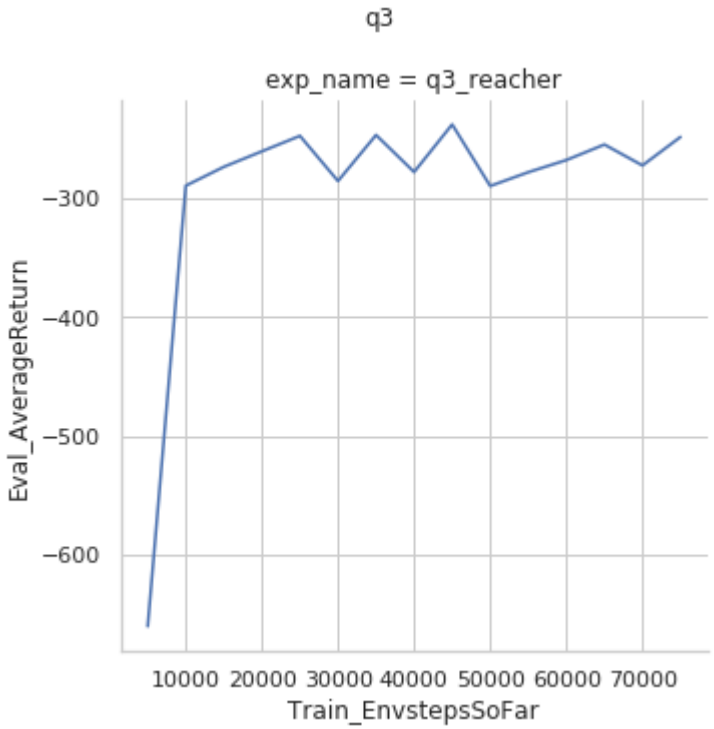
MPE: 2.2142596



q3

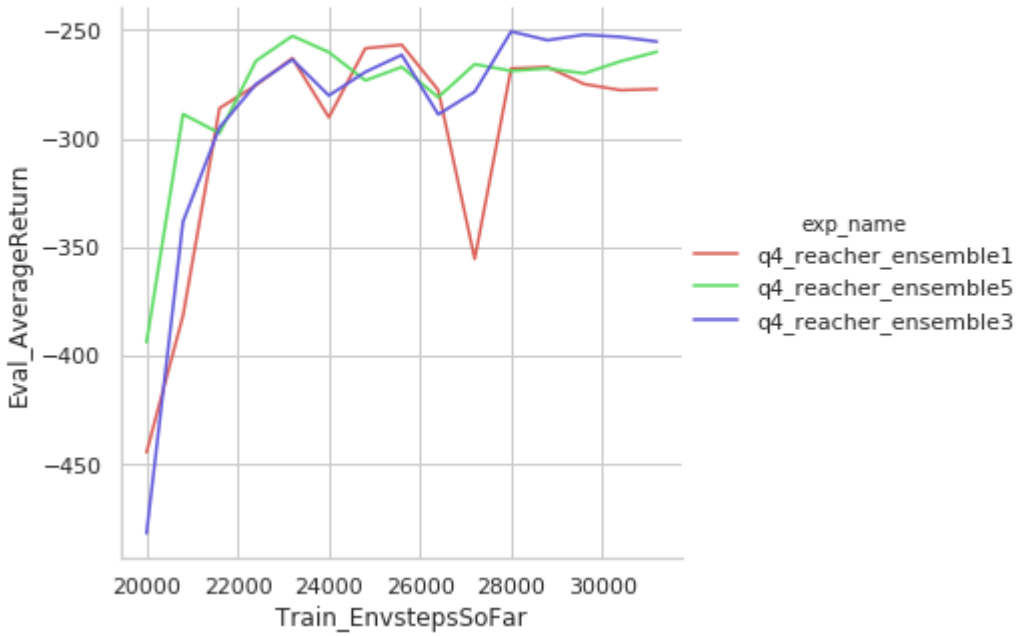

q3
exp_name = q3_cheetah
Eval_AverageReturn
Train_EnvstepsSoFar
375
350
325
300
275
250
225
200
175
20000
40000
60000
80000
100000


q3
exp_name = q3_obstacles
Eval_AverageReturn
Train_EnvstepsSoFar
−40
−60
−80
−100
−120
−140
−160
6000
8000
10000
12000
14000
16000

