view_frames Result Recorded at time: 2801.018 sensor_frame Broadcaster: /base_broadcaster Average rate: 10000.000 Hz Most recent transform: 0.000 (2801.018 sec old) Buffer length: 0.000 sec world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (2801.018 sec old) Buffer length: 0.000 sec link_base Broadcaster: /robot_base_broadcaster Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 50.207 Hz Most recent transform: 2800.987 (0.031 sec old) Most recent transform: 0.000 (2801.018 sec old) Buffer length: 0.000 sec Buffer length: 4.820 sec gazebo_base link1 Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 2800.987 (0.031 sec old) Buffer length: 4.820 sec link2 Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 2800.987 (0.031 sec old) Buffer length: 4.820 sec link3 Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 2800.987 (0.031 sec old) Buffer length: 4.820 sec link4 Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 2800.987 (0.031 sec old) Buffer length: 4.820 sec link5 Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 2800.987 (0.031 sec old) Buffer length: 4.820 sec link6 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (2801.018 sec old) Buffer length: 0.000 sec link_eef Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (2801.018 sec old) Buffer length: 0.000 sec xarm_gripper_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Average rate: 50.207 Hz Average rate: 50.207 Hz Average rate: 10000.000 Hz Average rate: 50.207 Hz Most recent transform: 0.000 (2801.018 sec old) Most recent transform: 2800.987 (0.031 sec old) Most recent transform: 2800.987 (0.031 sec old) Most recent transform: 2800.987 (0.031 sec old) Most recent transform: 2800.987 (0.031 sec old) Buffer length: 0.000 sec Buffer length: 4.820 sec Buffer length: 4.820 sec Buffer length: 4.820 sec Buffer length: 4.820 sec link_tcp left_inner_knuckle right_outer_knuckle left_outer_knuckle right_inner_knuckle Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Average rate: 50.207 Hz Most recent transform: 2800.987 (0.031 sec old) Most recent transform: 2800.987 (0.031 sec old) Buffer length: 4.820 sec Buffer length: 4.820 sec left_finger right_finger