Complexity Analysis of Polynomial Algorithms

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Abstract

This work is about three different proofs of the same fact and a computational comparison between them, looking for the best one.

Let R be a real closed field and $n \geq 2$. We prove that: (1) for every finite subset F of R^n, the semialgebraic set $R^n \setminus F$ is a polynomial image of R^n; and (2) for any independent linear forms $l_1, \dots, l_r$ of R^n, the semialgebraic set $\{l_1 > 0, \dots, l_r > 0\} \subset R^n$ is a polynomial image of R^n.

The key proof here is that $\mathcal{Q} = \{x > 0, y > 0\}$ is a polynomial image of $\mathbb{R}^2$. This assert is proved in three different ways: a first approach using real algebraic geometry; a second and shorter one, using the composition of 3 rather simple maps; and a third one that applies topology with no computer computations.

(...)

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Polynomial images of R^n

1.1 Introduction

Definition 1.1. Let R be a real closed field and $m, n \in \mathbb{N}_{>0}$. A map $f = (f_1, \dots, f_n) : R^m \longrightarrow R^n$ is said to be polynomial if $f_i \in R[x_1, \dots, x_m], i = 1, \dots, n$.

A very famous theorem by Tarski and Seidenberg states:

Theorem 1.1 (Tarski-Seidenberg)**.** The image of every polynomial map $f : R^m \longrightarrow R^n$ is a semialgebraic subset of R^n.

In this work we are studying sort of a converse of this statement. In an *Oberwolfach* week [G], J.M. Gamboa proposed to characterize the semialgebraic subsets of R^n that are polynomial images of R^m.

Notation. We need to mention to which topology we refer to when we talk about closures, boundaries, etc. More specifically, the **exterior boundary** of a set S is $\delta S := \overline{S} \setminus S$, with $\overline{S}$ being the **closure** of S in R^n in the usual topology. $\overline{S}^{\text{zar}}$ is the closure of S with respect to the Zariski topology. $A \subset R^n$ is **irreducible** if its Zariski closure $\overline{A}^{\text{zar}}$ is an irreducible algebraic set.

1.1.1 Necessary conditions and examples

To begin working on this idea, we provide some necessary conditions for a set $S \subset R^n$ to be polynomial image of R^m.

It is trivial that for $m = n = 1$ (so $f : R \to R$), the images of polynomial maps are either a set of one point or singletons (if the map is constant), or unbounded closed intervals (think of $f(x) = x^2$), or the whole R (think of $f(x) = x$).

In the general case, by Tarski-Seidenberg, S must be a semialgebraic set and, moreover, semialgebraically connected. Even more, by the identity principle for polynomials, S is irreducible and pure dimensional.

In the polynomial case there are more constrains.

Definition 1.2. A polynomial map $f : R^m \longrightarrow R^n$ is said to be **semialgebraically proper at a point** $p \in R^n$ if there exists an open neighbourhood K of p such that the restriction

$$\begin{aligned} f^{-1}(K) &\longrightarrow K \\ x &\longmapsto f(x) \end{aligned}$$

is a semialgebraically proper map.

Definition 1.3. A parametric semiline of R^n is a non-constant polynomial image of R.

It is clear that every parametric semiline is semialgebraically closed, since every polynomial map from R to R^n is semialgebraically proper. Let $\mathscr{S}_f$ denote the set of points $p \in R^n$ at which f is **not** semialgebraically proper.

Theorem 1.2 (Jelonek)**.** Let $f : R^2 \longrightarrow R^2$ be a dominant polynomial map. Then $\mathscr{S}_f$ is a finite union of parametric semilines.

With all these ideas in mind, we can get some conclusions in the following proposition:

Proposition 1.1. *Let $f : R^m \longrightarrow R^n$ be a polynomial map and $S = f(R^m)$.*

(1) $\delta S \subset \mathscr{S}_f$.

Proof. Suppose $p \in \delta S \setminus \mathscr{S}_f$. Because $p \notin \mathscr{S}_f$, there exists an open neighbourhood K of p such that the restriction $f^{-1}(K) \to K$ of f is proper, and thus its image $K \cap S$ is a closed subset of K. Hence, $p \in K \cap \overline{S} = K \cap (\overline{K \cap S}) = K \cap S$, which yields in a contradiction.

(2) Let $m = n = 2$ and Γ be a 1-dimensional irreducible component of $\overline{\delta S}^{zar}$. Γ is the Zariski closure of a parametric semiline of R^2.

Proof. Since f is a dominant map, we can apply Jelonek and get that $\mathscr{S}_f$ is a finite union of parametric semilines, say $M_1, \dots, M_s$ in R^2. Then, using (1) we get: $\Gamma \subset \overline{\delta S}^{\text{zar}} \subset \overline{\mathscr{S}_f}^{\text{zar}} = \cup_{i=1}^{s} \overline{M_i}^{\text{zar}}$. Lastly, using that both Γ and the $\overline{M_i}^{\text{zar}}$'s are irreducible, we must have that for some $i = 1, \dots, s : \Gamma = \overline{M_i}^{\text{zar}}$.

(3) Let $p : R^n \to R$ be a polynomial map which is non-constant on S. Then $p(S)$ is unbounded.

