

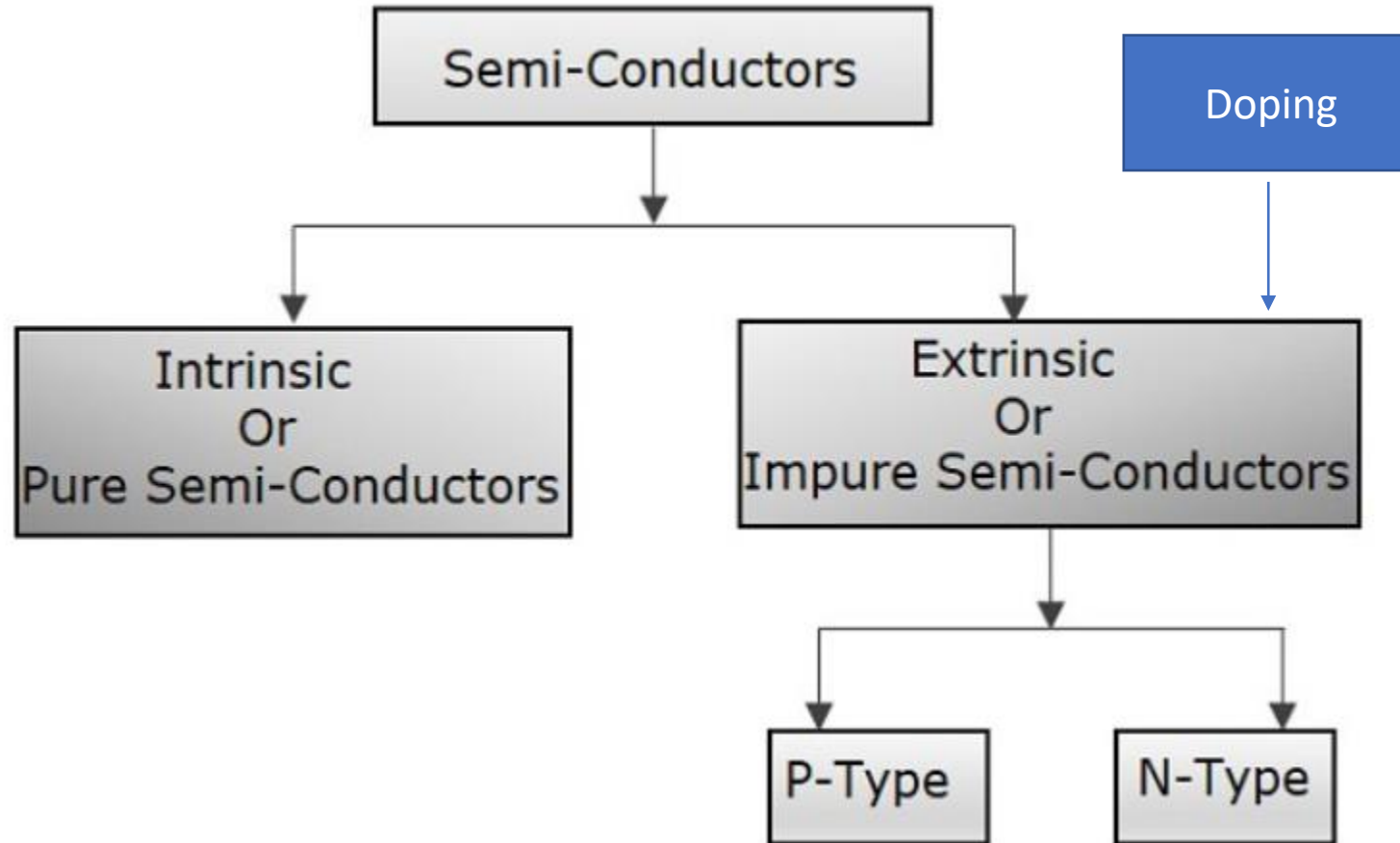
Review of Semiconductors: Energy band structure of Insulator, Semiconductor and Metal, Intrinsic and extrinsic semiconductor.

P-N Junction Diodes, and its application:, clipping and clamping circuits, Rectifiers and filters, Zener diode and regulators.

Semiconductors

- A **semiconductor** is a substance whose resistivity lies between the conductors and insulators.
 - Semiconductors have the resistivity which is less than insulators and more than conductors.
 - Semiconductors have **negative temperature co-efficient**.
 - The **resistance** in semiconductors, **increases with the decrease in temperature** and vice versa.
 - The **Conducting properties** of a Semiconductor **changes**, when a **suitable metallic impurity is added** to it, which is a very important property

Classification of semiconductors



Conduction in Semiconductors

- **Valence electrons:** The outermost shell has the electron which are loosely attached to the nucleus
- Such an atom, having valence electrons when brought close to the other atom, the valence electrons of both these atoms combine to form “**Electron pairs**”
- This bonding is not so very strong and hence it is a **Covalent bond (Sharing)**

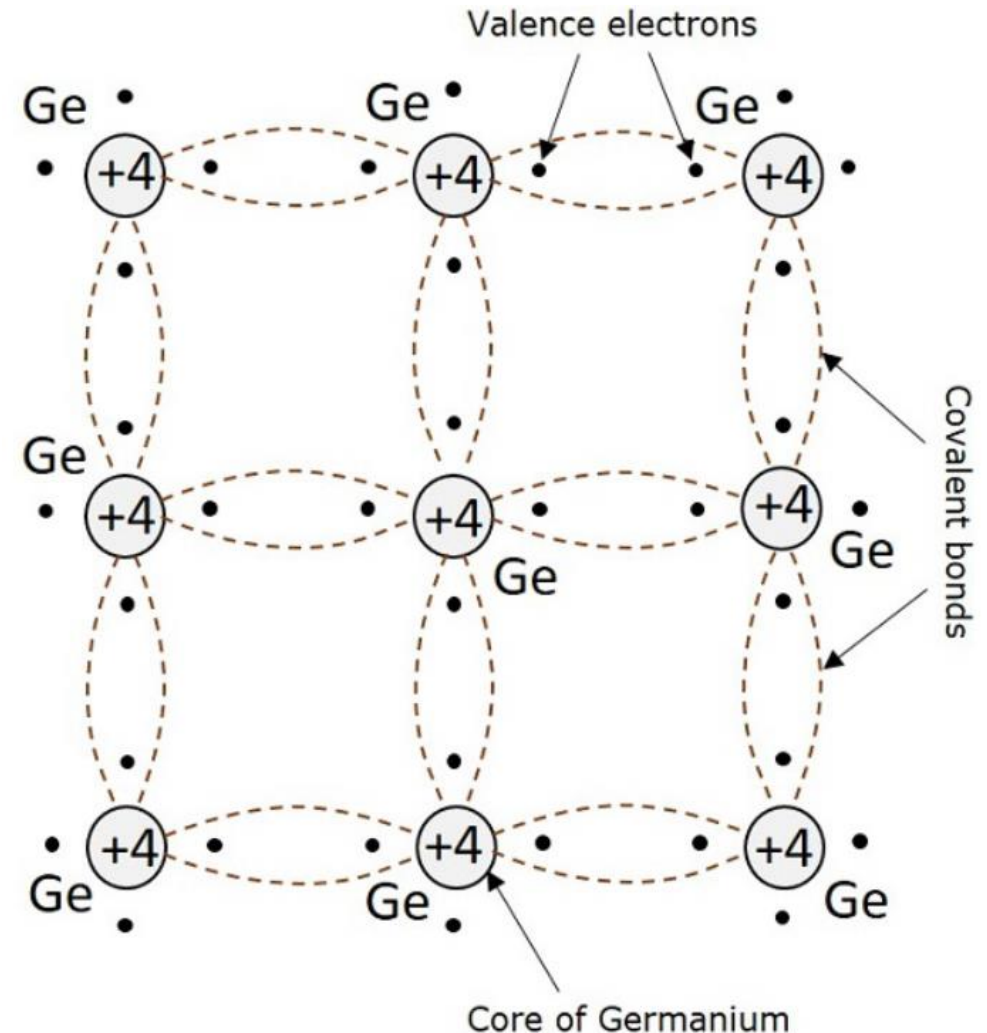
Germanium

Electronic configuration:

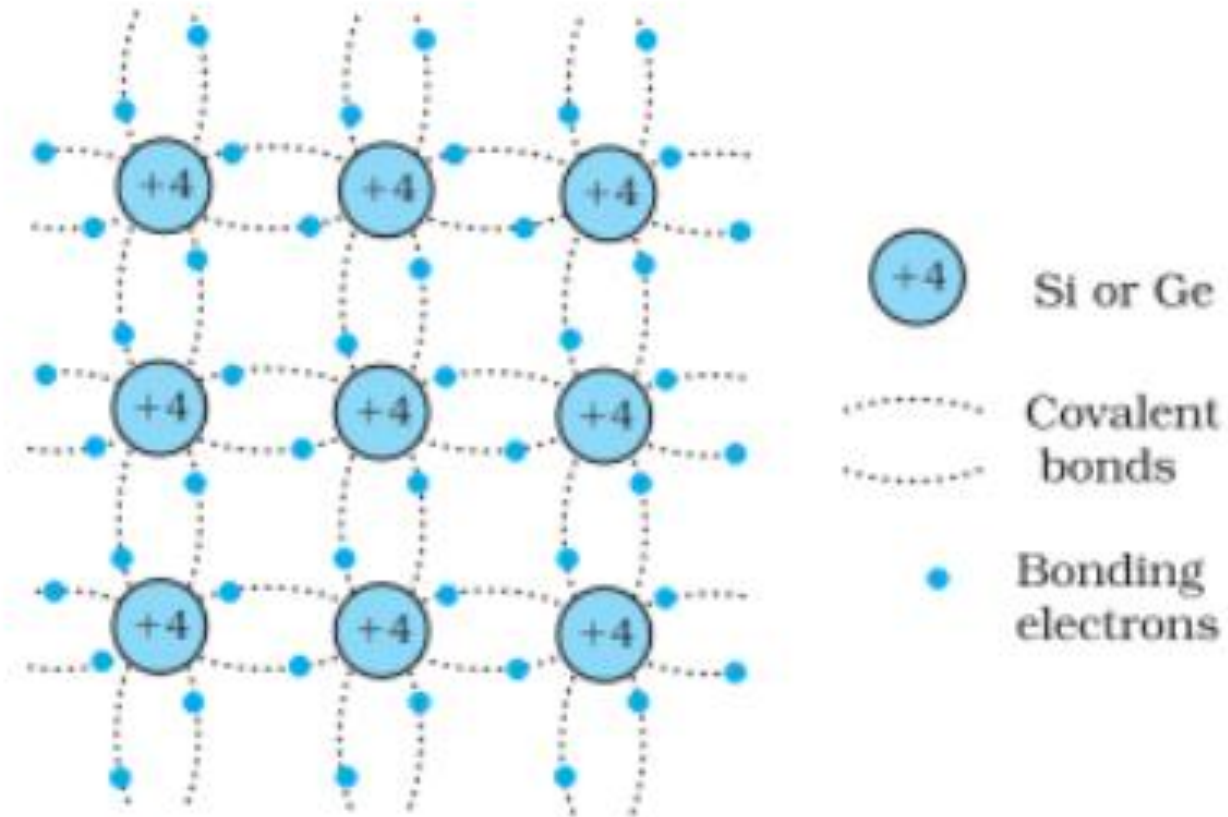
2 (First orbit), 8, 18,

4 (Last orbit) (Valence els)

Stable Ge (8 els)



Hole generation and movement



Schematic two-dimensional representation of Si or Ge structure showing covalent bonds at low temperature (all bonds intact). +4 symbol indicates inner cores of Si or Ge.

Cont.

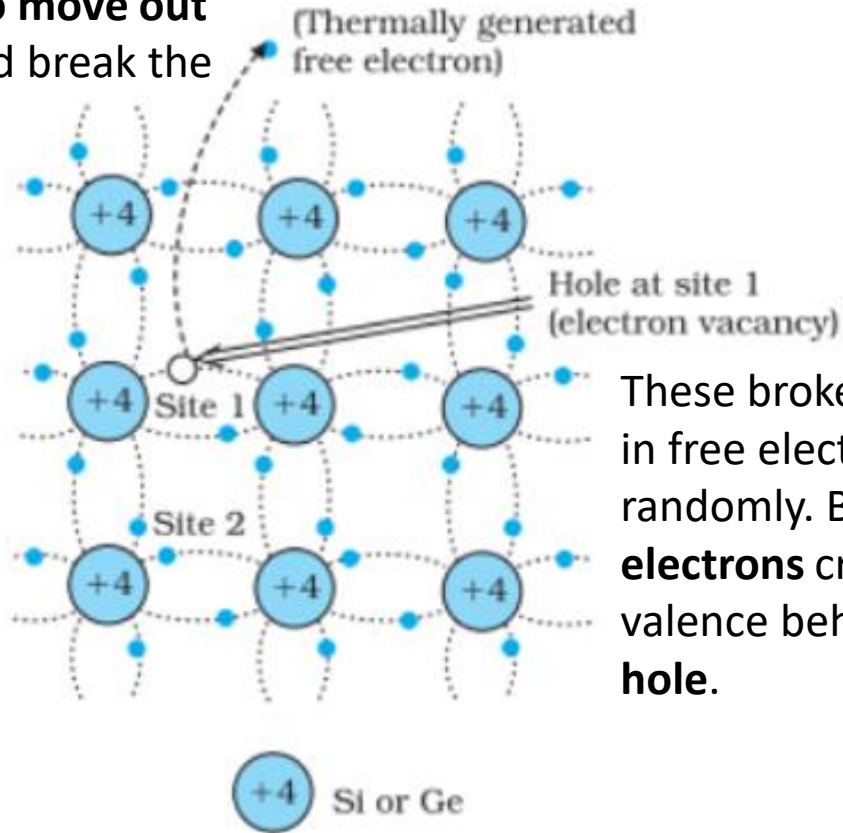
(Higher Energy level)CB (Max Freedom) E1

Temperature (E1-E2)

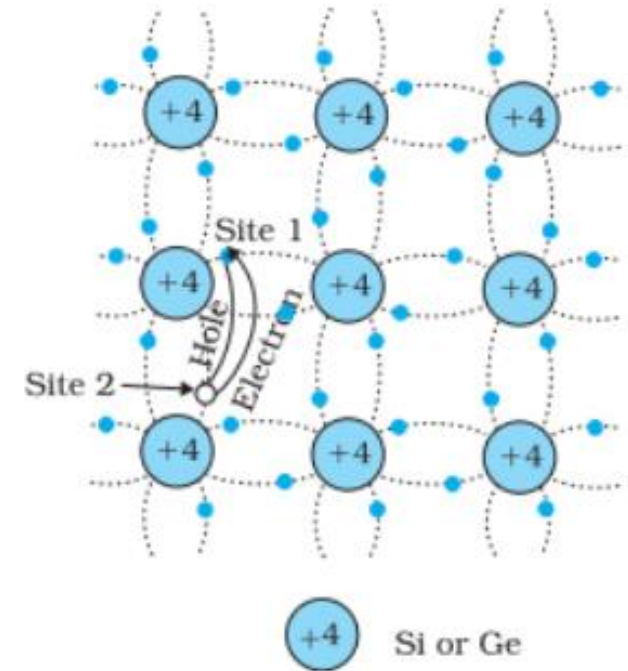
(Lower Energy level)VB (Bonded) E2

thermal energy
the crystal, some
end to move out
ce and break the
onds.

This **hole** which represents a **missing electron** can be considered as a **unit positive charge** while the electron is considered as a unit negative charge.



These broken covalent bonds, result in free electrons which wander randomly. But the **moved away electrons** creates an empty space or valence behind, which is called as a **hole**.



model of generation of hole at site 1 and conduction electron due to thermal energy at moderate temperatures.

Simplified representation of possible thermal motion of a hole. The electron from the lower left hand covalent (site 2) goes to the earlier hole site 1, leaving a hole at its site indicating apparent movement of the hole from site 1 to site 2.

Current in semiconductor

Under an electric field, these holes move towards the negative potential generating hole current (I_h). Hence, the total current (I) is:

$$I = I_e + I_h$$

Cont.

Electron-hole generation and recombination

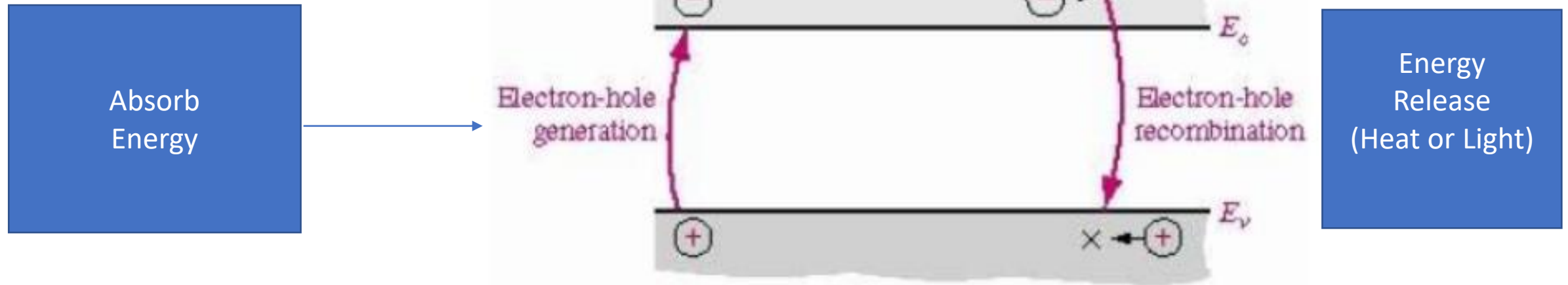
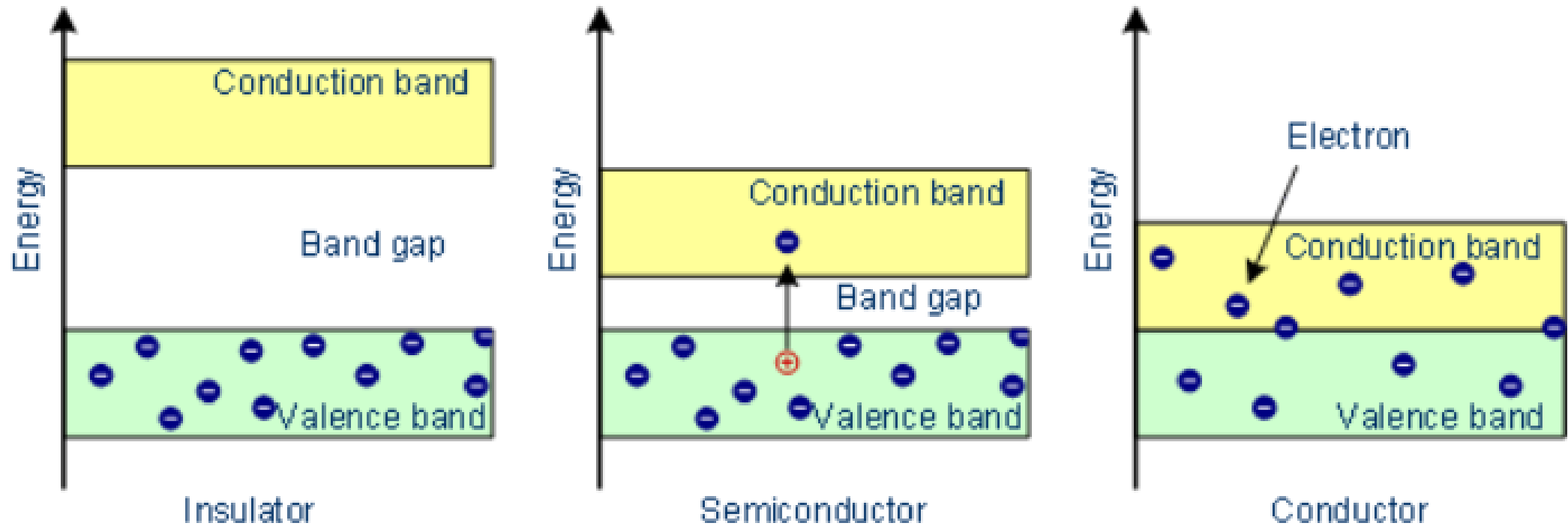


Figure 6.1 | Electron-hole generation and recombination.

