

EIGEN VALUE PROBLEMS IN OPTIMIZATION

eigen vectors are vectors x that do not get "rotated" by A , only "stretched" (by a factor of λ).

$$Ax = \lambda x$$

eigen value of A can be obtained by solving the characteristic equation $|A - \lambda I| = 0$. eigen vectors form the null space of matrix $(A - \lambda I)$.

interesting properties

- $A^2 x = \lambda^2 x$
- $\prod_i \lambda_i = |A|$
- $\sum_i \lambda_i = \text{tr}(A)$
- every vector is an eigen vector of I .
- symmetric matrices have real eigen values.
- spectral theorem:
symmetric matrices $S = Q \Lambda Q^T$
- generalized eigen value problem of 2 symmetric matrices A and B .

$$Ax = \lambda Bx$$

$$S = \sum_{i=1}^N \lambda_i X_i X_i^T$$

$n \times n$

$$S = Q \Lambda Q^T$$

$$\begin{bmatrix} Q \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_N \end{bmatrix} \begin{bmatrix} Q^T \end{bmatrix}$$

data compression:

new basis vectors, if you get eigen vectors, you can get more optimally.

do not want to transmit basis - DCT

$$Ax = \lambda x \quad \text{classical eigen value problem.}$$

↓

$$Ax = \lambda Bx \quad \text{generalized eigen value problem.}$$

eigen - standard trick, do cholesky of B.

$$Ax = \lambda L L^T x$$

$$L^{-1} A x = \lambda L^T x$$

$$\text{let } y = L^T x$$

$$x = L^{-T} y$$

$$(L^{-1} A L^{-T}) y = \lambda y \quad ?? \quad \text{converted to classical problem.}$$

$$Ax = \lambda L L^T x$$

$$L^{-1} A x = \lambda L^T x$$

$$A' y = \lambda y$$

$$A' = L^{-1} A L^{-T} \quad y = L^T x$$

$$A x = \lambda B x$$

$B^{-1}A$ need not have similar properties of B and A .

$$\text{opt. } x^T A x \quad \text{s.t. } \|x\| = 1$$

$$x^T A x - \lambda (x^T x - 1)$$

$$\frac{\partial}{\partial x} = 0 \Rightarrow$$

$$(Ax = \lambda x) \quad \text{or } x \text{ is } \bar{EV} \text{ of } A.$$

$$\text{as we know } x^T x = 1$$

$$\Rightarrow x^T A x = \underline{\lambda}$$

pick largest value, so objective is λ .
min., pick smallest eigen value.

$$Ax = 0$$

$$\min \|Ax\| \quad \text{st.} \quad \|x\| = 1$$

scalar

$$x^T A^T A x - \lambda (x^T x - 1)$$

remove trivial solns.
get a fixed magnitude

$$A^T A x = \lambda x$$

$$z^* = \lambda$$

PRESENCE OF EV IN OM

many optimization problems take the form:

$$\min_x z = x^T A x,$$

$$\text{st. } \|x\|^2 = 1$$

soln. gives us $Ax = \lambda x$

$$z^* = \lambda$$

maximum variance line fitting

let y_1, \dots, y_N be the points,

and w be the direction,

variance of x on w should be maximized with a constraint on $\|w\| = 1$. also $x = w^T(y - b)$

$$\frac{1}{N} \sum_{i=1}^N \left(x_i - \frac{1}{N} \sum_{i=1}^N x_i \right)^2 + \lambda (w^T w - 1)$$

least norm soln. to $Ax = 0$,

$$\min_x \|Ax\|^2$$

$$\text{st. } \|x\|^2 = 1$$

$$\text{soln. } (A^T A) x = \lambda x$$

$$z^* = \lambda$$

APPLICATIONS: PCA

Objective function of PCA is defined as:

given data matrix $X: (N \times M)$, find a direction

u such that the variance of the projection of X on u is maximized (max. information captured).

projection of X on u is X_u .

mean of projections is \bar{X}_u .

$$\max_u \| (X - \bar{X}) \cdot u \|^2, \quad \|u\|^2 = 1$$

the constraint comes because u is only a direction

$$\max_u u^T \Sigma u, \quad u^T u = 1$$

$$\max_u u^T \Sigma u - \lambda (u^T u - 1)$$

$$\Sigma u = \lambda u, \quad z^* = \lambda$$

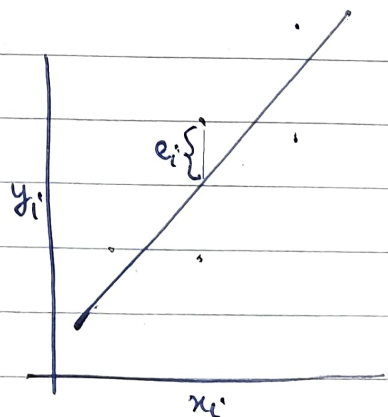
$$\min \|y_i - w^T x_i\|$$

$L_2 \rightarrow$ LSE

$L_1 \rightarrow$ LP

$L_0 \rightarrow$ most points passing

$L_{\infty} \rightarrow$ distance to largest outlier smallest.



suddenly becomes an EV problem.