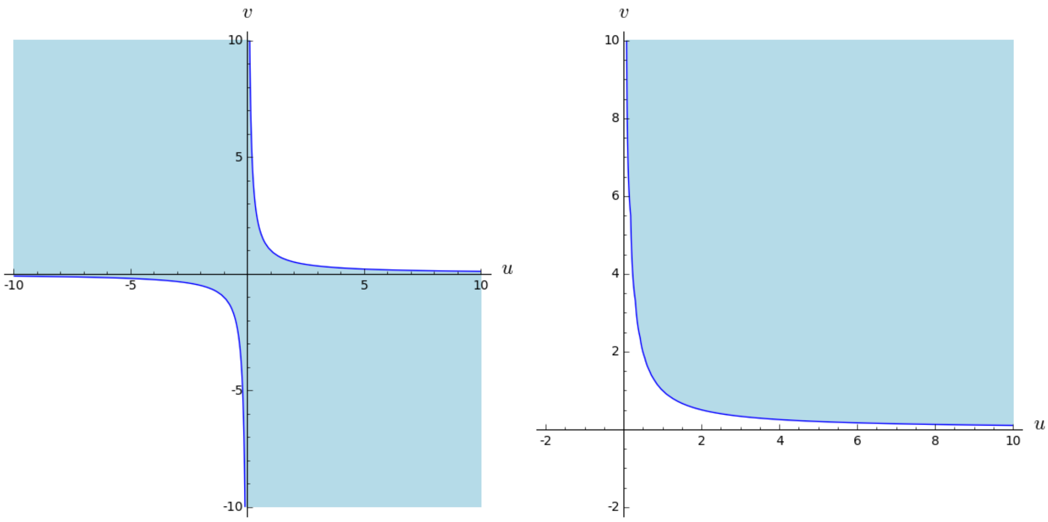
Proof. If $a \in R^m$, let us define $\varphi_a : R \to R$ as $\varphi_a(t) := p(f(ta))$. Then, $\forall a \in R^m$, $p(S)$ would contain the image $\varphi_a(R)$: $\varphi_a(R) \subset p(S)$. Now suppose that $\varphi_a(R)$ is bounded $\forall a$. Then $\varphi_a(R)$ would be a point r_a, and given $a, b \in R^m$: $\varphi_a(1) = p(f(ta)) = r_a = \varphi_a(0) = \varphi_b(0) = r_b = p(f(tb)) = \varphi_b(1)$. This implies that p would be constant on S, which is a contradiction.

Corolary 1.1. *Because of (3) in proposition 1.1, all linear projections of S are either a point or unbounded. Consequently, S is also unbounded or a point.*

Example 1.1.

(i) The exterior of the closed unit disc $S = \{u^2 + v^2 > 1\}$ **is not** a polynomial image of R^2. This is because the only irreducible component of $\overline{\delta S}^{\text{zar}}$ is $\{u^2 + v^2 = 1\}$ and this set is not a parametric semiline because it is bounded.

(ii) Let $S_1 = \{uv < 1\}$ and $S_2 = \{uv > 1, u > 0\}$ (see fig. 1.1). They both **are not** polynomial images of R^2 since the Zariski closure of the exterior boundary ($\overline{\delta S_1}^{\text{zar}}$ and $\overline{\delta S_2}^{\text{zar}}$) is the hyperbola $uv = 1$, which is not a parametric semiline.



(a) $S_1 = \{uv < 1\}$.

(b) $S_2 = \{uv > 1, u > 0\}$.

Figure 1.1: Plots of the regions defined in example 1.1 (ii).

(iii) Let $S = R^2 \setminus \{(0,0)\}$ be the punctured plane. Then S is the image of the polynomial map $(x, y) \mapsto (xy - 1, (xy - 1)x^2 - y)$.

(iv) Let $\mathbb{H} = \{v > 0\}$ be the open upper half-plane. Then $\mathbb{H}$ is the image of $(x, y) \mapsto (y(xy - 1), (xy - 1)^2 + x^2)$. Furthermore, all the open half-planes are a polynomial image of R^2. This is probably the simplest polynomial map whose image is $\mathbb{H}$.

1.1.2 Statement of the main results

Indeed, the main results of this chapter are generalizations of the examples (iii) and (iv) from 1.1, meaning:

Theorem 1.3. Let $n \geq 2$. For every finite set $F \subset R^n$, the semialgebraic set $R^n \setminus F \subset R^n$ is a polynomial image of R^n.

Theorem 1.4. Let $n \geq 2$. For any independent linear forms $l_1, \ldots, l_r$ of R^n, the open semialgebraic set $\{l_1 > 0, \ldots, l_r > 0\}$ is a polynomial image of R^n.

Before the paper [FerGam], the known open sets that are polynomial images of R^2 have irreducible exterior boundary, and they are all deformations of $\mathbb{H}$. J.M. Gamboa and J.M. Ruiz outlined the problem of finding if the first open quadrant $\mathcal{Q} = \{x > 0, y > 0\}$ is a polynomial image of R^2 or not, since its exterior boundary is not irreducible. This problem is a key particular case from theorem 1.4. The best known approach to try to solve this problem is the transformation

$$\begin{aligned} \psi : R^2 &\longrightarrow \mathcal{Q} \cup \{(0,0)\} \\ (x, y) &\longmapsto (x^4y^2, x^2y^4) \end{aligned}$$

. So our main task here is to prove:

Theorem 1.5. The first open quadrant $\mathcal{Q}$ is a polynomial image of R^2.

