

Supplementary Material: Minimizing Adaptive Regret with One Gradient per Iteration

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A Main Analysis

In this section, we provide the omitted proofs.

A.1 Proof of Theorem 1

We start our proof by investigating a new game between the learner and the adversary. In each round t , firstly the learner is asked to choose an action \mathbf{x}_t in \mathcal{D} ; next, an adversary *reveals* a loss function $L_t^e(\cdot)$, as defined in (8), instead of $f_t(\cdot)$ to the learner. Then the learner suffers a loss $L_t^e(\mathbf{x}_t)$. By definition, the SAR incurred under this new scenario is:

$$\begin{aligned} & \text{SAR}_{L_1^e, \dots, L_T^e}(\tau) \\ &= \max_{I \subseteq [T], |I|=\tau} \left\{ \sum_{t \in I} L_t^e(\mathbf{x}_t) - \sum_{t \in I} L_t^e(\mathbf{x}_*^{I,e}) \right\}. \end{aligned} \quad (26)$$

where $\mathbf{x}_*^{I,e} = \arg \min_{\mathbf{x} \in \mathcal{D}} \sum_{t \in I} L_t^e(\mathbf{x})$. Our first observation is that for any algorithm, its SAR under the new problem, as defined in (26), is an upper bound of that of the original problem, as defined in (1).

Lemma 3. *Given a parameter τ , let $\text{SAR}_f(\tau)$ and $\text{SAR}_{L^e}(\tau)$ be the SAR of any online learning algorithm which are defined in (1) and (26) respectively, then we have $\forall \tau > 0$,*

$$\text{SAR}_f(\tau) \leq \text{SAR}_{L^e}(\tau). \quad (27)$$

Proof of Lemma 3

Given τ , consider a time interval I_* , such that

$$I_* = \arg \max_{I \subseteq [T], |I|=\tau} \left\{ \sum_{t \in I} f_t(\mathbf{x}_t) - \sum_{t \in I} f_t(\mathbf{x}_*^I) \right\}. \quad (28)$$

where $\mathbf{x}_*^I = \min_{\mathbf{x} \in \mathcal{D}} \sum_{t \in I} f_t(\mathbf{x})$. By Lemma 1, we have $\forall t \in I_*$,

$$\begin{aligned} f(\mathbf{x}_t) - f(\mathbf{x}_*^{I_*}) &\leq -\frac{\gamma}{2} (\mathbf{x}_t - \mathbf{x}_*^{I_*})^\top \nabla_t \nabla_t^\top (\mathbf{x}_t - \mathbf{x}_*^{I_*}) \\ &\quad + \nabla_t^\top (\mathbf{x}_t - \mathbf{x}_*^{I_*}) \end{aligned}$$

Combining with (8), we get

$$f(\mathbf{x}_t) - f(\mathbf{x}_*^{I_*}) \leq -L_t^e(\mathbf{x}_*^{I_*})$$

Since $L_t^e(\mathbf{x}_t) = 0$, the equation above leads to

$$f(\mathbf{x}_t) - f(\mathbf{x}_*^{I_*}) \leq L_t^e(\mathbf{x}_t) - L_t^e(\mathbf{x}_*^{I_*}) \quad (29)$$

By adding things together over I_* , we have

$$\begin{aligned} \text{SAR}_f(\tau) &= \sum_{t \in I_*} \left(f(\mathbf{x}_t) - f(\mathbf{x}_*^{I_*}) \right) \\ &\leq \sum_{t \in I_*} L_t^e(\mathbf{x}_t) - \sum_{t \in I_*} L_t^e(\mathbf{x}_*^{I_*}) \\ &\leq \sum_{t \in I_*} L_t^e(\mathbf{x}_t) - \sum_{t \in I_*} L_t^e(\mathbf{x}_*^{I_*,e}) \\ &\leq \max_{I \subseteq [T], |I|=\tau} \sum_{t \in I} L_t^e(\mathbf{x}_t) - \sum_{t \in I} L_t^e(\mathbf{x}_*^{I,e}) \\ &= \text{SAR}_{L^e}(\tau) \end{aligned} \quad (30)$$

The second inequality is derived by the definition of \mathbf{x}_t^I and $\mathbf{x}_*^{I,e}$, and the third inequality is obtained by the definition of SAR_{L^e} . The proof can be finished by noticing that the (30) holds $\forall \tau > 0$.

