"Solving Dynamic General Equilibrium Models Using a Second-Order Approximation to the Policy Function," by Stephanie Schmitt-Grohe and Martin Uribe (JEDC, vol. 28, January 2004, pp. 755-775)

Matlab code

First-order approximation

gx hx.m

Second-order approximation

gxx_hxx.m gss_hss.m

Obtaining the derivatives of f

(requires Matlab's Symbolic Math Toolbox)

anal deriv.m num eval.m

Model Simulation:

simu 2nd.m

Writing the Output of anal_deriv.m to an M-file: This program saves significant amount of computational time in applications in which the output of anal_deriv.m has to be evaluated repeatedly.

anal deriv print2f.m by Andrea Pescatori

Computing Unconditional Second Moments: mom.m

Computing Unconditional Means: unconditional mean.m

Implementing Iskrev's Identifiability Test

Example 1: The neoclassical growth model

(requires Matlab's Symbolic Math Toolbox)

neoclassical model.m

neoclassical model ss.m

neoclassical model run.m

Example 2: A Two-Country Model With Complete Asset Markets (J. Kim and S. Kim, JIE, 2003)

(requires Matlab's Symbolic Math Toolbox)

kim model.m

kim ss.m

kim run.m

Example 3: An Asset Pricing Model (Burnside, *JEDC* 1998; and Collard and Juillard, *JEDC* 2001)

(requires Matlab's Symbolic Math Toolbox)

asset model.m

asset ss.m

asset run.m