

Progress report:
Repair probabilities for the RCL polymer with
two DSBs

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1 Motivation

Double Strand Breaks (DSB) are a highly cytotoxic type of DNA damage that occur when both strands of duplex DNA break, for instance, after ionizing radiation and cancer chemotherapy. Two principal pathways of DSB repair have evolved: non-homologous end joining (NHEJ) and homologous recombination (HR). NHEJ is the major pathway of DSB repair and consists on the synapsis and ligation of the broken ends. Here, we aim to simulate and study the repair and misrepair rates after two DSBs, via the NHEJ pathway. Polymer models (and in particular, a generalization of the Gaussian chain, the Randomly Cross-Linked (RCL) Polymer) will be used as a model of the chromatin. Stochastic simulations of molecular dynamics will be performed with the goal of characterize the factors that contribute to interfere or improve the repair probability, namely: the distance between the DSBs, the degree of folding of the polymer (simulated by the number of cross-links connecting non-neighbor monomers) and the dispersion effect induced by the DNA repair machinery (simulated by exclusion forces and the local removal of cross-links in the damage foci).

2 Methods

2.1 The RCL polymer

To simulate the chromatin we consider the model of a randomly cross-linked (RCL) polymer. An RCL polymer is formed by a chain of N monomers connected by harmonic springs of constant κ as backbone, and N_c extra cross-links (CLs) which connect non-neighbor monomers with springs of constant κ' . CLs are added uniformly over all $\frac{(N-1)(N-2)}{2}$ combinations of non-neighbor monomer pairs. We also define the RCL polymer connectivity ξ as the fraction of added cross-links with respect to the total number of possible pairings, i.e. $\xi = \frac{2N_c}{(N-1)(N-2)}$.

We characterize the RCL polymer by two $N \times N$ admittance (Laplacian) matrices: the Rouse matrix M which describes the backbone, and B which describes the added connectors. A Laplacian matrix results from the difference between the diagonal degree matrix D that accounts for the total number of connections each monomer has, and the adjacency matrix A that accounts for the connectivity ($A_{m,n} = 1$ if monomers m and n are connected, 0 otherwise). So

$$M_{m,n} = (D_{\text{backbone}} - A_{\text{backbone}})_{m,n} = \begin{cases} -1 & \text{if } |m - n| = 1 \\ -\sum_{i=1, i \neq n}^N M_{i,n} & \text{if } m = n \\ 0 & \text{otherwise} \end{cases} \quad (1)$$

and, analogically

$$B_{m,n} = (D_{\text{CLS}} - A_{\text{CLS}})_{m,n} = \begin{cases} -1 & \text{if } m \text{ and } n \neq m \text{ are connected by a CL} \\ -\sum_{i=1, i \neq n}^N B_{i,n} & \text{if } m = n \\ 0 & \text{otherwise} \end{cases} \quad (2)$$

An schematic illustration of an RCL polymer is described in Fig. 1-A along with its respective Laplacian matrices (Fig.1-B).

2.2 Langevin dynamics of the RCL polymer

We supposed the RCL polymer subdued to Langevin dynamics, i.e., if monomer positions of the polymer in time t are represented by the $N \times 3$ matrix $(R_t)_{t \geq 0} = (R_1, \dots, R_N)_{t \geq 0}$ with each $R_i \in \mathbb{R}^3, i = 1, \dots, N$, the dynamics are described by Eq. (3):

$$dR_t = -\frac{1}{\zeta} \nabla \phi(R_t) dt + \sqrt{2D} dW_t \quad (3)$$

where ζ is the friction coefficient, ϕ is an harmonic potential, D is the diffusion coefficient and $(W_t)_{t \geq 0}$ is a $N \times 3$ -dimensional Brownian motion.

The harmonic potential of a RCL polymer is given by the classical Rouse potential and by the potential induced by the random cross-links:

$$\begin{aligned} \phi(R) &= \frac{\kappa}{2} \sum_{n=1}^{N-1} \|R_{n+1} - R_n\|^2 + \frac{\kappa'}{2} \sum_{i,j \in \mathcal{R}} \|R_i - R_j\|^2 \\ &= \frac{\kappa}{2} \text{tr}(R^T M R) + \frac{\kappa'}{2} \text{tr}(R^T B R) \end{aligned} \quad (4)$$

where κ and κ' are spring constants we will suppose equal, \mathcal{R} is the set of monomers which have been randomly connected, and M and B are the Laplacian matrices introduced in Eq. 1 and Eq. 2. Since $\frac{\kappa}{\gamma} = \frac{3D}{b^2}$ where b is the standard deviation of the bonds length, we'll consider the matrix equation:

$$dR_t = -\frac{3D}{b^2} (M + B) R_t dt + \sqrt{2D} dW_t \quad (5)$$

In the following, we implement the Euler's scheme of Eq. 5, setting $D = 0.008 \mu^2 \text{m/s}$ and $b = 0.2 \mu\text{m}$. When it is important, the Δt used in the discretization of Eq. 5 will be specified. $\Delta t = 0.005 \text{ sec}$ will be the usual value. Anyhow, to assure numerical stability, condition in Eq. 6 must always be verified [Ref].

$$\sqrt{2D\Delta t} \leq c\Delta r^* \quad (6)$$

In Eq. 6, Δr^* stands for the smallest spatial scale used (it will normally be the monomers encounter distance as it is defined later on) and c is a confidence factor that will be set at $c = 0.2$ in the simulations.

2.3 Useful statistical properties of the RCL polymer

Some useful statistical properties will be measured to study the polymer repair. For instance, the Mean Radius of Gyration (MRG) will be computed as a proper indicator of the polymer compaction. The MRG is defined as the root mean square distance from each monomer to the center of mass of the polymer (Eq. 7).

$$\text{MRG}(R) = \sqrt{\frac{1}{N} \sum_{m=1}^N (R_m - \bar{R})^2} \quad (7)$$

It has been proven [2] that for a given connectivity fraction ξ and when the connectivity is low ($N_c \ll \frac{1}{2}N^2$) the mean square radius of gyration MSRG (MRG²) can be approximated by Eq. 8.

$$\text{MSRG}(\xi) \approx \frac{3b^2}{4(1-\xi)\sqrt{N\xi}} \quad (8)$$

2.4 Induction of Double Strand Breaks (DSBs)

In particular, we are interested on the probability of repair after two DSBs. One DSB (damage focus «A») will be randomly induced between neighbor monomers A_1 and $A_2 = A_1 + 1$, where $A_1 \sim \mathcal{U}[1, N - g - 2]$. The other DSB (damage focus «B») will be induced in neighbor monomers B_1 and B_2 . A deterministic inter-break genomic distance g will be imposed between A and B, defined as the shortest distance between the DSBs along the backbone, i.e. $g = B_1 - A_2$. A scheme of two DSBs is represented in Fig. 1-C. The two breaks define thus three interconnected fragments: the upstream fragment (formed by monomers 1 to A_1), the central fragment (monomers A_2 to B_1) and the downstream fragment (monomers B_2 to N).

2.5 Definition of encounter times and probabilities

We define the first encounter time between monomers m and n as

$$T_{m,n}^\epsilon := \inf\{t \geq 0 : \|(R_m)_t - (R_n)_t\| < \epsilon\} \quad (9)$$

where ϵ is the encounter distance. Then, the repair probability is defined as

$$\mathbb{P}(\text{Repair}) = \mathbb{P}(\inf\{T_{A_1,A_2}^\epsilon, T_{B_1,B_2}^\epsilon\} \leq \inf\{T_{A_1,B_1}^\epsilon, T_{A_1,B_2}^\epsilon, T_{A_2,B_1}^\epsilon, T_{A_2,B_2}^\epsilon\})$$

and the First Encounter Time (FET) as:

$$\text{FET} = \inf\{T_{A_1,A_2}^\epsilon, T_{B_1,B_2}^\epsilon, T_{A_1,B_1}^\epsilon, T_{A_1,B_2}^\epsilon, T_{A_2,B_1}^\epsilon, T_{A_2,B_2}^\epsilon\}$$

We remark that when monomers are well mixed, the expected repair probability is $2/6 = 1/3$ (favorable encounters / total possible encounters).

2.6 Simulation of chromatin decondensation around DSBs: Removal of CLs and Excluded Volume Interactions

It has been reported that the DNA repair machinery induces a relaxation of the chromatin around damage foci (DF) [Ref]. To simulate this dispersion two effects are considered independently: the removal of CLs in the damage foci to induce decompactation of the polymer around the breaks; and the addition of an exclusion potential around the damaged monomers, to simulate self-avoidance towards the cut ends.

In general, excluded volume forces are added to the polymer dynamics through a new harmonic potential ϕ_{ev} that is added to the potential ϕ defined in Eq. 4:

$$\phi_{ev}(R) = -\frac{\kappa_{ev}}{2} \sum_{i,j : i \neq j} ||R_i - R_j||^2 1_{||R_i - R_j|| < \sigma} \quad (10)$$

where σ is a cutoff radius of exclusion and $1_{||R_i - R_j|| < \sigma} = 1$ if $||R_i - R_j|| < \sigma$ and 0 otherwise.

In our case, to simulate the dispersion of chromatin around DSBs only, we'll induce first volume exclusion for the DF monomers only and take $\kappa_{ev} = \kappa$:

$$\phi_{local-ev}(R) = -\frac{\kappa_{ev}}{2} \sum_{i \in DF} \sum_{j \neq i} ||R_i - R_j||^2 1_{||R_i - R_j|| < \sigma} \quad (11)$$

Later on, considering that in spite of the exclusion induced by repair proteins, the whole repair machinery looks for affine ends to join them, we'll consider repair exclusion spheres that repel all monomers except the other cut ends. So, if any two cut ends approach they won't feel exclusion forces. This new exclusion potential ϕ_{repair}^{sphere} is defined in Eq. 12.

$$\phi_{repair}^{sphere}(R) = -\frac{\kappa_{ev}}{2} \sum_{i \in DF} \sum_{j \notin DF} ||R_i - R_j||^2 1_{||R_i - R_j|| < \sigma} \quad (12)$$

Thereby, volume exclusion potentials originate a new Laplacian E as defined in Eq. 13, that will be added to the Laplacian matrices considered up to now (Eq. 5):

$$E_{m,n} = \begin{cases} -1 & \text{if } m \in DF, n \notin DF \text{ and } ||R_m - R_n|| < \sigma \\ -1 & \text{if } n \in DF, m \notin DF \text{ and } ||R_m - R_n|| < \sigma \\ -\sum_{i=1, i \neq n}^N E_{m,i} & \text{if } m = n \\ 0 & \text{otherwise} \end{cases} \quad (13)$$

So when exclusion forces are considered the simulated system will subdue the dynamic described by Eq. 14.

