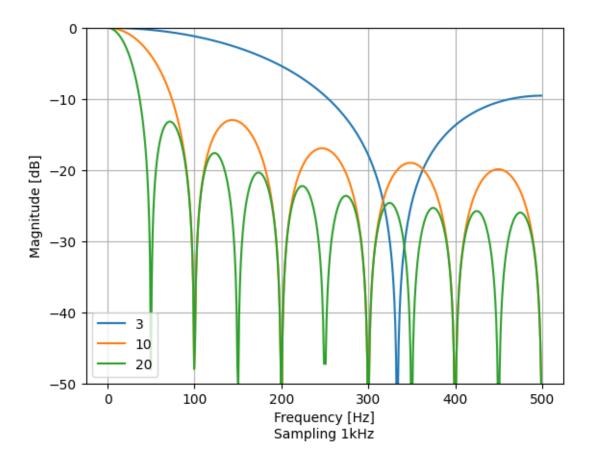
moving-average

December 6, 2022

https://www.dafx.de/paper-archive/2013/papers/06.dafx2013_submission_46.pdf https://www.isprs.org/PROCEEDINGS/XXV/congress/part7/163_XXV-part7.pdf Moving median is a complex non linear filter

```
[]: import warnings
     warnings.filterwarnings('ignore')
     fs = 1000 \# Hz
     w = np.linspace(0, np.pi, 1024)
     fig, ax = plt.subplots()
     for samples in [3, 10, 20]:
         # numerator co-effs of filter transfer function
         b = (np.ones(samples))/samples
         a = np.ones(1) # denominator co-effs of filter transfer function
         w, h = signal.freqz(b, a)
         f = w * fs / (2*np.pi)
         ax.plot(f, 20 * np.log10(abs(h)), label="" + str(samples))
     plt.ylabel('Magnitude [dB]')
     plt.xlabel('Frequency [Hz]\nSampling 1kHz')
     plt.grid(True)
     plt.ylim(-50, 0)
     plt.legend()
     plt.show()
```



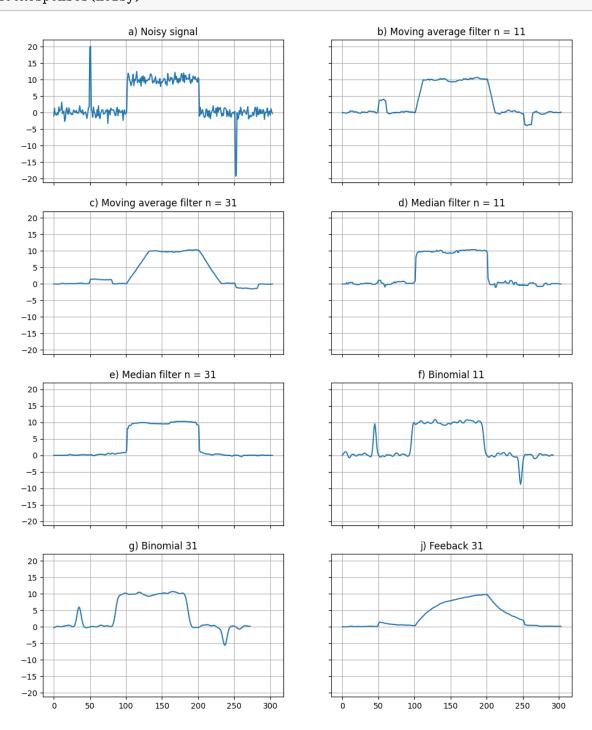
IIR filter below, lookback of 1. Where n is a weigh for previous output

$$Y_n = \tfrac{1}{n} * X_n + \tfrac{n-1}{n} * Y_{n-1}$$

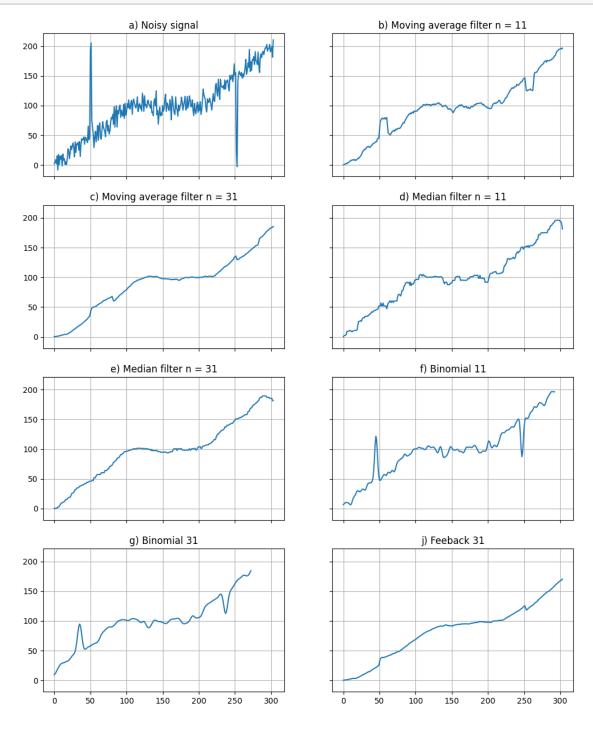
https://www.electronicdesign.com/technologies/analog/article/21778422/use-software-filters-to-reduce-adc-noise