Next, we bound the SAR of MARSL-exp under the new problem. To start with, we prove the exp-concavity of $L_t^e(\cdot)$:

Lemma 4. *If Assumptions 1 and 2 hold, then $L_t^e(\mathbf{u})$ is α' exp-concave, where*

$$\alpha' = \gamma / (1 + 2\gamma DG + \gamma^2 D^2 G^2).$$

Proof of Lemma 4

Firstly we introduce the following lemma for exp-concave functions [Hazan, 2016]:

Lemma 5. *A twice differentiable function f is α exp-concave if and only if $\nabla^2 f_t(\mathbf{x}) \succeq \alpha \nabla f(\mathbf{x}) \nabla f(\mathbf{x})^\top$.*

By (8), the gradient of $L_t^e(\mathbf{u})$ is

$$\nabla L_t^e(\mathbf{u}) = \gamma \nabla_t \nabla_t^\top (\mathbf{u} - \mathbf{x}_t) + \nabla_t, \quad (31)$$

Thus,

$$\begin{aligned} & \nabla L_t^e(\mathbf{u}) (\nabla L_t^e(\mathbf{u}))^\top \\ &= \gamma^2 \nabla_t \nabla_t^\top (\mathbf{u} - \mathbf{x}_t) (\mathbf{u} - \mathbf{x}_t)^\top \nabla_t \nabla_t^\top \\ &\quad + \gamma \nabla_t \nabla_t^\top (\mathbf{u} - \mathbf{x}_t) \nabla_t^\top + \gamma \nabla_t (\mathbf{u} - \mathbf{x}_t)^\top \nabla_t \nabla_t^\top \\ &\quad + \nabla_t \nabla_t^\top \\ &= \gamma^2 \nabla_t \left[\nabla_t^\top (\mathbf{u} - \mathbf{x}_t) \right] \left[(\mathbf{u} - \mathbf{x}_t)^\top \nabla_t \right] \nabla_t^\top \\ &\quad + \gamma \nabla_t \left[\nabla_t^\top (\mathbf{u} - \mathbf{x}_t) \right] \nabla_t^\top + \gamma \nabla_t \left[(\mathbf{u} - \mathbf{x}_t)^\top \nabla_t \right] \nabla_t^\top \\ &\quad + \nabla_t \nabla_t^\top \\ &\preceq (\gamma^2 D^2 G^2 + 2\gamma DG + 1) \nabla_t \nabla_t^\top \end{aligned}$$

On the other hand,

$$\nabla^2 L_t^e(\mathbf{u}) = \gamma \nabla_t \nabla_t^\top. \quad (32)$$

The proof is finished by using Lemma 5.

Lemma 4 indicates that the series of loss function $L_1^e(\cdot), \dots, L_T^e(\cdot)$ are all exp-concave. Besides, by the definition of $\nabla L_t^e(\cdot)$, we have $\forall \mathbf{u} \in \mathcal{D}$:

$$\|\nabla L_t^e(\mathbf{u})\| \leq \frac{5}{4}GD =: G^e \quad (33)$$

Thus, by simply applying AFLH on the new problem, according to Theorem 1.2 in [Hazan and Seshadhri, 2007], we can immediately obtain the following lemma:

Lemma 6. *Suppose Assumptions 1 and 2 hold and all functions f_1, \dots, f_T are α -exp-concave. Then, MARS-L-exp achieves:*

$$\begin{aligned} & \text{SAR}_{L_1^e, \dots, f_T^e}(\tau) \\ & \leq (\log T + 1) \left(\left(\frac{4 + 5d}{\alpha'} + dG^e D \right) \log T + 1 \right) \\ & = O\left(\frac{1}{\alpha'} \log^2 T\right) \end{aligned} \quad (34)$$

The proof of Theorem 1 can be finished by combining Lemma 3 and Lemma 6.

A.2 Proof of Theorem 2

For strongly convex functions, following the proof of Theorem 1, we define the SAR under the loss function series $L_1^{sc}(\cdot), \dots, L_T^{sc}(\cdot)$ as

$$\begin{aligned} & \text{SAR}_{L_1^{sc}, \dots, L_T^{sc}}^T(\tau) \\ & = \max_{I \subseteq [T], |I|=\tau} \left\{ \sum_{t \in I} L_t^{sc}(\mathbf{x}_t) - \sum_{t \in I} L_t^c(\mathbf{x}_*^{I, sc}) \right\}. \end{aligned} \quad (35)$$

where $\mathbf{x}_*^{I, sc} = \arg \min_{\mathbf{x} \in \mathcal{D}} \sum_{t \in I} L_t^{sc}(\mathbf{x})$. It can be easily verified that $L_1^{sc}(\cdot), \dots, L_T^{sc}(\cdot)$ are all λ strongly convex. Besides, we have $\forall \mathbf{u} \in \mathcal{D}$,

$$\|\nabla L_t^{sc}(\mathbf{u})\| = \|\lambda(\mathbf{x}_t - \mathbf{u}) - \nabla_t\| \leq \lambda D + G =: G^{sc}.$$

By Lemma 2, it implies that all surrogate losses are λ/G^{sc} -exp-concave. Thus, according to Lemma 3, we derive the following lemma:

Lemma 7. *Given a parameter τ , let $\text{SAR}_f(\tau)$ and $\text{SAR}_{L^{sc}}(\tau)$ be the SAR of any online learning algorithm which are defined in (1) and (35) respectively, then we have $\forall \tau > 0$,*

$$\text{SAR}_f(\tau) \leq \text{SAR}_{L^e}(\tau). \quad (36)$$

Next, we focus on the SAR of our algorithm under the new problem. Following Lemma 4.5 in [Hazan and Seshadhri, 2007], we have the following lemma:

Lemma 8. *Suppose Assumptions 1 and 2 hold and all functions $L_1^{sc}(\cdot), \dots, L_T^{sc}(\cdot)$ are λ strongly convex. Then, MARS-L-sc attains*

$$\begin{aligned} & \text{SAR}_{L_1^{sc}, \dots, L_T^{sc}}(\tau) \\ & \leq (\log T + 1) \left(\frac{(G^{sc})^2}{2\lambda} (\log T + 1) + 1 \right) \\ & = O(\log^2 T) \end{aligned} \quad (37)$$

The proof of Theorem 2 can be finished by combining Lemma 7 and Lemma 8.

