Mesh Addition Based on the Depth Image (MABDI)

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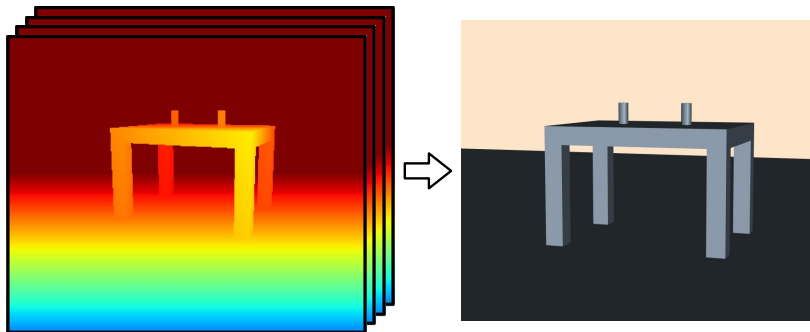
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November 2016

Outline

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1. **Introduction**
   - Goal

What is the main objective?

RGB-D sensor to make a useful representation of the environment

(Marton et al. 2009) On Fast Surface Reconstruction Methods for Large and Noisy Point Clouds