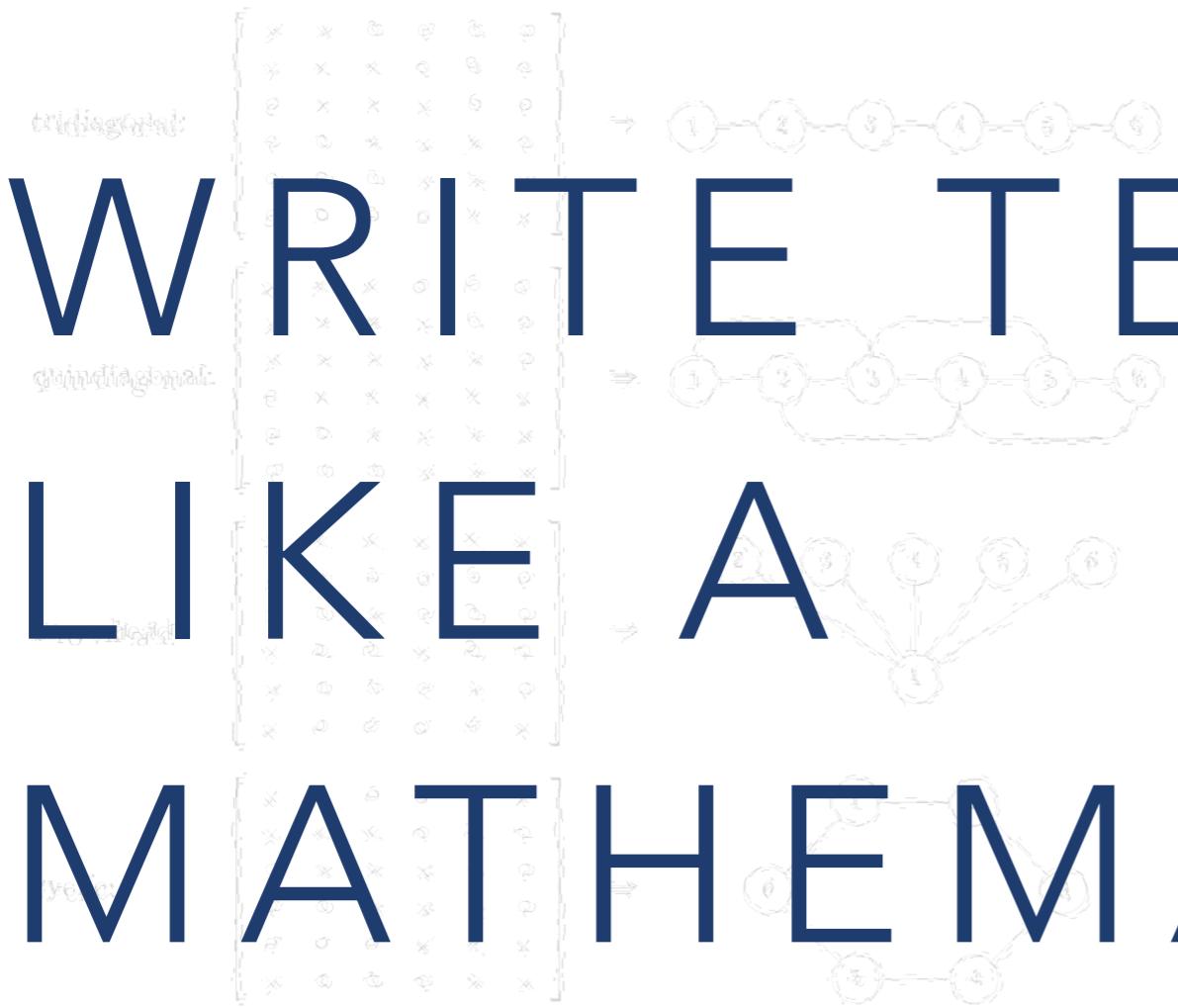


Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

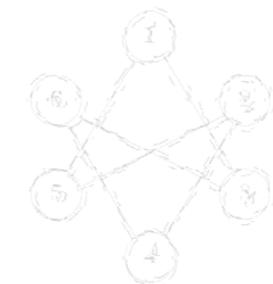


WRITE TESTS LIKE A MATHEMATICIAN

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

ISAAC J. LEE

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, first recall the relations as follows

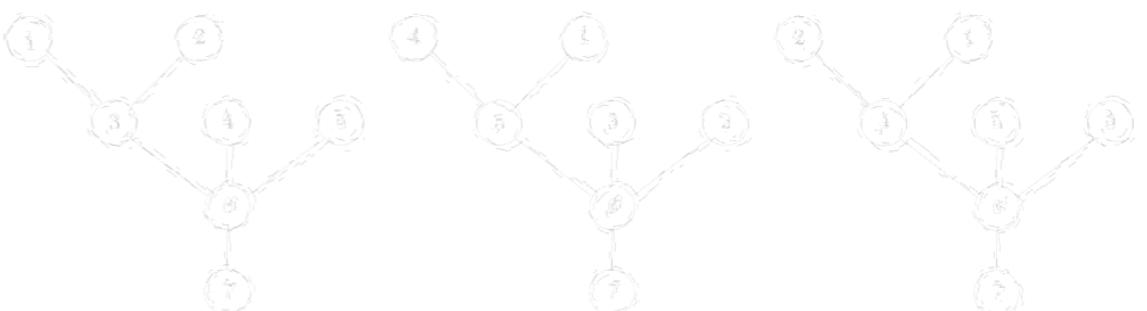
$$1 \rightarrow 2, 2 \rightarrow 3, 3 \rightarrow 4, 4 \rightarrow 5, 5 \rightarrow 6, 6 \rightarrow 1.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

Let α be an ordered set of vertices $\{\alpha_i\}_{i=1}^n$, $\beta \in \mathbb{S}$ is called a path joining the vertices α and β if $\alpha \in \{\alpha_i, \alpha_{i+1}\}_{i=1}^n$, $\beta \in \{\alpha_i, \alpha_{i+1}\}_{i=1}^n$ and for every $k = 1, 2, \dots, n-1$ the set $\{\alpha_k, \alpha_{k+1}\} \cap \{\beta_k, \beta_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that \mathbb{G} is a tree if each two members of \mathbb{V} are joined by a unique simple path. Both tridiagonal and quidiagonal matrices correspond to trees, but this is not the case with either quadiagonal or cyclic matrices when $n \geq 3$.

Given a tree \mathbb{G} and an arbitrary vertex $r \in \mathbb{V}$, the pair $\mathbb{T} = (\mathbb{G}, r)$ is called a rooted tree, while r is said to be the root. Unlike an ordinary graph, \mathbb{T} admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $\mathbb{V} \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in \mathbb{V} \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree \mathbb{T} is monotonically ordered if each vertex is labelled before all its predecessors (or, more precisely, we have the relation from the top of the tree to the root. If we have already said it, relabeling a graph is tantamount to relabeling the rows and the columns of the underlying matrix).

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three monotone orderings of the sample rooted tree:



Theorem III.1. Let \mathbb{A} be a symmetric matrix whose graph \mathbb{G} is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of \mathbb{A} have been arranged so that $\mathbb{T} = (\mathbb{G}, r)$ is monotonically ordered. Given that $\mathbb{A} = \mathbb{L}\mathbb{U}^T$ is a Cholesky factorization, it is true that

$$a_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

5 Rules of Writing Tests

Filter:

Module: Acceptance | Outline



EmberFest 18.10.2019

Running:

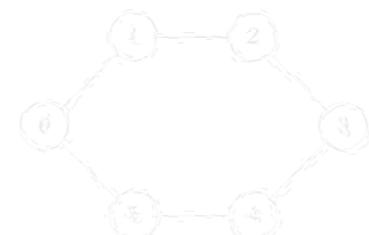
asymmetric:

$$\begin{bmatrix} 0 & 2 & 3 & 2 & 2 \\ 2 & 0 & 2 & 2 & 2 \\ 3 & 2 & 0 & 2 & 2 \\ 2 & 2 & 2 & 0 & 2 \\ 2 & 2 & 2 & 2 & 0 \end{bmatrix} \Rightarrow$$



cyclic:

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix} \Rightarrow$$



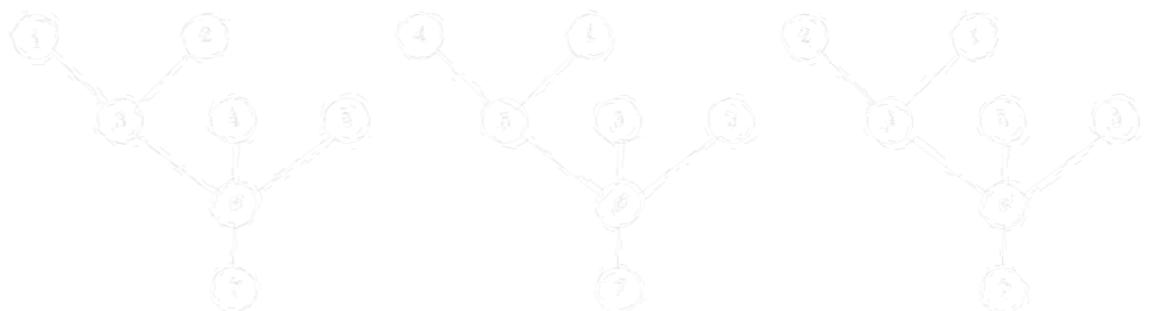
The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} 0 & 2 & * & 0 & * & 0 \\ 2 & 0 & 0 & * & x & 0 \\ * & 0 & 0 & 0 & 0 & * \\ 0 & * & 0 & 0 & 0 & * \\ * & 0 & 0 & 0 & 0 & 0 \\ 0 & * & * & 0 & 0 & 0 \end{bmatrix}.$$

At a first glance, there is nothing to think in the case of the four matrices that we have just displayed, but its graph,

which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is *monotonically ordered* if each vertex is labelled before all its predecessors; in other words, we label the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ki}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

5 Rules of Writing Tests

Filter:

Module: Acceptance | Outline

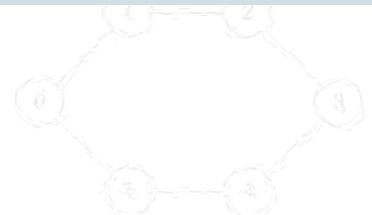
EmberFest 18.10.2019

1 assertion of 1 passed, 0 failed.

If, if, if

cyclic:

$$\begin{bmatrix} * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \end{bmatrix} \Rightarrow$$



before all its predecessors in other words: we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three monotone orderings of the same rooted tree:



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $T = (G, r)$ is monotonically ordered. Then, that $A = L U$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ki}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

At a first glance, there is nothing to think in the case of the four matrices that we have just displayed, but its graph.

5 Rules of Writing Tests

Filter:

Module: Acceptance | Outline

EmberFest 18.10.2019

2 assertions of 2 passed, 0 failed.

If, if, if

Use common, everyday words

5 Rules of Writing Tests

Filter:

Module:

Acceptance | Outline



EmberFest 18.10.2019

3 assertions of 3 passed, 0 failed.

! If, if, if

! Use common, everyday words

! Write less with theorems and new terms

$$\begin{bmatrix} * & * & * & 0 & * & 0 \\ 0 & * & 0 & * & * & 0 \\ * & 0 & * & * & 0 & * \\ 0 & * & 0 & * & * & 0 \\ * & * & 0 & * & * & 0 \\ 0 & * & * & 0 & * & * \end{bmatrix}.$$

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph:



Theorem 11.1 Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $\mathbf{T} = (G, r)$ is monotonically ordered. Then, that $A = \mathbf{L}\mathbf{U}^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

5 Rules of Writing Tests

Filter:

Module:

Acceptance | Outline



EmberFest 18.10.2019

4 assertions of 4 passed, 0 failed.

! If, if, if

! Use common, everyday words

! Write less with theorems and new terms

! All your basis are belong to us

$$\begin{bmatrix} 0 & 3 & 0 & 0 & 0 \\ 3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,

Theorem 11.1 Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $\tilde{T} = (G, r)$ is monotonically ordered. Then, that $A = \tilde{L}\tilde{U}$ is a Cholesky factorization, it is true that

$$t_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ki}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

5 Rules of Writing Tests

Filter:

Module: [Acceptance](#) | [Outline](#) ▾

EmberFest 18.10.2019

5 assertions of 5 passed, 0 failed.

! If, if, if

! Use common, everyday words

! Write less with theorems and new terms

! All your basis are belong to us

! 1 picture = 1000 words

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} * & * & * & 0 & * & * \\ 0 & * & 0 & * & * & * \\ * & 0 & * & 0 & * & * \\ 0 & * & 0 & * & 0 & * \\ * & * & 0 & 0 & * & * \\ 0 & 0 & * & * & * & * \end{bmatrix}$$

At a first glance, there is nothing to think in the case just displayed, but its graph,



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

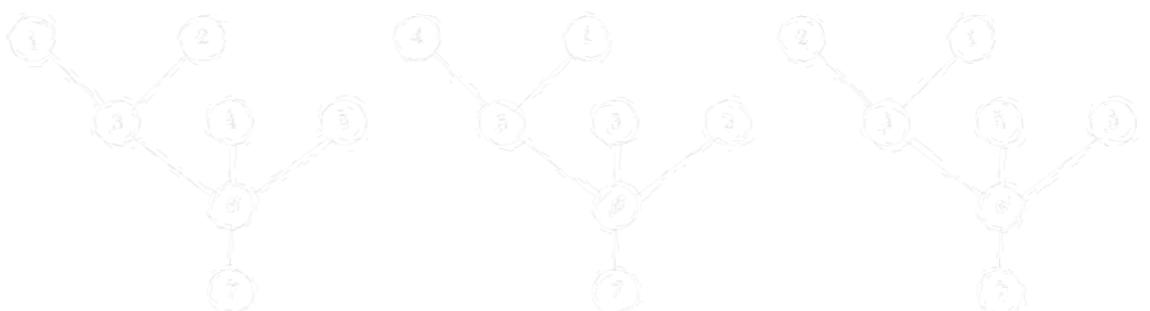
$$1 \rightarrow 1, \quad 2 \rightarrow 5, \quad 3 \rightarrow 2, \quad 4 \rightarrow 3, \quad 5 \rightarrow 6, \quad 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and quidiagonal matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in a ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A were been arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = L U$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{k,j}}{l_{j,j}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\text{IF} \quad \begin{bmatrix} * & * & 0 & 0 & 0 \\ 0 & * & * & 0 & 0 \\ * & 0 & * & 0 & 0 \\ 0 & 0 & 0 & * & * \\ 0 & 0 & 0 & * & * \end{bmatrix}.$$

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,



tells a different story – it is nothing other than a cyclic matrix in disguise. To see this, just read the weights as follows:

$$1 \rightarrow 1, 2 \rightarrow 3, 3 \rightarrow 2, 4 \rightarrow 1, 5 \rightarrow 6, 6 \rightarrow 8.$$

This, of course, is equivalent to reading the weights of the edges of the graph. An *undirected graph* $G = (V, E)$ is a set of vertices $V = \{v_1, v_2, \dots, v_n\}$ and edges $E \subseteq \{v_i, v_j\} \mid 1 \leq i, j \leq n\}$. G is called *connected* if for every two vertices $v_i, v_j \in V$ there is a path from v_i to v_j . A *cycle* in G is a vertex v_i such that there is a path from v_i to v_i that does not visit any vertex more than once. We say that G is a *tree* if for any two vertices of V there is a unique path from one to the other. Both tridiagonal and symmetric matrices correspond to trees, the case with either quadrangular or cyclic matrices when $n \geq 3$.

Given a tree, while it is natural to consider a root r in it, it can best be explained by an analogy with a family tree. Thus, the *ancestor* of all the vertices in $V \setminus \{r\}$ are the vertices and *successor* of r , every $a \in V \setminus \{r\}$ is joined to r by a single path and we designate this path, except for r and a , as a *predecessor* of a and a *successor* of r . Note that the rooted tree is *monotonically ordered*, that is, each vertex is labelled *monotonically* in other words, we label the vertices from the top of the tree. (As we have already said in relabelling a graph it is tantamount to rows and columns of the underlying matrix.)

Every node in a tree is *not a leaf* and the monotonically ordered and, in general, not a *complete* ordering of the vertices of the tree.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are then arranged so that $\mathbf{T} = (G, r)$ is monotonically ordered. Given that $A = \mathbf{L}\mathbf{U}$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & 0 \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \end{bmatrix}.$$

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,



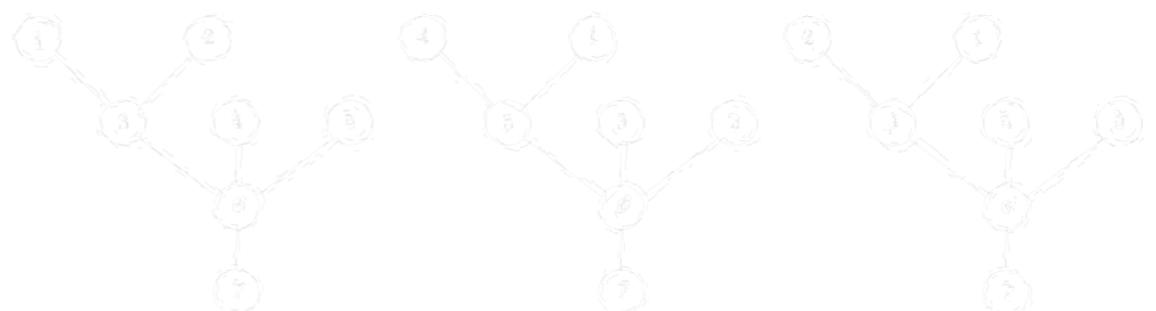
tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ in \mathbb{G} is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_{k+1}, j_{k+1}\} \cap \{i_k, j_k\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that \mathbb{G} is a tree if each two members i, j are joined by a unique simple path. Both tridiagonal and quidiagonal matrices correspond to trees; this is not the case with either quidiagonal or cyclic matrices.

Let \mathbb{G} be a tree and an arbitrary vertex $r \in V$. The pair $T = (\mathbb{G}, r)$ is called a rooted tree, where r is said to be the root. Unlike in a cyclic graph, there is no unique path from a vertex to the root. This can best be explained by an example. Let \mathbb{G} be a tree with r as the root, which is the predecessor of all the vertices in $V \setminus \{r\}$. Then r is the root of \mathbb{G} . Moreover, every $v \in V \setminus \{r\}$ is joined to r by a unique path, which consists of vertices along this path. We say that the rooted tree T is monotonically ordered if every vertex v is a predecessor of r and all its predecessors in other words, v is layered above r . We call r its root. (As we have already said, it, relabelling a graph, is possible to permute the rows and the columns of the underlying matrix.) Every rooted tree will be monotonically ordered and, in general, we can hope to give three consecutive snapshots of the construction of T .



Theorem 11.1. Let A be a symmetric matrix whose graph \mathbb{G} is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are then arranged so that $T = (\mathbb{G}, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{j,j}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their analysis.

1

```
assert.speaker().getsPersonal();  
  
await sing('Happy Birthday');  
  
assert.audience().isHappy();
```

just displayed, but its graph:

$$t_{k,j} = \frac{q_{kj}}{q_j}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

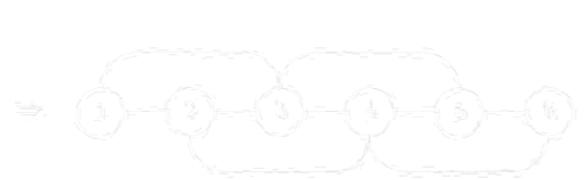
Therefore we will now give a few examples of matrices (represented by their sparsity)

and their graphs.

