Custom Computing: Assessed Coursework

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Question 1

Recurring engin eering costs are the costs that will occur in a repeating fashion during the production, usually involving fabriction. These costs are usually descriped in a per unit form.

Non-recurring engineering cost is the one-time up-front cost for research, design, testing and development of a new product.

As we can see below, the minimum number of units that need to be sold for the ASIC implementation to be cost-effective is 1 million units.

$$C_{FPGA} > C_{ASIC} \Rightarrow \pounds2 \times N_{units} > \pounds10^6 + \pounds1 \times N_{units} \Rightarrow N_{units} > 10^6$$

Question 2

(a) Diagramatic and symbolic Simulation

Diagram of circuit Q1

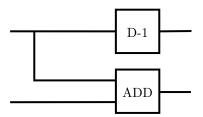


Figure 1: the circuit as derrived from Q1

Diagram of circuit P1

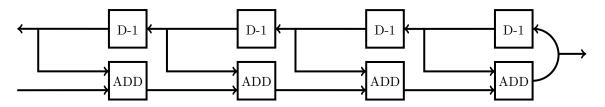


Figure 2: the circuit as derrived from P1

Simulation

The source code of the simulation (uninitialized delay) is the following:

```
INCLUDE "prelude.rby".
P1 n = Q1^n; fork\sim1.
Q1 = snd fork; rsh; [add,D^\sim1].
current = P1 4.
The result after executing re "a;b;c"
0 - \langle a,? \rangle \sim ((((a + ?) + ?) + ?) + ?)
1 - \langle b,? \rangle \sim ((((b + ?) + ?) + ?) + ((((a + ?) + ?) + ?) + ?))
2 - \langle c, ? \rangle \sim ((((c + ?) + ?) + ((((a + ?) + ?) + ?) + ?)) + ((((b + ?) + ?) + ?))
            +((((a + ?) + ?) + ?) + ?)))
The source code of the simulation (initialized delay with 0) is the following:
INCLUDE "prelude.rby".
P1 n = Q1^n; fork\sim1.
Q1 = snd fork; rsh; [add,DI 0^{\sim}1].
current = P1 4.
The result after executing re "a;b;c"
0 - \langle a, 0 \rangle  ((((a + 0) + 0) + 0) + 0)
1 - \langle b, 0 \rangle  ((((b + 0) + 0) + 0) + ((((a + 0) + 0) + 0) + 0))
2 - \langle c, 0 \rangle  ((((c + 0) + 0) + ((((a + 0) + 0) + 0) + 0)) + ((
              ((b + 0) + 0) + 0) + ((((a + 0) + 0) + 0) + 0)))
The result after executing re -s 4 1"
0 - <1,0> ~ 1
1 - <1,0> ~ 2
2 - \langle 1, 0 \rangle ^{-4}
3 - <1.0> ~ 8
```

The simulation output (for 4 cycles) can be found in the included zip file.

Question 3

(a) Proof by induction

In order to show that $[P,Q]^n$; R=R; Q^n for n>0, we first have to show that it is True for n=1.

Base case: $[P,Q]^1$; R=R; Q^1

This is intuitively shown to be true by the given assumption $[P,Q]^n$; R=R; Q which is equivalent.

Assuming that it is also true for n = k > 0

Inductive Hypothesis: $[P,Q]^k$; R=R; Q^k

We need to show that the same is true for n = k + 1 and $[P, Q]^{k+1}$; R = R; Q^{k+1}

```
\begin{split} &[P,Q]^{k+1}; R \text{ LHS} \\ &= [P,Q]^k; [P,Q]; R \text{ (by sequential expansion of } [P,Q]^{k+1}) \\ &= [P,Q]^k; R; Q \text{ (since } [P,Q]; R = R; Q \text{ given)} \\ &= R; Q^k; Q \text{ (by the i.h. } [P,Q]^k; R = R; Q^k) \\ &= R; Q^{k+1} \text{ (by sequential contraction of } Q^k; Q) \text{ RHS} \end{split}
```

So by induction we have **proved** that if [P,Q]; R=R; Q is given to be True, for n>0:

$$[P,Q]^n$$
; $R=R$; Q^n is also $True$

(b) Inductive Definitions

Right-reduction

$$\begin{split} rdr_1 &= fst \: [-]^{-1}; R. \\ rdr_{n+1} &= fst \: apl_n^{-1}; lsh; snd(rdr_n \: R); R. \end{split}$$

Delta (triangle)

$$\Delta_0 = [].$$

$$\Delta_{n+1} = [\Delta_n, R^n] \backslash apr_n.$$

(c) Horner's Rule

Left-hand side

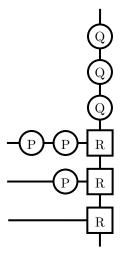


Figure 3: LHS of the rule for n = 3

Right-hand side

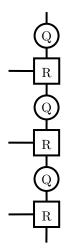


Figure 4: RHS of the rule for n=3

(d) Polynomial Evaluation

R stands for the add operation (addition), P and Q both stand for multiplication by a constant (let this constant be x). For the given coefficients a_0, a_1, a_2, a_3 , the circuit will be the following.

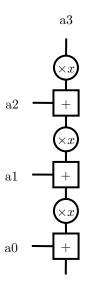


Figure 5: The optimised circuit as adjusted for polynomial evaluation

and the simulation written in Ruby:

```
INCLUDE "prelude.rby".
multc n = pi1^~1; snd n; mult.
Q = multc 'x'.
R = add.
POL n = rdr n (snd Q; R).
current = POL 3.
run with re "a_0 a_1 a_2 a_3" produces the following output:
Simulation start :
    0 - <<a_0,a_1,a_2>,a_3> ~ (a_0 + ((a_1 + ((a_2 + (a_3 * x)) * x)) * x))
Simulation end :
```

Question 4