In the **steady state**, the **thermal generation rate is balanced by the recombination rate**

Energy band structure of Insulator, Semiconductor and Metal



Intrinsic Semiconductors

- A Semiconductor in its extremely **pure form** is said to be an **intrinsic semiconductor**.
- The properties of this pure semiconductor are as follows –
 - The **electrons and holes are solely** created by **thermal excitation**.
 - The number of free **electrons is equal** to the number of **holes**.
 - The **conduction capability is small** at room temperature.
- In order to **increase** the **conduction** capability of intrinsic semiconductor, it is better to add some impurities.
- This process of adding impurities is called as **Doping**.
- Now, this **doped intrinsic semiconductor** is called as an **Extrinsic Semiconductor**

Doping

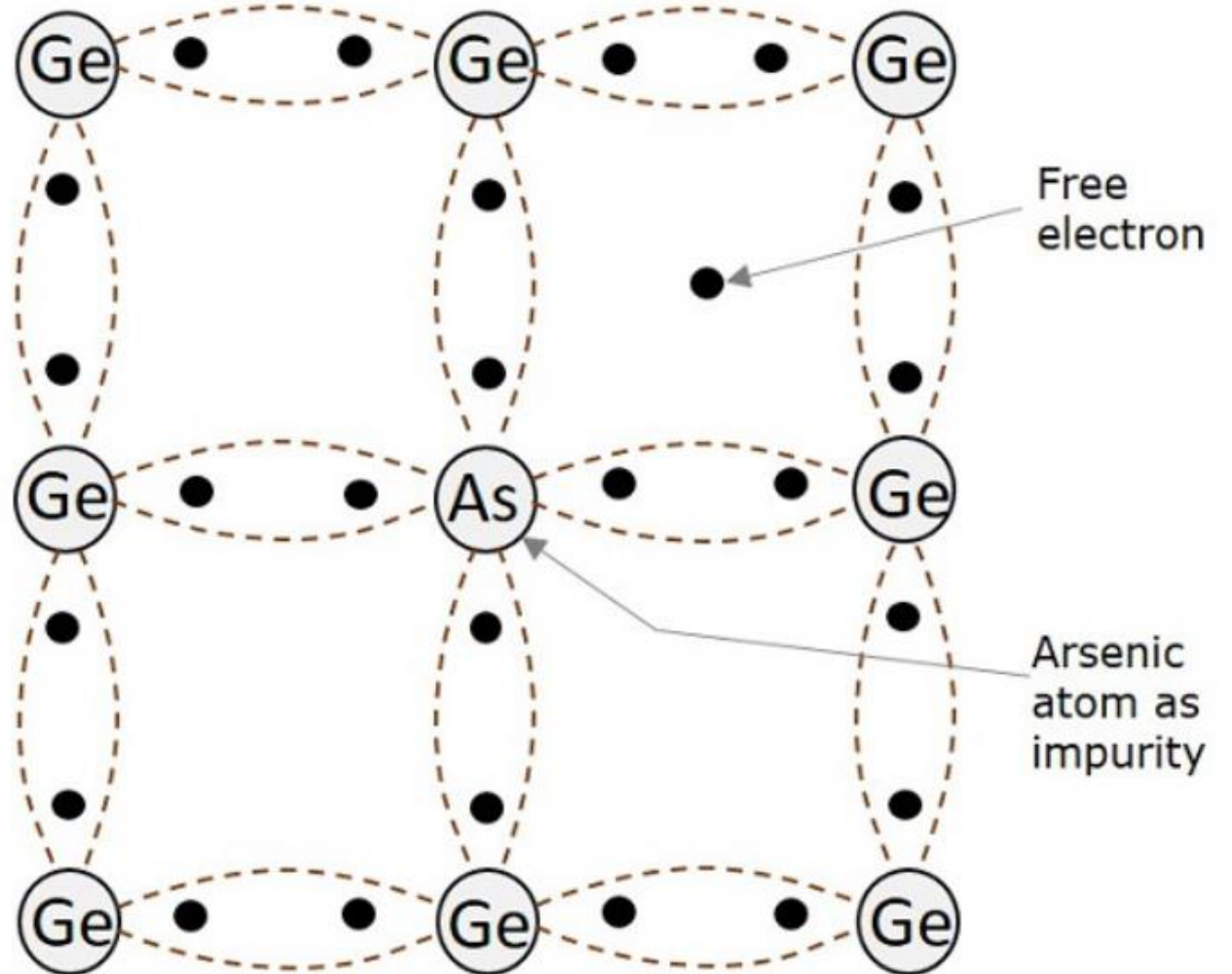
- Generally pentavalent and trivalent impurities
- **Pentavalent Impurities**
 - The **pentavalent** impurities are the ones which has **five valence electrons** in the outer most orbit. Example: Bismuth, Antimony, Arsenic, Phosphorus
 - The pentavalent atom is called as a **donor atom** because it **donates one electron to the conduction band** of pure semiconductor atom.
- **Trivalent Impurities**
 - The **trivalent** impurities are the ones which has **three valence electrons** in the outer most orbit. Example: Gallium, Indium, Aluminum, Boron
 - The trivalent atom is called as an **acceptor atom** because it accepts one electron from the semiconductor atom.

Extrinsic Semiconductor

- An impure semiconductor, which is formed by doping a pure semiconductor is called as an **extrinsic semiconductor**.
- There are two types of extrinsic semiconductors depending upon the type of impurity added.
- They are **N-type extrinsic semiconductor** and **P-Type extrinsic semiconductor**.

N-Type Extrinsic Semiconductor

- **N-type extrinsic semiconductor:** Conduction takes place through electrons, the **electrons are majority** carriers, and the **holes are minority carriers**.
- As there is no addition of positive or negative charges, the electrons are electrically neutral



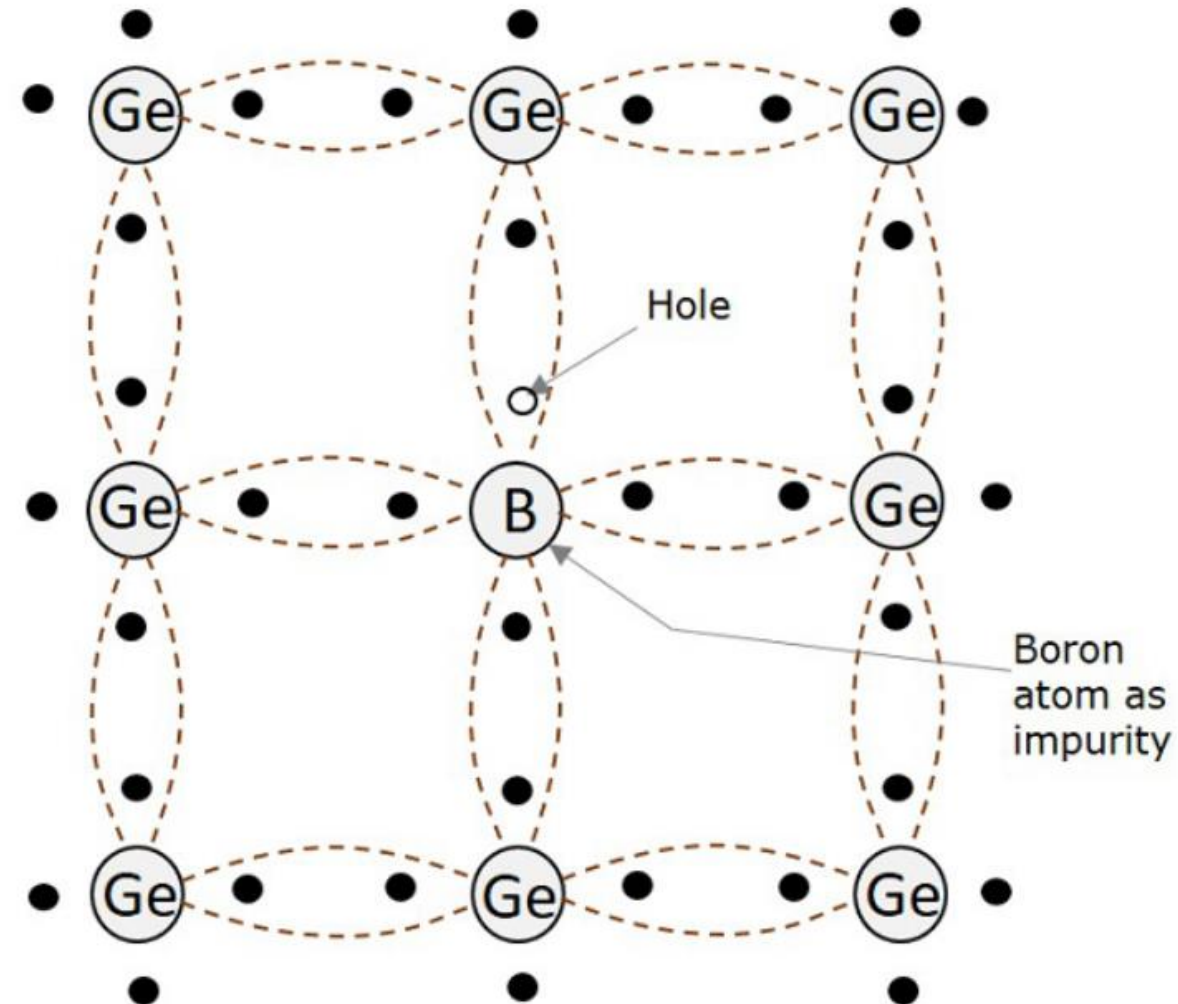
P-Type Extrinsic Semiconductor

- **P-type extrinsic semiconductor:** conduction takes place through holes; the **holes are majority** carriers while the **electrons are minority** carriers.

- The impurity added here provides holes which are called as **acceptors**, because they **accept electrons from the germanium atoms**.

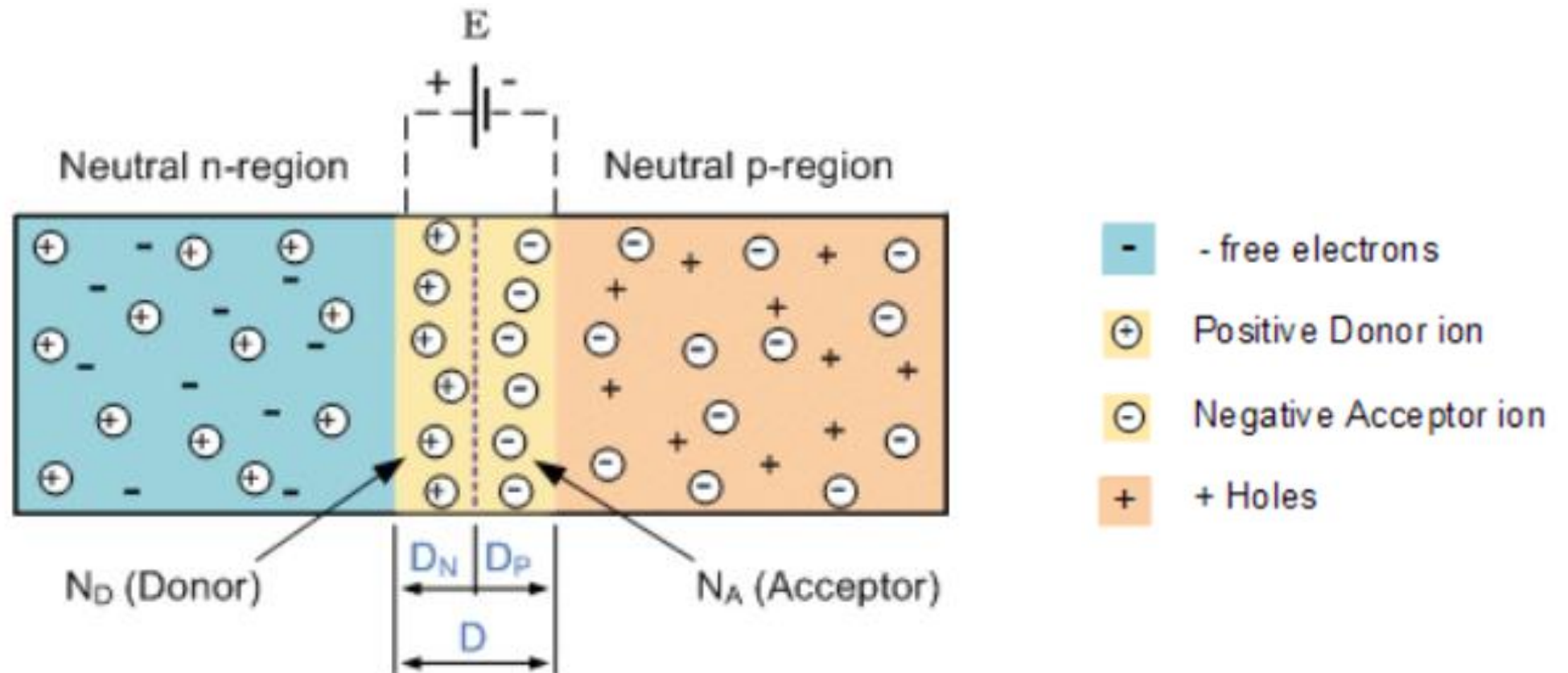
- As the number of mobile holes remains equal to the number of acceptors, the P-type semiconductor remains electrically neutral.

- In this P-type conductivity, the **valence electrons move from one covalent bond to another**, unlike N-type

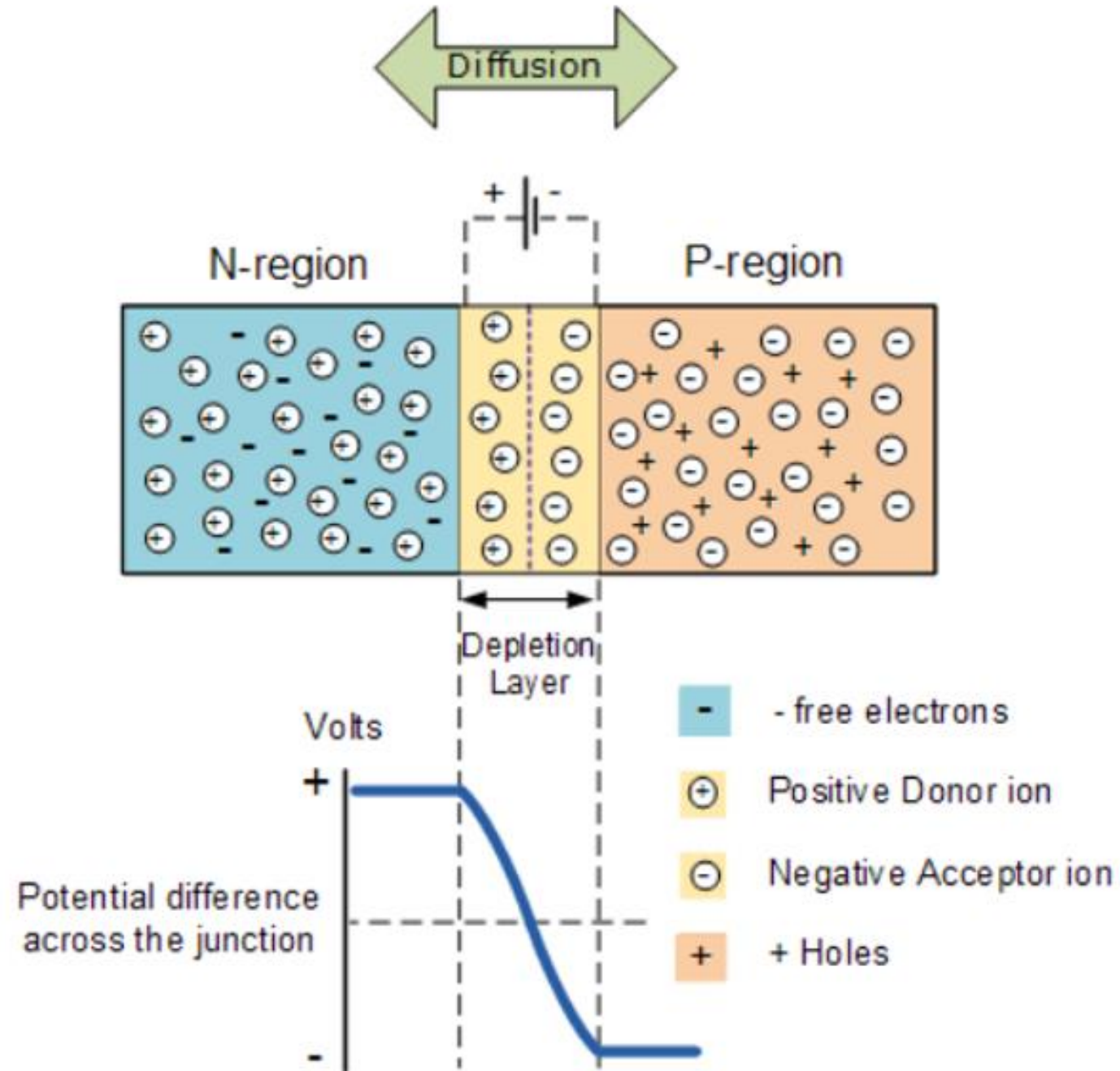


P-N Junction Diode

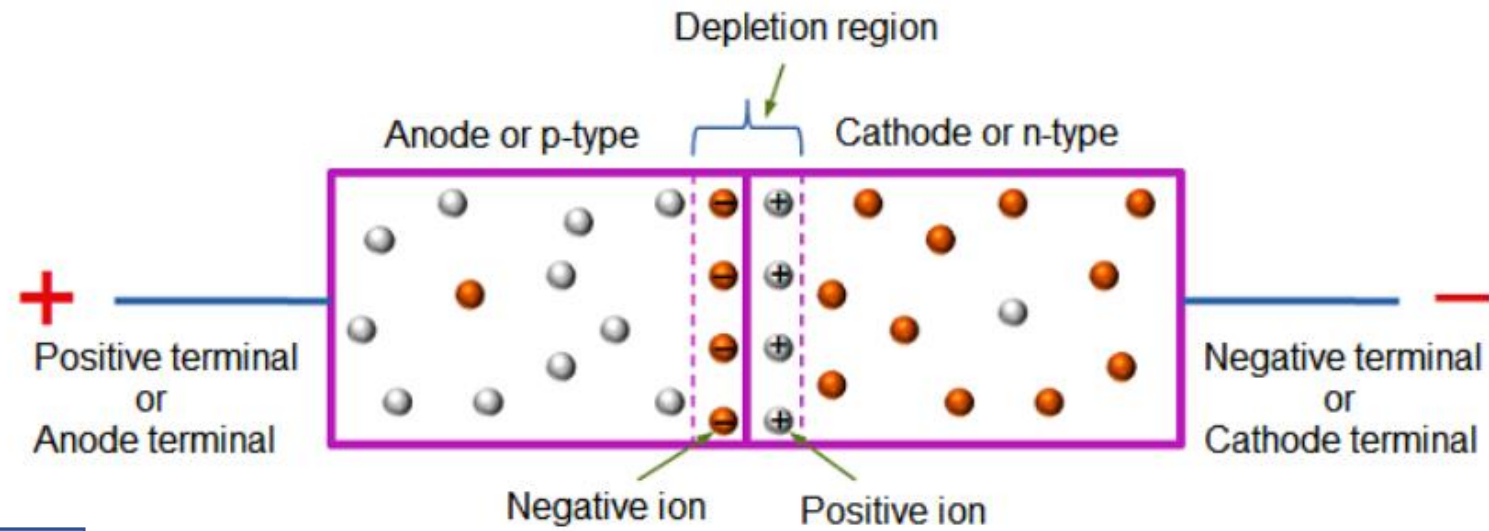
- A p-n junction diode is two-terminal or two-electrode semiconductor device, which allows the electric current in only one direction while blocks the electric current in opposite or reverse direction.