SUSPECT 1

quindiagonal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ * & * & * & * & * & 0 \\ * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & * \end{bmatrix}$$



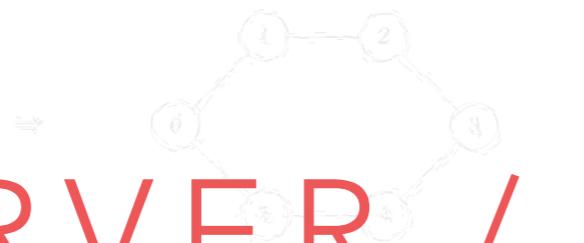
symmetric:

$$\begin{bmatrix} * & * & * & * & * & * \\ * & * & 0 & 0 & 0 & 0 \\ * & 0 & * & 0 & 0 & 0 \\ * & 0 & 0 & * & 0 & 0 \\ * & 0 & 0 & 0 & * & 0 \\ * & 0 & 0 & 0 & 0 & * \end{bmatrix}$$



cyclic:

$$\begin{bmatrix} * & 0 & 0 & 0 & * & * \\ * & * & 0 & 2 & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ 0 & * & * & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$

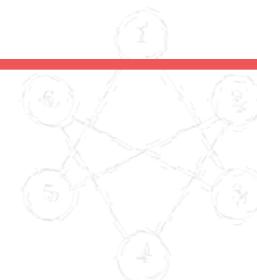


OBSERVER /

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

COMPUTED

At a first glance, the matrix A and its structure of the lower triangular matrix just displayed, but its graph,



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, \quad 2 \rightarrow 5, \quad 3 \rightarrow 2, \quad 4 \rightarrow 3, \quad 5 \rightarrow 6, \quad 6 \rightarrow 8.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tri-diagonal and any other matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{k,j}}{l_{j,j}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their up to

SUSPECT 2



EMBER DATA

FORM BUILDER

As a final step, we can use `addGraph` to add the graph of the function to the `Diagram` object that we have just displayed, but its graph.

$$t_{k,j} = \frac{a_{k,j}}{f_{k,j}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (01.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

and their graphs.

SUSPECT 3



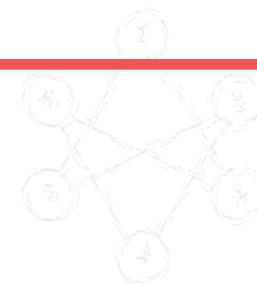
UNSETTLED

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix



At a first glance, the matrix does not reveal much about its structure, but the graph is quite interesting.

just displayed, but its graph.



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 1.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ $\subseteq \mathbb{E}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that \mathbb{G} is a tree if each two members of \mathbb{V} are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree \mathbb{T} and an arbitrary vertex $r \in \mathbb{V}$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in \mathbb{V} \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph \mathbb{G} is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A were then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their up to

SUSPECT 4

1. **EST**

LEAKAGE

After a `print` statement, it will return the `dict` structure of the flowchart, but in this case, it is just displayed, but its graph.

$$t_{k,j} = \frac{a_{k,j}}{f_{k,j}}, \quad k = j+1, j+2, \dots, \hat{j}, \quad j = 1, 2, \dots, d-1. \quad (01.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

and their graphs.

SUSPECT 5



ADMIN

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

PRIVILEGE

At a first glance, this is nothing but the structure of the famous 0-1 matrix just displayed, but its graph:



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

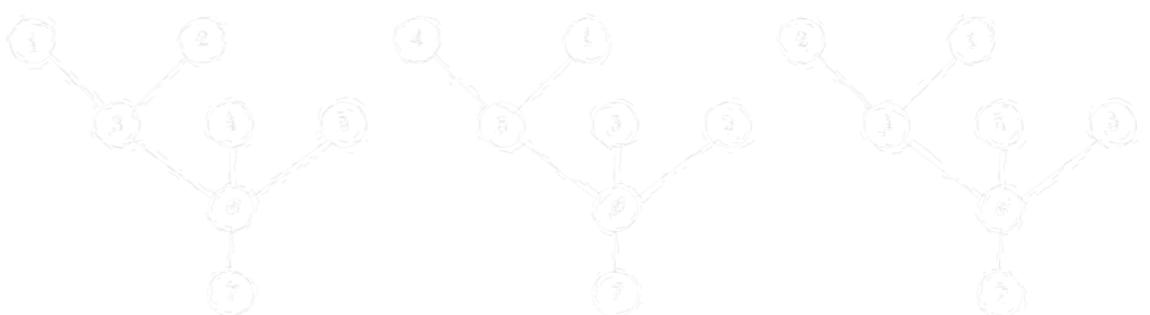
$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 7.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in a ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

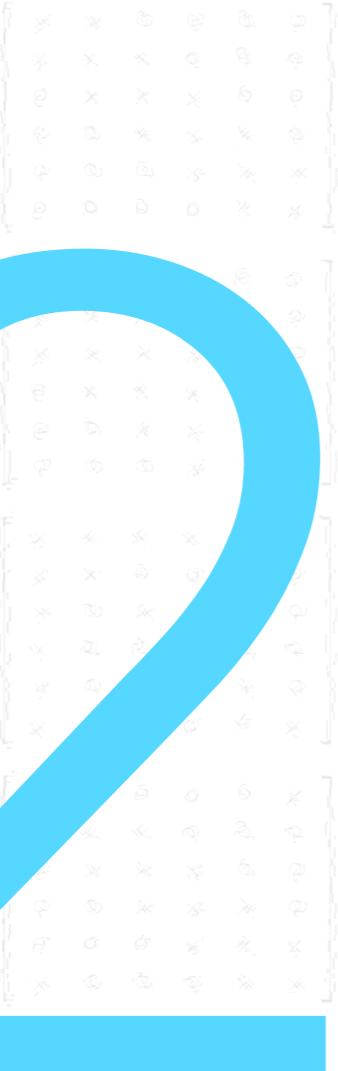
Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree:

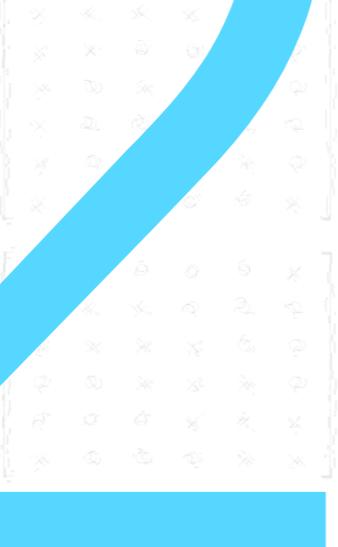


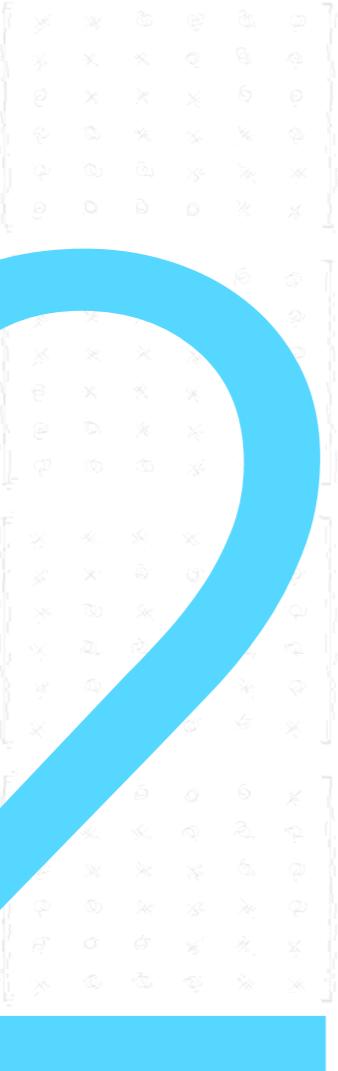
Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

tridiagonal:


symmetric:


cyclic:


2

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix



At a first glance, there is nothing to link it to any of the three structures just displayed, but its graph,

USE COMMON EVERYDAY WORDS



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{v_i, v_j\}_{i < j}$ in \mathbb{S} is called a path joining the vertices v_i and v_j ($i, j \in \mathbb{N}$). If $v_i = v_j$ and the edge $\{v_i, v_i\} = \{v_i, v_i\}$ is a member of \mathbb{S} , it is a simple path if it does not visit any vertex more than once. We say that \mathbb{G} is tree if each two members of \mathbb{V} are joined by a unique simple path. (In this case, \mathbb{G} and any other matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $p \geq 3$.)

Given a tree \mathbb{G} and an arbitrary vertex $r \in \mathbb{V}$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $\mathbb{V} \setminus \{r\}$ and these vertices are successors of r . Moreover, every $v \in \mathbb{V} \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and v , as a predecessor of v and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we label the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is unique. To give the precise definition of the unique rooted tree,



Theorem 1. Let A be a symmetric matrix whose graph \mathbb{G} is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = L U$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{k,j}}{l_{j,j}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

triangular: $\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & * & 0 \\ 0 & 0 & 0 & 0 & 0 & * \end{bmatrix} \Rightarrow \begin{array}{c} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{array} \rightarrow 1-2-3-4-5-6$

quidiagonal: $\begin{bmatrix} * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ * & * & * & * & * & 0 \\ 0 & * & * & * & * & * \\ 0 & 0 & * & * & * & * \\ 0 & 0 & 0 & * & * & * \end{bmatrix} \Rightarrow \begin{array}{c} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{array} \rightarrow 1-2-3-4-5-6$

superdiagonal: $\begin{bmatrix} * & * & * & * & * & * \\ * & 0 & 0 & 0 & 0 & 0 \\ * & 2 & 0 & 0 & 0 & 0 \\ * & 2 & 2 & 0 & 0 & 0 \\ * & 2 & 2 & 2 & 0 & 0 \\ * & 2 & 2 & 2 & 2 & 0 \end{bmatrix} \Rightarrow \begin{array}{c} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{array} \rightarrow 1-2-3-4-5-6$

cyclic: $\begin{bmatrix} * & 0 & 0 & 0 & * & * \\ * & * & 0 & 0 & 2 & 2 \\ * & * & * & 0 & 2 & 2 \\ * & * & * & * & 0 & 2 \\ * & * & * & * & 2 & 0 \\ * & * & * & * & 2 & 0 \end{bmatrix} \Rightarrow \begin{array}{c} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{array} \rightarrow 1-2-3-4-5-6$

CONVENTION;

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

AGREED ON BY MANY

At a first glance, this is not a triangular matrix, but it is a tree structure, as the one just displayed, but its graph:



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ $\subseteq \mathbb{E}$ is called a path joining the vertices i_0 and j_0 if $i_0, j_0 \in \{1, \dots, n\}$, $i_0 \neq j_0$, $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in a ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree:



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A were been arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

tridiagonal:

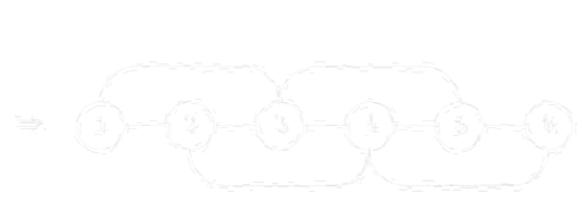
$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & 0 & * & * & 0 & 0 \\ 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & * & * \\ 0 & 0 & 0 & 0 & 0 & * \end{bmatrix}$$

EVERYDAY



quindiagonal:

$$\begin{bmatrix} * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ * & * & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



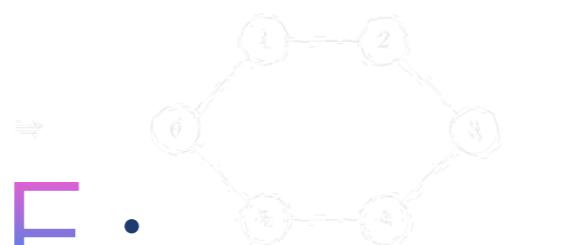
superdiagonal:

$$\begin{bmatrix} * & * & * & * & * & * \\ * & * & 0 & 0 & 0 & 0 \\ 0 & 0 & * & * & * & * \\ 0 & 0 & * & * & * & * \\ 0 & 0 & * & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



cyclic:

$$\begin{bmatrix} * & 0 & 0 & 0 & * & * \\ * & * & 0 & 2 & * & * \\ 0 & 0 & * & * & * & * \\ 0 & 2 & * & * & * & * \\ 0 & 0 & * & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



SIMPLE;

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

FAMILIAR TO MANY

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & * & * & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & * & * & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & * & * & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & * & * & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & * \end{bmatrix}$$

At a first glance this is not a matrix that is familiar to many, but it is the matrix just displayed, but its graph.



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

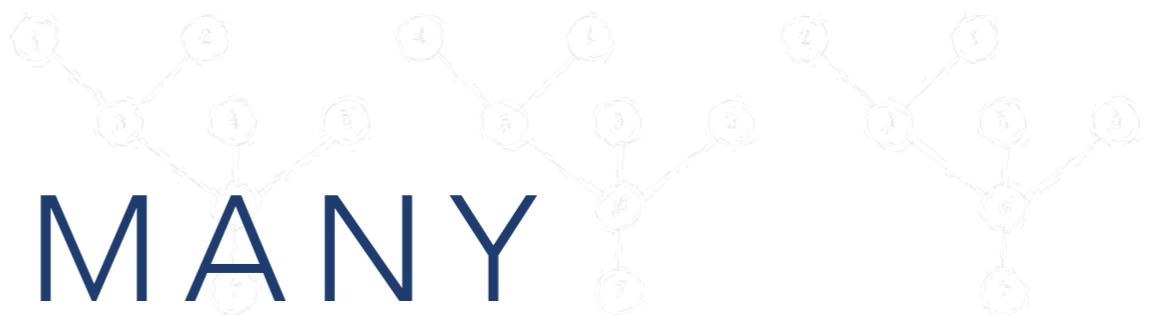
$$1 \rightarrow 1, \quad 2 \rightarrow 5, \quad 3 \rightarrow 2, \quad 4 \rightarrow 3, \quad 5 \rightarrow 6, \quad 6 \rightarrow 8.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ $\subseteq \mathbb{E}$ is called a path joining the vertices i_0 and j_0 if $i_0, j_0 \in \{1, \dots, n\}$, $i_0 \neq j_0$, $\beta \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, \nu - 1$ the set $\{i_{k+1}, j_{k+1}\} \cap \{i_k, j_k\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and quidiagonal matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in a ordinary graph, T adapts a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

triangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$

quadrangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$

cyclic:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$

At a first glance, the last matrix is not symmetric, but it is a triangular matrix, as we have just displayed, but its graph,



IF f IS CONTINUOUS IN $[a, b]$, AND IF $f(a)f(b) < 0$,

THEN f MUST HAVE A ZERO IN (a, b) .



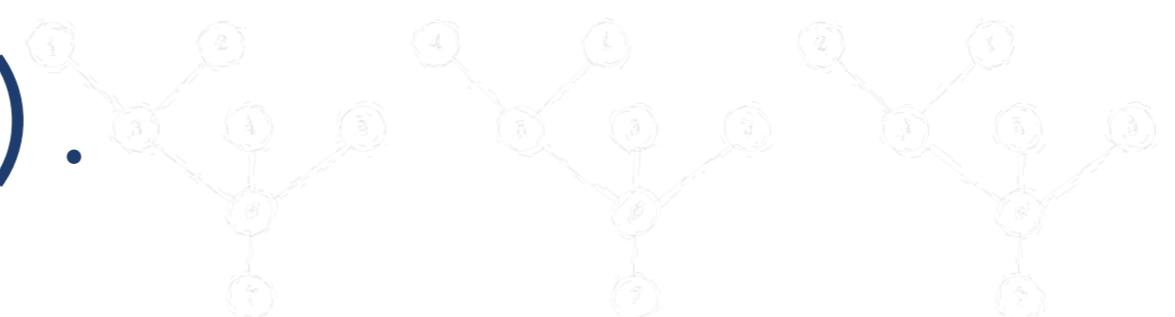
tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 3 \rightarrow 5, \quad 2 \rightarrow 4 \rightarrow 6, \quad 3 \rightarrow 1, \quad 4 \rightarrow 2.$$

Of course, it is equivalent to reordering simultaneously the equations and variables. As a result, we get the following graph G . It is called a tree spanning the vertices a and b ($a \in \{1, 2, \dots, n\}$, $b \in \{1, 2, \dots, n\}$) and for every $k = 1, 2, \dots, n-1$ the set $\{v_k, w_k\} \cap \{v_{k+1}, w_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both triangular and quadrangular matrices correspond to trees, but this is not the case with either quadrangular or cyclic matrices when $n \geq 3$.

It is natural to call a tree $T = (G, r)$ a rooted tree, where r is the root. Unlike in a binary tree, there is a natural partial order, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $V \setminus \{r\}$ and these vertices are successors of r . Moreover, every $v \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and v , as a predecessor of v and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled by an integer from 1 to n in such a way that the vertices from the top of the tree to the bottom are in increasing order. (In other words, we say the vertices from the top of the tree to the bottom are in increasing order, because from the top to the bottom, the labels increase.) Labelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree:



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

```
assert.dom('[data-test-message]')  
  .hasText(  
    'Thanks for signing up!',  
    'The user sees a welcome message.'  
  );
```

Therefore we will now give a few examples of matrices (represented by their sparsity)

triangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



quadrangular:

supersingular:

$$\begin{bmatrix} * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ * & * & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & * & * & * \end{bmatrix}$$



cyclic:

$$\begin{bmatrix} * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \end{bmatrix}$$



ZERO IN (a, b) .

$$\begin{bmatrix} * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \end{bmatrix}$$

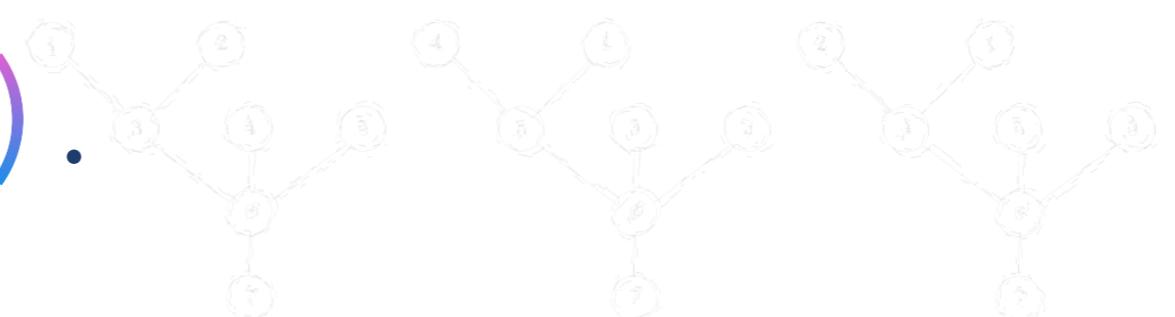
It tells a different story - it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:



It is of course, as equivalent to requiring (equivalently) the equations and variables. As you can see, the set $\{v_i, v_{i+1}\}$ is called a *pair* (spelling the vertices v_i and v_{i+1} $\in \{v_1, v_2, \dots, v_n\}$, $i \in \{1, 2, \dots, n-1\}$) and for every $i = 1, 2, \dots, n-1$ the set $\{v_i, v_{i+1}\} \cap \{v_{i+1}, v_{i+2}\}$ contains exactly one member. It is a *simple path* if it does not visit any vertex more than once. We say that G is a *tree* if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either of banded or cyclic matrices when $n \geq 3$.

It is of course, as equivalent to requiring (equivalently) the equations and variables. As you can see, the set $\{v_i, v_{i+1}\}$ is called a *pair* (spelling the vertices v_i and v_{i+1} $\in \{v_1, v_2, \dots, v_n\}$, $i \in \{1, 2, \dots, n-1\}$) and for every $i = 1, 2, \dots, n-1$ the set $\{v_i, v_{i+1}\} \cap \{v_{i+1}, v_{i+2}\}$ contains exactly one member. It is a *simple path* if it does not visit any vertex more than once. We say that G is a *tree* if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either of banded or cyclic matrices when $n \geq 3$.

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree:



Theorem 11.1 Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

At a first glance, this is not a very useful formula, but it is the basis for the following theorem.

just displayed, but its graph.

