

HUDM 6026

04 – Multivariate Optimization

MLE example (11.12 on p. 339)

Find the MLE of the Gamma distribution

Let X_1, \dots, X_n be a random sample from $\Gamma(r, \lambda)$ distribution

Then the likelihood function is:

$$L(r, \lambda) = \frac{\lambda^{nr}}{\Gamma(r)^n} \prod_{i=1}^n x_i^{r-1} \exp \left(-\lambda \sum_{i=1}^n x_i \right)$$

and the log-likelihood is:

$$l(r, \lambda) = nr \log(\lambda) - n \log \Gamma(r) + (r - 1) \sum_{i=1}^n \log x_i - \lambda \sum_{i=1}^n x_i$$

MLE example (cont.)

We need to find the simultaneous solution to:

$$\frac{\partial}{\partial \lambda} l(\lambda, r) = \frac{nr}{\lambda} - \sum_{i=1}^n x_i = 0$$

$$\frac{\partial}{\partial r} l(\lambda, r) = n \log(\lambda) - n \frac{\Gamma'(r)}{\Gamma(r)} + \sum_{i=1}^n \log(x_i) = 0$$

The first equation implies that:

$$\hat{\lambda} = \frac{\hat{r}}{\bar{x}}$$

and substituting in the second equation we obtain

$$n \log\left(\frac{\hat{r}}{\bar{x}}\right) - n \frac{\Gamma'(\hat{r})}{\Gamma(\hat{r})} + \sum_{i=1}^n \log(x_i) = 0$$

The Gradient

Definition of *gradient* for a real-valued function of:

one variable: $\nabla f_1(x_1) = \left(\frac{df}{dx_1} \right)$

two variables: $\nabla f_2(x_1, x_2) = \left(\frac{df}{dx_1}, \frac{df}{dx_2} \right)$

three variables: $\nabla f_3(x_1, x_2, x_3) = \left(\frac{df}{dx_1}, \frac{df}{dx_2}, \frac{df}{dx_3} \right)$

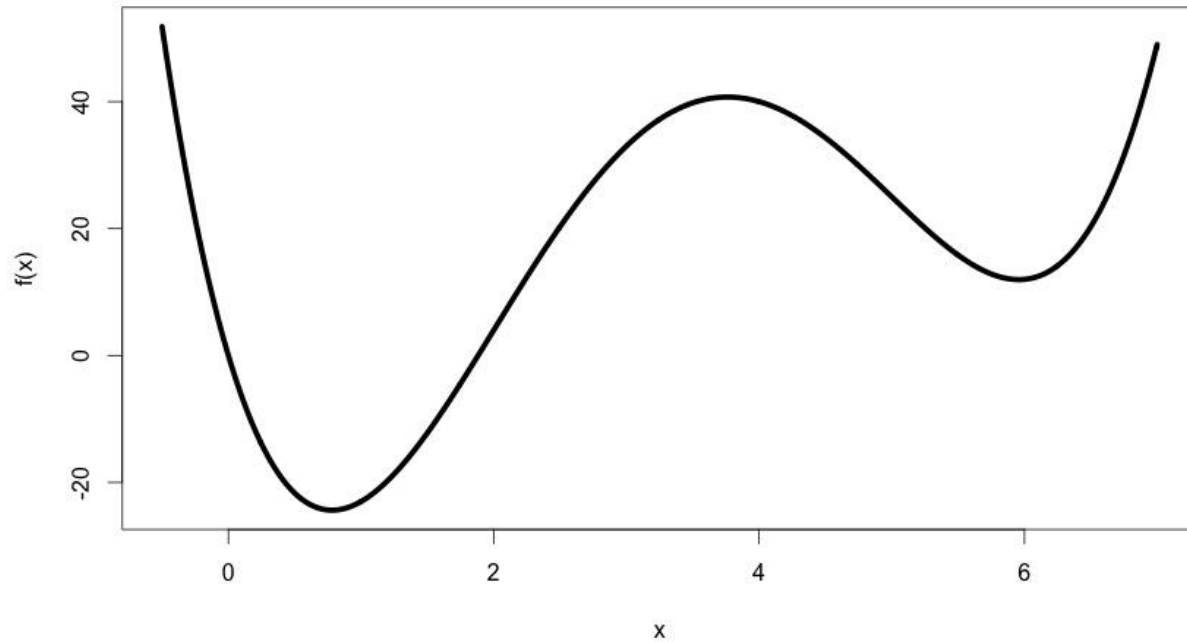
k variables: $\nabla f_k(x_1, x_2, \dots, x_k) = \left(\frac{df}{dx_1}, \frac{df}{dx_2}, \dots, \frac{df}{dx_k} \right)$

The Gradient

The gradient at x_0 represents the direction in the domain along which the function f increases the most rapidly at x_0 .