(eg. PCA).

Set of dimensions

x_1, \dots, x_n

set of points

x_1, x_2, x_3

interested in finding the plane

no special axis

orthogonal distance.

Variance is maximum

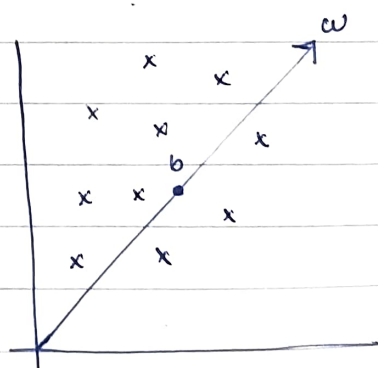
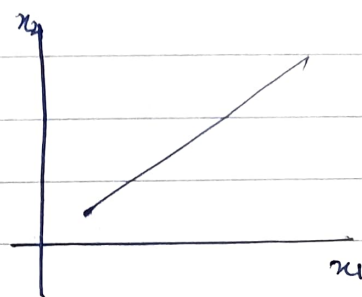
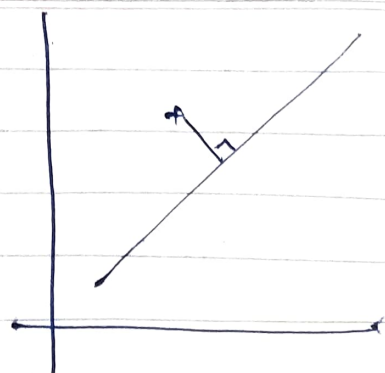
y_1, \dots, y_N

$$x = \underset{\substack{\uparrow \\ \text{to}}}{w}^T (\underset{\substack{\uparrow \\ \text{find}}}{y} - b)$$

we would like variance to be maximized.

$$\max_w \frac{1}{N} \sum_i (x_i - \frac{1}{N} \sum x_i)^2 \quad \text{st. } \|w\| = 1$$

$$\max_w \frac{1}{N} \sum_i (x_i - \bar{x})^2 - \lambda (1 - w^T w)$$



$$\rightarrow \frac{1}{N} \sum_i \left(\omega^T (y_i - b) - \frac{1}{N} \sum_i \omega^T (y_i - b) \right)^2$$

$$\rightarrow \frac{1}{N} \sum_i \left(\omega^T (y_i - b - \frac{1}{N} \sum_i y_i + \frac{1}{N} N b) \right)^2$$

$$\rightarrow \frac{1}{N} \sum_i \left(\omega^T (y_i - \frac{1}{N} \sum_i y_i) \right)^2$$

$$\rightarrow \frac{1}{N} \sum_i \omega^T (y_i - \bar{y}) (y_i - \bar{y})^T \omega$$

covariance of y_i

$$\omega^T \Sigma \omega - \lambda (1 - \omega^T \omega)$$

ω is the EV of Σ .

ω is the eigen vector corresponding to largest eigen value of $\underline{\Sigma}$.

b is the mean of y_i .

projection of points resulting max. variance. (b).

$$f: (x-1)^2 + y^2 \quad x+y=2$$

$$L: (x-1)^2 + y^2 - \lambda (x+y-2) = 0$$

$$\frac{\partial L}{\partial x} = 0 \Rightarrow 2(x-1) - \lambda = 0 \quad 2(x-1) = \lambda$$

$$\frac{\partial L}{\partial y} = 0 \Rightarrow 2y - \lambda = 0 \quad 2y = \lambda$$

$$(3/2, 1/2) \quad \frac{\partial L}{\partial \lambda} = 0 \Rightarrow x+y=2.$$

SIMPLE GRAPH PARTITIONING / CLUSTERING

- matrices

edges = m

vertices = n

- incidence matrix (J): $m \times n$

- degree matrix: diagonal (D): $n \times n$

- adjacency (A): $n \times n \in \{0, 1\}$

- laplacian (L): $n \times n$ $L = D - A$;

$$L = J^T J$$

- affinity / weight ($A(w)$): $n \times n$

- affinity matrix A ;

A_{ij} : affinity of i^{th} and j^{th} node (eg. $A_{ij} = e^{-d(x_i, x_j)}$)

- w : vector with w_i being the "membership" of i vertex / sample into the cluster.