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, first relabel the vertices as follows:



Dashboard

Explore

Settings



vertices more than once. We say that G is a *tree* if each two members of V are joined by a unique simple path. Both tridiagonal and super-diagonal matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $p \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a *rooted tree*, while r is said to be the *root*. Unlike in ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the *predecessor* of all the vertices in $T \setminus \{r\}$ and these vertices are *successors* of r . Moreover, every $\alpha \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a *predecessor* of α and a *successor* of r . We say that the rooted tree T is *monotonically ordered* if each vertex is labelled before all its predecessors. In other words, if label the vertices from the root of the

'[data-test-link="Dashboard"]'

'[data-test-link="Explore"]'

'[data-test-link="Settings"]'

just displayed, but its graph.

$$t_{k,j} = \frac{a_{kj}}{a_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

Save



tridiagonal:	$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$
quidiagonal:	$\begin{bmatrix} * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ * & * & * & * & * & 0 \\ * & * & * & * & * & 0 \\ 0 & * & * & * & * & * \\ 0 & 0 & * & * & * & * \end{bmatrix}$
quidiagonal:	$\begin{bmatrix} * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ 0 & * & * & * & * & * \end{bmatrix}$



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, first relabel the vertices as follows:

$1 \rightarrow 5, 2 \rightarrow 3, 3 \rightarrow 4, 4 \rightarrow 6, 5 \rightarrow 2$.

or reordering (simultaneously) the equations and variables.

$\{(v_i, j)\}_{i,j=1}^n$ is called a path joining the vertices v_i and v_j , and for every $k = 1, 2, \dots, n-1$ the set $\{v_k, j_k\} \cap$

vertices, contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and quidiagonal matrices correspond to trees. This is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

From a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, T admits a natural partial order, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $a \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and a , as a predecessor of a and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors. In other words, if travel the vertices from the root of the

Cancel



'[data-test-button="Save"]'

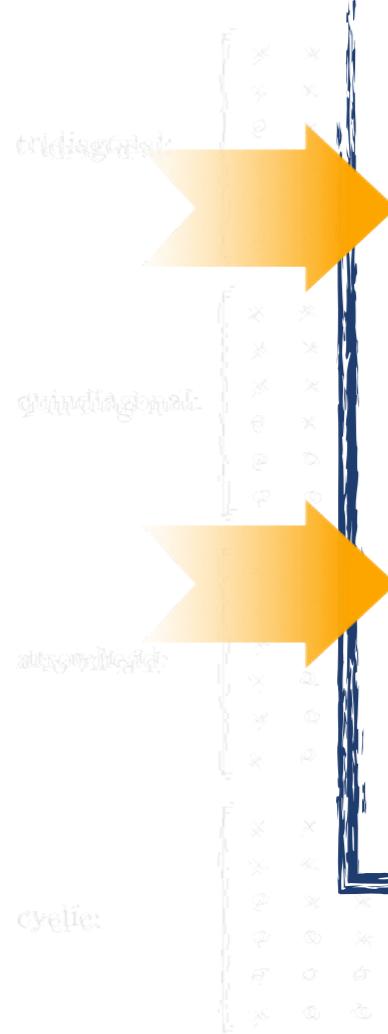
'[data-test-button="Cancel"]'

'[data-test-button="Add item"]'

just displayed, but its graph.

$$t_{k,j} = \frac{a_{k,j}}{a_{j,j}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



Name*

Description

permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the sample rooted tree.

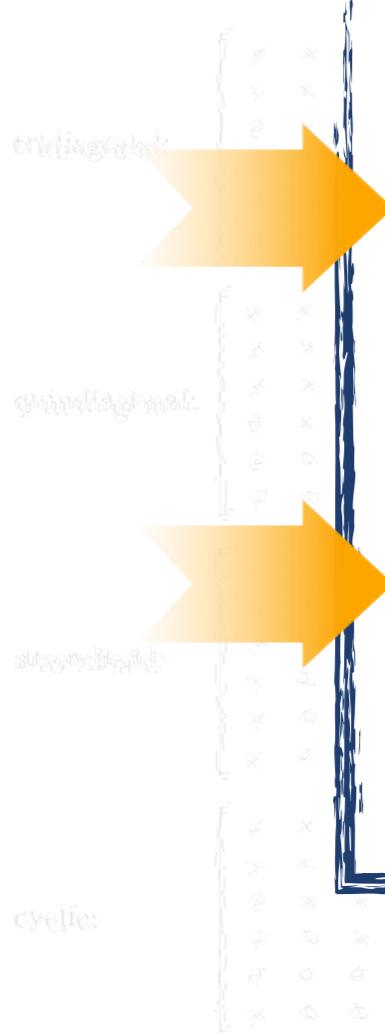
```
[data-test-field="Name"]
```

```
[data-test-field="Description"]
```

just displayed, but its graph.

$$t_{k,j} = \frac{a_{k,j}}{a_{j,j}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1, \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



Name

Little Bobby Tables

Description

Better not drop me!

matrix in disguised. To see
 $6 \Rightarrow 3$.
equations and vegetables.
th joining the vertices of
 $\{v_1, v_2, \dots, v_p\} \cap V$ in
ch if it does not visit any
numbers of V are joined by
edges correspond to trees.
atries when $p \geq 3$.
- (G, α) is called a rooted
digraph with natural partial
order. It is a family tree. Thus, the
se vertices are *successors* or
e path and we designate
son of α and a *successor*
if each vertex is labelled
from the top of the
graph is tantamount to
permuting the rows and the columns of the underlying matrix.)
Every rooted tree will be monotonically ordered and, in general, such an ordering
is not unique. We now give three monotonic orderings of the sample rooted tree.

'[data-test-field="Name"]'

'[data-test-field="Description"]'

just displayed, but its graph.

$$t_{k,j} = \frac{a_{kj}}{a_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix



At a first glance, there is nothing to think in the case just displayed, but its graph,

WRITE LESS WITH THEOREMS AND NEW TERMS

Theorem 11.1. Let A be a $n \times n$ matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are then arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = LU$ is a Cholesky factorization, it is true that

$$l_{kj} = \frac{a_{kj}}{L_{jj}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

triangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



quadrangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



supernodal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



cyclic:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



IF f IS CONTINUOUS IN $[a, b]$, AND IF $f(a)f(b) < 0$,

THEN f MUST HAVE A

ZERO IN (a, b) .



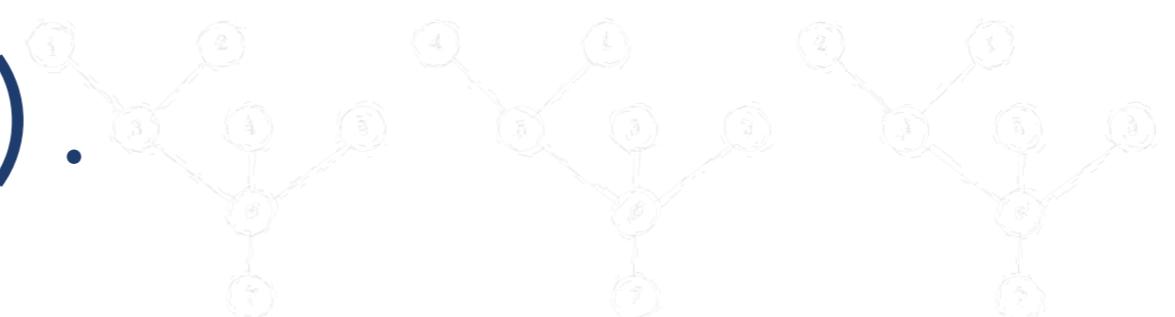
tells a different story - it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 2, 3 \rightarrow 3, 4 \rightarrow 4, 5 \rightarrow 5, 6 \rightarrow 3.$$

Of course, it is equivalent to replacing (arbitrarily) the equations and variables. As you can see from the figure, the graph G is called a tree, since the vertices a and b ($a \in V \setminus \{b\}$, $b \in V \setminus \{a\}$) and for every $k = 1, 2, \dots, n-1$ the set $\{v_1, v_2, \dots, v_k\} \cap \{v_{k+1}, v_{k+2}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either of banded or cyclic matrices when $n \geq 3$.

Of course, a tree is equivalent to a rooted tree. A vertex $r \in V$ is called a root of the tree if it is not a predecessor of any other vertex. Unlike in a binary tree, there is a natural partial order on which can be expressed by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $V \setminus \{r\}$ and these vertices are successors of r . Moreover, every $v \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and v , as a predecessor of v and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled by an integer from 1 to n in such a way that the vertices from the top of the tree to the bottom are arranged in increasing order. (In other words, we say the vertices from the top of the tree to the bottom are arranged in increasing order. Labeling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree:



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

At a first glance, this is not a very useful formula, but it is the basis for the algorithm just displayed, but its graph.

Therefore we will now give a few examples of matrices (represented by their sparsity)

PROOF. USE THE INTERMEDIATE VALUE THEOREM.

cyclic:

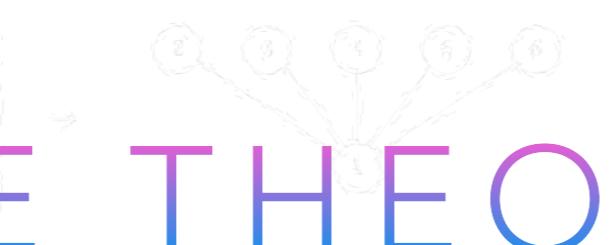
$$\begin{bmatrix} * & * & 0 & 0 & 0 \\ 0 & * & * & 0 & 0 \\ * & 0 & * & 0 & 0 \\ 0 & 0 & 0 & * & 0 \\ 0 & 0 & 0 & 0 & * \end{bmatrix}$$



$$\begin{bmatrix} * & * & 0 & 0 & 0 \\ 0 & * & * & 0 & 0 \\ * & 0 & * & 0 & 0 \\ 0 & 0 & 0 & * & 0 \\ 0 & 0 & 0 & 0 & * \end{bmatrix}$$



$$\begin{bmatrix} * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ * & 0 & * & * & 0 & 0 \\ 0 & 0 & 0 & * & 0 & 0 \\ 0 & 0 & 0 & 0 & * & 0 \\ 0 & 0 & 0 & 0 & 0 & * \end{bmatrix}$$



The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & 0 \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & 0 \\ * & 0 & * & 0 & * & 0 \\ 0 & 0 & 0 & 0 & 0 & * \end{bmatrix}$$

At a first glance this is not a cyclic matrix, but it is a bit. It is a 6x6 matrix, but it is not just displayed, but its graph.



tells a different story - it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

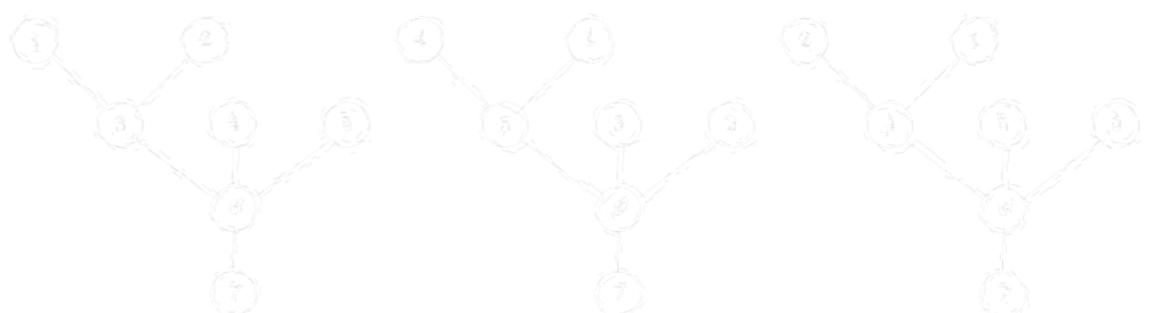
$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \mathbb{N}_0, i_0 \neq j_0}$ in \mathbb{G} is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $p = 1, 2, \dots, v-1$ the set $\{i_p, j_p\} \cap \{i_{p+1}, j_{p+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertices more than once. We say that \mathbb{G} is a tree if in two members of \mathbb{V} are joined by a unique simple path. Known tridiagonal and cyclic matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $p \geq 3$.

Given a tree \mathbb{T} and an arbitrary vertex $r \in \mathbb{V}$, the pair $\mathbb{T} = (\mathbb{G}, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, \mathbb{T} admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root is the ancestor of all the vertices in $\mathbb{V} \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in \mathbb{V} \setminus \{r\}$ is joined to r by a simple path and we designate any vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree \mathbb{T} is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree.



Therefore we will now give a few examples of matrices (represented by their sparsity)

tridiagonal: $\begin{bmatrix} * & * & 0 & 0 & 0 \\ * & * & * & 0 & 0 \\ 0 & 0 & * & * & 0 \\ 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & * \end{bmatrix}$

PROOF.

quasidiagonal: $\begin{bmatrix} * & * & 0 & 0 & 0 \\ * & * & * & 0 & 0 \\ 0 & * & * & * & 0 \\ 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & * \end{bmatrix}$

graph:

USE IVT.

quasidiagonal: $\begin{bmatrix} * & * & * & * & * \\ * & * & 0 & 0 & 0 \\ 0 & 0 & * & * & * \\ 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * \end{bmatrix}$

graph:

cyclic: $\begin{bmatrix} * & 0 & 0 & 0 & * \\ * & * & 0 & 2 & * \\ 0 & * & * & * & 0 \\ 0 & 2 & * & * & 0 \\ 0 & 0 & 0 & * & * \end{bmatrix}$

graph:

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$\begin{bmatrix} * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & 0 \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \end{bmatrix}$

At a first glance this is not a tridiagonal matrix, but it is a tridiagonal matrix, just displayed, but its graph:



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, \quad 2 \rightarrow 5, \quad 3 \rightarrow 2, \quad 4 \rightarrow 3, \quad 5 \rightarrow 6, \quad 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and quasidiagonal matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, T adapts a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree:

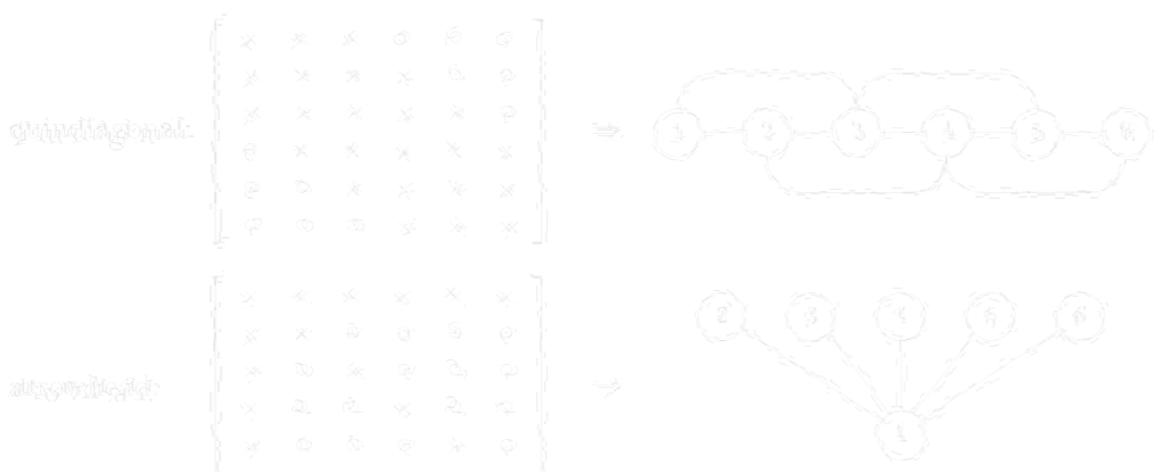


Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{j,j}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

THEOREM



PROVEN

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

TO BE TRUE

At a first glance this is a random matrix, but it has a very simple structure, just displayed, but its graph:



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

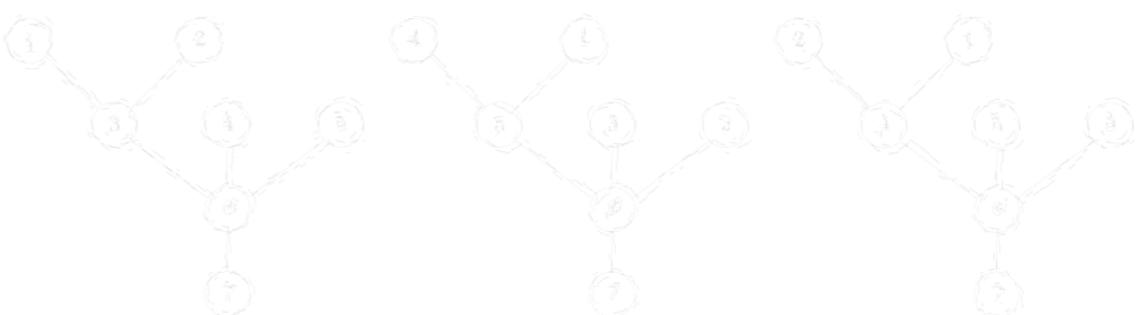
$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in a ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $a \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and a , as a predecessor of a and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree:



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A were been arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

```
import { fillIn } from '@ember/test-helpers';

export async function fillForm(fields) {
  for (const { label, value } of fields) {
    // input, textarea
    await fillIn(`[data-test-field="${label}"`, value);
  }
};
```

```
import { fillForm } from '../helpers/my-test-helpers';

...
test('User can create account', async function(assert) {
  await visit('/signup');
  await fillForm([
    { label: 'Name', value: 'Little Bobby Tables' },
    { label: 'Email', value: 'little.bobby@gmail.com' }
  ]);
  ...
});
```

Therefore we will now give a few examples of matrices (represented by their sparsity)

tri-diagonal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & 0 & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix} \Rightarrow \text{graph: } \begin{array}{c} 1 \\ \text{---} \\ 2 \text{---} 3 \text{---} 4 \text{---} 5 \text{---} 6 \end{array}$$

quindiagonal:

$$\begin{bmatrix} * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ * & * & * & * & * & 0 \\ 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix} \Rightarrow \text{graph: } \begin{array}{c} 1 \\ \text{---} \\ 2 \text{---} 3 \text{---} 4 \text{---} 5 \text{---} 6 \end{array}$$

super-diagonal:

$$\begin{bmatrix} * & * & * & * & * & * \\ * & 0 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & 0 \end{bmatrix} \Rightarrow \text{graph: } \begin{array}{c} 1 \\ \text{---} \\ 2 \text{---} 3 \text{---} 4 \text{---} 5 \text{---} 6 \end{array}$$

cyclic:

$$\begin{bmatrix} * & 0 & 0 & 0 & * & * \\ * & * & 0 & 0 & 0 & 0 \\ 0 & 0 & * & 0 & 0 & 0 \\ 0 & 0 & 0 & * & 0 & 0 \\ 0 & 0 & 0 & 0 & * & 0 \\ 0 & 0 & 0 & 0 & 0 & * \end{bmatrix} \Rightarrow \text{graph: } \begin{array}{c} 1 \text{---} 2 \text{---} 3 \text{---} 4 \text{---} 5 \text{---} 6 \text{---} 1 \end{array}$$

UBIQUITOUS

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

IDEA

At a first glance this is not a matrix, but a graph. But it is a matrix, as we have just displayed, but its graph:



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 8.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(v_i, j_i)\}_{i=1}^n$ in \mathbb{G} is called a path joining the vertices v_i and j_i if $i \in \{1, \dots, n\}$, $j_i \in \{1, \dots, n\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{v_i, j_i\} \cap \{v_{i+1}, j_{i+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that \mathbb{G} is a tree if each two members of \mathbb{V} are joined by a unique simple path. Both tri-diagonal and super-diagonal matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree \mathbb{T} and an arbitrary vertex $r \in \mathbb{V}$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, T adapts a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $\mathbb{V} \setminus \{r\}$ and these vertices are successors of r . Moreover, every $v \in \mathbb{V} \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and v , as a predecessor of v and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree:



Theorem 11.1. Let A be a symmetric matrix whose graph \mathbb{G} is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

triangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$

quadrangular:

supernodal:

cyclic:



IF f IS CONTINUOUS IN $[a, b]$, AND IF $f(a)f(b) < 0$,

THEN f MUST HAVE A

ZERO IN (a, b) .



