



Massachusetts Institute of Technology

# Work on Efficient Computer Vision Methods in FIFA 23

## 6.506 Final Presentation

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Work on Efficient Computer Vision Methods in FIFA  
23

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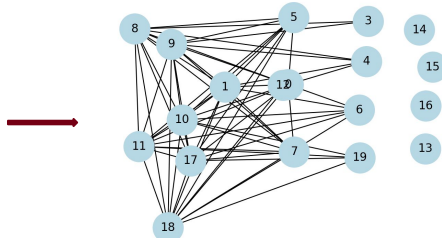
Demo Video: <https://github.com/ijga/FIFACoachBot/blob/main/demo.mov>

Github Repo: <https://github.com/ijga/FIFACoachBot>

# Overview of Project

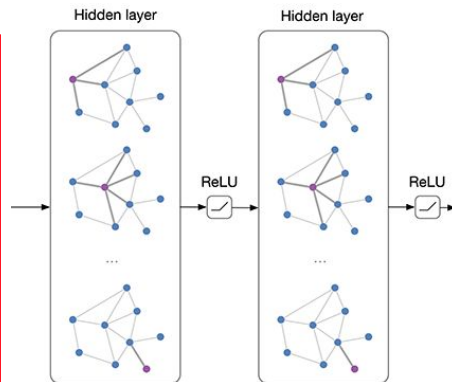
## Goal

- Quickly create high quality graph representations of soccer matches
- Create a ML coaching model that gives instant coaching based on the state of the game



## Challenges

- Finding small objects, specifically the ball
- Personal laptops have slower hardware compared to the state of the art systems



# Three Interesting Problems

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## Training a Quality CV Model

- Used bounding box object detection
- 100 images with little variability

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## Applying CV Model to Footage

- Tiling frames and processing them sequentially and in parallel
- No downscaling of frames

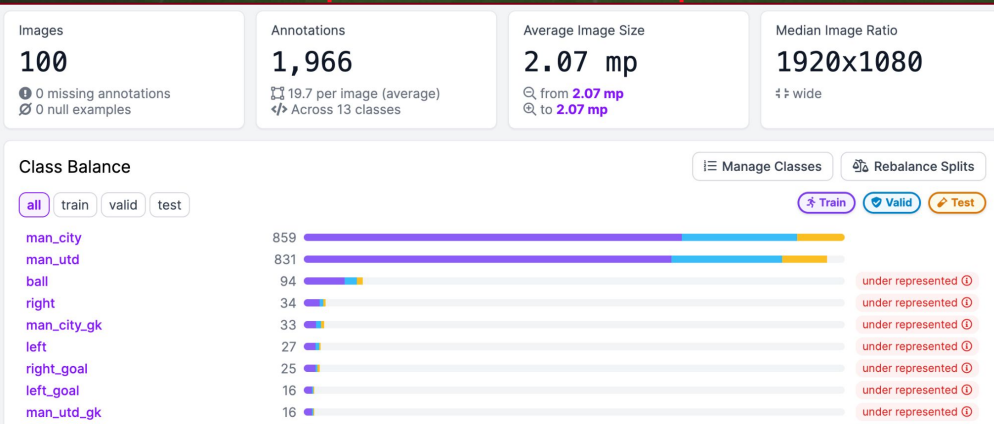
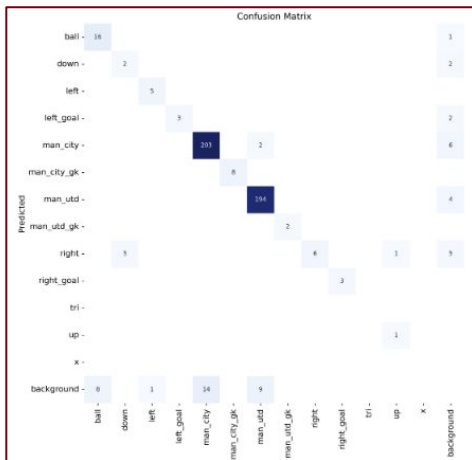
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## Consistent Representations with Different Camera Angles

- A lot of image processing to determine angle from fixed camera
- Discuss other work

# CV Model Generation with YOLOv8 and Roboflow

- **Labeled 100 images**
  - Attempted to encode controller input
- **Tiled Images 2 rows x 3 columns [1]**
- **1440 Total Images**
- **200 Epochs**



Preprocessing: Auto-Orient: Applied  
Tile: 2 rows x 3 columns

Augmentations: Outputs per training example: 3  
Blur: Up to 0px  
Noise: Up to 0.49% of pixels

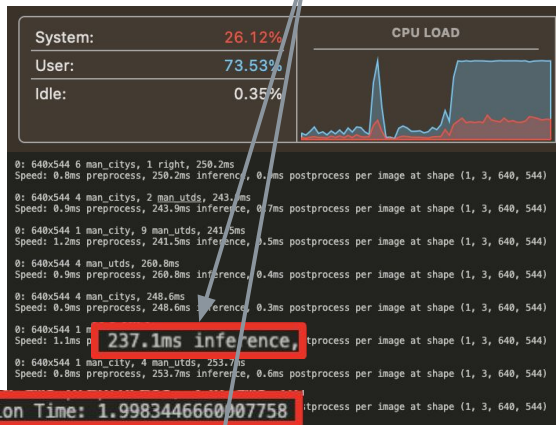
# Applying CV Model to Footage

## - Tiling [2]

### Serial

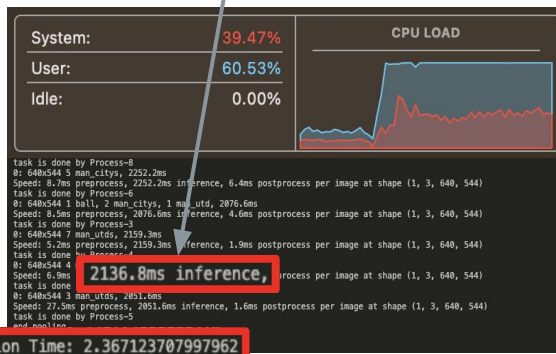
- Library implemented in parallel?

Wall-clock time to complete object detection on a tile



### Parallel [3]

- Memory sharing problems (1MB)
- Process management overhead







# Consistent Representations with Different Camera Angles

## Homography transform to project players into a non-warped frame

- Improves consistency and quality

## Time is dominated by object detection

- 60ms for dynamic homography
- 200-1500ms for object detection

## Other Steps

- Graph creation
- Duplicate bounding box deletion

## Real world applications

- One camera needed



## Conclusions

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- Very difficult to get graph representations in an quick enough time for instant coaching feedback on personal laptops
- Need to explore different computer vision models besides bounding box object detection with Yolov8
  - Yolov8 is very easy to work with
  - Image segmentation
  - Label more data to create better model
- Python multiprocessing is missing documentation for shared memory and has its limitations
  - Python is used a lot for computer vision
- Coach for end of game feedback
  - Still need performance since most frames will have no coaching insights



# Thank you!

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## References:

- [1] <https://blog.roboflow.com/detect-small-objects/#how-to-effectively-detect-small-objects>
- [2] <https://github.com/niconielsen32/tiling-window-detection/blob/main/tiling.py>
- [3] <https://www.digitalocean.com/community/tutorials/python-multiprocessing-example>