$$dR_t = -\frac{3D}{b^2} (M + B + E) R_t dt + \sqrt{2D} dW_t \quad (14)$$

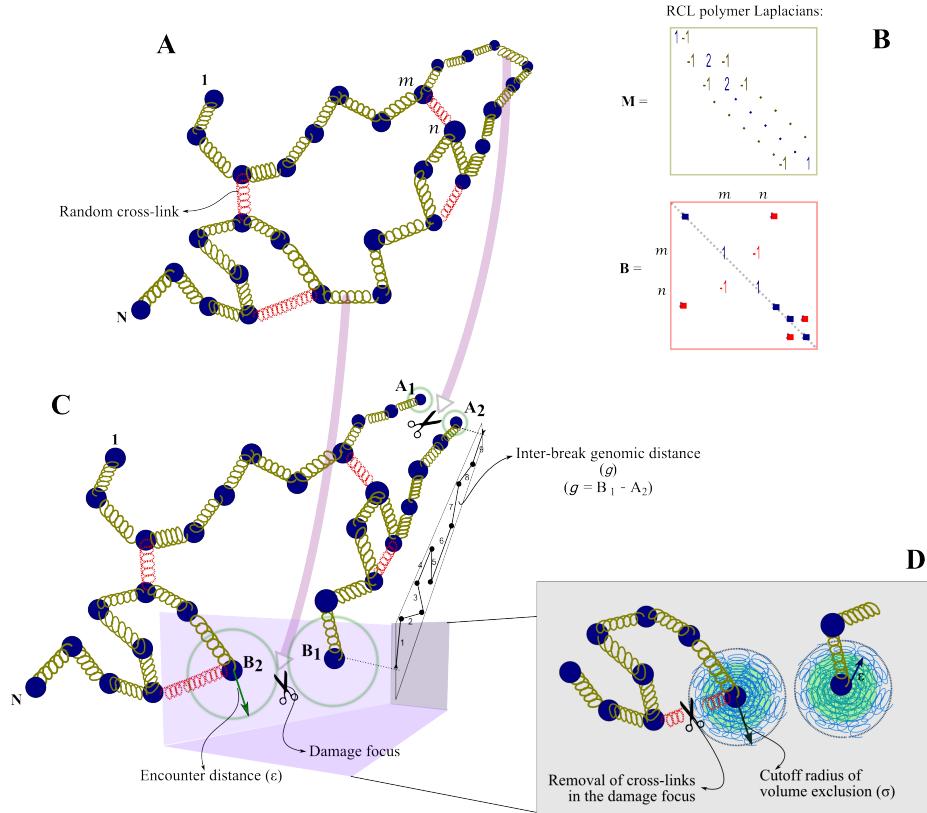


Figure 1: Model of an RCL polymer for chromatin repair simulations. **A:** Example of the Rouse backbone with some cross-links. **B:** Laplacian matrices of the RCL polymer represented in **A**: the Rouse matrix (M) and the CLs matrix (B). **C:** Scheme of the induction of two DSBs A and B at a distance g . **D:** To simulate the effect of the sparsity induced by the repair machinery, excluded volume forces are added in the damage foci and the concerned CLs are removed.

We call the total $M + B + E$ the total Laplacian matrix of the system. The two decondensation effects are summarized in Fig. 1-D.

2.7 Scaling distances under condensation: ξ -adaptive encounter distances and exclusion radii

As indicated by Eq. 8 (cf. Fig. 9 for an empirical example), as N_c (equivalently ξ) increases the polymer compaction increases too. Since the spatial scale of a compact polymer is different from the spatial scale used by a decompact polymer, and thus for the same ε , an encounter which is rare enough for the later might be too common for the former, for a more compact polymer, smaller

spatial scales should be used. In effect, scaling ε and σ for different degrees of compaction will allow to measure the repair rates conditionally to the compaction, invariantly to the polymer size. So ε and σ will be redefined to be ξ -adaptive and preserve the spatial scale. Thus, ε and σ will be proportional to the polymer mean size, and in particular, to the MRG. Starting from Eq. 8 we will define the adaptive encounter distance $\tilde{\varepsilon}(\xi)$ as in Eq. 15, and the adaptive cutoff radius of exclusion $\tilde{\sigma}(\xi)$ as in Eq. 16, where $v > 1$ is a factor which indicates how much bigger is the exclusion sphere with respect to the encounter distance.

$$\begin{aligned}\tilde{\varepsilon}(\xi) &= 2\sqrt{\frac{3b^2}{N(1-\xi)\sqrt{y^2-1}}} \\ y &= 1 + \frac{N\xi}{2(1-\xi)}\end{aligned}\tag{15}$$

$$\tilde{\sigma}(\xi) = v \cdot \tilde{\varepsilon}(\xi)\tag{16}$$

2.8 Pipeline of the simulations

A number I of independent polymer realizations will be simulated to extract mean statistical properties and the repair probabilities conditional to the parameters defined so far. The main pipeline of each realization goes as described below:

1. **Initialization of the polymer backbone** from a random walk in \mathbb{R}^3 where each step is i.i.d. $\mathcal{N}(0, b^2)$.
2. **Predefinition of DSBs A and B .** We take $A_1 \sim \mathcal{U}[1, N - g - 2]$ and then $A_2 = A_1 + 1$, $B_1 = A_2 + g$, $B_2 = B_1 + 1$.
3. **Induction of random cross-links.** N_c cross-links are induced between non-neighbor monomers such that after breaks A and B the polymer rests fully connected. In practice, we make random connections until obtaining one which verifies the full connectivity condition.
4. **Relaxation.** Once the polymer is validly cross-linked, the polymer is subdued to Langevin dynamics (discretized as an Euler's scheme for Eq. 5) until relaxation time τ , which is computed analytically [Ref] as:

$$\tau = \frac{\dots}{\dots}$$

5. **DSBs Induction and actualization of the total Laplacian matrix.** When the polymer reaches relaxation time, the two cuts are induced between the predefined monomers A_1 , A_2 and B_1 , B_2 . Removed bonds are thus cleaned out from the Laplacian matrix. Besides, if CLs are removed from the separated monomers and if Volume Exclusion is included, those effects are also added to the Laplacian as in Eq. 14.

6. **Waiting.** As a way to exclude the repair events which happen immediately after the break, and since the DNA repair is not instantaneous (it requires the arrival of specific proteins to the cut ends), the polymer is let to evolve under Eq. 5 for some waiting time T_{wait}
7. **Simulation until encounter.** Once T_{wait} is reached, simulation continues until an encounter, as defined in Eq. 9, happens between any of the cut ends. If two or more pairs of monomers encounter at the same simulated instant, we randomly choose over those pairs to be the first encounter. If no encounters occur before a threshold time T_{max} the simulation is discarded.
8. Statistical properties and the encounter event that occurred (repair or misrepair) are saved and a new polymer is initialized to perform the same simulation.

Finally, the conditional probability of repair is estimated as

$$\mathbb{P}(\text{Repair}|\Theta) = \frac{\text{Number of } A_1\text{-}A_2 \text{ or } B_1\text{-}B_2 \text{ encounters}}{\text{Total number of encounters}}$$

where Θ summarizes the experiment parameters,

$$\Theta = (N, b, N_c, g, \varepsilon, \sigma, T_{wait}, T_{max}).$$

3 Results

3.1 First Encounter Time (FET) distribution when CLs are kept and removed in the damage foci

Since the FET distribution can be approximated by a single exponential [1], an exponential function with amplitude a and rate λ as parameters, $t \mapsto a \exp(-\lambda t)$, is fitted to the frequency histograms, aiming to compare the λ fitted in each one of the experiments sets.

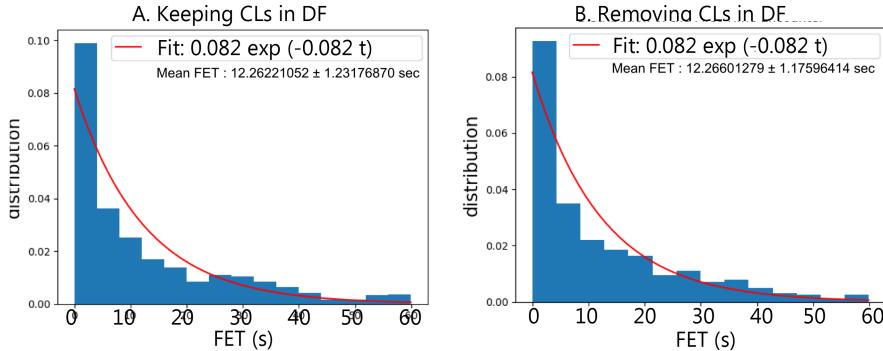
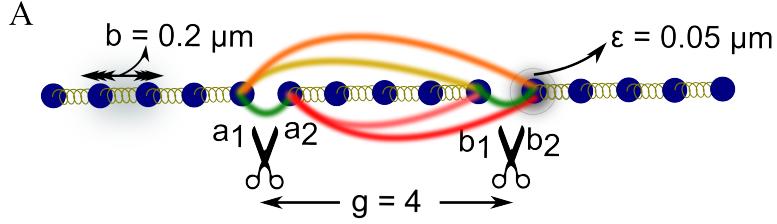


Figure 2: Distribution of the first encounter time keeping and removing the cross-links in the cleaved monomers. An exponential function has been fitted to each histogram. $N = 100$ monomers, $N_c = 5$, $g = 10$, $T_{wait} = 25\text{sec}$, and $T_{max} = 60\text{sec}$.

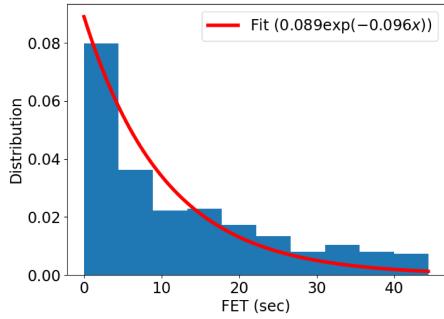
The results in Fig. 2 indicate that the removal of cross-links does not seem to affect the mean first encounter time, the estimated rate parameter (λ) is 0.08 for both cases. Nonetheless, it's no surprising considering that for $N = 100$ and $N_c = 5$ the mean number of connectors in the DF is about 0.4, so the removal of CLs is not actually occurring for the majority of cases. To overcome this situation and to properly study the effect of removing the CLs a new Laplacian matrix will be included, which will impose a certain number N_d of extra cross-links in the DF monomers. Fig. 3 shows the difference in the FET distributions when we impose $N_d = 2$ CLs in the DF. We can see that when we remove the 2 imposed CLs the mean FET increases in 2 seconds, and the repair rate increases as well. We also observe that when we remove the CLs the most common misrepair corresponds to the looping of the central segment of the broken polymer (A_2-B_1). In the spirit way Fig. 4 shows that increasing the imposed N_d reduces the mean FET when those CLs are kept, but not when they are removed.