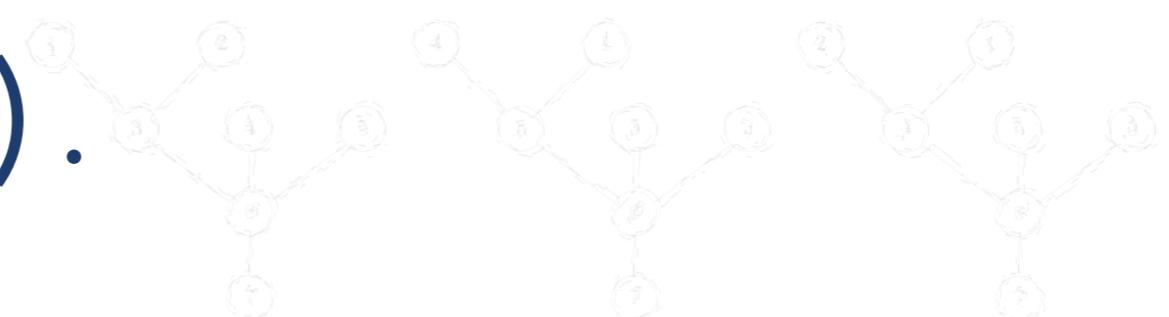
tells a different story - it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 3, 2 \rightarrow 5, 3 \rightarrow 6, 4 \rightarrow 3, 5 \rightarrow 4, 6 \rightarrow 3.$$

Of course, it is equivalent to reordering simultaneously the equations and variables. As a result, we get the following: G is called a tree if visiting the vertices α and β ($\alpha, \beta \in V \cup \{r\}$, $\beta \in V \cup \{r\}$) and for every $k = 1, 2, \dots, n-1$ the set $\{v_k, \alpha\} \cap \{v_{k+1}, \beta\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either of banded or cyclic matrices when $n \geq 3$.

As a matter of fact, a tree $T = (G, r)$ is called a rooted tree, which is to be understood in the following way. To date, a natural partial order, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $V \setminus \{r\}$ and these vertices are successors of r . Moreover, every $v \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and v , as a predecessor of v and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled by an integer from 1 to n (in other words, we say the vertices from the top of the tree to the bottom, as we have already said). Labelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree:



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are now arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

At a first glance, this is nothing but the formula of the lower triangular matrix just displayed, but its graph.

Therefore we will now give a few examples of matrices (represented by their sparsity)

triangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



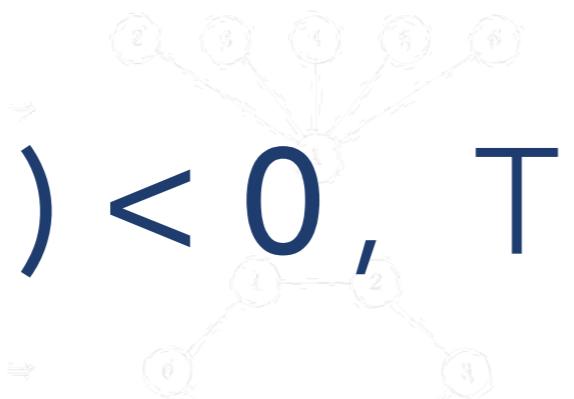
quadratic:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



triangular:

$$\begin{bmatrix} * & * & * & 0 & 0 & 0 \\ * & * & 0 & * & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



cyclic:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} * & * & * & 0 & * & 0 \\ 0 & * & 0 & * & * & 0 \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & * & 0 \\ * & * & 0 & 0 & * & * \\ 0 & * & 0 & 0 & * & * \end{bmatrix}$$



At a first glance, this is not a triangular or quadratic matrix, but it is a cyclic matrix, just displayed, but its graph:



tells a different story - it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 3, 3 \rightarrow 2, 4 \rightarrow 4, 5 \rightarrow 6, 6 \rightarrow 3.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ $\subseteq \mathbb{E}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{1, \dots, n\}$, $j_0 \in \{1, \dots, n\}$ and for every $p = 1, 2, \dots, \nu - 1$ the set $\{i_p, j_p\} \cap \{i_{p+1}, j_{p+1}\}$ contains only one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both quadiagonal and cyclic matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree G and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in a digraph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the predecessor of the vertex v is the vertex u if v is an ancestor of u (i.e., v is an offspring of u). Moreover, every $u \in G$ is the root of a path and we designate u as the parent along this path, except for r , which is a predecessor of r and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we label the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We will give three examples consisting of the same rooted tree:

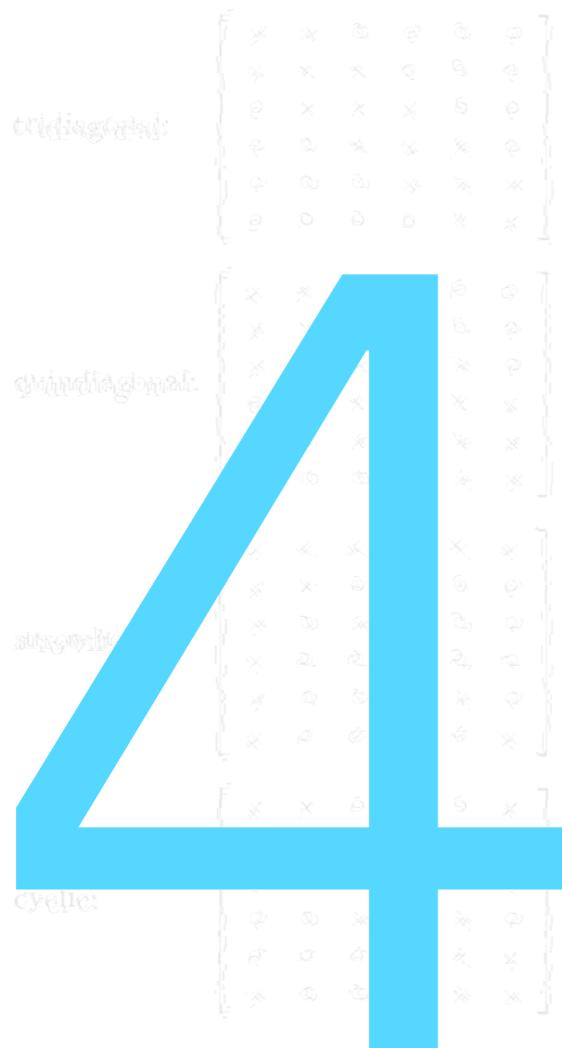


Theorem 11.1 Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

```
hooks.beforeEach(function(assert) {  
  ...  
  // Example: assert.isEnabled('Submit', 'Woot!');  
  assert.isEnabled = (label, message) => {  
    assert.dom(`[data-test-button="${label}"]`)  
      .doesNotHaveAttribute('disabled', message);  
  };  
  ...  
});
```

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \end{bmatrix}$$

At a first glance, there is nothing to link it to any of the four structures just displayed, but its graph,

ALL YOUR BASIS ARE BELONG TO US



Let us illustrate it by a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{kj} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

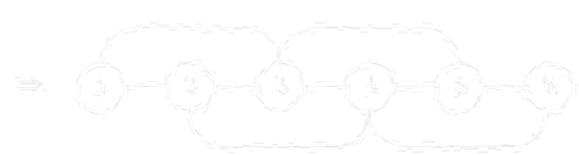
triangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



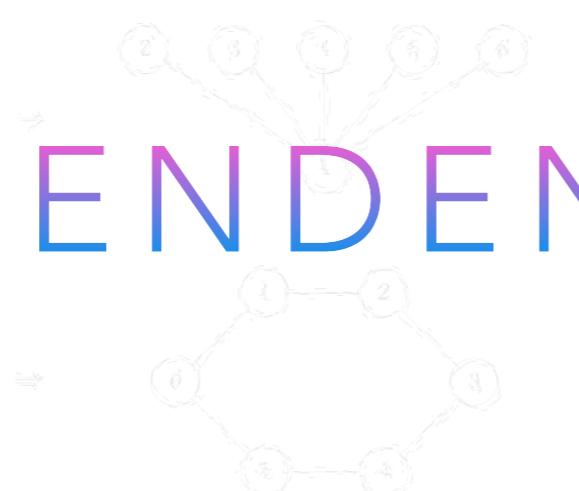
quidiagonal:

$$\begin{bmatrix} * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ * & * & * & * & * & 0 \\ 0 & * & * & * & * & * \\ 0 & * & * & * & * & * \\ 0 & 0 & * & * & * & * \end{bmatrix}$$



symmetric:

$$\begin{bmatrix} * & * & * & * & * & * \\ * & * & 0 & 0 & 0 & 0 \\ * & 0 & * & 0 & 0 & 0 \\ * & 0 & 0 & * & 0 & 0 \\ * & 0 & 0 & 0 & * & 0 \\ * & 0 & 0 & 0 & 0 & * \end{bmatrix}$$



THAT

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

SPAN THE ENTIRE SPACE

At a first glance, the matrix A in (11.1) does not look like it has a triangular structure, just displayed, but its graph,



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, \quad 2 \rightarrow 5, \quad 3 \rightarrow 2, \quad 4 \rightarrow 3, \quad 5 \rightarrow 6, \quad 6 \rightarrow 1.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(v_i, j)\}_{i=1}^n$ in \mathbb{G} is called a path joining the vertices v_i and v_j if $i \in \{1, \dots, n\}$, $j \in \{1, \dots, n\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{v_i, j\} \cap \{v_{i+k}, v_{i+k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that \mathbb{G} is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree \mathbb{G} and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the only vertex in all the paths, and the vertices are successors of r . Moreover, every $v \in V \setminus \{r\}$ is joined to r by a simple path, and we designate each vertex alone, throughout, except for r and a, as a predecessor of r and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree:



Theorem 11.1. Let A be a symmetric matrix whose graph \mathbb{G} is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A were then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



At a first glance, there is nothing to link in the case of the four matrices that we have just displayed, but its graph.



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 8.$$

Of course, it is equivalent to renumbering (cyclic shift) the vertices and to consider a different set of edges $\{ (i, j) \mid i, j \in \{1, 2, \dots, 8\} \text{ and } |i - j| \leq 2 \}$. It is called a *cycle* if the graph G contains exactly one member. It is a *simple path* if it does not visit any vertex more than once. We say that G is a *tree* if each two members of V are joined by exactly one path. Both tridiagonal and any banded matrices correspond to the case of a tree. The case with either quidiagonal or cyclic matrices when $\{1, 2, \dots, n\}$ is a cycle and no arbitrary vertex $r \in \{1, 2, \dots, n\}$ is called a *rooted tree* and r is called the *root*. Unlike in a ordinary graph, T admits a natural partial order that must be explained by an analogy with a family tree. Thus, the ancestor of all the vertices in $T \setminus \{r\}$ and these vertices are successive. Every $a \in V \setminus \{r\}$ is joined to r by a simple path and we designate this path, except for r and a , as a *predecessor* of a and a *successor* of r . The rooted tree T is *monotonically ordered* if each vertex is labelled with a natural number in other words, we label the vertices from the top of the tree to the bottom (we have already done it, relabeling a graph to obtain a tree). This is the case for any banded matrix. In general, such a ordering does not give three examples of the simple sparse trees.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{j,j}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 3, 3 \rightarrow 2, 4 \rightarrow 4, 5 \rightarrow 6, 6 \rightarrow 8.$$

Of course, it is equivalent to renumbering (cyclic shift) the vertices and the corresponding set of edges $\{ (i, i+1) \mid i \in \{1, 2, \dots, 6\} \}$. It is called a *cycle* joining the vertices $i \in \{1, 2, \dots, 6\}$, $i \neq i+1$, and for every $i = 1, 2, \dots, 6$ the set $\{i, i+1\}$ contains exactly one member. It is a *simple path* if it does not visit any vertex more than once. We say that G is a *tree* if each two members of V are joined by a *simple path*. Both tridiagonal and cyclic matrices correspond to trees. There are two types of trees: with either quiddidum or cyclic number of vertices $n \geq 3$. A *quiddidum* tree is a tree with an arbitrary vertex $r \in V$ (the root). It is called a *rooted tree* and r is said to be the *root*. Unlike in a ordinary graph, T admits a natural partial order that must be explained by an analogy with a family tree. Thus, the *ancestor* of all the vertices in $T \setminus \{r\}$ and these vertices are *successors*. Every $a \in V \setminus \{r\}$ is joined to r by a *simple path* and we designate this path, except for r and a , as a *predecessor* of a and a *successor*. The rooted tree T is *monotonically ordered* if each vertex is labelled with its *depth* in other words, we label the vertices from the top of the tree to the bottom (we have already done it, relabeling a graph to a tree). (This is another reason to call a tree a *partial order* and, in general, such a ordering is called a *topological ordering* of the simple directed tree.)

LATITUDE

30.267°

LONGITUDE

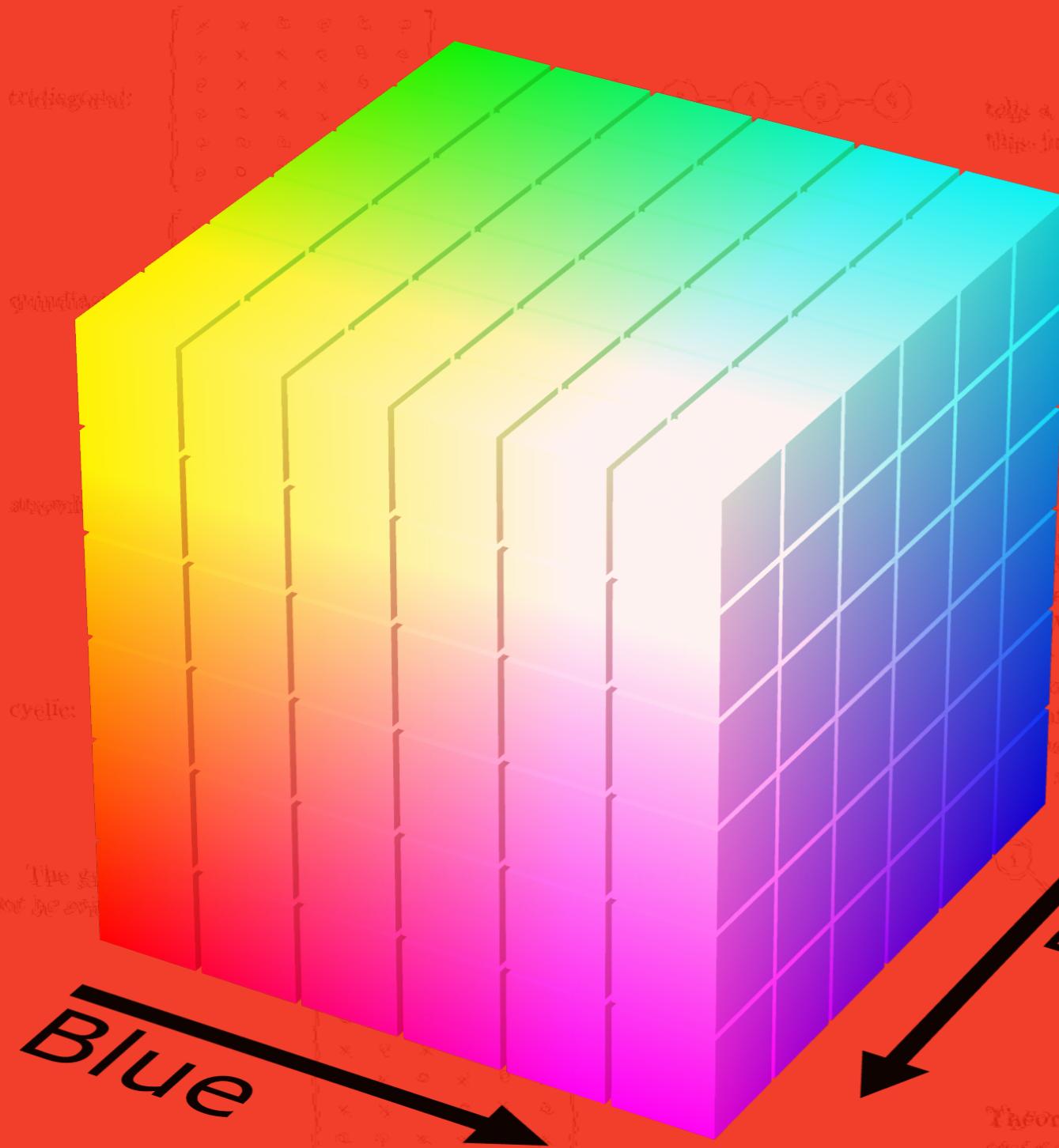
-97.743°



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



At a first glance, there is nothing to link in to any of the four matrices that we have just displayed, but its graph.



RED

224

tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$0 \rightarrow 1, 2 \rightarrow 3, 3 \rightarrow 2, 4 \rightarrow 5, 5 \rightarrow 6, 6 \rightarrow 4$$

Of course, it is equivalent to reordering (simultaneously) the columns and rows. A *partial set of steps* $\{(v_i, j_i)\}_{i=1}^n \subseteq \mathbb{E}$ is called a *path* joining the vertices v_i and v_j if $(v_i, j_i) \in \mathbb{E}$, $j_i \in \{i, j\}$, $i \in \{1, n\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{v_k, j_k\} \cap \{(v_i, j_i)\}$ contains exactly one member. It is a *simple path* if it does not visit any vertex more than once. We say that G is a *tree* if each two members of V are joined by a simple path. Both tri-diagonal and quasi-diagonal matrices correspond to trees. (This is not the case with either quidiagonal or cyclic matrices when $p \geq 3$.)

Let's start with an arbitrary vertex $r \in V$. The set $T = \{v \in V \mid v \text{ is joined to } r \text{ by a simple path}\}$ is called a *rooted tree* with r added to be the root. Unlike a ordinary tree, T does not have a unique root, which can best be explained by an example of a family tree. This is the reason why we call the set of all the vertices in T a *rooted tree* and these vertices are *descendants* of the root. A vertex $v \in V \setminus \{r\}$ is joined to r by a simple path and we designate v as an *ancestor* of r and r as a *descendant* of v , except for r and v , as a *predecessor* of v and a *successor* of r . We say that a rooted tree T is *monotonically ordered* if each vertex is labelled with a unique integer $\ell(v)$ in other words we label the vertices from the top of the tree to the bottom. (We have already said it, relabelling a graph is the same as relabelling the rows and the columns of the underlying matrix.)