The Gradient

$$f(x) = x^4 - 14x^3 + 60x^2 - 70x, \quad \text{where } x \in [-0.5, 7]$$

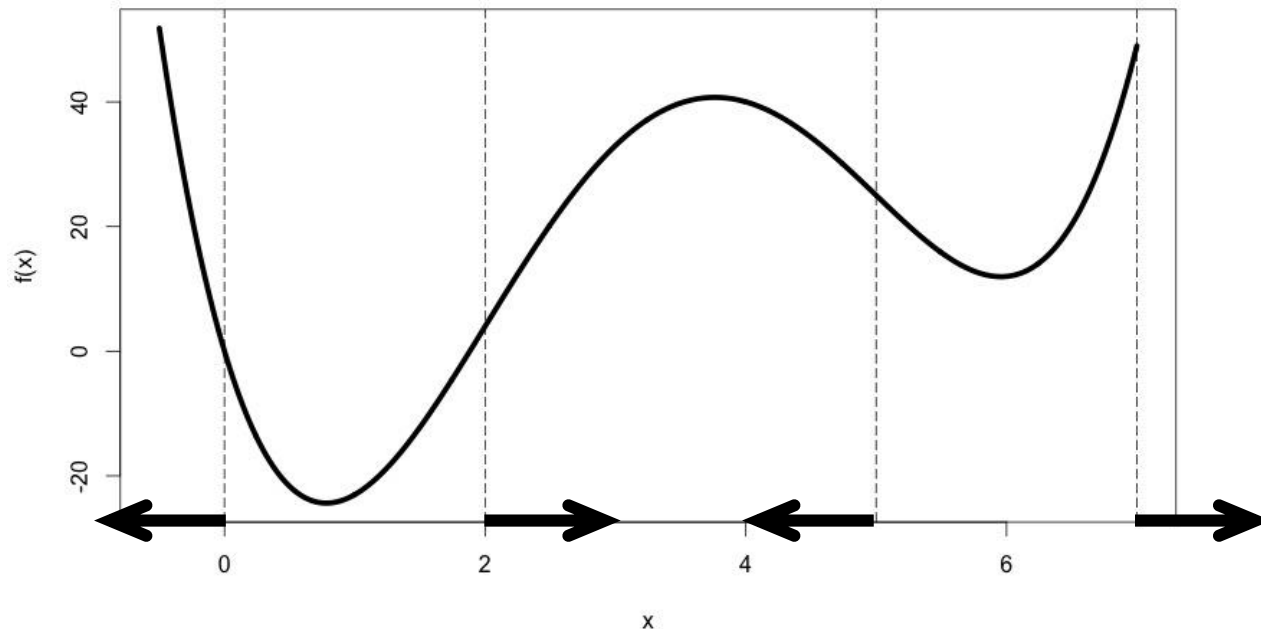


The gradient of f at x_0 is the vector that starts at x_0 and ends at the point $x_0 + f'(x_0)$.

The Gradient – Function of 1 Variable

$$f(x) = x^4 - 14x^3 + 60x^2 - 70x$$

$$f'(x) = 4x^3 - 42x^2 + 120x - 70$$



$$x_0 = 0, 2, 5, 7 \quad f'(x_0) = -70, 34, -20, 84$$

Or, expressed as unit vectors from the point of interest, -1, 1, -1, 1

The Gradient – Function of 2 Variables

To find the max of a surface we move in the direction where the surface appears to be increasing most steeply. That is, where it has the largest positive slope.

The gradient vector at (x_0, y_0) tells us the slope of the line tangent to the surface $f(x, y)$ at (x_0, y_0) in the x -direction and y -direction.