The proof of theorem 1.5 will consist in two parts:

- ⋆ Choosing a “good” candidate to be the polynomial map, and giving the reasons behind this choice (see subsection 1.3.1).
- ⋆ Checking that the image of the map is $\mathcal{Q}$ indeed. After some arguments, this will reduce to prove the non-existence of real roots of certain polynomials in one variable on certain intervals, and to compare some rational functions on those intervals. In order to do this, we use symbolic computations with tools like Sage and Maple. Because of the high degree of the polynomials involved, the actual check of non-existence of root is done with a Maple package that performs Sturm algorithm ([BoCoRo, 1.2.10]) and a Python program that implements Laguerre's method.

Now, it is really important that provided we are proved theorem 1.5, then theorem 1.4 is proved as follows:

Proof. (of theorem 1.4)

Clearly, that after a linear change of coordinates we can suppose that $l_1 = x_1, \ldots, l_r = x_r$, and so, we only have to prove that for every pair of positive integers $r \leq n$ the semialgebraic set $\{x_1 > 0, \ldots, x_r > 0\} \subset R^n$ is a polynomial image of R^n. This is reduced to prove the following two steps:

- ⋆ $\mathbb{H} = \{x_1 > 0\}$ and $\mathcal{Q} = \{x_1 > 0, x_2 > 0\} \subset R^2$ are polynomial images of R^2, which is true by example 1.1 (iv) and theorem 1.5, respectively.

- ⋆ Now, $\mathcal{O} = \{x_1 > 0, x_2 > 0, x_3 > 0\} \subset R^3$ is a polynomial image of R^3. Let $H_1, H_2 : R^2 \to R^2$ be polynomial maps whose respective images are $\mathbb{H}$ and $\mathcal{Q}$. Let us define:

$$\begin{aligned}(H_1, \mathrm{id}_R) :& R^3 = R^2 \times R \longrightarrow R^3 = R^2 \times R \\ (\mathrm{id}_R, H_2) :& R^3 = R \times R^2 \longrightarrow R^3 = R \times R^2\end{aligned}$$

. Then, $\mathcal{O}$ is the image of the map defined by:

$$H = (\mathrm{id}_R, H_2) \circ (H_1, \mathrm{id}_R) : R^3 \to R^3$$

. □

The proofs of theorems 1.3 and 1.5 are written for the case $R = \mathbb{R}$. For both theorems, explicit polynomial maps are given. Hence, the transfer principle ([BoCoRo], 5.2.3) extends the results to arbitrary R.

1.2 Complementary set of a finite set (th. 1.3)

We proceed to prove theorem 1.3:

Proof. (of theorem 1.3)

Let $F = \{p_1, \dots, p_k\}$. We are going to see that it suffices to prove the result for points of the form $p_j = (a_j, \vec{0}) \in \mathbb{R} \times \mathbb{R}^{n-1}$:

After a linear change of coordinates we can assume that each pair of points have non-equal first components, that is, if we denote $p_j := (a_{1j}, \dots, a_{nj})$ then $a_{1j} \neq a_{1l}$ if $j \neq l$. Then, $\exists P_1 \in \mathbb{R}[T]$ such that $P_1(a_{1j}) = a_{nj}, j = 1, \dots, n$, so denoting $x' = (x_1, \dots, x_{n-1})$, we can define the polynomial map

$$\begin{aligned}h_1 : \mathbb{R}^n &\longrightarrow \mathbb{R}^n \\ (x', x_n) &\longmapsto (x', x_n + P_1(x_1))\end{aligned}$$

. h_1 is bijective: Every point of $\mathbb{R}^n$ has a preimage in $\mathbb{R}^n$, namely if $x = (x_1, \dots, x_n)$, then $(x', x_n - P_1(x_1))$ is its preimage, so h_1 is onto. As for being injective, any two points x, y cannot have the same image through h_1, because if not $h_1(x) = (x_1, \dots, x_n + P_1(x_1)) = (y_1, \dots, y_n + P_1(y_1)) = h_1(y)$, so then $x_i = y_i, i = 1, \dots, n-1$. Also $x_n + P_1(x_1) = y_n + P_1(y_1)$, but since $x_1 = y_1 \Rightarrow P_1(x_1) = P_1(y_1) \Rightarrow x_n = y_n \Rightarrow x = y$.