Every vertex then will be monotonically ordered and, in general, such an ordering is not unique. We can give three consecutive orderings of the same rooted tree:

Red

Green

Blue

Red

Green

Blue

Red

Green

Blue

BLUE

57

Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are re-arranged so, that $T = (v_i, r)$ is monotonically ordered. Then, that $A = L U$ is a Cholesky factorization. It is true that

$$a_{k,j} = \frac{a_{k,j}}{a_{j,j}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

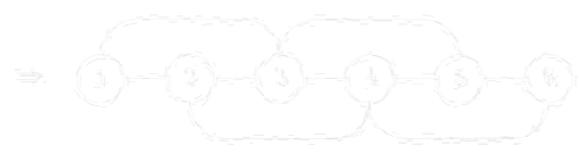
and their graphs

tridiagonal:
$$\begin{bmatrix} * & * & 0 & 0 & 0 \\ * & * & * & 0 & 0 \\ 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & * & 0 \\ 0 & 0 & 0 & 0 & * \end{bmatrix}$$

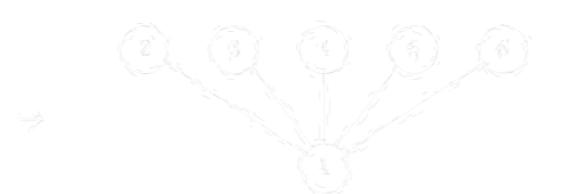


BASIS

quindiagonal:

$$\begin{bmatrix} * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & * & 0 \\ 0 & 0 & 0 & 0 & 0 & * \end{bmatrix}$$


superdiagonal:

$$\begin{bmatrix} * & * & * & * & * & * \\ * & * & 0 & 0 & 0 & 0 \\ 0 & 0 & * & 0 & 0 & 0 \\ 0 & 0 & 0 & * & 0 & 0 \\ 0 & 0 & 0 & 0 & * & 0 \\ 0 & 0 & 0 & 0 & 0 & * \end{bmatrix}$$


cyclic:

$$\begin{bmatrix} * & 0 & 0 & 0 & * & * \\ * & * & 0 & 0 & 0 & 0 \\ 0 & 0 & * & 0 & 0 & 0 \\ 0 & 0 & 0 & * & 0 & 0 \\ 0 & 0 & 0 & 0 & * & 0 \\ 0 & 0 & 0 & 0 & 0 & * \end{bmatrix}$$


BUILDING BLOCKS

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

OF TESTS

At a first glance, this is not a matrix, but a graph of 10 nodes. It is, however, a matrix, just displayed, but its graph:



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{1, \dots, n\}$, $j_0 \in \{1, \dots, n\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and superdiagonal matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in a ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is unique. The following diagram shows three consecutive orderings of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A were been arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



tells a different story - it is nothing other than the cyclic matrix in disguised. To see this, just re-label the weights as follows:



Create Edit Delete Clone Import

[[*, 0, 0, 0, 0, 0], [0, *, 0, 0, 0, 0], [0, 0, *, 0, 0, 0], [0, 0, 0, *, 0, 0], [0, 0, 0, 0, *, 0], [0, 0, 0, 0, 0, *]]

A single simple path. Both tridiagonal and any banded matrices correspond to trees, but this is not the case with either anti-diagonal or cyclic matrices when $n > 3$.

	Name	Description
<input checked="" type="checkbox"/>	Little Bobby Tables	Better not drop me!
<input type="checkbox"/>	Big Bobby Tables	
<input type="checkbox"/>	Foo Bar	Making up names is hard.



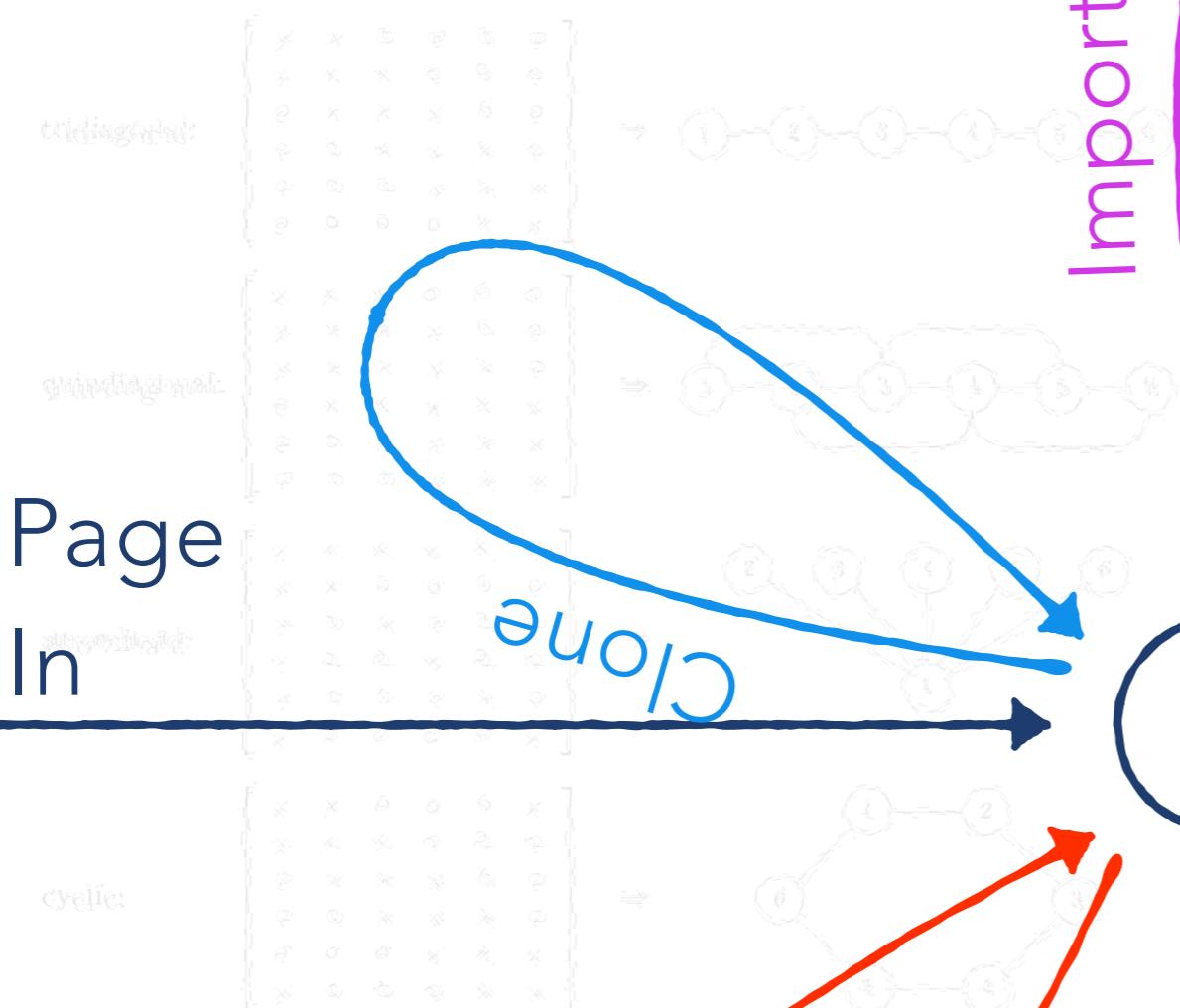
Theorem 11.1 Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $\mathbf{T} = (G, r)$ is monotonically ordered. Given that $A = \mathbf{L}\mathbf{U}$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph:



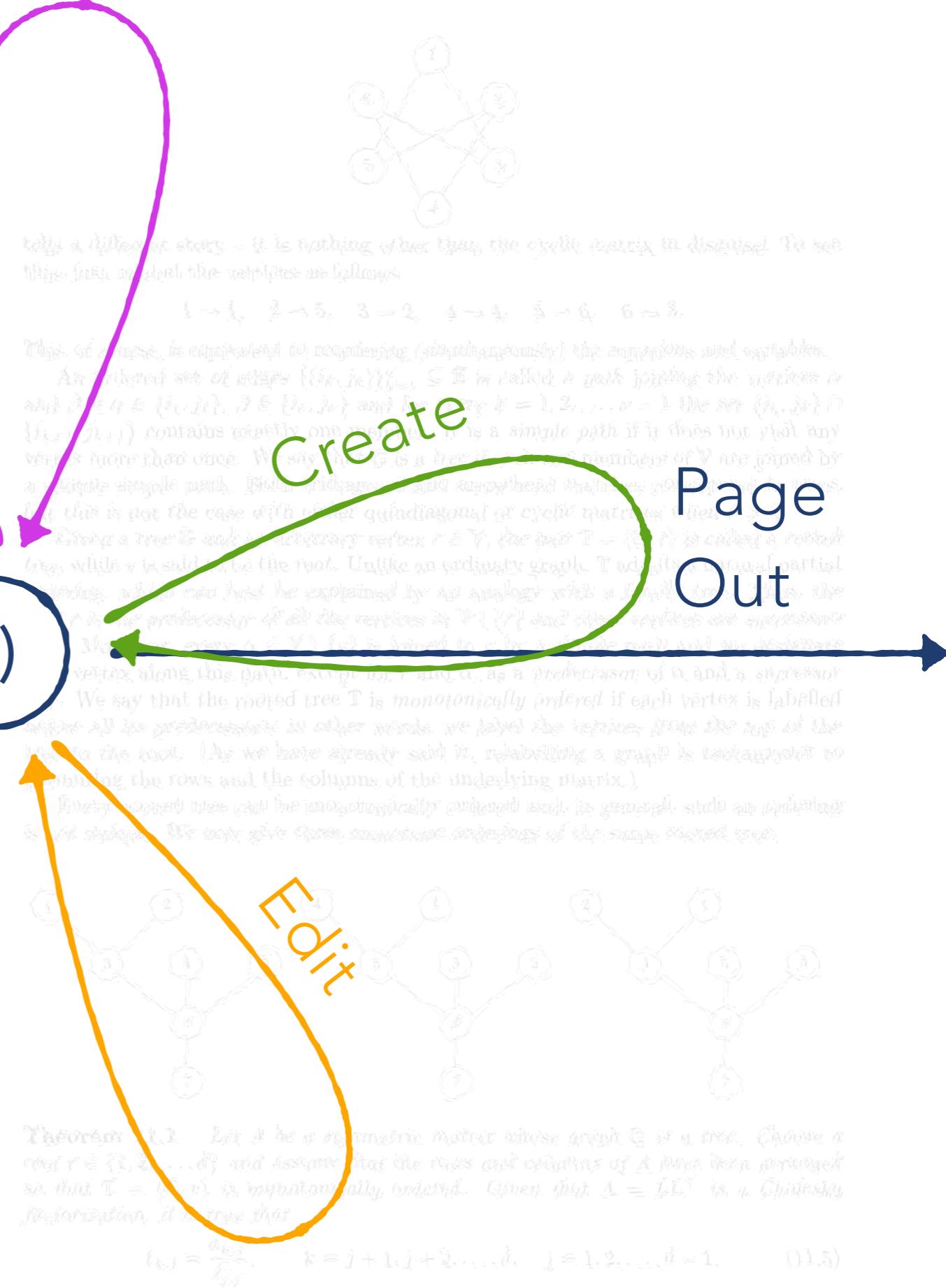
Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



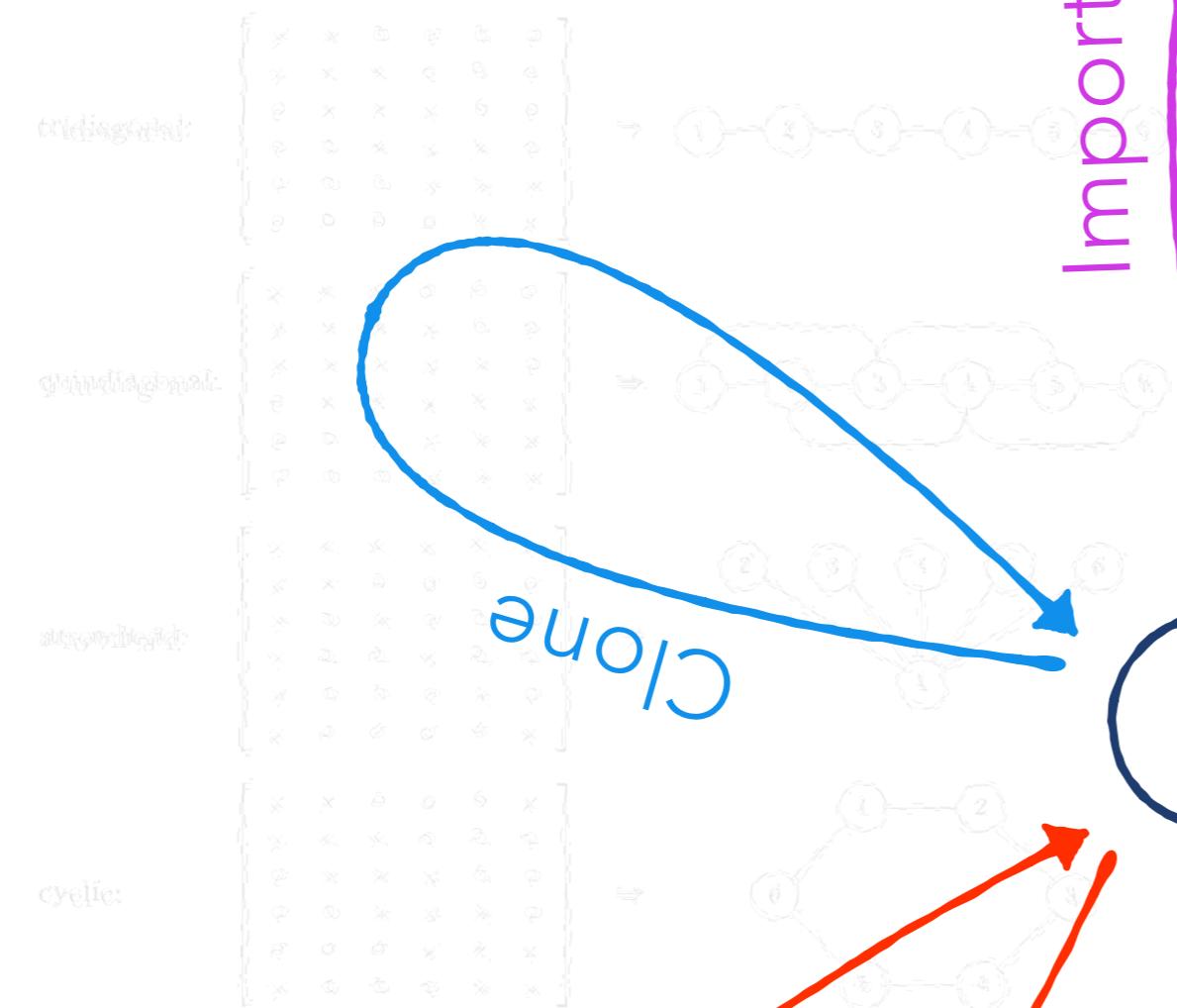
The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix



At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,



Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



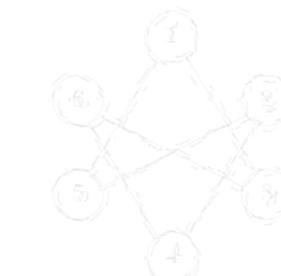
The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$

Delete

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,

Import



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just read the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 3, 3 \rightarrow 2, 4 \rightarrow 4, 5 \rightarrow 6, 6 \rightarrow 8.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0), \dots, (i_{v-1}, j_{v-1})\}$ is called a path joining the vertices i_0 and i_{v-1} ($i_0, i_1, \dots, i_{v-1}, i_v \in V$, $j_0, j_1, \dots, j_{v-1} \in V$), and for any $k = 1, 2, \dots, v-1$ the set $\{(i_k, j_k) \mid (i_k, j_{k+1}) \in \{(i_0, j_0), \dots, (i_{v-1}, j_{v-1})\}\}$ contains exactly one edge. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if no two members of V are joined by a single simple path. Both tridiagonal and quadiagonal matrices correspond to trees, but this is not the case with either quadiagonal or cyclic matrices when $n \geq 3$.

Create a tree T and a arbitrary vertex $r \in V$, the pair $T \sim (r, T)$ is called a rooted tree, while r is said to be the root. Unlike in a ordinary graph, T has a natural partial order, which can best be explained by an analogy with a family tree. Thus, the vertex r is a predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $a \in V \setminus \{r\}$ is joined to r by a simple path and we designate vertex along this path, except r and a , as a predecessor of a and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to relabelling the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We will give three consecutive drawings of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are now arranged so, that $T = (r, T)$ is monotonically ordered. Then, that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{k,j}}{l_{j,j}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

Page
In

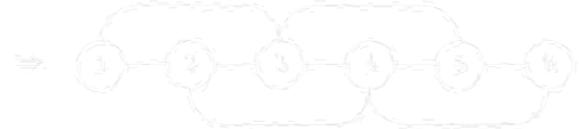
quidiagonal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & 0 & 0 & 0 & 0 \\ 0 & * & * & 0 & 0 & 0 \\ 0 & 0 & * & * & 0 & 0 \\ 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



quidiagonal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ * & * & * & * & * & 0 \\ 0 & 0 & * & * & * & * \\ 0 & 0 & 0 & * & * & * \end{bmatrix}$$

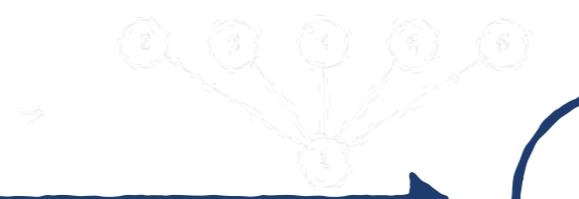


Page

Out

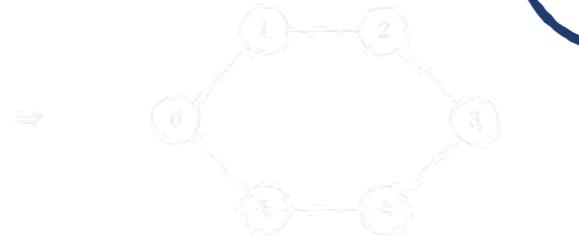
triangular:

$$\begin{bmatrix} * & * & * & * & * & * \\ * & * & 0 & 0 & 0 & 0 \\ * & 0 & * & 0 & 0 & 0 \\ 0 & * & * & 0 & 0 & 0 \\ 0 & 0 & * & * & 0 & 0 \\ 0 & 0 & 0 & * & * & 0 \end{bmatrix}$$



triangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ * & * & * & * & * & 0 \\ 0 & 0 & * & * & * & * \\ 0 & 0 & 0 & * & * & * \end{bmatrix}$$



The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & x & 0 \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & * & * \end{bmatrix}$$

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, \quad 2 \rightarrow 5, \quad 3 \rightarrow 2, \quad 4 \rightarrow 3, \quad 5 \rightarrow 6, \quad 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, v-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tri-diagonal and any other matrices considered above, but this is not the case with either quidiagonal or cyclic matrices.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, T admits a natural partial order, which can best be explained by an analogy with a family tree. The vertex r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors. Moreover, every $\alpha \in V \setminus \{r\}$ has a unique predecessor α' and an immediate vertex along this path, except for r and α , as a predecessor of α and a successor.

We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree.



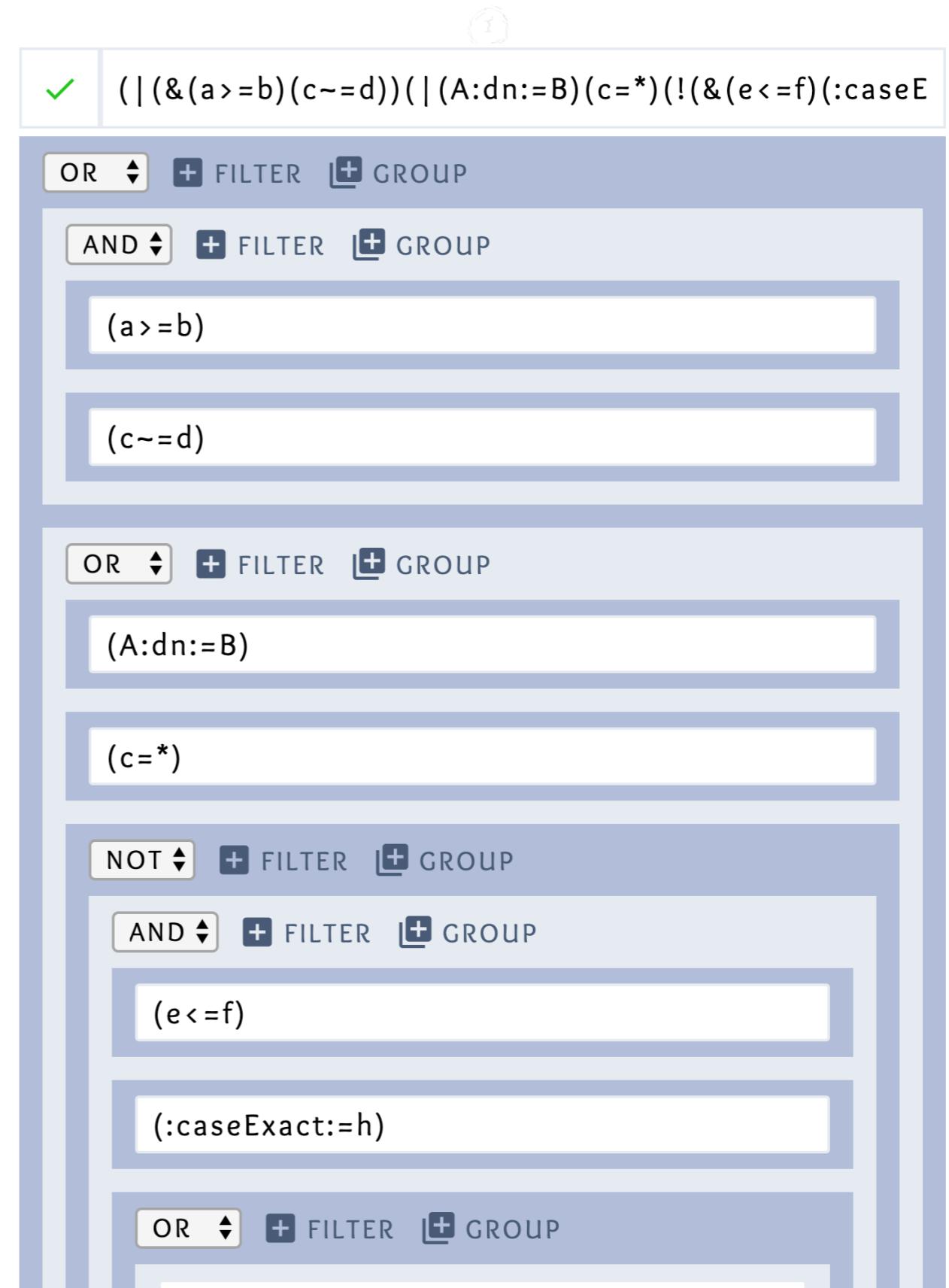
Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ki}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Page
Out

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their analysis.