In the following, we will determine the effect of the removal of CLs with respect to the inter-break distance g and the number of random CLs N_c .



Keeping CLs in DF

B.1

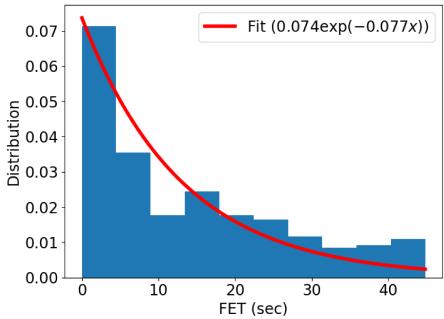


B.2



Removing CLs in DF

C.1



C.2

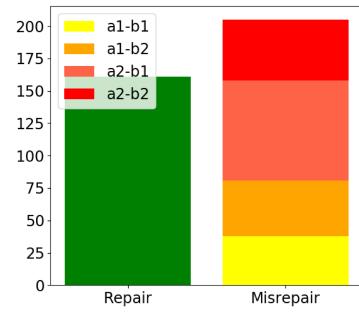


Figure 3: Distribution of the first encounter times and events, keeping and removing the cross-links when imposing CLs in the DF. Both results corresponds to $I = 500$ simulations, with $N = 100$, $N_c = 12$, $N_d = 2$, $g = 10$, $\varepsilon = 0.05\mu\text{m}$, $T_{max} = 45$ sec, $T_{wait} = 2.5$ sec and $\sigma = 0$ (no volume exclusion). **A:** Schematic representation of the experimental set and possible encounters. **B:** Results keeping CLs in DF. **1.** Histogram of relative frequencies and fitted exponential function, with an estimated rate of 0.096 and a mean FET of 12.600 ± 1.032 sec. **2.** Encounter events distribution. **C:** Results removing CLs in DF. **1.** Histogram of relative frequencies and fitted exponential function, with an estimated rate of 0.077 and a mean FET of 14.171 ± 1.117 sec. **2.** Encounter events distribution.

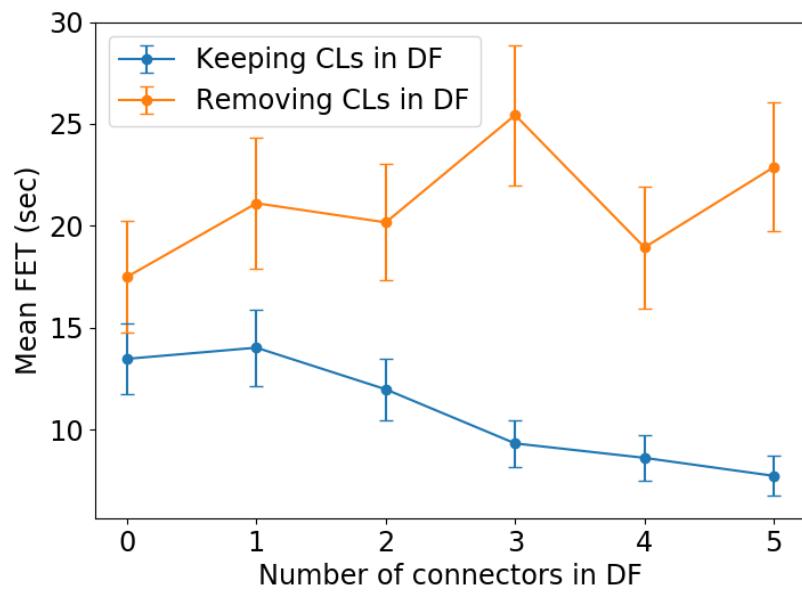


Figure 4: Mean FET as function of N_d when CLs in the DF are kept and removed. $N_c = 12$ and ε is $(N_c + N_d)$ -adaptive, ranging from $0.096 \mu\text{m}$ ($N_d = 0$) to $0.088 \mu\text{m}$ ($N_d = 5$).

3.2 Changes on the repair probability conditionally to g , N_c and decondensation

3.2.1 Effect of g on the repair probability

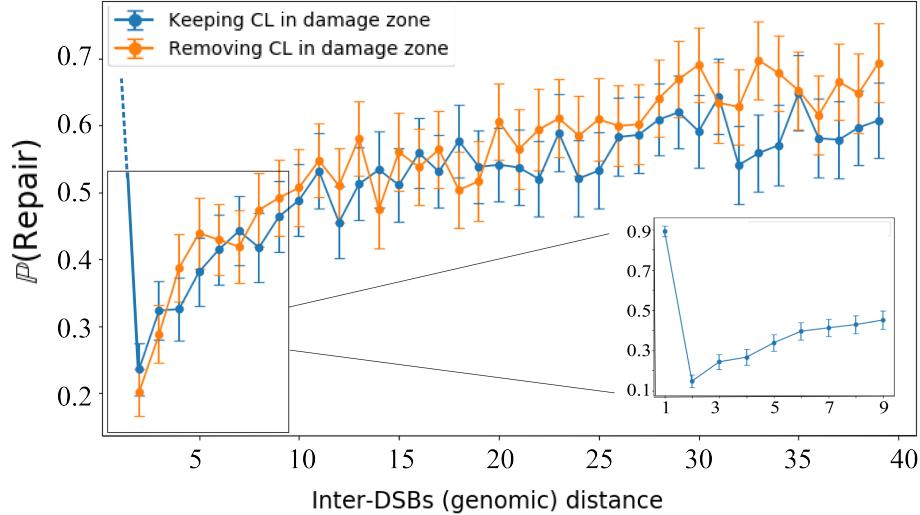


Figure 5: Repair probability as function of the genomic distance g between the two DSBs. $N = 100$, $N_c = 15$, $\varepsilon = 0.1\mu\text{m}$ and $N_d = 0$ (no CLs imposed in DF).

Fig. 5 shows that regardless the removal of cross-links, repair probability increases as the inter-break genomic distance increases.

Besides, when we keep CLs in the DF, we can remark an important gap between the probabilities at $g = 1$ (i.e., the two DSBs are connected, $A2$ and $B1$ being neighbors) and the other genomic distances (Fig. 5 Zoom). As only valid cuts are allowed (the polymer rests fully connected after the breaks) the central segment is indeed connected to the upstream and/or the downstream fragment. The probability of being connected to only one of them is higher than the probability of being connected to both, so the segment could be pushed towards one of the free monomers rapidly and then induce a good ratio of repair. This case will be treated as an out-layer from now on, and thus the following comparative analysis will be performed for $g \geq 2$.

Fig. 5 does not show any significant difference for the removal of CLs, because no CLs were imposed in the DF. However, imposing $N_d = 2$, as in Fig. 6 and 7, shows that the removal of DSB' CLs helps the reparation for distant breaks. Nonetheless, near breaks ($g < 10$) seems to perform better reparation rates when the CLs are kept in the DF. Fig. 7 complements Fig. 6 and show the effect of g and the removal of CLs in other observables (the MSRG at encounter time, the mean FET and the fitted rate parameter λ to the FET distribution). We observe that at encounter time the MSRG is, as expected, bigger when we

remove CLs (the polymer is more decompact). We also see that removing CLs extend the FET.

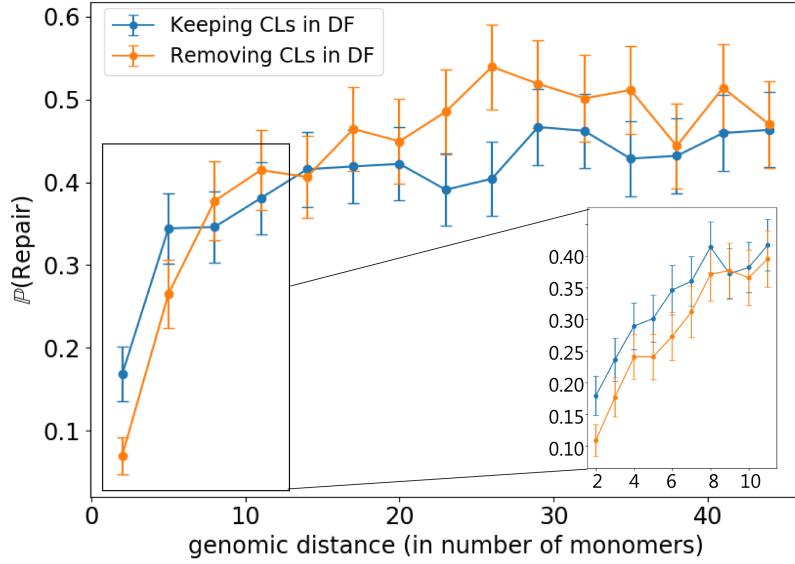


Figure 6: Repair probability as function of g when $N = 100$, $N_c = 15$, $\varepsilon = 0.1\mu\text{m}$ and $N_d = 2$ (2 CLs imposed in DF) which are kept (blue) or removed (orange) after the induction of the DSBs. ($I = 500$ simulations)

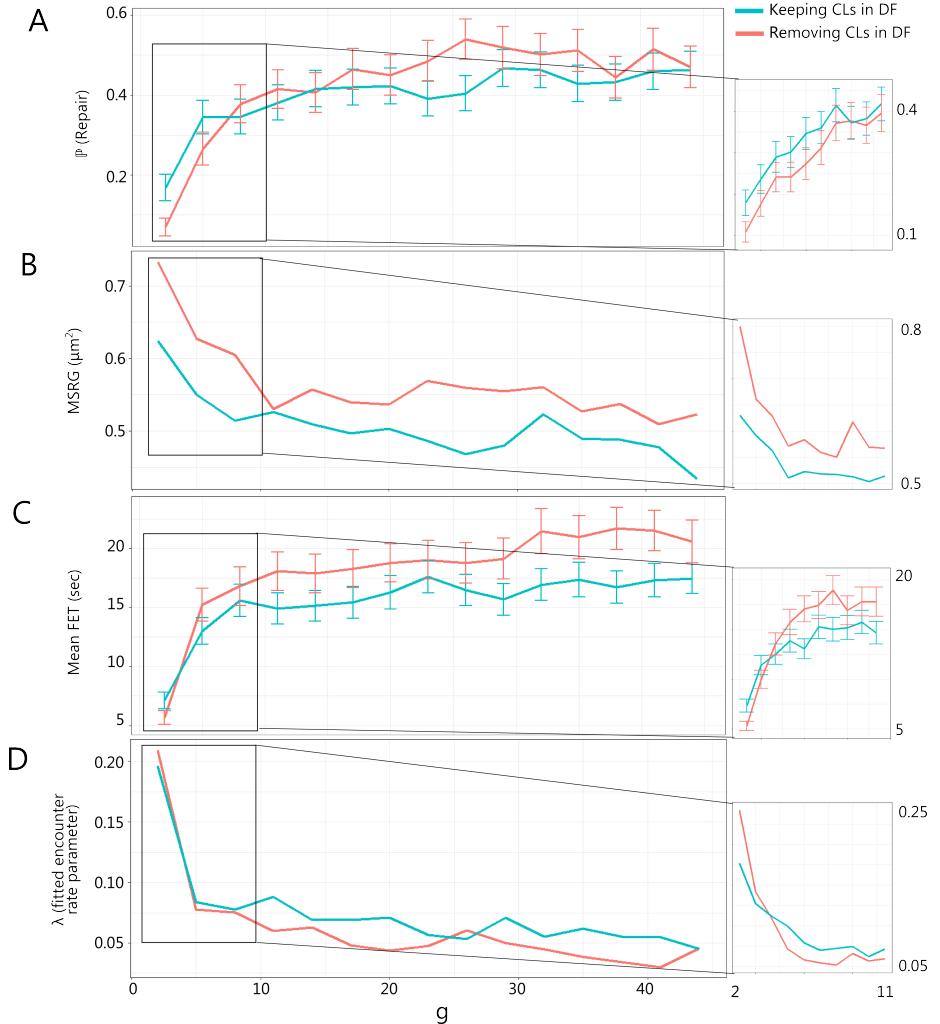


Figure 7: Repair probability (A), MSRG at encounter time (B), mean FET (C) and estimated encounter rate parameter (λ) (D) as functions of g when $N = 100$, $N_c = 15$, $\varepsilon = 0.1\mu\text{m}$ and $N_d = 2$ (2 CLs imposed in DF). A window zooming in $g \in [2, 11]$ with 500 simulations for each g is at the right of each graph.