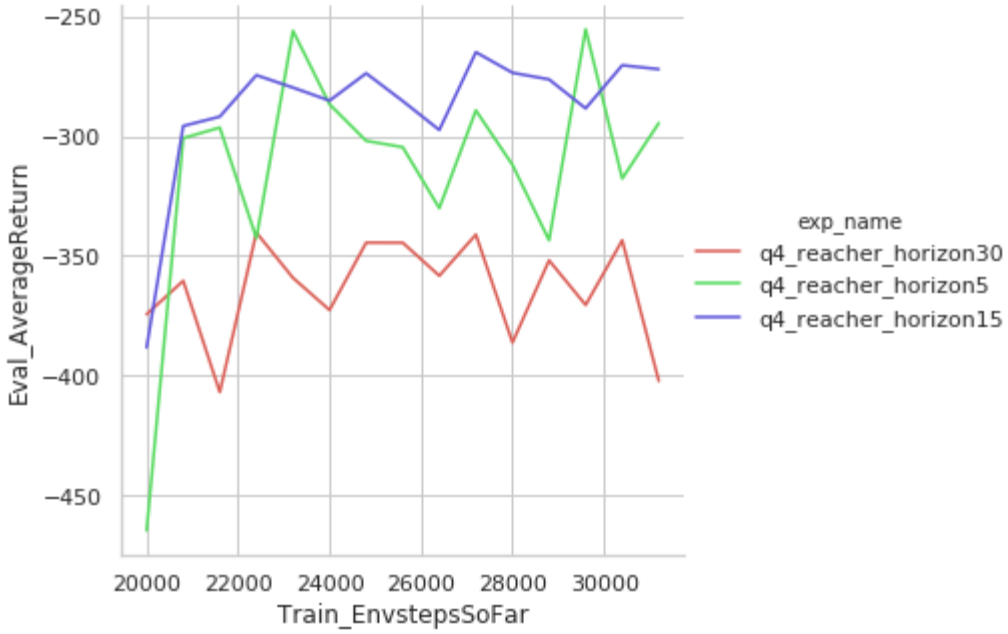

q3
exp_name = q3_reacher
−300
−400
−500
−600
Eval_AverageReturn
10000 20000 30000 40000 50000 60000 70000
Train_EnvstepsSoFar

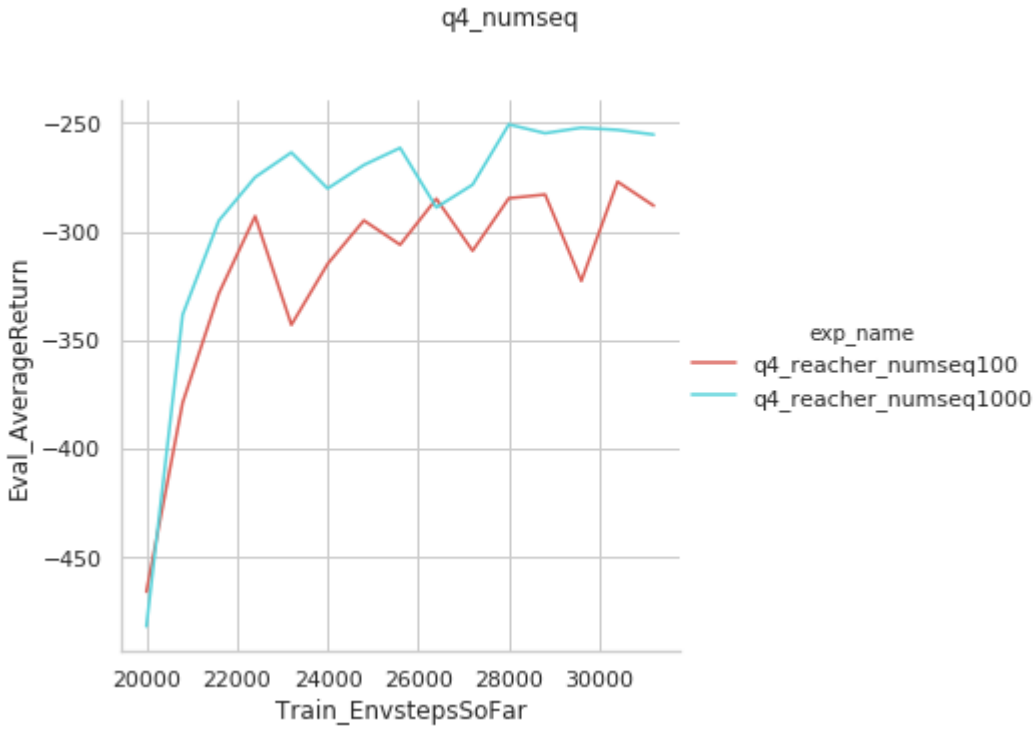
q4

q4_ensemble



q4_horizon




q4_numseq
−250
−300
−350
−400
−450
Eval_AverageReturn
20000
22000
24000
26000
28000
30000
Train_EnvstepsSoFar
exp_name
q4_reacher_numseq100
q4_reacher_numseq1000