Examples:

$$\nabla f(x_0, y_0) = (5, 5)$$
$$\nabla f(x_0, y_0) = (1, 3)$$
$$\nabla f(x_0, y_0) = (-5, 5)$$

The Gradient – Function of 2 Variables

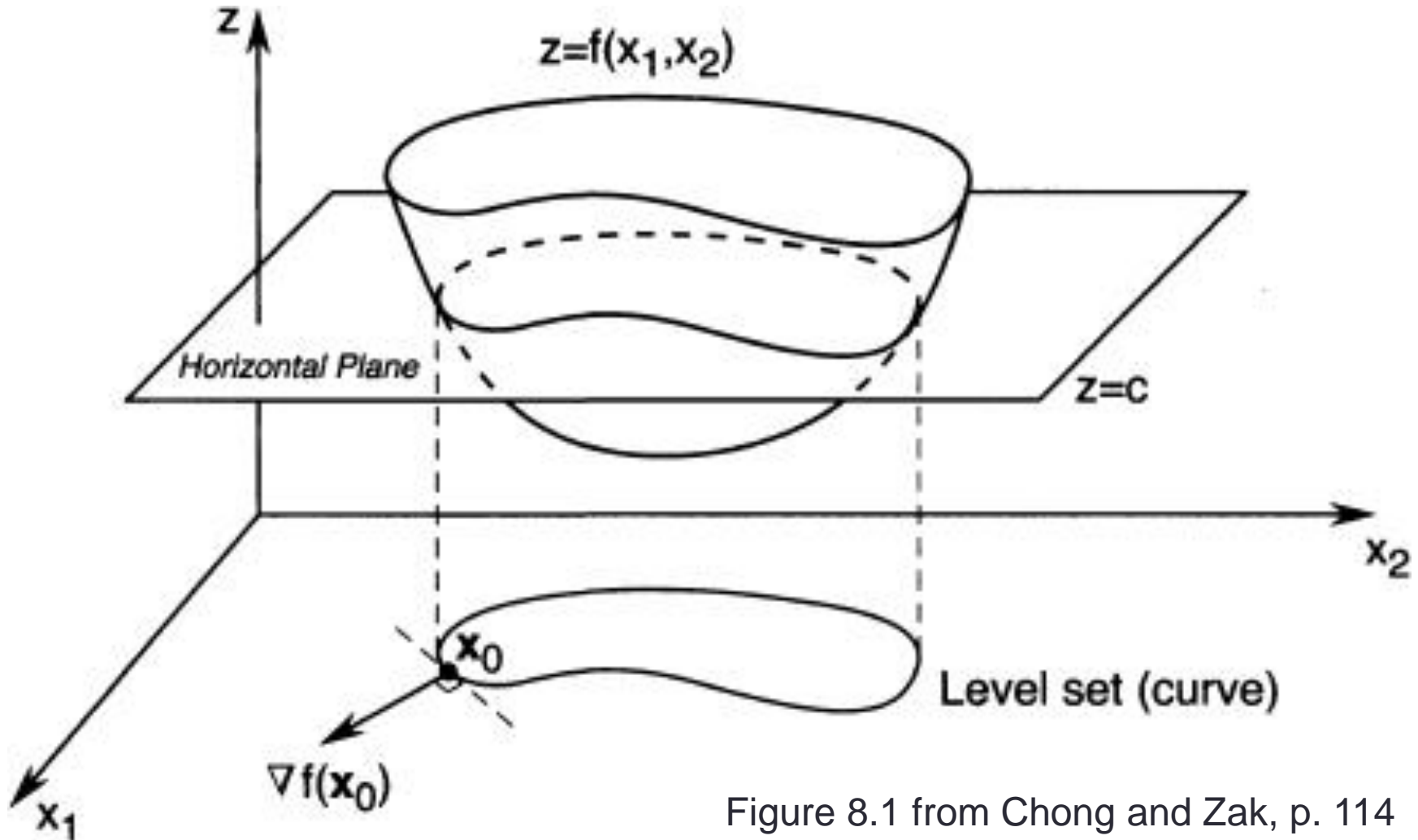


Figure 8.1 from Chong and Zak, p. 114

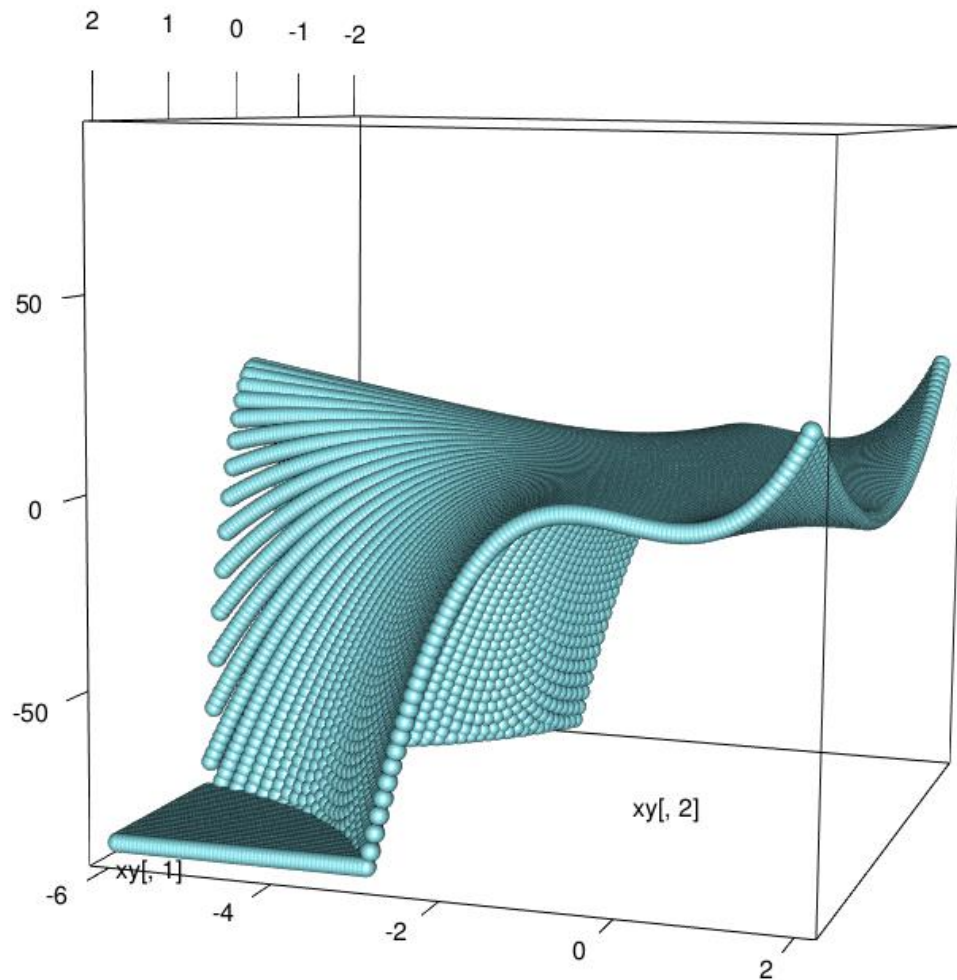