3.2.2 Effect of N_c on the repair probability

3.2.2.1 Effect of N_c under fixed ε

Increasing the number of cross-links approaches the simulated probabilities to $1/3$, which is the result expected in the well-mixed case, as we observe in Fig. 8. Indeed, increasing the number of CLs and therefore approaching all monomers not only increases the chances of repair, but also of mismatch. The well-mixed scenario is particularly favored by the fact that a constant ε is used as encounter distance, despite the increasing compactness induced by the addition of CLs. Anyhow, it is interesting that systems which had a repair probability $\leq 1/3$ because had DSBs at a very small genomic distance ($g \leq 3$) (so the chances of a bad matching were higher) improve their repair probabilities when we increase the number of cross-links.

Fig. 9 proves that increasing the number of random connectors increases as well the compactness of the polymer, revealed as a decrease of the mean radius of gyration. Besides, we can see that the position of the breaks does not affect the ensemble mean of the gyration radius.

In conclusion, **the compactness help to repair polymers cut in a small neighborhood.** This is coherent with which was observed in Fig. 7-A, where at small genomic distances, the repair probabilities were better when CLs were kept in the DF. On the other hand, at a big genomic distance ($g = 20$), it can be observed in Fig. 10 that the presence of CLs in the DSB's monomers swifts the repair probabilities down, although the removal of those CLs after the break.

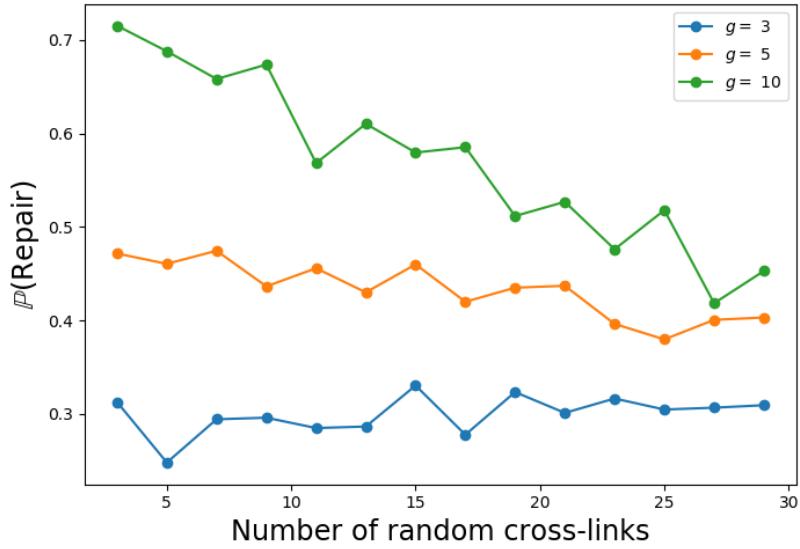


Figure 8: Repair probability as a function of N_c for $N = 100$, $\varepsilon = 0.1\mu\text{m}$ and $N_d = 0$. If any, CLs are removed in DF.

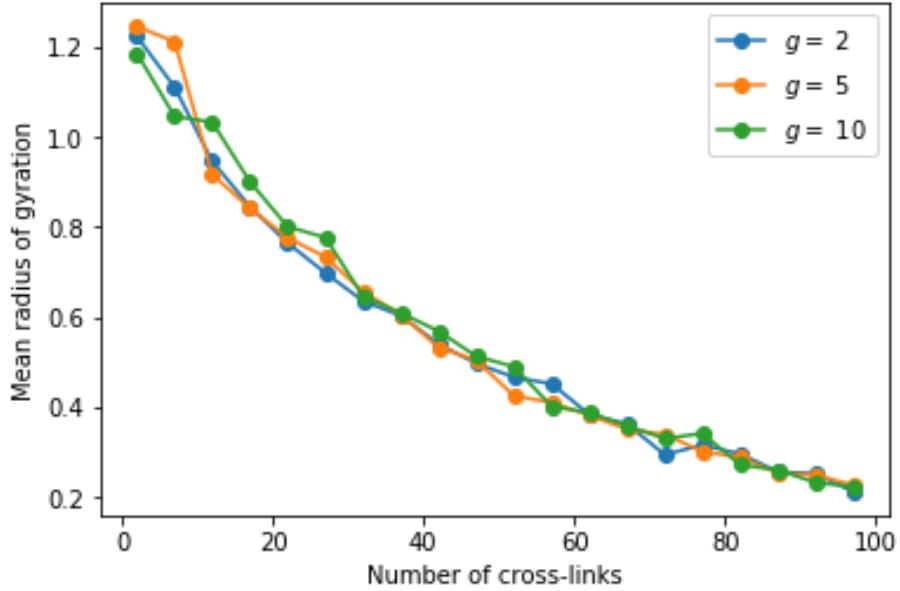


Figure 9: Polymer of 100 monomers. Mean radius of gyration in function of the number of cross-links.

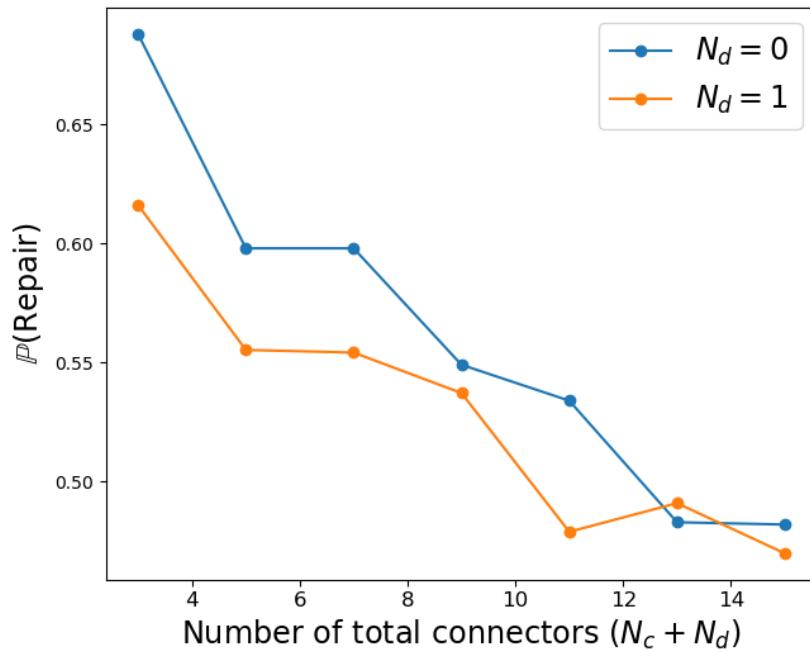


Figure 10: Repair probability in function of the total number of polymer CLs ($N_c + N_d$) where N_d is fixed to 0 (blue) and 1 (orange). In both cases, CLs are removed from the DF monomers, $N = 100$, $g = 20$, $\varepsilon = \tilde{\varepsilon}(\xi)$ according to Eq. 15 and the step Δt is also adapted such that Eq. 6 remains verified.

3.2.2.2 Effect of N_c under a ξ -adaptive ε

We use now an adaptive ε that evolves according the polymer compactness, i.e., according to the fraction ξ defined by N_c , following the formula in Eq. 15. Fig. 11 shows the adaptivity of ε compared with the MRG for different N_c 's.

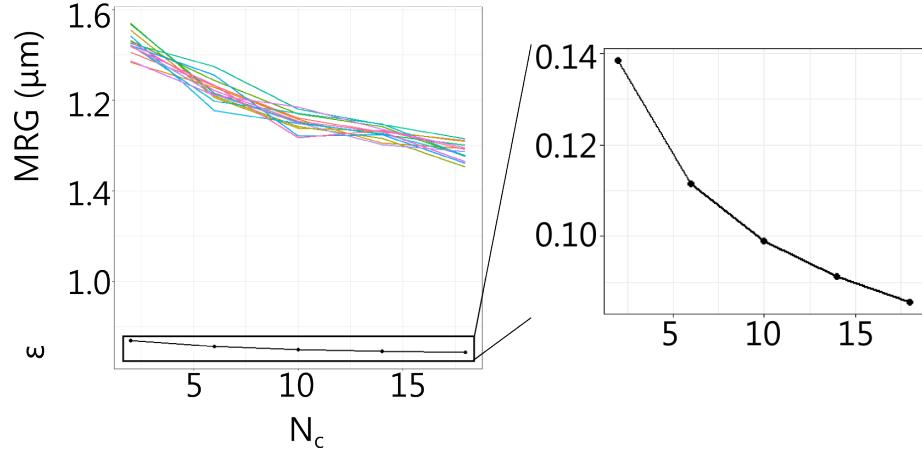


Figure 11: $\tilde{\varepsilon}(\xi)$ for different values of N_c and comparison with the MRG curve.

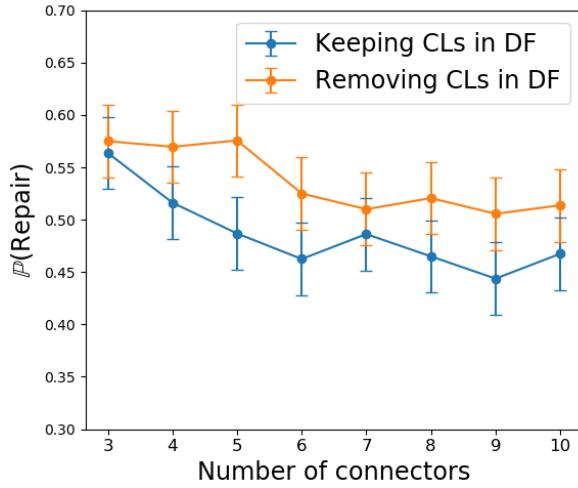


Figure 12: Repair probability in function of N_c when $N_d = 2$, $g = 20$ and $\varepsilon = \tilde{\varepsilon}(\xi)$.