Now, for $p'_j = (a_{1j}, \dots, a_{(n-1)j}, 0)$ we have that $h_1(p'_j) = p_j$. Analogously, we can take $P_2 \in \mathbb{R}[T]$ such that $P_2(a_{1j}) = a_{(n-1)j}$, and define the polynomial bijection

$$\begin{aligned}h_2 : \mathbb{R}^n &\longrightarrow \mathbb{R}^n \\ (x'', x_{n-1}, x_n) &\longmapsto (x'', x_{n-1} + P_2(x_1), x_n)\end{aligned}$$

, where $x'' = (x_1, \dots, x_{n-2})$. Then $h_2(p''_j) = p'_j$ for $p''_j = (a_{1j}, \dots, a_{(n-2)j}, 0, 0)$. Then it is clear that the polynomial bijection

$$(h_1 \circ h_2)(p''_j) = h_1(h_2(p''_j)) = h_1(p'_j) = p_j$$

, so we can inductively construct a polynomial bijection $h : \mathbb{R}^n \to \mathbb{R}^n$ such that $h(q_j) = p_j$ for $q_j = (a_{1j}, \vec{0}) \in \mathbb{R} \times \mathbb{R}^{n-1}$. Now let $G = \{q_1, \dots, q_k\}$ and $g : \mathbb{R}^n \to \mathbb{R}^n$ be a polynomial map such that $g(\mathbb{R}^n) = \mathbb{R}^n \setminus G$. Then $(h \circ g)(\mathbb{R}^n) = \mathbb{R}^n \setminus F$, which concludes the first part of the proof. Now, in what follows, we can suppose that $p_j = (a_j, \vec{0})$.

We claim that the image of the polynomial map $f = (f_1, \dots, f_n)$:

$$f(x) = \big(x_1x_2 - r + a_1,\ x_1^4\rho(x) + x_1^2\sigma(x) + x_2,\ x_3, \dots,\ x_n\big)$$

is $\mathbb{R}^n \setminus F$, with r an integer such that $r \neq a_1 - a_j$ for $j = 1, \dots, k$, and

$$\sigma(x) = \sum_{j=3}^{n} x_j^2\ , \qquad \rho(x) = \prod_{j=1}^{k} (x_1x_2 - r + a_1 - a_j)$$

. First, suppose that $\exists\, b = (b_1, \dots, b_n) \in R^n$ such that $f(b) = p_\ell$ for some $\ell = 1, \dots, k$. Then $f_1(b) = b_1b_2 - r + a_1 = a_\ell \Rightarrow$ for $j = \ell$ we get on ρ: $b_1b_2 - r + a_1 + a_\ell = a_\ell - a_\ell \Rightarrow \rho(b) = 0$. On top of that, $f_i(b) = 0$ for $i = 2, \dots, n$. Thus, since $f_i \equiv \text{id}$ for $i = 3, \dots, n$ we get that $b_i = 0$ when $i = 3, \dots, n \Rightarrow \sigma(b) = 0$. Now, since σ and ρ are null: $f_2(b) = b_2$, and $f_2(b) = 0$, so $b_2 = 0 \Rightarrow$ looking to $f_1(b)$: $a_1 - r = a_\ell$, or $r = a_1 - a_\ell$, which is a contradiction. So $\text{im}(f) \subset \mathbb{R}^n \setminus F$.

Conversely, let $u = (u_1, \dots, u_n) \in \mathbb{R}^n \setminus F$. We need to find a solution for the system of polynomial equations:

$$\begin{cases} f_1(x) &= x_1x_2 - r + a_1 = u_1 \\ f_2(x) &= x_1^4\rho(x) + x_1^2\sigma(x) + x_2 = u_2 \\ f_j(x) &= x_j = u_j, \quad j \geq 3 \end{cases}$$

(i) If $u_1 = a_1 - r$ then $f(0, u_2, \dots, u_n) = u$.

(ii) If $u_1 \neq a_1 - r$, looking at f_1, we can start by making the substitution

$$x_2 = \frac{u_1 - a_1 + r}{x_1} \qquad \text{and} \qquad x_j = u_j \text{ for } j \geq 3$$

. Now, we shall expand $f_2(x)$:

$$x_1^4\rho(x) + x_1^2\sigma(x) - u_2 = -x_2 = -\frac{u_1 - a_1 + r}{x_1} \implies$$
$$x_1^5\rho(x) + x_1^3\sigma(x) - u_2x_1 + (u_1 - a_1 + r) = 0,$$

but then we get $\displaystyle\prod_{j=1}^{k} (u_1 - a_j)$ and $\sigma(x) = \sigma(u)$.

Now it is clear that x_1 must be a nonzero root of the polynomial:

$$Q(T) = \left(\prod_{j=1}^{k}(u_1 - a_j)\right) T^5 + \sigma(u)T^3 - u_2T + (r - a_1 + u_1)$$

, which has odd degree, if it wouldn't: $u_1 = a_j$ for some $j = 1, \dots, k$, so then $Q(T)$ has degree 3, except if $\sigma(u) = 0 \Rightarrow u_j = 0, j = 3, \dots, n$. Then $Q(T)$ has degree 1, except if $u_2 = 0$, but that is not possible because $u \notin F$. In any case, Q has odd degree. Now, since $u_1 \neq a_1 - r \Rightarrow Q(0) = r - a_1 + u_1 \neq 0 \Rightarrow$ the root x_1 we are looking for is not null. Let b_1 be a real root of Q, we then have:

$$f\left(b_1,\ \frac{u_1 - a_1 + r}{b_1},\ u_3,\ \dots,\ u_n\right) = u$$

, as required.

