

Table 1: Find threshold distance (d) for any robot

<b>testcase</b>	<b>d</b>	<b>comp.time</b>
12 ware12 quad57 cs=16	5	0h 46m 10s
12 ware12 quad57 cs=14	5	0h 29m 0s
12 ware12 quad57 cs=12	5	0h 16m 42s
12 ware12 quad57 cs=10	6	0h 22m 33s
12 ware12 quad57 cs=8	6	0h 12m 12s
12 ware12 quad57 cs=6	7	0h 22m 27s
12 ware12 quad57 cs=4	8	0h 25m 52s
12 ware12 quad57 cs=2	9	0h 54m 25s
12 ware12 quad57 cs=1	9	1h 4m 35s
12 ware12 turt9 cs=16	5	0h 13m 23s
12 ware12 turt9 cs=14	6	0h 11m 39s
12 ware12 turt9 cs=12	6	0h 6m 50s
12 ware12 turt9 cs=10	6	0h 4m 30s
12 ware12 turt9 cs=8	7	0h 2m 55s
12 ware12 turt9 cs=6	8	0h 4m 15s
12 ware12 turt9 cs=4	8	0h 2m 53s
12 ware12 turt9 cs=2	9	0h 2m 1s
12 ware12 turt9 cs=1	9	0h 1m 51s