The Gradient – Function of 2 Variables

Let $f(x, y) = x^2 y^3 - 4y$

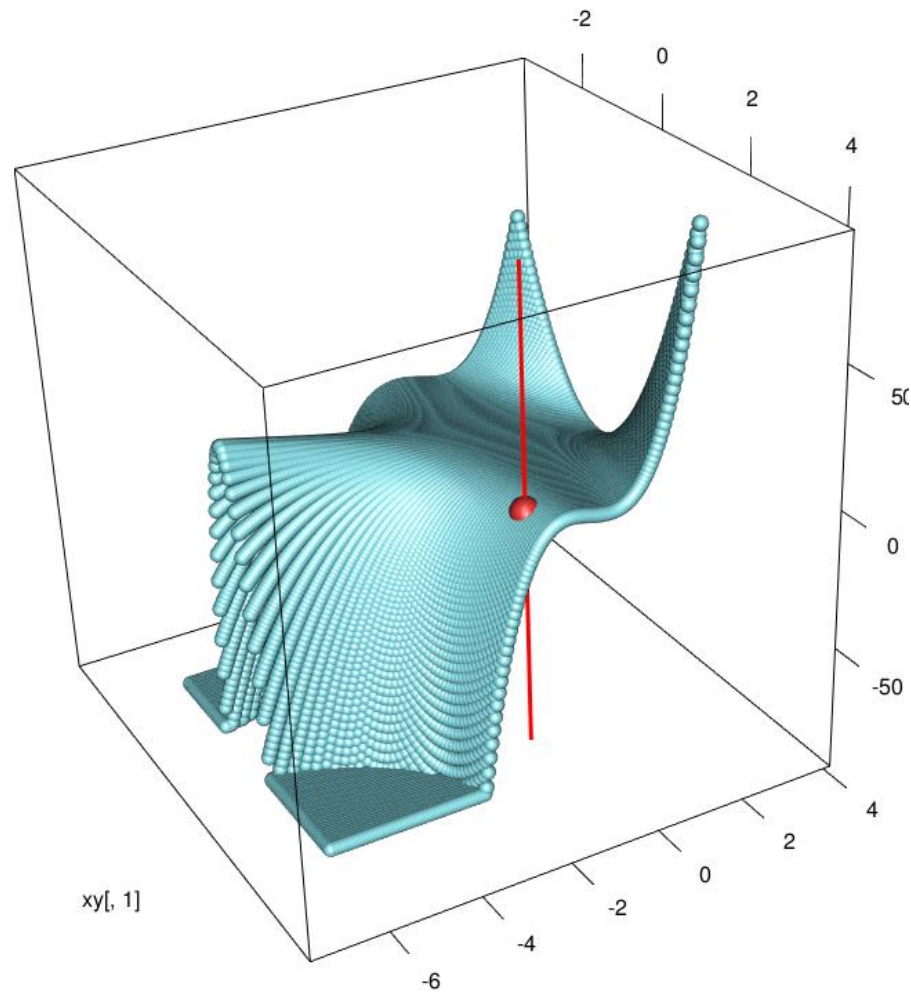
Question 1: $\nabla f(2, -1) = ?$

Question 2: how far should we move in that direction? Call the distance a 'step size' and denote it by alpha (α).