$\square$

1.3 The open quadrant $\mathcal{Q}$ problem

1.3.1 Reasons behind the choice

It is remarkable that even though $(0, +\infty)$ is a polynomial image of $\mathbb{R}^2$ (by $f(x, y) = (xy - 1)^2 + x^2$, see fig. 1.2), the latter does not happen for $\mathbb{R}$.

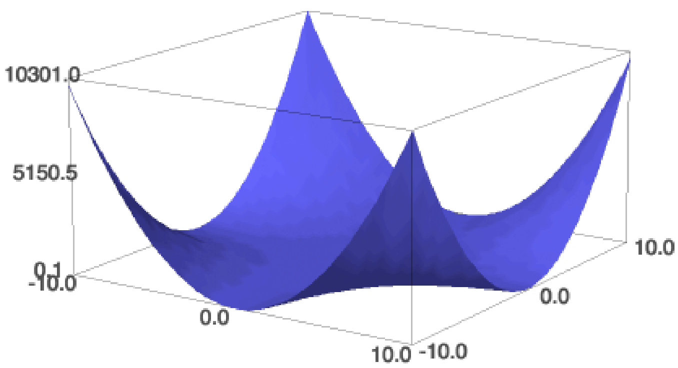


Figure 1.2: $f(x, y) = (xy - 1)^2 + x^2$.

Now, even if it holds, it does not help to obtain $\mathcal{Q}$ at all:

Remark 1.1. There is no polynomial map

$$f(P_1, P_2) : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$$

satisfying $f(\mathbb{R}^2) = \mathcal{Q}$ and $P_1(x, y) = (xy - 1)^2 + x^2$.

The proof of this remark use the Curve Selection Lemma ([AnBrRz], VIII.2.6) to approach a point $(\lambda^2, 0) \in \overline{\mathcal{Q}}$ with $\lambda > 0$, to get a contradiction.

On the topic of finding a polynomial map $\Phi : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ that satisfies $\Phi(\mathbb{R}^2) = \mathcal{Q}$, the mayor difficulty is:

$$\boxed{\textit{The closure of its image contains the positive half-axes.}} \qquad (\clubsuit)$$

Remark 1.2. Using theorem 1.3, we just need to find a polynomial map

$$\mathcal{P} = (\mathcal{F}, \mathcal{G}) : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$$

such that $\mathcal{P}(\mathbb{R}^2)$ is the disjoint union of $\mathcal{Q}$ and a set with finite preimage, say F: $\mathcal{P}(\mathbb{R}^2) = \mathcal{Q} \sqcup F$. This way we could apply the theorem and transform $\mathbb{R}^2$ into $\mathbb{R}^2 \setminus F$ with a map φ, and then use $\mathcal{P}$ to get $\mathcal{Q} \rightsquigarrow \Phi = \mathcal{P} \circ \varphi$.

We are going to give a map $\mathcal{P} = (\mathcal{F}, \mathcal{G})$ that accomplish this task, with $\mathcal{F}$ being the set $\{(-1, 0), (0, -1)\}$. If we are able to find such $\mathcal{P}$, then $(\clubsuit)$ will immediately be satisfied.

Thus, for every $\lambda, \mu \geq 0$ there will exist analytic half branch curve germs $\alpha_\lambda(s), \beta_\mu(s)$ which can not be extended to 0 and such that:

$$\lim_{s \to 0} P(\alpha_\lambda(s)) = (\lambda^2, 0) \qquad \text{and} \qquad \lim_{s \to 0} P(\beta_\mu(s)) = (0, \mu^2).$$

We can try parametrizations like:

$$\alpha_\lambda(s) = \left(s^{n_\lambda}, \frac{a_{\lambda 0} + a_{\lambda 1} s + \cdots}{s^{m_\lambda}}\right) \qquad \text{and} \qquad \beta_\mu(s) = \left(\frac{b_{\mu 0} + b_{\mu 1} s + \cdots}{s^{\ell_\mu}}, s^{k_\mu}\right).$$

Then $a_{\lambda 0}, b_{\mu 0}$ must be constants (except maybe for finitely many values of λ and μ). In view of this, we will take curves of the type:

$$\alpha_\lambda(s) = \left(s^{n_\lambda}, \frac{1 + a_{\lambda 1} s + \cdots}{s^{m_\lambda}}\right) \qquad \text{and} \qquad \beta_\mu(s) = \left(\frac{1 + b_{\mu 1} s + \cdots}{s^{\ell_\mu}}, s^{k_\mu}\right),$$

and we can choose the simplest possible curves:

$$\alpha_\lambda(s) = \left(s, \frac{1 + a_\lambda s}{s}\right) \qquad \text{and} \qquad \beta_\mu(s) = \left(\frac{1 + b_\mu s}{s}, s^3\right).$$

The following pair of polynomials:

$$\boxed{\begin{aligned} \mathcal{F}(x, y) &= (1 - x^3 y + y - x y^2)^2 + (x^2 y)^2 &&= \mathcal{F}_1^2 + \mathcal{F}_2^2 \\ \mathcal{G}(x, y) &= (1 - xy + x - x^4 y)^2 + (x^2 y)^2 &&= \mathcal{G}_1^2 + \mathcal{G}_2^2 \end{aligned}}$$

have a good behavior along these curves, meaning:

(a) · $\mathcal{F}_1 \circ \alpha_\lambda = 1 - a_\lambda - a_\lambda^2 s - s^2 - a_\lambda s^3 \in \mathbb{R}[s, a_\lambda]$.