- optimization problem:

$$\max. w^T A w$$

$$\text{s.t. } w^T w = 1$$

- w is the eigen vector of A and characterize a good cluster,

SPECTRAL GRAPH PARTITIONING / CLUSTERING

- A be the adjacency matrix.

eg. (i) fully connected with all nodes have degree d ;

(ii) 2 separate components of each have degree d .

- $Ax = y$; y_i is the sum of neighbors of node i .

- case 1: $Ax = \lambda x$; $x = [1, 1, \dots, 1]^T$ and $\lambda = d$.

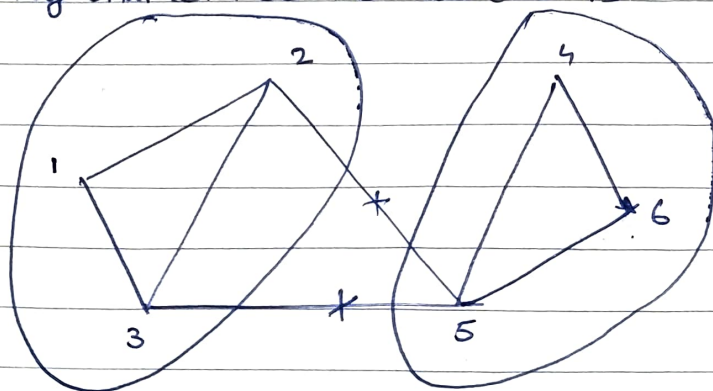
- case 2: $x' = [1, \dots, 1, 0, \dots, 0]^T$ and $\lambda' = d_1$ and
 $x'' = [0, \dots, 0, 1, \dots, 1]^T$ and $\lambda'' = d_2$

- $Lx = 0$ is true for a constant vector say $x_i = 1$ vector, with $\lambda = 0$ (why? D_{ii} is y_i).

- fiedler vector: eigen vector corresponding to the smallest positive (second smallest) eigen value.

- x_2 is orthogonal to x_1 .

Some elements of x_2 are positive and some negative, they characterize the two clusters.



Matrices $m = \# \text{ edges}$

x_1, \dots, x_k

$n = \# \text{ vertices}$

affinity matrix

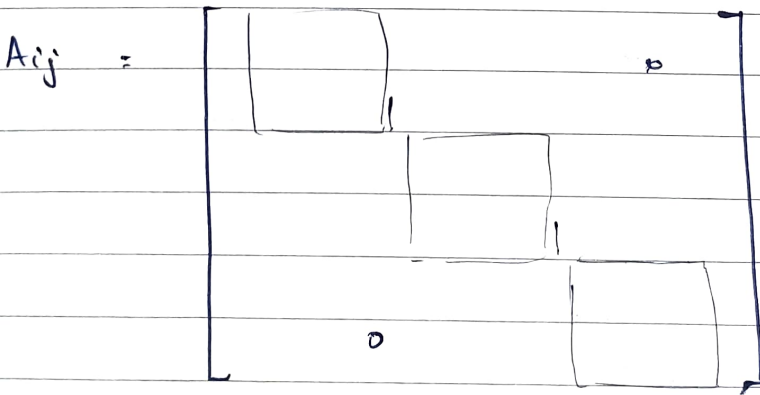
$$A_{ij} = c^{-d} \leftarrow \text{distance}$$

how to do clustering

$A_{ij} = \text{affinity matrix } e^{-d}$

$$d_{ij} \rightarrow 0 \Rightarrow e^{-d} = 1$$

$$d_{ij} \rightarrow \infty \Rightarrow e^{-d} = 0$$



$$\max w^T A w$$

$$\text{st. } \|w\| = 1$$

$$\sum_i \sum_j w_i w_j A_{ij}$$

$$A_{ij} \rightarrow 0 \Rightarrow w_i w_j A_{ij} \rightarrow 0$$

ω is the \overline{EV} of A

$$\begin{bmatrix} 1 \\ \vdots \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\omega_i = 1 \quad \text{if}$$

threshold the values.

adjacency matrix $\begin{bmatrix} 0 & 1 & 1 & 1 & 1 & 1 \\ & A & & & & \end{bmatrix}$

$$A \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} = \begin{bmatrix} n-1 \\ n-1 \\ n-1 \\ n-1 \end{bmatrix}$$

$$A \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} = (n-1) \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$\textcircled{n-1} \quad \textcircled{n-1}$$

2n matrix

$$\begin{bmatrix} A \end{bmatrix} \begin{bmatrix} 1 \\ \vdots \\ 1 \\ 0 \end{bmatrix} = (n-1) \begin{bmatrix} 1 \\ \vdots \\ 1 \\ 0 \end{bmatrix}$$