The Gradient – Function of 2 Variables

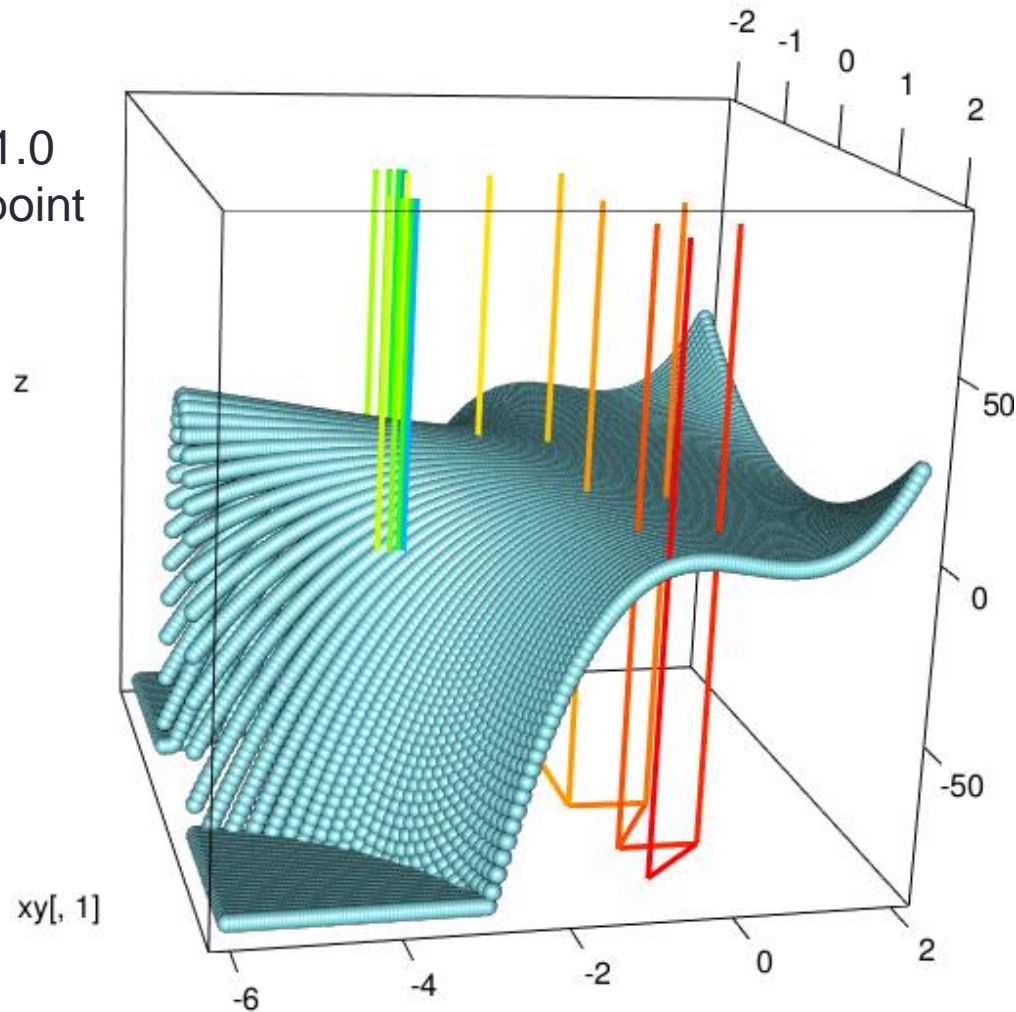


The Gradient – Function of 2 Variables