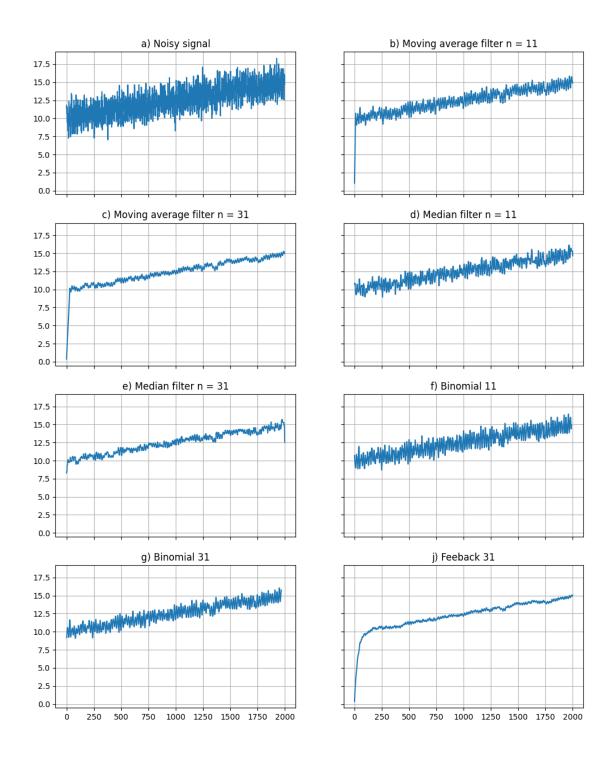
```
def feedback(x, n=5):
   result=[]
    y_prev = 0;
    for item in x:
        y_prev = 1.0/n*item+(n-1)/n*y_prev
        result.append(y_prev)
    return np.array(result);
def plotResponses(noisy):
    yBinomial11 = np.convolve(noisy, binomcoeffs(11), mode='valid')
    yBinomial31 = np.convolve(noisy, binomcoeffs(31), mode='valid')
    yFeedback = feedback(noisy, 31);
    # Moving average filters
    ym11 = ma(noisy, 11)
    ym31 = ma(noisy, 31)
    # Median filter from scipy.signal
    ymed11 = signal.medfilt(noisy, 11)
    ymed31 = signal.medfilt(noisy, 31)
    # Plots with shared x and y-axis
    f, ((ax1, ax2), (ax3, ax4), (ax5, ax6), (ax7, ax8)) = plt.subplots(
        nrows=4, ncols=2, sharex=True, sharey=True)
    ax1.plot(noisy)
    ax1.set_title("a) Noisy signal")
    ax2.plot(ym11)
    ax2.set_title("b) Moving average filter n = 11")
    ax3.plot(ym31)
    ax3.set_title("c) Moving average filter n = 31")
    ax4.plot(ymed11)
    ax4.set_title("d) Median filter n = 11")
    ax5.plot(ymed31)
    ax5.set_title("e) Median filter n = 31")
    ax6.plot(yBinomial11)
    ax6.set_title("f) Binomial 11")
    ax7.plot(yBinomial31)
    ax7.set_title("g) Binomial 31")
    ax8.plot(yFeedback)
    ax8.set_title("j) Feeback 31")
    # plt.ylim(-30,30);
    for ax in f.axes:
        ax.grid()
    f.set_size_inches(12, 15)
    plt.show()
```

noisy = ym+np.random.randn(304)
plotResponses(noisy)



[]: # simple random noise with spikes



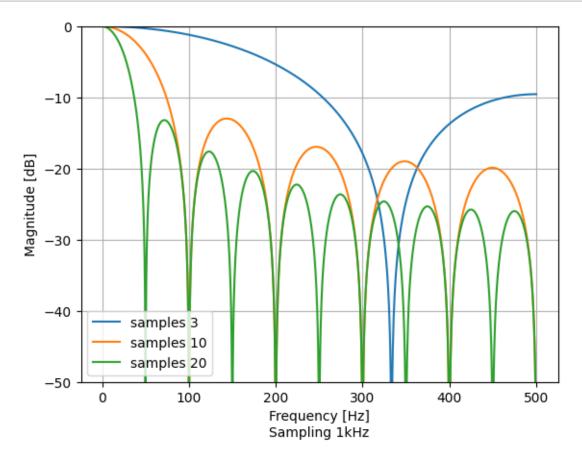


```
[]: # Moving avergae filters
fs = 1000 # Hz
w = np.linspace(0, np.pi, 1024)

fig, ax = plt.subplots()
```

```
for samples in [3, 10, 20]:
    f = w * fs / (2*np.pi)
    H = (1/samples)*(1-np.exp(-1j*w*samples))/(1-np.exp(-1j*w))
    ax.plot(f, 20 * np.log10(abs(H)), label="samples " + str(samples))

plt.ylabel('Magnitude [dB]')
plt.xlabel('Frequency [Hz]\nSampling 1kHz')
plt.grid(True)
plt.legend()
plt.ylim(-50, 0)
plt.show()
```



```
[]: # simple binomial filter
fs = 1000  # Hz
w = np.linspace(0, np.pi, 1024)
fig, ax = plt.subplots()
# numerator co-effs of filter transfer function
filt = np.array([0.25, 0.5, 0.25])
a = np.ones(1)  # denominator co-effs of filter transfer function
```

```
w, h = signal.freqz(filt, a)
f = w * fs / (2*np.pi)
ax.plot(f, 20 * np.log10(abs(h)), label="" + str(samples))

plt.ylabel('Magnitude [dB]')
plt.xlabel('Frequency [Hz]\nSampling 1kHz')
plt.grid(True)
plt.ylim(-50, 0)
plt.legend()
plt.show()
```