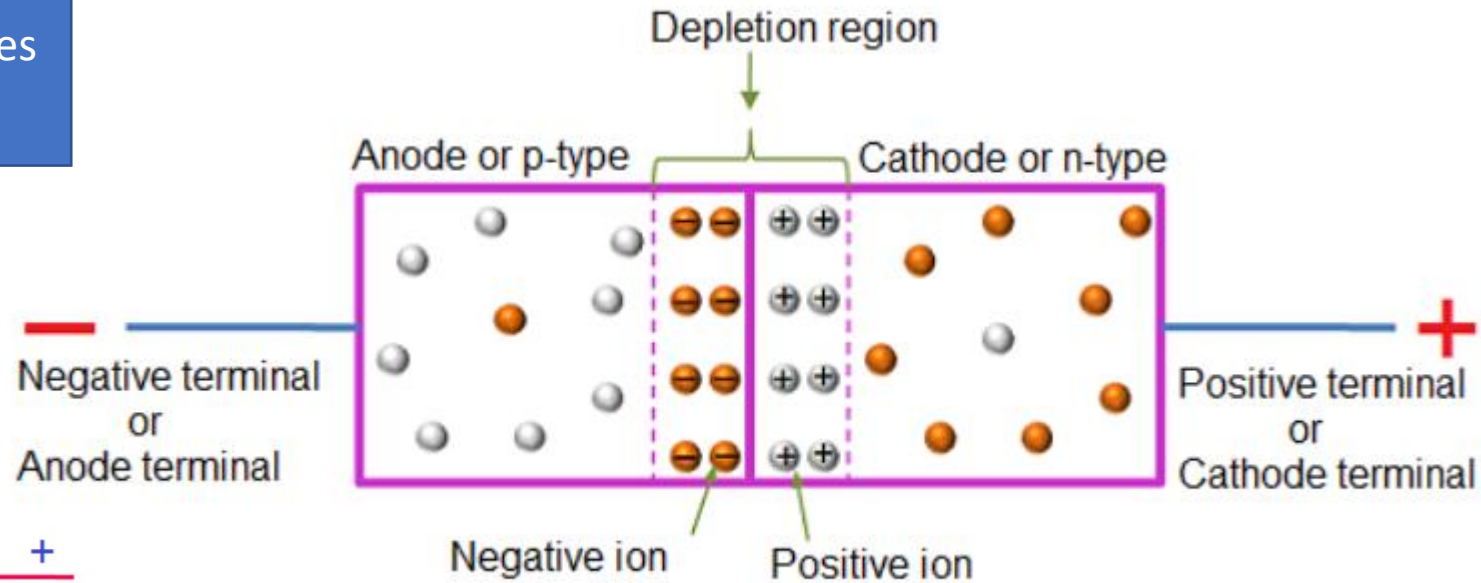
PN Junction



PN Junction biasing



Forward biased



Reverse biased



Forward biased



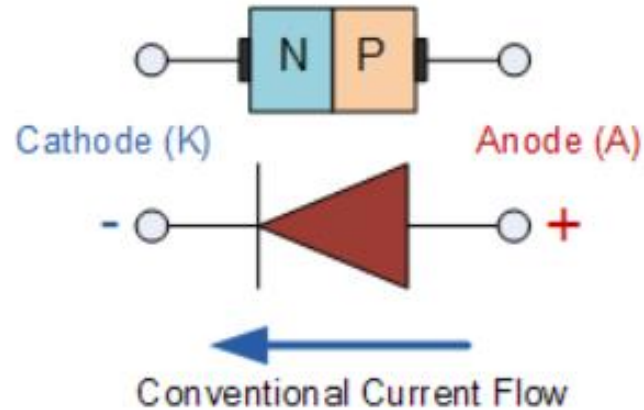
Reverse biased

Higher Force = 1e and 1Hole
(KE) = A = EHP (KE) = A =
EHP(KE) = Sufficient Charges
= Current

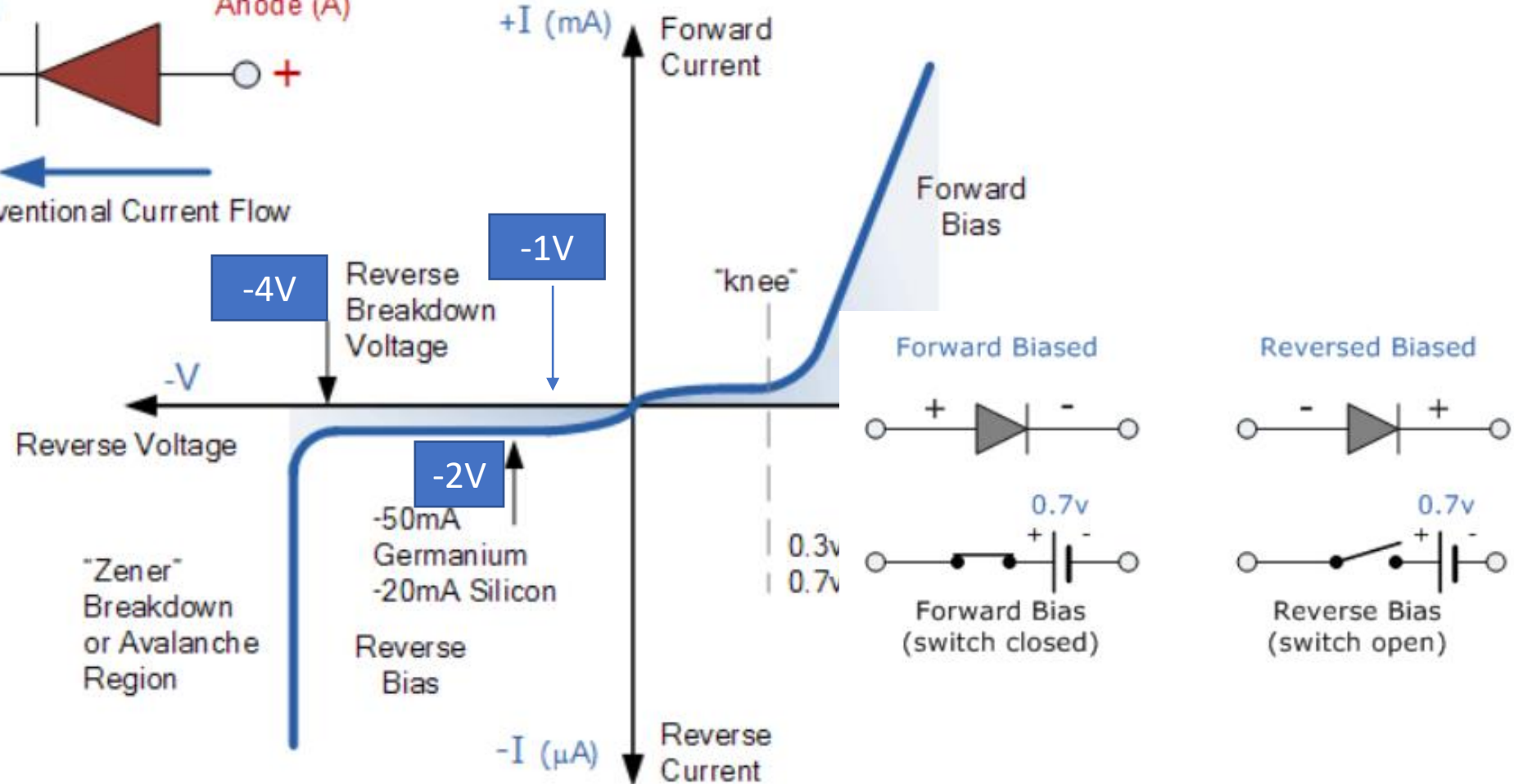
PN Junction Diode V-I Characteristics

$$E = -dV_r / dx$$

$$F = qE$$



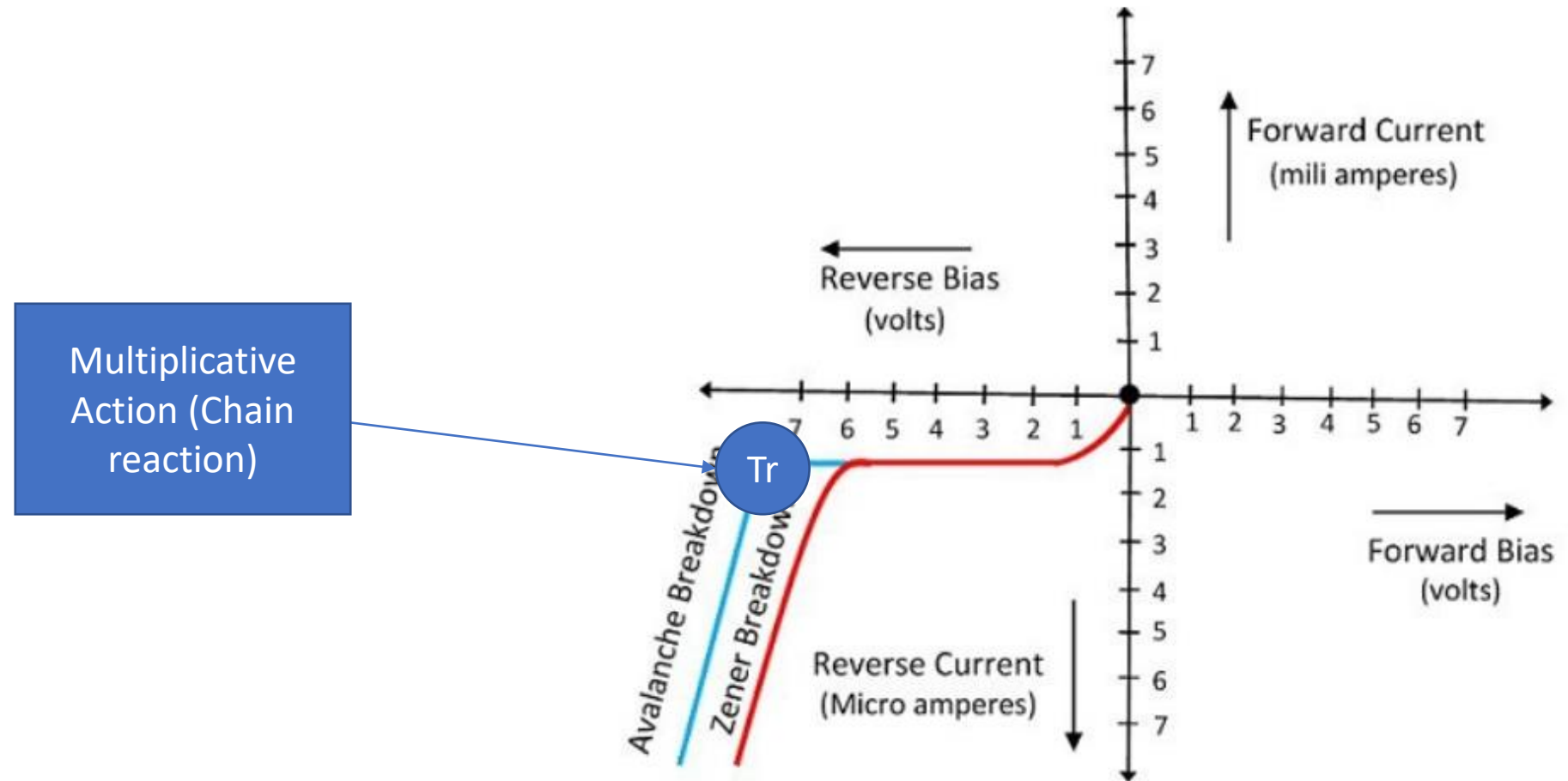
Higher Force = $1e$ and
 $1\text{Hole (KE)} = A = EHP \text{ (KE)}$
 $= A = EHP(KE) = \text{Sufficient}$
 Charges = Current



Breakdown

Breakdown Characteristic Graph

The graphical representation of the Avalanche and Zener breakdown is shown in the figure below.



Breakdown Characteristic

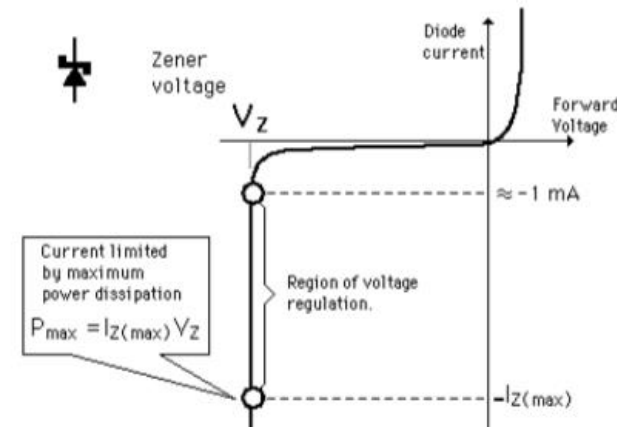
Circuit Globe

What is Breakdown?

- Deleterious effect that occurs in the presence of **high electric field**.
- Causes **high resistance** elements to allow flow of **high current**.

Avalanche/Zener Breakdown

- 'Zener diode' and 'avalanche diode' are terms often used interchangeably.
- Both refer to breakdown of a diode under reverse bias.



Avalanche/Zener Breakdown (con't)

- **Reverse bias** = Very little current flow
= Open circuit

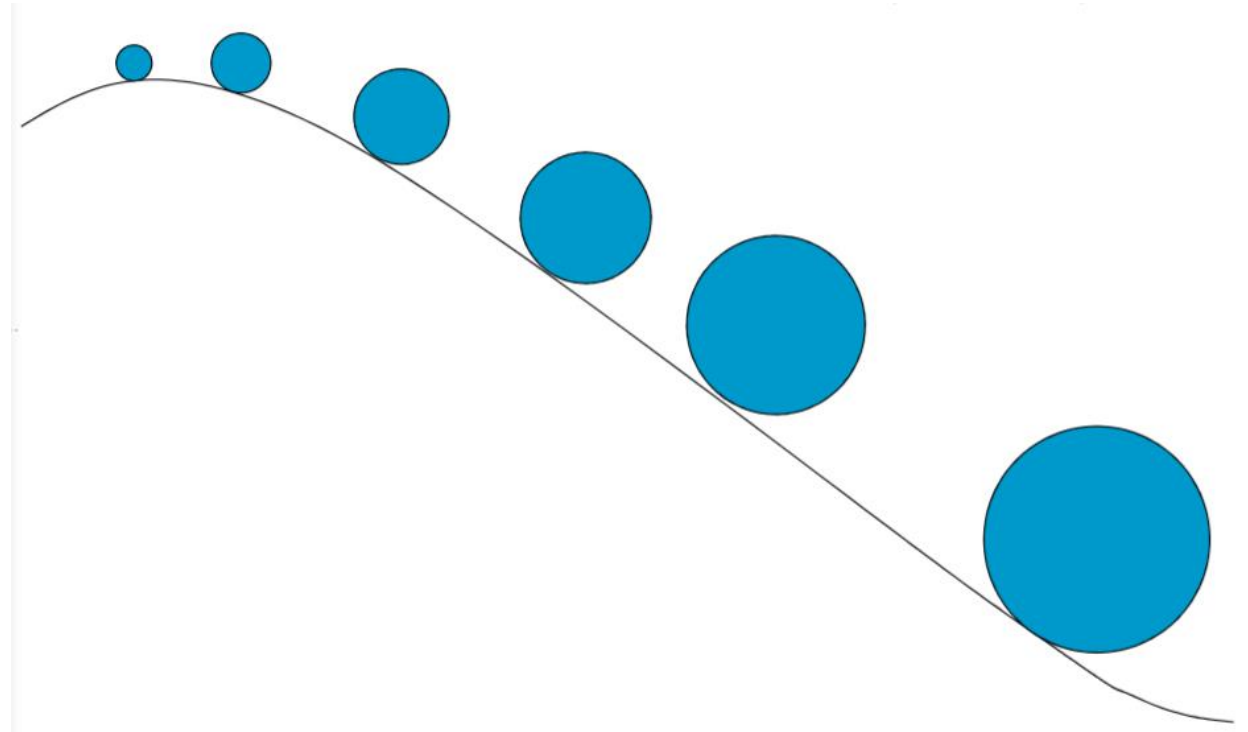
- As Reverse voltage ↑ a point is reached where current ↑
dramatically, therefore dynamic resistance ↓.

- ➡ Very few electrons make it through depletion region with high velocity
- ➡ These electrons collide with atoms in the depletion region and free more electrons (Process called Multiplication).
- ➡ Results in higher and higher current flow

Avalanche Breakdown (con't)



By analogy, the process is named because a single carrier can spawn literally thousands of additional carriers through collisions, just as a single snowball can cause an avalanche.