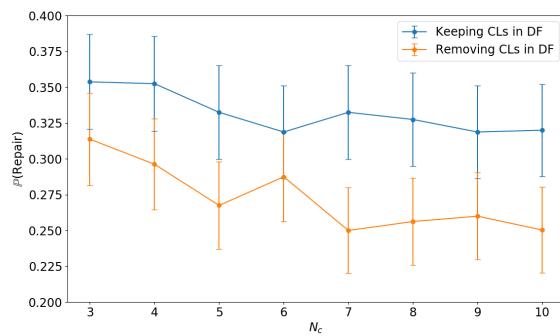


Figure 13: Repair probability in function of N_c when $N_d = 2$, $g = 4$ and $\varepsilon = \tilde{\varepsilon}(\xi)$.

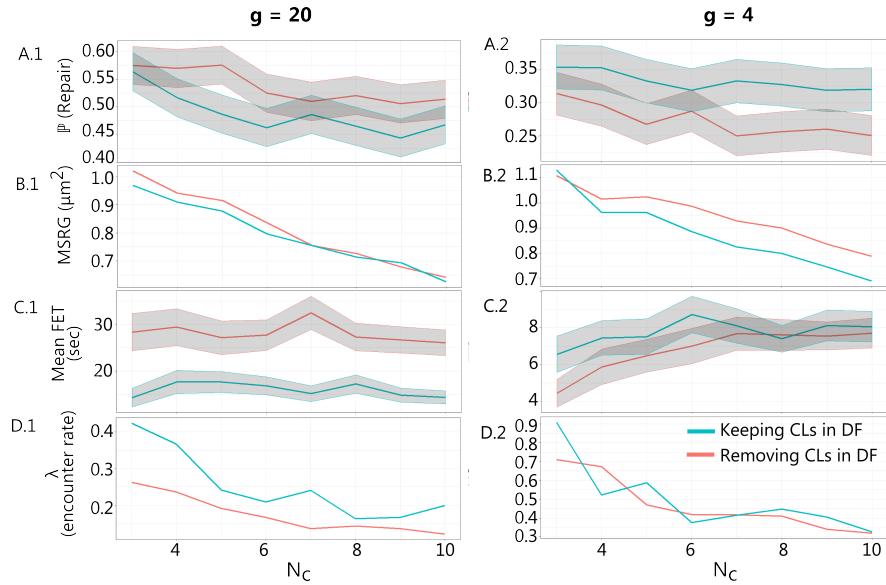


Figure 14: Repair probability (A), MSRG at encounter time (B), mean FET (C) and fitted encounter rate parameter (λ) (D) as functions of N_c when $g = 20$ (left) and $g = 4$ (right), for $N = 100$, $N_d = 2$ and $\varepsilon = \tilde{\varepsilon}(\xi)$.

Summary of the effects of g and N_c on the repair and induced differences keeping or removing CLs in the DF

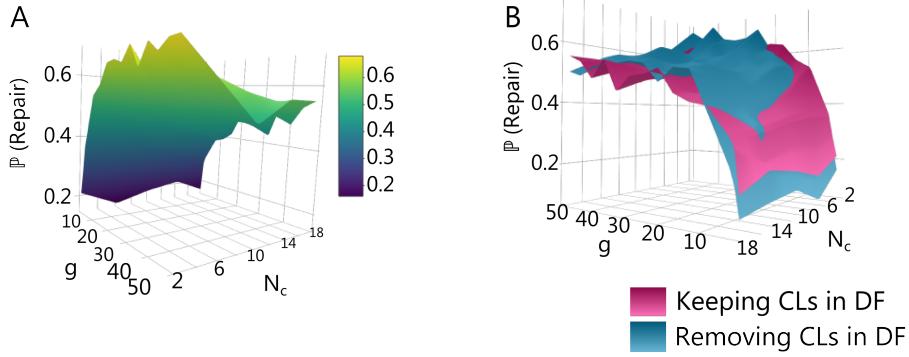


Figure 15: Repair probability as function of g and N_c with $N = 100$, $N_d = 1$ and ξ -adaptive ε . **A.** Probability surface when CLs are kept in the DF. **B.** Comparison between the probability surfaces when CLs are kept (as in A) and removed.

3.2.3 Effect of volume exclusion on the repair probability

3.2.3.1 Effect of undiscriminating exclusion

First we consider volume exclusion around the DF monomers and affecting indiscriminately every monomer reaching the exclusion region. We'll see how increasing the value of the exclusion radius σ affects the repair probability in this case.

Fig. 16 shows larger values of σ make the waiting for looping times last longer and thus make the encounter events rarer for the same N_c , however they do not affect dramatically the repair probability overall (Fig. 17).

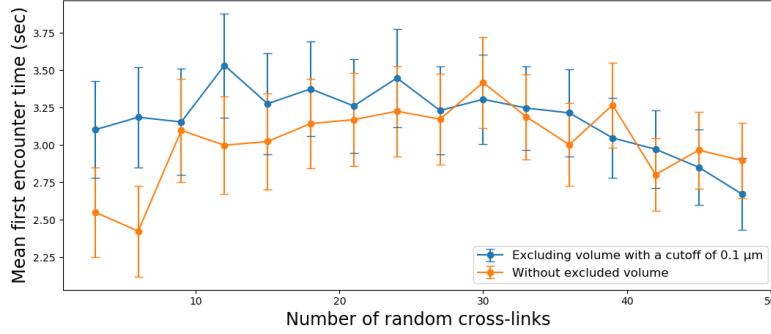


Figure 16: Mean FET in function of N_c , with and without an excluded volume of $\sigma = 0.1 \mu\text{m}$. ε is fixed at $0.04 \mu\text{m}$ and so, either ε and σ are adapted to the polymer compaction.

Fig. 18 shows that, as expected, the misrepair scenarios are associated with smaller radius of gyration, i.e. **misrepair happens in a compact polymer**. This could be an indication that decondensation of the polymer chain in the damage loci could lead to better repair probabilities.

It can be observed that **the repair probability function considering excluded volume interactions is always below the repair probability in the non-excluded case** (Figs. 19 and 20). Even for small genomic distances and high connectivity (20 random cross-links) the local volume exclusion seems to interfere with the correct repair, rather than helping it. (21 and 22)

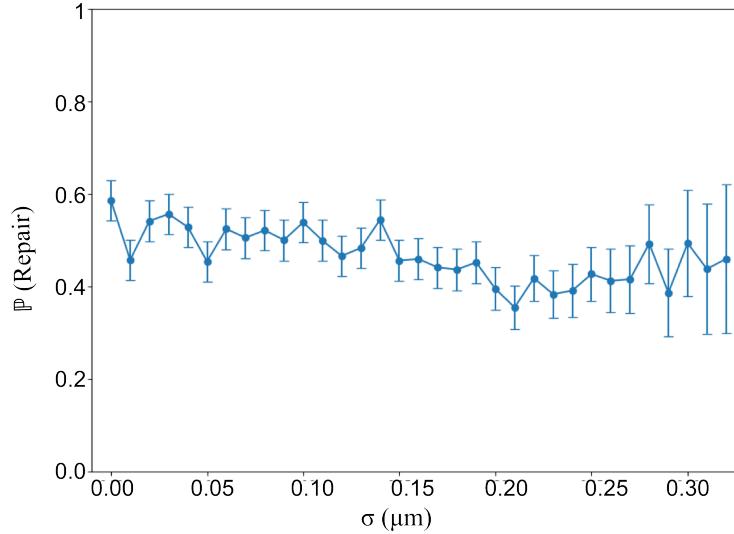


Figure 17: Probability and 95% confidence interval of repair, in function of the cutoff radius of volume exclusion.

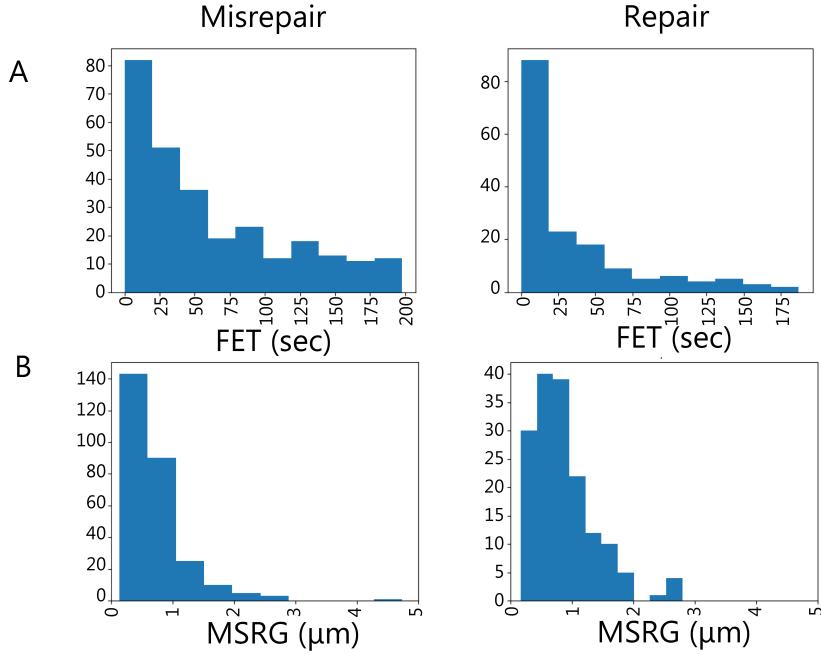


Figure 18: Distribution of FET (A) and MSRG at encounter time (B) in misrepair (left) and repair (right) events considering local excluded volume interactions with $\sigma = 0.1\mu\text{m}$.

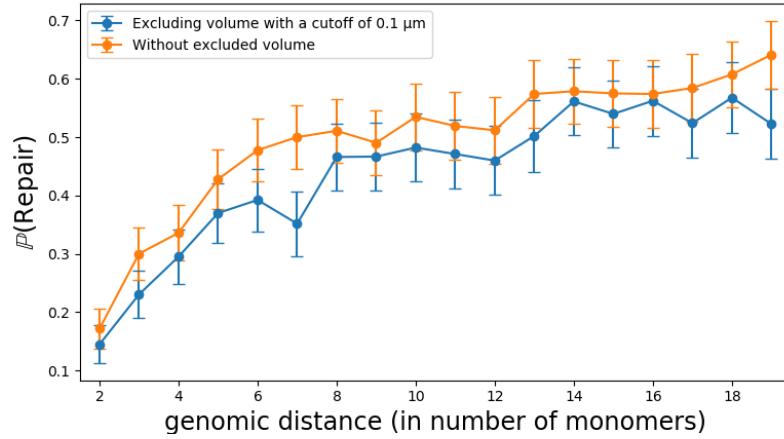


Figure 19: Probability of repair in function of the genomic separation between the breaks.