$(|(&(a>=b)(c\sim=d))$
 $(| (A:dn:=B)(c=^*)$
 $(!(&(e<=f)$
 $(:caseExact:=h)$
 $(| (i=j)(!(k<=l))))))))$



just displayed, but its graph.

$$t_{k,j} = \frac{a_{k,j}}{b_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1, \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

(| (! (a>=b) (c~d)))
(| (A:dn := B) (c=*))
(!(&(e<=f))
(:caseExact:=h))
(| (i=j) (! (k<=l)))))))

! (| (! (a>=b) (c~d))) (| (A:dn := B) (c=*)) (!(&(e<=f)) (:caseE>))

OR FILTER GROUP

NOT FILTER GROUP

You can negate only 1 filter in a group.

(a>=b)

(c~d)

You need to use ~=.

OR FILTER GROUP

(A:dn := B)

You need to trim the attribute and filter type.

(c=*)

NOT FILTER GROUP

AND FILTER GROUP

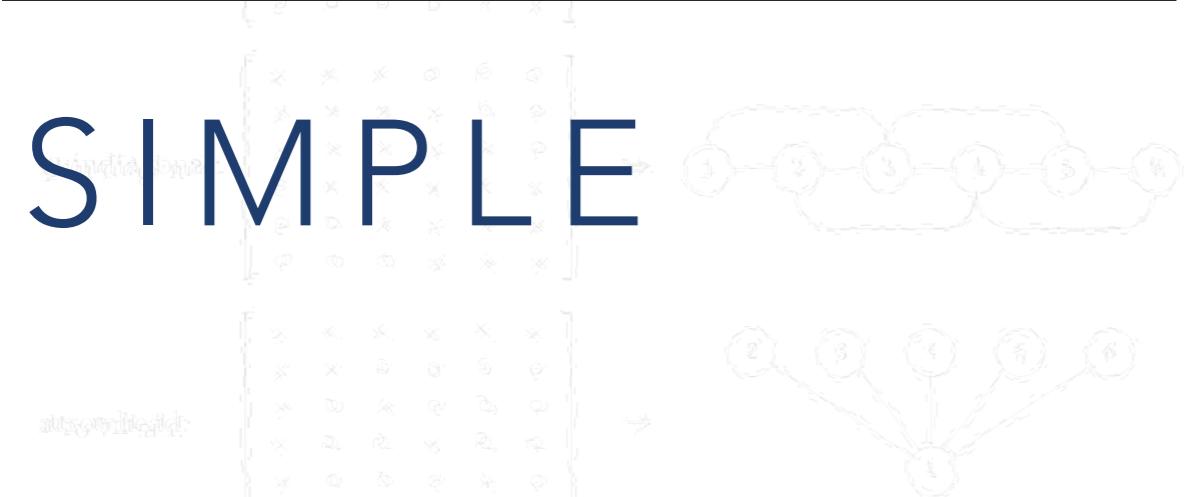
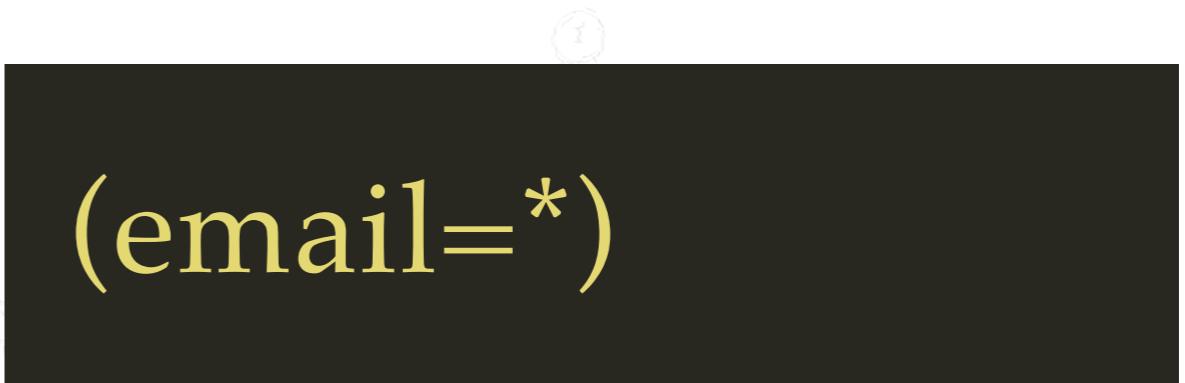
(e<=f)

(:caseExact:=h)

just displayed, but its graph.

$$t_{k,j} = \frac{a_{k,j}}{b_{j,j}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1, \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



PRESENT

This, of course, is equivalent to requiring (simultaneously) the equations and variables. An ordered set of edges $\{v_i, w_i\}$ ($i \in \mathbb{N}$) is called a path joining the vertices v_i and w_i ($i \in \mathbb{N}$) and, for every $i = 1, 2, \dots, n-1$ the set $\{v_i, w_i\} \cap \{v_{i+1}, w_{i+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $p \geq 3$.

Given a tree G and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in a ordinary graph, T adopts a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $v \in V \setminus \{r\}$ has a parent to r by a simple path and we designate



The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparser pattern. Thus, consider the matrix

SUBSTRING



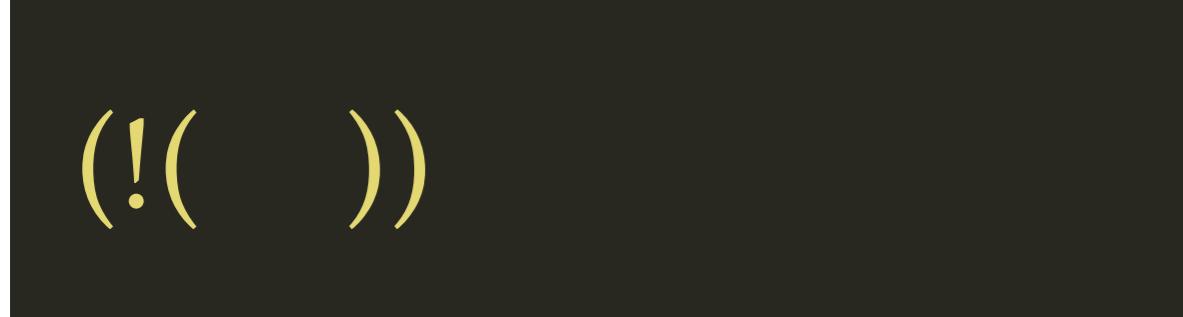
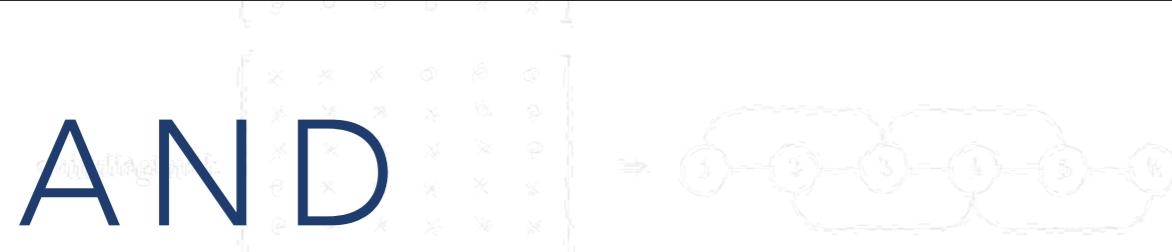
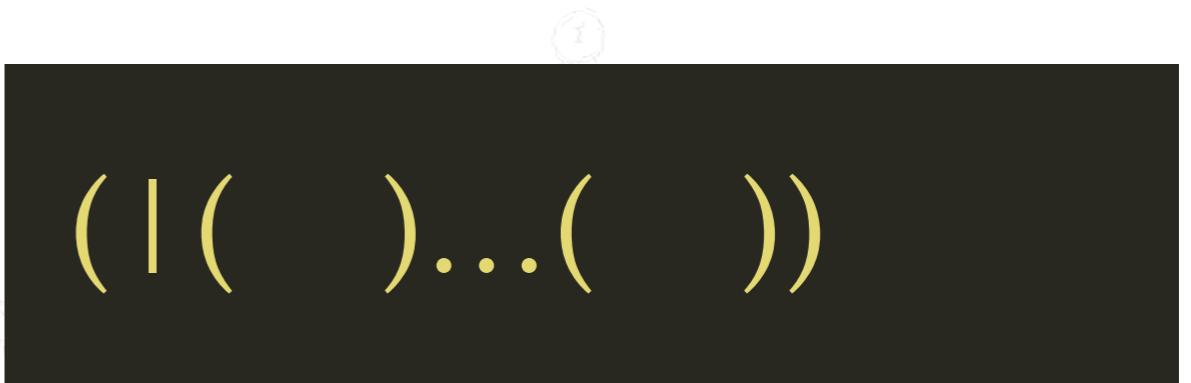
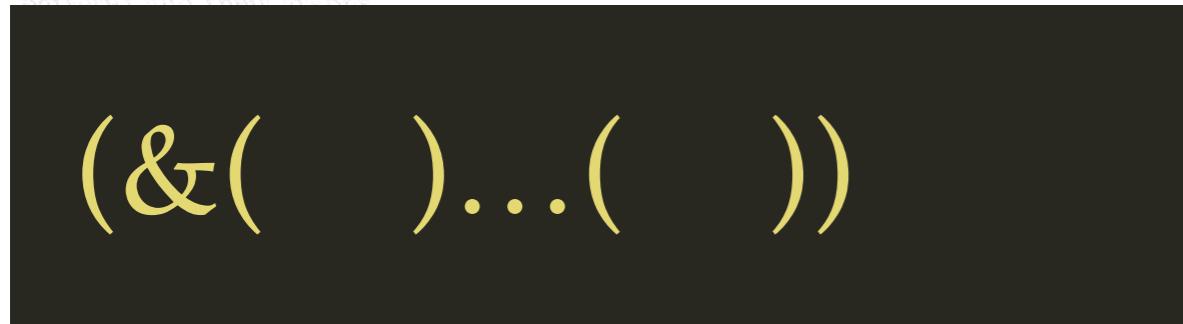
At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,



Theorem 11.1 Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix



At a first glance, there is nothing to think in the case of the four matrices that we have just displayed, but its graph,



$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

```
function addOne(x) {
  if (Number.isFinite(x)) {
    x = x + 1;
  } else {
    console.log('error');
  }
  return x;
}
```

just displayed, but its graph:



tells a different story – \mathbf{g} is not a tree. In a cyclic matrix in discussed. To see this, just re-label the vertices as follows:

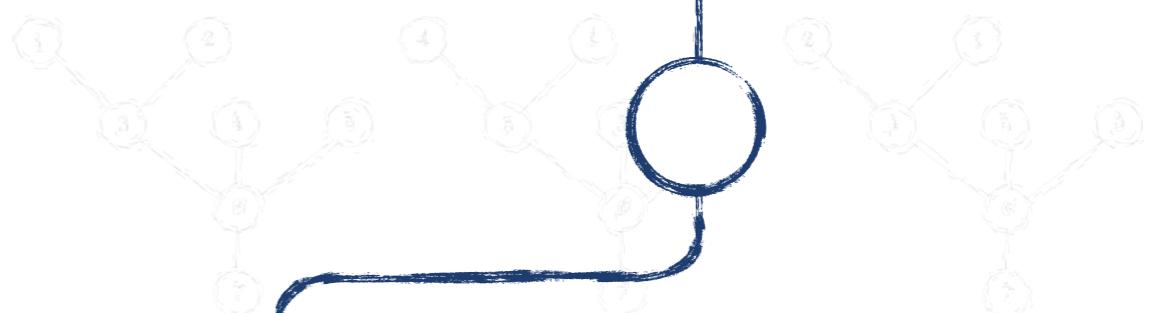
$$1 \rightarrow 1, \quad 2 \rightarrow 3, \quad 3 \rightarrow 2, \quad 4 \rightarrow 5, \quad 5 \rightarrow 6, \quad 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (swapping) the equations and variables.

An ordered set of edges $\{(i_1, j_1)\}_{i_1, j_1 \in \{1, \dots, n\}}$ is a path joining the vertices i_1 and j_1 if $i_1 \in \{1, \dots, n\}$, $j_1 \in \{1, \dots, n\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_{k+1}, j_{k+1}\} \cap \{i_k, j_k\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that \mathbf{G} is a tree if each two members of \mathbf{V} are joined by a unique simple path. Both tridiagonal and banded matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n > 3$.

Given a tree \mathbf{G} and an arbitrary vertex $r \in \mathbf{V}$, the path $T = (Q, \pi)$ is called a rooted tree, while r is said to be the root. Unlike in an ordinary tree, the root r is not necessarily unique, which can best be explained by an analogy with a family tree. The root r is the predecessor of all the vertices in $\mathbf{V} \setminus \{r\}$ and these vertices are successors of r . Moreover, every $a \in \mathbf{V} \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and a , as a predecessor of a and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, a vertex a is to the right of r if it is further from the root to the left. (As we have already said, we are permuting the rows and the columns of the matrix \mathbf{A} to obtain the Cholesky factorization of the matrix.)

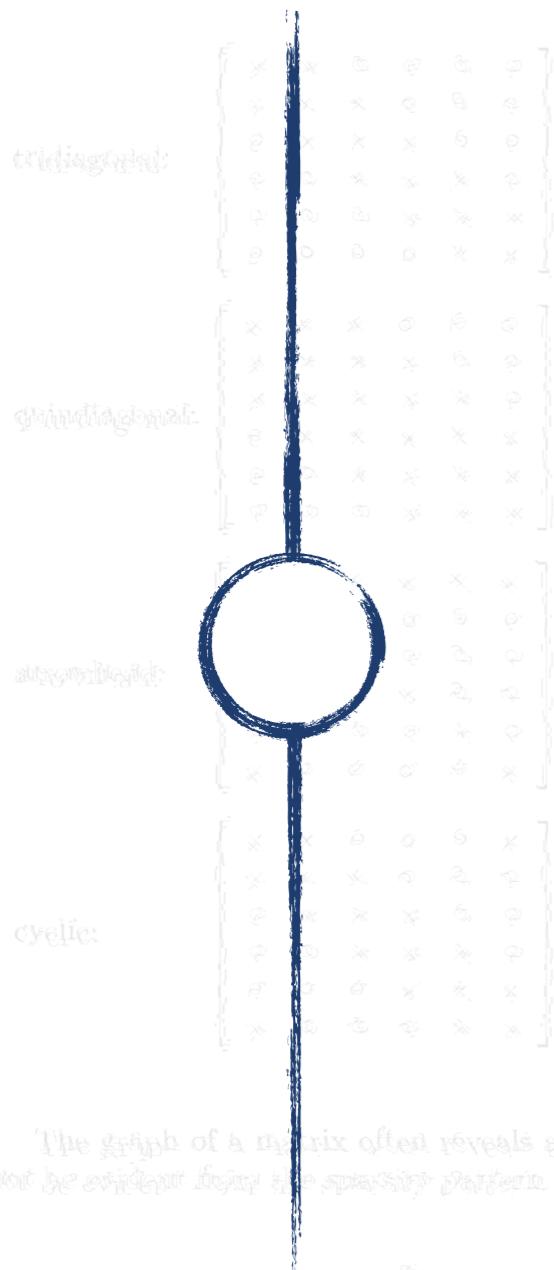
Every rooted tree will be monotonically ordered, but in general such an ordering is not unique. We now give three consecutive stages of the same rooted tree:



Theorem 2.1 Let \mathbf{A} be a symmetric matrix whose graph \mathbf{G} is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and a monotonically ordered set \mathbf{V} such that \mathbf{G} is a tree with root r . Assume that the rows and columns of \mathbf{A} are then arranged so that $\mathbf{T} = (Q, \pi)$ is a rooted tree. Then there exists a unique Cholesky factorization of \mathbf{A} if and only if \mathbf{A} is positive definite.

$$l_{k,j} = \frac{a_{k,j}}{a_{j,j}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

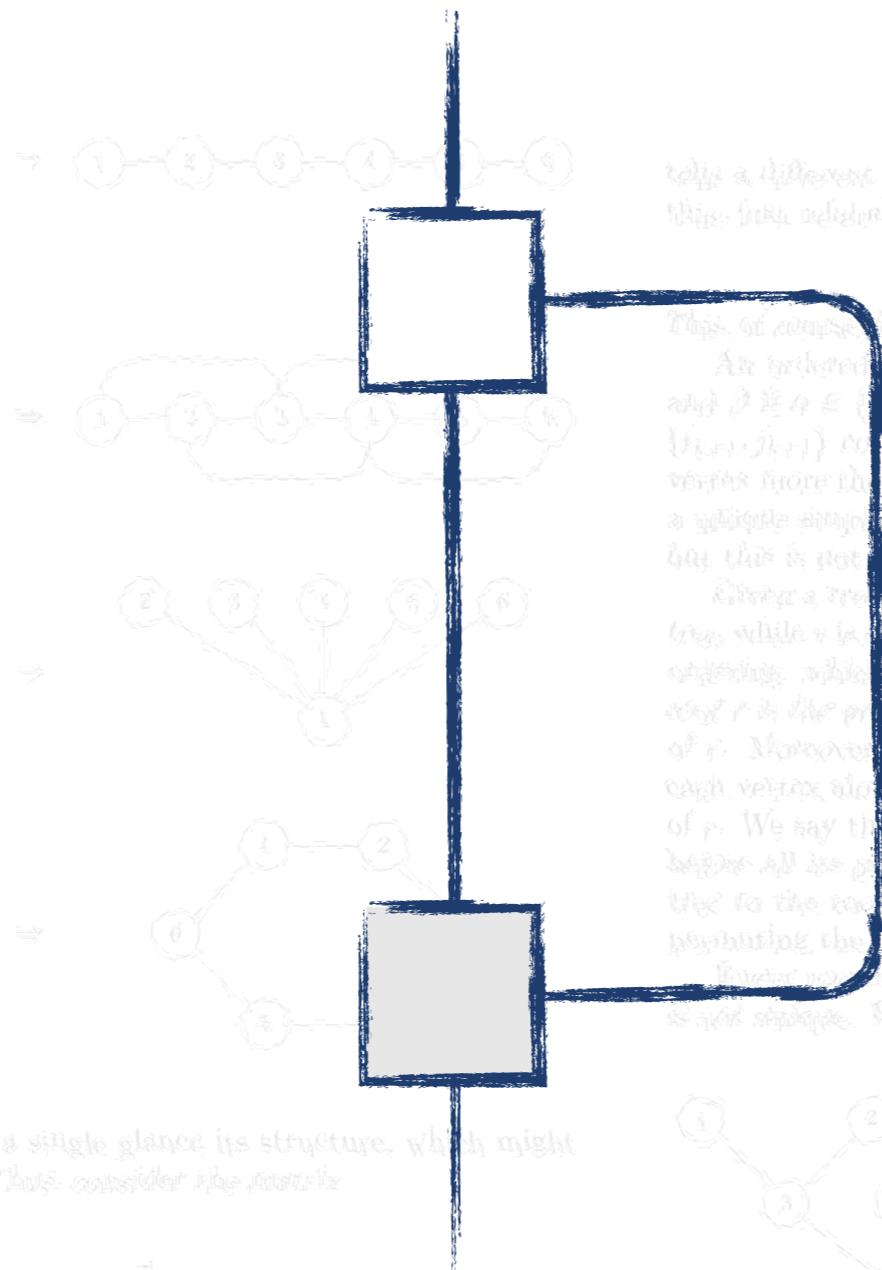


The graph of a matrix often reveals at a single glance its structure, which might not be evident from its sparsity pattern. Thus, consider the matrix

$$\text{LOG} \quad \begin{bmatrix} * & 0 & * & 0 & * & 0 \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & 0 & * & 0 \\ 0 & 0 & * & 0 & 0 & * \\ 0 & * & 0 & 0 & * & 0 \\ 0 & 0 & 0 & * & 0 & 0 \end{bmatrix}$$

| F

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, first recall that the vertices are