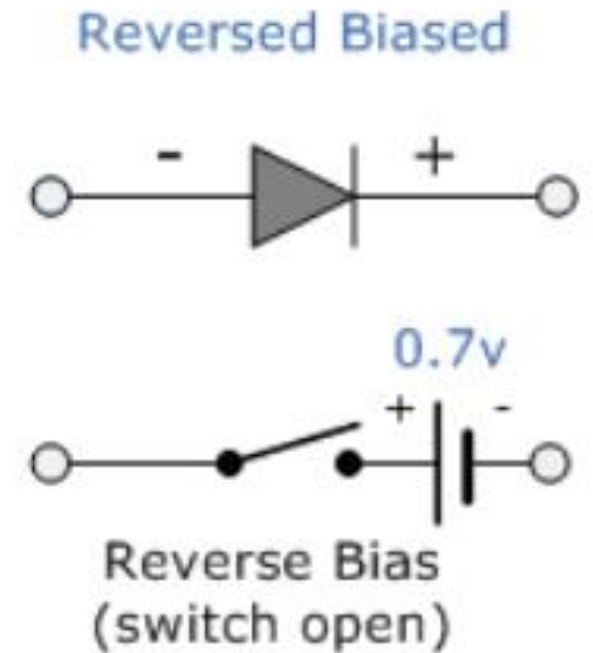
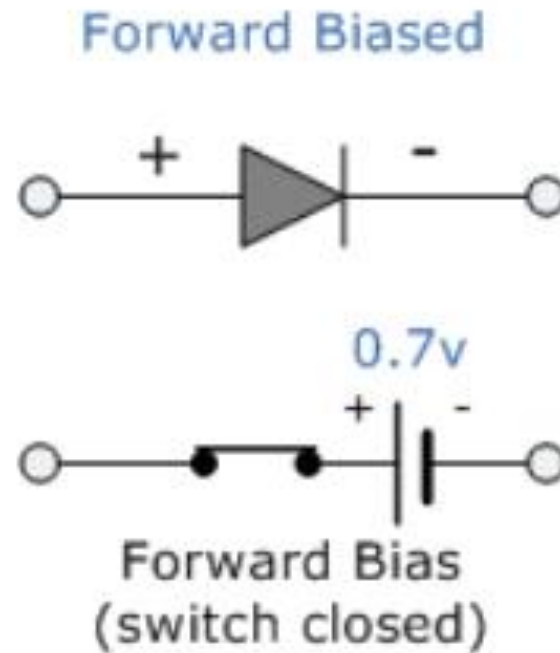


Zener Breakdown ($DR = 1:10^4$) $ND(1:10^8)$

- The **width of the depletion region** depends on the **doping** of the P and N-type semiconductor material.
- If the material is **heavily doped**, the **width** of the depletion region becomes **very thin**.
- The phenomenon of the **Zener breakdown** occurs in the **very thin depletion region**.
- The thin depletion region has more numbers of free electrons. The reverse bias applied across the PN junction develops the electric field intensity across the depletion region.
- The **strength of the electric field intensity becomes very high**.

P-N Junction Diodes application

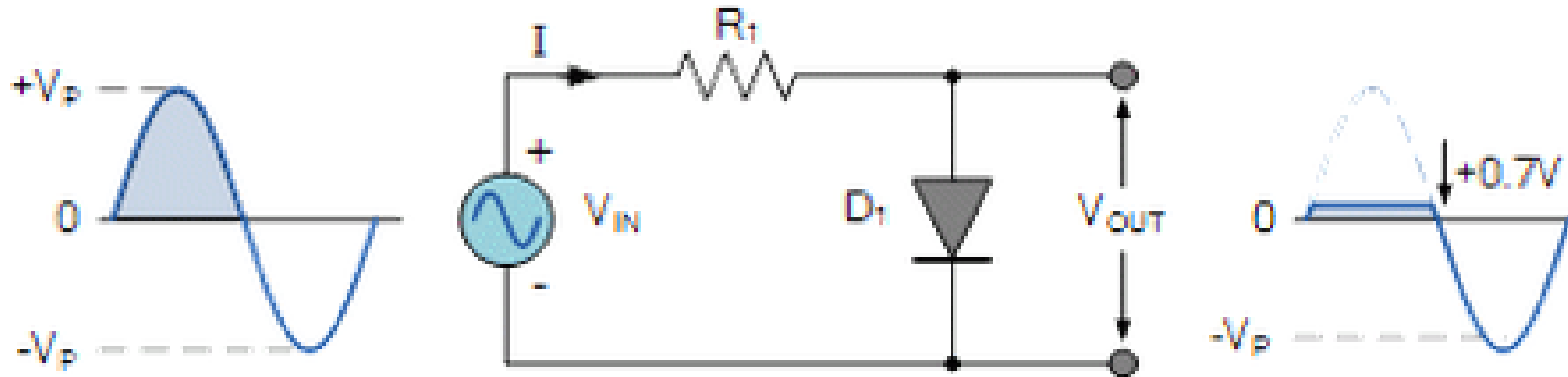
- Clipping and clamping circuits
- Rectifiers
- Filters
- Zener diode and regulators



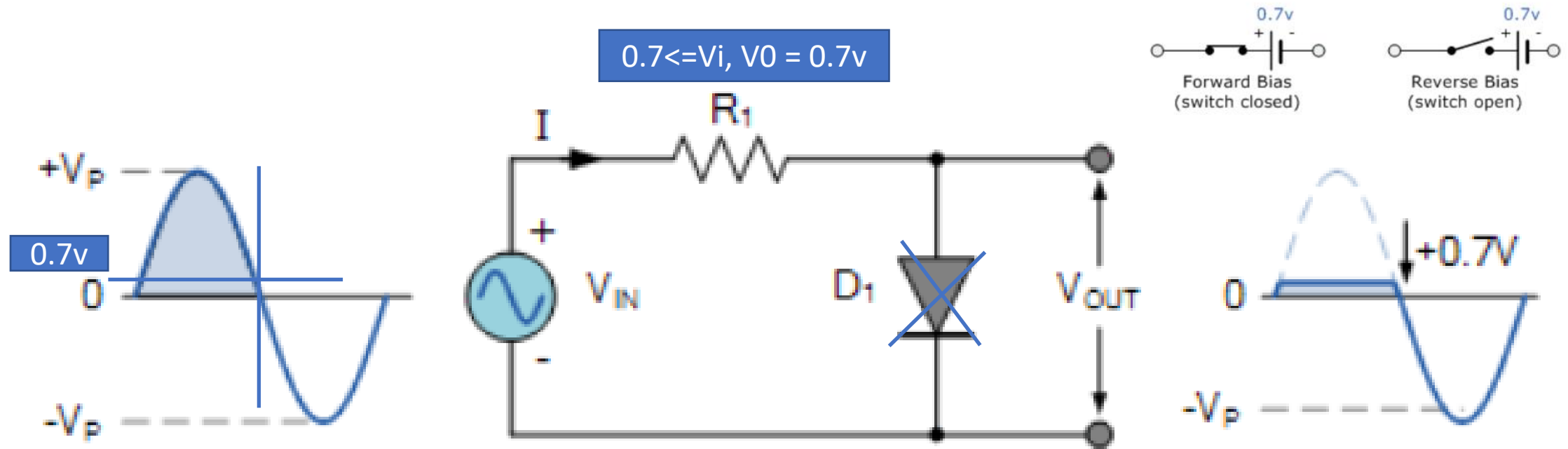
Clipping and clamping circuits (Clipper and Clamper)

Diode Clipping Circuits

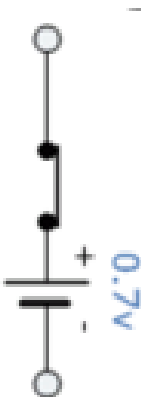
The **Diode Clipper**, also known as a *Diode Limiter*, is a **wave shaping circuit** that takes an input waveform and **clips or cuts off** its top half, bottom half or both halves together.



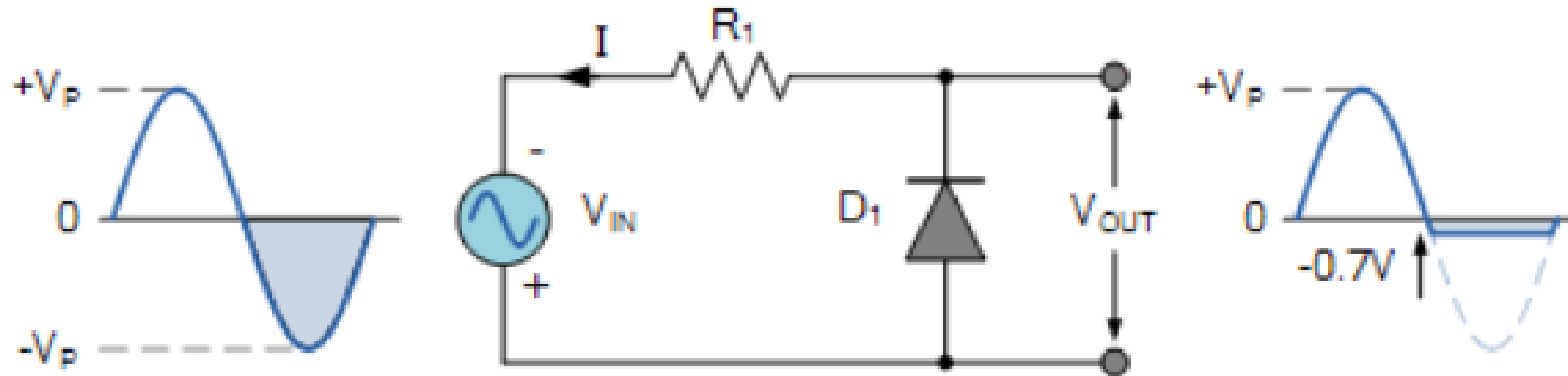
Positive Diode Clipping Circuits



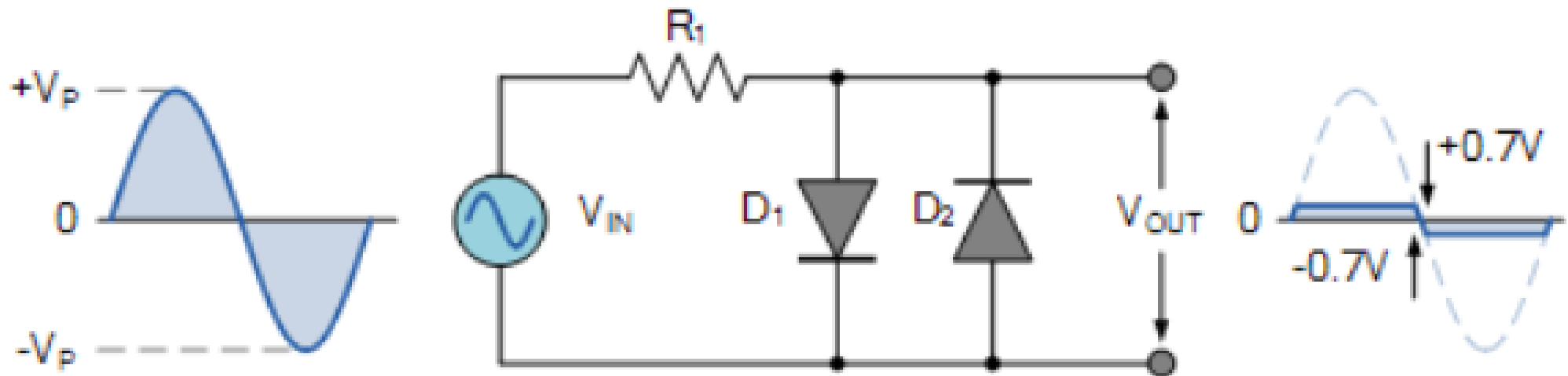
- In +ve cycle when IP voltage is greater than the 0.7V and 0.3V the diode begins to conduct and holds the voltage across it constant at 0.7V until the sinusoidal waveform falls below this value.
- Thus the output voltage which is taken across the diode **can never exceed 0.7 volts** during the **positive half cycle**.



Negative Diode Clipping Circuits



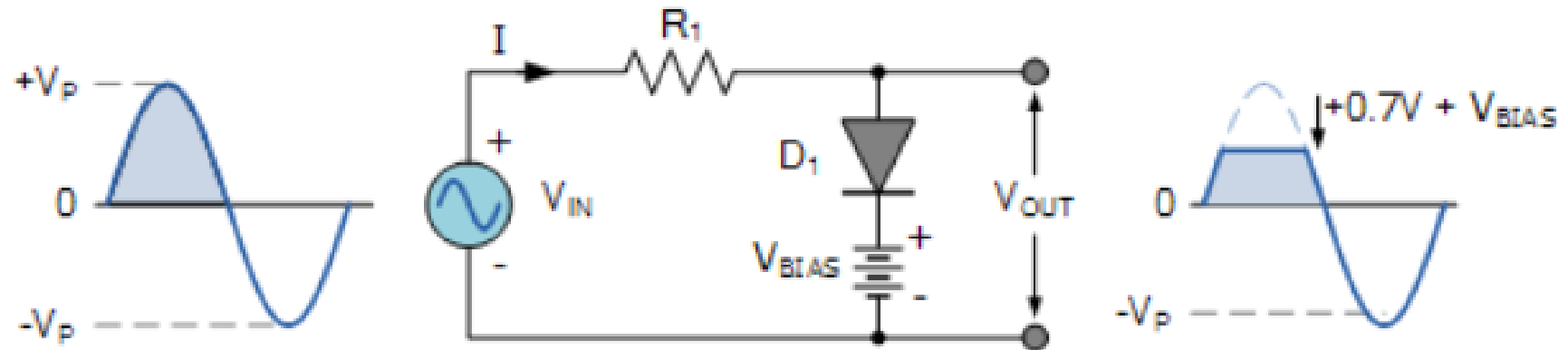
Clipping of Both Half Cycles



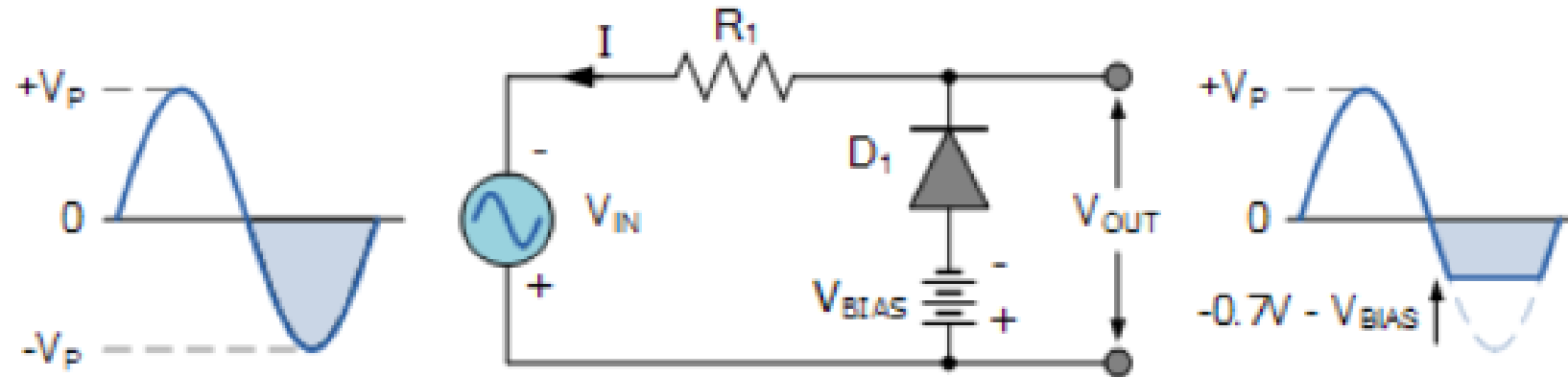
Biased Diode Clipping Circuits

To produce diode clipping circuits for **voltage waveforms at different levels**, a bias voltage, V_{BIAS} is added in series with the diode to produce a combination clipper as shown.

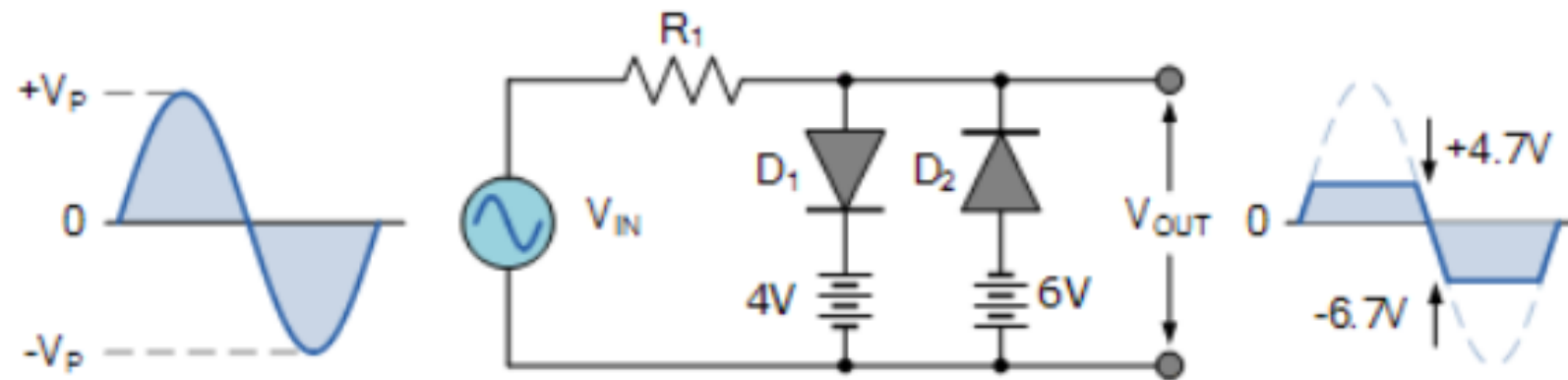
Positive Bias Diode Clipping



Negative Bias Diode Clipping

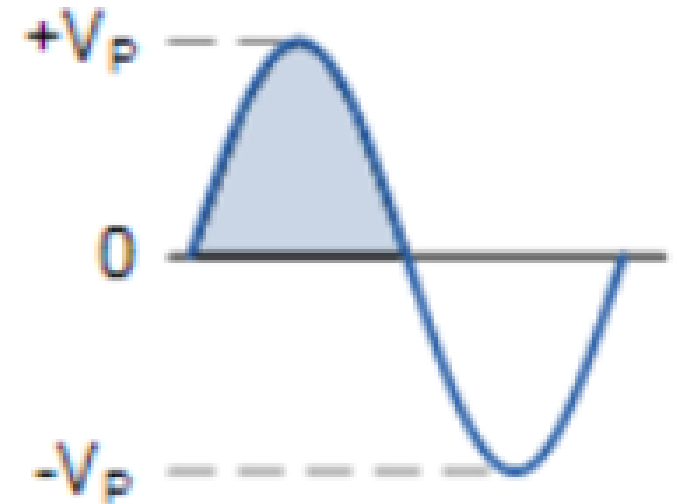


Diode Clipping of Different Bias levels



Clamper Circuits

- A Clamper Circuit is a circuit that **adds a DC level** to an **AC signal**.
- The positive and negative peaks of the signals can be placed at desired levels using the clamping circuits.
- As the DC level gets shifted, a clamper circuit is called as a **Level Shifter**.
- Clamper circuits consist of energy storage elements like **capacitors**. A simple clamper circuit comprises of a **capacitor, a diode, a resistor and a dc battery** if required.

