




















PVCorobotWork / PLC_1 [CPU 1214C DC/DC/DC]

Variabili PLC

	Nome	Tipo di dati	Indirizzo	Riten- zione	Accessi- bile da HMI/OPC UA	Scrivibile da HMI/OPC UA	Visibile in HMI Engi- neering	Controllo	Commento
	varWWW	Int	%MW0	False	True	True	True		
	PWM_Pulse_1	Int	%QW1000	False	True	True	True		
	PWM_inverse_1	Bool	%Q8.4	False	True	True	True		
	PWM_Pulse_2	Int	%QW1002	False	True	True	True		
	PWM_Pulse_3	Int	%QW1004	False	True	True	True		
	PWM_Pulse_4	Int	%QW1006	False	True	True	True		
	PWM_inverse_2	Bool	%Q8.5	False	True	True	True		
	PWM_inverse_3	Bool	%Q8.6	False	True	True	True		
	PWM_inverse_4	Bool	%Q8.7	False	True	True	True		
	position_arm_Corobot	Bool	%I1.0	False	True	True	True		
	position_arm_WebCam	Bool	%I1.1	False	True	True	True		
	ON	Bool	%M10.0	False	True	True	True		
	Comando vocale motori	Bool	%M0.1	False	True	True	True		
	OFF	Bool	%M10.1	False	True	True	True		
	ONCAM	Bool	%M10.2	False	True	True	True		
	CAMOFF	Bool	%M10.3	False	True	True	True		
	riconoscimento	Bool	%M0.2	False	True	True	True		
	STAY	Bool	%M10.4	False	True	True	True		
	Reset_robot	Bool	%M0.3	False	True	True	True		