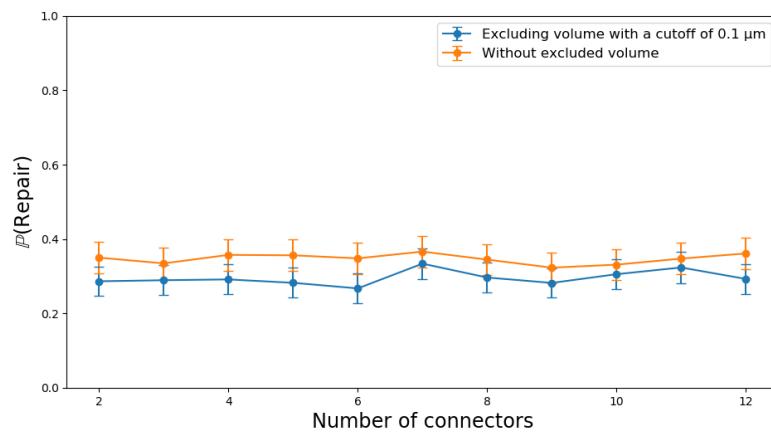


Figure 20: Probability of repair in function of the number of random cross-links, for two breaks separated by 4 monomers ($g=5$).

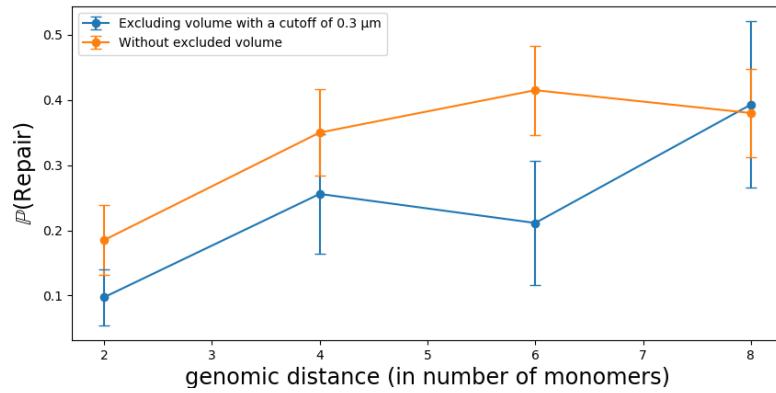


Figure 21: Probability of repair in function of the genomic separation between the breaks.

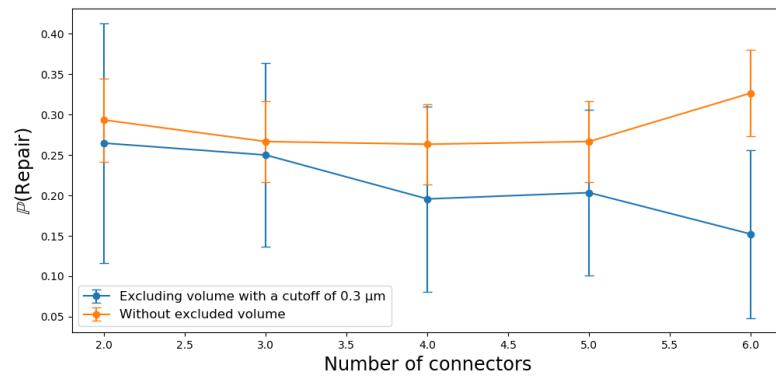


Figure 22: Probability of repair in function of the total number of cross-links, with an inter-break genomic distance $g = 4$.

3.2.3.2 Effect of a selective repair sphere

Now a repair sphere will be considered, which will repeal any monomer that is not one of the DF cut ends. On the other hand, DF monomers will not be repealed, which is performed adding the potential $\phi_{\text{repair}}^{\text{sphere}}$ defined in Eq. 12.

Fig. 23 shows that the selective repair sphere, when $N_d = 1$ CLs are imposed in the DF, allows to achieve better repair probabilities. Indeed, larger σ lead to a greater repair probability. At the same time, larger σ induce shorter FETs. For $\sigma = b = 0.2 \mu\text{m}$ the encounter rate increases significantly (23-C and D). But, even though the encounter occurs rapidly, the repair rate is higher.

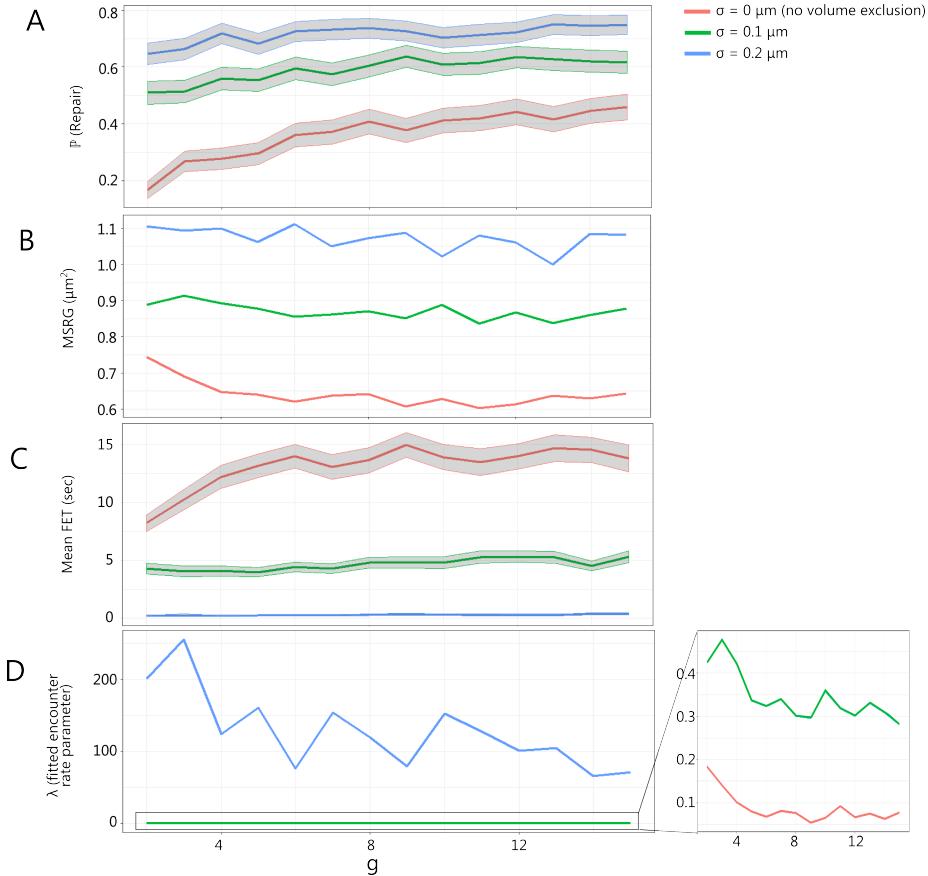


Figure 23: Repair probability (A), MSRG at encounter time (B), mean FET (C) and fitted encounter rate parameter (λ) (D) as functions of g for $\sigma = 0, 0.1 \mu\text{m}$ and $0.2 \mu\text{m}$. $N = 100$, $b = 0.2 \mu\text{m}$, $N_c = 10$, $N_d = 1$, $\varepsilon = 0.05 \mu\text{m}$.

Now, for an increasing N_c and adapting both σ and ε to the connectivity as indicated by Eqs. 15 and 16, Fig. 24 shows that the scaled selective volume

exclusion leads to better repair probabilities. Thus, contrastively to the undiscriminating volume exclusion, **the selective repair sphere, particularly with scaled encounter and cutoff radii, helps the repair.**

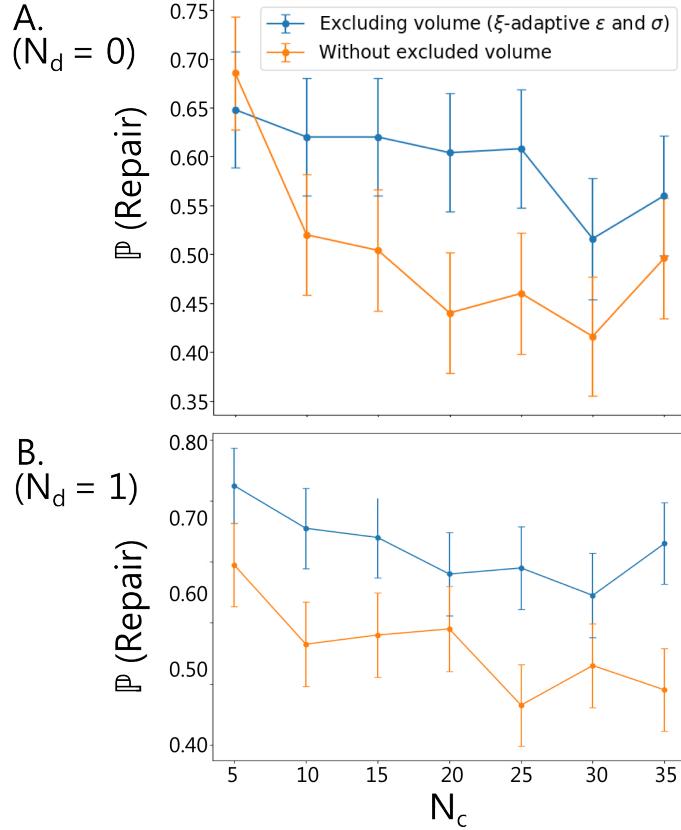


Figure 24: Repair probability considering a selective volume exclusion with ξ -adaptive ε and σ with $v = 2$ (i.e. $\sigma = 2\varepsilon$) for $g = 4$ and $N_d = 0$ (A) and $N_d = 1$ (B)

We focus now on the impact induced by σ on the repair. Figs. 25 and 26 show the shapes of repair probability, the MSRG and the mean FET as function of σ . We observe that selective exclusion lead to better repair probabilities, but an excessive σ is also detrimental. For $g = 4$ an optimum exclusion radius is reached few before the value of b . Concerning the MSRG at encounter time, it increases with σ as expected. On the other hand, the MFET decays rapidly as σ increases.