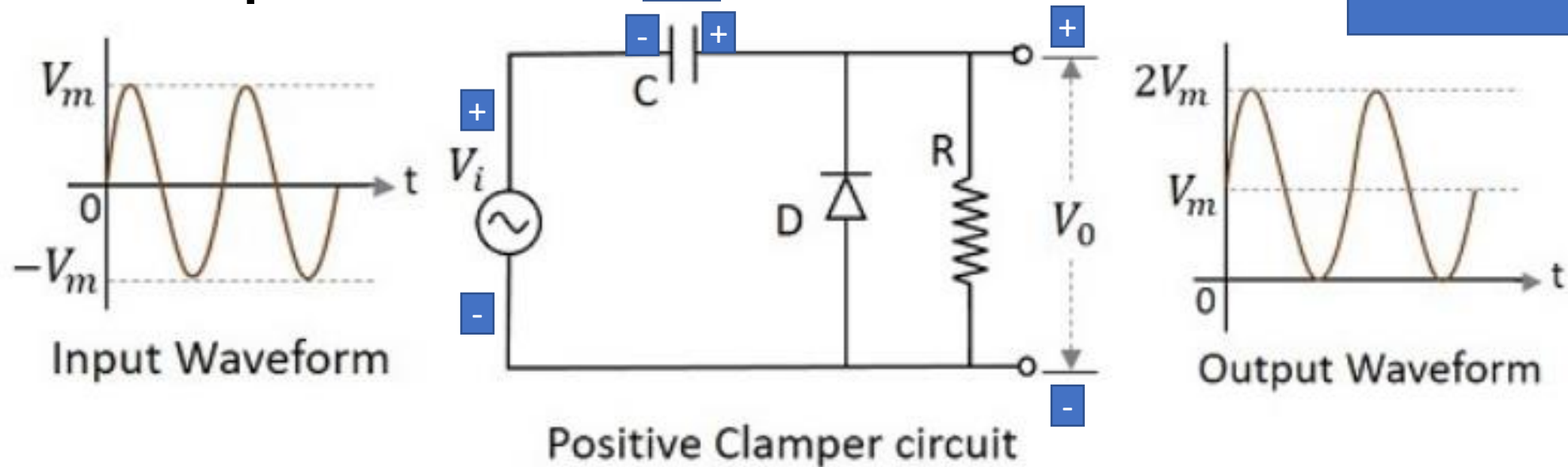


Types of Clampers

There are few types of clamper circuits, such as

- ▣ Positive Clamper
- ▣ Positive clamper with positive V_r
- ▣ Positive clamper with negative V_r
- ▣ Negative Clamper
- ▣ Negative clamper with positive V_r
- ▣ Negative clamper with negative V_r

Positive Clamper Circuit



$$+ - - + +$$

$$V_o = V_i + V_m$$

In order to maintain the time period of the wave form, the τ must be greater than, half the time period
Discharging time of the capacitor should be slow.

$$\tau = Rc$$

Where

- R is the resistance of the resistor employed
- C is the capacitance of the capacitor used

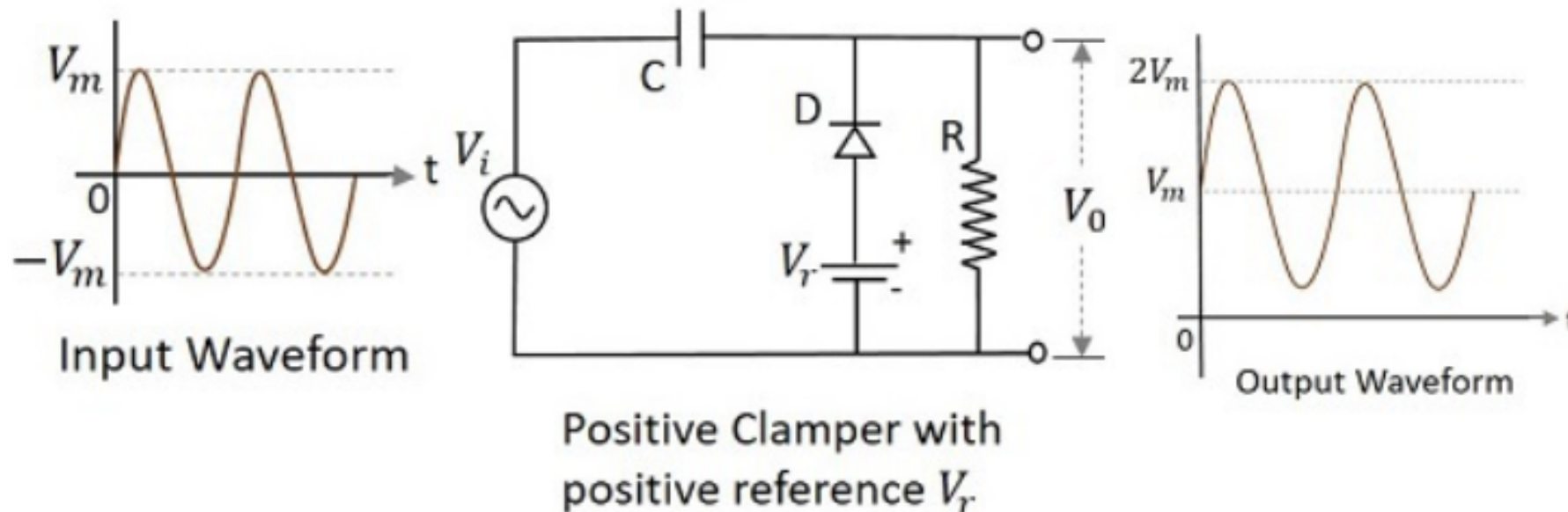
$$V_o = V_i + V_m$$

$$\begin{aligned} V_i &= 0 \\ V_o &= V_m, \\ V_i &= V_m \\ V_o &= 2V_m \\ V_i &= -V_m \\ V_o &= 0 \end{aligned}$$

Biased Clamper

Positive Clamper with Positive V_r

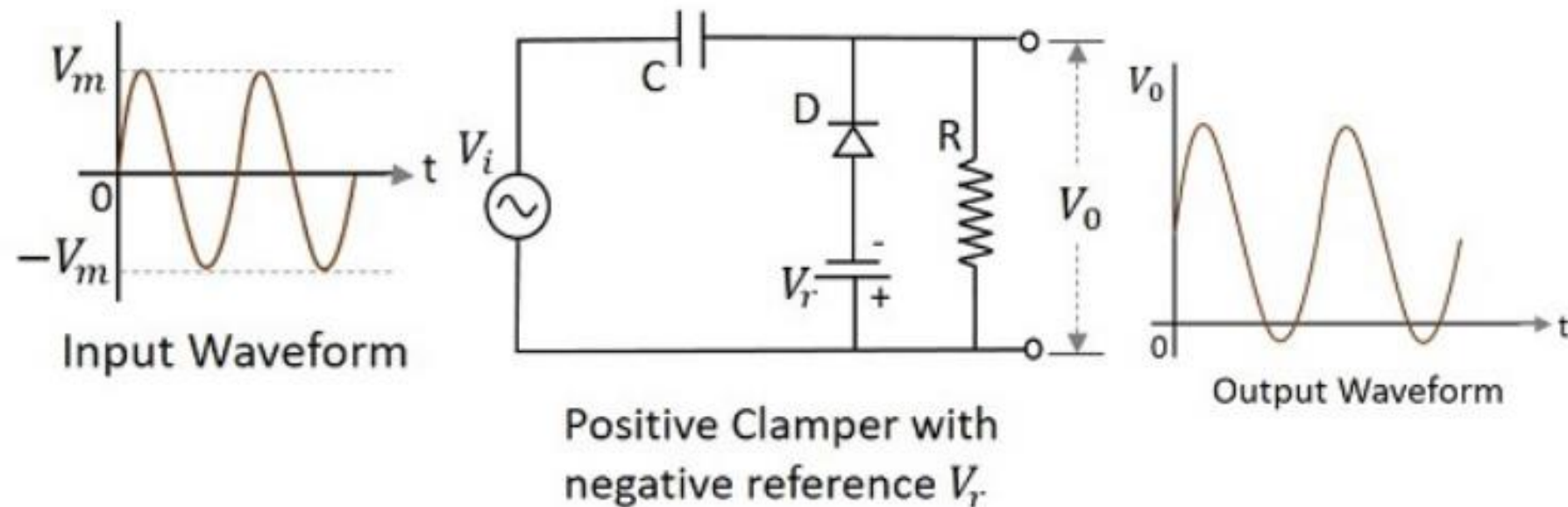
A Positive clamper circuit if biased with some positive reference voltage, that voltage will be added to the output to raise the clamped level. Using this, the circuit of the positive clamper with positive reference voltage is constructed as below.



$$\text{FB Voltage for diode} = -V_m - V_r$$

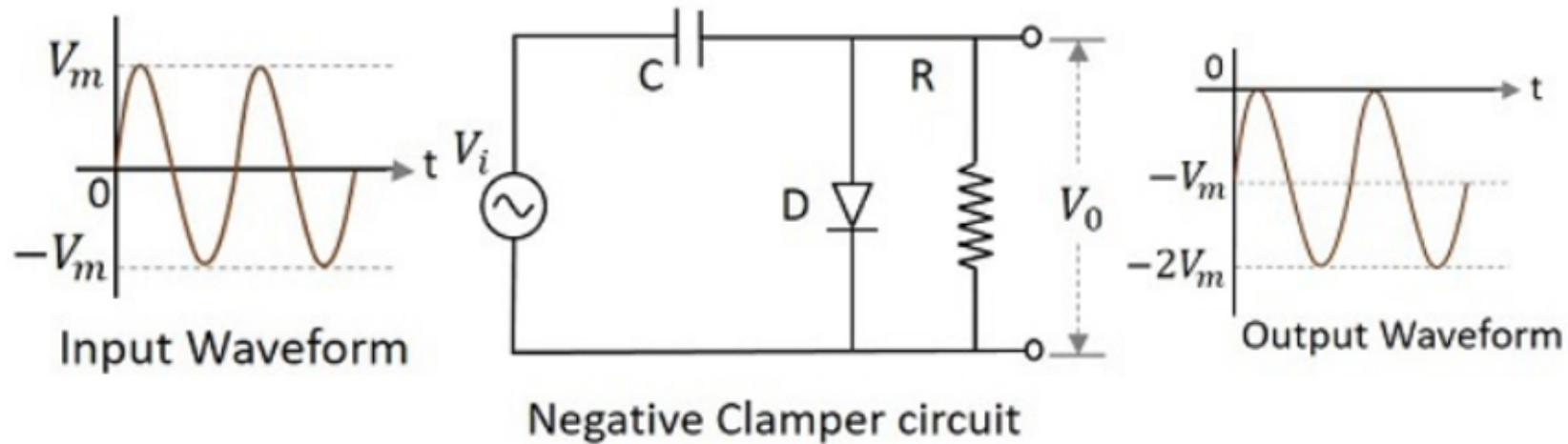
Positive Clamper with Negative V_r

A Positive clamper circuit if biased with some negative reference voltage, that voltage will be added to the output to raise the clamped level. Using this, the circuit of the positive clamper with positive reference voltage is constructed as below.



Negative Clamper

A Negative Clamper circuit is one that consists of a diode, a resistor and a capacitor and that shifts the output signal to the negative portion of the input signal. The figure below explains the construction of a negative clamper circuit.

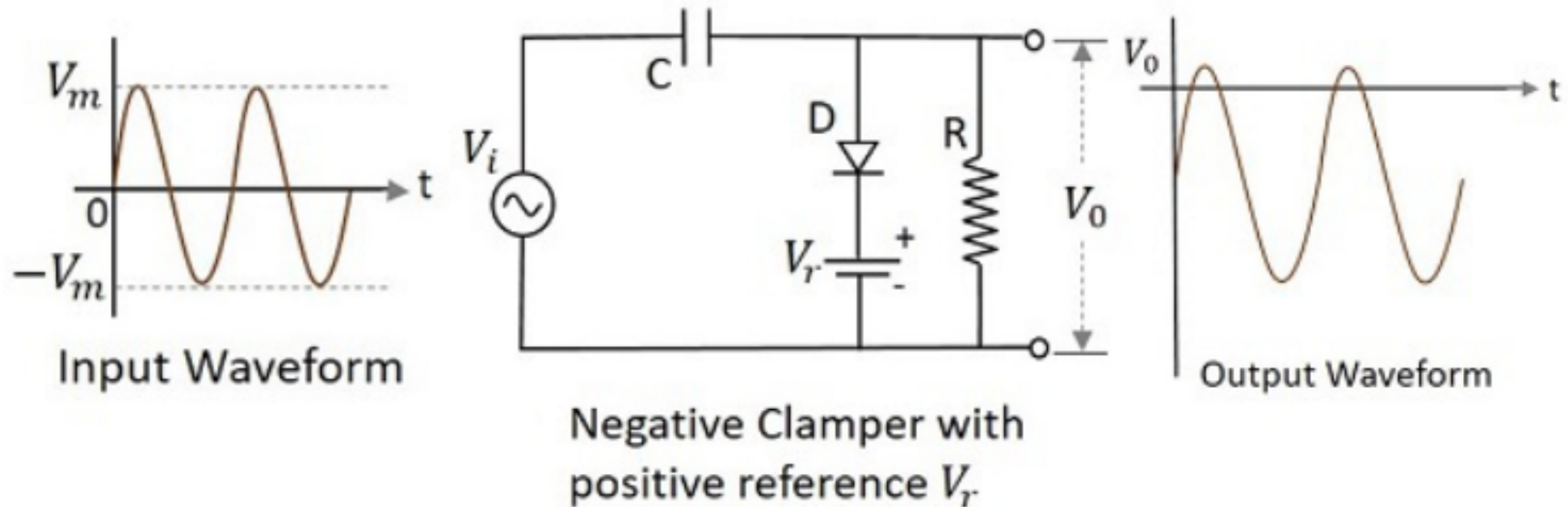


During the positive half cycle, the capacitor gets charged to its peak value v_m . The diode is forward biased and conducts. During the negative half cycle, the diode gets reverse biased and gets open circuited. The output of the circuit at this moment will be

$$V_o = V_i - V_m$$

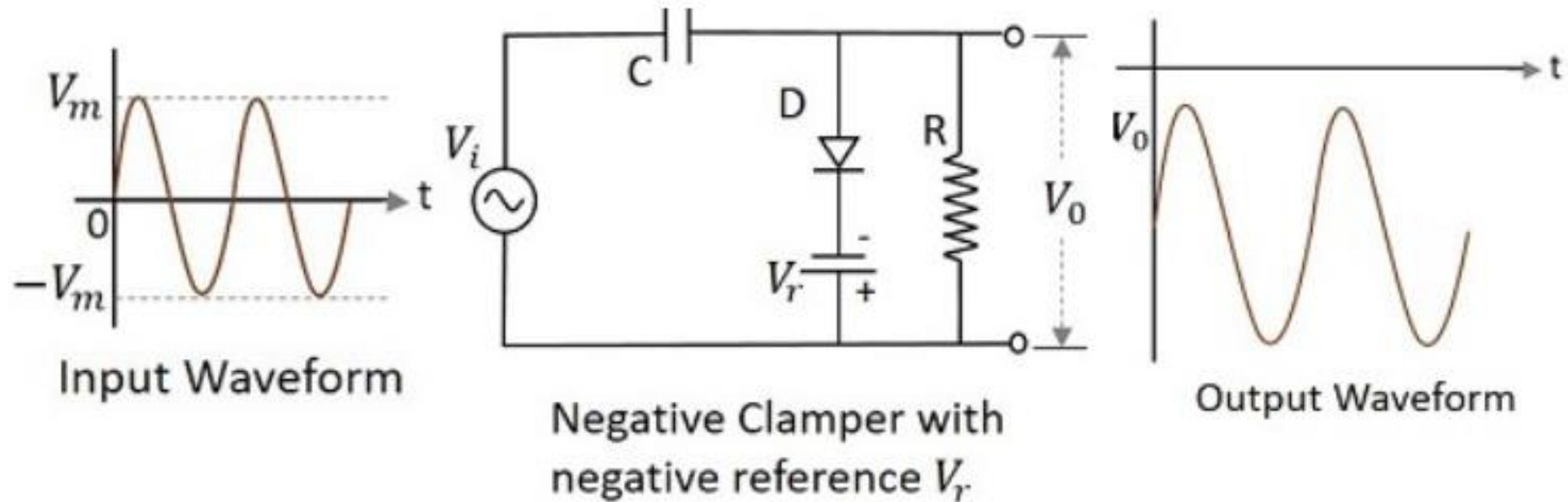
Negative clamper with positive V_r

A Negative clamper circuit if biased with some positive reference voltage, that voltage will be added to the output to raise the clamped level. Using this, the circuit of the negative clamper with positive reference voltage is constructed as below.



Negative Clamper with Negative V_r

A Negative clamper circuit if biased with some negative reference voltage, that voltage will be added to the output to raise the clamped level. Using this, the circuit of the negative clamper with negative reference voltage is constructed as below.



Applications

There are many applications for both Clippers and Clampers such as

Clippers

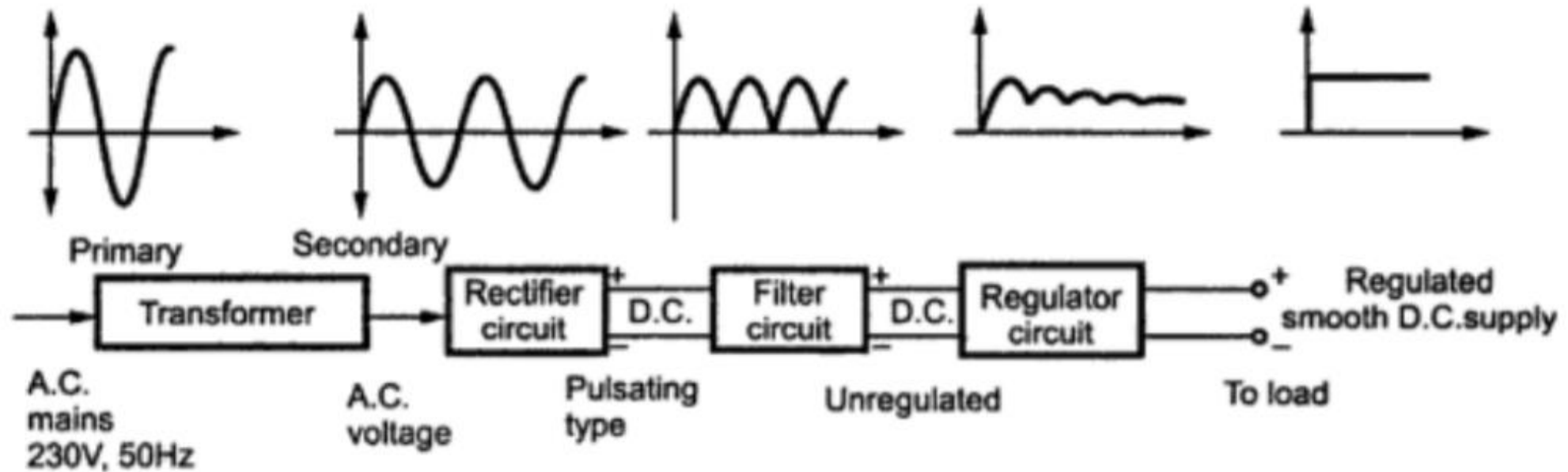
- ▣ Used for the generation and shaping of waveforms
- ▣ Used for the protection of circuits from spikes
- ▣ Used for amplitude restorers
- ▣ Used as voltage limiters
- ▣ Used in television circuits
- ▣ Used in FM transmitters

Clampers

- ▣ Used as direct current restorers
- ▣ Used to remove distortions
- ▣ Used as voltage multipliers
- ▣ Used for the protection of amplifiers
- ▣ Used as test equipment
- ▣ Used as base-line stabilizer

Rectifiers and filters

A rectifier is a device which converts a.c. voltage to pulsating d.c. voltage, using one or more p-n junction diode.