$\mathcal{F}_1 \circ \alpha_\lambda(0) = 1 - a_\lambda$.

· $\mathcal{F}_1 \circ \beta_\mu = -3\, b_\mu s - 3\, b_\mu^2 s^2 - \big(b_\mu^3 - 1\big)s^3 - s^5 - b_\mu s^6 \in \mathbb{R}[s, b_\mu]$.

$\mathcal{F}_1 \circ \beta_\mu(0) = 0$.

(b) · $\mathcal{G}_1 \circ \alpha_\lambda = (1 - a_\lambda)s - s^3 - a_\lambda s^4 \in \mathbb{R}[s, a_\lambda]$.

$\mathcal{G}_1 \circ \alpha_\lambda(0) = 0$.

· $\mathcal{G}_1 \circ \beta_\mu = 1 - 3\, b_\mu - 6\, b_\mu^2 s - \big(4\, b_\mu^3 + 1\big)s^2 - \big(b_\mu^4 + b_\mu\big)s^3 \in \mathbb{R}[s, b_\mu]$.

$\mathcal{G}_1 \circ \beta_\mu(0) = 1 - 3b_\mu$.

(c) · $\mathcal{F}_2 \circ \alpha_\lambda = s + a_\lambda s^2 = \mathcal{G}_2 \circ \alpha_\lambda \in \mathbb{R}[s, a_\lambda]$.

· $\mathcal{F}_2 \circ \beta_\mu = s + 2\, b_\mu s^2 + b_\mu^2 s^3 = \mathcal{G}_2 \circ \beta_\mu \in \mathbb{R}[s, b_\mu]$.

· $\mathcal{F}_2 \circ \alpha_\lambda(0) = \mathcal{G}_2 \circ \alpha_\lambda(0) = \mathcal{F}_2 \circ \beta_\mu(0) = \mathcal{G}_2 \circ \beta_\mu(0) = 0$.

All of these map compositions were computed by Sage. Thus, we get these properties:

(i) The polynomials $\mathcal{F}, \mathcal{G}$ are non-negative in $\mathbb{R}^2$.

(ii) · $\mathcal{F}^{-1}(0) = \mathcal{F}_1^{-1}(0) \cap \mathcal{F}_2^{-1}(0) = \{(0, -1)\} \xmapsto{\mathcal{P}} \{(0, 1)\}$.

· $\mathcal{G}^{-1}(0) = \mathcal{G}_1^{-1}(0) \cap \mathcal{G}_2^{-1}(0) \ = \ \{(-1, 0)\} \xmapsto{\mathcal{P}} \{(1, 0)\}$.

(iii) · $P \circ \alpha_\lambda = (F \circ \alpha_\lambda, G \circ \alpha_\lambda) =$

$(\ a_\lambda^2 - 2\, a_\lambda + 1 + 2\,(a_\lambda^3 - a_\lambda^2)s + (a_\lambda^4 + 2\, a_\lambda - 1)s^2 + 4\, a_\lambda^2 s^3 + (2\, a_\lambda^3 + a_\lambda^2 + 1)s^4 + 2\, a_\lambda s^5 + a_\lambda^2 s^6, \qquad (a_\lambda^2 - 2\, a_\lambda + 2)s^2 + 2\, a_\lambda s^3 + (a_\lambda^2 + 2\, a_\lambda - 2)s^4 + 2\,(a_\lambda^2 - a_\lambda)s^5 + s^6 + 2\, a_\lambda s^7 + a_\lambda^2 s^8 \ )$.

· $P \circ \beta_\mu = (F \circ \beta_\mu, G \circ \beta_\mu) =$

$(\ (9\, b_\mu^2 + 1)s^2 + 2\,(9\, b_\mu^3 + 2\, b_\mu)s^3 + 3\,(5\, b_\mu^4 + 2\, b_\mu^2 - 2\, b_\mu)s^4 + 2\,(3\, b_\mu^5 + 2\, b_\mu^3 - 3\, b_\mu^2)s^5 + (b_\mu^6 + b_\mu^4 - 2\, b_\mu^3 + 6\, b_\mu + 1)s^6 + 12\, b_\mu^2 s^7 + 2\,(4\, b_\mu^3 - 1)s^8 + 2\,(b_\mu^4 - b_\mu)s^9 + s^{10} + 2\, b_\mu s^{11} + b_\mu^2 s^{12}, \qquad 9\, b_\mu^2 - 6\, b_\mu + 1 + 12\,(3\, b_\mu^3 - b_\mu^2)s + (60\, b_\mu^4 - 8\, b_\mu^3 + 6\, b_\mu - 1)s^2 + 2\,(27\, b_\mu^5 - b_\mu^4 + 9\, b_\mu^2 + b_\mu)s^3 + (28\, b_\mu^6 + 20\, b_\mu^3 + 6\, b_\mu^2 + 1)s^4 + 2\,(4\, b_\mu^7 + 5\, b_\mu^4 + 2\, b_\mu^3 + b_\mu)s^5 + (b_\mu^8 + 2\, b_\mu^5 + b_\mu^4 + b_\mu^2)s^6 \ )$.