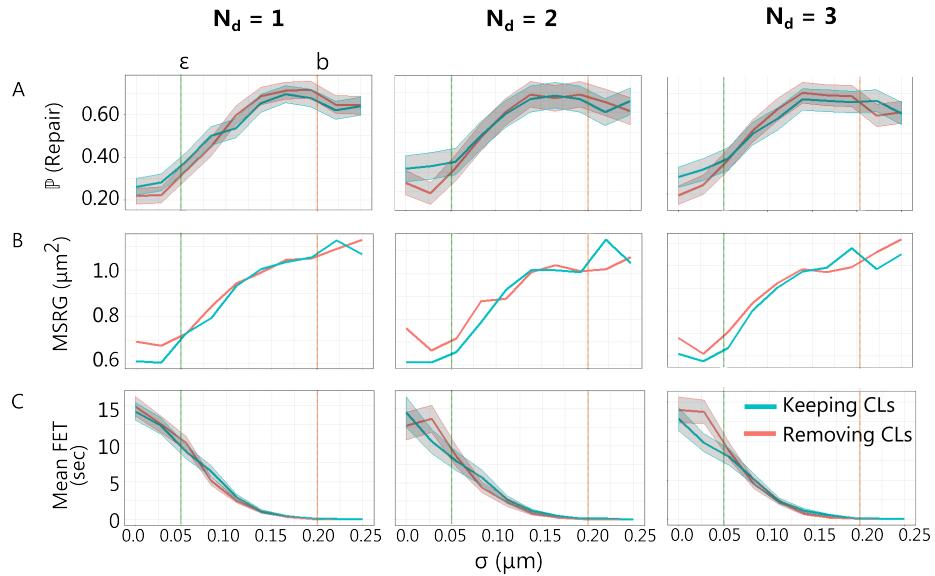


Figure 25: Repair probability (A), MSRG (B) and mean FET (C) as functions of σ with selective exclusion, imposing $N_d = 1, 2$ and 3 CLs in the DF, for then keeping or removing them. $N = 100$, $g = 4$, $\varepsilon = 0.05 \mu\text{m}$ and $N_c = 10$.

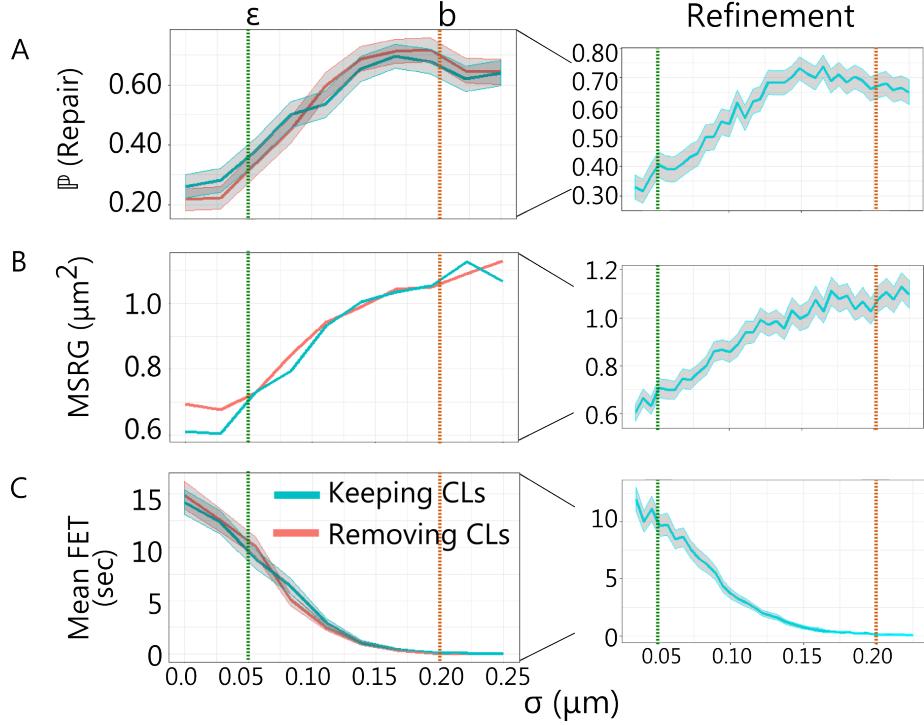


Figure 26: Repair probability (A), MSRG (B) and mean FET (C) as functions of σ with selective exclusion and $N_d = 1$ as in the left panels of Fig. 25, but here refining the evaluated values of σ (at right).

Fig. 27 shows the impact of the exclusion spring constant κ_{ve} for $g = 4$ and $\sigma = 0.1\mu\text{m}$. For the experimental set, exclusion with a bigger elastic constant leads to a better repair probability, as well as a more decompact polymer. The MFET also decays rapidly as κ_{ve} increases.

Finally, the joint action of σ and κ_{ve} is studied in Fig. 28. We observe that high values of σ along with weak κ_{ev} lead to better repairs. Stronger κ_{ve} are also beneficial for smaller exclusion ($\sigma < b$.) Thus, an optimal region combining different values of σ and κ_{ve} can be observed in the repair probability curve. We also observe that the MFET decays geometrically for κ_{ve} , and that the decay is faster as σ increases.

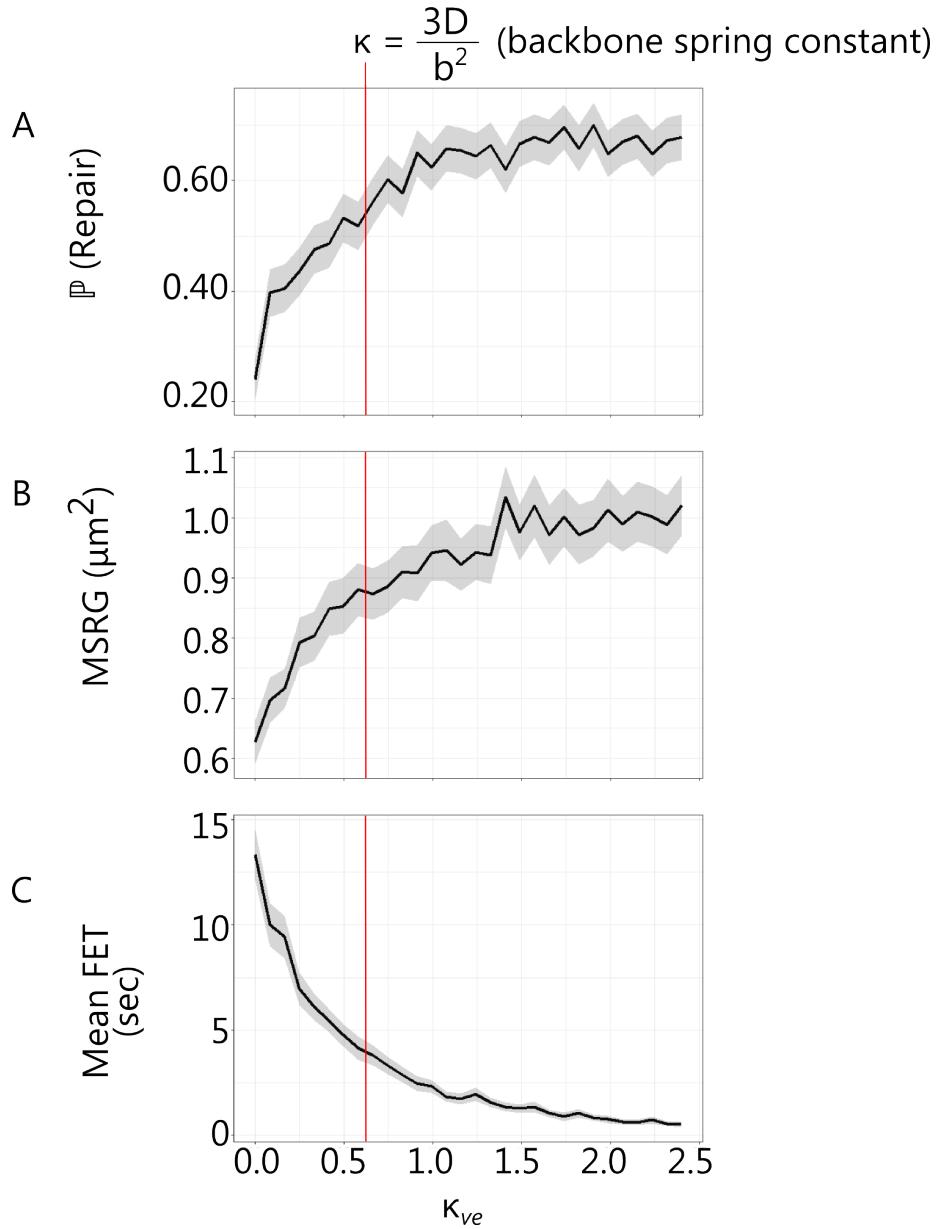


Figure 27: Repair probability (A), MSRG (B) and mean FET (C) as functions of κ_{ve} with selective exclusion, $N = 100$, $N_d = 1$, $g = 4$, $\varepsilon = 0.05 \mu\text{m}$, $N_c = 10$ and $\sigma = 0.1 \mu\text{m}$. The global spring constant defined for the backbone and the CLs is indicated in red.

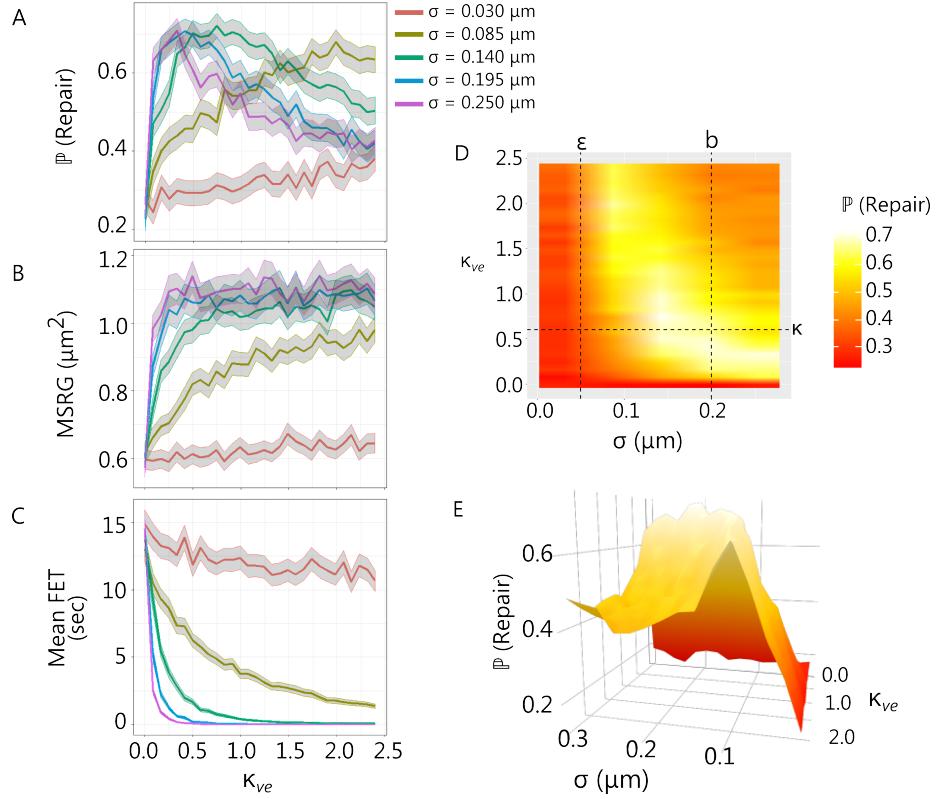


Figure 28: (Left) Repair probability (A), MSRG (B) and mean FET (C) as functions of κ_{ve} for different values of σ and with selective exclusion, $N = 100$, $N_d = 1$, $g = 4$, $\varepsilon = 0.05 \mu\text{m}$ and $N_c = 10$. (Right) Repair probability as function of both σ and κ_{ve} in matrix form (D) and as a surface in space (E).