Block Diagram of a typical DC Power Supply

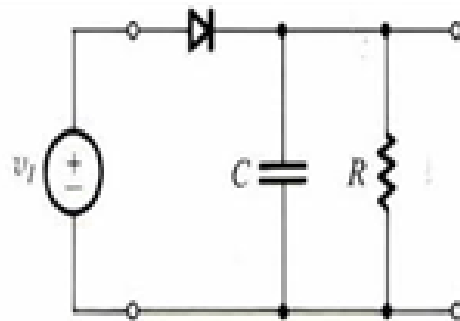
Characteristic of Rectifier

- a) **Waveform of the load current** : As rectifier converts a.c. to pulsating d.c., it is important to analyze the nature of the current through load which ultimately determines the waveform of the load voltage.
- b) **Regulation of the output voltage** : As the load current changes, load voltage changes. Practically load voltage should remain constant. So concept of regulation is to study the effect of change in load current on the load voltage.
- c) **Rectifier efficiency** : It signifies, how efficiently the rectifier circuit converts a.c. power into d.c. power.
- d) **Peak value of current in the rectifier circuit** : The peak value is the maximum value of an alternating current in the rectifier circuit. This decides the rating of the rectifier circuit element which is diode.
- e) **Peak value of voltage across the rectifier element in the reverse direction (PIV)** : When the diode is not conducting, the reverse voltage gets applied across the diode. The peak value of such voltage decides the peak inverse voltage i.e. PIV rating of a diode.
- f) **Ripple factor** : The output of the rectifier is of pulsating d.c. type. The amount of a.c. content in the output can be mathematically expressed by a factor called ripple factor.

Types of Rectifier

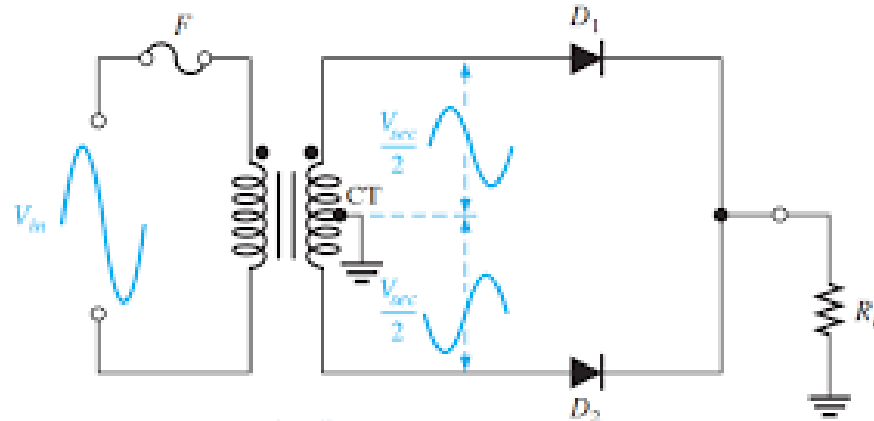
Rectifier

Half wave
rectifier

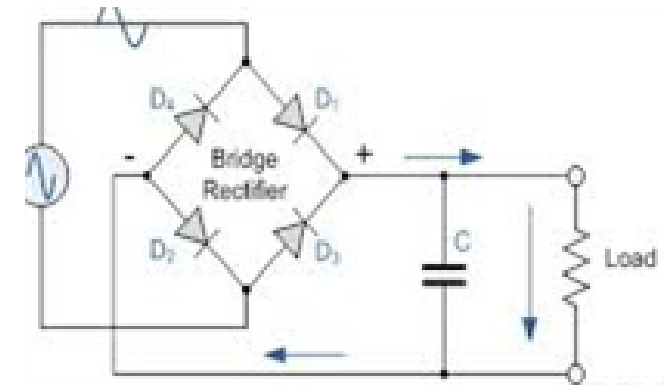


Full wave
rectifier

Center Tapped Full
Wave Rectifier

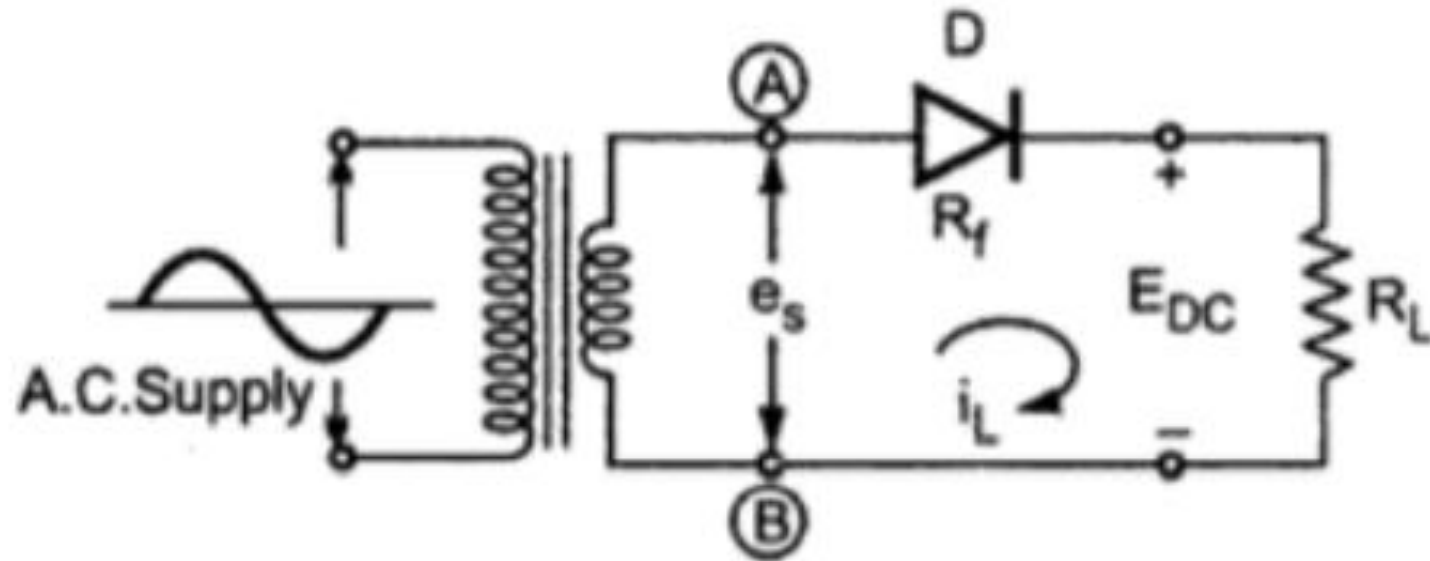


Bridge
Rectifier

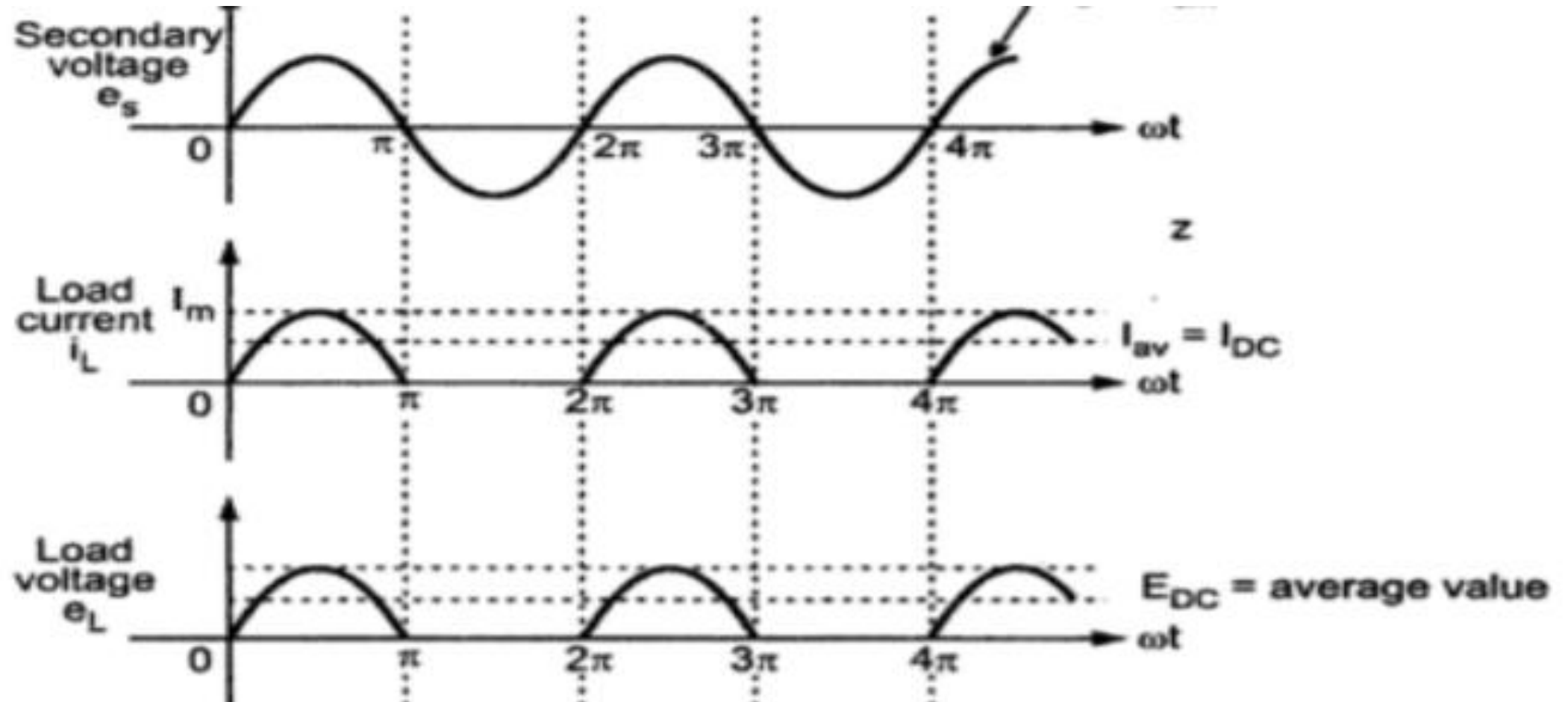


Half Wave Rectifier:

- A Type of rectifier that converts only the **half cycle** of the alternating current (AC) into direct current (DC) is known as halfwave rectifier



Operation of the ckt



Cont.

The average or dc value of alternating current is obtained by integration.

For finding out the average value of an alternating waveform, we have to determine the area under the curve over one complete cycle i.e. from 0 to 2π and then dividing it by the base i.e. 2π

Mathematically, current waveform can be described as,

$$i_L = I_m \sin \omega t \quad \text{for } 0 \leq \omega t \leq \pi$$

$$i_L = 0 \quad \text{for } \pi \leq \omega t \leq 2\pi$$

$$I_m = \text{peak value of load current}$$

Average DC Load Current (I_{DC})

where

\therefore

$$I_{DC} = \frac{1}{2\pi} \int_0^{2\pi} i_L d(\omega t) = \frac{1}{2\pi} \int_0^{2\pi} I_m \sin(\omega t) d(\omega t)$$

As no current flows during negative half cycle of ac input voltage, i.e. between $\omega t = \pi$ to $\omega t = 2\pi$, we change the limits of integration.

\therefore

$$\begin{aligned} I_{DC} &= \frac{1}{2\pi} \int_0^{\pi} I_m \sin(\omega t) d(\omega t) \\ &= \frac{I_m}{2\pi} [-\cos(\omega t)]_0^{\pi} = -\frac{I_m}{2\pi} [\cos(\pi) - \cos(0)] \\ &= -\frac{I_m}{2\pi} [-1 - 1] = \frac{I_m}{\pi} \end{aligned}$$

\therefore

$$I_{DC} = \frac{I_m}{\pi} = \text{average value}$$

Cont.

Average DC Load Voltage (E_{DC})

It is the product of average D.C. load current and the load resistance R_L .

$$E_{DC} = I_{DC} R_L$$

Substituting value of I_{DC} ,

$$E_{DC} = \frac{I_m}{\pi} R_L = \frac{E_{sm}}{(R_f + R_L + R_s) \pi} R_L$$
$$I_m = \frac{E_{sm}}{R_f + R_L + R_s}$$

The winding resistance R_s and forward diode resistance R_f are practically very small compared to R_L .

$$\therefore E_{DC} = \frac{E_{sm}}{\pi \left[\frac{R_f + R_s}{R_L} + 1 \right]}$$

But as R_f and R_s are small compared to R_L , $(R_f + R_s)/R_L$ is negligibly small compared to 1. So neglecting it we get,

$$\therefore E_{DC} \approx \frac{E_{sm}}{\pi}$$

Cont.

R.M.S. Value of Load Current (I_{RMS})

The R.M.S means squaring, finding mean and then finding square root. Hence R.M.S. value of load current can be obtained as,

$$\begin{aligned} I_{RMS} &= \sqrt{\frac{1}{2\pi} \int_0^{\pi} (I_m \sin \omega t)^2 d(\omega t)} \\ &= \sqrt{\frac{1}{2\pi} \int_0^{\pi} (I_m^2 \sin^2 \omega t d(\omega t))} \\ &= I_m \sqrt{\frac{1}{2\pi} \int_0^{\pi} \frac{[1 - \cos(2\omega t)] d(\omega t)}{2}} \\ &= I_m \sqrt{\frac{1}{2\pi} \left\{ \frac{\omega t}{2} - \frac{\sin(2\omega t)}{4} \right\}_0^{\pi}} \\ &= I_m \sqrt{\frac{1}{2\pi} \left(\frac{\pi}{2} \right)} \quad \text{as } \sin(2\pi) = \sin(0) = 0 \\ &= \frac{I_m}{2} \\ \therefore I_{RMS} &= \frac{I_m}{2} \end{aligned}$$

Cont.

D.C. Power Output (P_{DC})

The d.c. power output can be obtained as,

$$P_{DC} = E_{DC} I_{DC} = I_{DC}^2 R_L$$

$$\text{D.C. Power output} = I_{DC}^2 R_L = \left[\frac{I_m}{\pi} \right]^2 R_L = \frac{I_m^2}{\pi^2} R_L$$

$$\therefore P_{DC} = \frac{I_m^2}{\pi^2} R_L$$

$$\text{where } I_m = \frac{E_{sm}}{R_f + R_L + R_s}$$

$$\therefore P_{DC} = \frac{E_{sm}^2 R_L}{\pi^2 [R_f + R_L + R_s]^2}$$

Cont.

i A.C. Power Input (P_{AC})

The power input taken from the secondary of transformer is the power supplied to three resistances namely load resistance R_L , the diode resistance R_f and winding resistance R_s . The a.c. power is given by,

$$P_{AC} = I_{RMS}^2 [R_L + R_f + R_s]$$

but

$$I_{RMS} = \frac{I_m}{2} \quad \text{for half wave,}$$

\therefore

$$P_{AC} = \frac{I_m^2}{4} [R_L + R_f + R_s]$$

Cont.

Rectifier Efficiency (η)

The rectifier efficiency is defined as the ratio of output d.c. power to input a.c. power.

$$\therefore \eta = \frac{\text{D.C. output power}}{\text{A.C. input power}} = \frac{P_{\text{DC}}}{P_{\text{AC}}}$$

$$\therefore \eta = \frac{\frac{I_m^2}{\pi^2} R_L}{\frac{I_m^2}{4} [R_f + R_L + R_s]} = \frac{(4 / \pi^2) R_L}{(R_f + R_L + R_s)}$$

$$\therefore \eta = \frac{0.406}{1 + \left(\frac{R_f + R_s}{R_L} \right)}$$

If $(R_f + R_s) \ll R_L$ as mentioned earlier, we get the maximum theoretical efficiency of half wave rectifier as,

$$\% \eta_{\text{max}} = 0.406 \times 100 = 40.6 \%$$

Cont.

Ripple Factor (γ)

$$\text{Ripple factor } \gamma = \frac{\text{R.M.S. value of a.c. component}}{\text{Average or d.c. component}}$$

Now the output current is composed of a.c. component as well as d.c. component.

Let I_{ac} = r.m.s. value of a. c. component present in output

I_{DC} = d.c. component present in output

I_{RMS} = R.M.S. value of total output current

$$\therefore I_{RMS} = \sqrt{I_{ac}^2 + I_{DC}^2}$$

$$\therefore I_{ac} = \sqrt{I_{RMS}^2 - I_{DC}^2}$$

$$\text{Now Ripple factor} = \frac{I_{ac}}{I_{DC}} \quad \text{as per definition}$$

$$\therefore \gamma = \frac{\sqrt{I_{RMS}^2 - I_{DC}^2}}{I_{DC}}$$

$$\therefore \gamma = \sqrt{\left(\frac{I_{RMS}}{I_{DC}}\right)^2 - 1}$$

This is the general expression for ripple factor and can be used for any rectifier circuit.

Cont.

Now for a half wave circuit,

$$I_{RMS} = \frac{I_m}{2} \quad \text{while} \quad I_{DC} = \frac{I_m}{\pi}$$

$$\therefore \gamma = \sqrt{\left[\frac{\left(\frac{I_m}{2} \right)}{\left(\frac{I_m}{\pi} \right)} \right]^2 - 1} = \sqrt{\frac{\pi^2}{4} - 1} = \sqrt{1.4674}$$

$$\therefore \gamma = 1.211$$

This indicates that the ripple contents in the output are 1.211 times the d.c. component i.e. 121.1 % of d.c. component. The ripple factor for half wave is very high which indicates that the half wave circuit is a poor converter of a.c. to d.c. The ripple factor is minimised using filter circuits along with rectifiers.

Cont.

Peak Inverse Voltage (PIV)

The Peak Inverse Voltage is the peak voltage across the diode in the reverse direction i.e. when the diode is reverse biased. In half wave rectifier, the load current is ideally zero when the diode is reverse biased and hence the maximum value of the voltage that can exist across the diode is nothing but E_{sm} .

$$\begin{aligned}\therefore \text{PIV of diode} &= E_{sm} = \text{Maximum value of secondary voltage} \\ &= \pi E_{DC} \big|_{I_{DC}=0}\end{aligned}$$

This is called PIV rating of a diode. So diode must be selected based on this PIV rating and the circuit specifications.

Cont.

Transformer Utilization Factor (T.U.F.)

The factor which indicates how much is the utilization of the transformer in the circuit is called Transformer Utilization Factor (T.U.F.)