A.3 Proof of Theorem 3

To begin with, following the proof of Theorem 1, we define the SAR under $L_t^c(\cdot), \dots, L_t^c(\cdot)$ as

$$\begin{aligned} & \text{SAR}_{L_1^c, \dots, L_T^c}(\tau) \\ & = \max_{I \subseteq [T], |I|=\tau} \left\{ \sum_{t \in I} L_t^c(\mathbf{x}_t) - \sum_{t \in I} L_t^c(\mathbf{x}_*^{I, c}) \right\}. \end{aligned} \quad (38)$$

where $\mathbf{x}_*^{I, c} = \arg \min_{\mathbf{x} \in \mathcal{D}} \sum_{t \in I} L_t^c(\mathbf{x})$. The following Lemma illustrates the relations between (38) and (1):

Lemma 9. *Given a parameter τ , let $\text{SAR}_f(\tau)$ and $\text{SAR}_{L^c}(\tau)$ be the SAR which are defined in (1) and (38), then we have $\forall \tau < T$,*

$$\text{SAR}_f(\tau) \leq 2GD (\text{SAR}_{L^c}(\tau)). \quad (39)$$

Proof of Lemma 9

Given a parameter τ , consider a time interval I_* , which is defined in (28). By Definition 2, we have $\forall t \in I_*$,

$$f(\mathbf{x}_t) - f(\mathbf{x}_*^{I_*}) \leq \nabla f(\mathbf{x}_t)^\top (\mathbf{x}_t - \mathbf{x}_*^{I_*}). \quad (40)$$

By (20), we get

$$f(\mathbf{x}_t) - f(\mathbf{x}_*^{I_*}) \leq -2GDL_t^c(\mathbf{x}_*^{I_*}) + GD.$$

Since $L_t^c(\mathbf{x}_t) = 1/2$, the equation above leads to

$$f(\mathbf{x}_t) - f(\mathbf{x}_*^{I_*}) \leq 2GD (L_t^c(\mathbf{x}_t) - L_t^c(\mathbf{x}_*^{I_*})) \quad (41)$$

By summing the inequality above in both side over I_* , we have

$$\begin{aligned} \text{SAR}_f(\tau) & = \sum_{t \in I_*} (f(\mathbf{x}_t) - f(\mathbf{x}_*^{I_*})) \\ & \leq 2GD \left(\sum_{t \in I_*} L_t^c(\mathbf{x}_t) - \sum_{t \in I_*} L_t^c(\mathbf{x}_*^{I_*}) \right) \\ & \leq 2GD \left(\sum_{t \in I_*} L_t^c(\mathbf{x}_t) - \sum_{t \in I_*} L_t^c(\mathbf{x}_*^{I_*, e}) \right) \\ & \leq 2GD \left(\max_{I \subseteq [T], |I|=\tau} \sum_{t \in I} L_t^c(\mathbf{x}_t) - \sum_{t \in I} L_t^c(\mathbf{x}_*^{I, c}) \right) \\ & = \text{SAR}_{L^c}(\tau) \end{aligned}$$

The proof can be finished by noticing that the inequality above holds $\forall \tau > 0$.

Next, we bound the SAR of our algorithm under the new problem. To start with, it is easy to verify that $L_t^c(\mathbf{u})$ is convex, since it is a linear function with respect to \mathbf{u} . Besides, by the definition of $\nabla L_t^e(\cdot)$, we have $\forall \mathbf{u} \in \mathcal{D}$,

$$\|\nabla L_t^e(\mathbf{u})\|_2 \leq \frac{1}{2D} =: G^c. \quad (42)$$

Thus, by simply applying CBCE on the new problem, according to Theorem 2 in [Jun et al., 2016], we can immediately obtain the following lemma:

Lemma 10. *Suppose Assumptions 1 and 2 hold, and all functions f_t are α exp-concave, then we have:*

$$\begin{aligned}
& \text{SAR}_{L_1^c, \dots, L_T^c}^T(\tau) \\
& \leq \sqrt{\tau} \left(\frac{12D^2G^c}{\sqrt{2}-1} + 8\sqrt{7\log T + 5} \right) \quad (43) \\
& = O\left(\sqrt{\tau \log T}\right)
\end{aligned}$$

The Proof of Theorem 3 can be finished by combining Lemma 3 and Lemma 10.