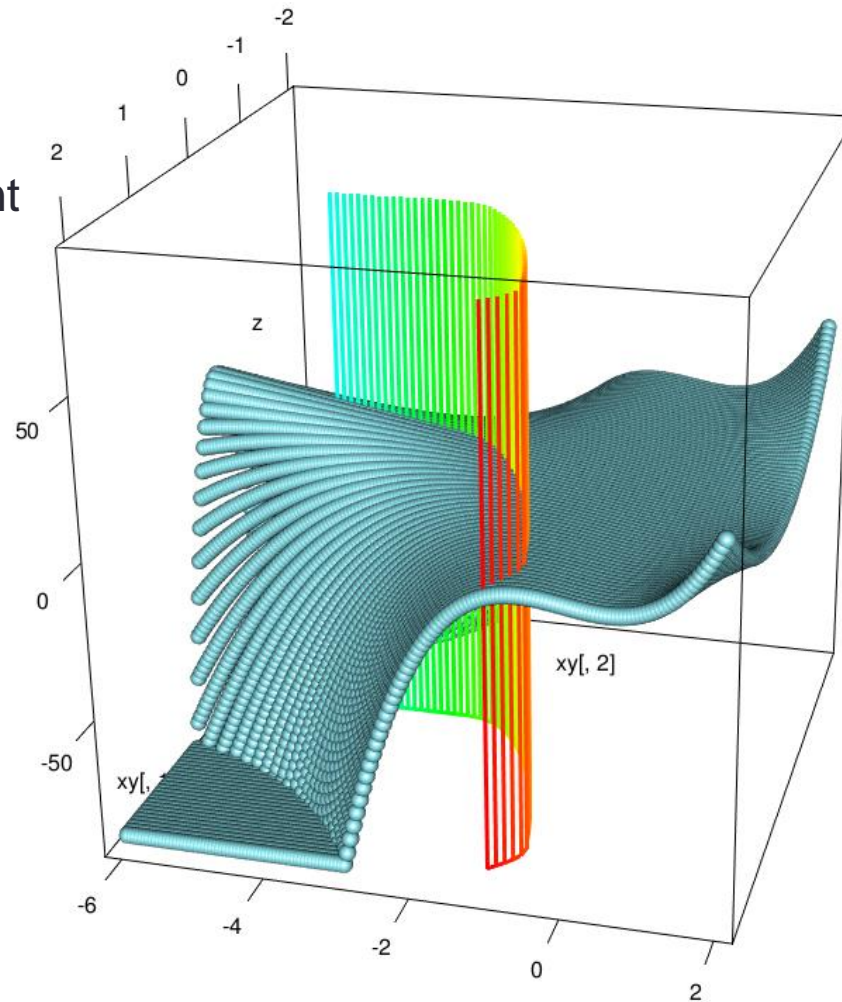
The Gradient – Function of 2 Variables

8 iterations
with $\alpha = 1.0$
and starting point
(2, -1).



