

## (3) OPTIMIZATION FORM 4

$$\begin{aligned} & \text{minimize } \|X - \Phi\Phi^T X\|_F^2 & X \in \mathbb{R}^{d \times n} \\ & \text{st. } \Phi^T \Phi = I & \Phi \in \mathbb{R}^{d \times d} \end{aligned}$$

→ Frobenius norm

here  $X$  is the matrix from the optimization problem  
 $\Phi$  is the matrix consisting of columns of eigenvectors

the objective fn. can be simplified as:

$$\|X - \Phi\Phi^T X\|_F^2 = \text{tr}(X^T X - XX^T \Phi\Phi^T)$$

→ trace of matrix.

its lagrangian is  $(f(x) - \lambda g(x))$

$$\begin{aligned} \mathcal{L} &= \text{tr}(X^T X) - \text{tr}(X^T X \Phi\Phi^T) \\ &\quad - \text{tr}(\Lambda^T (\Phi^T \Phi - I)) \end{aligned}$$

→ eigenvalue matrix  $\mathbb{R}^{d \times d}$

equating derivative of  $\mathcal{L}$  to 0 gives:

$$\frac{\partial \mathcal{L}}{\partial \Phi} = 2XX^T\Phi - 2\Phi\Lambda = 0$$

$$\Rightarrow XX^T\Phi = \Phi\Lambda \quad \Rightarrow \underline{A\Phi = \Phi\Lambda}$$

→ eigenvalue problem

this can be useful in machine learning, when we want to consider several PCA directions of dimensionality reduction in vector form.

④

# FISHER DISCRIMINANT ANALYSIS

this is a dimensionality reduction technique which attempts to classify a set of points in reduced dimensions. it tries to keep the mean of both classes as separate as possible, while trying to minimize variance within a class.

objective:  $\max. w^T S_B w$   $\rightarrow$  max. mean sep.  
 $w^T S_W w$   $\rightarrow$  min. variance within.

$w$  = projection surface

$$S_B = \sum_{i=1}^c (u_i - u_c)(u_i - u_c)^T$$

$$S_W = \sum_{i=1}^c \sum_{j=1}^n (x_{ji} - u_c)(x_{ji} - u_c)^T$$

this objective can be restated as:

$$\max. w^T S_B w$$

$$\text{st. } w^T S_W w = 1$$

finding its lagrangian, and equating its derivative to 0 yields:

$$S_B w = \lambda S_W w$$

since this is now in generalized eigenvalue problem form, we can now use one of the solution methods to obtain  $w$ . (projection plane).

### ⑤ LLE PSEUDOCODE

A. select K nearest neighbours for each point  
for each point  $X_i$   $i = 1 \sim N$

B. find reconstruction weights for each point

$Z$  = matrix of all neighbours of  $X_i$

Subtract  $X_i$  from every column of  $Z$

local covariance  $C = Z^T Z$

solve  $Cw = I$  for  $w$

set  $w_{ij} = 0$  if  $j$  is not neighbour of  $i$ .

remaining elements in row  $w_i$  normalized  $= w_i / \sum w_i$

C. map to target dimension (Y using weights  $w$ )

$$M = (I - w)^T (I - w)$$

find bottom  $d+1$  eigenvectors of  $M$ .

(corresponding to  $d+1$  smallest eigenvalues)

set the  $i$ th row of  $Y$  to be  $i+1$ th ~~sm~~ eigenvector

(discard eigenvector  $[1, 1, 1, \dots]$  with eigenvalue 0)



⑥ line:  $x - y = 1$

100 points:  $(1, 0), (2, 1), (3, 2), \dots, A$

the output is computed in python.

Covariance matrix:

$$\begin{bmatrix} 842 & 842 \\ 842 & 842 \end{bmatrix}$$

eigenvectors:

1.  $\begin{bmatrix} 0.707 & 0.707 \end{bmatrix}$

$$1683$$

2.  $\begin{bmatrix} -0.707 & 0.707 \end{bmatrix}$

$$\sim 0$$

the main eigen vector is the first one which is parallel with respect to the slope line.

(eigen vectors are computed from the covariance matrix)

(7) (A) initialization : 626.1

(B) it. 1 : 16.5

(C) it. 2 : 16.5

..3

3

conv.

(8) (A) if we increase  $K \Rightarrow$  we allow more classes so error can decrease further. agree.

(B) the max. value of  $K$  can be  $N$  (no. of points). then objective (error) would be 0.

(C) normalized objective (error) would decrease too, (but objective  $K$  might not change).

- ① Find the graph distance (distance on the nearest neighbour graph) between points  $x[0]$  and  $x[784]$  for

$$K=1 : -1$$

$$K=2 : 3943.914$$

$$K=3 : 393.839$$

$$K=5 : 393.669$$

$$\text{true distance: } 393.955$$

$$\text{euclidean distance: } 41.505$$

$$x = 10(\cos t - 0.784 \times 50)$$

$$y = 10 \sin t (0 - 0.784 \times 50)$$

$$z = t (0 - 0.784 \times 50)$$

$$x = R \cos t$$

$$\frac{dx}{dt} = -R \sin t$$

$$y = R \sin t$$

$$z = Ht$$

$$\frac{dy}{dt} = R \cos t$$

$$\frac{dz}{dt} = H$$

$$S = \int_{x_1}^{x_2} \sqrt{dx^2 + dy^2 + dz^2}$$

$$= \int_{x_1}^{x_2} \sqrt{(R \sin t)^2 + (R \cos t)^2 + H^2} dt$$

$$= \int_{x_1}^{x_2} \sqrt{R^2 \sin^2 t + \cos^2 t + H^2} dt$$

$$= \int_{x_1}^{x_2} \sqrt{R^2 + H^2} dt$$

$$= \int \sqrt{1001} dt$$

$$\left[ \sqrt{1001} t \right]_{t_1}^{t_2}$$

$$= \sqrt{1001} \cdot 50 (0.784 - 0)$$

$$= 393.9855$$