The T.U.F. is defined as the ratio of d.c. power delivered to the load to the a.c power rating of the transformer. While calculating the a.c. power rating, it is necessary to consider r.m.s. value of a.c. voltage and current.

The T.U.F. for half wave rectifier can be obtained as,

$$\begin{aligned}\text{A.C. power rating of transformer} &= E_{\text{RMS}} I_{\text{RMS}} \\ &= \frac{E_{\text{sm}}}{\sqrt{2}} \cdot \frac{I_m}{2} = \frac{E_{\text{sm}} I_m}{2\sqrt{2}}\end{aligned}$$

Remember that the secondary voltage is purely sinusoidal hence its r.m.s. value is $1/\sqrt{2}$ times maximum while the current is half sinusoidal hence its r.m.s. value is $1/2$ of the maximum, as derived earlier.

$$\text{D.C. power delivered to the load} = I_{\text{DC}}^2 R_L$$

Cont.

$$\begin{aligned} &= \left(\frac{I_m}{\pi} \right)^2 R_L \\ \therefore \text{T.U.F.} &= \frac{\text{D.C. Power delivered to the load}}{\text{A.C. Power rating of the transformer}} \\ &= \frac{\left(\frac{I_m}{\pi} \right)^2 R_L}{\left(\frac{E_{sm} I_m}{2\sqrt{2}} \right)} \end{aligned}$$

Neglecting the drop across R_f and R_s we can write,

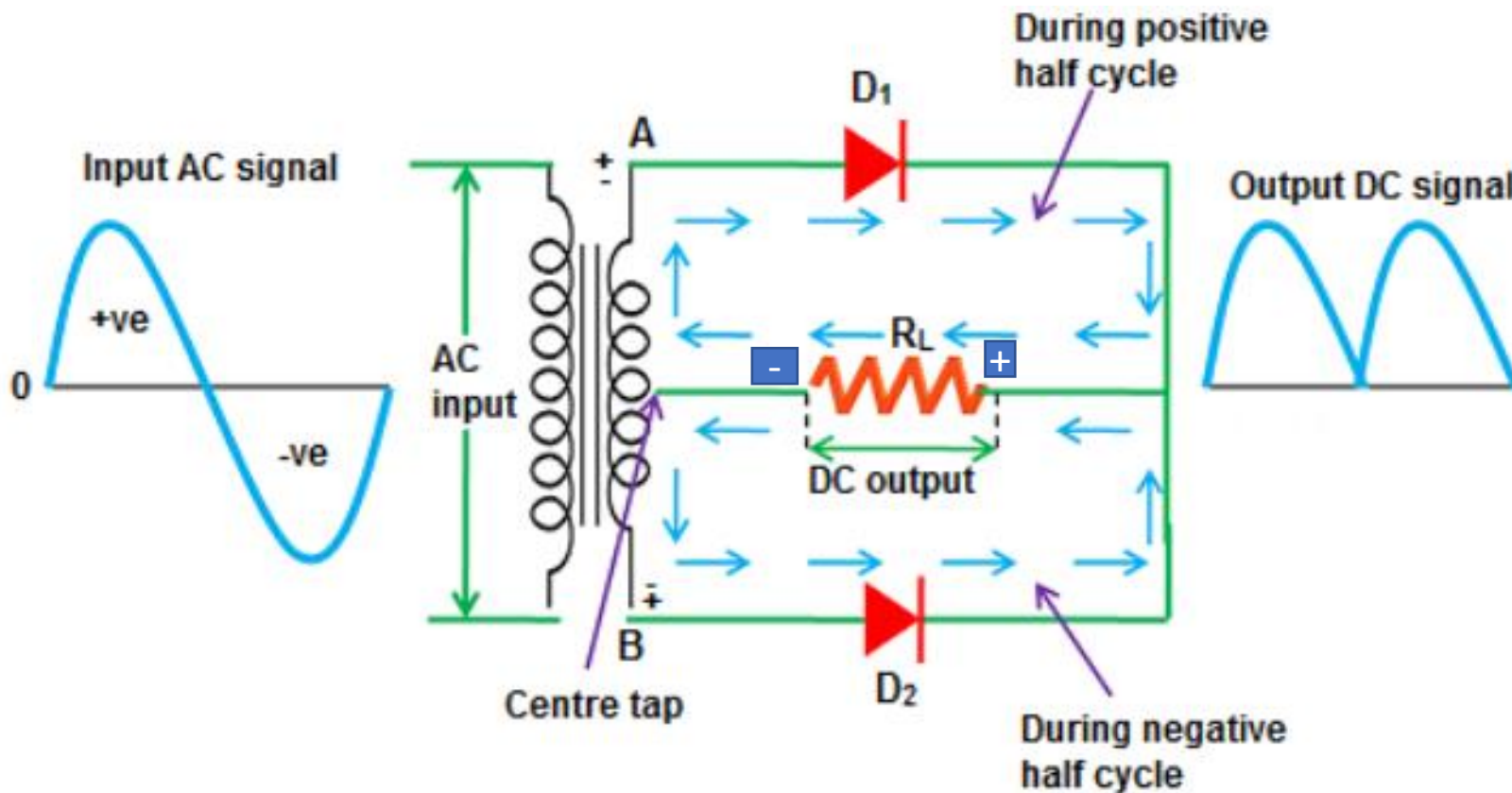
$$\begin{aligned} E_{sm} &= I_m R_L \\ \therefore \text{T.U.F.} &= \frac{I_m^2}{\pi^2} \cdot \frac{R_L \cdot 2\sqrt{2}}{I_m^2 R_L} \\ &= \frac{2\sqrt{2}}{\pi^2} \\ &= 0.287 \end{aligned}$$

The value of T.U.F. is low which shows that in half wave circuit, the transformer is not fully utilized.

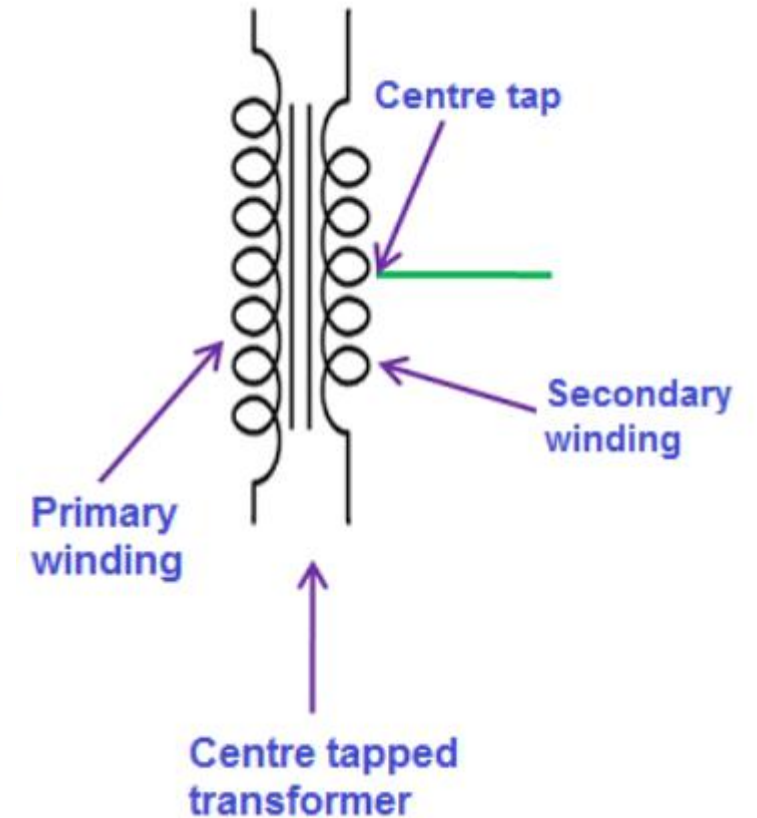
Full wave rectifier definition

A full wave rectifier is a type of rectifier which converts both half cycles of the AC signal into pulsating DC signal.

Centre tapped FWR

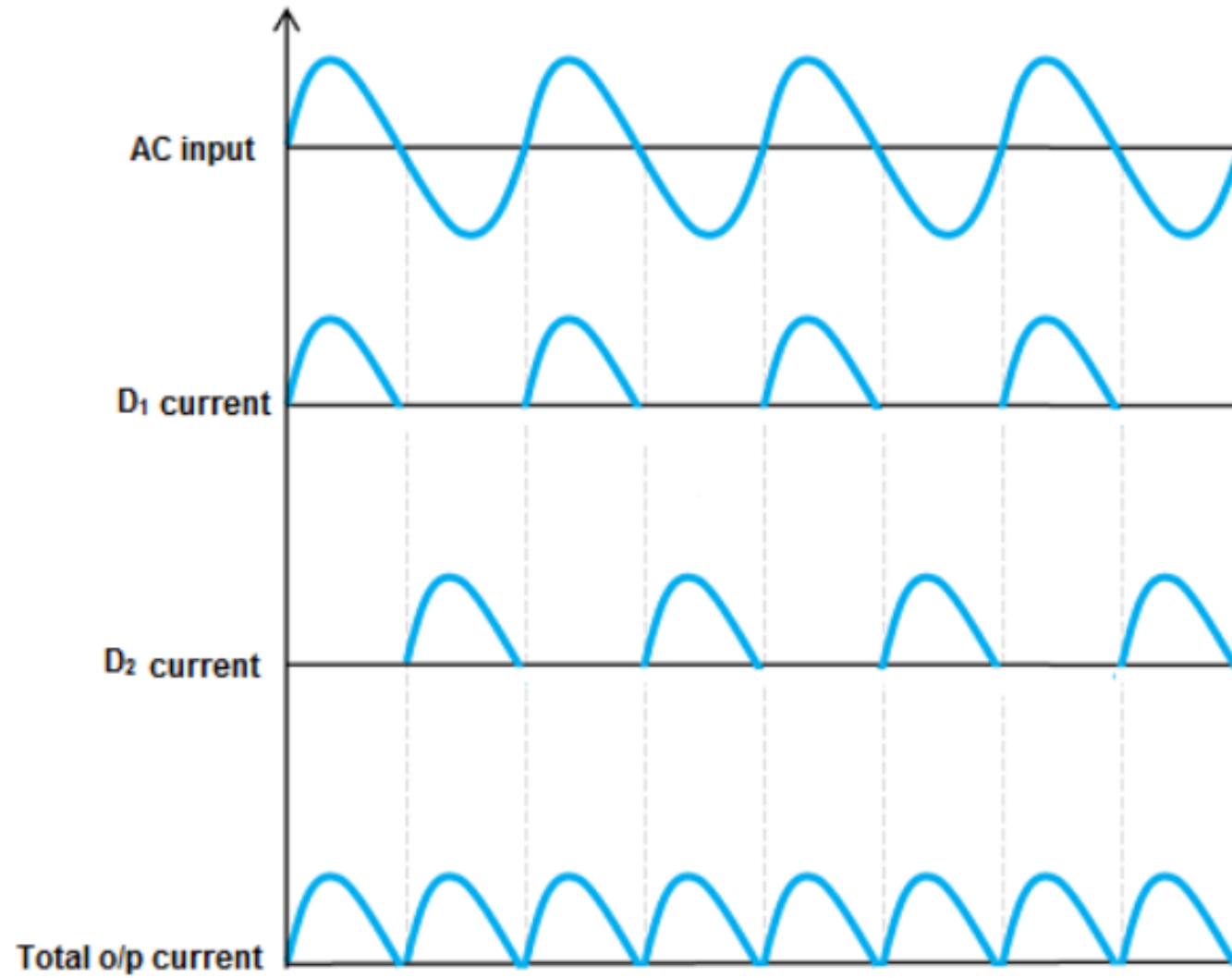


Centre tapped transformer



Cont.

Output waveforms of full wave rectifier



Cont.

Characteristics of full wave rectifier

Root mean square (RMS) value of load current I_{RMS}

The root mean square (RMS) value of load current in a full wave rectifier is

$$I_{RMS} = \frac{I_m}{\sqrt{2}}$$

Root mean square (RMS) value of the output load voltage V_{RMS}

The root mean square (RMS) value of output load voltage in a full wave rectifier is

$$V_{RMS} = I_{RMS} R_L = \frac{I_m}{\sqrt{2}} R_L$$

Cont.

DC output current

At the output load resistor R_L , both the diode D_1 and diode D_2 currents flow in the same direction. So the output current is the sum of D_1 and D_2 currents.

The current produced by D_1 is I_{\max} / π and the current produced by D_2 is I_{\max} / π .

So the output current $I_{DC} = 2I_{\max} / \pi$

Where,

I_{\max} = maximum DC load current

DC output voltage

The DC output voltage appeared at the load resistor R_L is given as

$$V_{DC} = 2V_{\max} / \pi$$

Where,

V_{\max} = maximum secondary voltage

Cont.

Rectifier efficiency

Rectifier efficiency indicates how efficiently the rectifier converts AC into DC. A high percentage of rectifier efficiency indicates a good rectifier while a low percentage of rectifier efficiency indicates an inefficient rectifier.

Rectifier efficiency is defined as the ratio of DC output power to the AC input power.

It can be mathematically written as

$$\eta = \text{output } P_{DC} / \text{input } P_{AC}$$

The rectifier efficiency of a full wave rectifier is 81.2%.

The rectifier efficiency of a full wave rectifier is twice that of the half wave rectifier. So the full wave rectifier is more efficient than a half wave rectifier

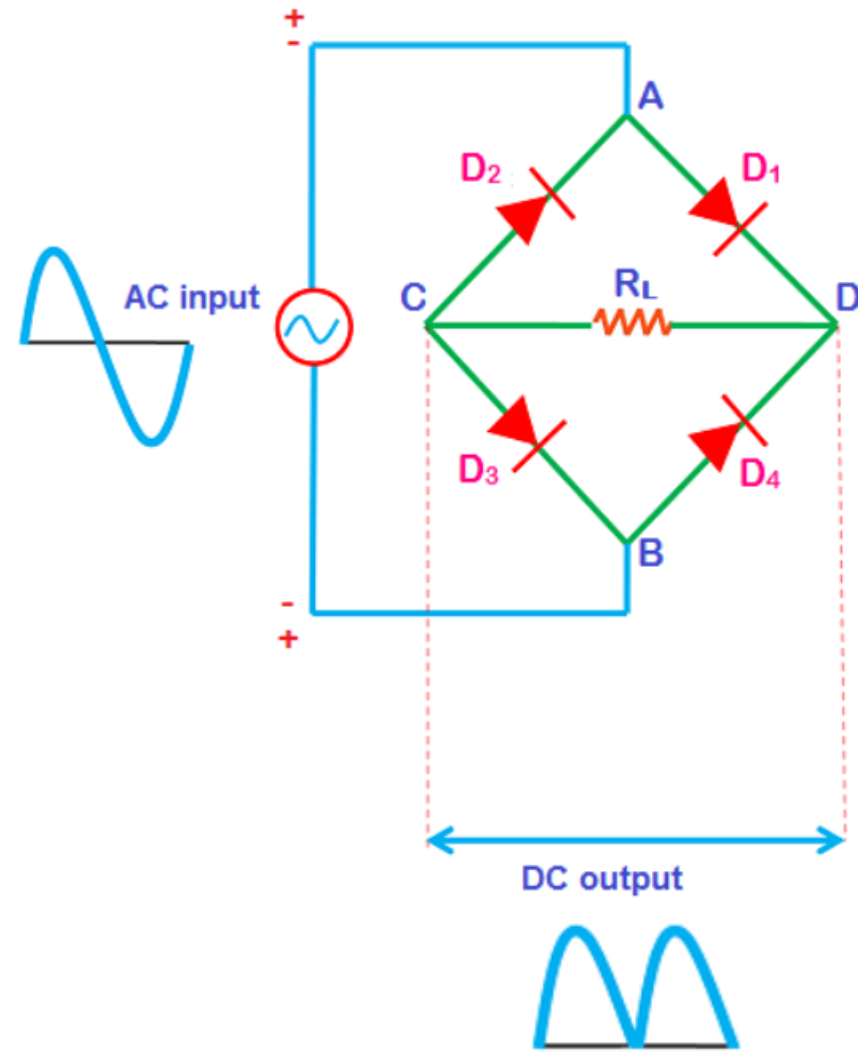
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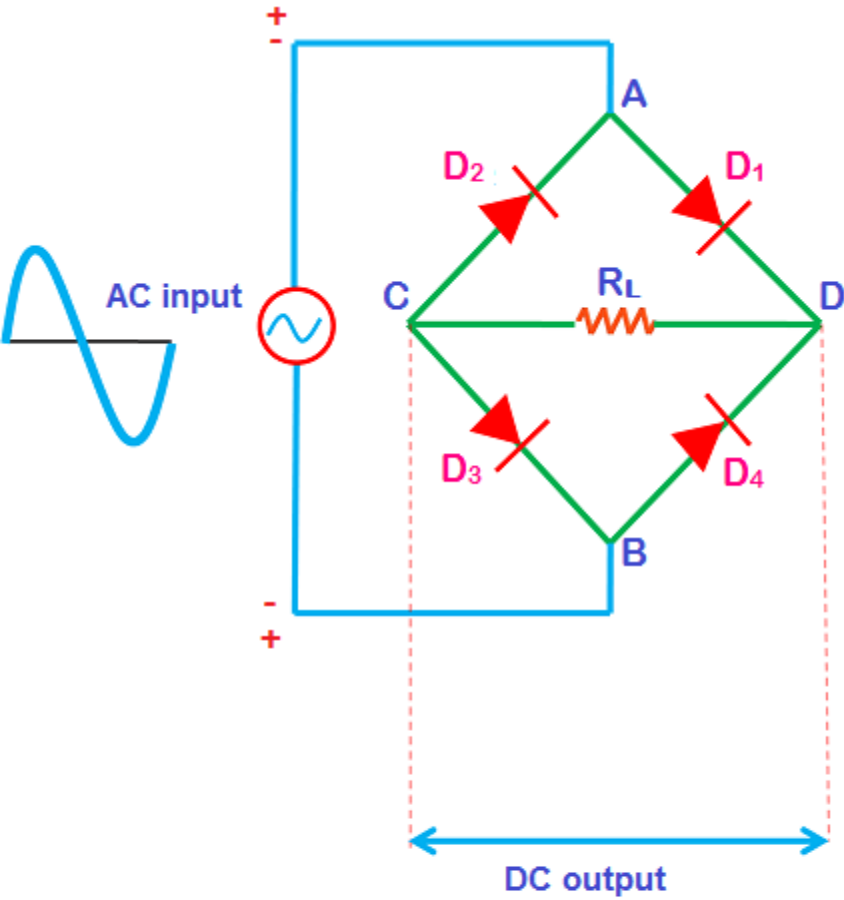
Peak inverse voltage (PIV)

Peak inverse voltage or peak reverse voltage is the maximum voltage a diode can withstand in the reverse bias condition. If the applied voltage is greater than the peak inverse voltage, the diode will be permanently destroyed.

The peak inverse voltage (PIV) = $2V_{smax}$

Bridge Rectifier





ing the positive half cycle is shown in the figure A (I.e. A to D to C to B).

