

Mesh Addition Based on the Depth Image (MABDI)

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November 2016



*This work was supported in part by:
Sandia National Laboratories under Purchase Order: 1179196 and NSF grant OISE #1131305.*

Outline

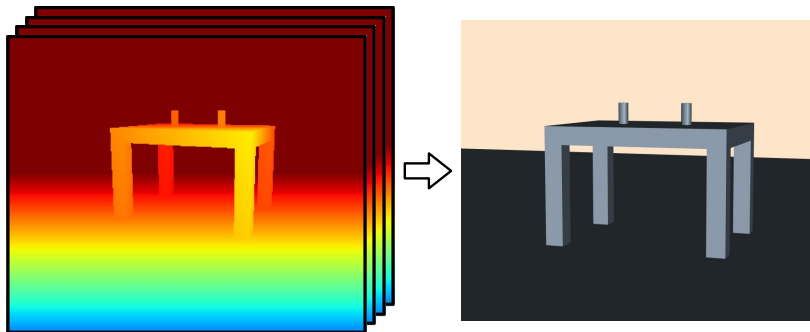
- 1 Introduction
 - Goal

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What is the main objective?

RGB-D sensor to make a useful representation of the environment



(Marton et al. 2009) On Fast Surface Reconstruction Methods for Large and Noisy Point Clouds