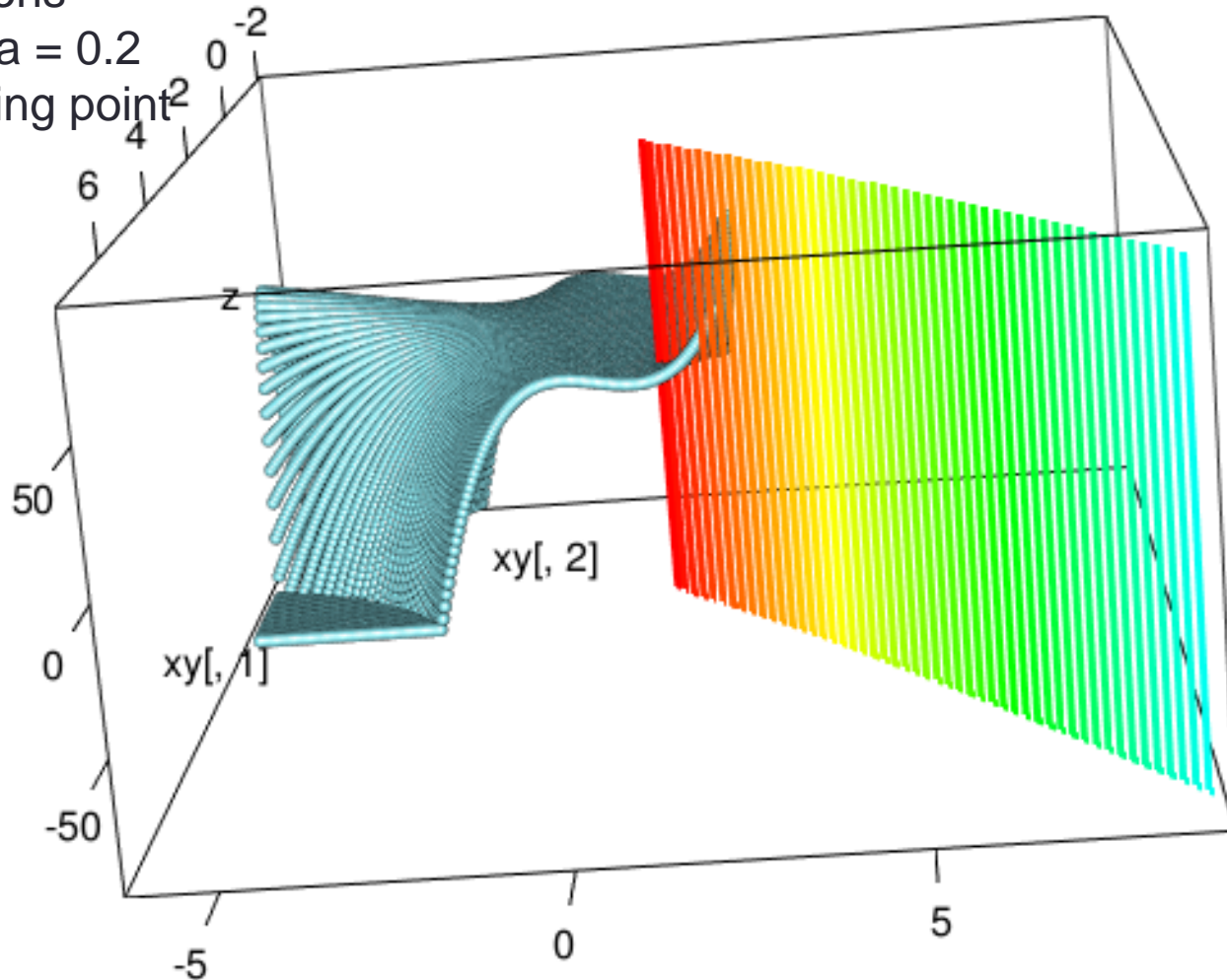
The Gradient – Function of 2 Variables

50 iterations
with $\alpha = 0.1$
and starting point
(2, -1).



The Gradient – Function of 2 Variables

50 iterations
with $\alpha = 0.2$
and starting point
(1.5, 1).



Gradient Descent (or Ascent)

The algorithm, then, consists of moving the \mathbf{x} vector along the direction of the gradient, by a step-size alpha.

So, for ascent:
$$x_{k+1} = x_k + \alpha \cdot \nabla f(x_k)$$

and, for descent:
$$x_{k+1} = x_k - \alpha \cdot \nabla f(x_k)$$

Steepest Descent

The step size α can be set equal to a constant for all iterations, or it may be allowed to vary iteration by iteration.

Definition:

If we choose the step size so that it maximizes the decrease (for minimization) in f at each step, the algorithm is called *steepest descent*.

That is, at each iteration k ,

$$\alpha_k = \operatorname{argmin}_{\alpha \geq 0} f(x_k - \alpha \cdot \nabla f(x_k))$$

Steepest Descent

$$g(\alpha) = f(x_k - \alpha \cdot \nabla f(x_k))$$

The problem of finding the best step size, alpha, is a univariate optimization problem.

Thus, we may use one of our univariate optimizers such as the secant method or the golden section method.