The polynomials $F\circ\alpha_\lambda, G\circ\alpha_\lambda \in \mathbb{R}[s, a_\lambda]$ and $F\circ\beta_\mu, G\circ\beta_\mu \in \mathbb{R}[s, b_\mu]$ were computed with Sage. As we anticipated before, by (ii) $F = \{(-1, 0), (0, -1)\}$.

1.3.2 The proof

Proof. (of theorem 1.5)

We are going to see that $\mathcal{Q} \subset \mathcal{P}(\mathbb{R}^2)$, and to do this it is enough to fix $v > 0$, and if $\mathcal{G} = v$ then the image of $\mathcal{F}$ must contain the whole positive interval $(0, +\infty)$.

$\boxed{\textbf{Step 1}}$ *Parametrization of the curve* $\{\mathcal{G} - v = 0\}$.

We start by solving the equation $\mathcal{G} - v = 0 = (1 - xy + x - x^4y)^2 + (x^2y)^2 - v$. It has degree 2 on y, so we obtain the roots $y^+(x,v),\ y^-(x,v)$:

$$\begin{aligned} y^+(x,v) &= \frac{1 + x + x^3 + x^4 + \sqrt{\Delta(x,v)}}{x(x^2 + (x^3+1)^2)} \\ y^-(x,v) &= \frac{1 + x + x^3 + x^4 - \sqrt{\Delta(x,v)}}{x(x^2 + (x^3+1)^2)} \end{aligned}$$

where $\Delta(x,v) = \Delta_v(x) := v(x^2 + (x^3+1)^2) - x^2(x+1)^2,\ \deg_x(\Delta) = 6$.

The common domain of these two functions is defined by $D_v = \{x \in \mathbb{R} : \Delta(x,v) \geq 0, x \neq 0\}$. Let

$$\begin{aligned} \gamma_v^+ : D_v &\longrightarrow \mathbb{R} & \qquad \gamma_v^- : D_v &\longrightarrow \mathbb{R} \\ x &\longmapsto \mathcal{F}(x, y^+(x,v)) & x &\longmapsto \mathcal{F}(x, y^-(x,v)) \end{aligned}$$

Notice that $\operatorname{im}(\mathcal{F}(\{\mathcal{G} = v\})) = \operatorname{im}(\gamma_v^+) \cup \operatorname{im}(\gamma_v^-)$, so our aim is to prove that $\operatorname{im}(\gamma_v^+) \cup \operatorname{im}(\gamma_v^-) \supset (0, +\infty)$.

$\boxed{\textbf{Step 2}}$ *Main properties of* γ_v^+ *and* γ_v^-.

In this section we are going to prove that:

$$\text{(i)} \lim_{x\to\pm\infty} \gamma_v^+(x) = \lim_{x\to\pm\infty} \gamma_v^-(x) = 0.$$

$$\text{(ii)} \lim_{x\to 0} \gamma_v^+(x) = +\infty \qquad \lim_{x\to 0} \gamma_v^-(x) = \begin{cases} +\infty & \text{for } v \neq 1 \\ 4 & \text{for } v = 1 \end{cases}$$

With Sage, we can symbolically check how γ_v^+ and γ_v^- look like, getting polynomials $A_1, A_2, B_1, B_2 \in \mathbb{R}[x,v]$ and $C \in \mathbb{R}[x]$ such that:

$$\text{(a) } \gamma_v^+(x) = \frac{A_1(x,v) + B_1(x,v)\sqrt{\Delta(x,v)}}{C(x)},\ \ \gamma_v^-(x) = \frac{A_2(x,v) + B_2(x,v)\sqrt{\Delta(x,v)}}{C(x)}$$

$$\text{(b)} \quad \begin{aligned} A_1(x,v) &= A_2(x,v)\,, & \deg_x(A_1) = \deg_x(A_2) &= 24 \\ B_1(x,v) &= -B_2(x,v)\,, & \deg_x(B_1) = \deg_x(B_2) &= 21 \\ C(x) &= x^2(x^2 + (x^3+1)^2)^4\,, & \deg_x(C) &= 26 \end{aligned}$$

We proceed to study γ_v^+ and γ_v^- at the origin. Since Δ has even degree and positive leading coefficient on x, it is positive for $|x|$ large enough, so (i) holds.

Now, for $x = 0$, we get $\Delta(0,v) = v > 0 \Rightarrow 0 \in \overline{D_v}$. Also:

$\star$ $A_1(0,v) + B_1(0,v)\sqrt{\Delta(0,v)} = v(1 + \sqrt{v})^2 > 0$.

$\star$ $A_2(0,v) + B_2(0,v)\sqrt{\Delta(0,v)} = v(1-\sqrt{v})^2 \geq 0$, and it is 0 $\Leftrightarrow v = 1$.

Thus, (ii) holds (we also checked with Sage).