3.3 Effect of sub-domain folding on the repair probability

We'll now consider a polymer folded in two connected sub-domains (simulating topologically associating domains (TADs) of chromatin) as represented in Fig. 29. We'll define M sub-domains where each sub-domain i has a connectivity ξ_i defined by their number of inner CLs $N_c^{(i)}$. A number $N_{lr}^{(i,j)}$ of large-range CLs connecting different pairs $i \neq j$ of sub-domains are also added. Thus, we define the connectivity matrix \mathbb{N}_c characterizing the TAD-folded RCL polymer by Eq. 17.

$$\mathbb{N}_c = \begin{pmatrix} N_c^{(1)} & N_{lr}^{(1,2)} & \dots & N_{lr}^{(1,M)} \\ & N_c^{(2)} & \dots & N_{lr}^{(2,M)} \\ & \ddots & \vdots & \\ & & & N_c^{(M)} \end{pmatrix} \quad (17)$$

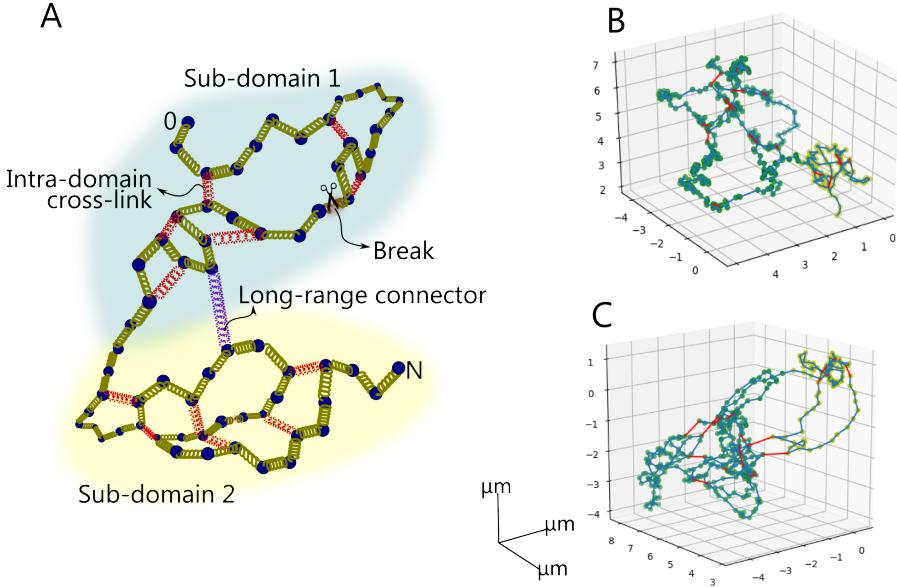


Figure 29: Model of the RCL polymer folded in two connected sub-domains. **A.** Schematic representation. **B.** One realization after relaxation time of a polymer with two sub-domains of $N_1 = 100$ and $N_2 = 300$ monomers, $N_c^{(1)} = 5$, $N_c^{(2)} = 12$ and $N_{lr} = 0$ inter-domain CLs. **C.** Another realization now with $N_{lr} = 2$

To verify the effect of the presence of a juxtaposed sub-domain next to the broken polymer, two DSBs are induced **in the same sub-domain** with a defined genomic distance g between the breaks as in the previous section. The repair probability is measured again to see if the presence of a juxtaposed sub-domain without breaks affects the repair in the first sub-domain.

Figures 30 and 32 suggest that the presence of a juxtaposed cross-linked polymer chain of any size does not affect the repair performance for two DSBs at a given genomic distance when the number of long-range connectors remains little. Figure 31 suggest that a higher number of long-range connectors increases the randomness of the system, making the probabilities go to $1/3$. If the correct repair probability was already about $1/3$ without long-range connections (for example, thanks to a high number of intra-domain cross-links), adding the long-range links does not change the repair rates.

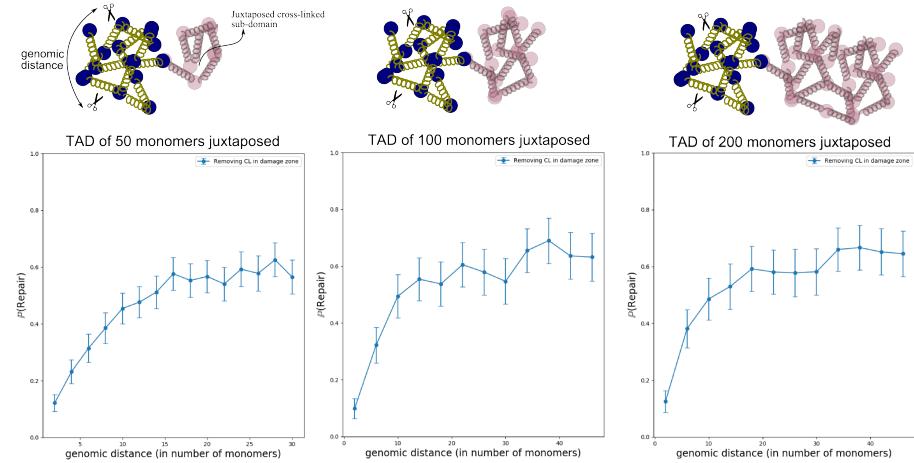


Figure 30: Repair probability of a 100-monomers sub-domain with two DSBs, in function of the genomic inter-break distance between the DSBs. Juxtaposed to the broken sub-domain, there is another sub-domain of size 50, 100 and 200 without breaks. The first sub-domain has 10 inner cross-links and the juxtaposed one has a connectivity of 0.2%. There are no long-range connectors between the two sub-domains.

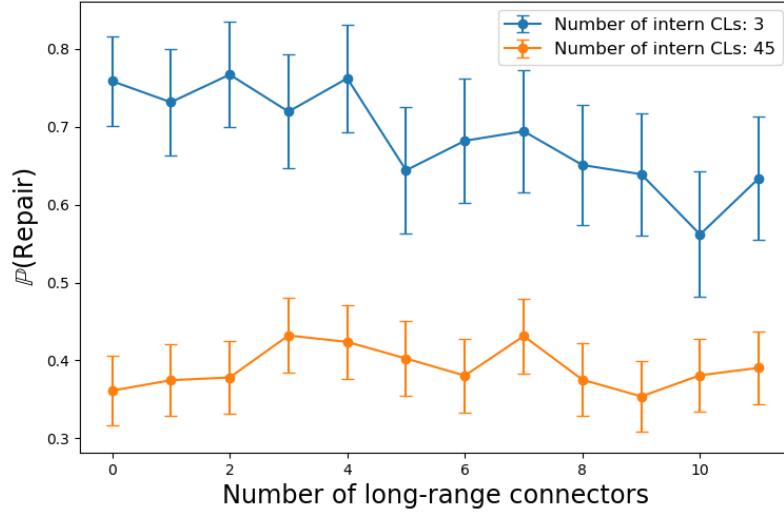


Figure 31: Probability of repair in function of the number of long-range connectors. Two DSBs were induced at a genomic distance of 5 in the first sub-domain of a polymer conformed by 2 sub-domains of 100 monomers with 3 and 45 inner cross-links.

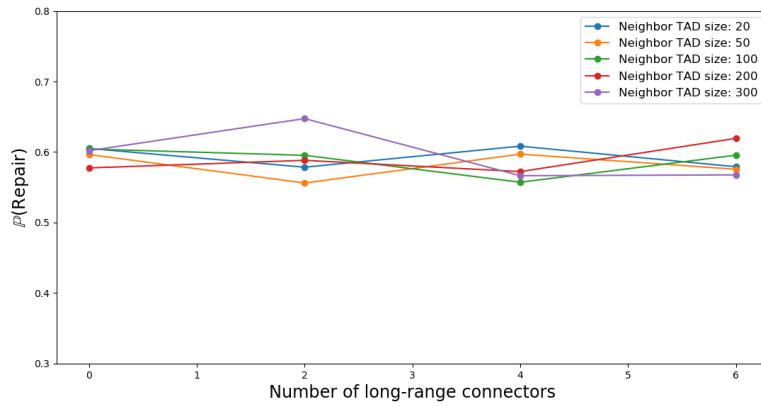


Figure 32: Probability of repair for 0,2,4 and 6 long-range connectors, and different sizes for the juxtaposed unbroken sub-domain. Two DSBs were induced at a genomic distance of 30 in the first sub-domain (100 monomers). The juxtaposed sub-domain has a constant connectivity fraction (0.2%).

4 Partial conclusions

- At short genomic distances ($g < 4$) the removal of CLs in the DF makes FET shorter (or equivalently the encounter rate λ higher) and the repair probabilities worse than when CLs are kept in the breaks. At further g , the observed behavior is the opposite and the expected one: the removal of CLs makes FET longer, but the repair rates are increased.
- When the mismatch rate is high (near DSBs and/or high connectivity) the most common misrepair seems to be the " $a_2 - b_1$ " one, which corresponds to the looping of the central segment of the cut RCL polymer.
- Keeping or removing the cross-links in the separated neighbors does not seem to particularly help the repair, at least without considering volume exclusion. The joint action of CLs removal and volume exclusion in the damage foci should be analyzed more carefully to conclude if this "relaxation" helps or not the repair.
- If there are enough cross-links, even for DSBs separated by a large genomic distance the repair probability goes down to $1/3$, i.e. the expected value by pure chance. The best correct repair probabilities occur, as one could expect, at large interbreak genomic distances with few random cross-links. However, if the breaks are close and the repair probability is less than $1/3$, the increment of cross-links improves the correct match rate.
- Local excluded volume in the damage foci seems to do not affect or even obstruct the repair, rather than improving its probability. Probability curves with local local exclusion volume are indeed down shifted in comparison with the non-excluded ones.

References

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- [2] Shukron, O. and Holcman D. Statistics of randomly cross-linked polymer models to interpret chromatin conformation capture data. *Phys. Rev. E* 96, 012503 – Published 27 July 2017.