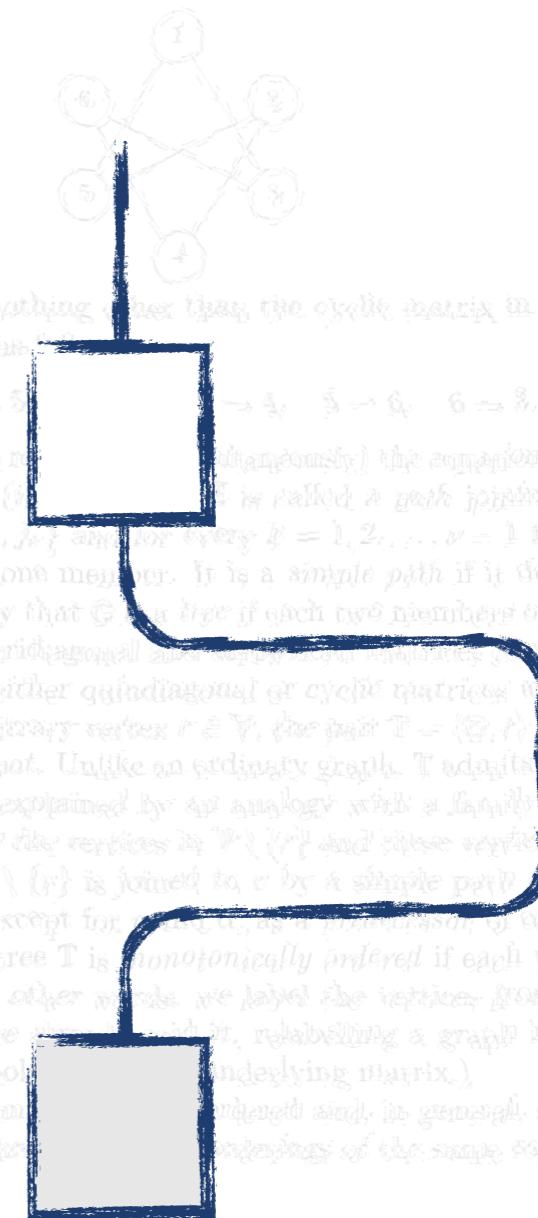
$$1 \rightarrow 1, \quad 2 \rightarrow 5, \quad \dots \rightarrow 5, \quad 6 \rightarrow 3.$$

This, of course, is equivalent to renumbering (simultaneously) the equations and variables.

An ordered set of edges $\{(v_i, w_i)\}_{i=1}^n$ in $G = (V, E)$ is called a path joining the vertices v_1 and v_n if $i \in \{1, \dots, n\}$, $v_i \in V$, $w_i \in V$, and for every $k = 1, 2, \dots, n-1$ the set $\{v_{k+1}, w_k\} \cap \{v_k, w_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and pentadiagonal matrices correspond to trees, but this is not the case with either quadiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $v \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r itself, as a predecessor of v and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors in other words, we layed the vertices from the top of the tree to the root. (As we have mentioned it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Even a binary tree will be monotonically ordered and, in general, such an ordering is not unique. We will give the



FN

Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Then, that $A = LL^T$ is a Cholesky factorization, it is true that

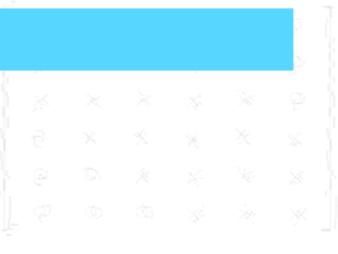
$$l_{k,j} = \frac{a_{kj}}{a_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

triangular:



quadratic:



symmetric:



cyclic:



The graph of a matrix often reveals at a single glance its structure, which may not be evident from the sparsity pattern. Thus, consider the matrix



At a first glance, there is nothing to think in the case just displayed, but its graph,

1

PICTURE

1000

WORDS



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

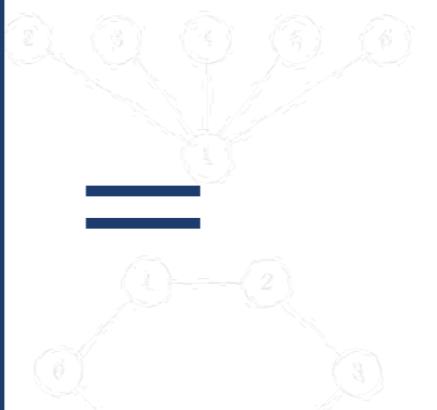
$$1 \rightarrow 1, 2 \rightarrow 5, 3 \rightarrow 2, 4 \rightarrow 3, 5 \rightarrow 6, 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_1, j_1), (i_2, j_2), \dots, (i_v, j_v)\}$ in \mathbb{G} is called a *path* joining the vertices i_1, i_2, \dots, i_v (j_1, j_2, \dots, j_v) and, for every $k = 1, 2, \dots, v-1$ the set $\{(i_k, j_k), (i_{k+1}, j_{k+1})\}$ contains exactly one edge. It is a *simple path* if it does not visit any vertex more than once. We say that \mathbb{G} is a *tree* if each two members of \mathbb{V} are joined by a single simple path. Back to graphs, the quadiagonal matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $p \geq 3$.

Given a tree \mathbb{G} and an arbitrary vertex $r \in \mathbb{V}$, the pair $T = (G, r)$ is called a *rooted tree*, while r is said to be the *root*. Unlike in ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the *predecessor* of all the vertices in $\mathbb{V} \setminus \{r\}$ and these vertices are *successors* of r . Moreover, every $\alpha \in \mathbb{V} \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a *predecessor* of α and a *successor* of r . We say that the rooted tree T is *monotonically ordered* if each vertex is labelled before all its predecessors; in other words, we *layer* the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is unique. We now give three consecutive endings of the same rooted tree:



Theorem 1. Let A be a symmetric matrix whose graph \mathbb{G} is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

```
// TODO: Write tests later

test('it renders', async function(assert) {
  await render(hbs`<ComplexComponent />`);
  assert.ok(true);
});
```

```
import { percySnapshot } from 'ember-percy';

...
// TODO: Write tests later

test('complex workflow', async function(assert) {
  await visit('/complex-page');
  percySnapshot(assert);
});
```

Therefore we will now give a few examples of matrices (represented by their sparsity)

triangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



quadrangular:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



supernodal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



cyclic:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



IF f IS CONTINUOUS IN $[a, b]$, AND IF $f(a)f(b) < 0$,

THEN f MUST HAVE A

ZERO IN (a, b) .



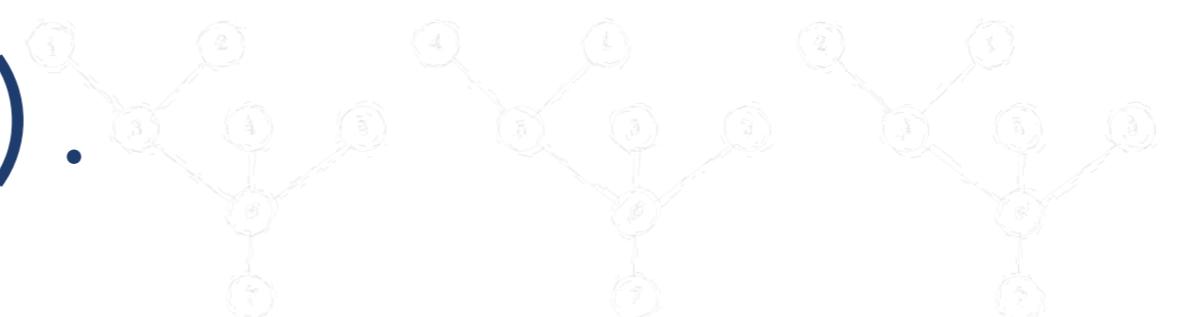
tells a different story - it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 2, 3 \rightarrow 3, 4 \rightarrow 4, 5 \rightarrow 5, 6 \rightarrow 6.$$

Of course, it is equivalent to renumbering the equations and variables. As you can see from the figure, G is called a tree, since the vertices v and α ($v \in V \setminus \{\alpha\}$, $\beta \in V \setminus \{\alpha\}$) and for every $k = 1, 2, \dots, n-1$ the set $\{v_1, v_2, \dots, v_k\} \cap \{v_{k+1}, v_{k+2}, \dots, v_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either of banded or cyclic matrices when $p \geq 3$.

Of course, it is equivalent to renumbering the equations and variables. As you can see from the figure, G is called a tree, since the vertices v and α ($v \in V \setminus \{\alpha\}$, $\beta \in V \setminus \{\alpha\}$) and for every $k = 1, 2, \dots, n-1$ the set $\{v_1, v_2, \dots, v_k\} \cap \{v_{k+1}, v_{k+2}, \dots, v_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either of banded or cyclic matrices when $p \geq 3$.

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree:



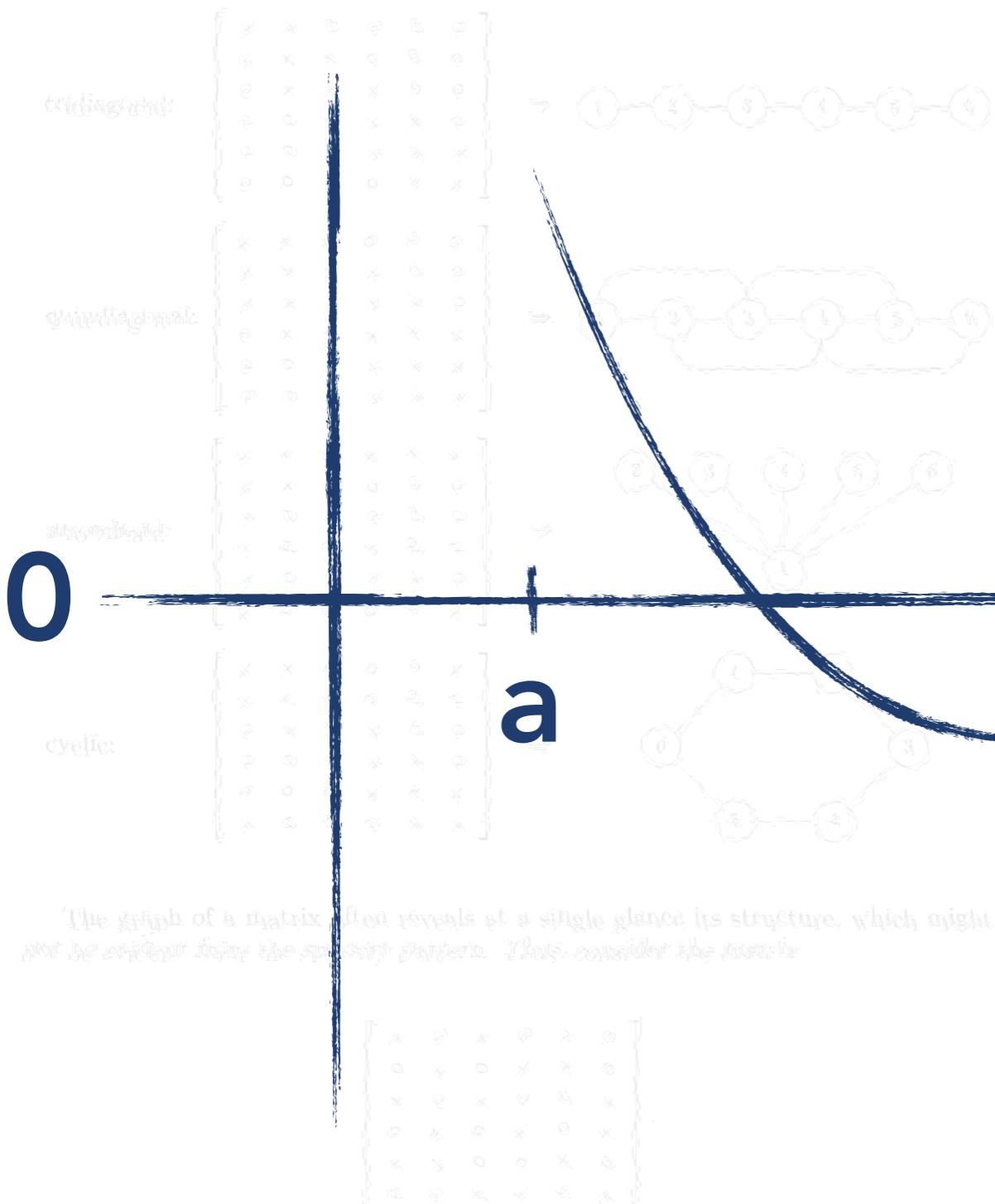
Theorem 11.1 Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

At a first glance, this is not a very useful formula, but it is the basis for the following algorithm.

just displayed, but its graph:

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



At a first glance, there is nothing to link in the case of the four matrices that we have just displayed, but its graph.



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

$$1 \rightarrow 1, \quad 2 \rightarrow 5, \quad 3 \rightarrow 2, \quad 4 \rightarrow 3, \quad 5 \rightarrow 6, \quad 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and any other matrices correspond to trees, but this is not the case with either quidiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . The set $\{v \in V \mid v \text{ is a successor of } r\}$ is called an out-neighborhood of r . We designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its descendants. In other words, we layed the tree down the top at the tree's root. (As we have seen, it is said it, relabelling α is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree:



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are then arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity)

YOU CAN FIND EQUALLY MANY NUMBERS BETWEEN 0 AND 1 AS YOU CAN

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

BETWEEN $-\infty$ AND ∞ .

At a first glance this is not a matrix, but it is a little known triangular matrix, just displayed, but its graph,



It is a different story – it is nothing other than the cyclic matrix in disguised. To see this, let us relabel the vertices as follows:

$$1 \rightarrow 1, 2 \rightarrow 3, 3 \rightarrow 2, 4 \rightarrow 4, 5 \rightarrow 6, 6 \rightarrow 8.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(u_i, v_i)\}_{i=1}^p$ in \mathbb{G} is called a path joining the vertices u_1 and u_p if $u_i \in \{u_1, u_2\}$, $v_i \in \{v_1, v_2\}$ and for every $i = 1, 2, \dots, p-1$ the set $\{u_i, v_i\} \cap \{u_{i+1}, v_{i+1}\} = \emptyset$. A path is called simple if it does not visit any vertex more than once. We say that a path is closed if all its vertices are joined by a single simple path. Below we present two examples. Matrices corresponding to these, but this is not the case with either quidiagonal or cyclic matrices when $p \geq 3$.

Given a tree \mathbb{G} and an arbitrary vertex $r \in \mathbb{V}$, the pair $T = (G, r)$ is called a rooted tree, while r is said to be the root. Unlike in a ordinary graph, T admits a natural partial ordering, which can best be explained by an analogy with a family tree. Thus, the root r is the ancestor of the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $a \in \mathbb{V} \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and a , as a predecessor of a and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors; in other words, we label the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three concrete examples of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph \mathbb{G} is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

tridiagonal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix} \rightarrow \text{Graph: } 1 \rightarrow 2 \rightarrow 3 \rightarrow 4 \rightarrow 5 \rightarrow 6$$



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, first, re-label the weights as follows:

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16

$$\begin{bmatrix} * & 0 & * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * & 0 & 0 \\ * & 0 & * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * & 0 & * \\ * & 0 & * & 0 & * & 0 & * & 0 \\ 0 & * & * & 0 & * & 0 & * & 0 \\ 0 & 0 & * & * & 0 & * & 0 & 0 \\ 0 & 0 & 0 & * & * & 0 & * & 0 \\ 0 & 0 & 0 & 0 & * & * & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & * & * & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & * \end{bmatrix}$$



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are then arranged so, that $\mathbb{T} = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

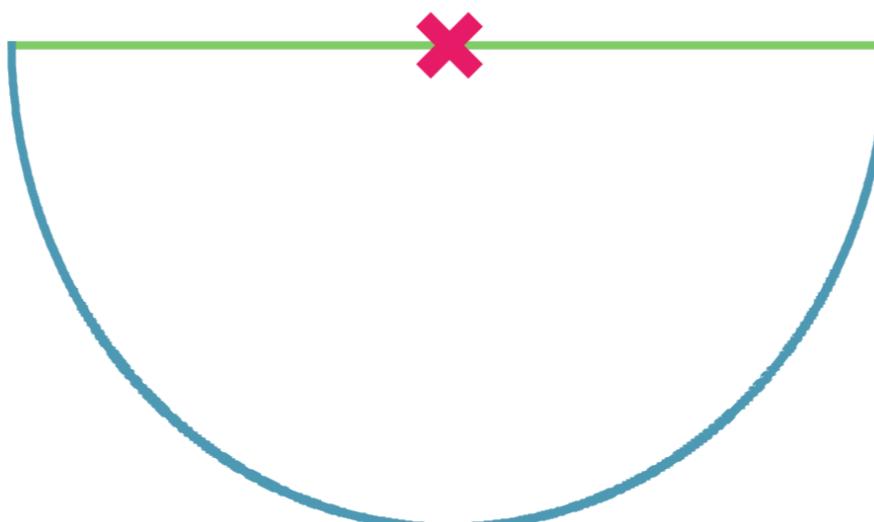
At a first glance, there is nothing to think in the case of the first matrices that we have just displayed, but its graph.

