





Course 'Operating Systems Architecture' – tutorial: Concurrency problems

UFAZ, L2

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http://pages.cs.wisc.edu/~remzi/OSTEP/

http://pages.cs.wisc.edu/~remzi/OSTEP/Homework/homework.html

This homework lets you explore some real code that deadlocks (or avoids deadlock). The different versions of code correspond to different approaches to avoiding deadlock in a simplified vector add() routine.

See the $\ensuremath{\mathtt{README}}$ for details on these programs and their common substrate.

1. Exercise 1

First let's make sure you understand how the programs generally work, and some of the key options. Study the code in vector-deadlock.c, as well as in main-common.c and related files.

- 1.1 Now, run ./vector-deadlock -n 2 -l 1 -v, which instantiates two threads (-n 2), each of which does one $vector_add(-l 1)$, and does so in verbose mode (-v). Make sure you understand the output.
- 1.2 How does the output change from run to run?

2. Exercise 2

Now add the -d flag, and change the number of loops (-1) from 1 to higher numbers.

- 2.1 What happens?
- 2.2 Does the code (always) deadlock?

3. Exercise 3

- 3.1 How does changing the number of threads (-n) change the outcome of the program?
- 3.2 Are there any values of -n that ensure no deadlock occurs?

4. Exercise 4

Now examine the code in vector-global-order.c.

4.1 First, make sure you understand what the code is trying to do; do you understand why the code avoids deadlock?







4.2 Also, why is there a special case in this vector_add() routine when the source and destination vectors are the same?

5. Exercise 5

Now run the code with the following flags: -t -n 2 -1 100000 -d.

- 5.1 How long does the code take to complete?
- 5.2 How does the total time change when you increase the number of loops, or the number of threads?

6. Exercise 6

- 6.1 What happens if you turn on the parallelism flag (-p)?
- 6.2 How much would you expect performance to change when each thread is working on adding different vectors (which is what -p enables) versus working on the same ones?

7. Exercise 7

Now let's study vector-try-wait.c. First make sure you understand the code.

- 7.1 Is the first call to pthread mutex trylock() really needed?
- 7.2 Now run the code. How fast does it run compared to the global order approach?
- 7.3 How does the number of retries, as counted by the code, change as the number of threads increases?

8. Exercise 8

Now let's look at vector-avoid-hold-and-wait.c.

8.1 What is the main problem with this approach? How does its performance compare to the other versions, when running both with -p and without it?

9. Exercise 9

Finally, let's look at vector-nolock.c.

- 9.1 This version doesn't use locks at all; does it provide the exact same semantics as the other versions?
- 9.2 Why or why not?







Now compare its performance to the other versions, both when threads are working on the same two vectors (no $\neg p$) and when each thread is working on separate vectors ($\neg p$).

10.1 How does this no-lock version perform?