


# INDERJOT SAGGU

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## EDUCATION

<b>University of California, San Diego</b> Master of Science, Electrical and Computer Engineering <i>Machine Learning and Data Science</i>	2018 - 2020 GPA: 3.8/4.0
<b>Indian Institute of Technology (IIT), Delhi</b> Bachelor of Technology, Electrical Engineering	2014 - 2018 GPA: 8.5/10.0

## WORK EXPERIENCE

<b>Machine Learning Intern</b> , Mitek Systems, Inc. <i>Document Tooling Team</i>	Jun 2019 - Present
<ul style="list-style-type: none"><li>Designed ID matching tool that reduced FPs by 92% over the legacy matcher while retaining over 80% of TPs</li><li>Tool uses computer vision algorithms like FLANN matching, histogram equalization and SSIM based image difference</li><li>Developed novel ID segmentation algorithm based on a U-Net architecture that achieved IoU of 0.98</li></ul>	
<b>Graduate Research Assistant</b> , University of California, San Diego <i>Relative Camera Pose Estimation for Large Viewpoint Changes</i>	Prof. Dinesh Bharadia, ECE, UCSD Nov 2018 - Present
<ul style="list-style-type: none"><li>Developed end-to-end 6-DoF relative camera pose estimation technique that exploits visual cues and co-visible objects</li><li>Proposed semantic augmented input representation and novel loss functions that imposed geometrical constraints</li><li>Improved over the baseline for end-to-end relative pose estimation by 85% in translation and 90% in orientation error</li></ul>	

## PROJECTS

<b>Simultaneous Localization and Mapping (SLAM)</b> <i>Sensing and Estimation in Robotics</i>	Prof. Nikolay Atanasov, ECE, UCSD Jan 2019 - March 2019
<ul style="list-style-type: none"><li>Implemented particle filter based SLAM using odometry, IMU and LIDAR measurements from a differential-drive robot</li><li>Constructed a texture map by projecting colored points from RGB-D sensor onto 2D occupancy grid</li><li>Implemented visual-inertial SLAM using Extended Kalman Filter (EKF) given data from an IMU and stereo camera</li></ul>	
<b>PetFinder.my : Improving Pet Adoption Rates</b> <i>Programming for Data Analysis</i>	Prof. José Unpingco, ECE, UCSD Jan 2019 - March 2019
<ul style="list-style-type: none"><li>Performed EDA and feature engineering on pet profiles to explore relationship between pet features and adoptability rate</li><li>Used sentiment score as a feature for pet-description and reduced dimensionality of entire feature space using PCA</li><li>Trained a decision tree for predicting pet-adoptability (discrete values from 0 to 4) and achieved 83% accuracy</li></ul>	
<b>Deep Siamese CNN for Learning Visual Similarity</b> <i>Fundamentals of Deep Learning</i>	Dr. Raghavendra Singh, IBM Research Sep 2017 - Dec 2017
<ul style="list-style-type: none"><li>Developed a multi-task Siamese CNN for transforming images of apparels to a latent space where images of visually similar items and same item in different poses were close together</li><li>Created a visual search algorithm that used nearest neighbor matching on the pose-invariant embedding space for finding stylistically similar products</li></ul>	

## TECHNICAL SKILLS

<b>Programming Languages</b>	Python, C/C++, MATLAB, OpenMP
<b>Tools</b>	Pytorch, Tensorflow, Git, Linux, Docker, Kubernetes

## CO-CURRICULAR ACTIVITIES

- Teaching Assistant*: **Graduate course on Machine Learning for Image Processing** (Spring 2019) : Designed final quiz and a project on Neural Style Transfer using Cycle-GAN
- Designated **Nikola Tesla Electrical Engineering Scholar** and offered \$2500 scholarship by Columbia University
- Technical Secretary*: Electrical Engineering Society (EES), IIT Delhi 2016-17