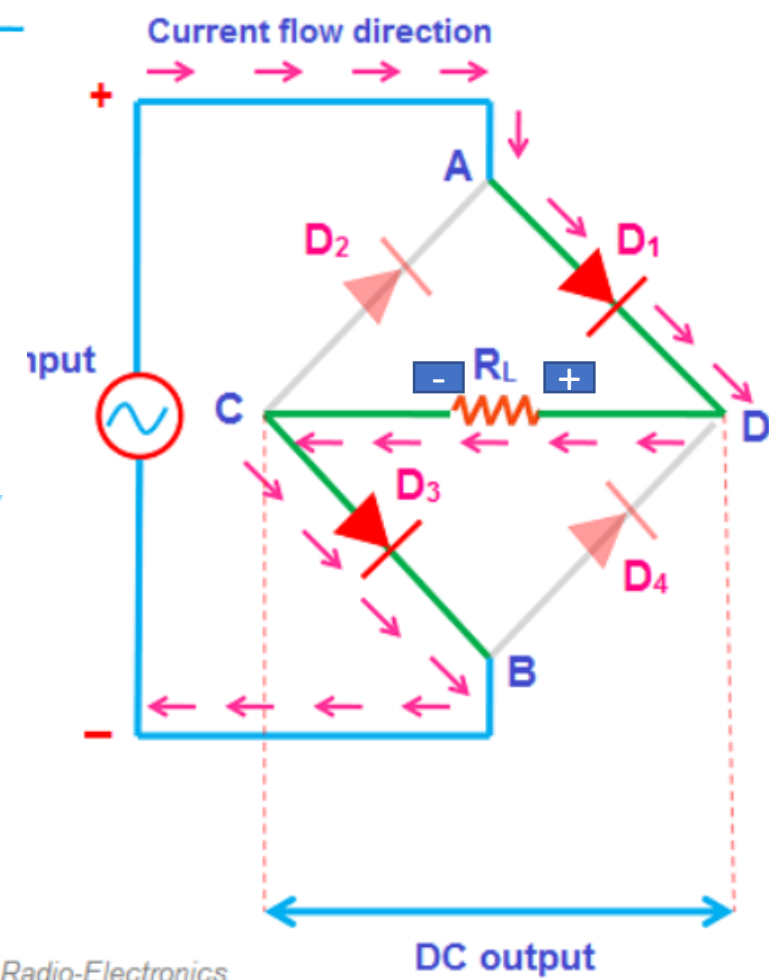
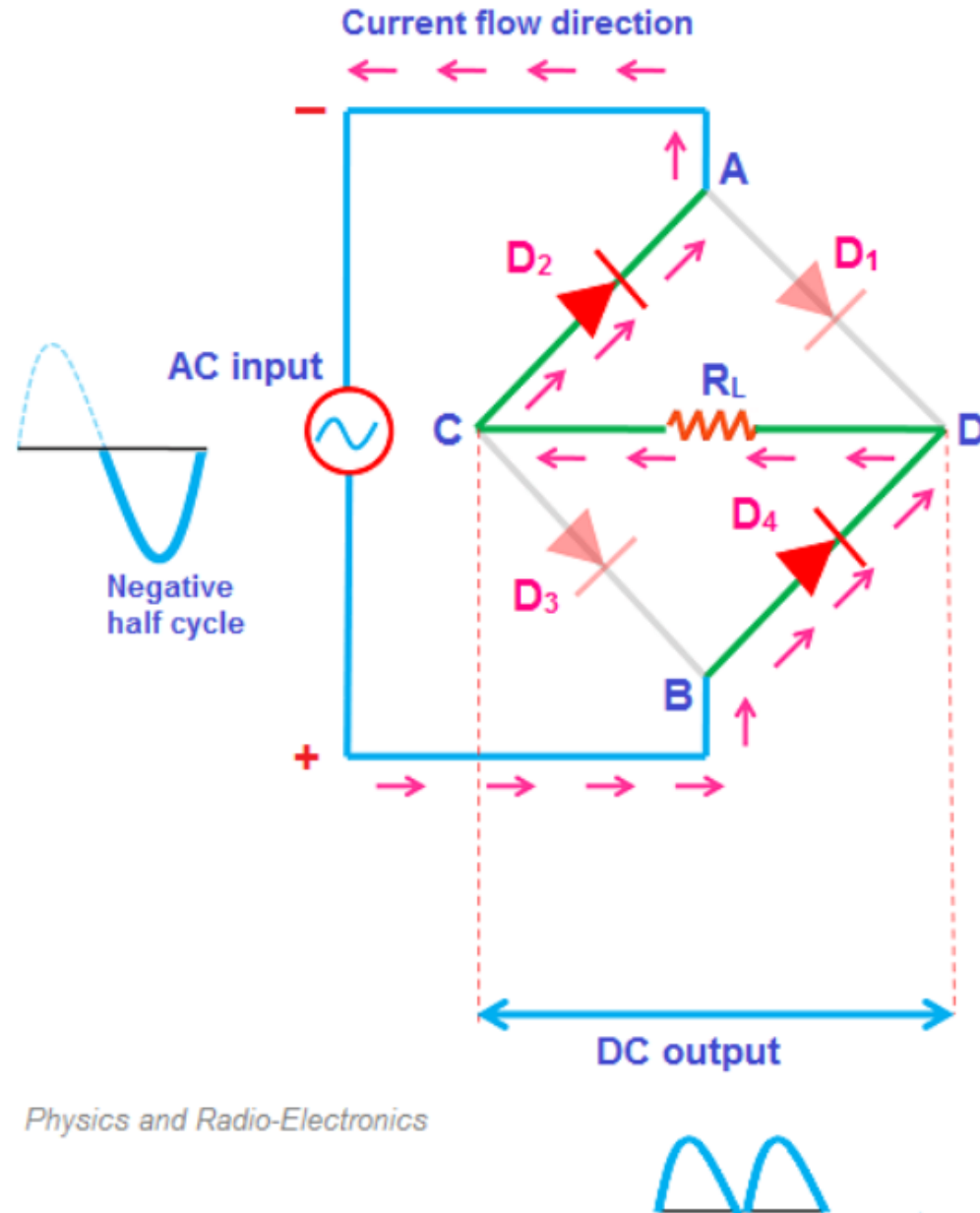


Fig: Bridge Rectifier

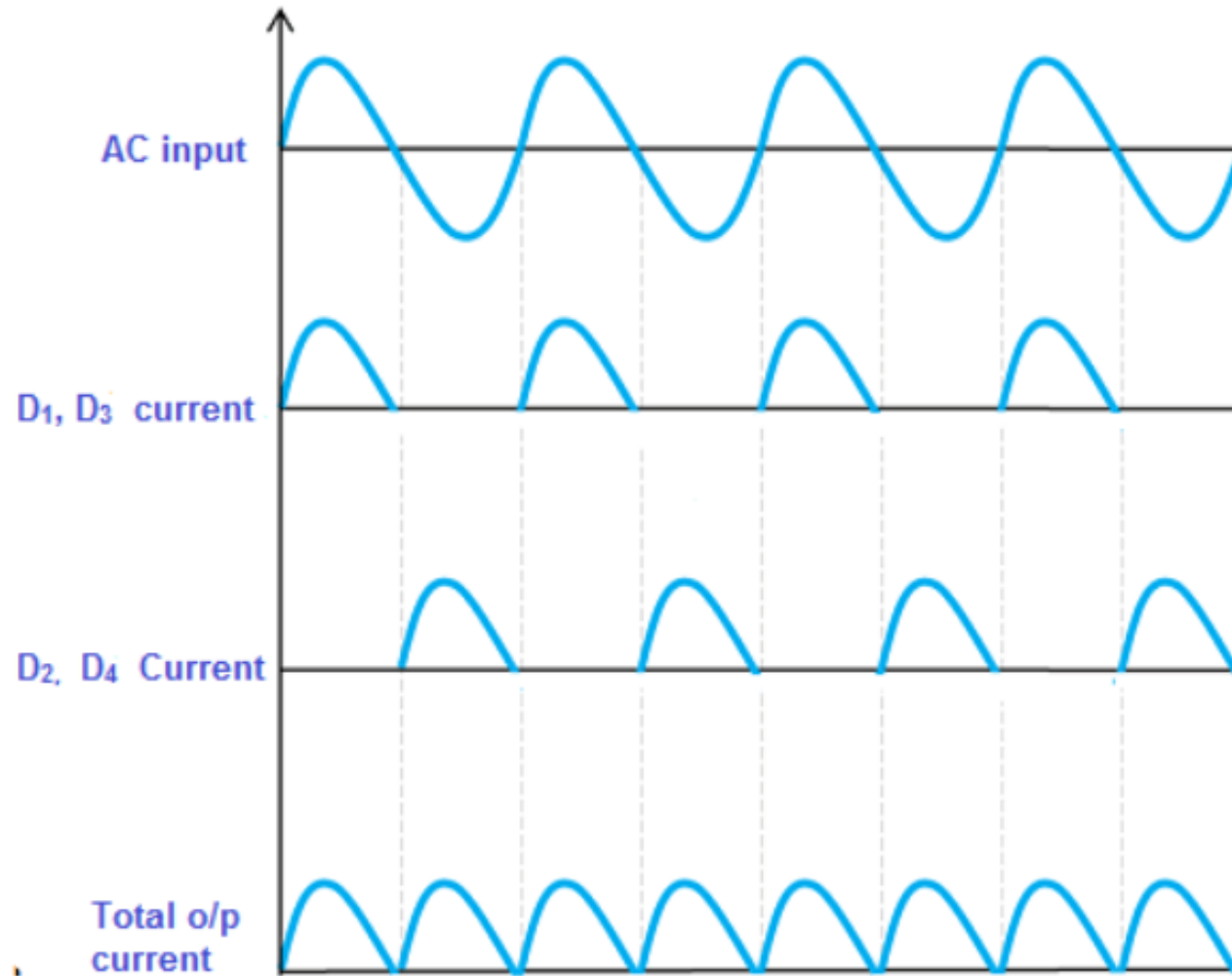
Cont.

The current flow direction during negative half cycle is shown in the figure B (I.e. B to D to C to A).



Cont.

The output waveforms of the bridge rectifier is shown in the below figure.



Cont.

Characteristics of bridge rectifier

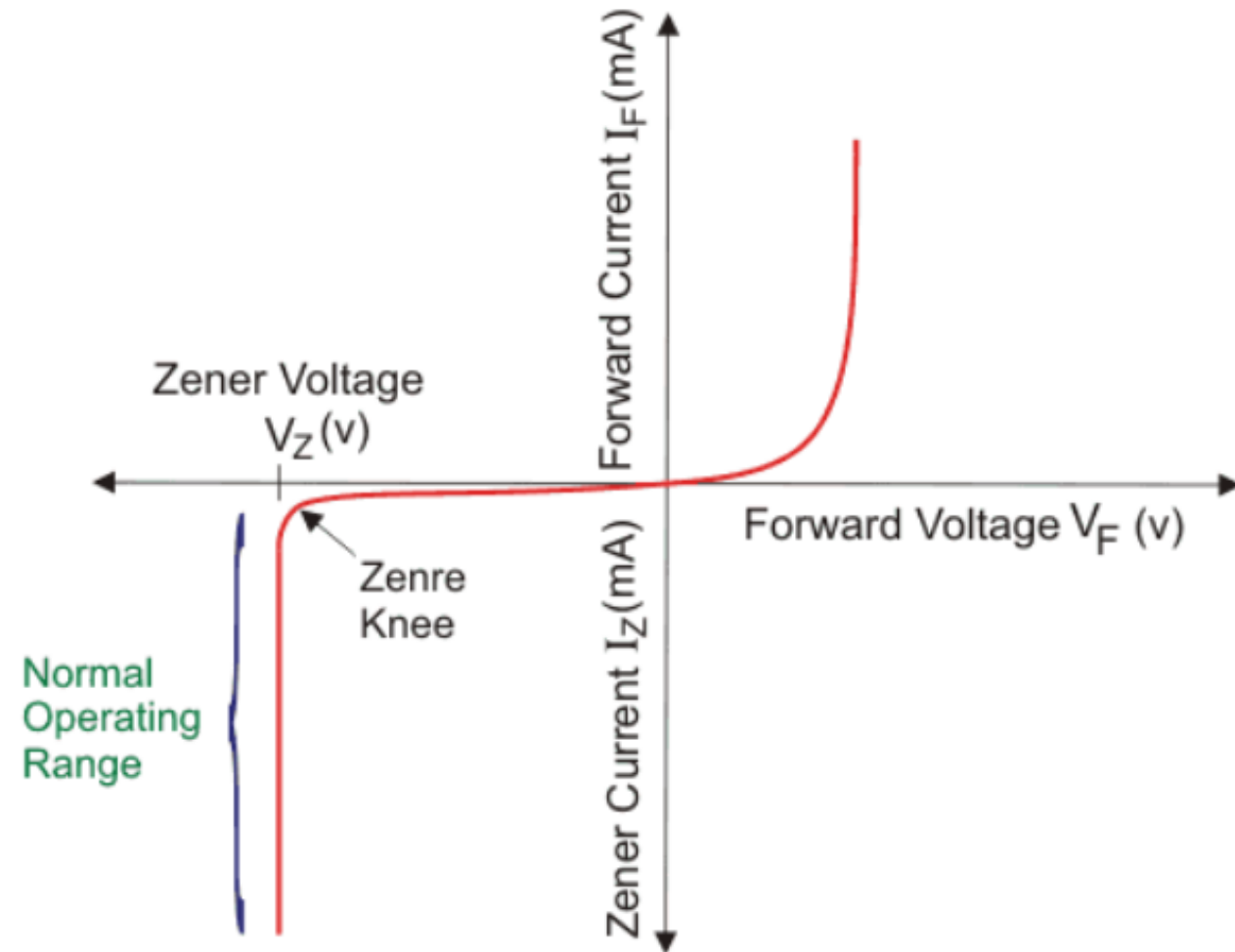
- Assignment

Zener Diode as Voltage Regulator

- A [Zener diode](#) is one of the specially designed [diodes](#) that predominately works in reverse biased conditions.
- They are more heavily doped than ordinary diodes, due to which they have narrow depletion region.
- While regular diodes get damaged when the [voltage](#) across them exceeds the reverse breakdown voltage, Zener diodes work exclusively in this region.
- The depletion region in Zener diode goes back to its normal state when the reverse voltage gets removed.
- This particular property of Zener diodes makes it useful as a **voltage regulator**.

Zener diode Characteristics

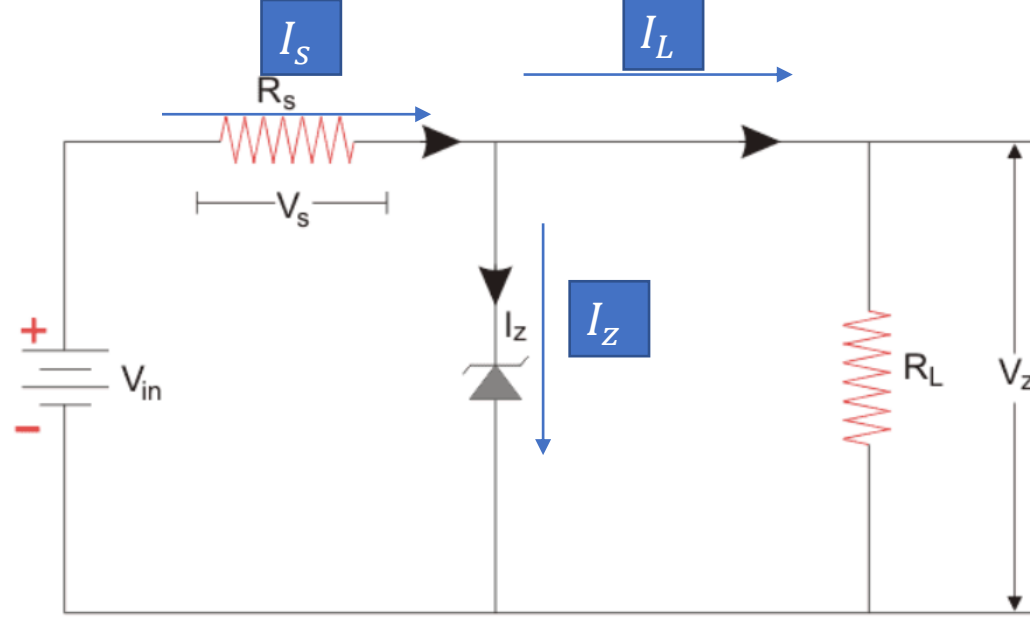
- When we apply a reverse voltage to a Zener diode, a negligible amount of [current](#) flows through the circuit.
- When a voltage higher than Zener breakdown voltage is applied, [Zener breakdown](#) occurs.
- Zener breakdown is a phenomenon where a significant amount of current flows through the diode with a negligible drop in voltage.
- When we increase the reverse voltage further, the [voltage](#) across the [diode](#) remains at the same value of Zener breakdown voltage whereas the current through it keeps on rising as seen in the graph above.
- Here in the graph V_z refers to the Zener breakdown voltage. Zener breakdown voltage typically can range from 1.2 V to 200 V depending on its application.



Zener Diode as Voltage Regulator

For example, we want that the voltage across a load in our circuit does not exceed, let's say, 12 volts. Then we can select a Zener diode with a breakdown voltage of 12 volts and connect it across the load. Then even if the input voltage exceeds that value, the voltage across the load will never exceed 12 volts.

$$I_s = I_L + I_Z$$
$$(V_{in} - V_Z) / R_s = V_Z / R_L + I_Z$$



Here the Zener diode is connected across the load R_L . We want the voltage across the load to be regulated and not cross the value of V_Z . Depending on our requirement, we choose the suitable Zener diode with a Zener breakdown voltage near to the voltage we require across the load. We connect the Zener diode in reverse bias condition. When the voltage across the diode exceeds the Zener breakdown voltage, a significant amount of current starts flowing through the diode. As the load is in parallel to the diode, the voltage drop across the load is also equal to the Zener breakdown voltage. The Zener diode provides a path for the current to flow and hence the load gets protected from excessive currents. Thus the Zener diode serves two purposes here: **Zener diode as a voltage regulator** as well as it protects the load from excessive current.

Zener Diode Example No1

A 5.0V stabilized power supply is required to be produced from a 12V DC power supply input source. The maximum power rating P_Z of the zener diode is 2W. Using the zener regulator circuit above calculate:

a). The maximum current flowing through the zener diode.

$$\text{Maximum Current} = \frac{\text{Watts}}{\text{Voltage}} = \frac{2\text{w}}{5\text{v}} = 400\text{mA}$$

b). The minimum value of the series resistor, R_S

$$R_S = \frac{V_S - V_Z}{I_Z} = \frac{12 - 5}{400\text{mA}} = 17.5\Omega$$

c). The load current I_L if a load resistor of $1\text{k}\Omega$ is connected across the zener diode.

$$I_L = \frac{V_Z}{R_L} = \frac{5\text{v}}{1000\Omega} = 5\text{mA}$$

d). The zener current I_Z at full load.

$$I_Z = I_S - I_L = 400\text{mA} - 5\text{mA} = 395\text{mA}$$