$\boxed{\textbf{Step 3}}$ *When $v \geq 0.28^2$ we have that im$(\gamma_v^+) \supset (0,+\infty)$.*

We are now going to study the domain D_v, in order to see whether $(\gamma_v^+) \cup \mathrm{im}(\gamma_v^-) \supset (0,+\infty)$ or not. Taking into account the definition of D_v, we need to study when $\Delta(x,v) = 0$, so it seems convinient to define:

$$v(x) = \frac{x^2(x+1)^2}{x^2+(x^3+1)^2}$$

If $x \in (-\infty, 0)$, using Laguerre's method[1] we checked that $\Delta(x, 0.28^2)$ has 4 complex roots and 2 real ones[2], with the real ones being $\delta_0 \approx 0.236$ and $\delta_1 \approx 4.336$. Thus, we get that when $v \geq 0.28^2$, $\Delta(x,v)$ has no negative roots, and moreover, it is positive $\Rightarrow (-\infty,0) \subset D_v$. But then, since γ_v^+ is continuous and recalling the limits computed in Step 2, we get that $(0,+\infty) \subset \mathrm{im}(\gamma_v^+) \subset \mathrm{im}(\gamma_v^+) \cup \mathrm{im}(\gamma_v^-)$.

$\boxed{\textbf{Step 4}}$ *When $0 < v < 0.28^2$ we have that im$(\gamma_v^-) \supset (0,+\infty)$.*

To prove that for $0 < v < 0.28^2$ we have that $(0,+\infty) \subset \mathrm{im}(\gamma_v^-)$ it is enough to prove the existence of real numbers $N_v < \delta_v$ verifying

$$\boxed{(-\infty, N_v] \cup [\delta_v, +\infty) \subset D_v \text{ and } \gamma_v^-(N_v) > \gamma_v^+(\delta_v)} \qquad (\spadesuit)$$

To prove the existance of such N_v and δ_v, we must compute the roots of $\Delta_v(x)$ in the field of Puiseux series $\mathbb{C}(\{v^*\})$, because $\overline{\mathbb{R}[x,v]} = \mathbb{C}(\{v^*\}) = \mathbb{C}(\{x^*\})$. Such roots are power series in $\mathbb{C}(\{w\})$ with $w = \sqrt{v}$, and we can take the most and the less negative roots of Δ_v in $\mathbb{R}(\{v^*\})$ that makes the infinitesimal v greater than 0, namely:

$$\begin{cases} \eta_v = -\dfrac{1}{w} + 1 + w + w^2 + \dfrac{5}{2}w^3 + \cdots \\ \xi_v = -w - w^2 - \dfrac{5}{2}w^3 - 6w^4 + \cdots \end{cases}$$

Considering the infinitesimal v, it is clear that the first coefficient of the series is the most meaningful (order wise) $\Rightarrow \eta_v < \xi_v$. Thus, and to be able to make calculations, we need to find a finite number of coefficients of the series, and relevant ones. Let

[1] Implemented with Python 2.7.

[2] The value $v_0 = 0.28^2$ comes from a careful observation of the plots figure **??**.

$$\begin{cases} N_v = -\dfrac{1}{w} + 1 + w + w^2 = \eta_v - (\dfrac{5}{2}w^3 + \cdots) < \eta_v \\ \delta_v = -w - w^2 - \dfrac{5}{2}w^3 = \xi_v - (-6w^4 + \cdots) > \xi_v \end{cases}$$

We can check on Sage that $-\infty < N_v < \delta_v < 0$ for $0 < v < 0.28^2$.

A
Auxiliary definitions and results

Definition A.1. A **real closed field** is a field R that has the 1^{st} order properties as the field of real numbers $\mathbb{R}$.

Definition A.2. A **semialgebraic set** is a subset $S \subset R^n$ (for some real closed field R) defined by a finite sequence of polynomial equations of the form:

$$\begin{cases} P_1(x_1, \dots, x_n) = 0 \\ \vdots \\ P_r(x_1, \dots, x_n) = 0 \\ Q_1(x_1, \dots, x_n) > 0 \\ \vdots \\ Q_l(x_1, \dots, x_n) > 0 \end{cases}$$

A **semialgebraic map** is a map that has semialgebraic graph. Moreover, the finite union, intersection and complement of semialgebraic sets is still a semialgebraic set.

Definition A.3 (Zariski topology)**.** It is a topology on algebraic varieties whose closed sets are the algebraic subsets of the variety. Its sets are defined as the set of solutions of a system of polynomial equations over a field R. In this topology, when we talk about the irreducibility of an element, we mean that it is not the union of two smaller sets that are closed under the Zariski topology.

Definition A.4. A set $S \subset R^n$ is said to be **pure dimensional** if its irreducible components are of the same dimension.

Definition A.5. A map f is called **proper** if the preimage of every compact set is compact. A semialgebraic map $f : f^{-1}(K) \longrightarrow K$ is called **semialgebraically proper** if the preimage $f^{-1}(C)$ of a compact and semialgebraic subset $C \subset K$ is compact. This condition is weaker than the previous one.

Definition A.6. A polynomial map is said to be **dominant** if it has a dense image.

Definition A.7. An **analytic half-branch curve germ** ([BoCoRo], VII.4) is ...

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