#### OM Review - XIX

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https://forms.gle/o2f5oioWCPRirUgW8

# Context for next question

We saw in one of the problems in the last lecture that K-Means is prone to local minima. Consider strategies S1, S2, S3 aimed to solve this issue. Given dataset S we need to find initial set of cluster centroids T.

S1: Pick k points from S that are farthest away from each other.

S2: Pick  $x \in S$  uniformly at random and set  $T \leftarrow \{x\}$  While |T| < k:

(i) Pick  $x \in S$  at random, with probabilities directly proportional to  $\min_{z \in T} \|x - z\|$ (ii)  $T \leftarrow T \cup \{x\}$ 

S3: Pick  $x \in S$  uniformly at random and set  $T \leftarrow \{x\}$  While |T| < k:

(i)Pick  $x \in S$  at random, with probabilities inversely proportional to  $\min_{z \in T} \|x - z\|$ (ii)  $T \leftarrow T \cup \{x\}$ 

Which of these are true with regards to above?

- (A) S2 is the best among S1,S2,S3
- (B) S3 is the best among S1,S2,S3
- (C) S1 is prone to outliers
- (D) S1 is not prone to outliers

More than one may be correct.

Which of these is true about following statements on K Means?

- (i) Bad initialization can lead to poor convergence speed
- (ii) Bad initialization can lead to bad overall clustering
- (iii) If we choose K = |S|, ie size of dataset; then J = 0, hence it is a good choice for K.
- (A) (i),(ii),(iii)
- (B) None of the others
- (C) (i)
- (D) (i),(ii)

Which of these is true?

- (i) MDS with Euclidean distance gives a linear combination of data as the answer
- (ii) ISOMAP tries to preserve Euclidean distances between all pairs of points
- (A) Both (i) and (ii)
- (B) Neither (i) nor (ii)
- (C) (i) only
- (D) (ii) only

Which of these is true about ISOMAP?

- (A) It can be obtained by solving for the eigenvectors of  $K = -\frac{1}{2}HDH$  where D is the Euclidean distance matrix and H is the centering matrix
- (B) It requires us to solve APSP problem once.
- (C) It requires us to solve APSP problem more than once.

APSP problem: All pairs shortest paths problem More than one may be correct.

Which of these is true?

- (A) It is poosible that LLE can lead to the same solution as PCA
- (B) None of the others
- (C) In Laplacian Eigenmaps, weights are optimized in one of the steps
- (D) In Laplacian Eigenmaps, weights are constants

More than one may be correct