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

tridiagonal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix} \rightarrow \text{Graph: } 1 \rightarrow 2 \rightarrow 3 \rightarrow 4 \rightarrow 5 \rightarrow 6$$

tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, first, re-label the vertices as follows:



$$\begin{bmatrix} * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & * & 0 \\ * & 0 & * & 0 & 0 & * \\ 0 & * & 0 & * & 0 & * \\ * & 0 & * & 0 & 0 & * \\ 0 & * & * & * & * & * \end{bmatrix}$$

At a first glance, there is nothing to think in the case of the first matrices that we have just displayed, but its graph:



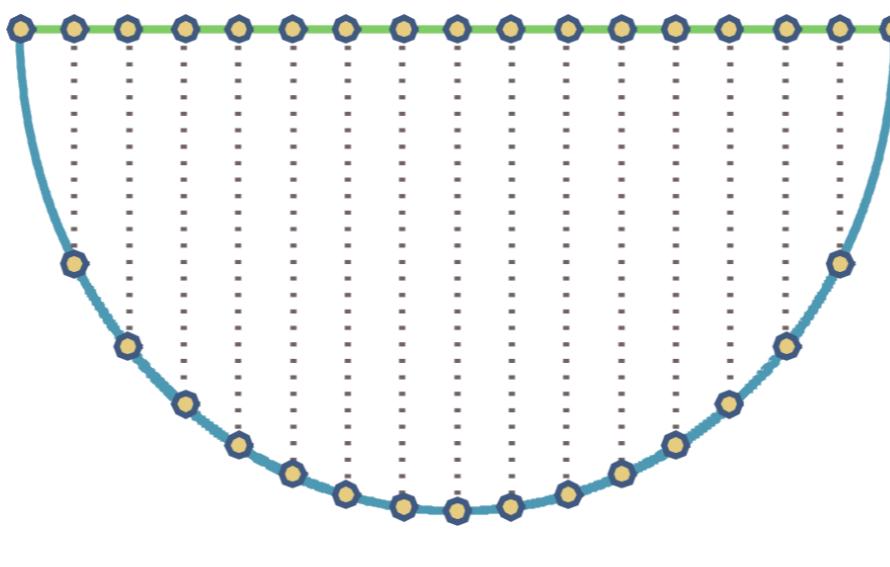
Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $\mathbb{T} = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, first recall the weights as follows:



At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph:



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $\mathbb{T} = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

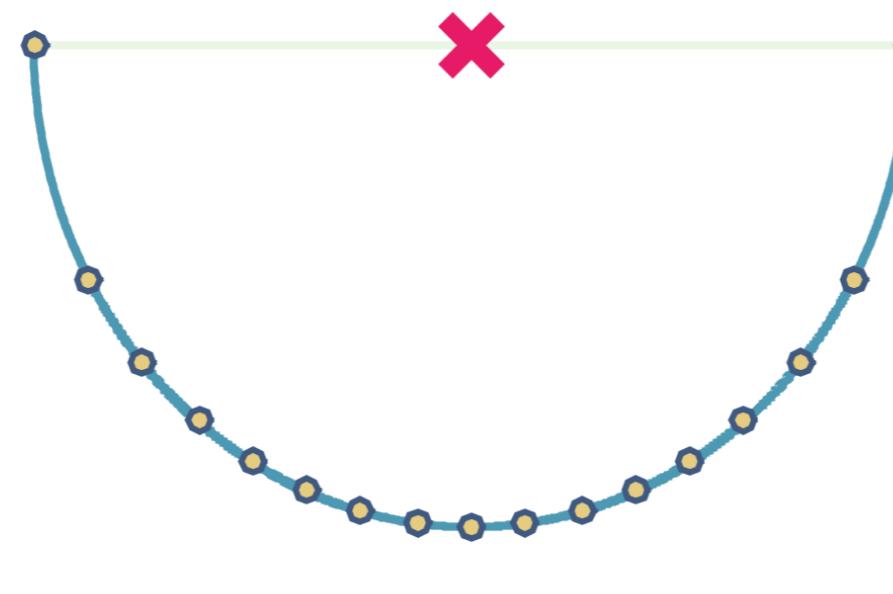
$$l_{k,j} = \frac{a_{kj}}{l_{jj}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

tridiagonal:

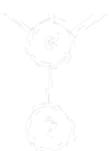
$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix} \rightarrow \text{Graph: } 1 \rightarrow 2 \rightarrow 3 \rightarrow 4 \rightarrow 5 \rightarrow 6$$

tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, first recall the weights as follows:



$$\begin{bmatrix} * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & * & 0 \\ * & 0 & * & 0 & 0 & * \\ 0 & * & 0 & * & 0 & * \\ * & 0 & * & 0 & 0 & * \\ 0 & * & * & * & * & * \end{bmatrix}$$

At a first glance, there is nothing to think in the case of the four matrices that we have just displayed, but its graph:



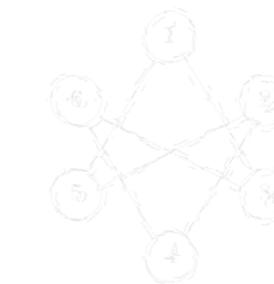
Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $\mathbb{T} = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

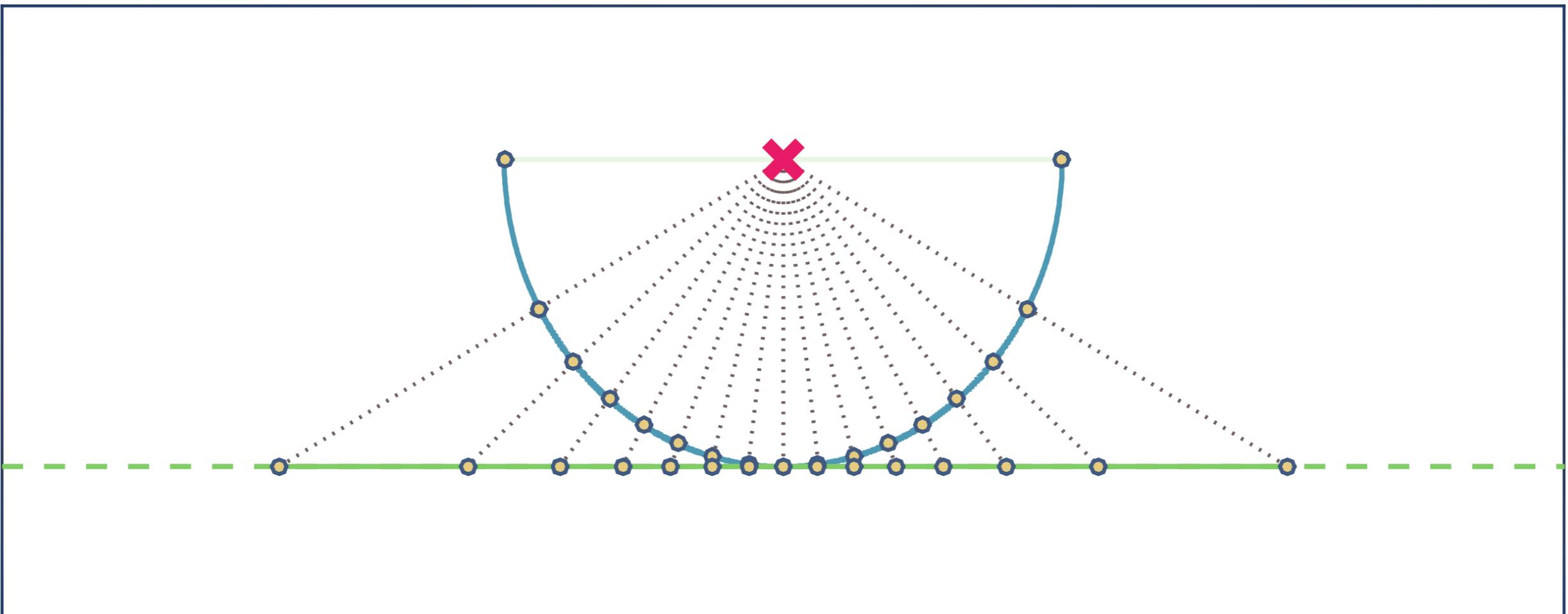
Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

tridiagonal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix} \rightarrow \text{Graph: } 1 \rightarrow 2 \rightarrow 3 \rightarrow 4 \rightarrow 5 \rightarrow 6$$

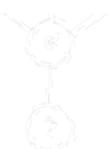


tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just re-label the vertices as follows:



$$\begin{bmatrix} * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & 0 \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & 0 \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \end{bmatrix}.$$

At a first glance, there is nothing to think in the case of the four matrices that we have just displayed, but its graph:



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $\mathbb{T} = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

tridiagonal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix} \rightarrow \text{Graph: } 1 \rightarrow 2 \rightarrow 3 \rightarrow 4 \rightarrow 5 \rightarrow 6$$



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just re-label the weights as follows:

1 2 3 4 5 6 7 8 9 10 11 12

$$\begin{bmatrix} * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & * & 0 \\ * & 0 & * & 0 & 0 & * \\ 0 & * & 0 & * & 0 & * \\ * & 0 & * & 0 & 0 & * \\ 0 & * & * & * & * & * \end{bmatrix}.$$

At a first glance, there is nothing to think in the case of the first matrices that we have just displayed, but its graph:



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $\mathbb{T} = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

5 Rules of Writing Tests

Filter:

Module: Acceptance | Outline



EmberFest 18.10.2019

Running:

asymmetric:

$$\begin{bmatrix} 0 & 2 & 3 & 2 & 2 \\ 2 & 0 & 2 & 2 & 2 \\ 3 & 2 & 0 & 2 & 2 \\ 2 & 2 & 2 & 0 & 2 \\ 2 & 2 & 2 & 2 & 0 \end{bmatrix} \Rightarrow$$



cyclic:

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix} \Rightarrow$$



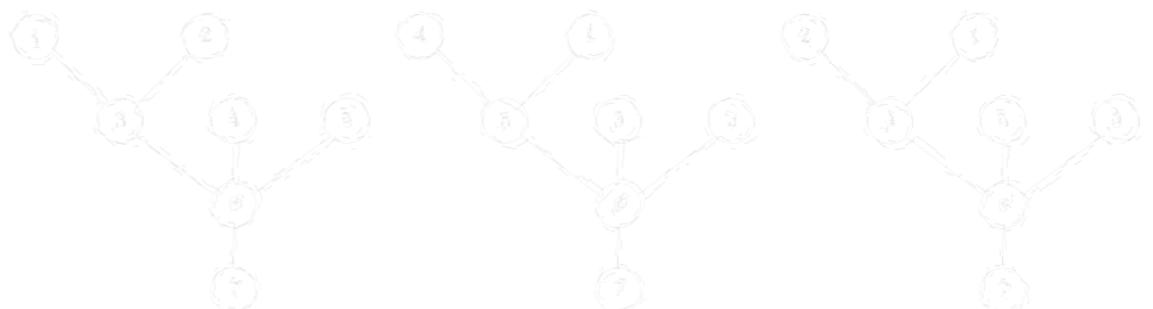
The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} 0 & 2 & * & 0 & * & 0 \\ 2 & 0 & 0 & * & x & 0 \\ * & 0 & 2 & 0 & 0 & * \\ 0 & * & 0 & 0 & * & 0 \\ * & x & 0 & 0 & 0 & * \\ 0 & 0 & * & 0 & * & 0 \end{bmatrix}.$$

At a first glance, there is nothing to think in the case of the four matrices that we have just displayed, but its graph,

which can best be explained by an analogy with a family tree. Thus, the root r is the predecessor of all the vertices in $V \setminus \{r\}$ and these vertices are successors of r . Moreover, every $v \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and v , as a predecessor of v and a successor of r . We say that the rooted tree T is *monotonically ordered* if each vertex is labelled before all its predecessors; in other words, we label the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so that $T = (G, r)$ is monotonically ordered. Then, that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ki}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

5 Rules of Writing Tests

Filter:

Module: Acceptance | Outline

EmberFest 18.10.2019

1 assertion of 1 passed, 0 failed.

If, if, if

cyclic:

$$\begin{bmatrix} * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \\ * & * & * & * & * & * \end{bmatrix} \Rightarrow$$



before all its predecessors in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three monotone orderings of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $T = (G, r)$ is monotonically ordered. Then, that $A = L U$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i \sim j} a_{ki}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

At a first glance, there is nothing to think in the case of the four matrices that we have just displayed, but its graph.

5 Rules of Writing Tests

Filter:

Module: Acceptance | Outline

EmberFest 18.10.2019

2 assertions of 2 passed, 0 failed.

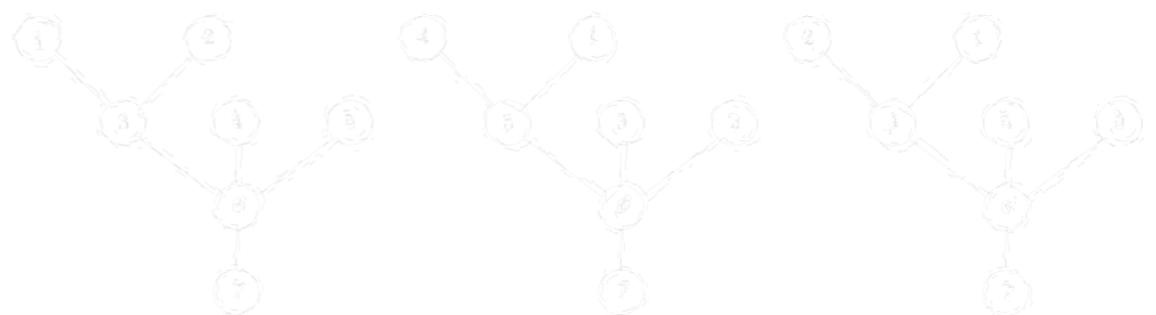
! If, if, if

! Use common, everyday words

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} * & * & * & 0 & * & 0 \\ 0 & * & 0 & * & * & 0 \\ * & 0 & * & 0 & * & * \\ 0 & * & 0 & * & 0 & * \\ * & * & 0 & 0 & * & * \\ 0 & 0 & * & * & * & * \end{bmatrix}.$$

At a first glance, there is nothing to think in to any of the four matrices that we have just displayed, but its graph.



Theorem 11.1 Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $\mathbf{T} = (G, r)$ is monotonically ordered. Given that $A = LL^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

5 Rules of Writing Tests

Filter:

Module:

Acceptance | Outline



EmberFest 18.10.2019

3 assertions of 3 passed, 0 failed.

! If, if, if

! Use common, everyday words

! Write less with theorems and new terms

$$\begin{bmatrix} * & * & * & 0 & * & 0 \\ 0 & * & 0 & * & * & 0 \\ * & 0 & * & * & 0 & * \\ 0 & * & 0 & * & * & 0 \\ * & * & 0 & * & * & 0 \\ 0 & * & * & 0 & * & * \end{bmatrix}.$$

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph:



Theorem 11.1 Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $\mathbf{T} = (G, r)$ is monotonically ordered. Then, that $A = \mathbf{L}\mathbf{U}^T$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ii}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

5 Rules of Writing Tests

Filter:

Module:

Acceptance | Outline



EmberFest 18.10.2019

4 assertions of 4 passed, 0 failed.

! If, if, if

! Use common, everyday words

! Write less with theorems and new terms

! All your basis are belong to us

$$\begin{bmatrix} 0 & 3 & 0 & 0 & 0 \\ 3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,

Theorem 11.1 Let A be a symmetric matrix whose graph G is a tree. Choose a root $r \in \{1, 2, \dots, d\}$ and assume that the rows and columns of A are then arranged so, that $\tilde{T} = (G, r)$ is monotonically ordered. Then, that $A = \tilde{L}\tilde{U}$ is a Cholesky factorization, it is true that

$$t_{k,j} = \frac{a_{kj}}{\sum_{i=1}^j a_{ki}}, \quad k = j+1, j+2, \dots, d, \quad j = 1, 2, \dots, d-1. \quad (11.5)$$

5 Rules of Writing Tests

Filter:

Module: [Acceptance](#) | [Outline](#) ▾

EmberFest 18.10.2019

5 assertions of 5 passed, 0 failed.

! If, if, if

! Use common, everyday words

! Write less with theorems and new terms

! All your basis are belong to us

! 1 picture = 1000 words

Therefore we will now give a few examples of matrices (represented by their sparsity pattern) and their graphs.

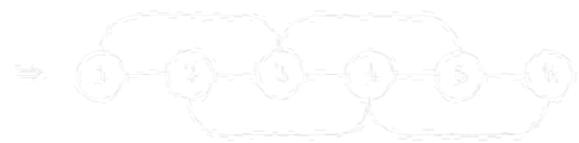
tridiagonal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ 0 & * & * & * & 0 & 0 \\ 0 & 0 & * & * & * & 0 \\ 0 & 0 & 0 & * & * & * \\ 0 & 0 & 0 & 0 & * & * \end{bmatrix}$$



qundiagonal:

$$\begin{bmatrix} * & * & 0 & 0 & 0 & 0 \\ * & * & * & 0 & 0 & 0 \\ * & * & * & * & 0 & 0 \\ * & * & * & * & * & 0 \\ * & * & * & * & * & * \\ * & * & * & * & * & * \end{bmatrix}$$



crunchingnumbers.live

@ijlee2

The graph of a matrix often reveals at a single glance its structure, which might not be evident from the sparsity pattern. Thus, consider the matrix

$$\begin{bmatrix} * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & 0 \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \\ * & 0 & * & 0 & * & 0 \\ 0 & * & 0 & * & 0 & * \end{bmatrix}.$$

At a first glance, there is nothing to link it to any of the four matrices that we have just displayed, but its graph,



tells a different story – it is nothing other than the cyclic matrix in disguised. To see this, just relabel the vertices as follows:

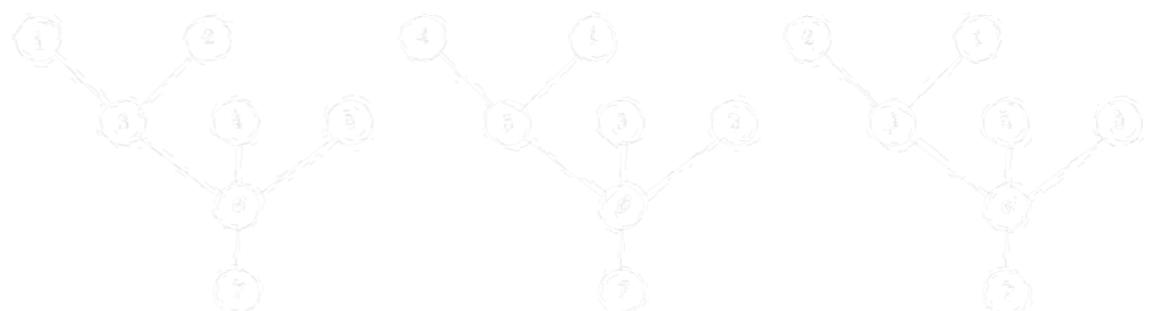
$$1 \rightarrow 1, \quad 2 \rightarrow 5, \quad 3 \rightarrow 2, \quad 4 \rightarrow 3, \quad 5 \rightarrow 6, \quad 6 \rightarrow 4.$$

This, of course, is equivalent to reordering (simultaneously) the equations and variables.

An ordered set of edges $\{(i_0, j_0)\}_{i_0, j_0 \in \{1, \dots, n\}}$ is called a path joining the vertices i_0 and j_0 if $i_0 \in \{i_0, j_0\}$, $j_0 \in \{i_0, j_0\}$ and for every $k = 1, 2, \dots, n-1$ the set $\{i_k, j_k\} \cap \{i_{k+1}, j_{k+1}\}$ contains exactly one member. It is a simple path if it does not visit any vertex more than once. We say that G is a tree if each two members of V are joined by a unique simple path. Both tridiagonal and qundiagonal matrices correspond to trees, but this is not the case with either qundiagonal or cyclic matrices when $n \geq 3$.

Given a tree T and an arbitrary vertex $r \in V$, the pair $T = (G, r)$ is called a rooted tree, where the vertex r is the root. Unlike in a ordinary graph, T admits a natural partial order which should be explained by an analogy with a family tree. Thus, the vertex r is the predecessor of all the vertices in $T \setminus \{r\}$ and these vertices are successors of r . Moreover, every $\alpha \in V \setminus \{r\}$ is joined to r by a simple path and we designate each vertex along this path, except for r and α , as a predecessor of α and a successor of r . We say that the rooted tree T is monotonically ordered if each vertex is labelled before all its predecessors in other words, we layed the vertices from the top of the tree to the root. (As we have already said it, relabelling a graph is tantamount to permuting the rows and the columns of the underlying matrix.)

Every rooted tree will be monotonically ordered and, in general, such an ordering is not unique. We now give three consecutive orderings of the same rooted tree.



Theorem 11.1. Let A be a symmetric matrix whose graph G is a tree. Consider a root $r \in \{1, 2, \dots, n\}$ and assume that the rows and columns of A are now arranged so, that $T = (G, r)$ is monotonically ordered. Given that $A = PLU$ is a Cholesky factorization, it is true that

$$l_{k,j} = \frac{a_{kj}}{p_{jj}}, \quad k = j+1, j+2, \dots, n, \quad j = 1, 2, \dots, n-1. \quad (11.5)$$

Q.E.D.